

Standard Code Library

Your TeamName

Your School

March 26, 2021

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开始

宏定义

```
1  #include<bits/stdc++.h>
2  using namespace std;
3  typedef long long LL;
4  typedef __int128 LLL;
5  typedef unsigned u32;
6  typedef unsigned long long u64;
7  typedef long double LD;
8  #define il inline
9  #define pln putchar('\n')
10 #define For(i,a,b) for(int i=(a),(i##i)=(b);i<=(i##i);++i)
11 #define Rep(i,n) for(int i=0,(i##i)=(n);i<(i##i);++i)
12 #define Fodn(i,a,b) for(int i=(a),(i##i)=(b);i>=(i##i);--i)
13 const int M=1000000007,INF=0x3f3f3f3f;
14 const long long INFLL=0x3f3f3f3f3f3f3f3fLL;
15 const int N=1000010;
```

快读

```
1  ios::sync_with_stdio(0);cin.tie(0);cout.tie(0);

1  template <typename T>
2  inline bool read(T &x) {
3      x = 0; char c = getchar(); int f = 1;
4      while (!isdigit(c) && (c != '-' && (c != EOF))) c = getchar();
5      if (c == EOF) return 0;
6      if (c == '-') f = -1, c = getchar();
7      while (isdigit(c)) { x = x * 10 + (c & 15); c = getchar();}
8      x *= f; return 1;
9  }

10
11 template <typename T, typename... Args>
12 inline bool read(T &x, Args &...args) {
13     bool res = 1;
14     res &= read(x);
15     res &= read(args...);
16     return res;
17 }
```

对拍

```
1  //in.txt
2  //AC.exe std.txt
3  //MY.exe my.txt
4
5  void init(){
6      FILE*F=fopen("int.txt","w");
7
8      //srand(time(0));
9      //int a=(long long)rand()*rand()%1001;
10     //fscanf(F,"%d",&a);fprintf(F,"%d\n",a);
11
12     fclose(F);
13 }
14
15 int main(){
16     init();
17     while(1){
18         system("AC.exe < in.txt > std.txt");
19
20         system("MY.exe < in.txt > my.txt");
21
22         if(system("fc std.txt my.txt")){
23             puts("WA");
24             return 0;
25         }else puts("AC\n\n");
26     }
```

```

27         init();
28     }
29 }

```

数学

模乘模幂

- longlong 范围用 fpl

```

1  inline LL mul(LL a, LL b, LL p) {
2      LL res = a * b - ((LL)((LD)a * b / p) * p);
3      return res < 0 ? res + p : (res < p ? res : res - p);
4  }
5
6  inline LL fp(LL a, LL b, LL Mod) {
7      LL res = (Mod != 1);
8      for (; b >= 1, a = a * a % Mod)
9          if (b & 1)
10             res = res * a % Mod;
11     return res;
12 }
13
14 inline LL fpl(LL a, LL b, LL Mod) {
15     LL res = (Mod != 1);
16     for (; b >= 1, a = mul(a, a, Mod))
17         if (b & 1)
18             res = mul(res, a, Mod);
19     return res;
20 }

```

GCD

```

1  template <typename T>
2  inline T gcd(T a, T b) {
3      while (b){
4          T t = b;
5          b = a % b;
6          a = t;
7      }
8      return a;
9  }
10
11 template <typename T>
12 inline T lcm(T a, T b) { return a / gcd(a, b) * b; }
13
14 template <typename T>
15 T exgcd(T a, T b, T &x, T &y) {
16     if (!b) {
17         x = 1;
18         y = 0;
19         return a;
20     }
21     T res = exgcd(b, a % b, x, y);
22     T t = x;
23     x = y;
24     y = t - a / b * y;
25     return res;
26 }

```

CRT

- 需要 GCD 64 位模乘
- 用来合并同余方程
- 返回最小正数解或最小非负解无解返回-1

```

1  inline LL Crt(LL a1, LL a2, LL mod1, LL mod2) {
2      LL u, v;

```

```

3     LL g = exgcd(mod1, mod2, u, v);
4     if ((a2 - a1) % g) return -1;
5     LL m12 = abs(lcm(mod1, mod2));
6     LL res = (mul(mod1, mul(u, ((a2 - a1) / g), m12), m12) + a1) % m12;
7     return res <= 0 ? res + m12 : res; /* 求最小正数解还是非负解 */
8 }

```

线性筛

```

1 struct primenumberlist{
2     #define MAXN (100000000)
3     int cnt, pri[100000000];
4     bool np[MAXN + 10];
5     primenumberlist(){
6         np[1] = 1; cnt = 0;
7         for (int i = 2; i <= MAXN; ++i) {
8             if (!np[i]) pri[++cnt] = i;
9             for (int j = 1; j <= cnt; ++j) {
10                 LL t = pri[j] * i;
11                 if (t > MAXN) break;
12                 np[t] = 1;
13                 if (!(i % pri[j])) break;
14             }
15         }
16     }
17 } prime;

```

ϕ 单点欧拉函数

```

1 template <typename T>
2 inline T phi(T x) {
3     T res = x;
4     for (T i = 2; i * i <= x; ++i)
5         if ((x % i) == 0) {
6             res = res / i * (i - 1);
7             while ((x % i) == 0) x /= i;
8         }
9     if (x > 1) res = res / x * (x - 1);
10    return res;
11 }

```

Miller-Rabin 素性测试

- $n \leq 10^{18}$
- 需要 64 位模乘 64 位模幂

```

1 inline bool MR(LL x, LL n, int t) {
2     LL las = x;
3     for (int i = 1; i <= t; ++i) {
4         x = mul(x, x, n);
5         if (x == 1 && las != 1 && las != (n - 1)) return 0;
6         las = x;
7     }
8     return x == 1;
9 }
10
11 inline bool isPrime(LL n) {
12     if (n == 4685624825598111 || n < 2) return 0;
13     if (n == 2 || n == 3 || n == 7 || n == 61 || n == 24251) return 1;
14     LL d = n - 1;
15     int t = 0;
16     while ((d & 1) == 0) d >>= 1, ++t;
17     return MR(fpl(2, d, n), n, t) && MR(fpl(61, d, n), n, t);
18 }

```

Pollard-Rho 分解质因数

- 需要 64 位模乘 gcd

- 求 n 的一个大于 1 的因子可能返回 n 本身
- 调用 `PR()` 前务必判断 n 的素性检查 $n > 1$

```

1 mt19937 mt(time(0)); //随机化
2 inline LL PR(LL n) {
3     LL x = uniform_int_distribution<LL>(0, n - 1)(mt), s, t, c = uniform_int_distribution<LL>(1, n - 1)(mt); //随机化
4     for (int gol = 1; gol <= n; gol++) {
5         for (int stp = 1; stp <= gol; ++stp) {
6             t = (mul(t, t, n) + c) % n;
7             x = mul(x, abs(s - t), n);
8             if ((stp & 127) == 0) {
9                 LL d = gcd(x, n);
10                if (d > 1) return d;
11            }
12        }
13        LL d = gcd(x, n);
14        if (d > 1) return d;
15    }
16 }

```

组合数

- 数较小模数为较大质数求逆元
- - 如果模数固定可以 $O(n)$ 预处理阶乘的逆元
- 数较大模数为较小质数用 *Lucas* 定理
- -

$$C_n^m \equiv C_{\lfloor \frac{n}{p} \rfloor}^{\lfloor \frac{m}{p} \rfloor} * C_{n \bmod p}^{m \bmod p} \pmod{p}$$

- 数较大模数较小用 *exLucas* 定理求 $C_n^m \bmod P$

exLucas

- 需要模乘 CRT
- $O(P \log P)$
- 不要求 P 为质数

```

1 namespace EXLUCAS {
2     inline LL idxp(LL n, LL p) {
3         LL nn = n;
4         while (n > 0) nn -= (n % p), n /= p;
5         return nn / (p - 1);
6     }
7
8     LL facp(LL n, LL p, LL pk) {
9         if (n == 0) return 1;
10        LL res = 1;
11        if (n >= pk) {
12            LL t = n / pk, k = 1, els = n - t * pk;
13            for (LL i = 1; i <= els; ++i) if (i % p) k = k * i % pk;
14            res = k;
15            for (LL i = els + 1; i < pk; ++i) if (i % p) k = k * i % pk;
16            res = res * fp(k, n / pk, pk) % pk;
17        }
18        else for (LL i = 1; i <= n; ++i) if (i % p) res = res * i % pk;
19        return res * facp(n / p, p, pk) % pk;
20    }
21
22    inline LL exlucas(LL n, LL m, LL p, LL pk, LL k) {
23        LL a = facp(n, p, pk) * fp(facp(n - m, p, pk) * facp(m, p, pk) % pk, pk / p * (p - 1) - 1, pk) % pk;
24        LL b = idxp(n, p) - idxp(m, p) - idxp(n - m, p);
25        if (b >= k) return 0;
26        while (b--) a *= p;
27        return a % pk;
28    }
29 }

```

```

29
30 /* 接口 */ inline LL exlucas(LL n, LL m, LL p) {
31     LL a = 0, b = 1;
32     for (LL i = 2; i * i <= p; ++i) {
33         if (p % i) continue;
34         LL t = 0, pk = 1;
35         while (p % i == 0) ++t, p /= i, pk *= i;
36         a = Crt(a, exlucas(n, m, i, pk, t), b, pk);
37         b *= pk;
38     }
39     return (p > 1) ? Crt(a, exlucas(n, m, p, p, 1), b, p) : a;
40 }
41 }

```

二维计算几何

- Point 直接支持整型和浮点型
- 部分函数可以对整型改写
- 多边形 (凸包) 按逆时针存在下标 1..n

点向量基本运算

```

1  template <typename T>
2  struct Point {
3      T x, y;
4      Point() {}
5      Point(T u, T v) : x(u), y(v) {}
6      Point operator+(const Point &a) const { return Point(x + a.x, y + a.y); }
7      Point operator-(const Point &a) const { return Point(x - a.x, y - a.y); }
8      Point operator*(const T &a) const { return Point(x * a, y * a); }
9      T operator*(const Point &a) const { return x * a.x + y * a.y; }
10     T operator%(const Point &a) const { return x * a.y - y * a.x; }
11     double len() const { return hypot(x, y); }
12     double operator^(const Point &a) const { return (a - (*this)).len(); }
13     double angle() const { return atan2(y, x); }
14     bool id() const { return y < 0 || (y == 0 && x < 0); }
15     bool operator<(const Point &a) const { return id() == a.id() ? (*this) % a > 0 : id() < a.id(); }
16 };
17 typedef Point<double> point;
18
19 #define sqr(x) ((x) * (x))
20 const point O(0, 0);
21 const double PI(acos(-1.0)), EPS(1e-8);
22 inline bool dcmp(const double &x, const double &y) { return fabs(x - y) < EPS; }
23 inline int sgn(const double &x) { return fabs(x) < EPS ? 0 : ((x < 0) ? -1 : 1); }
24 inline double mul(point p1, point p2, point p0) { return (p1 - p0) % (p2 - p0); }

```

位置关系

```

1  inline bool in_same_seg(point p, point a, point b) {
2      if (fabs(mul(p, a, b)) < EPS) {
3          if (a.x > b.x) swap(a, b);
4          return (a.x <= p.x && p.x <= b.x && ((a.y <= p.y && p.y <= b.y) || (a.y >= p.y && p.y >= b.y)));
5      } else return 0;
6  }
7
8  inline bool is_right(point st, point ed, point a) {
9      return ((ed - st) % (a - st)) < 0;
10 }
11
12 inline point intersection(point s1, point t1, point s2, point t2) {
13     return s1 + (t1 - s1) * (((s1 - s2) % (t2 - s2)) / ((t2 - s2) % (t1 - s1)));
14 }
15
16 inline bool parallel(point a, point b, point c, point d) {
17     return dcmp((b - a) % (d - c), 0);
18 }
19

```

```

20 inline double point2line(point p, point s, point t) {
21     return fabs(mul(p, s, t) / (t - s).len());
22 }
23
24 inline double point2seg(point p, point s, point t) {
25     return sgn((t - s) * (p - s)) * sgn((s - t) * (p - t)) > 0 ? point2line(p, s, t) : min((p ^ s), (p ^ t));
26 }

```

多边形

求多边形面积

```

1 inline double area(int n, point s[]) {
2     double res = 0;
3     s[n + 1] = s[1];
4     for (int i = 1; i <= n; ++i)
5         res += s[i] % s[i + 1];
6     return fabs(res / 2);
7 }

```

判断点是否在多边形内

- 特判边上的点
- 使用了 $a[1] \dots a[n+1]$ 的数组

```

1 inline bool in_the_area(point p, int n, point area[]) {
2     bool ans = 0; double x;
3     area[n + 1] = area[1];
4     for (int i = 1; i <= n; ++i) {
5         point p1 = area[i], p2 = area[i + 1];
6         if (in_same_seg(p, p1, p2)) return 1; //特判边上的点
7         if (p1.y == p2.y) continue;
8         if (p.y < min(p1.y, p2.y)) continue;
9         if (p.y >= max(p1.y, p2.y)) continue;
10        ans ^= (((p.y - p1.y) * (p2.x - p1.x) / (p2.y - p1.y) + p1.x) > p.x);
11    }
12    return ans;
13 }

```

凸包

- *Andrew* 算法
- $O(n \log n)$
- 可以应对凸包退化成直线/单点的情况但后续旋转卡壳时应注意特判
- 注意是否应该统计凸包边上的点

```

1 inline bool pcmp1(const point &a, const point &b) { return a.x == b.x ? a.y < b.y : a.x < b.x; }
2
3 inline int Andrew(int n, point p[], point ans[]) { //ans[] 逆时针存凸包
4     sort(p + 1, p + 1 + n, pcmp1);
5     int m = 0;
6     for (int i = 1; i <= n; ++i) {
7         while (m > 1 && mul(ans[m - 1], ans[m], p[i]) < 0) --m; //特判凸包边上的点
8         ans[++m] = p[i];
9     }
10    int k = m;
11    for (int i = n - 1; i >= 1; --i) {
12        while (m > k && mul(ans[m - 1], ans[m], p[i]) < 0) --m; //特判凸包边上的点
13        ans[++m] = p[i];
14    }
15    return m - (n > 1); //返回凸包有多少个点
16 }

```

凸包直径·平面最远点对

- 旋转卡壳算法

- $O(n)$
- 凸包的边上只能有端点，否则不满足严格单峰
- 凸包不能退化成直线，调用前务必检查 $n \geq 3$
- 使用了 $a[1] \dots a[n+1]$ 的数组

```

1 inline double Rotating_Caliper(int n, point a[]) {
2     a[n + 1] = a[1];
3     double ans = 0;
4     int j = 2;
5     for (int i = 1; i <= n; ++i) {
6         while (fabs(mul(a[i], a[i + 1], a[j])) < fabs(mul(a[i], a[i + 1], a[j + 1]))) j = (j % n + 1);
7         ans = max(ans, max((a[j] ^ a[i]), (a[j] ^ a[i + 1])));
8     }
9     return ans;
10 }

```

平面最近点对

- 分治 + 归并
- $O(n \log n)$

```

1 namespace find_the_closest_pair_of_points {
2     const int N = 200010; //maxn
3     inline bool cmp1(const point &a, const point &b) { return a.x < b.x || (a.x == b.x && a.y < b.y); }
4     inline bool operator>(const point &a, const point &b) { return a.y > b.y || (a.y == b.y && a.x > b.x); }
5
6     point a[N], b[N];
7     double ans;
8     inline void upd(const point &i, const point &j) { ans = min(ans, i ^ j); }
9
10    void find(int l, int r) {
11        if (l == r) return;
12        if (l + 1 == r) {
13            if (a[l] > a[r]) swap(a[l], a[r]);
14            upd(a[l], a[r]); return;
15        }
16        int mid = (l + r) >> 1;
17        double mx = (a[mid + 1].x + a[mid].x) / 2;
18        find(l, mid); find(mid + 1, r);
19        int i = l, j = mid + 1;
20        for (int k = l; k <= r; ++k) b[k] = a[(j > r) || (i <= mid && a[j] > a[i]) ? (i++) : (j++)];
21        for (int k = l; k <= r; ++k) a[k] = b[k];
22        int tot = 0;
23        for (int k = l; k <= r; ++k) if (fabs(a[k].x - mx) <= ans) {
24            for (int j = tot; j >= 1 && (a[k].y - b[j].y <= ans); --j) upd(a[k], b[j]);
25            b[++tot] = a[k];
26        }
27    }
28
29    //接口
30    inline double solve(int n, point ipt[]){
31        ans = 0x3f3f3f3f3f3f3f3f; //max distance
32        for (int i = 1; i <= n; ++i) a[i] = ipt[i];
33        sort(a + 1, a + 1 + n, cmp1);
34        find(1, n);
35        return ans;
36    }
37 }

```

圆

三点垂心

```

1 inline point geto(point p1, point p2, point p3) {
2     double a = p2.x - p1.x;
3     double b = p2.y - p1.y;
4     double c = p3.x - p2.x;
5     double d = p3.y - p2.y;
6     double e = sqr(p2.x) + sqr(p2.y) - sqr(p1.x) - sqr(p1.y);

```

```

7     double f = sqr(p3.x) + sqr(p3.y) - sqr(p2.x) - sqr(p2.y);
8     return {(f * b - e * d) / (c * b - a * d) / 2, (a * f - e * c) / (a * d - b * c) / 2};
9 }

```

最小覆盖圆

- 随机增量 $O(n)$

```

1 inline void min_circlefill(point &o, double &r, int n, point a[]) {
2     mt19937 myrand(20011224); shuffle(a + 1, a + 1 + n, myrand); //越随机越难 hack
3     o = a[1];
4     r = 0;
5     for (int i = 1; i <= n; ++i) if ((a[i] ^ o) > r + EPS) {
6         o = a[i];
7         r = 0;
8         for (int j = 1; j < i; ++j) if ((o ^ a[j]) > r + EPS) {
9             o = (a[i] + a[j]) * 0.5;
10            r = (a[i] ^ a[j]) * 0.5;
11            for (int k = 1; k < j; ++k) if ((o ^ a[k]) > r + EPS) {
12                o = geto(a[i], a[j], a[k]);
13                r = (o ^ a[i]);
14            }
15        }
16    }
17 }

```