DASTA STRUCTURE AND ALGORITHM

CLASS 1

Seongjin Lee

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insight@gnu.ac.kr http://resourceful.github.io Systems Research Lab. GNU



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MISCELLENEA

Text Book

Fundamentals of Data Structure in C, 2nd Ed.

by Horowitz, Sahni, and Anderson-Freed

http://www.cise.ufl.edu/~sahni/fdsc2ed/

Presentations are uploaded in

 $\bigcirc \ \, https://github.com/resourceful/lecture_dsa2017-1$



Contact

E-mail: insight@gnu.ac.kr

Room: 407-314

Visiting Hour: Monday and Wednesday 14:00 - 16:00



Evaluation

- O Midterm 20%
- Final 30%
- Assignments 40%
- O Attendance 10%



BASIC CONCEPTS

Overview: System Life Cycle

Requirements

describe informations(input, output, initial)

Analysis

○ bottom-up, top-down

Design

data objects and operations performed on them

Coding

 choose representations for data objects and write algorithms for each operation

Overview: System Life Cycle Cnt'd

Verification

- correctness proofs: select algorithms that have been proven correct
- testing: working code and sets of test data
- error removal: If done properly, the correctness proofs and system test indicate erroneous coed

ALGORITHM SPECIFICATION

Algorithm Specification

Definition

o a finite set of instructions - accomplish a particular task

Criteria

- zero or more inputs
- at least one output
- definiteness(clear, unambiguous)
- finiteness(terminates after a finite number of steps)

Algorithm Specification: Selection Sort

Ex Selection Sort: Sort n(geq1) integers

 From those integers that are currently unsorted, find the smallest and place it next in the sorted list

```
for (i=0; i<n; i++) {
    Examine list[i] to list[n-1] and suppose
    that the smallest integer is at list[min];
    Interchange list[i] and list[min];
}</pre>
```



Algorithm Specification: Selection Sort

finding the smallest integer

- assume that minimum is list[i]
- compare current minimum with list[i+1] to list[n-1] and find smaller number and make it the new minimum

interchanging minimum with list[i]

- **function**: swap(&a,&b) easier
- \bigcirc **macro**: swap(x,y,t) no type-checking

assumption

 sorted n(1) distinct integers stored in the array list return

○ index i (if i, list[i] = searchnum)

or -1 (otherwise)

denote left and right

- left and right ends of the list to be searched
- initially, left=0 and right=n-1

let middle=(left+right)/2 middle position in the list compare list[middle] with the searchnum and adjust left or right

compare list[middle] with searchnum

- searchnum < list[middle] set right to middle-1
- searchnum = list[middle] return middle
- searchnum > list[middle] set left to middle+1

if searchnum has not been found and there are more integers to check

recalculate middle and continue search

```
while(there are more integers to check) {
   middle=(left+right)/2;
   if(searchnum < list[middle])
      right=middle-1;
   else if(searchnum == list[middle])
      return middle;
   else left=middle+1;
}</pre>
```

- determining if there are any elements left to check
- handling the comparison (through a function or a macro)

```
int binsearch(int list[],int searchnum,
                      int left,int right) {
  int middle;
  while(left <= right) {</pre>
     middle = (left + right) / 2;
     switch(COMPARE(list[middle],searchnum)) {
        // COMPARE() returns -1, 0, or 1
        case -1: left = middle + 1;
                break:
        case 0: return middle:
        case 1: right = middle - 1;
  return -1;
```





Recursive Algorithms

direct recursion

call themselves

indirect recursion

- call other function that invoke the calling function again
 recursive mechanism
 - extremely powerful
 - o allows us to express a complex process in very clear terms

any function that we can write using assignment, if-else, and while statements can be written recursively

Recursive Algorithms: Binary Search

transform iterative version of a binary search into a recursive one

- o establish boundary condition that terminate the recursive call
 - success: list[middle]=searchnum
 - 2. failure: left & right indices cross
- implement the recursive calls so that each call brings us one step closer to a solution

Recursive Algorithms: Binary Search

```
int binsearch(int list[],int searchnum,int left,int right) {
  int middle;
  if(left <= right) {
    middle=(left+right)/2;
    switch(COMPARE(list[middle], searchnum)) {
      case -1 : return
         binsearch(list,searchnum,middle+1,right);
      case 0 : return middle
      case 1 : return
         binsearch(list,searchnum,left,middle-1);
    }
}
return -1;
}</pre>
```



Recursive Algorithms: Permutations

given a set of n(1) elements

- print out all possible permutations of this seteg) if set a,b,c is given,
 - then set of permutations is(a,b,c), (a,c,b), (b,a,c), (b,c,a), (c,a,b), (c,b,a)

Recursive Algorithms: Permutations

if look at the set a,b,c,d, the set of permutations are

- 1. a followed by all permutations of (b,c,d)
- 2. b followed by all permutations of (a,c,d)
- 3. c followed by all permutations of (a,b,d)
- 4. d followed by all permutations of (a,b,c)

"followed by all permutations": clue to the recursive solution

Recursive Algorithms: Permutations

```
void perm(char *list,int i,int n) {
  int j, temp;
  if(i==n) {
     for(j=0;j<=n;j++)
     printf("%c", list[j]);
     printf(" ");
  else {
     for(j=i;j<=n;j++) {
        SWAP(list[i],list[j],temp);
        perm(list, i+1, n);
        SWAP(list[i],list[j],temp);
```

initial function call is

o perm(list,o,n-1);

recursively generates permutations

○ until i=n



DATA ABSTRACTION

Data Abstraction: Data Type

definition

- a collection of objects and
- a set of operations that act on those objects
- basic data type
 - o char, int, float, double
- omposite data type
 - o array, structure
- user-defined data type
- pointer data type

Data Abstraction: Abstract Data Type (ADT)

definition

- data type that is organized in such a way that
- the specification of the objects and the specification of the operations on the objects is separated from
- the representation of the objects and the implementation of the operations

Data Abstraction

specification

- names of every function
- type of its arguments
- type of its result
- description of what the function does

classify the function of data type

- creator/constructor
- transformers
- observers/reporters

Data Abstraction: Abstract Data Type

```
structure Natural_Number(Nat_No) is
  objects: an ordered subrange of the integers
          starting at zero and ending at the max.
          integer on the computer
  functions: for all x, y in Natural_Number;
          TRUE, FALSE in Boolean,
          and where +. -. <. and == are
          the usual integer operations.
  Nat No Zero() ::= 0
  Nat No Add(x.v) ::= if ((x+v) \le INT MAX) return x+v
     else return INT MAX
  Nat No Subtract(x,v) ::= if (x<v) return 0
     else return x-v
  Boolean Equal(x,y) ::= if (x==y) return TRUE
     else return FALSE
  Nat_No Successor(x) ::= if (x==INT_MAX) return x
     else return x+1
  Boolean Is_Zero(x) ::= if (x) return FALSE
     else return TRUE
end Natural Number
```



Data Abstraction

objects and **functions** are two main sections in the definition function Zero is a **constructor** function Add, Substractor, Successor are **transformers** function Is_Zero and Equal are **reporters**



PERFORMANCE ANALYSIS

Performance Analysis

Performance evaluation

- performance analysis: machine independent complexity theory
- O performance measurement: machine dependent

space complexity

- the amount of memory that it needs to run to completion time complexity
 - $\, \bigcirc \,$ the amount of computer time that it needs to run to completion

Performance Analysis: Space Complexity

fixed space requirements

- don't depend on the number and size of the program's inputs and outputs
- o eg) instruction space

variable space requirement

 the space needed by *structured variable* whose size depends on the particular instance, I, of the problem being solved

Performance Analysis: Space Complexity

total space requirement S(P)

$$S(P) = c + Sp(I)$$

- c : constant representing the fixed space requirements
- \bigcirc Sp(I): function of some characteristics of the instance I

Performance Analysis: Space Complexity

```
float abc(float a, float b, float c) {
  return a+b+b*c+(a+b-c)/(a+b)+4.00;
}
```

- input three simple variables
- ouput a simple variable
- \bigcirc fixed space requirements only Sabc(I) = 0

Iterative Version

```
float sum(float list[], int n) {
   float tempsum = 0;
   int i;
   for(i = 0; i < n; i++)
        tempsum += list[i];
       return tempsum;
}</pre>
```

- output a simple variable
- input an array variable

Pascal pass arrays by value

- entire array is copied into temporary storage before the function is executed
- \bigcirc Ssum(I) = Ssum(n) = n

C pass arrays by pointer

- passing the address of the first element of the array
- \bigcirc Ssum(n) = 0

Recursive Version

```
float rsum(float list[],int n) {
  if(n) return rsum(list,n-1) + list[n-1];
  return 0;
}
```

handled recursively

- compiler must save
 - the parameters
 - the local variables
 - the return address
- for each recursive call

space needed for one recursive call

- number of bytes required for the two parameters and the return address
- 6 bytes needed on 80386
 - o 2 bytes for pointer list[]
 - o 2 bytes for integer n
 - o 2 bytes for return address

assume array has n=MAX_SIZE numbers, total variable space Srsum(MAX_SIZE)

 \bigcirc Srsum(MAX_SIZE) = 6 * MAX_SIZE

PERFORMANCE ANALYSIS: TIME

COMPLEXITY

The time T(P), taken by a program P,

- o is the sum of its compile time and its run(or execution) time
- We really concerned only with the program's execution time, Tp
 count the number of operations the program performs
 - give a machine-independent estimation

Iterative summing of a list of numbers

```
float sum(float list[], int n) {
  float tempsum=0;
  count++; /* for assignment */
  int i;
  for(i = 0; i < n; i++) {
     count++; /* for the for loop */
     tempsum += list[i];
     count++; /*for assignment*/
  }
  count++; /* last execution of for */
  count++; /* for return */
  return tempsum;
}</pre>
```



eliminate most of the program statements from Program to obtain a simpler program that **computes the same value for count**

```
float sum(float list[], int n) {
   float tempsum=0;
   int i;
   for(i = 0; i < n; i++)
        count+=2;
   count += 3;
   return tempsum;
}</pre>
```



Recursive summing of a list of numbers

```
float rsum(float list[], int n) {
   count++;
   if(n) {
      count++;
      return rsum(list,n-1)+list[n-1];
   }
   count++;
   return 0;
}
```



when n=0 only the if conditional and the second return statement are executed (termination condition)

- \bigcirc step count for n = 0:2
- \bigcirc each step count for n > 0:2

total step count for function : 2n + 2

- O less step count than iterative version, but
- take more time than those of the iterative version

Matrix Addition determine the step count for a function that adds two-dimensional arrays(rows and cols)



apply step counts to add function



combine counts

```
initially count = 0;
total step count on termination : 2 \cdot rows \cdot cols + 2 \cdot rows + 1;
```

Tabular Method

construct a step count table

- 1. first determine the step count for each statement
 - steps/execution(s/e)
- next figure out the number of times that each statement is executed
 - frequency
- 3. total steps for each statement
 - (total steps)=(s/e)* frequency)

Iterative function to sum a list of numbers

Statement	s/e	Frequency	Total steps
float sum(float list[],int n) {	0	0	0
float tempsum=0;	1	1	1
int i;	0	0	0
for(i=0;i< n;i++)	1	n+1	n+1
tempsum+=list[i];	1	n	n
return tempsum;	1	1	1
}	0	0	0
total			2n+3

Figure: step count table

Recursive function to sum a list of numbers

Statement	s/e	Frequency	Total steps
float rsum(float list[],int n) {	0	0	0
if(n)	1	n+1	n+1
return rsum(list,n-1)+list[n-1];	1	n	n
return 0;	1	1	1
}	0	0	0
total			2n+2

Figure: step count table for recursive summing function

Matrix addition

Statement	s/e	Frequency	Total steps
void add(int a[][M_SIZE] ···) {	0	0	0
int i,j;	0	0	0
for(i=0;i <rows;i++)< td=""><td>1</td><td>rows+1</td><td>rows+1</td></rows;i++)<>	1	rows+1	rows+1
for(j=0;j < cols;j++)	1	rows· (cols+1)	rows·cols+rows
c[i][j] = a[i][j] + b[i][j];	1	rows-cols	rows·cols
}	0	0	0
total			2·rows·cols+2·rows+1

Figure: step count table for matrix addition

factors: time complexity

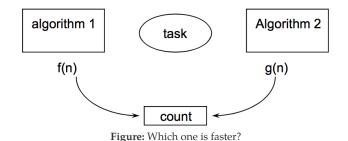
- input size
 - depends on size of input(n): T(n) = ?
- 2. input form
 - depends on different possible input formats
 - o average case: A(n) = ?
 - \circ worst case: W(n) = ?
 - concerns mostly for "worst case"
 - worst case gives "upper bound"
 - o exist different algorithm for the same task
 - o which one is faster?

TOTIC NOTATION

PERFORMANCE ANALYSIS: ASYMP-

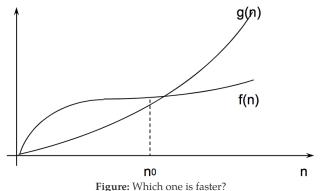
comparing time complexities

- exist different algorithms for the same task
- which one is faster ?



Big "OH"

- \bigcirc **def** f(n) = O(g(n))
 - iff there exist positive constants c and no such that
 - $\circ \ f(n) \geq c {\cdot} g(n) \ \text{for all } n, \, n \geq no$





rigure: which one is fast

$$f(n) = 25 \cdot n, g(n) = 1/3 \cdot n^2$$

$$\bigcirc$$
 25·n = O(n²/3) if let c = 1

n	$f(n) = 25 \cdot n$	$g(n) = n^2 / 3$
1	25	1/3
2	50	4/3
•	•	•
•	•	•
•	•	
75	1875	1875

Figure: Which one is faster?

$$|25 \cdot n| 1 \cdot |n^2/3|$$
 for all $n \ge 75$



$$f(n) = O(g(n))$$

- \bigcirc g(n) is an upper bound on the value of f(n) for all n, n \ge no
- but, doesn't say anything about how good this bound is
 - $n = O(n^2), n = O(n^{2.5})$
 - $n = O(n^3), n = O(2^n)$
- \bigcirc g(n) should be as small a function of n as one can come up with for which f(n)= O(g(n))

$$f(n) = O(g(n)) \neq O(g(n)) = f(n)$$

```
theorem) if f(n) = a_m n^m + ... + a_1 n + a_0, then f(n) = O(nm)

proof) f(n)|a_k|n^k + |a_{k-1}|n^{k-1} + ... + |a_1| \cdot n + |a_0|

= |a_k| + |a_{k-1}|/n + ... + |a_1|/n^{k-1} + |a_0|/n^k \cdot n^k

\leq |a_k| + |a_{k-1}| + ... + |a_1| + |a_0| \cdot n^k

= c \cdot n^k (c = |a_k| + |a_{k-1}| + ... + |a_1| + |a_0|) = O(n^k)
```



Omega def) $f(n) = \Omega(g(n))$

- iff there exist positive constants c and no such that f(n) c· g(n) for all n, $n \ge n^0$
- \bigcirc g(n) is a lower bound on the value of f(n) for all n, n \ge no
- should be as large a function of n as possible

theorem) if
$$f(n) = a_m n^m + ... + a_1 n + a_0 a n d a m > 0$$
, then $f(n) = \Omega(n^m)$

Theta def) $f(n) = \Theta(g(n))$

- \bigcirc iff there exist positive constants c^1 , c^2 , and n^0 such that
- $c^1 \cdot g(n) \le f(n) \le c^2 \cdot g(n)$ for all $n, n \ge n^0$
- omore precise than both the "big oh" and omega notations
- \bigcirc g(n) is both an upper and lower bound on f(n)

Complexity of matrix addition

Statement	Asymptotic complexity
void add(int a[][M_SIZE] ···) {	0
int i, j;	0
for($i = 0$; $i < rows$; $i++$)	$\Theta(\text{rows})$
for(j = 0; j < cols; j++)	Θ(rows·cols)
c[i][j] = a[i][j] + b[i][j];	Θ(rows·cols)
}	0
Total	Θ(rows·cols)

Figure: time complexity of matrix addition

PERFORMANCE ANALYSIS: PRACTI-

CAL COMPLEXITIES

```
O(1): constant
O(log2n): logarithmic
O(n): linear
                                polynomial
O(n·log2n): log-linear
                                   time
O(n<sup>2</sup>): quadratic
O(n^3): cubic
O(2<sup>n</sup>): exponential
O(n!): factorial
                                exponential
                                   time
```

Figure: Class of time complexities

polynomial time

- tractable problem exponential time
- intractable (hard) problem

eg)

- sequential search
- binary search
- insertion sort
- heap sort
- satisfiablity problem
- testing serializable scheduling

instance characteristic n							
time	name	1	2	4	8	16	32
1	constant	1	1	1	1	1	1
log n	logarithmic	0	1	2	3	4	5
n	linear	1	2	4	8	16	32
n log n	log linear	0	2	8	24	64	160
n ²	quadratic	1	4	16	64	256	1024
n^3	cubic	1	8	64	512	4096	32768
2n	exponential	2	4	16	256	655536	4294967296
n!	factorial	1	2	24	40326	20922789888000	26313×10 ³³

Figure: function value

If a program needs 2^n steps for execution

- n=40: number of steps = 1.1*1012 in computer systems
 1 billion steps/sec 18.3 min
- n=50 13 days
- n=60 310.56 years
- n=100 4*1013 years

If a program needs n^{10} steps for execution

- n=10 10 sec
- n=100 3171 years