

Non-parametric density Estimation.

Parametric estimation: Functional form assumed to the class-conditional density.

In Non-Parametric methods, no need to assume any functional form.

The basic idea: suppose $x \in \mathbb{R}$.

Given $x_i, i = 1, \dots, n$.

Problem: Estimate the density function $f(x)$.
with no form for f known.

One possible solution: Learn a piece-wise constant approximation to f .

(71).

Divide the x-axis into small intervals
& build a function that is constant in
each of these intervals.

i.e, $f(x) = k$ over an interval $[a, b]$

then by definition of PDF, we have

$$\begin{aligned} P[a \leq x \leq b] &= k(b-a) \\ &= f(x) \cdot (b-a) \end{aligned}$$

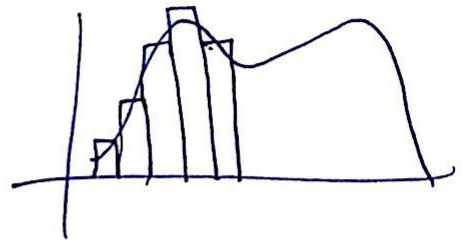
Also, this probability is well approximated
by the mass [fraction of datapoints] falling
in that intervals.

$$\therefore f(x) = \frac{P[a \leq x \leq b]}{b-a}$$

This is the basic idea of the histogram -
approximation.

(72).

The approximation can be made better by having finer intervals.



This requires more memory.

Also may lead to many empty bins, more-so in high-dimensions.

This may be resolved by erecting bins only around training samples.

Generalization of the histogram idea:

Let $B(x)$ be a region [eg: ball of some radius] around x .

$$\text{Let } \rho = \int_{B(x)} f(x') dx'$$

Now if $f(x)$ is nearly constant over $B(x)$

then $\rho = f(x) v$, where v is the volume of

$$B(x). \Rightarrow f(x) = \frac{\rho}{v}.$$

(73).

Question: How to find out ρ & v ?

We have $X_i \sim f(x)$, IID. $i=1, \dots, n$

Suppose out of n IID samples, K samples fall in $B(x)$.

Then, K forms a binomial distribution with parameter n & ρ .

$$P(K) = n C_K \rho^K (1-\rho)^{n-K}$$

We also have that for very large n , binomial distribution sharply peaks at its mean $(n\rho)$.

$$\therefore K \approx n\rho \text{ or } \rho \approx \frac{K}{n}$$

$$\Rightarrow f(x) \approx \frac{\rho}{v} \approx \frac{K}{n v}$$

This is the basic idea of non-parametric density estimation.

At any x , take a small volume V around $x \in \mathbb{R}$. Count the no of data points falling in that region. This gives $\hat{f}(x)$.

(74)

Choice of V affects the quality of approximation.

i.e., for $f \approx f(x)V$ to be true, we need V to be small.

But if V is very small, k may be zero most of the time.

\therefore There is a trade-off b/w these two for the choice of V .

Let V_n - volume with n eqs.

$f_n(x)$ & k_n be the corresponding values.

$$f_n(x) = \frac{k_n/n}{V_n}$$

X

if $f_n \rightarrow f$, as $n \rightarrow \infty$, we must have

$$V_n \rightarrow 0, \quad \frac{k_n}{n} \rightarrow 0 \rightarrow \left[\begin{array}{l} \text{if } f(x) \neq 0, \\ \text{then } k_n \rightarrow \infty \end{array} \right]$$

\downarrow

to get correct estimates

also $\frac{k_n}{n} \rightarrow 0$
to get proper estimates

(75). 7

Depending upon the way histograms are constructed there are two approaches.

1) Fix v & calculate k - Parzen window kernel density

2) Fix k & calculate v - knn approach for density estimation.

We'll look at both one by one.

Parzen-window method.

Define a fn $\phi : \mathbb{R}^d \rightarrow \mathbb{R}$ by

$$\phi(u) = 1 \quad \text{if } |u_i| \leq 0.5, i=1, \dots, d$$
$$= 0 \quad \text{otherwise}$$

$$u = (u_1, u_2, \dots, u_d)^T$$

$\phi(u)$ is a unit hypercube in \mathbb{R}^d ,
centered at origin. $\phi(u) = \phi(-u)$.

$\phi\left(\frac{u-u_0}{h}\right)$ - Hypercube of side h ,
centered at u_0 .

As usual let $D = \{x_1, \dots, x_n\}$ be the
IID data samples.

Then, $\forall x$, $\phi\left(\frac{x-x_i}{h}\right) = 1$ iff x_i falls
in a hypercube of side h centered at x .

\therefore number of datapoints falling in a
hypercube of side h centered at x is

$$k = \sum_{i=1}^n \phi\left(\frac{x-x_i}{h}\right).$$

Also, volume of the hypercube of side h in
 \mathbb{R}^d is $\underline{h^d}$.

(77)

\therefore The estimated density function at x of g could be written as

$$\hat{f}(x) = \frac{1}{n} \sum_{i=1}^n \frac{1}{h^d} \phi \left(\frac{x - x_i}{h} \right)$$

The above is called the parzen window estimate.

\therefore If we store all x_i , we can calculate $f(x)$ at any x .

The value of h determines the size of the volume element [and thus the quality of the estimate]

This choice of ϕ , however, leads to abrupt discontinuities as in the case of histogram.

Thus, one might use 'smoother' versions of ϕ s.t

$$\phi(u) \geq 0 \quad \forall u \quad \& \quad \int_{\mathbb{R}^d} \phi(u) du = 1.$$

if the above happens, then

$$\hat{f}(x) = \frac{1}{n} \sum_{i=1}^n \frac{1}{V} \phi\left(\frac{x - x_i}{h}\right)$$

would be a density $\Rightarrow \hat{f}(x) \geq 0 \quad \& \quad \int \hat{f}(x) = 1$

ϕ is often called the kernel & hence the name kernel density estimation.

One popular choice of ϕ ,

$$\phi(u) = \left(\frac{1}{\sqrt{2\pi}}\right)^d \exp\left[-\frac{1}{2} \|u\|^2\right]$$

d-dim Gaussian: For this too,

$$\underline{V = h^d.}$$

(7a)

$$\text{Now, } \hat{f}(x) = \frac{1}{n} \sum_{i=1}^n \left(\frac{1}{h\sqrt{2\pi}} \right)^d \exp \left[-\frac{\|x - x_i\|^2}{2h^2} \right]$$

Essentially, erecting a Gaussian centered around each data point & representing the unknown density as a mixture of these Gaussian. This gives a smoother estimate

One can show that a kernel density estimate is consistent.

knn-approach.

~~Now,~~

Kernel density estimates are essentially mixture densities

$$\hat{f}(x) = \frac{1}{n} \sum_{i=1}^n \frac{1}{V} \phi \left(\frac{x - x_i}{h} \right)$$

We end up storing all the training samples.

(80).

Consider a 2-class problem with n_1 & n_2 samples in each class.

Thus, with a gaussian kernel estimate at every test x , we need to compute n Gaussians - Computationally expensive.

Also, the 'size' of the volume element h is a critical hyperparameter.

In an alternative approach (knn) we do not choose h (volume element).

Instead we choose K & find V that encloses K nearest neighbours of x .

$$\text{Then } \hat{f}(x) = \frac{K}{nV}.$$

(81).

This takes us to the end of Density estimation and also B. posterior prob based classification schemes..

Some unsupervised techniques.

k-nearest neighbour classifier.

Consider a 2-class problem with priors P_i & class conditionals f_i , $i=0,1$.

$f(x) = P_0 f_0(x) + P_1 f_1(x)$ is the overall density of the feature.

Suppose there are n data samples with n_i being from class $i=0,1$.

Let's do a k-nn estimation of f . [as well as f_i]

Let there are k_i samples of class i in this volume.