

# **ENGG5781 Matrix Analysis and Computations**

## **Lecture 0: Overview**

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# Course Information

# General Information

- Instructor: Wing-Kin Ma
  - office: SHB 323
  - e-mail: [wkma@ee.cuhk.edu.hk](mailto:wkma@ee.cuhk.edu.hk)
- Lecture hours and venue:
  - Monday 11:30am–12:15pm, Yasumoto International Academic Park LT7
  - Tuesday 4:30pm–6:15pm, Mong Man Wai Building Room 710
- Class website: <http://www.ee.cuhk.edu.hk/~wkma/engg5781>

# Course Contents

- This is a foundation course on matrix analysis and computations, which are widely used in many different fields, e.g.,
  - machine learning, computer vision,
  - systems and control, signal and image processing, communications, networks,
  - optimization, and many more...
- **Aim:** covers matrix analysis and computations at an advanced or research level.
- **Scope:**
  - basic matrix concepts, subspace, norms,
  - linear least squares
  - eigendecomposition, singular value decomposition, positive semidefinite matrices,
  - linear system of equations, LU decomposition, Cholesky decomposition
  - pseudo-inverse, QR decomposition
  - (advanced) tensor decomposition, advanced matrix calculus, compressive sensing, structured matrix factorization

## Learning Resources

- Notes by the instructor will be provided.
- Recommended readings:
  - Gene H. Golub and Charles F. van Loan, *Matrix Computations* (Fourth Edition), John Hopkins University Press, 2013.
  - Roger A. Horn and Charles R. Johnson, *Matrix Analysis* (Second Edition), Cambridge University Press, 2012.
  - Jan R. Magnus and Heinz Neudecker, *Matrix Differential Calculus with Applications in Statistics and Econometrics* (Third Edition), John Wiley and Sons, New York, 2007.
  - Giuseppe Calafiore and Laurent El Ghaoui, *Optimization Models*, Cambridge University Press, 2014.
  - ECE 712 Course Notes by Prof. Jim Reilly, McMaster University, Canada (friendly notes for engineers)  
[http://www.ece.mcmaster.ca/faculty/reilly/ece712/course\\_notes.htm](http://www.ece.mcmaster.ca/faculty/reilly/ece712/course_notes.htm)

# Assessment and Academic Honesty

- Assessment:
  - Assignments: 60%
    - \* may contain MATLAB questions
    - \* where to submit: I will put a submission box outside my office, SHB 323
    - \* no late submissions would be accepted, except for exceptional cases.
  - Final examination: 40%
- Academic honesty: Students are strongly advised to read
  - our homework guideline: [http://www.ee.cuhk.edu.hk/~wkma/engg5781/hw/hw\\_guidelines.pdf](http://www.ee.cuhk.edu.hk/~wkma/engg5781/hw/hw_guidelines.pdf)
  - the University's guideline on academic honesty: <http://www.cuhk.edu.hk/policy/academichonesty>

You will be assumed to understand the aspects described therein.

## Additional Notice

- Sitting in is welcome, and please send me your e-mail address to keep you updated with the course.
- Course helpers whom you can consult:
  - Mingjie Shao, [mjshao@ee.cuhk.edu.hk](mailto:mjshao@ee.cuhk.edu.hk)
  - Ryan Wu, [rywu@ee.cuhk.edu.hk](mailto:rywu@ee.cuhk.edu.hk)
  - Qiong Wu, [qw@ee.cuhk.edu.hk](mailto:qw@ee.cuhk.edu.hk)
- You can also get consultation from me; send me an email for an appointment
- Do regularly check your CUHK Link e-mail address; this is the only way we can reach you
- CUHK Blackboard will be used to announce scores and for online homework submission

# A Glimpse of Topics



# Least Squares (LS)

- **Problem:** given  $\mathbf{A} \in \mathbb{R}^{m \times n}$ ,  $\mathbf{y} \in \mathbb{R}^n$ , solve

$$\min_{\mathbf{x} \in \mathbb{R}^n} \|\mathbf{y} - \mathbf{A}\mathbf{x}\|_2^2,$$

where  $\|\cdot\|_2$  is the Euclidean norm; i.e.,  $\|\mathbf{x}\|_2 = \sqrt{\sum_{i=1}^n |x_i|^2}$ .

- widely used in science, engineering, and mathematics
- assuming a tall and full-rank  $\mathbf{A}$ , the LS solution is uniquely given by

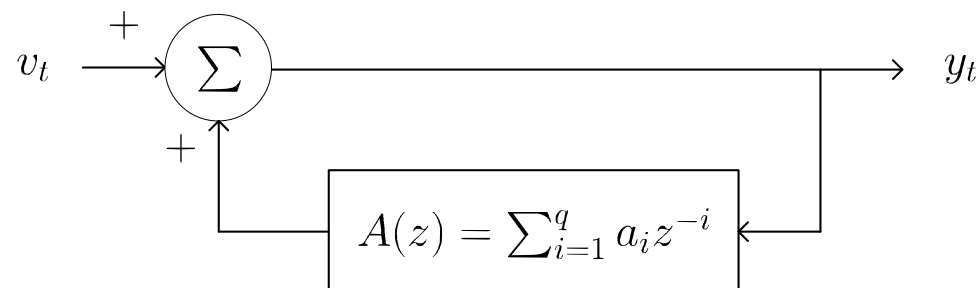
$$\mathbf{x}_{\text{LS}} = (\mathbf{A}^T \mathbf{A})^{-1} \mathbf{A}^T \mathbf{y}.$$

## Application Example: Linear Prediction (LP)

- let  $\{y_t\}_{t \geq 0}$  be a time series.
- **Model** (autoregressive (AR) model):

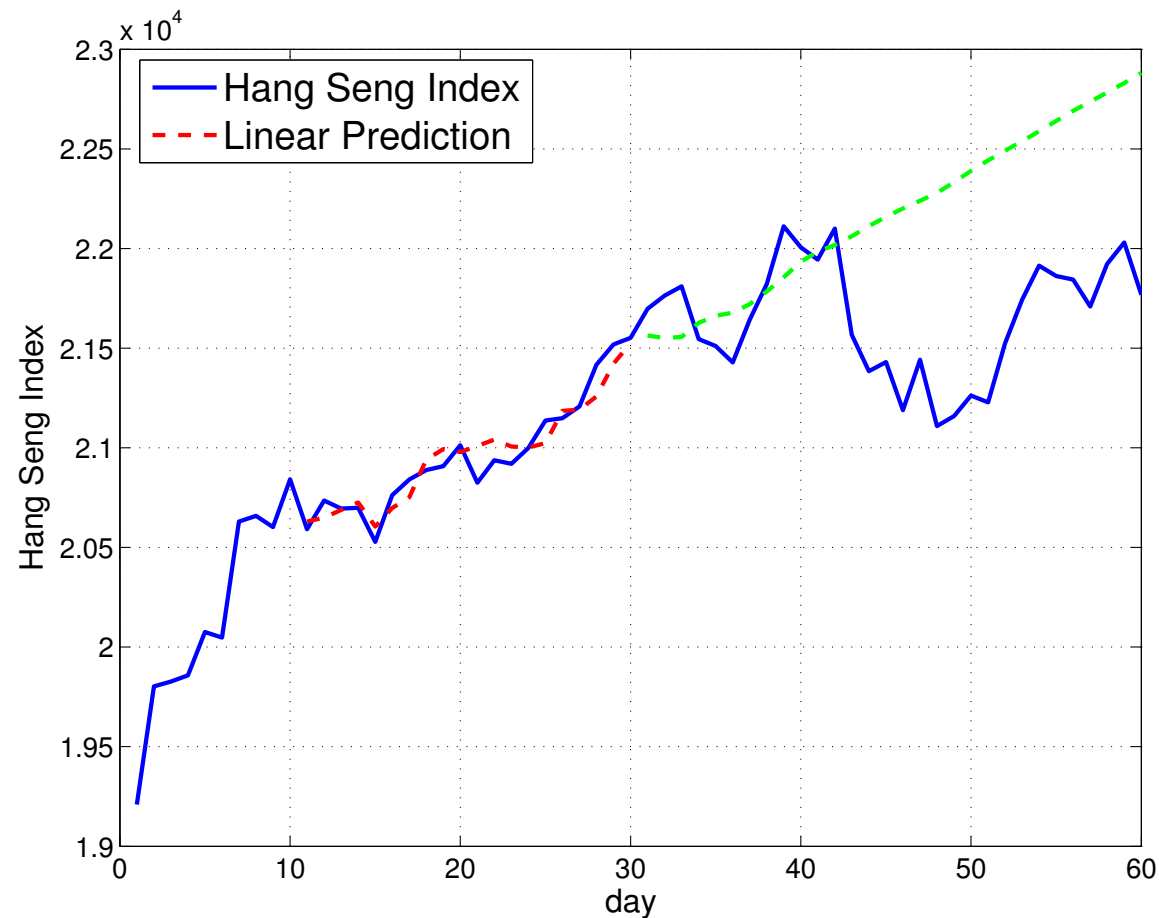
$$y_t = a_1 y_{t-1} + a_2 y_{t-2} + \cdots + a_q y_{t-q} + v_t, \quad t = 0, 1, 2, \dots$$

for some coefficients  $\{a_i\}_{i=1}^q$ , where  $v_t$  is noise or modeling error.



- **Problem:** estimate  $\{a_i\}_{i=1}^q$  from  $\{y_t\}_{t \geq 0}$ ; can be formulated as LS
- **Applications:** time-series prediction, speech analysis and coding, spectral estimation...

# A Toy Demo: Predicting Hang Seng Index

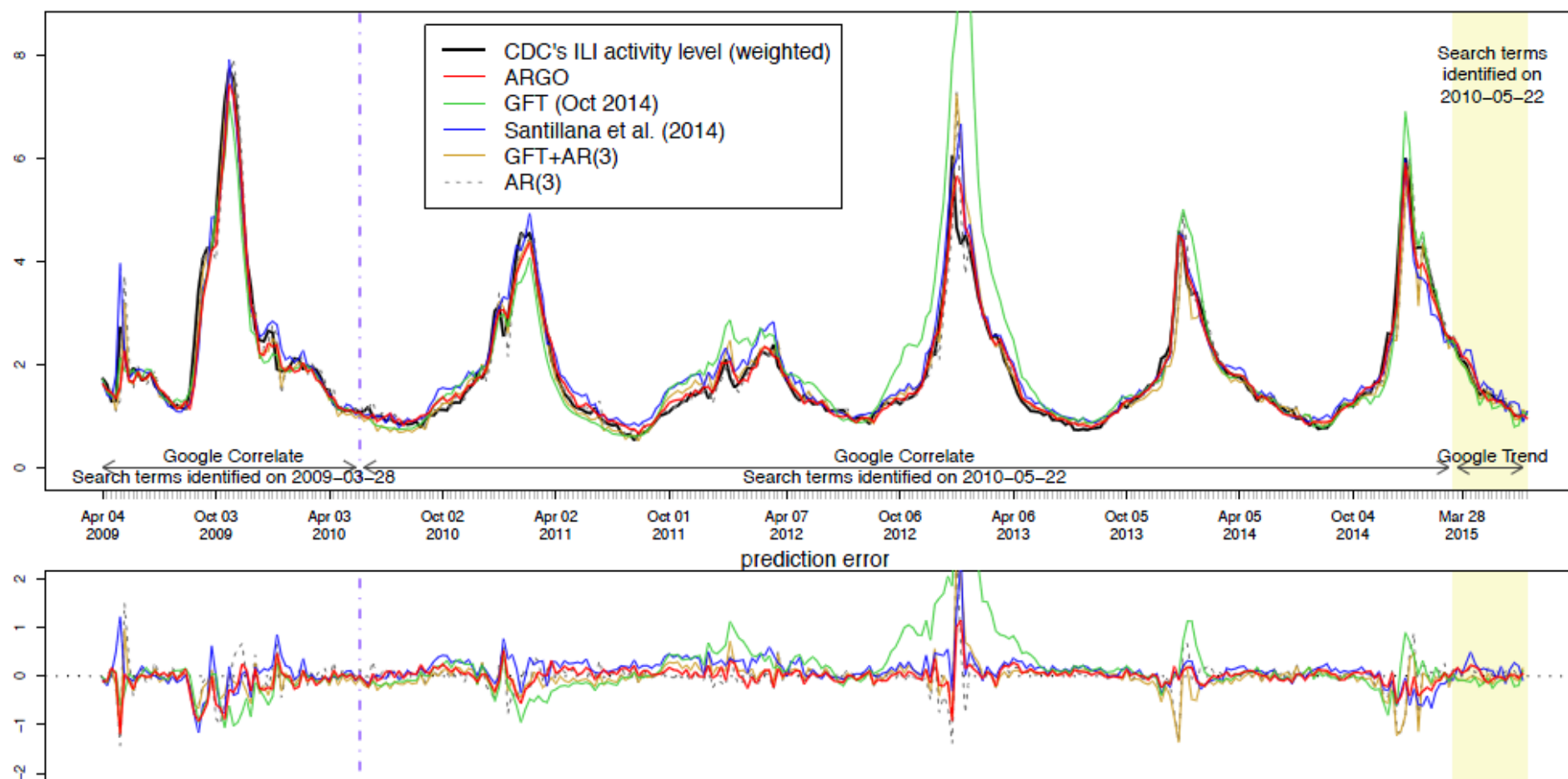


blue— Hang Seng Index during a certain time period.

red— training phase; the line is  $\sum_{i=1}^q a_i y_{t-i}$ ;  $\mathbf{a}$  is obtained by LS;  $q = 10$ .

green— prediction phase; the line is  $\hat{y}_t = \sum_{i=1}^q a_i \hat{y}_{t-i}$ ; the same  $\mathbf{a}$  in the training phase.

# A Real Example: Real-Time Prediction of Flu Activity



Tracking influenza outbreaks by ARGO — a model combining the AR model and Google search data.  
Source: [\[Yang-Santillana-Kou2015\]](#).

# Eigenvalue Problem

- **Problem:** given  $\mathbf{A} \in \mathbb{R}^{n \times n}$ , find a  $\mathbf{v} \in \mathbb{R}^n$  such that

$$\mathbf{A}\mathbf{v} = \lambda\mathbf{v}, \quad \text{for some } \lambda.$$

- **Eigendecomposition:** let  $\mathbf{A} \in \mathbb{R}^{n \times n}$  be symmetric; i.e.,  $a_{ij} = a_{ji}$  for all  $i, j$ . It also admits a decomposition

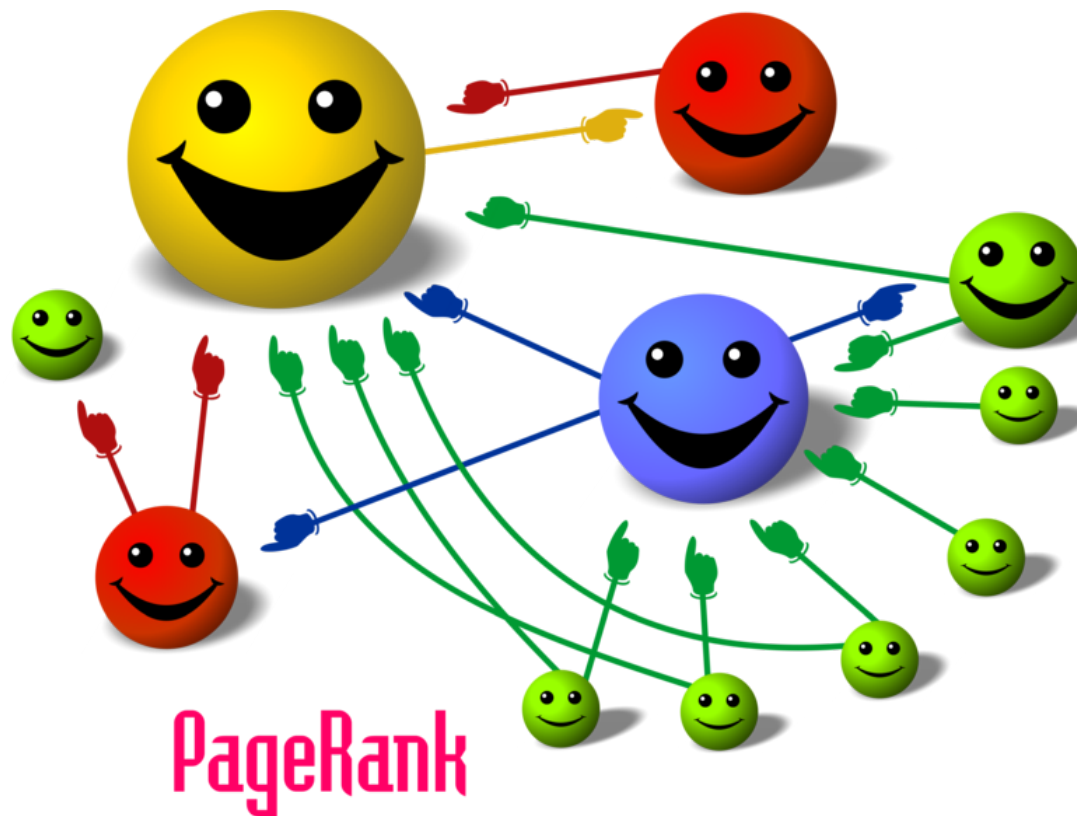
$$\mathbf{A} = \mathbf{Q}\mathbf{\Lambda}\mathbf{Q}^T,$$

where  $\mathbf{Q} \in \mathbb{R}^{n \times n}$  is orthogonal, i.e.,  $\mathbf{Q}^T\mathbf{Q} = \mathbf{I}$ ;  $\mathbf{\Lambda} = \text{Diag}(\lambda_1, \dots, \lambda_n)$

- also widely used, either as an analysis tool or as a computational tool
- no closed form in general; can be numerically computed

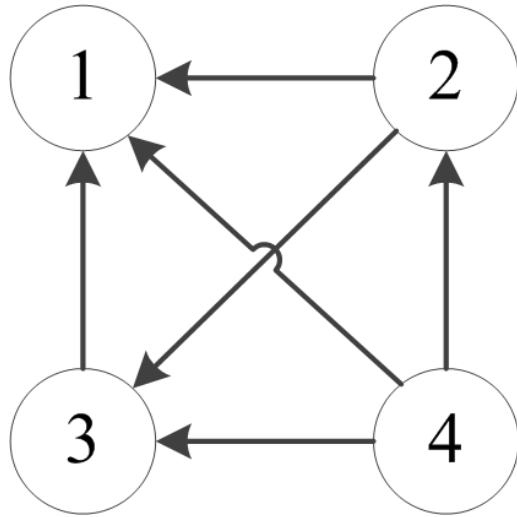
## Application Example: PageRank

- PageRank is an algorithm used by Google to rank the pages of a search result.
- the idea is to use counts of links of various pages to determine pages' importance.



Source: Wiki.

# One-Page Explanation of How PageRank Works



- Model:

$$\sum_{j \in \mathcal{L}_i} \frac{v_j}{c_j} = v_i, \quad i = 1, \dots, n,$$

where  $c_j$  is the number of outgoing links from page  $j$ ;  $\mathcal{L}_i$  is the set of pages with a link to page  $i$ ;  $v_i$  is the importance score of page  $i$ .

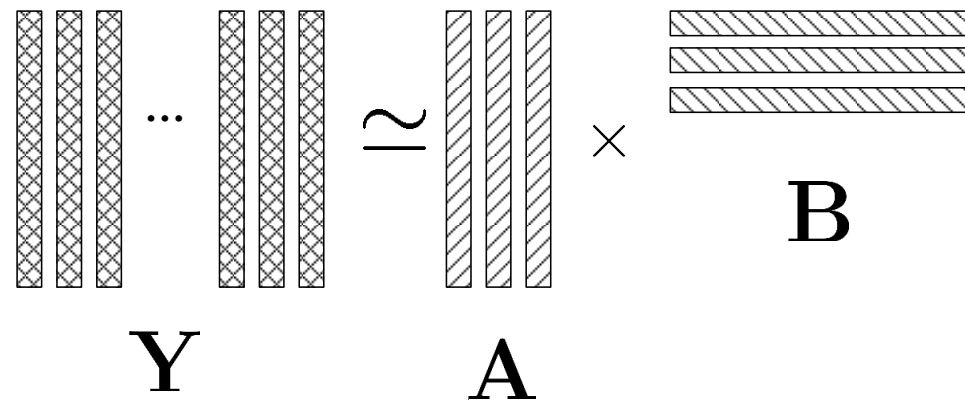
- as an example,

$$\overbrace{\begin{bmatrix} 0 & \frac{1}{2} & 1 & \frac{1}{3} \\ 0 & 0 & 0 & \frac{1}{3} \\ 0 & \frac{1}{2} & 0 & \frac{1}{3} \\ 0 & 0 & 0 & 0 \end{bmatrix}}^{\mathbf{A}} \overbrace{\begin{bmatrix} v_1 \\ v_2 \\ v_3 \\ v_4 \end{bmatrix}}^{\mathbf{v}} = \overbrace{\begin{bmatrix} v_1 \\ v_2 \\ v_3 \\ v_4 \end{bmatrix}}^{\mathbf{v}}.$$

- finding  $\mathbf{v}$  is an eigenvalue problem—with  $n$  being of order of millions!
- further reading: [\[Bryan-Tanya2006\]](#)

# Low-Rank Matrix Approximation

- **Problem:** given  $\mathbf{Y} \in \mathbb{R}^{m \times n}$  and an integer  $r < \min\{m, n\}$ , find an  $(\mathbf{A}, \mathbf{B}) \in \mathbb{R}^{m \times r} \times \mathbb{R}^{r \times n}$  such that either  $\mathbf{Y} = \mathbf{AB}$  or  $\mathbf{Y} \approx \mathbf{AB}$ .



- **Formulation:**

$$\min_{\mathbf{A} \in \mathbb{R}^{m \times r}, \mathbf{B} \in \mathbb{R}^{r \times n}} \|\mathbf{Y} - \mathbf{AB}\|_F^2,$$

where  $\|\cdot\|_F$  is the Frobenius, or matrix Euclidean, norm.

- **Applications:** dimensionality reduction, extracting meaningful features from data, low-rank modeling, ...



## Application Example: Image Compression

- let  $\mathbf{Y} \in \mathbb{R}^{m \times n}$  be an image.

(a) original image, size=  $102 \times 1347$



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- store the low-rank factor pair  $(\mathbf{A}, \mathbf{B})$ , instead of  $\mathbf{Y}$ .

(b) truncated SVD,  $k=5$



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(c) truncated SVD,  $k=10$



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(d) truncated SVD,  $k=20$



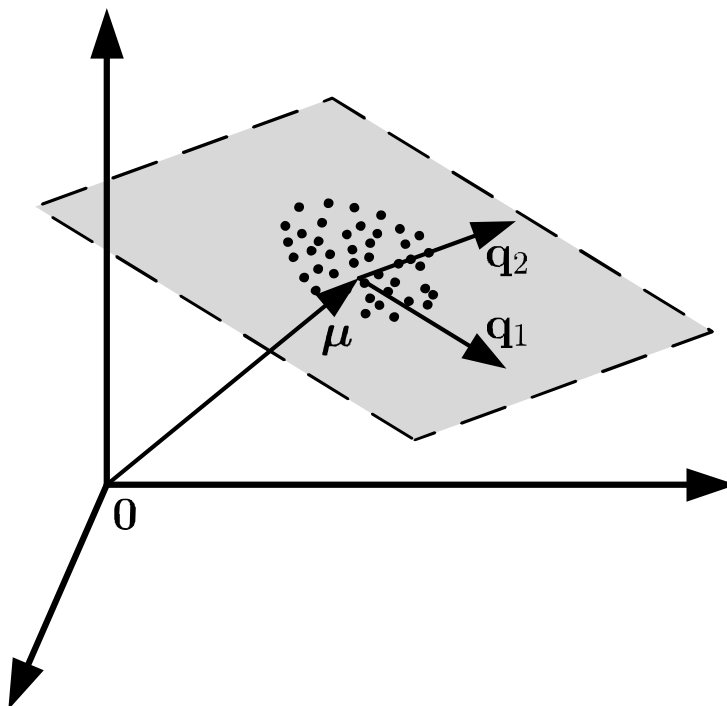
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## Application Example: Principal Component Analysis (PCA)

- **Aim:** given a set of data points  $\{\mathbf{y}_1, \mathbf{y}_2, \dots, \mathbf{y}_n\} \subset \mathbb{R}^n$  and an integer  $k < \min\{m, n\}$ , perform a low-dimensional representation

$$\mathbf{y}_i = \mathbf{Q}\mathbf{c}_i + \boldsymbol{\mu} + \mathbf{e}_i, \quad i = 1, \dots, n,$$

where  $\mathbf{Q} \in \mathbb{R}^{m \times k}$  is a basis;  $\mathbf{c}_i$ 's are coefficients;  $\boldsymbol{\mu}$  is a base;  $\mathbf{e}_i$ 's are errors

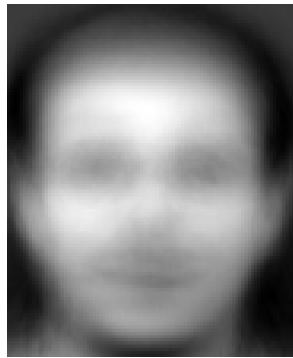


## Toy Demo: Dimensionality Reduction of a Face Image Dataset



A face image dataset. Image size =  $112 \times 92$ , number of face images = 400. Each  $\mathbf{x}_i$  is the vectorization of one face image, leading to  $m = 112 \times 92 = 10304$ ,  $n = 400$ .

# Toy Demo: Dimensionality Reduction of a Face Image Dataset



Mean face



1st principal left  
singular vector



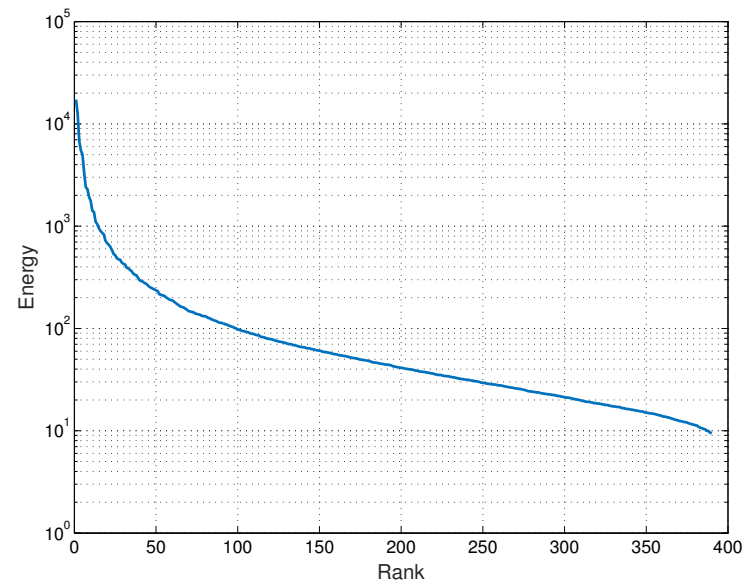
2nd principal left  
singular vector



3rd principal left  
singular vector



400th left singu-  
lar vector



Energy Concentration

# Singular Value Decomposition (SVD)

- **SVD:** Any  $\mathbf{Y} \in \mathbb{R}^{m \times n}$  can be decomposed into

$$\mathbf{Y} = \mathbf{U}\mathbf{\Sigma}\mathbf{V}^T,$$

where  $\mathbf{U} \in \mathbb{R}^{m \times m}$ ,  $\mathbf{V} \in \mathbb{R}^{n \times n}$  are orthogonal;  $\mathbf{\Sigma} \in \mathbb{R}^{m \times n}$  takes a diagonal form.

- also a widely used analysis and computational tool; can be numerically computed
- SVD can be used to solve the low-rank matrix approximation problem

$$\min_{\mathbf{A} \in \mathbb{R}^{m \times r}, \mathbf{B} \in \mathbb{R}^{r \times n}} \|\mathbf{Y} - \mathbf{AB}\|_F^2.$$

# Linear System of Equations

- **Problem:** given  $\mathbf{A} \in \mathbb{R}^{n \times n}$ ,  $\mathbf{y} \in \mathbb{R}^n$ , solve

$$\mathbf{Ax} = \mathbf{y}.$$

- **Question 1:** How to solve it?
  - don't tell me answers like  $\mathbf{x} = \text{inv}(\mathbf{A}) * \mathbf{y}$  or  $\mathbf{x} = \mathbf{A} \backslash \mathbf{y}$  on MATLAB!
  - this is about matrix computations
- **Question 2:** How to solve it when  $n$  is very large?
  - it's too slow to do the generic trick  $\mathbf{x} = \mathbf{A} \backslash \mathbf{y}$  when  $n$  is very large
  - getting better understanding of matrix computations will enable you to exploit problem structures to build efficient solvers
- **Question 3:** How sensitive is the solution  $\mathbf{x}$  when  $\mathbf{A}$  and  $\mathbf{y}$  contain errors?
  - key to system analysis, or building robust solutions

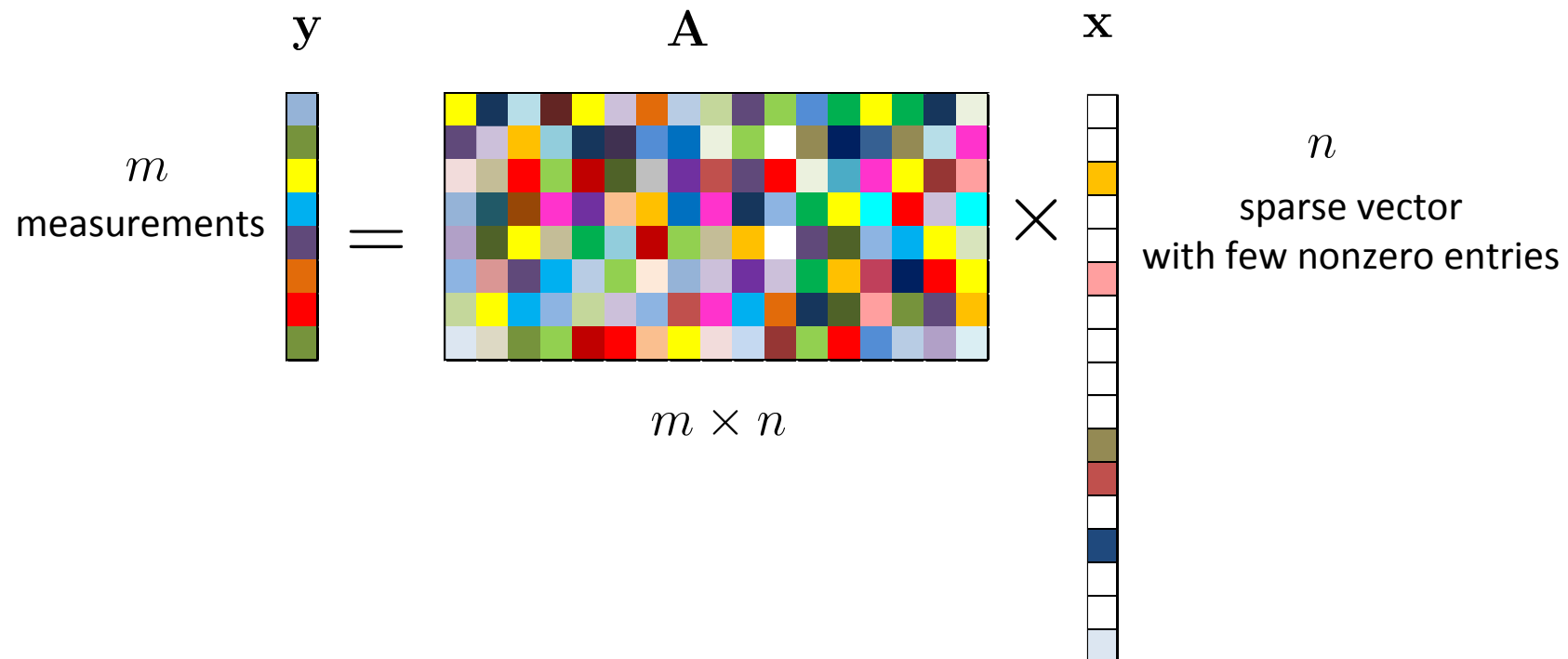
# Why Matrix Analysis and Computations is Important?

- as said, areas such as signal processing, image processing, machine learning, optimization, computer vision, control, communications, ..., use matrix operations extensively
- it helps you build the foundations for understanding “hot” topics such as
  - sparse recovery;
  - structured low-rank matrix approximation; matrix completion.

# The Sparse Recovery Problem

**Problem:** given  $\mathbf{y} \in \mathbb{R}^m$ ,  $\mathbf{A} \in \mathbb{R}^{m \times n}$ ,  $m < n$ , find a **sparsest**  $\mathbf{x} \in \mathbb{R}^n$  such that

$$\mathbf{y} = \mathbf{A}\mathbf{x}.$$



- by sparsest, we mean that  $\mathbf{x}$  should have as many zero elements as possible.

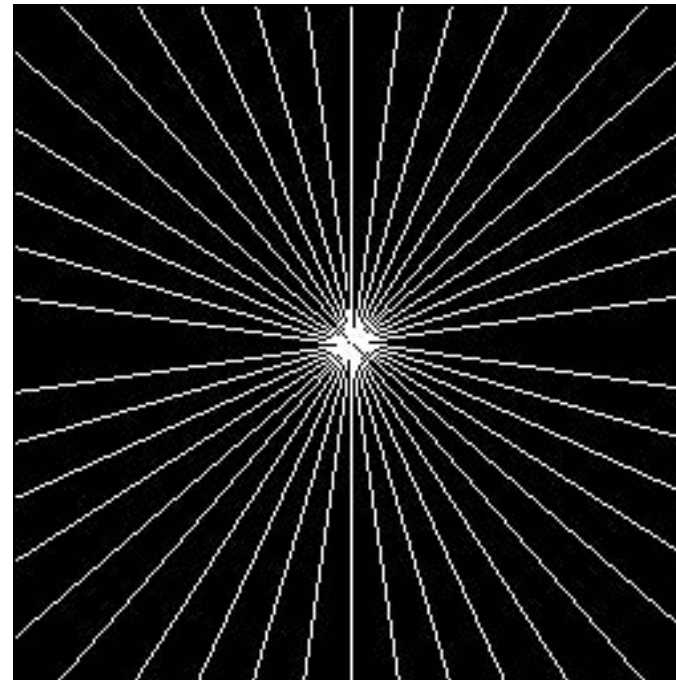


## Application: Magnetic resonance imaging (MRI)

**Problem:** MRI image reconstruction.



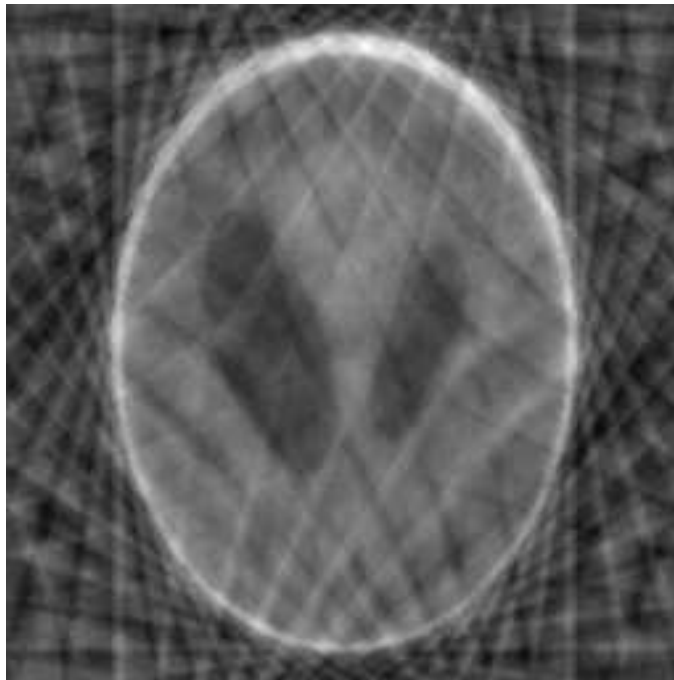
(a)



(b)

Fig. a shows the original test image. Fig. b shows the sampling region in the frequency domain. Fourier coefficients are sampled along 22 approximately radial lines. Source: [\[Candès-Romberg-Tao2006\]](#)

## Application: Magnetic resonance imaging (MRI)



(c)



(d)

Fig. c is the recovery by filling the unobserved Fourier coefficients to zero. Fig. d is the recovery by a sparse recovery solution. Source: [\[Candès-Romberg-Tao2006\]](#)

## Low-Rank Matrix Completion

- **Application:** recommendation systems
  - in 2009, Netflix awarded \$1 million to a team that performed best in recommending new movies to users based on their previous preference<sup>1</sup>.
- let  $\mathbf{Z}$  be a preference matrix, where  $z_{ij}$  records how user  $i$  likes movie  $j$ .

$$\mathbf{Z} = \begin{matrix} & \text{movies} \\ \begin{matrix} \text{users} \\ \left[ \begin{array}{cccccc} 2 & 3 & 1 & ? & ? & 5 & 5 \\ 1 & ? & 4 & 2 & ? & ? & ? \\ ? & 3 & 1 & ? & 2 & 2 & 2 \\ ? & ? & ? & 3 & ? & 1 & 5 \end{array} \right] \end{matrix} \end{matrix}$$

- some entries  $z_{ij}$  are missing, since no one watches all movies.
- $\mathbf{Z}$  is assumed to be of low rank; research shows that only a few factors affect users' preferences.
- **Aim:** guess the unknown  $z_{ij}$ 's from the known ones.

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<sup>1</sup>[www.netflixprize.com](http://www.netflixprize.com)

# Low-Rank Matrix Completion

- The 2009 Netflix Grand Prize winners used low-rank matrix approximations [Koren-Bell-Volinsky2009].
- **Formulation** (oversimplified):

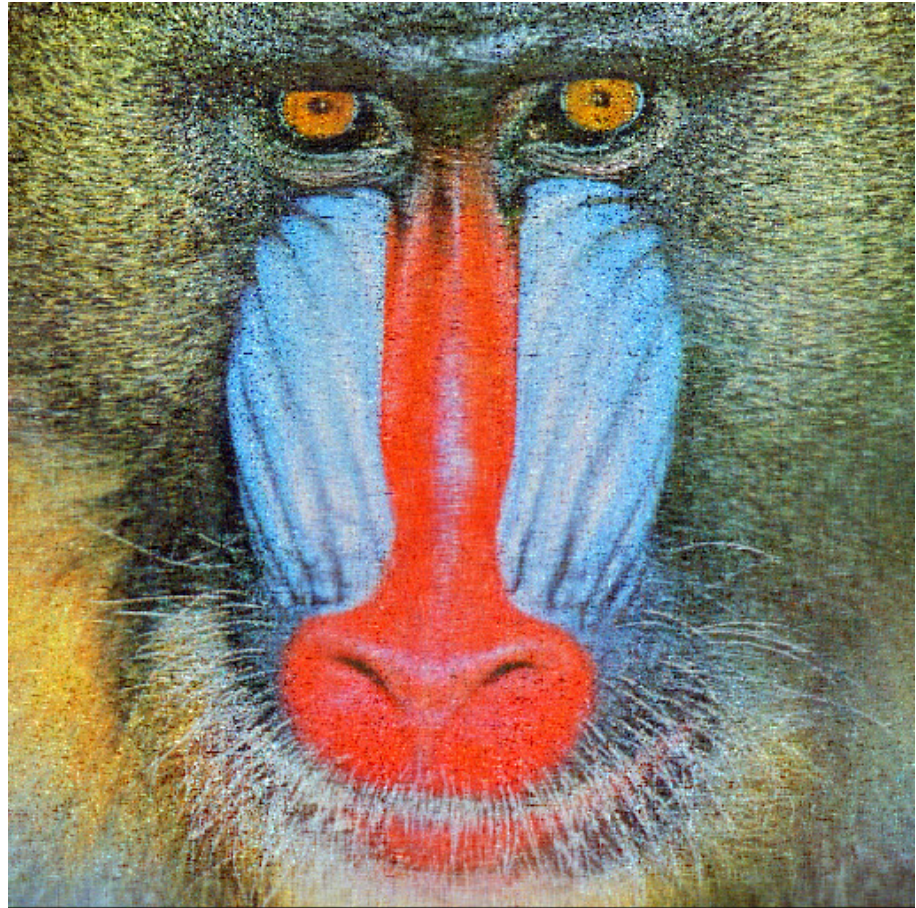
$$\min_{\mathbf{A} \in \mathbb{R}^{m \times r}, \mathbf{B} \in \mathbb{R}^{r \times n}} \sum_{(i,j) \in \Omega} |z_{ij} - [\mathbf{AB}]_{i,j}|^2$$

where  $\Omega$  is an index set that indicates the known entries of  $\mathbf{Z}$ .

- cannot be solved by SVD
- in the recommendation system application, it's a large-scale problem
- alternating LS may be used



## Toy Demonstration of Low-Rank Matrix Completion



Left: An incomplete image with 40% missing pixels. Right: the low-rank matrix completion result.  
 $r = 120$ .

# Nonnegative Matrix Factorization (NMF)

- **Aim:** we want the factors to be non-negative
- **Formulation:**

$$\min_{\mathbf{A} \in \mathbb{R}^{m \times r}, \mathbf{B} \in \mathbb{R}^{r \times n}} \|\mathbf{Y} - \mathbf{AB}\|_F^2 \quad \text{s.t. } \mathbf{A} \geq \mathbf{0}, \mathbf{B} \geq \mathbf{0},$$

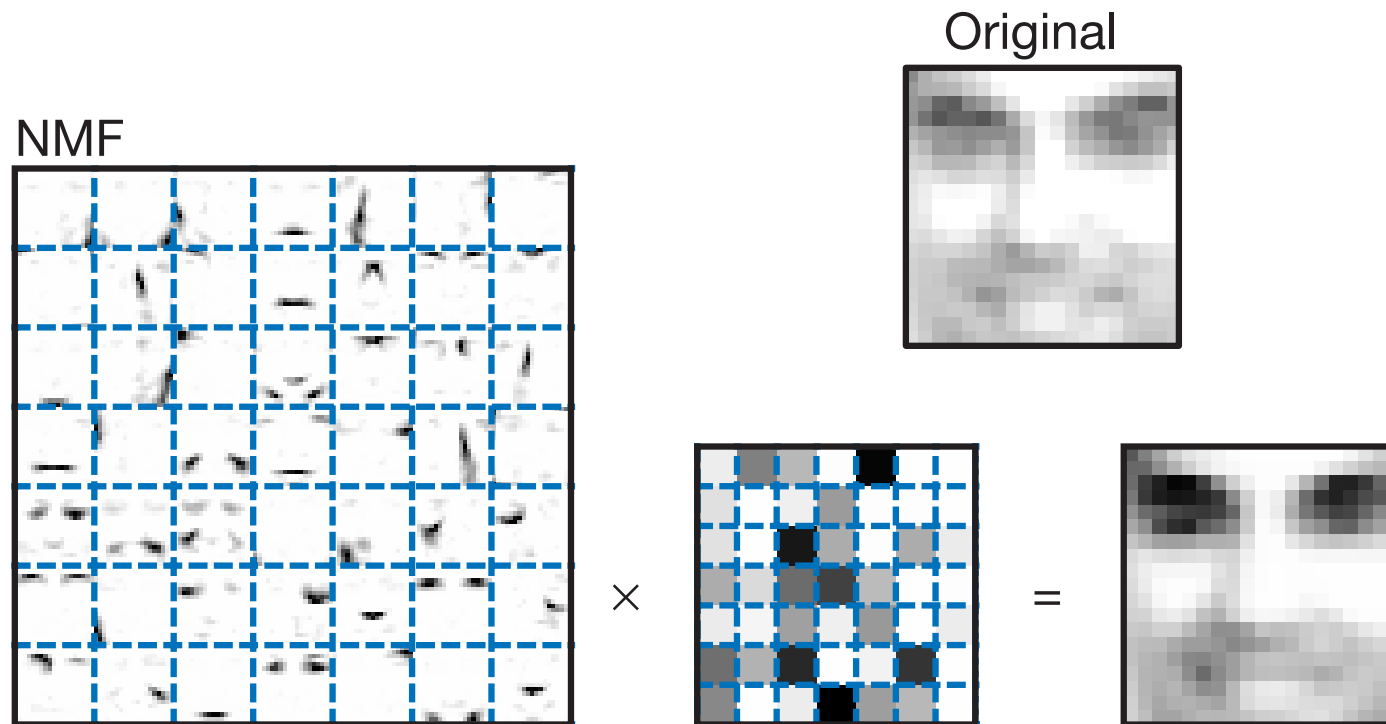
where  $\mathbf{X} \geq \mathbf{0}$  means that  $x_{ij} \geq 0$  for all  $i, j$ .

- arguably a topic in optimization, but worth noticing
- found to be able to extract meaningful features (by empirical studies)
- numerous applications, e.g., in machine learning, signal processing, remote sensing



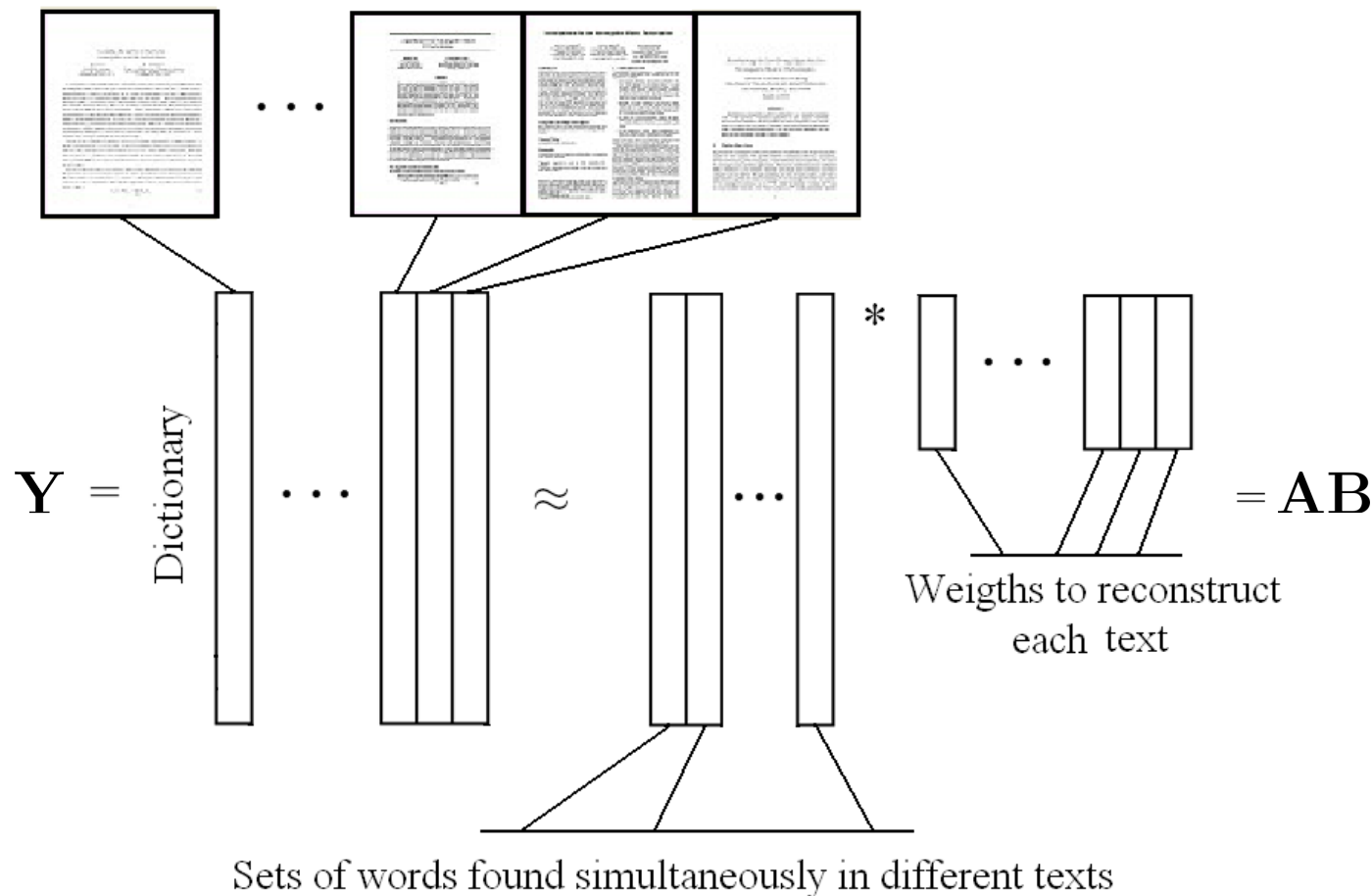
# NMF Examples

- Image Processing:



The basis elements extract facial features such as eyes, nose and lips. Source: [\[Lee-Seung1999\]](#).

## • Text Mining:



- basis elements allow us to recover different topics;
- weights allow us to assign each text to its corresponding topics.

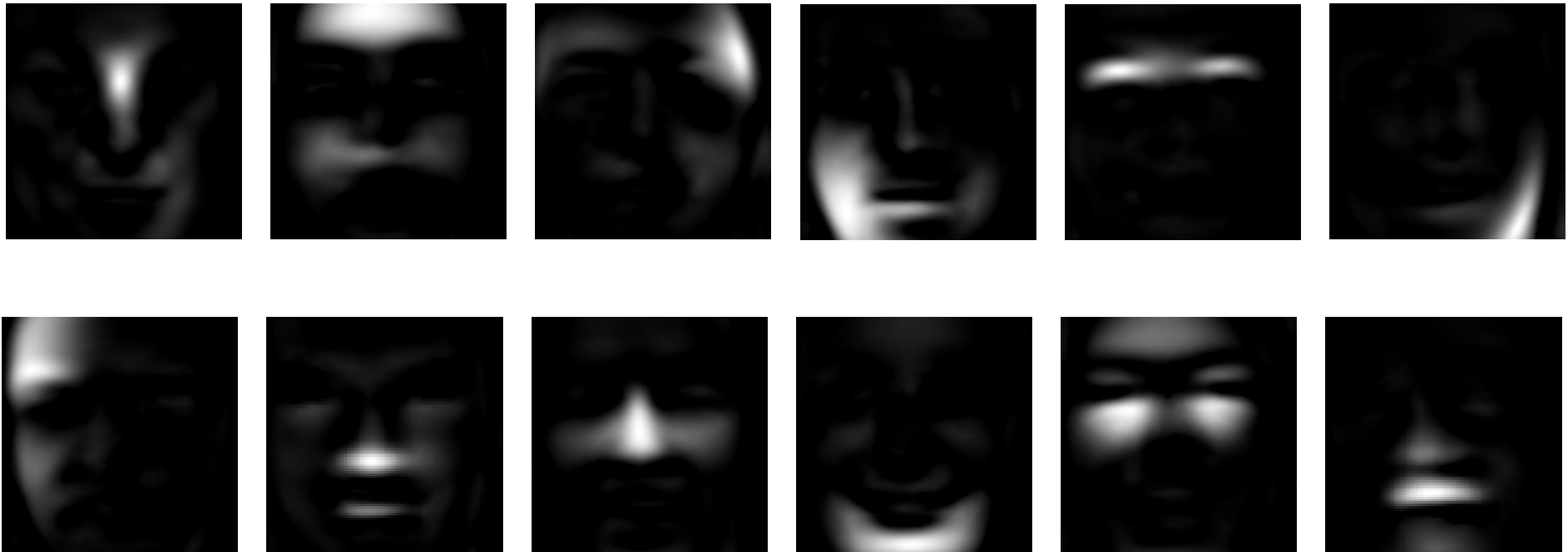


## Toy Demonstration of NMF



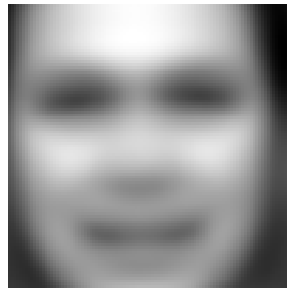
A face image dataset. Image size =  $101 \times 101$ , number of face images = 13232. Each  $\mathbf{x}_i$  is the vectorization of one face image, leading to  $m = 101 \times 101 = 10201$ ,  $n = 13232$ .

## Toy Demonstration of NMF: NMF-Extracted Features



NMF settings:  $r = 49$ , Lee-Seung multiplicative update with 5000 iterations.

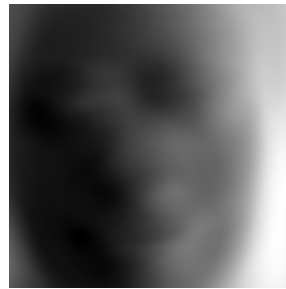
# Toy Demonstration of NMF: Comparison with PCA



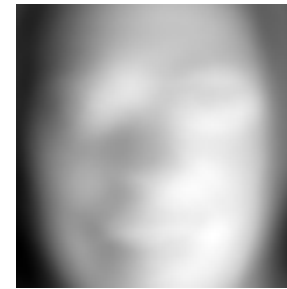
Mean face



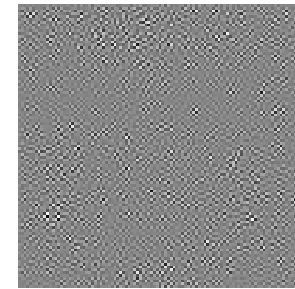
1st principal left  
singular vector



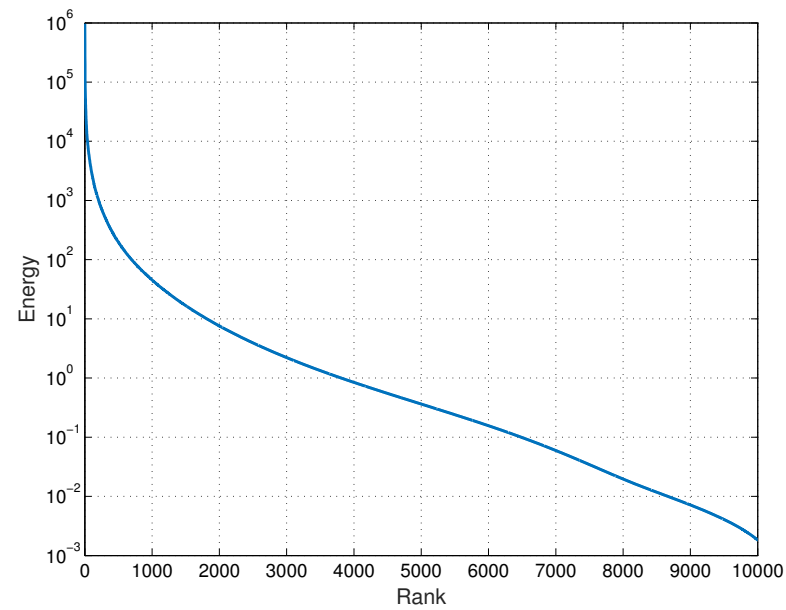
2nd principal left  
singular vector



3th principal left  
singular vector



last principal left  
singular vector



Energy Concentration

## A Few More Words to Say

- things I hope you will learn
  - how to read how people manipulate matrix operations, and how you can manipulate them (learn to use a tool);
  - what applications we can do, or to find new applications of our own (learn to apply a tool);
  - deep analysis skills (why is this tool valid? Can I invent new tools? Key to some topics, should go through at least once in your life time)
- feedbacks are welcome; closed-loop systems often work better than open-loop

## References

- [Yang-Santillana-Kou2015]** S. Yang, M. Santillana, and S. C. Kou, “Accurate estimation of influenza epidemics using Google search data via ARGO,” *Proceedings of the National Academy of Sciences*, vol. 112, no. 47, pp. 14473–14478, 2015.
- [Bryan-Tanya2006]** K. Bryan and L. Tanya, “The 25,000,000,000 eigenvector: The linear algebra behind Google,” *SIAM Review*, vol. 48, no. 3, pp. 569–581, 2006.
- [Candès-Romberg-Tao2006]** E. J. Candès, J. Romberg, and T. Tao, “Robust uncertainty principles: Exact signal reconstruction from highly incomplete frequency information,” *IEEE Trans. Information Theory*, vol. 52, no. 2, pp. 489–509, 2006.
- [Koren-Bell-Volinsky2009]** B. Koren, R. Bell, and C. Volinsky, “Matrix factorization techniques for recommender systems,” *IEEE Computer*, vol. 42 no. 8, pp. 30–37, 2009.
- [Lee-Seung1999]** D. D. Lee and H. S. Seung, “Learning the parts of objects by non-negative matrix factorization,” *Nature*, vol. 401, no. 6755, pp. 788–791, 1999.