

Graph Representation of Code

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SVF : Static Value-Flow Analysis Framework for Source Code

A **scalable, precise and on-demand** interprocedural program dependence analysis framework for both sequential and multithreaded programs.

- The SVF project
 - **Publicly available** since early 2015 and actively maintained: <http://svf-tools.github.io/SVF>.
 - Implemented on top of LLVM compiler (the latest version 10.0.0) with over 100 KLOC C/C++ code and **530+ stars with 30+ contributors** and over 1K commits on Github.
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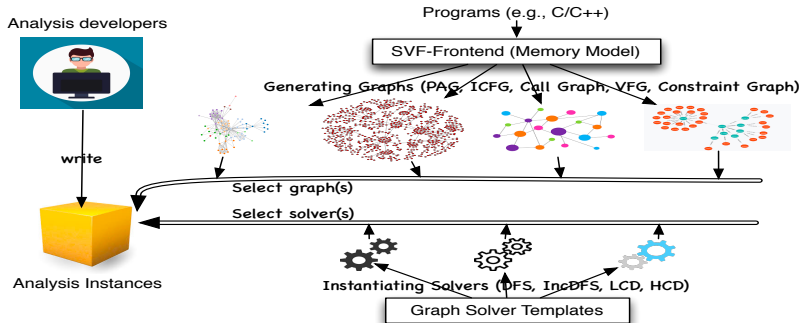
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- Value-Flow Analysis: resolves **both control and data dependence**.
 - Does the information generated at program point A flow to another program point B along some execution paths?
 - Can function F be called either directly or indirectly from some other function F' ?
 - Is there an unsafe memory access that may trigger a bug or security risk?

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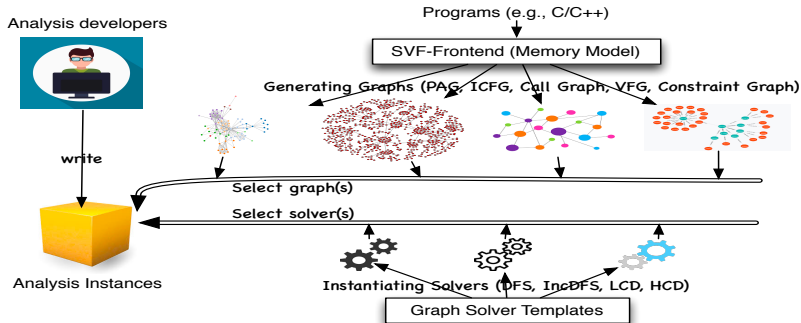
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 - Can function F be called either directly or indirectly from some other function F' ?
 - Is there an unsafe memory access that may trigger a bug or security risk?
- Key features of SVF
 - **Sparse**: compute and maintain the data-flow facts where necessary
 - **Selective** : support mixed analyses for precision and efficiency trade-offs.
 - **On-demand** : reason about program parts based on user queries.

SVF: Design Principle



- Serving as an open-source foundation for building practical static source code analysis
 - Bridge the gap between research and engineering
 - Minimize the efforts of implementing sophisticated analysis (**extendable**, **reusable**, and **robust** via layers of abstractions)
 - Support developing **different analysis variants** (flow-, context-, heap-, field-sensitive analysis) in a **sparse** and **on-demand** manner.

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 - Support developing **different analysis variants** (flow-, context-, heap-, field-sensitive analysis) in a **sparse** and **on-demand** manner.
- Client applications:
 - Static bug detection (e.g., memory leaks, null dereferences, use-after-frees and data-races)
 - Accelerate dynamic analysis (e.g., Google's Sanitizers and AFL fuzzing)

Graph Representation of Code

- What is a graph representation of code?
 - Representing a program's control-flow (i.e., execution order) and/or data-flow (variable definition and use relations) using nodes and edges of a graph.

Graph Representation of Code

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 - Representing a program's control-flow (i.e., execution order) and/or data-flow (variable definition and use relations) using nodes and edges of a graph.
- Why a graph representation?
 - Abstracting code from low-level complicated instructions
 - Applying general graph algorithms
 - Easy to maintain and extend

Call Graph

```
define i32 @main() #0 {  
  1 entry:  
  2 %a1 = alloca i8, align 1  
  3 %b1 = alloca i8, align 1  
  4 %a = alloca i8*, align 8  
  5 %b = alloca i8*, align 8  
  6 store i8* %a1, i8** %a, align 8  
  7 store i8* %b1, i8** %b, align 8  
  8 call void @swap(i8** %a, i8** %b)  
  9 ret i32 0  
}  
define void @swap(i8** %p, i8** %q) #0  
{  
  10 entry:  
  11 %0 = load i8** %p, align 8  
  12 %1 = load i8** %q, align 8  
  13 store i8* %1, i8** %p, align 8  
  14 store i8* %0, i8** %q, align 8  
  15 ret void  
}
```

Program calling relations between methods



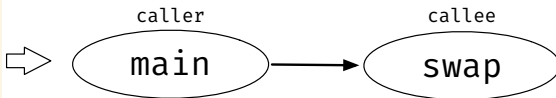
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```

- each node represents a program method
- each edge represents a calling relation between two program methods



Call Graph

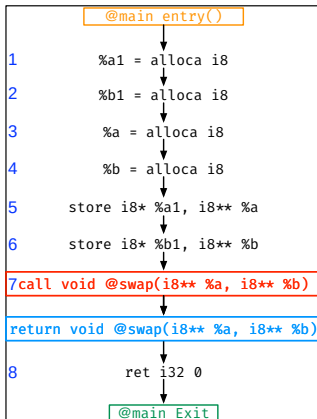
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Control Flow Graph

Program execution order between instructions.

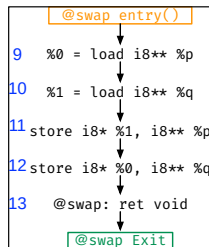
- Intra-procedural control-flow graph: control-flow graph within a program method.
- Inter-procedural control-flow graph: control-flow graph across program methods.

Intra-procedural Control Flow Graph



Program execution order between instructions

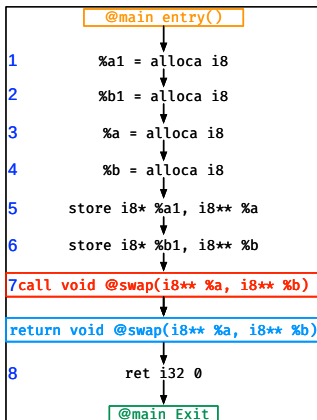
- Each node represents an instruction or a statement
- Each edge represents a control-flow dependence between two nodes



- IntraBlockNode
- FunEntryBlockNode
- FunExitBlockNode
- RetBlockNode
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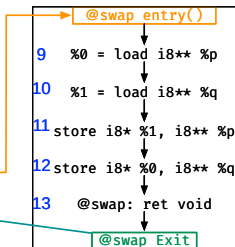
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Inter-procedural Control Flow Graph (ICFG)



Program execution order between instructions

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Constraint Graph (or Program Assignment Graph)

- Constraint Graph represents the assignment constraints between variables at the instruction level.
- Constraint Graph and Program Assignment Graph (PAG) are essentially the same.
- The difference is that PAG can not be changed while you can add edges or nodes on the Constraint Graph to perform constraint solving.

Constraint Graph (or Program Assignment Graph)

Program Assignment relation between two variables

- each node represent a pointer or an object
- each edge represents two nodes dependence or constraint relation

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define i32 @main() #0 {  
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```



alloca instruction allocates typed integer

8 bytes of memory object as O1 O2 O3 O4

→ Address

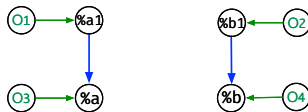
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→ Address → Store

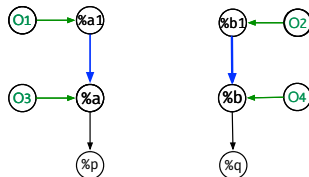
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→ Call

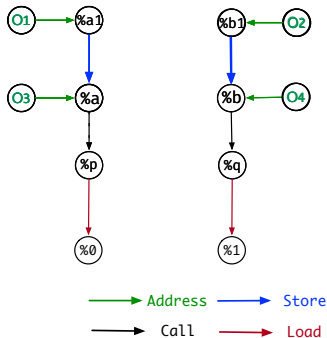
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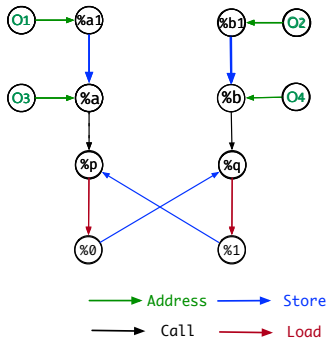
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What's next?

- (1) Compile two C programs (`swap.c` and `example.c`) into their LLVM IR.
 - A guide can be found here <https://github.com/SVF-tools/SVF-Teaching/wiki/CodeGraph#2-llvm-ir-generation>
 - Understand the mapping from a C program to its corresponding LLVM IR.
- (2) Generate and visualize the graph representation of LLVM IR (`swap.ll` and `example.ll`).
 - <https://github.com/SVF-tools/SVF-Teaching/wiki/CodeGraph#3-run-and-debug-your-codegraph>
- (3) Write code to iterate nodes and edges of ICFG and PAG and print their contents.
 - <https://github.com/SVF-tools/SVF-Teaching/blob/main/CodeGraph/CodeGraph.cpp#L65-L82>
- (4) More about LLVM IR and SVF's graph representation
 - LLVM language manual <https://llvm.org/docs/LangRef.html>
 - SVF website <https://github.com/SVF-tools/SVF>

Data-Dependence

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Data-Dependence

Pointer analysis

- Points-to Analysis: Statically determine the possible runtime values of a pointer at compile-time.
- Alias Analysis: determine whether two pointer dereferences refer to the same memory location.
- e.g., $p = \&a$; $p = q$;
- p and q both point to a . $*p$ and $*q$ are aliases.

Data-Dependence

Pointer analysis

Why do we need to learn pointer analysis

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- Essential for building data-dependence relations between variables
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Pointer analysis

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- Pointer analysis tells us what memory locations code uses or modifies
- Essential for building data-dependence relations between variables
 - $p = \&a; p = q; *p = x; y = *q$
- Good for program understanding, bug detection and compiler optimisations
 - Constant propagation
 - $p = 1; *q = x; r = p;$
 - r is a constant value and equals 1, if p and q do not alias each other, otherwise, can not perform constant propagation.

Data-Dependence

Pointer analysis

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 - $p = 1; *q = x; r = p;$
 - r is a constant value and equals 1, if p and q do not alias each other, otherwise, can not perform constant propagation.
 - Taint analysis
 - $p = \text{taintedInput}; x = *q;$
 - x is tainted if p and q alias each other.

Data-Dependence

Pointer analysis

An ongoing research topic classified into the following precision dimensions.

- Flow-insensitive analysis:
 - Ignore program execution order
 - A single solution at each program point
- Flow-sensitive analysis:
 - Respect the program execution order
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- Field-sensitive analysis:
 - Distinguish the fields of an aggregate object (e.g., struct object).
- Context-insensitive analysis:
 - Merges all of its calling contexts together when analysing a program method
- Context-sensitive analysis:
 - Distinguishes between different calling contexts of a program method

Andersen's Pointer analysis

- The most popular and widely used pointer analysis
- Constraint solving (inclusion-based constraints between program variables)

We will practice a flow-insensitive, field-insensitive and context-insensitive Andersen's analysis through analyzing the PAG (or Constraint Graph) of a program.

Andersen's Pointer Analysis

SVF transforms LLVM instructions into a PAG (or Constraint Graph).

- Node:
 - A pointer: (LLVM Value in pointer type)
 - An object: (heap, stack, global, function)
- Edge: A Constraint between two nodes

Constraint Type	C code	Constraint rule
Address:	$p = \&obj$	$\{obj\} \subseteq Pts(p)$
Copy:	$p = q$	$Pts(q) \subseteq Pts(p)$
Load:	$p = *q$	$\forall o \in Pts(q), Pts(o) \subseteq Pts(p)$
Store:	$*p = q$	$\forall o \in Pts(p), Pts(q) \subseteq Pts(o)$

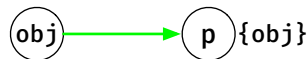
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Constraint Type	C code	LLVM IR
Address:	<code>p = obj</code>	<code>%p = alloca // obj</code>

Constraint Graph

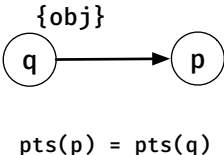


`pts(p) = {obj}`

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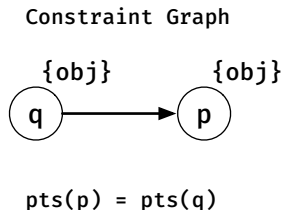
Constraint Type	C code	LLVM IR	Constraint Graph
Address:	<code>p = obj</code>	<code>%p = alloca // obj</code>	 <pre>graph LR; q((q)) --> p((p));</pre> <p>$\text{pts}(p) = \text{pts}(q)$</p>
Copy:	<code>p = q</code>	<code>%p = bitcast %q</code>	

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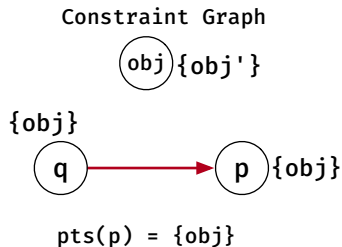


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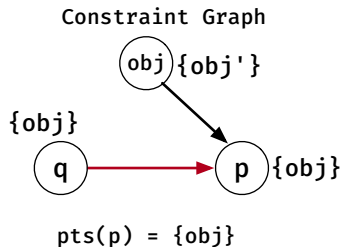


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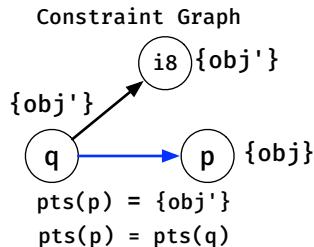


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Load:	<code>p = *q</code>	<code>%q = load %p</code>
Store:	<code>*p = q</code>	<code>store %q, %p</code>

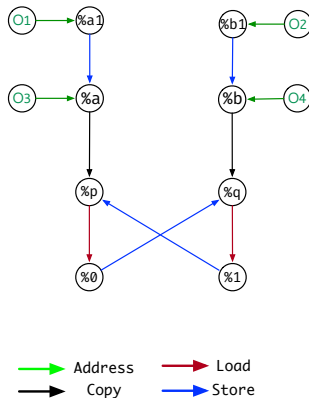


Andersen's Pointer Analysis

Algorithm

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%b = alloca i8*, align 8      // O4
store i8* %a1, i8** %a, align 8
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call void @swap(i8** %a, i8** %b)
ret i32 0
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define void @swap(i8** %p, i8** %q)
#0 {
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```



```
G = < V, E >    // Constraint Graph
V: a set of nodes in graph
E: a set of edges in graph
W: a vector of nodes

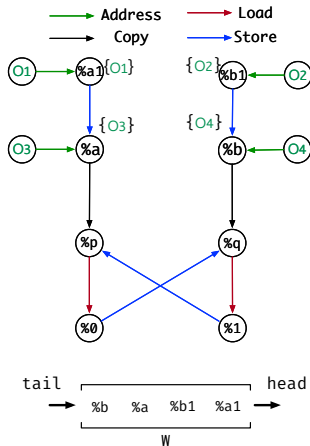
1 foreach address p = &o do
2   pts(p) = {o}
3   W ← W ∪ {p}
4 while W ≠ ∅ do
5   p ← select-from(W)
6   foreach o ∈ pts(p) do
7     foreach store *p = q do
8       if q → o ∉ E then
9         E ← E ∪ {q → o}
10        W ← W ∪ {q}
11     foreach load r = *p do
12       if o → r ∉ E then
13         E ← E ∪ {o → r}
14        W ← W ∪ {o}
15 foreach p → x ∈ E do
16   pts(x) ← pts(x) ∪ pts(p)
17   if pts(x) changed then
18     W ← W ∪ {x}
```

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%b = alloca i8*, align 8      // O4
store i8* %a1, i8** %a, align 8
store i8* %b1, i8** %b, align 8
call void @swap(i8** %a, i8** %b)
ret i32 0
}

define void @swap(i8** %p, i8** %q)
#0 {
entry:
%0 = load i8** %p, align 8
%1 = load i8** %q, align 8
store i8* %1, i8** %p, align 8
store i8* %0, i8** %q, align 8
ret void
}
```



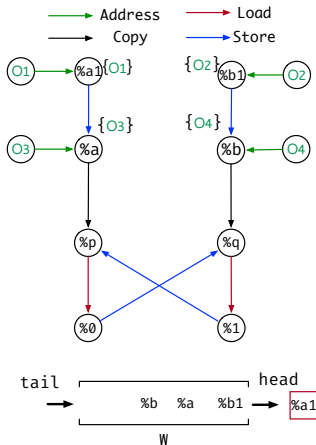
```
G = < V, E > // Constraint Graph
V: a set of nodes in graph
E: a set of edges in graph
W: a vector of nodes (WorkList)

1 foreach address p = &o do
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3   W ← W ∪ {p}
4 while W ≠ ∅ do
5   p ← select-from(W)
6   foreach o ∈ pts(p) do
7     foreach store *p = q do
8       if q → o ∉ E then
9         E ← E ∪ {q → o}
10        W ← W ∪ {q}
11     foreach load r = *p do
12       if o → r ∉ E then
13         E ← E ∪ {o → r}
14        W ← W ∪ {o}
15 foreach p → x ∈ E do
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Algorithm

```
define i32 @main() #0 {
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%a1 = alloca i8, align 1           // O1
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define void @swap(i8** %p, i8** %q)
#0 {
entry:
%0 = load i8** %p, align 8
%1 = load i8** %q, align 8
store i8* %1, i8** %p, align 8
store i8* %0, i8** %q, align 8
ret void
}
```



```

G = < V, E > // Constraint Graph
V: a set of nodes in graph
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6     foreach o ∈ pts(p) do
7         foreach store *p = q do
8             if q → o ∉ E then
9                 E ← E ∪ {q → o}
10                W ← W ∪ {q}
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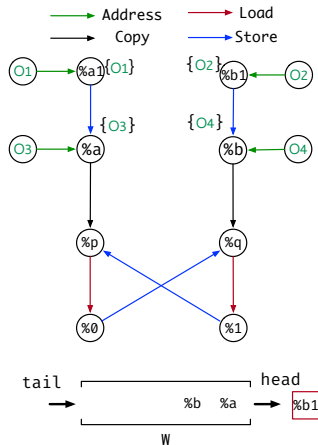
```


Andersen's Pointer Analysis

Algorithm

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entry:
%a1 = alloca i8, align 1      // O1
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call void @swap(i8** %a, i8** %b)
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%0 = load i8** %p, align 8
%1 = load i8** %q, align 8
store i8* %1, i8** %p, align 8
store i8* %0, i8** %q, align 8
ret void
}
```



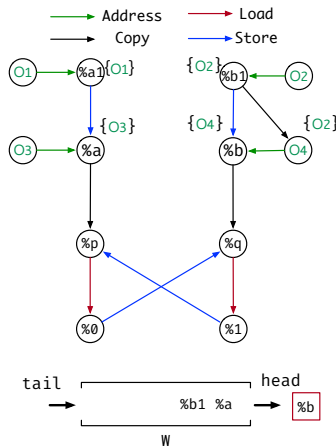
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Andersen's Pointer Analysis

Algorithm

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%1 = load i8** %q, align 8
store i8* %1, i8** %p, align 8
store i8* %0, i8** %q, align 8
ret void
}
```



```

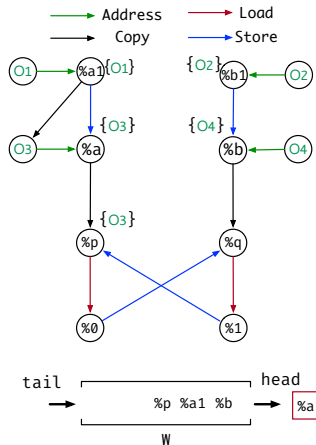
G = < V, E >  // Constraint Graph
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Andersen's Pointer Analysis

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  %a = alloca i8*, align 8      // O3  
  %b = alloca i8*, align 8      // O4  
  store i8* %a1, i8** %a, align 8  
  store i8* %b1, i8** %b, align 8  
  call void @swap(i8** %a, i8** %b)  
  ret i32 0  
}  
  
define void @swap(i8** %p, i8** %q)  
#0 {  
  entry:  
  %0 = load i8** %p, align 8  
  %1 = load i8** %q, align 8  
  store i8* %1, i8** %p, align 8  
  store i8* %0, i8** %q, align 8  
  ret void  
}
```

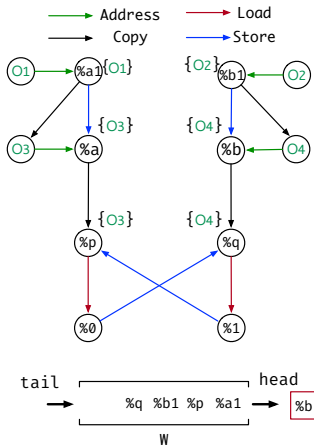


```
G = < V, E > // Constraint Graph  
V: a set of nodes in graph  
E: a set of edges in graph  
W: a vector of nodes (WorkList)  
1 foreach address p = &o do  
2   pts(p) = {o}  
3   W  $\leftarrow$  W  $\cup$  {p}  
4 while W  $\neq \emptyset$  do  
5   p  $\leftarrow$  select-from(W)  
6   foreach o  $\in$  pts(p) do  
7     foreach store *p = q do  
8       if q  $\rightarrow$  o  $\notin$  E then  
9         E  $\leftarrow$  E  $\cup$  {q  $\rightarrow$  o}  
10        W  $\leftarrow$  W  $\cup$  {q}  
11        foreach load r = *p do  
12          if o  $\rightarrow$  r  $\notin$  E then  
13            E  $\leftarrow$  E  $\cup$  {o  $\rightarrow$  r}  
14            W  $\leftarrow$  W  $\cup$  {o}  
15 foreach p  $\rightarrow$  x  $\in$  E do  
16   pts(x)  $\leftarrow$  pts(x)  $\cup$  pts(p)  
17   if pts(x) changed then  
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```

Andersen's Pointer Analysis

Algorithm

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define i32 @main() #0 {  
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  %a = alloca i8*, align 8      // O3  
  %b = alloca i8*, align 8      // O4  
  store i8* %a1, i8** %a, align 8  
  store i8* %b1, i8** %b, align 8  
  call void @swap(i8** %a, i8** %b)  
  ret i32 0  
}  
  
define void @swap(i8** %p, i8** %q)  
#0 {  
  entry:  
  %0 = load i8** %p, align 8  
  %1 = load i8** %q, align 8  
  store i8* %1, i8** %p, align 8  
  store i8* %0, i8** %q, align 8  
  ret void  
}
```



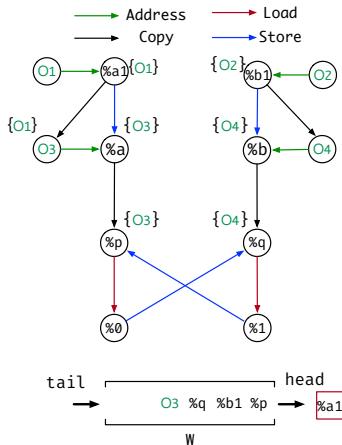
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3   W  $\leftarrow$  W  $\cup$  {p}  
4 while W  $\neq \emptyset$  do  
5   p  $\leftarrow$  select-from(W)  
6   foreach o  $\in$  pts(p) do  
7     foreach store *p = q do  
8       if  $q \rightarrow o \notin E$  then  
9         E  $\leftarrow$  E  $\cup$  { $q \rightarrow o$ }  
10        W  $\leftarrow$  W  $\cup$  {q}  
11        foreach load r = *p do  
12          if  $o \rightarrow r \notin E$  then  
13            E  $\leftarrow$  E  $\cup$  { $o \rightarrow r$ }  
14            W  $\leftarrow$  W  $\cup$  {o}  
15        foreach p  $\rightarrow$  x  $\in$  E do  
16          pts(x)  $\leftarrow$  pts(x)  $\cup$  pts(p)  
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Andersen's Pointer Analysis

Algorithm

```
define i32 @main() #0 {
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%a1 = alloca i8, align 1           // O1
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store i8* %a1, i8** %a, align 8
store i8* %b1, i8** %b, align 8
call void @swap(i8** %a, i8** %b)
ret i32 0
}

define void @swap(i8** %p, i8** %q)
#0 {
entry:
%0 = load i8** %p, align 8
%1 = load i8** %q, align 8
store i8* %1, i8** %p, align 8
store i8* %0, i8** %q, align 8
ret void
}
```



```
G = < V, E > // Constraint Graph
V: a set of nodes in graph
E: a set of edges in graph
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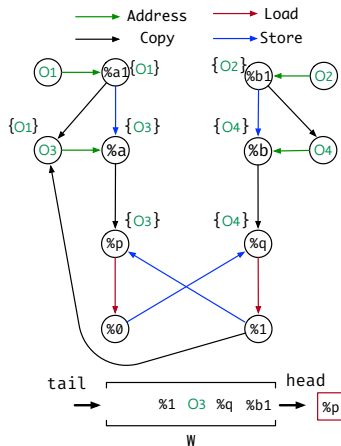
1 foreach address p = &o do
2   pts(p) = {o}
3   W ← W ∪ {p}
4 while W ≠ ∅ do
5   p ← select-from(W)
6   foreach o ∈ pts(p) do
7     foreach store *p = q do
8       if q → o ∉ E then
9         E ← E ∪ {q → o}
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Andersen's Pointer Analysis

Algorithm

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define void @swap(i8** %p, i8** %q)
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```



```
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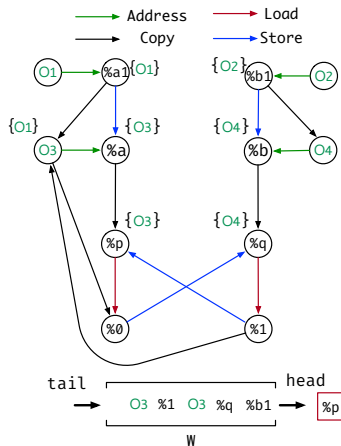
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Andersen's Pointer Analysis

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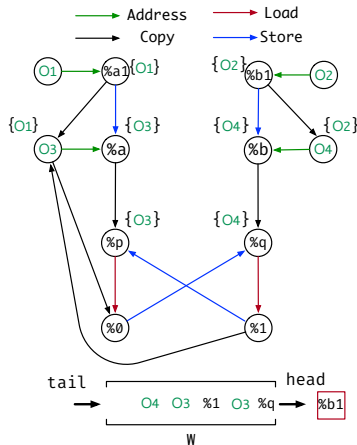
Andersen's Pointer Analysis

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store i8* %1, i8** %p, align 8
store i8* %0, i8** %q, align 8
ret void
}
    
```



```

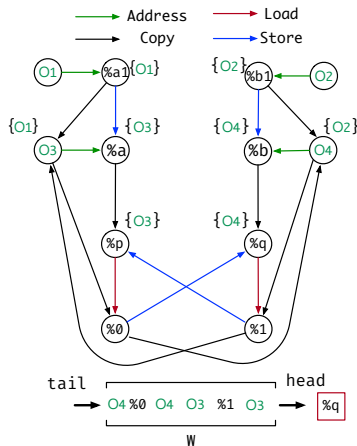
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Andersen's Pointer Analysis

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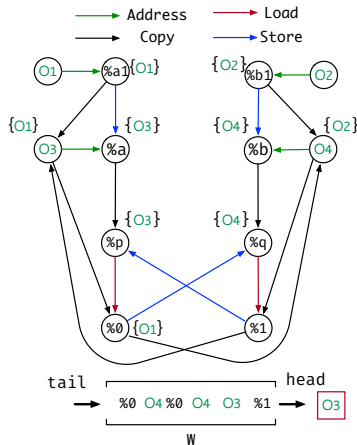
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Andersen's Pointer Analysis

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```



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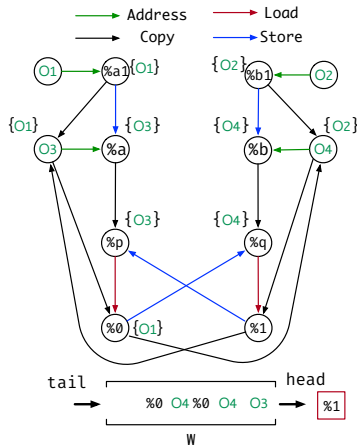
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Andersen's Pointer Analysis

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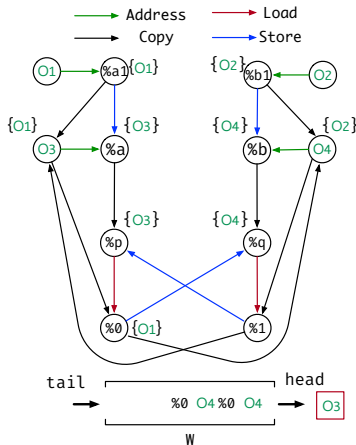
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5   p ← select-from(W)
6   foreach o ∈ pts(p) do
7     foreach store *p = q do
8       if q → o ∉ E then
9         E ← E ∪ {q → o}
10        W ← W ∪ {q}
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Andersen's Pointer Analysis

Algorithm

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entry:
%a1 = alloca i8, align 1      // O1
%b1 = alloca i8, align 1      // O2
%a = alloca i8*, align 8      // O3
%b = alloca i8*, align 8      // O4
store i8* %a1, i8** %a, align 8
store i8* %b1, i8** %b, align 8
call void @swap(i8** %a, i8** %b)
ret i32 0
}

define void @swap(i8** %p, i8** %q)
#0 {
entry:
%0 = load i8** %p, align 8
%1 = load i8** %q, align 8
store i8* %1, i8** %p, align 8
store i8* %0, i8** %q, align 8
ret void
}
```



```
G = < V, E > // Constraint Graph
V: a set of nodes in graph
E: a set of edges in graph
W: a vector of nodes (WorkList)

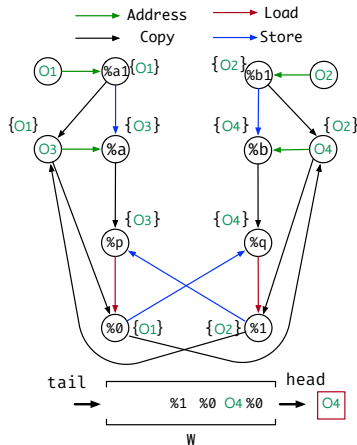
1 foreach address p = &o do
2   pts(p) = {o}
3   W ← W ∪ {p}
4 while W ≠ ∅ do
5   p ← select-from(W)
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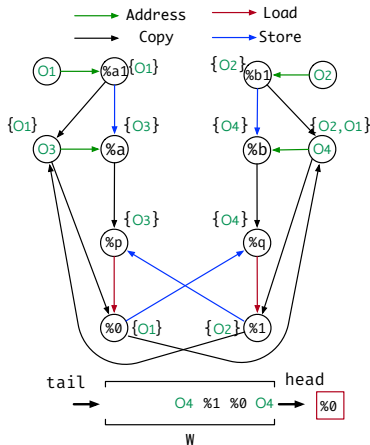
1 foreach address p = &o do
2   pts(p) = {o}
3   W ← W ∪ {p}
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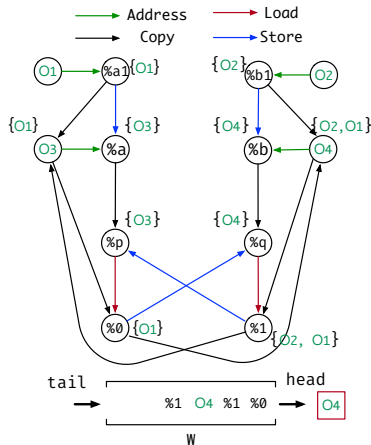
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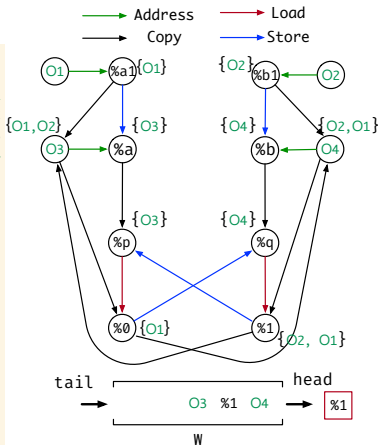
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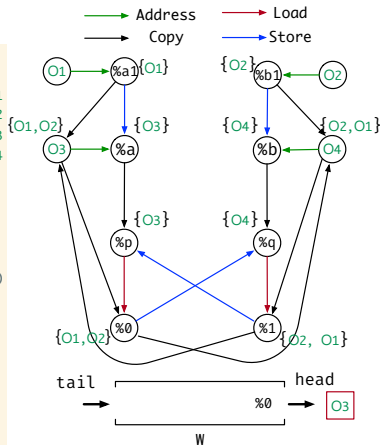
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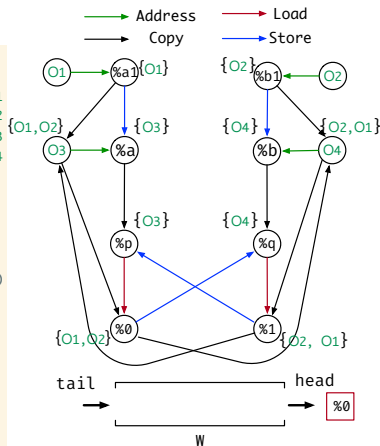
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