# Data-Dependence

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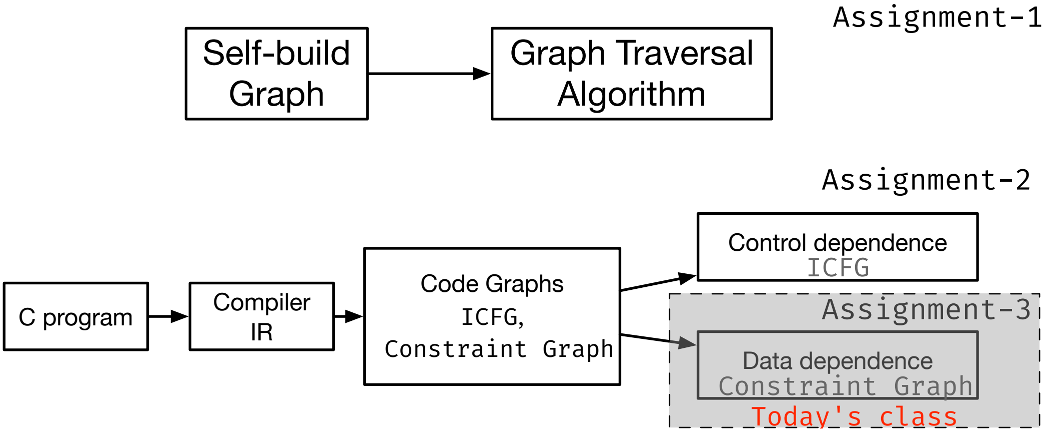

Assignment-1

Self-build Graph

Graph Traversal Algorithm

Assignment-2

C program

Compiler IR

Code Graphs
`ICFG,`
`Constraint Graph`

Control dependence
`ICFG`

Assignment-3

Data dependence
`Constraint Graph`

Today's class

# Data-Dependence

Definition-use relations between variables. Two types of variables on LLVM IR:

- **Top-level variables**, whose addresses are not taken (`ValPN` in SVF)
  - Including stack virtual **registers** (symbols starting with “%”) and **global** variables (symbols starting with “@”) are explicit, i.e., directly accessed.

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  - **Def-use for top-level variables are directly available on LLVM’s SSA form**.
  - For example, def-use for %a1 from Instruction-1 to Instruction-2.
    - Instruction-1: `%a1 = alloca i8, align 1;`
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- **Address-taken variables** (abstract objects), accessed indirectly at load or store instructions via top-level variables (`ObjPN` in SVF)
  - A **stack object** created at an LLVM’s ‘alloca‘ instruction or a **heap object** created via (e.g., ‘malloc‘ callsite) or a **global object**.

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  - A **stack object** created at an LLVM's 'alloca' instruction or a **heap object** created via (e.g., 'malloc' callsite) or a **global object**.
  - **Def-use for address-taken variables are computed via pointer analysis**.
  - For example, there is a def-use for object `o` from Instruction-1 to Instruction-2 if pointers `%a` and `%b` both point to `o`.
    - Instruction-1: `store i8* %a1, i8** %a, align 8`
    - Instruction-2: `%c = load i8** %b, align 8`

# Pointer analysis

- Points-to Analysis: aims to statically determine the possible runtime values of a pointer at compile-time.
  - Compute the *points-to set* (**a set of address-taken variables**) of each *pointer* (**top-level variable)**
  - For example, `p = &a; p = q;`
  - The resulting points-to sets of `p` and `q` are: `pts(p) = pts(q) =` $\{$`a`$\}$

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  - For example, `p = &a; p = q;`
  - The resulting points-to sets of `p` and `q` are: `pts(p) = pts(q) = {a}`
- Alias Analysis: determine whether two pointer dereferences refer to the same memory location.
  - If the points-to sets of two pointers `p` and `q` have overlapping elements (i.e., `pts(p)` ∩ `pts(q) is not empty`) then `p` and `q` are aliases. The derereferences of `p` and `q` may refer to the same memory location.

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  - `p = &a; q = p; *p = x; y = *q;`
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- Compiler optimizations and bug detection
  - Constant propagation
    - `p = 1; *q = r; x = p;`
      `x` is a constant value and equals 1, if `p` and `q` do not alias with each other.
    - `*p = 1; x = *q;`
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  - Taint analysis
    - `*p = taintedInput; x = *q;`
      `x` is tainted if `p` and `q` are aliases.

# Precision Dimensions

Can be generally classified into the following precision dimensions at different levels of abstractions.

**Flow-insensitive** analysis:

- Ignores program execution order
- A single solution at each program point

**Context-insensitive** analysis:

- Merges all of all calling contexts when analysing a program method

**Path-insensitive** analysis:

- Merges all incoming path information at the joint point of the control-flow graph

**Flow-sensitive** analysis:

- Respects the program execution order
- Separate solutions across whole program

**Context-sensitive** analysis:

- Distinguishes between different calling contexts of a program method

**Path-sensitive** analysis:

- Computes a solution per (abstract) program path.

# Precision Dimensions

## Levels of Abstractions

Assume x is a tainted value

```
p = x

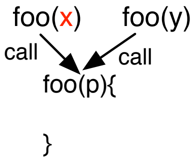
p = y
```

**flow-sensitivity**

at which

program point

p is tainted?



foo(x) foo(y)

call call

```
foo(p){

}
```

**context-sensitivity**

under which

calling context

p is tainted?

```
if(cond)
        p = x
else
        p = y
```

**path-sensitivity**

along which

program path

p is tainted?

# Andersen's Pointer analysis

## Flow-, context-, and path-insensitive analysis

In this subject, we will practice **Andersen's analysis**[1], a **flow-insensitive, context-insensitive and path-insensitive Andersen's analysis** through analyzing the **Constraint Graph** of a program.

- One of the most popular and widely used pointer analyses
- Constraint solving, i.e., inclusion-based constraint solving between program variables (`PAGNode` in SVF)

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[1] Andersen, L. O. (1994). Program analysis and specialization for the C programming language (Doctoral dissertation, University of Cophenhagen).

# Andersen’s Pointer Analysis

An inclusion-based analysis operating on top of the constraint graph of a program. SVF transforms each LLVM instruction into a constraint edge connecting two nodes

- A `ConstraintNode` represents
  - A pointer: (top-level variable) or
  - An object: (address-taken variable, i.e., heap, stack, global or function object)
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| **Constraint Type** | **C code** | **LLVM IR** | **Constraint rules** |
|---|---|---|---|
| `Address:` | `p = &o` | `%p = alloca //o` | `pts(p) = pts(p) ∪ pts(o)` |
| `Copy:` | `q = p` | `%q = bitcast %p` | `pts(q) = pts(q) ∪ pts(p)` |
| `Load:` | `q =*p` | `%q = load %p` | `∀ o ∈ pts(p):` **`pts(q) = pts(o) ∪ pts(q)`** |
| `Store:` | `*p = q` | `store %q, %p` | `∀ o ∈ pts(p):` **`pts(o) = pts(q) ∪ pts(o)`** |

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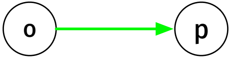

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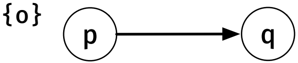

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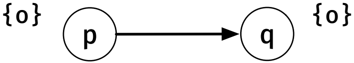

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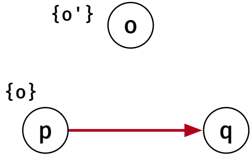

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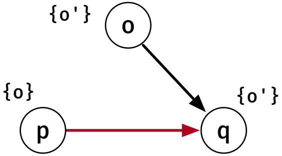

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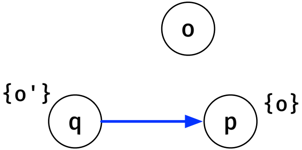

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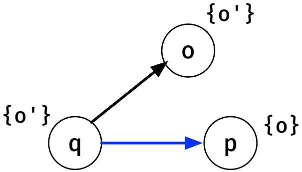

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# Compile C Code to LLVM IR

```
void swap(char **p, char **q){
  char* t = *p;
       *p = *q;
       *q = t;
}
int main(){
      char a1, b1;
      char *a = &a1;
      char *b = &b1;
      swap(&a,&b);
}
```

compile to

```
define i32 @main() #0 {
entry:
%a1 = alloca i8, align 1       // O1
%b1 = alloca i8, align 1       // O2
%a = alloca i8*, align 8       // O3
%b = alloca i8*, align 8       // O4
store i8* %a1, i8** %a, align 8
store i8* %b1, i8** %b, align 8
call void @swap(i8** %a, i8** %b)
ret i32 0
}
define void @swap(i8** %p, i8** %q)
#0 {
entry:
%0 = load i8** %p, align 8
%1 = load i8** %q, align 8
store i8* %1, i8** %p, align 8
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ret void
}
```

---

*https://github.com/SVF-tools/SVF-Teaching/wiki/CodeGraph#2-llvm-ir-generation

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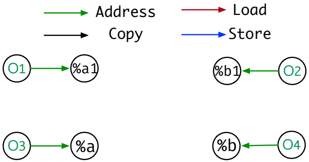

https://github.com/svf-tools/SVF/wiki/Analyze-a-Simple-C-Program#5-pag

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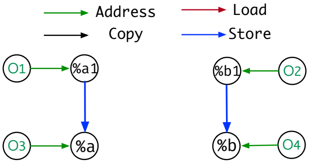

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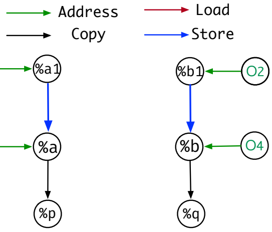

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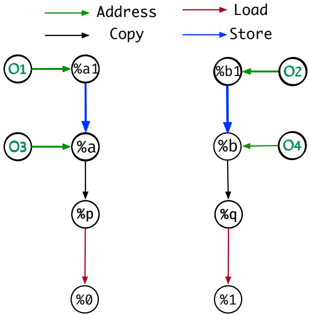

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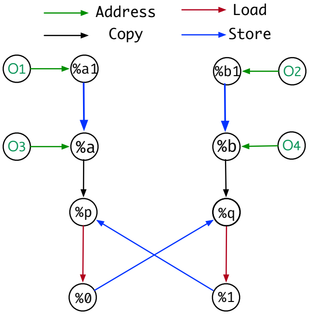

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# Andersen’s Pointer Analysis

## Algorithm

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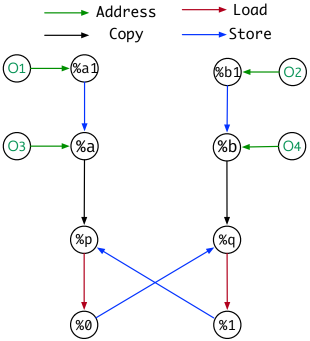
}
```



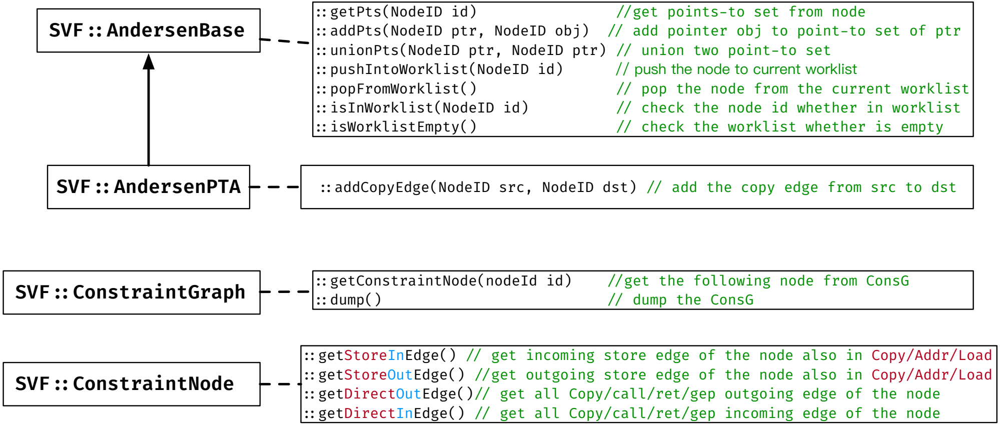
```
G = < V,E >  // Constraint Graph
V: a set of nodes in graph
E: a set of edges in graph
WorkList: a vector of nodes
foreach address p = &o do  // address rule
      pts(p) = {o}
      pushIntoWorklist(p)
while WorkList ≠ ∅ do
    p ← popFromWorklist()
    foreach o ∈ pts(p) do
        foreach store *p = q do// store rule
            if q→o ∉ E then
                E ← E ∪ {q→o}  // add copy edge
                pushIntoWorklist(q)
        foreach load r = *p do  // load rule
            if o→r ∉ E then
                E ← E ∪ {o→r}  // add copy edge
                pushIntoWorklist(o)
    foreach p→x ∈ E do         // copy rule
        pts(x) ← pts(x) ∪ pts(p)
        if pts(x) changed then
                pushIntoWorklist(x)
```

# Andersen's Pointer Analysis

## Constraint solving Algorithm

- A worklist holds a set of constraint graph nodes for processing
- Pop a node `p` from the worklist.
- Handle each incoming `store` edge and each outgoing `load` edge of node `p` by adding `copy` edges.
- Handle each outgoing `copy` edge of `p` by propagating points-to information.
- The constraint solving stops when no points-to set of a pointer is changed.

# APIs for Implementing Andersen's analysis



**SVF :: AndersenBase**

```
::getPts(NodeID id)                 //get points-to set from node
::addPts(NodeID ptr, NodeID obj)  // add pointer obj to point-to set of ptr
::unionPts(NodeID ptr, NodeID ptr) // union two point-to set
::pushIntoWorklist(NodeID id)       // push the node to current worklist
::popFromWorklist()                 // pop the node from the current worklist
::isInWorklist(NodeID id)           // check the node id whether in worklist
::isWorklistEmpty()                 // check the worklist whether is empty
```

**SVF :: AndersenPTA**

```
::addCopyEdge(NodeID src, NodeID dst) // add the copy edge from src to dst
```

**SVF :: ConstraintGraph**

```
::getConstraintNode(nodeId id)     //get the following node from ConsG
::dump()                           // dump the ConsG
```

**SVF :: ConstraintNode**

```
::getStoreInEdge() // get incoming store edge of the node also in Copy/Addr/Load
::getStoreOutEdge() //get outgoing store edge of the node also in Copy/Addr/Load
::getDirectOutEdge()// get all Copy/call/ret/gep outgoing edge of the node
::getDirectInEdge() // get all Copy/call/ret/gep incoming edge of the node
```

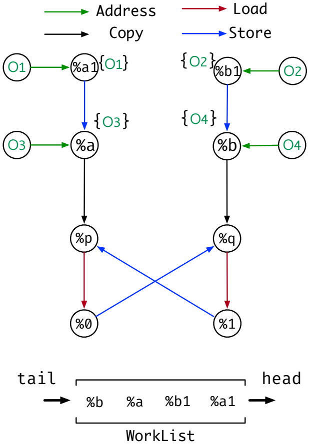
https://github.com/SVF-tools/SVF-Teaching/wiki/SVF-CPP-API#worklist-operations
https://github.com/SVF-tools/SVF-Teaching/wiki/SVF-CPP-API#points-to-set-operations

https://github.com/SVF-tools/SVF-Teaching/wiki/SVF-CPP-API#constraintgraph-constraintnode-and-constraintedge

# Andersen’s Pointer Analysis

## Constraint graph before the while loop worklist solving

```
define i32 @main() #0 {
entry:
%a1 = alloca i8, align 1        // O1
%b1 = alloca i8, align 1        // O2
%a = alloca i8*, align 8        // O3
%b = alloca i8*, align 8        // O4
store i8* %a1, i8** %a, align 8
store i8* %b1, i8** %b, align 8
call void @swap(i8** %a, i8** %b)
ret i32 0
}
define void @swap(i8** %p, i8** %q)
#0 {
entry:
%0 = load i8** %p, align 8
%1 = load i8** %q, align 8
store i8* %1, i8** %p, align 8
store i8* %0, i8** %q, align 8
ret void
}
```

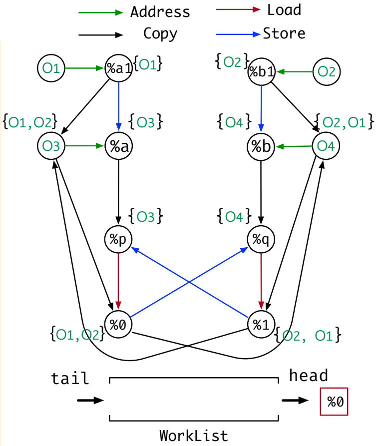


```
G = < V,E >   // Constraint Graph
V: a set of nodes in graph
E: a set of edges in graph
WorkList: a vector of nodes
foreach address p = &o do  // address rule
      pts(p) = {o}
      pushIntoWorklist(p)
while WorkList ≠ ∅ do
   p ← popFromWorklist()
   foreach o ∈ pts(p) do
      foreach store *p = q do// store rule
         if q→o ∉ E then
            E ← E ∪ {q→o}  // add copy edge
            pushIntoWorklist(q)
      foreach load r = *p do  // load rule
         if o→r ∉ E then
            E ← E ∪ {o→r}  // add copy edge
            pushIntoWorklist(o)
   foreach p→x ∈ E do         // copy rule
       pts(x) ← pts(x) ∪ pts(p)
       if pts(x) changed then
          pushIntoWorklist(x)
```

# Andersen’s Pointer Analysis

## Constraint graph after the while loop worklist solving

```
define i32 @main() #0 {
entry:
%a1 = alloca i8, align 1        // O1
%b1 = alloca i8, align 1        // O2
%a = alloca i8*, align 8        // O3
%b = alloca i8*, align 8        // O4
store i8* %a1, i8** %a, align 8
store i8* %b1, i8** %b, align 8
call void @swap(i8** %a, i8** %b)
ret i32 0
}
define void @swap(i8** %p, i8** %q)
#0 {
entry:
%0 = load i8** %p, align 8
%1 = load i8** %q, align 8
store i8* %1, i8** %p, align 8
store i8* %0, i8** %q, align 8
ret void
}
```



```
G = < V,E >  // Constraint Graph
V: a set of nodes in graph
E: a set of edges in graph
WorkList: a vector of nodes
foreach address p = &o do  // address rule
      pts(p) = {o}
      pushIntoWorklist(p)
while WorkList ≠ ∅ do
    p ← popFromWorklist()
    foreach o ∈ pts(p) do
        foreach store *p = q do// store rule
            if q→o ∉ E then
                E ← E ∪ {q→o}  // add copy edge
                pushIntoWorklist(q)
        foreach load r = *p do  // load rule
            if o→r ∉ E then
                E ← E ∪ {o→r}  // add copy edge
                pushIntoWorklist(o)
    foreach p→x ∈ E do          // copy rule
        pts(x) ← pts(x) ∪ pts(p)
        if pts(x) changed then
            pushIntoWorklist(x)
```

# What’s next?

- (1) Understand data-dependence in today’s slides
- (2) Implement Andersen’s pointer analysis, i.e., Task in Assignment 3
    - Refer to ‘Assignment-3.pdf‘ on Canvas to know more about Assignment 3.