

# Assignment 3

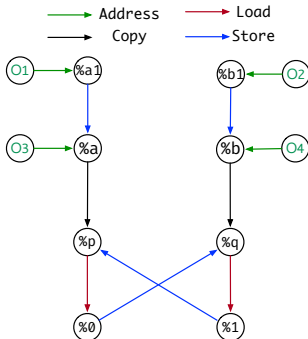
Yulei Sui

University of Technology Sydney, Australia

# Andersen's Pointer Analysis

## Algorithm

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define i32 @main() #0 {  
  entry:  
  %a1 = alloca i8, align 1      // O1  
  %b1 = alloca i8, align 1      // O2  
  %a = alloca i8*, align 8      // O3  
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  store i8* %a1, i8** %a, align 8  
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  call void @swap(i8** %a, i8** %b)  
  ret i32 0  
}  
define void @swap(i8** %p, i8** %q)  
#0 {  
  entry:  
  %0 = load i8** %p, align 8  
  %1 = load i8** %q, align 8  
  store i8* %1, i8** %p, align 8  
  store i8* %0, i8** %q, align 8  
  ret void  
}
```



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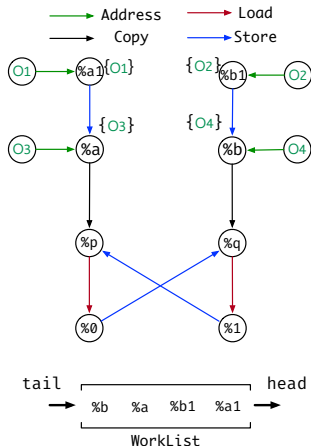
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G = < V, E > // Constraint Graph  
V: a set of nodes in graph  
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WorkList: a vector of nodes  
1 foreach address p = &o do // address rule  
2   pts(p) = {o}  
3   pushIntoWorklist(p)  
4 while WorkList != ∅ do  
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6   foreach o ∈ pts(p) do  
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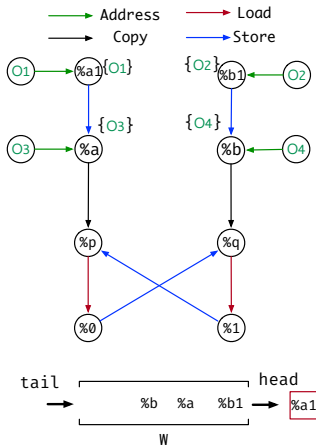
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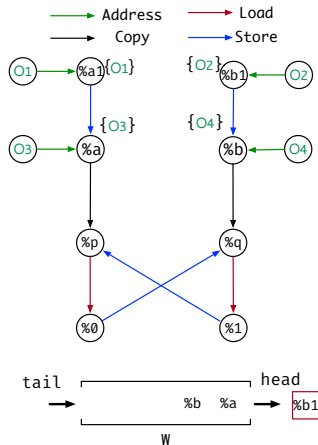
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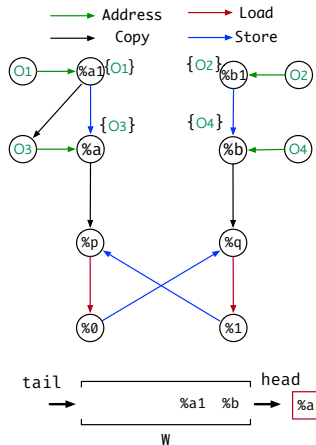
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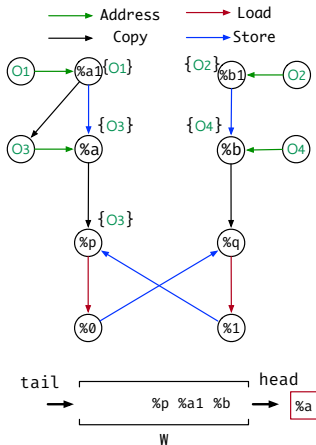
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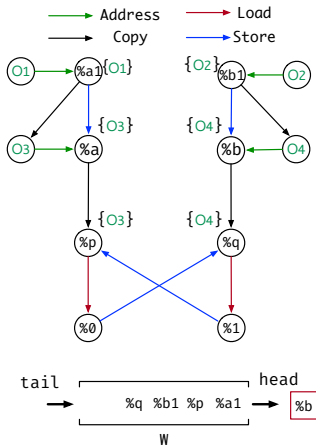


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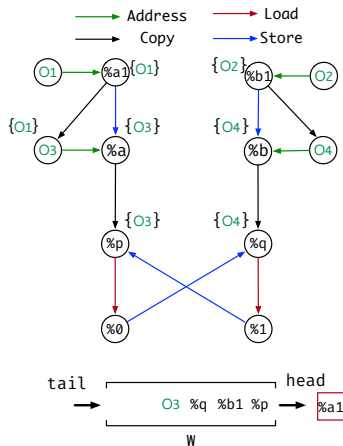
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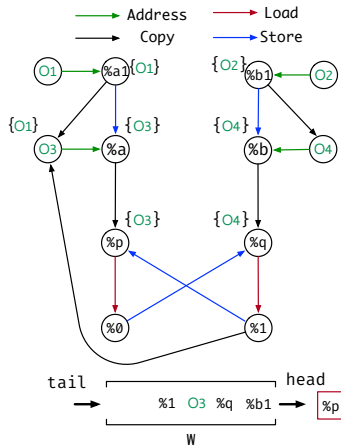
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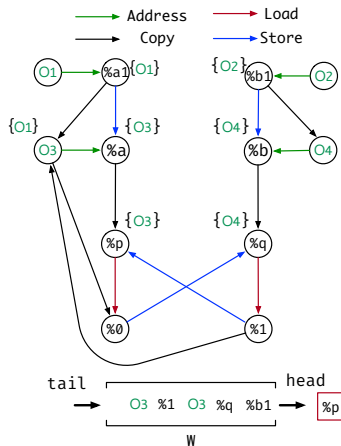
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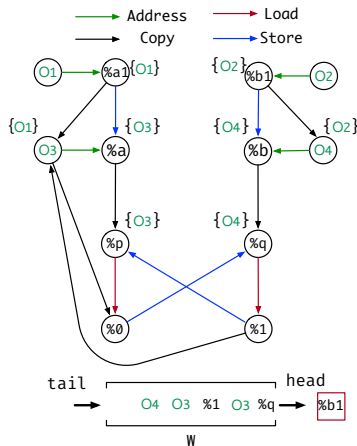
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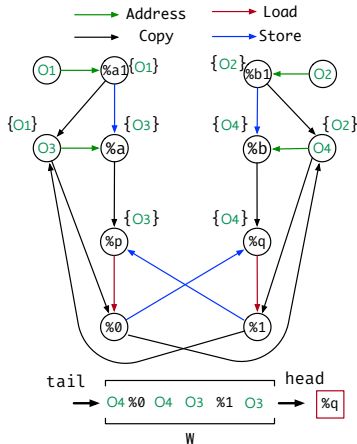
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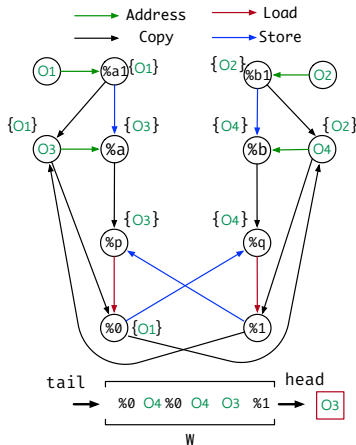
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12        if o → r ∉ E then
13          E ← E ∪ {o → r} // add copy edge
14          pushIntoWorklist(o)
15      foreach p → x ∈ E do // copy rule
16        pts(x) ← pts(x) ∪ pts(p)
17        if pts(x) changed then
18          pushIntoWorklist(x)
```

---

# Andersen's Pointer Analysis

## Algorithm

```
define i32 @main() #0 {  
  entry:  
  %a1 = alloca i8, align 1      // O1  
  %b1 = alloca i8, align 1      // O2  
  %a = alloca i8*, align 8      // O3  
  %b = alloca i8*, align 8      // O4  
  store i8* %a1, i8** %a, align 8  
  store i8* %b1, i8** %b, align 8  
  call void @swap(i8** %a, i8** %b)  
  ret i32 0  
}  
define void @swap(i8** %p, i8** %q)  
#0 {  
  entry:  
  %0 = load i8** %p, align 8  
  %1 = load i8** %q, align 8  
  store i8* %1, i8** %p, align 8  
  store i8* %0, i8** %q, align 8  
  ret void  
}
```



---

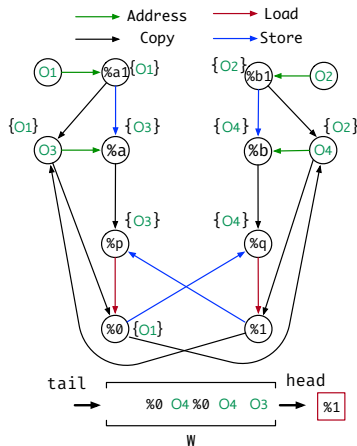
```
G = < V, E > // Constraint Graph  
V: a set of nodes in graph  
E: a set of edges in graph  
WorkList: a vector of nodes  
1 foreach address p = &o do // address rule  
2   pts(p) = {o}  
3   pushIntoWorklist(p)  
4 while WorkList ≠ ∅ do  
5   p ← popFromWorklist()  
6   foreach o ∈ pts(p) do  
7     foreach store *p = q do // store rule  
8       if q → o ∉ E then  
9         E ← E ∪ {q → o} // add copy edge  
10        pushIntoWorklist(q)  
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16   pts(x) ← pts(x) ∪ pts(p)  
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```

---

# Andersen's Pointer Analysis

## Algorithm

```
define i32 @main() #0 {
entry:
%a1 = alloca i8, align 1           // O1
%b1 = alloca i8, align 1           // O2
%a = alloca i8*, align 8           // O3
%b = alloca i8*, align 8           // O4
store i8* %a1, i8** %a, align 8
store i8* %b1, i8** %b, align 8
call void @swap(i8** %a, i8** %b)
ret i32 0
}
define void @swap(i8** %p, i8** %q)
#0 {
entry:
%0 = load i8** %p, align 8
%1 = load i8** %q, align 8
store i8* %1, i8** %p, align 8
store i8* %0, i8** %q, align 8
ret void
}
```




---

```
G = < V, E > // Constraint Graph
V: a set of nodes in graph
E: a set of edges in graph
WorkList: a vector of nodes

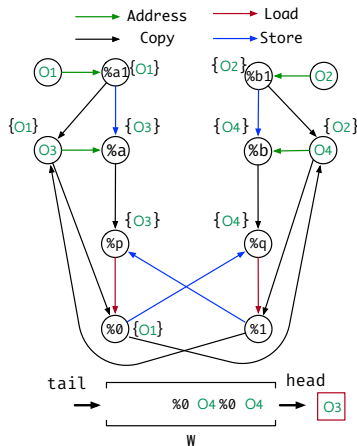
1 foreach address p = &o do // address rule
2   pts(p) = {o}
3   pushIntoWorklist(p)
4 while WorkList ≠ ∅ do
5   p ← popFromWorklist()
6   foreach o ∈ pts(p) do
7     foreach store *p = q do // store rule
8       if q → o ∉ E then
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```

---

# Andersen's Pointer Analysis

## Algorithm

```
define i32 @main() #0 {
entry:
%a1 = alloca i8, align 1           // O1
%b1 = alloca i8, align 1           // O2
%a = alloca i8*, align 8           // O3
%b = alloca i8*, align 8           // O4
store i8* %a1, i8** %a, align 8
store i8* %b1, i8** %b, align 8
call void @swap(i8** %a, i8** %b)
ret i32 0
}
define void @swap(i8** %p, i8** %q)
#0 {
entry:
%0 = load i8** %p, align 8
%1 = load i8** %q, align 8
store i8* %1, i8** %p, align 8
store i8* %0, i8** %q, align 8
ret void
}
```




---

```
G = < V, E > // Constraint Graph
V: a set of nodes in graph
E: a set of edges in graph
WorkList: a vector of nodes

1 foreach address p = &o do // address rule
2   pts(p) = {o}
3   pushIntoWorklist(p)
4 while WorkList ≠ ∅ do
5   p ← popFromWorklist()
6   foreach o ∈ pts(p) do
7     foreach store *p = q do // store rule
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14          pushIntoWorklist(o)
15      foreach p → x ∈ E do // copy rule
16        pts(x) ← pts(x) ∪ pts(p)
17        if pts(x) changed then
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```

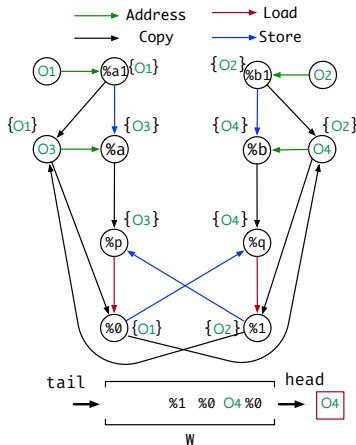
---



# Andersen's Pointer Analysis

## Algorithm

```
define i32 @main() #0 {  
  entry:  
  %a1 = alloca i8, align 1      // O1  
  %b1 = alloca i8, align 1      // O2  
  %a = alloca i8*, align 8      // O3  
  %b = alloca i8*, align 8      // O4  
  store i8* %a1, i8** %a, align 8  
  store i8* %b1, i8** %b, align 8  
  call void @swap(i8** %a, i8** %b)  
  ret i32 0  
}  
define void @swap(i8** %p, i8** %q)  
#0 {  
  entry:  
  %0 = load i8** %p, align 8  
  %1 = load i8** %q, align 8  
  store i8* %1, i8** %p, align 8  
  store i8* %0, i8** %q, align 8  
  ret void  
}
```

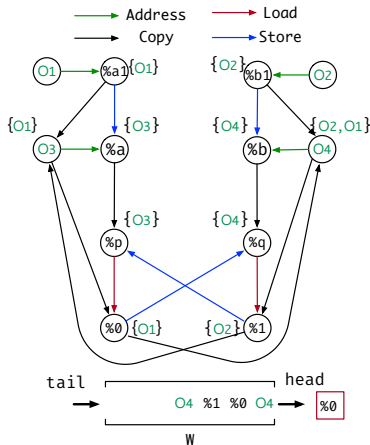


```
G = < V, E > // Constraint Graph  
V: a set of nodes in graph  
E: a set of edges in graph  
WorkList: a vector of nodes  
1 foreach address p = &o do // address rule  
2   pts(p) = {o}  
3   pushIntoWorklist(p)  
4 while WorkList ≠ ∅ do  
5   p ← popFromWorklist()  
6   foreach o ∈ pts(p) do  
7     foreach store *p = q do // store rule  
8       if q → o ∉ E then  
9         E ← E ∪ {q → o} // add copy edge  
10        pushIntoWorklist(q)  
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13          E ← E ∪ {o → r} // add copy edge  
14          pushIntoWorklist(o)  
15  foreach p → x ∈ E do // copy rule  
16    pts(x) ← pts(x) ∪ pts(p)  
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```

# Andersen's Pointer Analysis

## Algorithm

```
define i32 @main() #0 {
entry:
%a1 = alloca i8, align 1           // O1
%b1 = alloca i8, align 1           // O2
%a = alloca i8*, align 8           // O3
%b = alloca i8*, align 8           // O4
store i8* %a1, i8** %a, align 8
store i8* %b1, i8** %b, align 8
call void @swap(i8** %a, i8** %b)
ret i32 0
}
define void @swap(i8** %p, i8** %q)
#0 {
entry:
%0 = load i8** %p, align 8
%1 = load i8** %q, align 8
store i8* %1, i8** %p, align 8
store i8* %0, i8** %q, align 8
ret void
}
```




---

```

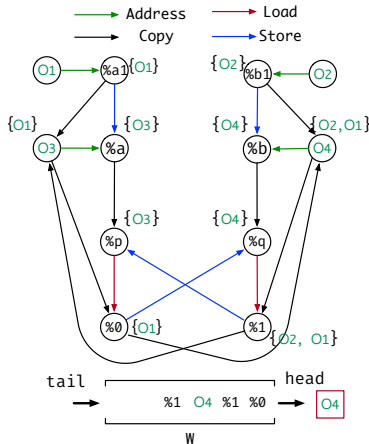
G = < V, E > // Constraint Graph
V: a set of nodes in graph
E: a set of edges in graph
WorkList: a vector of nodes
1 foreach address p = &o do // address rule
2   pts(p) = {o}
3   pushIntoWorklist(p)
4 while WorkList ≠ ∅ do
5   p ← popFromWorklist()
6   foreach o ∈ pts(p) do
7     foreach store *p = q do // store rule
8       if q → o ∉ E then
9         E ← E ∪ {q → o} // add copy edge
10        pushIntoWorklist(q)
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12        if o → r ∉ E then
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14          pushIntoWorklist(o)
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16    pts(x) ← pts(x) ∪ pts(p)
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```

---

# Andersen's Pointer Analysis

## Algorithm

```
define i32 @main() #0 {  
  entry:  
  %a1 = alloca i8, align 1      // O1  
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  %b = alloca i8*, align 8      // O4  
  store i8* %a1, i8** %a, align 8  
  store i8* %b1, i8** %b, align 8  
  call void @swap(i8** %a, i8** %b)  
  ret i32 0  
}  
define void @swap(i8** %p, i8** %q)  
#0 {  
  entry:  
  %0 = load i8** %p, align 8  
  %1 = load i8** %q, align 8  
  store i8* %1, i8** %p, align 8  
  store i8* %0, i8** %q, align 8  
  ret void  
}
```

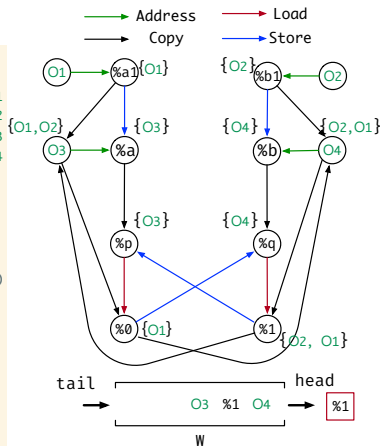


```
G = < V, E > // Constraint Graph  
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WorkList: a vector of nodes  
1 foreach address p = &o do // address rule  
2   pts(p) = {o}  
3   pushIntoWorklist(p)  
4 while WorkList ≠ ∅ do  
5   p ← popFromWorklist()  
6   foreach o ∈ pts(p) do  
7     foreach store *p = q do // store rule  
8       if q → o ∉ E then  
9         E ← E ∪ {q → o} // add copy edge  
10        pushIntoWorklist(q)  
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## Algorithm

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    %a1 = alloca i8, align 1           // O1
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    %a = alloca i8*, align 8           // O3
    %b = alloca i8*, align 8           // O4
    store i8* %a1, i8** %a, align 8
    store i8* %b1, i8** %b, align 8
    call void @swap(i8** %a, i8** %b)
    ret i32 0
}

define void @swap(i8** %p, i8** %q)
#0 {
entry:
    %0 = load i8** %p, align 8
    %1 = load i8** %q, align 8
    store i8* %1, i8** %p, align 8
    store i8* %0, i8** %q, align 8
    ret void
}
```



```

G = < V, E > // Constraint Graph
V: a set of nodes in graph
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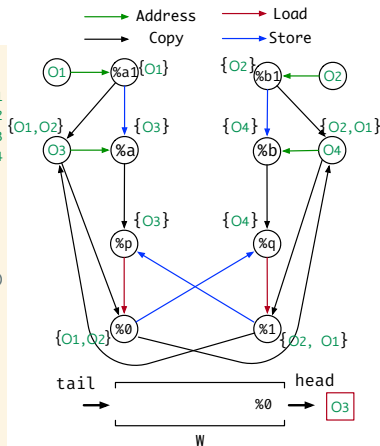
1 foreach address p = &o do // address rule
2     pts(p) = {o}
3     pushIntoWorklist(p)
4 while WorkList ≠ ∅ do
5     p ← popFromWorklist()
6     foreach o ∈ pts(p) do
7         foreach store *p = q do // store rule
8             if q → o ∉ E then
9                 E ← E ∪ {q → o} // add copy edge
10                pushIntoWorklist(q)
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```

# Andersen's Pointer Analysis

## Algorithm

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  store i8* %a1, i8** %a, align 8  
  store i8* %b1, i8** %b, align 8  
  call void @swap(i8** %a, i8** %b)  
  ret i32 0  
}  
define void @swap(i8** %p, i8** %q)  
#0 {  
  entry:  
  %0 = load i8** %p, align 8  
  %1 = load i8** %q, align 8  
  store i8* %1, i8** %p, align 8  
  store i8* %0, i8** %q, align 8  
  ret void  
}
```



---

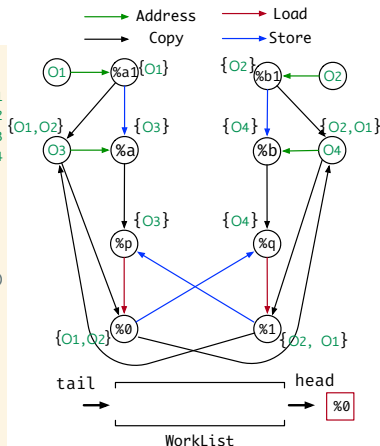
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WorkList: a vector of nodes  
1 foreach address p = &o do // address rule  
2   pts(p) = {o}  
3   pushIntoWorklist(p)  
4 while WorkList != ∅ do  
5   p ← popFromWorklist()  
6   foreach o ∈ pts(p) do  
7     foreach store *p = q do // store rule  
8       if q → o ∉ E then  
9         E ← E ∪ {q → o} // add copy edge  
10        pushIntoWorklist(q)  
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  store i8* %a1, i8** %a, align 8  
  store i8* %b1, i8** %b, align 8  
  call void @swap(i8** %a, i8** %b)  
  ret i32 0  
}  
define void @swap(i8** %p, i8** %q)  
#0 {  
  entry:  
  %0 = load i8** %p, align 8  
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  store i8* %1, i8** %p, align 8  
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  ret void  
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```



---

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---