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# Operating Systems

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# Process Synchronization

# Last class



- Producer - Consumer
- Implementation of counter
- Race condition
- Critical Section Problem
  - Structure
- 3 – requirements
  - Mutual Exclusion
  - Progress
  - Bounded Waiting
- 2 solutions
  - Solution 1 : Turn variable
  - Solution 2: Turn and flag[i]

# Hardware approach

- **Test\_and\_Set** instruction used to write to a memory location and return its old value as a single atomic (i.e., non-interruptible) operation.
- **Definition of the TestAndSet () instruction:**

```
boolean TestAndSet(boolean *target) {  
    boolean rv = *target;  
    *target = true;  
  
    return rv;  
}
```

# Mutual Exclusion with Test\_and\_Set instruction



Shared data: Boolean lock = false;

**Process  $P_0$**

```
do {  
  while (Test_And_Set( &lock))  
    ; //wait  
  critical section  
  lock = false;  
  remainder section  
} while (TRUE);
```

**Process  $P_1$**

```
do {  
  while (Test_And_Set( &lock))  
    ; //wait  
  critical section  
  lock = false;  
  remainder section  
} while (TRUE);
```

```
boolean TestAndSet(boolean *target)  
{ boolean rv = *target; *target = true; return rv; }
```

# swap () instruction



- Atomically swap two variables.

```
void Swap(boolean *a, boolean *b) {  
    boolean temp = *a;  
    *a = *b;  
    *b = temp;  
}
```

# Mutual Exclusion with Swap



Shared data (initialized to **false**):  
**boolean lock;**

Process  $P_i$

```
do {  
    key = true;  
    while (key == true)  
        Swap(lock, key);  
    critical section  
    lock = false;  
    remainder section  
} while (TRUE);
```

# Semaphores

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- is a variable which is treated in a special way
- allow processes to make use of critical section in exclusion to other processes
- is a synchronization tool that does not require busy waiting.
- process wanting to access critical section locks semaphore and releases lock on exit.



# Contd...



- Basic properties of semaphore:
    - Semaphore  $S$  – integer variable
    - can only be accessed via two operations
- wait (S):***
- ```
while  $S \leq 0$  do no-op;  
     $S--$ ;
```
- signal (S):***
- ```
 $S++$ ;
```
- Semaphore operation is atomic and indivisible
    - wait and signal operations are carried out without interruption
  - Binary semaphore : can have two values 0 and 1
  - On some systems, binary semaphores are known as **mutex locks**, as they are locks that provide *mutual exclusion*.

# Critical Section of $n$ Processes



Shared data:

**semaphore mutex;**

*//initially mutex = 1*

Process  $P_i$ :

**do {**

remainder section

**wait(mutex);**

critical section

**signal(mutex);**

remainder section

**} while (1);**

# Contd...



- semaphore can be used to solve various synchronization problems
- Example : two concurrent processes : P1 (with S1) and P2 (with S2) and semaphore variable : synch initialized to zero.

- requirement : **s2 should be executed only after s1 is executed**

P1:

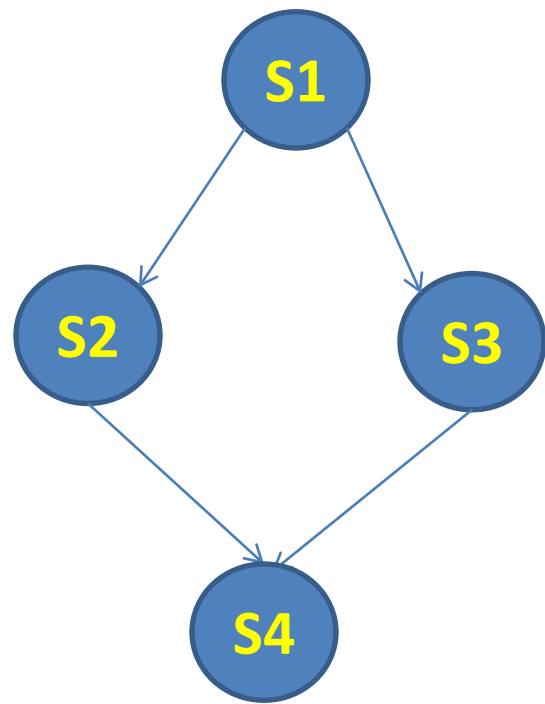
S1;

signal (synch);

P2:

wait (synch);

S2;



semaphore a, b, c, d // all are initialized  
to zero

begin

cobegin

begin S1; signal(a), signal (b) ; end

begin wait (a); S2; signal (c) ; end

begin wait (b); S3; signal (d) ; end

begin wait (c ); wait (d); S4; end

coend

end

# Contd...



- Main disadvantage : Busy Waiting
- semaphore is also called a **spinlock** because the process "spins" while waiting for the lock.
- To overcome busy waiting, we need to modify the definition of the wait () and signal () semaphore operations.

# Semaphore Implementation

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Define a semaphore as a record

```
typedef struct {  
    int value;  
    struct process *L;  
} semaphore;
```

Assume two simple operations:

- **block** suspends the process that invokes it.
- **wakeup(*P*)** resumes the execution of a blocked process **P**.

# Implementation

Semaphore operations now defined as

*wait(S):*

**S.value--;**

**if (S.value < 0) {**

add this process to **S.L**;  
**block;**

**}**

*signal(S):*

**S.value++;**

**if (S.value <= 0) {**

remove a process **P** from **S.L**;  
**wakeup(P);**

**}**

P1:

wait(S)

CS

signal(S)

RS

P2:

wait(S)

CS

signal(S)

RS

# Contd...



- The block operation places a process into a waiting queue associated with the semaphore, and the state of the process is switched to the waiting state.
- CPU scheduler selects another process to execute.
- wakeup () operation changes the process from the waiting state to the ready state



# Deadlock and Starvation

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**Deadlock** – two or more processes are waiting indefinitely for an event that can be caused by only one of the waiting processes.

**Starvation** – indefinite blocking. A process may never be removed from the semaphore queue in which it is suspended.

# Two Types of Semaphores

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- *Counting* semaphore – integer value can range over an unrestricted domain.
- *Binary* semaphore – integer value can range only between 0 and 1; can be simpler to implement.



# Classical Problems of Synchronization

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**Bounded-Buffer Problem**

Readers and Writers Problem

Dining-Philosophers Problem

# Bounded-Buffer Problem

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- Also known as producer consumer problem
- Describes two processes Producer and Consumer share a common fixed size buffer (queue)
- producer is to either go to sleep or discard data if the buffer is full
  - when consumer consumes a data item, notifies producer
- consumer can go to sleep if it finds the buffer to be empty.
  - when producer puts data into the buffer, it wakes up the sleeping consumer.
- An inadequate solution could result in a deadlock where both processes are waiting to be awakened.
- Best solution to use semaphore

# contd...



Contains buffer of size  $n$

3 semaphores:

- full : the number of items to be read from the buffer

- empty: number of empty spaces that are available

- mutex : provides mutual exclusion for the accesses to the buffer

**semaphore full, empty, mutex;**

Initially:

**full = 0, empty =  $n$ , mutex = 1**

*wait (S): while  $S \leq 0$  do no-op;*  
                  *S--;*  
*signal (S): S++;*



Producer Process:

```
do {  
  ...  
  produce an item in nextp  
  ...  
  wait(empty);  
  wait(mutex);  
  ...  
  add nextp to buffer  
  ...  
  signal(mutex);  
  signal(full);  
} while (1);
```

Consumer Process:

```
do {  
  wait(full)  
  wait(mutex);  
  ...  
  remove an item from buffer to  
  nextc  
  ...  
  signal(mutex);  
  signal(empty);  
  ...  
  consume the item in nextc  
  ...  
} while (1);
```