Hw14 Lifelong Learning

ML TAS

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Outline

- Introduction
- Dataset
- Sample Code
- COOL Quiz
- Grading
- Submission

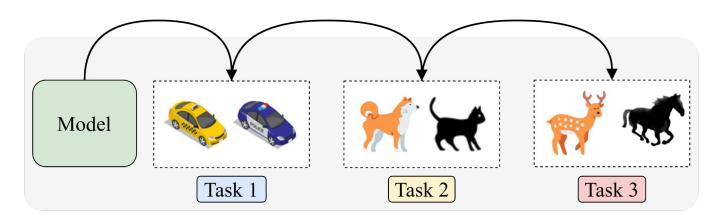
Introduction - LifeLong Learning

Goal: A model can beat all task!



Introduction - LifeLong Learning

Condition: Model Sequentially Learn Different Task! (In Training Time)



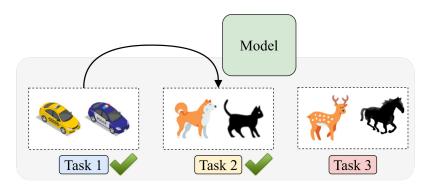
Introduction - LifeLong Learning

KeyPoint: Avoid Catastrophic Forgetting

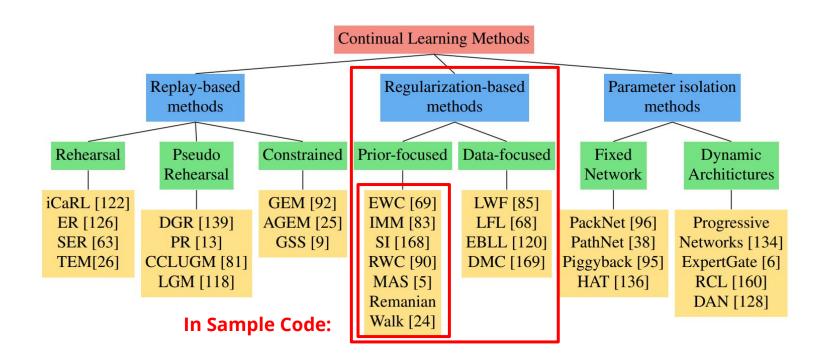
Catastrophic Forgetting

Task 1 Task 2 Task 3

Avoid Catastrophic Forgetting

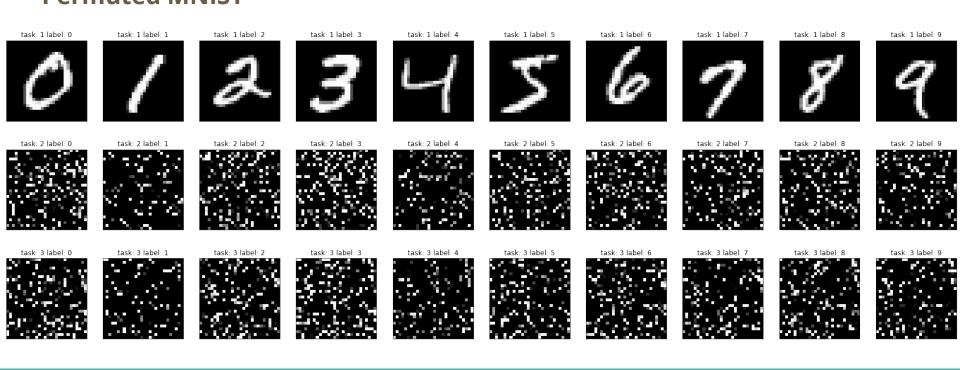


Introduction



Dataset

Permuted MNIST

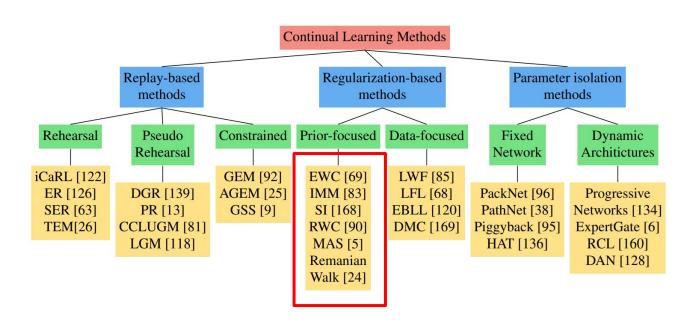


Sample Code - Training Detail

- 5 task / Each task has 10 epoches for training.
- Each method cost ~20 minutes for training model.
- <u>CoLab Link</u> (copy to your drive first! Don't simply run colab.)

Sample Code - Methods

- Baseline
- EWC
- MAS
- SI
- RWalk
- SCP

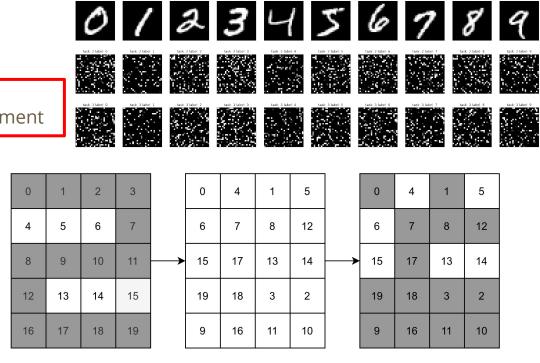


Sample Code - Guideline

- Utility
- Visualization
- Methods

- Utility
 - Permutation
 - Dataloader and Training Argument
 - Model
 - o train
 - evaluate
 - evaluate metric
- Visualization
- Methods

- Utility
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 - evaluate metric
- Visualization
- Methods



INPUT

PERMUTATION

OUTPUT

5 PERMUTATION = 5 TASK

Fixed model size!

- Utility
 - Permutation
 - Dataloader and
 - Model
 - train
 - evaluate
 - evaluate metric
- Visualization
- Methods

```
Model(
    (fc1): Linear(in_features=784, out_features=1024, bias=True)
    (fc2): Linear(in_features=1024, out_features=512, bias=True)
    (fc3): Linear(in_features=512, out_features=256, bias=True)
    (fc4): Linear(in_features=256, out_features=10, bias=True)
    (relu): ReLU()
)
```

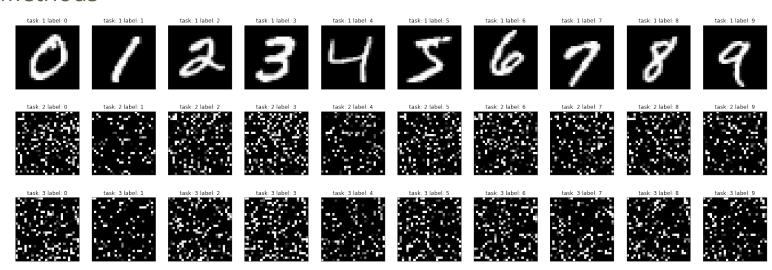
- Utility
 - Permutation
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 - o train
 - evaluate
 - evaluate metric

In k th task:

$$AverageAccuracy_k = rac{1}{k}\Sigma_{j=1}^k a_{k,j}$$

- Visualization
- Methods

- Utility
- Visualization
- Methods



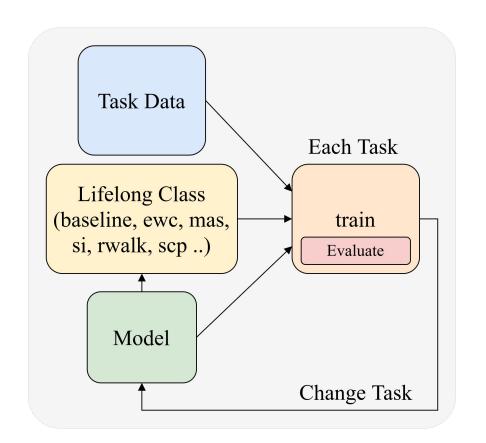
Sample Code - Guideline

- Utility
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 - Baseline
 - o EWC
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 - o SI
 - RWalk
 - SCP

Baseline

Sequentially Train

Training Pipeline:



Lifelong learning class

Lifelong Class (baseline, ewc, mas, si, rwalk, scp ..)

```
6 class baseline(object):
      baseline technique: do nothing in regularization term [initialize and all weight is zero]
 9
10
      def init (self, model, dataloaders, device):
11
12
           self.model = model
13
           self.dataloaders = dataloaders
14
           self.device = device
15
16
          self.params = {n: p for n, p in self.model.named parameters() if p.requires grad} #extract all parameters in models
17
          self.p old = {} # store current parameters
          self._precision_matrices = self. calculate_importance() # generate weight matrix
18
19
20
           for n, p in self.params.items():
               self.p old[n] = p.clone().detach() # keep the old parameter in self.p old
21
22
      def calculate importance(self):
23
24
          precision matrices = {}
25
           for n, p in self.params.items(): # initialize weight matrix (fill zero)
26
               precision matrices[n] = p.clone().detach().fill (0)
27
28
           return precision matrices
29
30
      def penalty(self, model: nn.Module)
31
32
           for n, p in model.named parameters():
33
               loss = self. precision matrices[n] * (p - self.p old[n]) ** 2
34
               loss += loss.sum()
35
           return loss
36
      def update(self, model):
37
38
           # do nothing
           return
```

Lifelong learning class

Lifelong Class (baseline, ewc, mas, si, rwalk, scp ..)

train

```
6 class baseline(object):
       baseline technique: do nothing in regularization term [initialize and all weight is zero]
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      def init (self, model, dataloaders, device):
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               loss += loss.sum()
           return loss
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      def update(self, model):
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           # do nothing
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```

EWC - Elastic Weight Consolidation

- 1. You need to know how to generate Guardiance weight from EWC!
- 2. Do this method need to use label?
- 3. Hint: (trace the class ewc and its calculate_importance function)

Paper Link: https://arxiv.org/pdf/1612.00796.pdf

MAS - Memory Aware Synapse

- You need to know how to generate Guardiance weight from MAS!
- 2. Do this method need to use label?
- 3. Hint: (trace the class mas and its calculate_importance function)

Paper Link: https://arxiv.org/abs/1711.09601

SI - Synaptic Intelligence

- 1. You need to know how to generate Guardiance weight from SI!
- 2. Do this method need to use label?
- 3. Hint: (Accumulated loss change in each update step)

Paper Link: https://arxiv.org/abs/1703.04200, Talk Slide

SI - Main Idea

$$L(\theta) = L_2(\theta) + c\sum_i \Omega_i \left(\theta_i - \theta_{1,i}^*\right)^2$$
 From learning trajectory

Parameter importance on-line from learning trajectory!

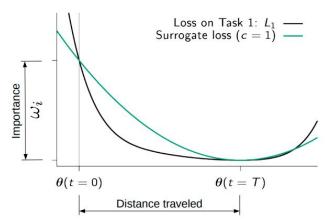
Picture comes from: Talk Slide

SI - Abstract

Leveraging per-parameter importance for continual learning

$$L(\theta) = L_2(\theta) + c \sum_{i} \Omega_i \left(\theta_i - \theta_{1,i}^* \right)^2 \qquad \Omega_i \equiv \frac{\omega_i}{(\Delta_i)^2 + \epsilon}$$

$$\Omega_i \equiv \frac{\omega_i}{(\Delta_i)^2 + \epsilon}$$



Picture comes from: Talk Slide

SI - Method

Total change in loss is given by the path integral over the gradient field

$$\int_{C} \mathbf{g}(\boldsymbol{\theta}(t)) d\boldsymbol{\theta} = \int_{t_0}^{t_1} \mathbf{g}(\boldsymbol{\theta}(t)) \cdot \boldsymbol{\theta}'(t) dt = L(t_1) - L(t_0)$$

$$= \sum_{k} \underbrace{\int_{t_0}^{t_1} g_k(t) \theta_k'(t) dt}_{t_0} \equiv -\sum_{k} \omega_k$$

• Is a parameter-specific quantity

 Can be computed on-line during training (running sum)

g: Gradient

 $\boldsymbol{\theta}$: Parameters

 $\boldsymbol{\theta'}$: Updates

Natural way of assigning credit for a global change to local parameters

$$L(t_1) - L(t_0) = -\sum_k \omega_k^{\mu}$$

Picture comes from: Talk Slide

RWalk - Remanian Walk

- Trace class rwalk and its update function!
- 2. Do this method need to use label?
- 3. Hint:(The code is similar to two method which mentioned in sample code)

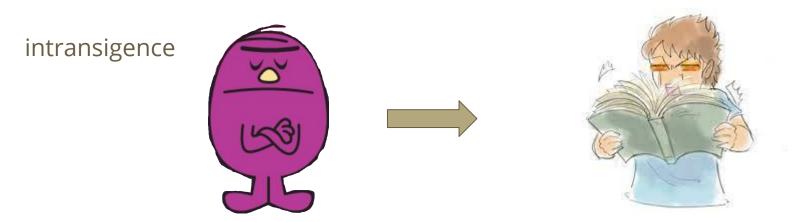
Paper Link: https://arxiv.org/abs/1801.10112

SCP - Sliced Cramer Preservation

- 1.Paper Link: https://openreview.net/pdf?id=BJge3TNKwH
- 2.Do this method need to use label?

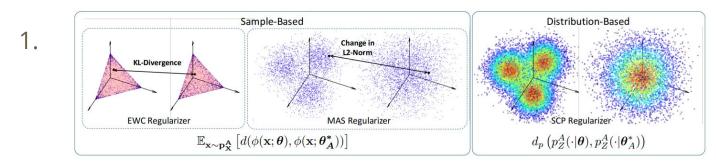
SCP - Main Idea

 Propose Distributed-based Distance to prevent fast intransigence and avoid overestimate the importance of parameter.



Model do not want to learn new task, and it just keep old task performance

SCP - Sliced Cramer Preservation (Hint)



Paper Link: https://openreview.net/pdf?id=Blge3TNKwH

COOL Quiz

- 25 multiple choice questions
- Basic Concept & Dataset : 4 Questions
- Sample Code: 15 Questions
 - EWC: 3 Questions
 - MAS: 3 Questions
 - SI: 3 Questions
 - Remanian Walk: 3 Questions
 - Sliced Cramer Preservation: 3 Questions
- Other Methods & scenario: 6 Questions
 - o ICaRL, LwF, GEM, DGR
 - Three Scenario

Grading

- All Questions (0.4pt)
- You have to choose ALL the correct answers for each question
- Warning: The answers in NTU Cool are not correct, NTU grading score before deadline is not the final grading score.
- Please do not select the choice depends on the grading score.

Submission

- No late submission!
- Deadline: 2021/07/02 23:59
 - Warning: The answers in NTU Cool are not correct, NTU grading score before deadline is not the final grading score.
- Please do not select the choice depends on the grading score.

Links

- CoLab Link
- NTU Cool Multiple Choice Question
- Warning: The answers in NTU Cool are not correct, NTU grading score before deadline is not the real grading score.
- Please do not select the choice depends on the grading score.

If any questions, you can ask us via...

- NTU COOL (recommended)
 - https://cool.ntu.edu.tw/courses/4793
- Email
 - ntu-ml-2021spring-ta@googlegroups.com
 - The title must begin with "[HW14]"
- TA hours
 - Each Monday 19:00~21:00 @Room 101, EE2 (電機二館101)
 - Each Friday 13:30~14:20 Before Class @Lecture Hall (綜合大講堂)
 - Each Friday During Class