

Machine Learning

Lecture. 10.

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• Discriminative classifiers directly provide a discriminant function of the form $f(\mathbf{x}; \mathbf{w}) = \mathbf{w}^\mathsf{T} \phi(\mathbf{x})$



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• If target values ± 1 test $g(\mathbf{x}; w_2, w_1, w_0)$ positive or negative so $f(\mathbf{x}; w_2, w_1, w_0) = \operatorname{sign}(\mathbf{w}^\mathsf{T} \mathbf{x} + w_0)$



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- For N data points $(\mathbf{x}_1, t_1) \cdots (\mathbf{x}_N, t_N)$ assume classes completely linearly separable then training data correctly classified if

$$t_n(\mathbf{w}^\mathsf{T}\mathbf{x} + w_0) > 0 \ \forall \ n = 1 \cdots N$$



Many possible solutions



Many possible solutions

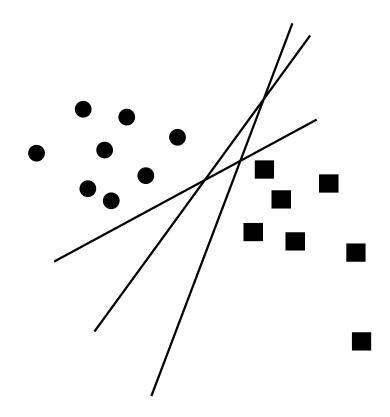


Figure 1: The samples of two classes denoted by sold circles and squares can be separated perfectly with no miss-classifications by a number of possible \mathbf{w} some examples of which are drawn on this cartoon.

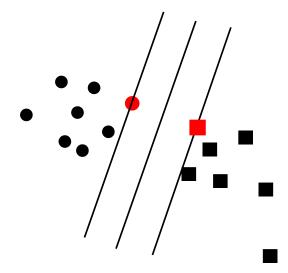
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 Upper-bound on generalisation error inversely proportional to perpendicular distance from separating hyperplane, w and hyperplane through closest points from both classes

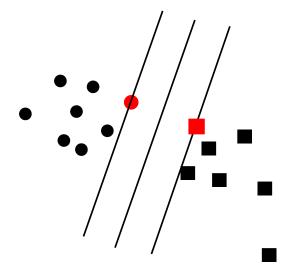


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• Called the *margin* so to minimise bound on generalisation error we seek to maximise the *margin* of our classifier



• Distance of ${\bf x}$ to hyper-plane H defined by all points that satisfy ${\bf w}^{\sf T}{\bf x}+w_0=0$ is given by

$$\frac{\mathbf{w}^\mathsf{T}\mathbf{x} + w_0}{||\mathbf{w}||}$$



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• If \mathbf{x}_1^* and \mathbf{x}_2^* are closest points from each class to \mathbf{w} margin of separation is

$$\frac{\mathbf{w}^{\mathsf{T}}\mathbf{x}_{1}^{*} + w_{0}}{||\mathbf{w}||} - \frac{\mathbf{w}^{\mathsf{T}}\mathbf{x}_{2}^{*} + w_{0}}{||\mathbf{w}||} = \frac{\mathbf{w}^{\mathsf{T}}}{||\mathbf{w}||}(\mathbf{x}_{1}^{*} - \mathbf{x}_{2}^{*})$$



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- Define canonical hyper-plane \mathbf{w} such that $\mathbf{w}^\mathsf{T}\mathbf{x}_1^* + w_0 = 1$ and $\mathbf{w}^\mathsf{T}\mathbf{x}_2^* + w_0 = -1$ in which case the margin is now simply $\frac{2}{||\mathbf{w}||}$



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- Maximise margin need to minimise $||\mathbf{w}||$ subject to all the points being correctly classified



The SVM optimisation can be written as

$$\min \frac{1}{2}||\mathbf{w}||^2$$

subject to

$$t_n(\mathbf{w}^\mathsf{T}\mathbf{x} + w_0) \ge 1 \ \forall \ n = 1 \cdots N$$

and by finding the solution to the above we will be using the \mathbf{w} in our classifier which will minimise the bound on the achievable generalisation error.



Given a constrained optimisation problem of the form

$$\min f(\mathbf{w})$$

subject to

$$g_i(\mathbf{w}) \leq 0 \quad i = 1 \cdots K$$

$$h_i(\mathbf{w}) = 0 \quad i = 1 \cdots M$$



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Form the Lagrangian function as

$$\mathcal{L}(\mathbf{w}, \boldsymbol{\alpha}, \boldsymbol{\beta}) = f(\mathbf{w}) + \sum_{i=1}^{K} \alpha_i g_i(\mathbf{w}) + \sum_{i=1}^{M} \beta_i h_i(\mathbf{w})$$



• Find maximum of $\mathcal{L}(\mathbf{w}, \boldsymbol{\alpha}, \boldsymbol{\beta})$ with respect to \mathbf{w} denoted as $\theta(\boldsymbol{\alpha}, \boldsymbol{\beta})$



- Find maximum of $\mathcal{L}(\mathbf{w}, \boldsymbol{\alpha}, \boldsymbol{\beta})$ with respect to \mathbf{w} denoted as $\theta(\boldsymbol{\alpha}, \boldsymbol{\beta})$
- Then solve the optimisation problem

$$\max \theta(\boldsymbol{\alpha}, \boldsymbol{\beta})$$

subject to

$$\alpha_i \ge 0 \quad \forall \quad i = 1 \cdots K$$



 The Lagrangian function for SVM, noting only one set of inequality constraints and no equality constraints then

$$\mathcal{L}(\mathbf{w}, w_0, \boldsymbol{\alpha}) = \frac{1}{2} ||\mathbf{w}||^2 + \sum_{n=1}^{N} \alpha_n \left(1 - t_n(\mathbf{w}^\mathsf{T} \mathbf{x}_n + w_0) \right)$$



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• Have defined each $g_i(\mathbf{w}) = 1 - t_n(\mathbf{w}^\mathsf{T}\mathbf{x}_n + w_0) \le 0$ which comes from our original constraint.



• Stationary point of $\mathcal{L}(\mathbf{w}, w_0, \boldsymbol{\alpha})$ so

$$\frac{\partial}{\partial \mathbf{w}} \mathcal{L}(\mathbf{w}, w_0, \boldsymbol{\alpha}) = \mathbf{w} - \sum_{n=1}^{N} \alpha_n t_n \mathbf{x}_n = 0 \Rightarrow \mathbf{w} = \sum_{n=1}^{N} \alpha_n t_n \mathbf{x}_n$$



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and

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• Using above define $\theta(\alpha)$ so plug-in results to $\mathcal{L}(\mathbf{w}, w_0, \alpha)$.



• Using result $\mathbf{w} = \sum_{n=1}^{N} \alpha_n t_n \mathbf{x}_n$ we should see that

$$\frac{1}{2}||\mathbf{w}||^2 = \frac{1}{2}\mathbf{w}^\mathsf{T}\mathbf{w} = \frac{1}{2}\left(\sum_{n=1}^N \alpha_n t_n \mathbf{x}_n^\mathsf{T}\right)\left(\sum_{m=1}^N \alpha_m t_m \mathbf{x}_m\right)$$
$$= \frac{1}{2}\sum_{n=1}^N \sum_{m=1}^N \alpha_n \alpha_m t_n t_m \mathbf{x}_n^\mathsf{T} \mathbf{x}_m$$



 Now the second component of our Lagrangian needs to be considered

$$\sum_{n=1}^{N} \alpha_n \left(1 - t_n(\mathbf{w}^\mathsf{T} \mathbf{x}_n + w_0) \right)$$

$$= \sum_{n=1}^{N} \alpha_n - \sum_{n=1}^{N} \alpha_n \mathbf{w}^\mathsf{T} \mathbf{x}_n - w_0 \sum_{n=1}^{N} \alpha_n t_n$$

$$= \sum_{n=1}^{N} \alpha_n - \sum_{n=1}^{N} \alpha_n \mathbf{w}^\mathsf{T} \mathbf{x}_n$$

$$= \sum_{n=1}^{N} \alpha_n - \sum_{n=1}^{N} \sum_{m=1}^{N} \alpha_n \alpha_m t_n t_m \mathbf{x}_n^\mathsf{T} \mathbf{x}_m$$



So combining the two parts we obtain

$$\theta(\boldsymbol{\alpha}) = \sum_{n=1}^{N} \alpha_n - \frac{1}{2} \sum_{n=1}^{N} \sum_{m=1}^{N} \alpha_n \alpha_m t_n t_m \mathbf{x}_n^\mathsf{T} \mathbf{x}_m$$



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• This has to be maximised with respect to all α_n , the constraints that $\alpha_n \geq 0 \quad \forall \quad n=1\cdots N$ and the additional constraint which emerges from our stationary conditions that is $\sum_{n=1}^N \alpha_n t_n = 0$



SVM optimisation problem

$$\max \sum_{n=1}^{N} \alpha_n - \frac{1}{2} \sum_{n=1}^{N} \sum_{m=1}^{N} \alpha_n \alpha_m t_n t_m \mathbf{x}_n^\mathsf{T} \mathbf{x}_m$$

subject to

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$$\sum_{n=1}^{N} \alpha_n t_n = 0$$

 There are a number of ways to solve this problem and we will employ a simple quadratic optimisation solver which is written in Matlab.



• A significant number of the α_n parameters are returned as having zero value from the optimisation



• The α_n which have non-zero values are important and as they are associated with each vector in the training sample \mathbf{x}_n these are referred to as the Support Vectors as the *support* the decision boundary between the two classes



Now discriminant function can be written as

$$f(\mathbf{x}_{new}; \mathbf{w}, w_0) = \operatorname{sign}(\mathbf{w}^\mathsf{T} \mathbf{x}_{new} + w_0)$$

$$= \operatorname{sign}\left(\sum_{n=1}^{N} t_n \alpha_n \mathbf{x}_n^\mathsf{T} \mathbf{x}_{new} + w_0\right)$$

$$= \operatorname{sign}\left(\sum_{n \in SV} t_n \alpha_n \mathbf{x}_n^\mathsf{T} \mathbf{x}_{new} + w_0\right)$$

$$= \operatorname{sign}\left(\sum_{n \in SV} t_n \alpha_n K(\mathbf{x}_n, \mathbf{x}_{new}) + w_0\right)$$



Figure (2) shows the SVM decision plane and the support vectors for this little toy data set.

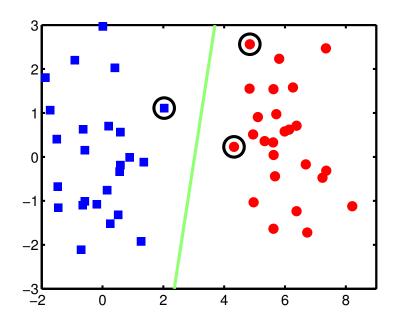


Figure 2: The SVM decision plane separating examples from two classes along with the support vectors which are highlighted. Note that there are only three non-zero α components and so only three points in the data set which are supporting the decision surface.



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- It turns out that a very simple change to the SVM optimisation is required and it changes the positivity constraint from $\alpha_n \geq 0$ to $0 \leq \alpha_n \leq C$, for all n, where C is a box constraint parameter
- Hyper-parameters consist of C and kernel parameters if any e.g. β from RBF kernel LOO needed



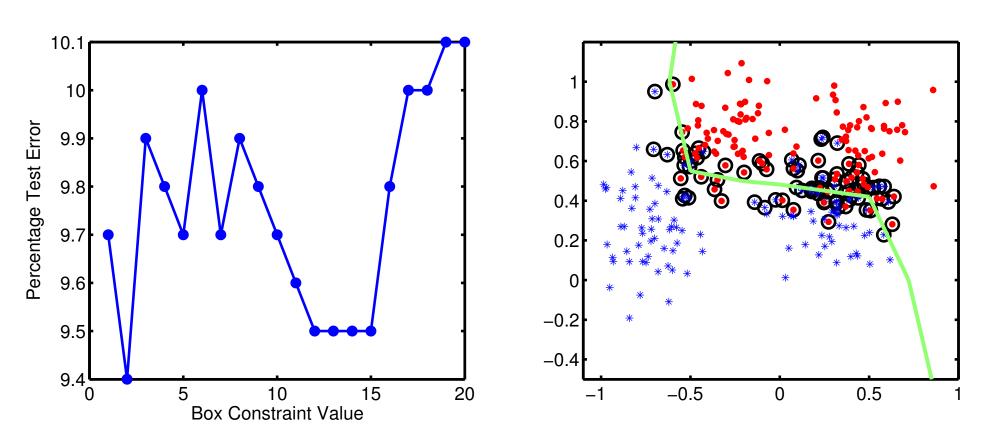


Figure 3: The left hand plot shows the test error achieved for varying values of C when using a polynomial order kernel function. The right hand plot shows the training data and the decision surface. The support vectors are highlighted and they can all be seen to be clumped around the decision surface.

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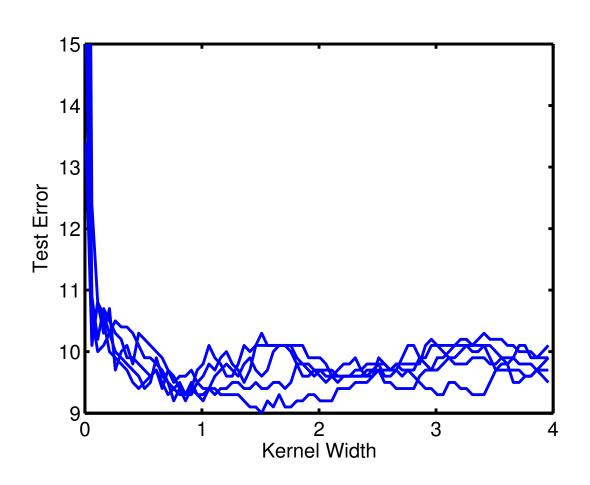


Figure 4: The percentage error achieved by an SVM using a Radial Basis Kernel function with a width parameter ranging from 0.01 to 4.0 in step sizes of 0.05. For each of these ranges a value of C was selected from 1 to 4 and we can see that the minimum test error of 9.0% was achieved with hyper-parameter values of C=1 and $\beta=1.4$.