

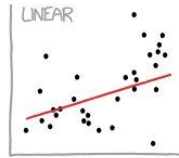
# Lecture 2: Linear models

MIPT, 2019

# Outline

1. Overview of linear models.
2. Linear regression.
3. Analytical solution.
4. Regularization.
5. Gauss-Markov theorem.
6. Probabilistic interpretation and intuition.

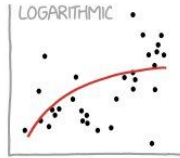
# CURVE-FITTING METHODS AND THE MESSAGES THEY SEND



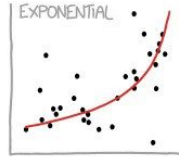
"HEY, I DID A REGRESSION."



"I WANTED A CURVED LINE, SO I MADE ONE WITH MATH."



"LOOK, IT'S TAPERING OFF!"



"LOOK, IT'S GROWING UNCONTROLLABLY!"



"I'M SOPHISTICATED, NOT LIKE THOSE BUMBLING POLYNOMIAL PEOPLE."



"I'M MAKING A SCATTER PLOT BUT I DON'T WANT TO."



"I NEED TO CONNECT THESE TWO LINES, BUT MY FIRST IDEA DIDN'T HAVE ENOUGH MATH."



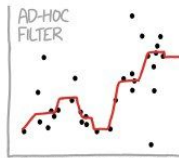
"LISTEN, SCIENCE IS HARD, BUT I'M A SERIOUS PERSON DOING MY BEST."



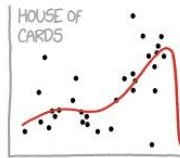
"I HAVE A THEORY, AND THIS IS THE ONLY DATA I COULD FIND."



"I CLICKED 'SMOOTH LINES' IN EXCEL."



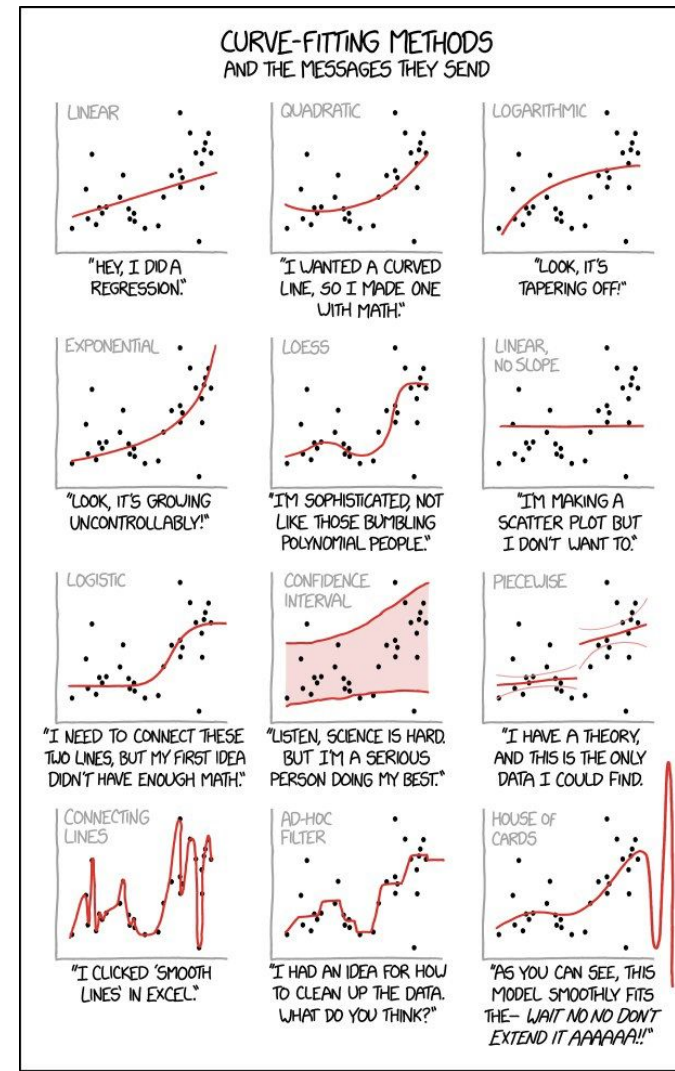
"I HAD AN IDEA FOR HOW TO CLEAN UP THE DATA. WHAT DO YOU THINK?"

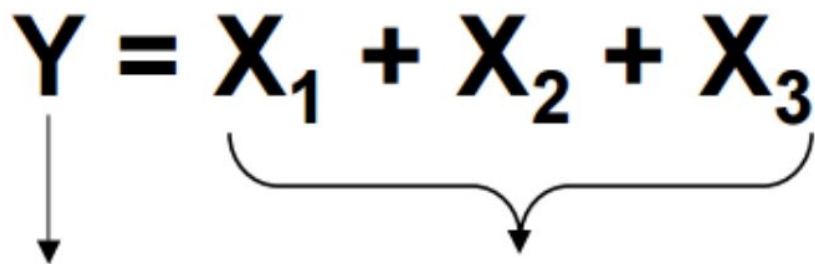


"AS YOU CAN SEE, THIS MODEL SMOOTHLY FITS THE- WAIT NO NO DON'T EXTEND IT AAAAAA!!!"

Example questions linear regression can solve (up right picture):

- What will be my monthly spending for the next year?
- Which factor is more important in deciding my monthly spending?
- How monthly income and trips per month are correlated with monthly spending?



$$Y = X_1 + X_2 + X_3$$


Dependent Variable

Outcome Variable

Response Variable

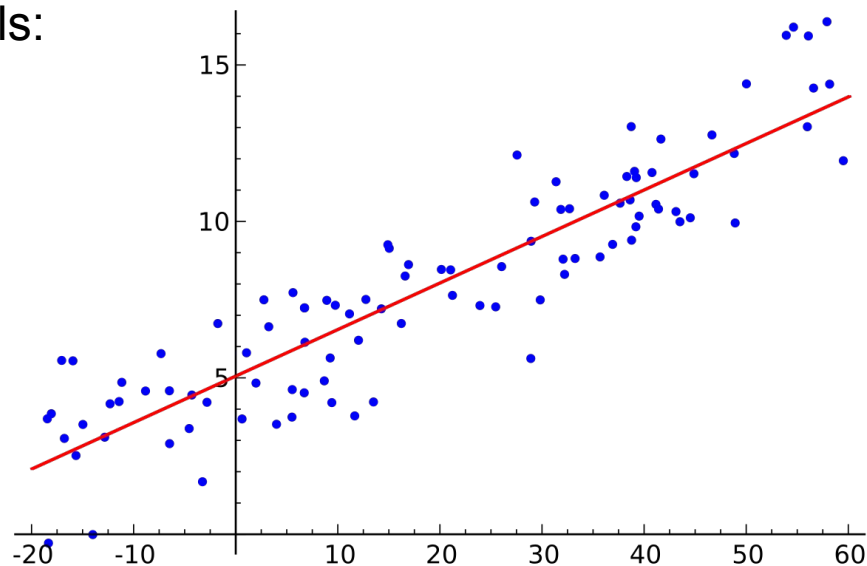
Independent Variable

Predictor Variable

Explanatory Variable

# Linear models

- Predictive models:



Estimated  
(or predicted)  
Y value for  
observation  $i$

Estimate of  
the regression  
intercept

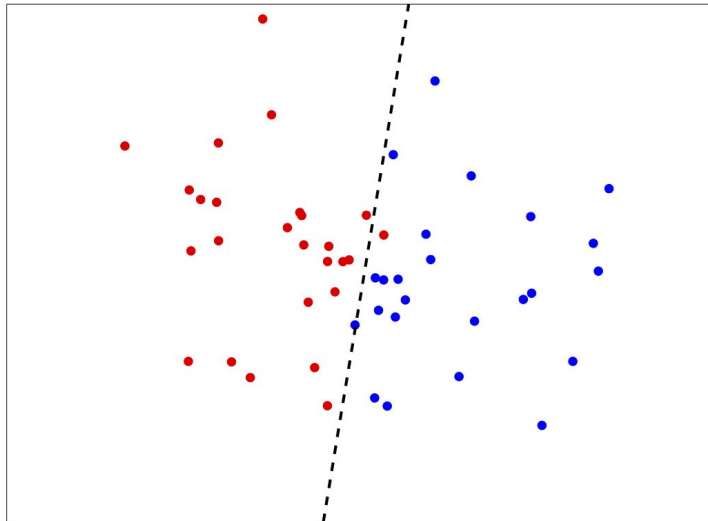
Estimate of the  
regression slope

Value of X for  
observation  $i$

$$\hat{Y}_i = b_0 + b_1 X_i$$

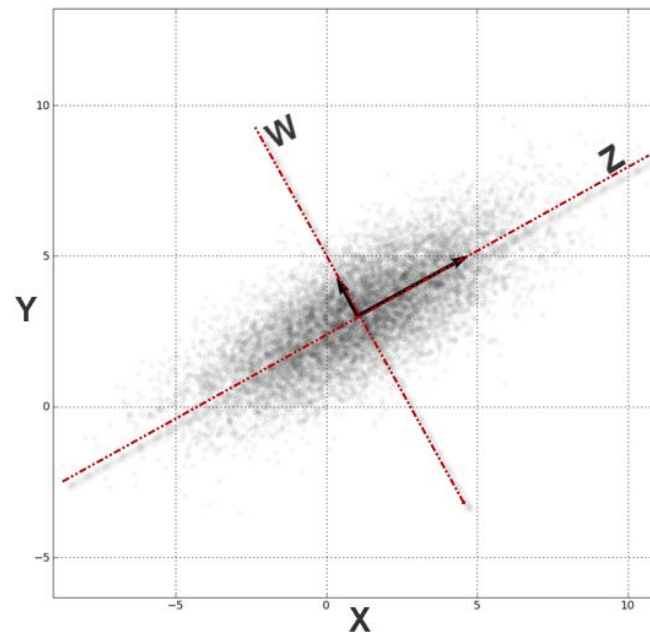
# Linear models

- Predictive models:
- Classification models:



# Linear models

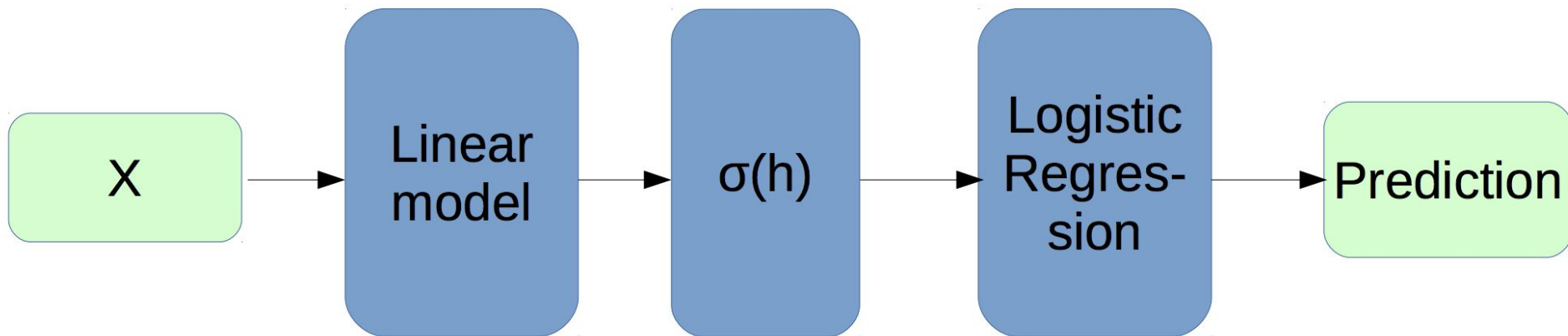
- Predictive models:
- Classification models:
- Unsupervised models (e.g. PCA analysis)





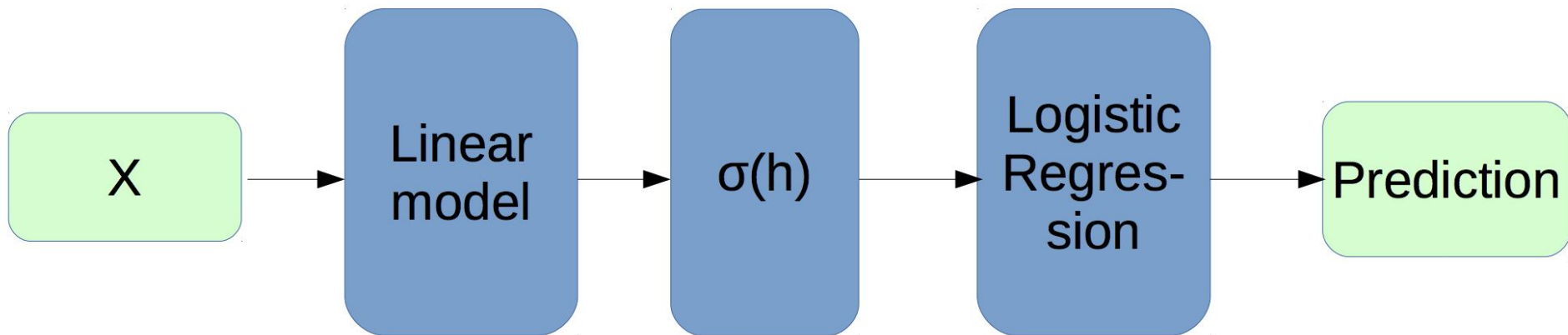
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- Building block of other models (ensembles, NNs, etc.)



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*Actually, it's a neural network. We will meet it later.*

# Linear regression

Linear regression problem statement:

- Training set  $\mathcal{L} = \{\mathbf{x}_i, y_i\}_{i=1}^n$  , where  $(\mathbf{x} \in \mathbb{R}^p, y \in \mathbb{R})$  .

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- Prediction model is linear:  $\hat{y}_i = a(w_0, \mathbf{w}, \mathbf{x}_i) = w_0 + w_1 x_{i1} + \dots w_p x_{ip}$  ,

Where  $\mathbf{w} = (w_1, \dots w_p)$  is weights vector,  $w_0$  is bias term.

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- Least squares method provides a solution:

$$\hat{\mathbf{w}} = \arg \min_{\mathbf{w}} \|\mathbf{w}_0 + (\mathbf{x}_1 \dots \mathbf{x}_n)^T \mathbf{w} - (y_1, \dots, y_n)\|_2^2$$

# Analytical solution

Denote quadratic loss function:  $Q(\mathbf{w}) = (Y - X\mathbf{w})^T(Y - X\mathbf{w}) = \|Y - X\mathbf{w}\|_2^2$ ,

where  $X = [\mathbf{x}_1, \dots, \mathbf{x}_n]$ ,  $\mathbf{x}_i \in \mathbb{R}^p$ ,  $Y = [y_1, \dots, y_n]$ ,  $y_i \in \mathbb{R}$ .

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what if this matrix is *singular*?

# Unstable solution

In case of multicollinear features the matrix  $X^T X$  is almost singular .

It leads to unstable solution:

```
w_true
```

```
array([ 2.68647887, -0.52184084, -1.12776533])
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w_star = np.linalg.inv(X.T.dot(X)).dot(X.T).dot(Y)  
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corresponding features are almost collinear

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the coefficients are huge and sum up to almost 0

To make the matrix nonsingular, we can add a diagonal matrix:

$$\hat{\mathbf{w}} = (X^T X + \lambda I)^{-1} X^T Y ,$$

where  $I = \text{diag}[1_1, \dots, 1_p]$ .

Actually, it's a solution for the case  $Q(\mathbf{w}) = \|Y - X\mathbf{w}\|_2^2 + \lambda^2 \|\mathbf{w}\|_2^2$ .

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exercise: check it by yourself



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Then the solution  $\hat{\mathbf{w}} = (X^T X)^{-1} X^T Y$  delivers BLEU: **B**est **L**inear **U**nbiased **E**stimator.

Once more: loss functions:

- $MSE = \frac{1}{n} \|\mathbf{x}^T \mathbf{w} - \mathbf{y}\|_2^2$

Regularization terms:

- $L_2: \|\mathbf{w}\|_2^2$



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only works for Gauss-Markov theorem

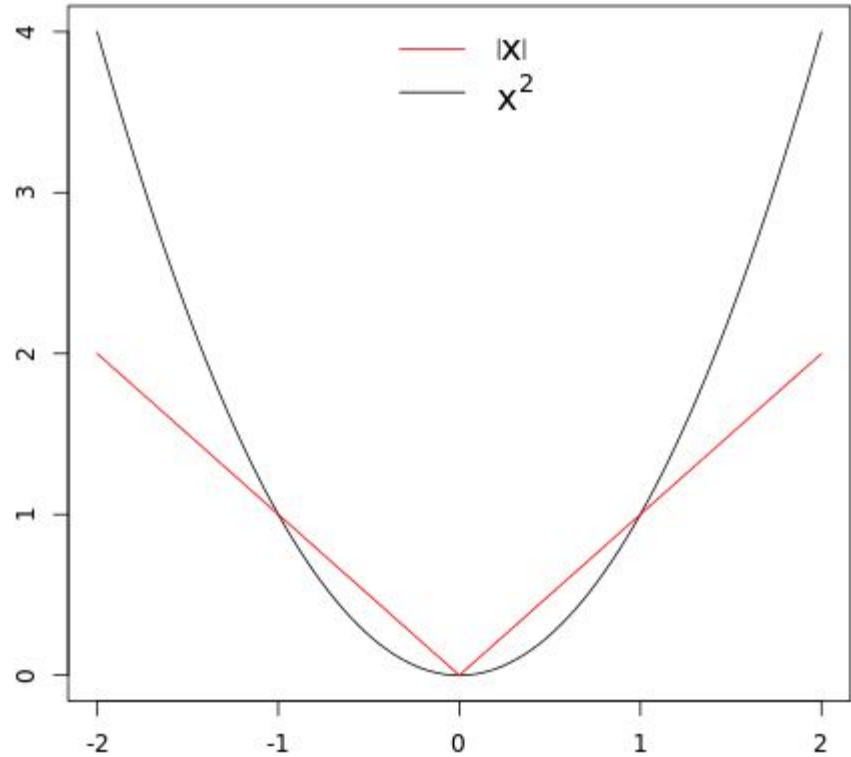
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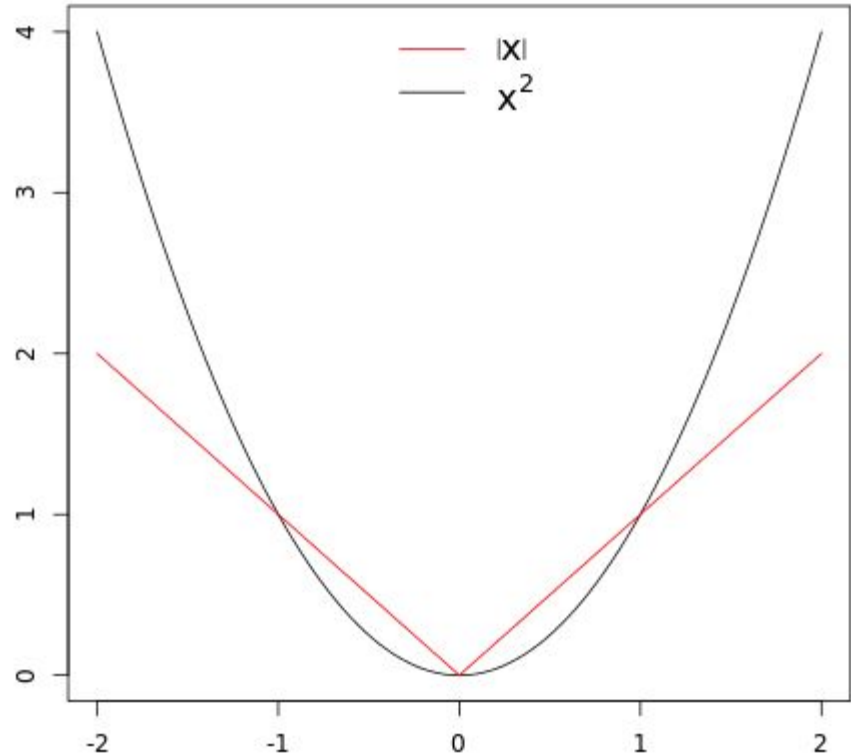
- $L_1: \|\mathbf{w}\|_1$

# What's the difference?



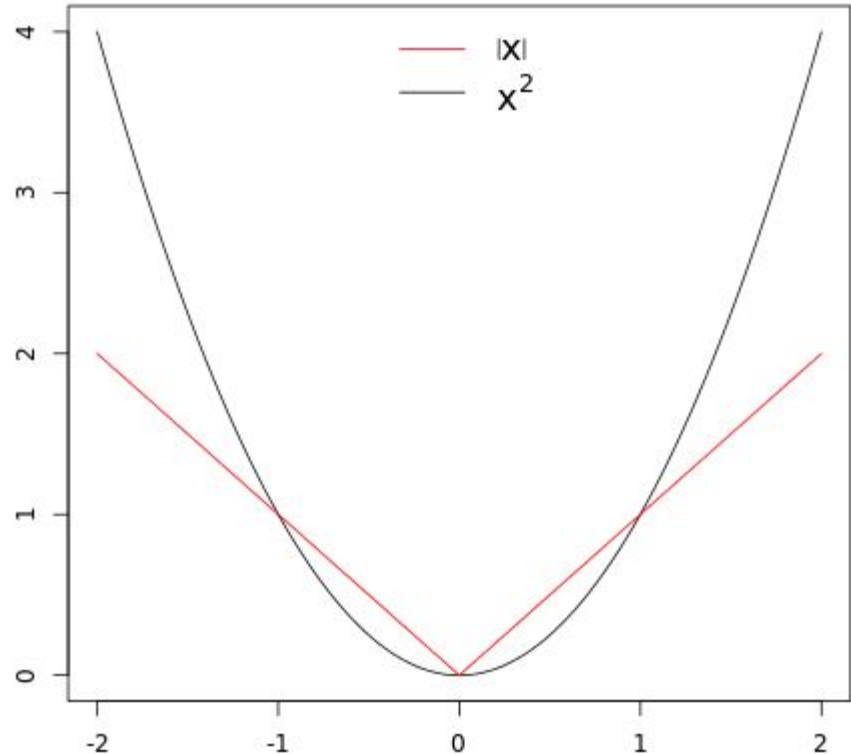
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- MSE
  - delivers BLUE according to Gauss-Markov theorem
  - differentiable
  - sensitive to noise



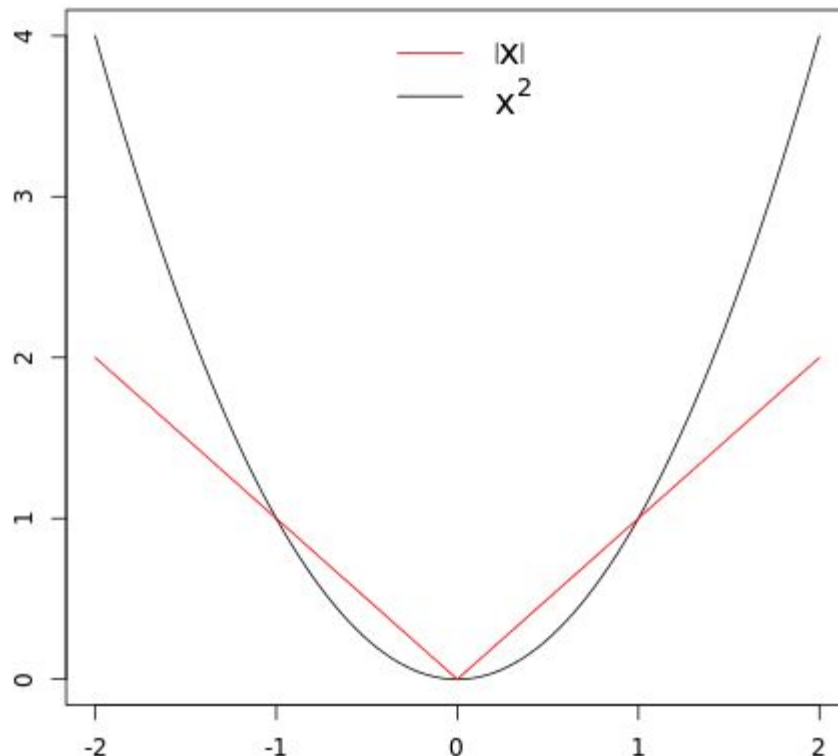
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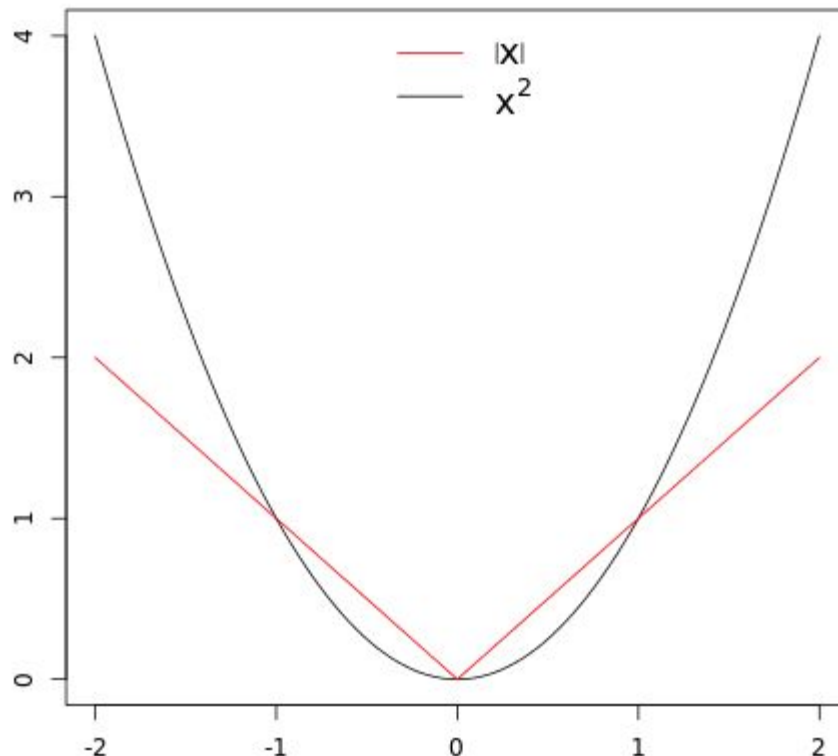
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  - constraints weights
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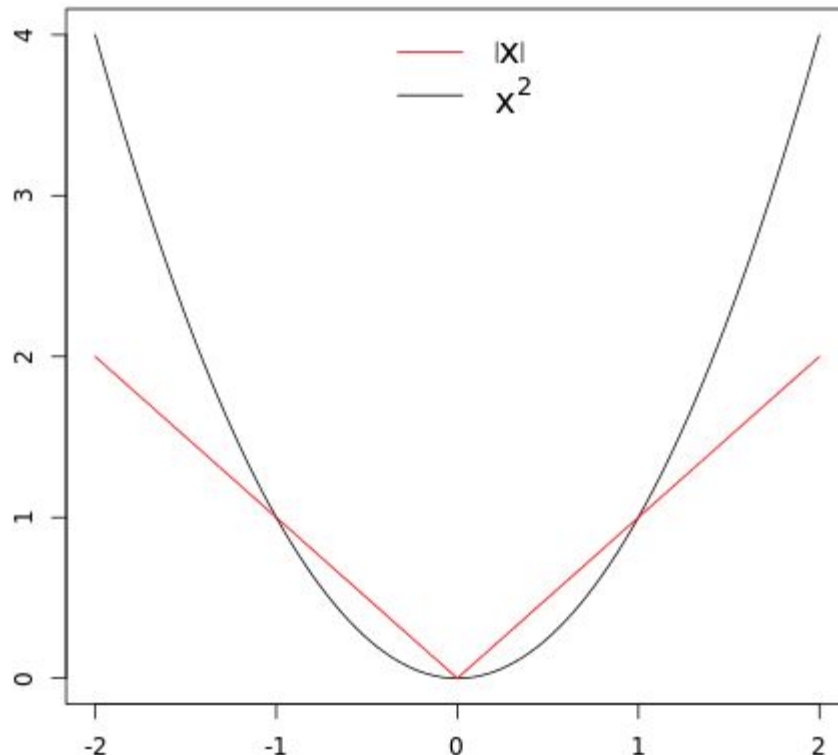
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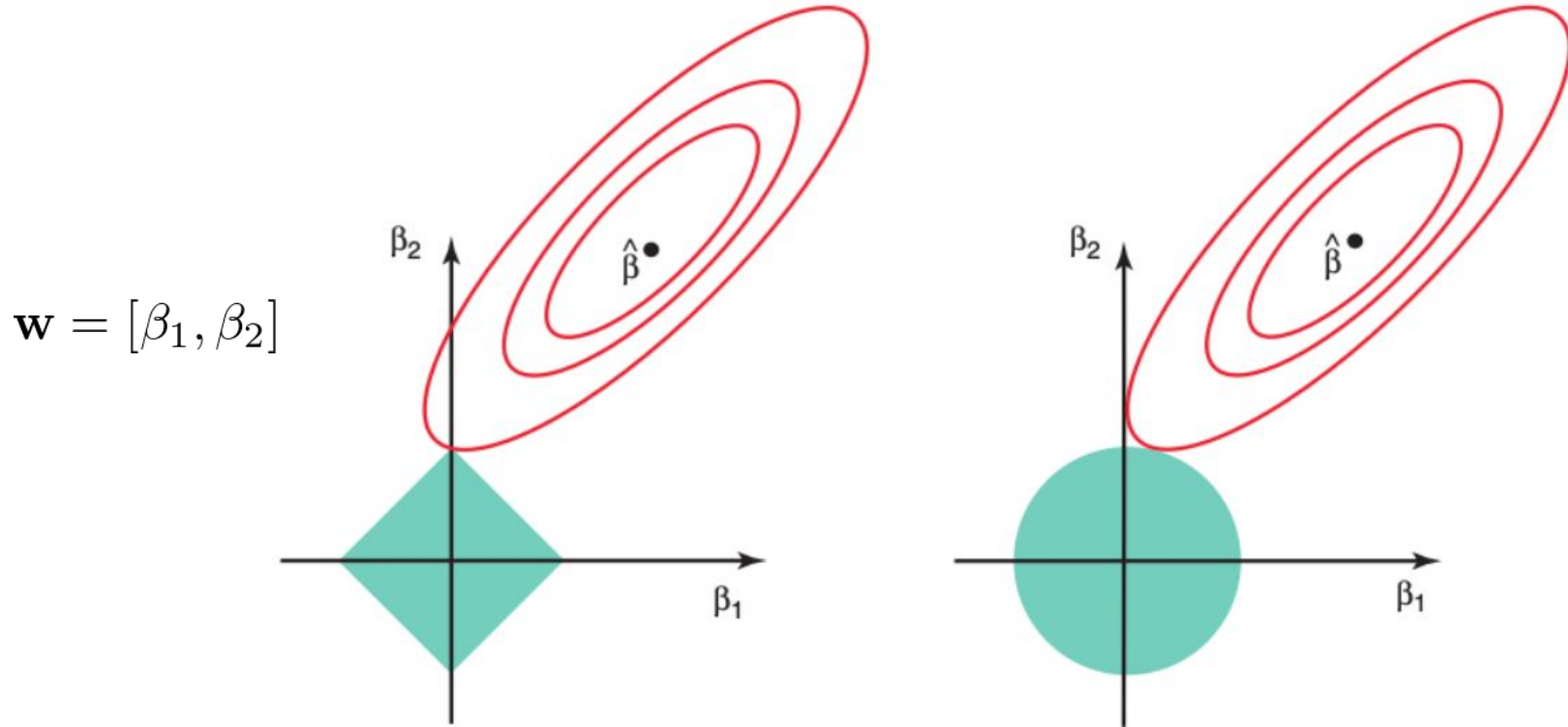
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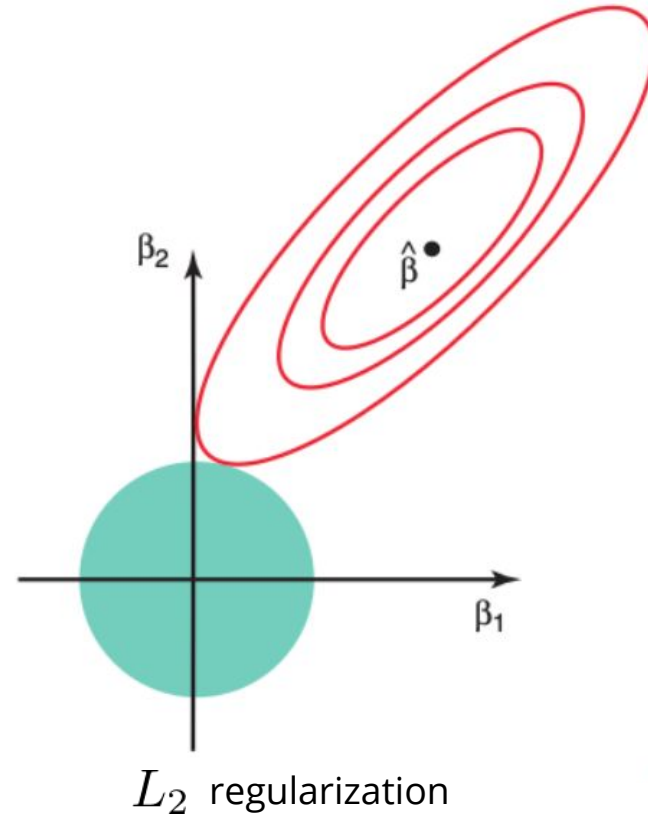
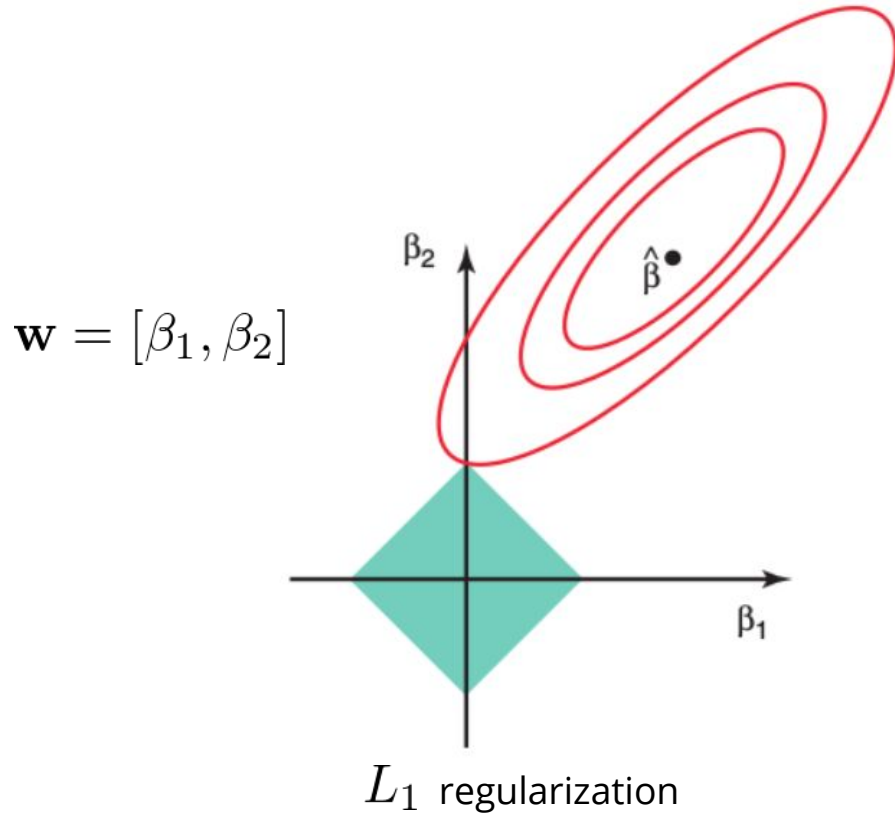


# Regularization: illustration



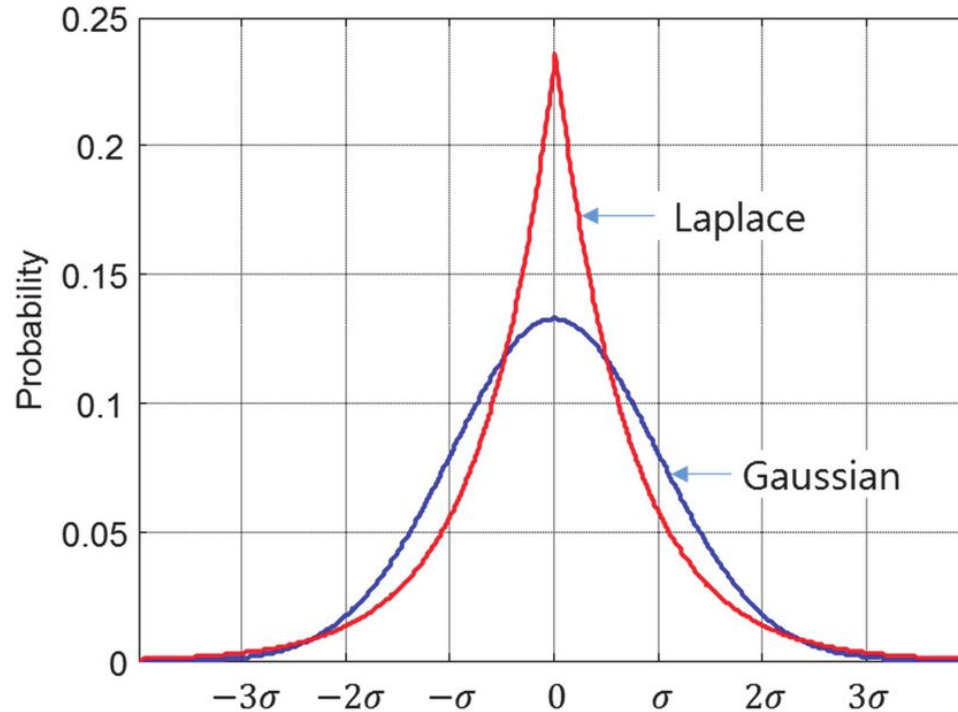
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# Regularization: illustration



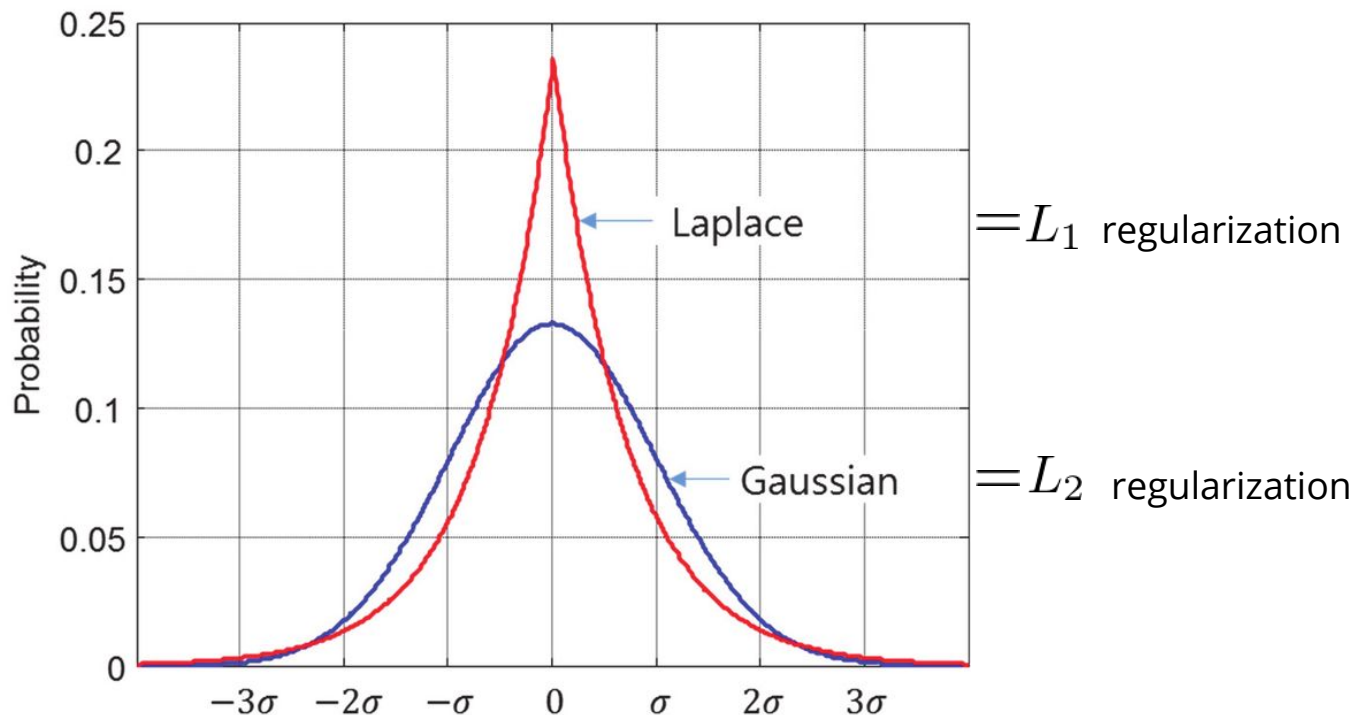
# Regularization: probability interpretation

assume  $\mathbf{w}$  elements are sampled from some *specific* distribution (prior distribution for the weights vector)



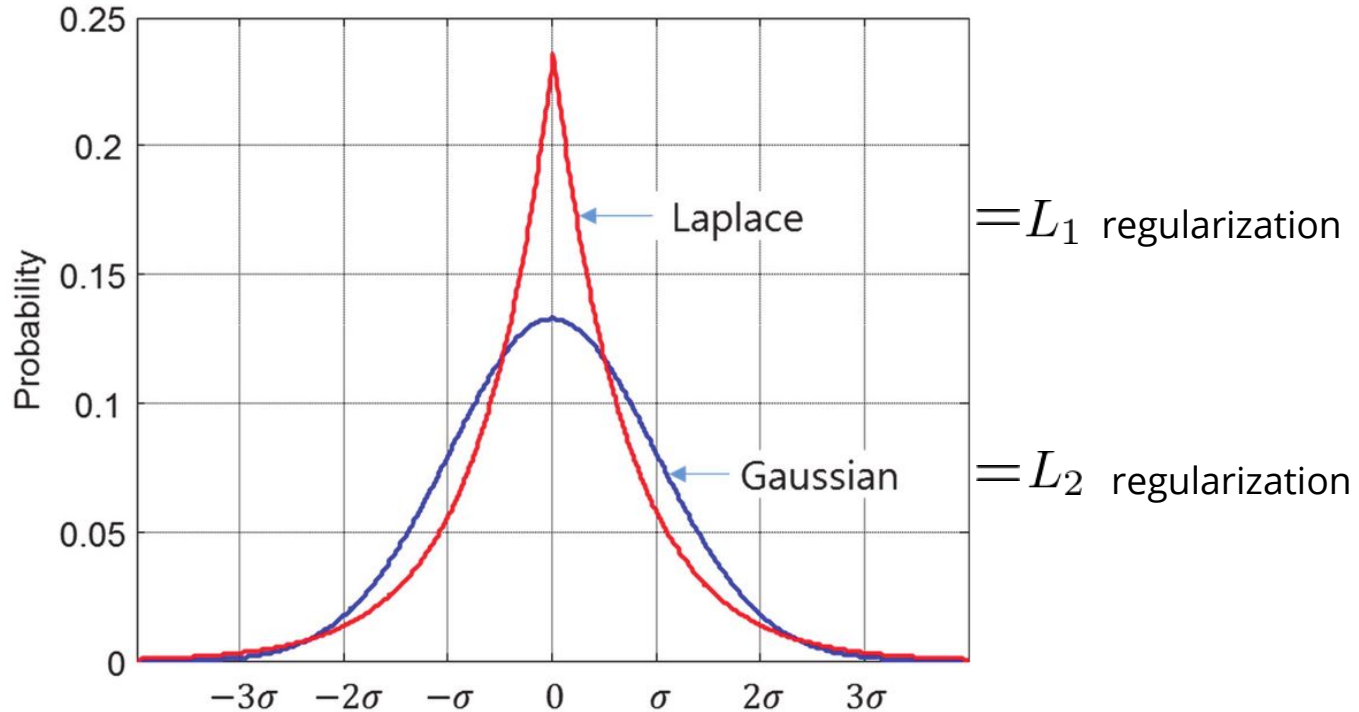
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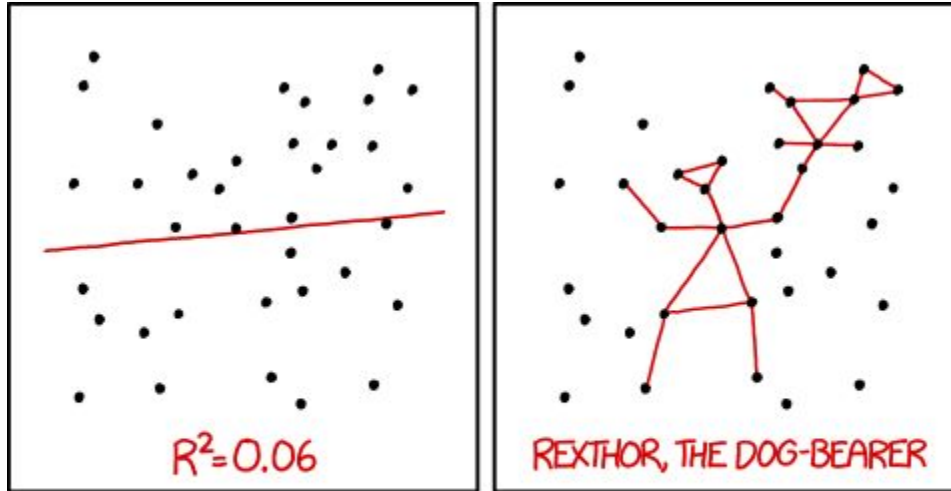


see seminar extra materials for more

# Welcome to the church of Bayes



That's all. Practice coming next.



I DON'T TRUST LINEAR REGRESSIONS WHEN IT'S HARDER  
TO GUESS THE DIRECTION OF THE CORRELATION FROM THE  
SCATTER PLOT THAN TO FIND NEW CONSTELLATIONS ON IT.