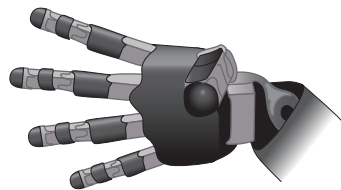
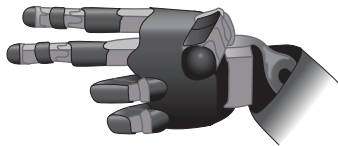


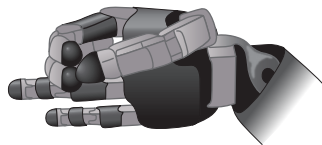
A 机器人手配置



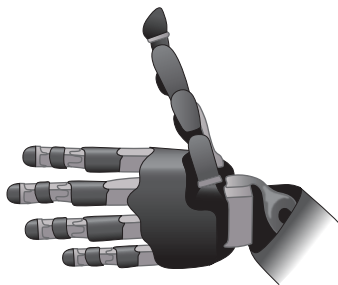
手指伸展



握

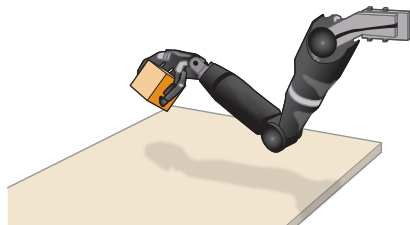
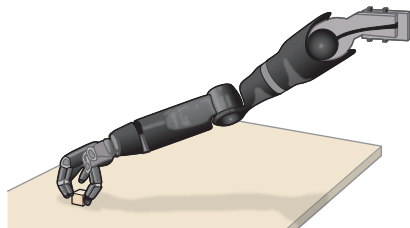


捏



手指发散

B 使用机械手抓取目标



C 机械手抓取的样本目标

