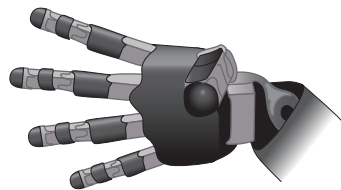
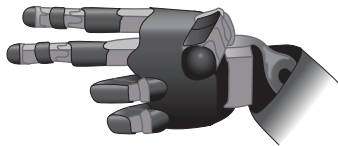


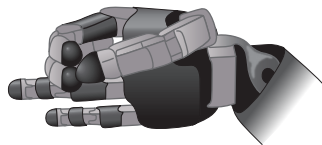
A Robotic hand configurations



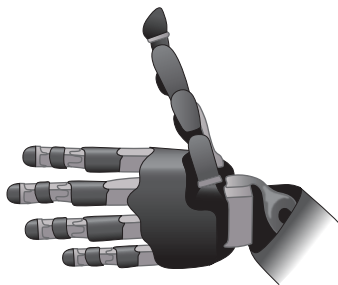
Fingers spread



Scoop

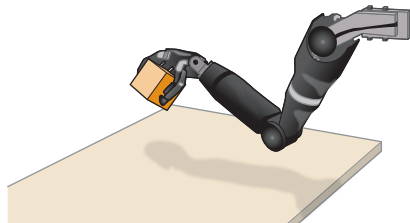
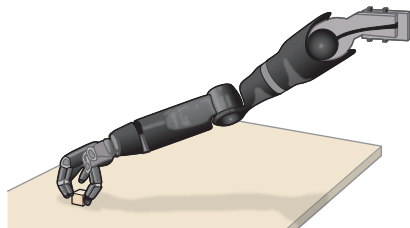


Pinch



Thumb extension

B Using the robotic hand to grasp objects



C Sample objects grasped by the robotic hand

