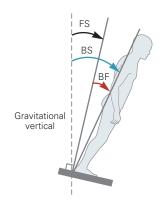
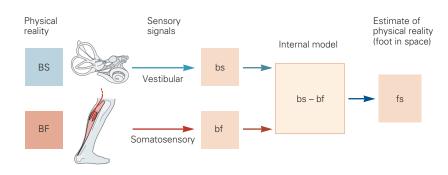
A Internal model for estimating physical reality





B Dynamic weighting of sensory inputs

