# cputopology-sched domain-sched group创建和初始化

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由于在task在创建或者task从idle会wakeup的流程中涉及到sched domain和sched group的知识,所以现在提前看下这部分.

根据实际的物理属性,CPU domain分成下面三种:

CPU 分类	Linux内核分类	描述
SMT(多线程)	CONFIG_SHCED_SMT	一个物理核心可以有两个以 及之上的执行线程,一个物理 核心里面的线程共享相同的 CPU资源和L1 cache,task的 迁移不会影响cache利用率
MC(多核)	CONFIG_SHCED_MC	每个物理核心有独立的L1 cache,多个物理核心可以组成一个cluster,cluster共享L2 cache
DIE(SoC)	简称为DIE	SoC级别

## 1 cpu topology的获取

arm64架构的cpu拓扑结构存储在cpu\_topology[NR\_CPUS]变量当中:

```
struct cpu topology {
          int thread id;
          int core id;
          int cluster id;
          cpumask t thread sibling;
          cpumask t core sibling;
     };
     extern struct cpu topology cpu topology[NR CPUS];
     #define topology_physical_package_id(cpu) (cpu_topology[cpu].cluster_id)
     #define topology core id(cpu) (cpu topology[cpu].core id)
     #define topology core cpumask(cpu) (&cpu topology[cpu].core sibling)
     #define topology sibling cpumask(cpu) (&cpu topology[cpu].thread sibling)
cpu_topology[]数组获取的路径如下(都是从dts里面获取的):
   kernel_init() -> kernel_init_freeable() -> smp_prepare_cpus() ->
      init_cpu_topology() -> parse_dt_topology()
     static int __init parse_dt_topology(void)
          struct device node *cn, *map;
          int ret = 0;
          int cpu;
          /*从dts里面获取cpu node的跟节点*/
          cn = of find node by path("/cpus");
          if (!cn) {
             pr err("No CPU information found in DT\n");
              return 0;
          }
           * When topology is provided cpu-map is essentially a root
           * cluster with restricted subnodes.
          map = of get child by name(cn, "cpu-map");
          if (!map)
              goto out;
          ret = parse_cluster(map, 0);
          if (ret != 0)
              goto out map;
           * Check that all cores are in the topology; the SMP code will
           * only mark cores described in the DT as possible.
          * /
          for_each_possible_cpu(cpu)
              if (cpu topology[cpu].cluster id == -1)
                 ret = -EINVAL;
      out_map:
         of_node_put(map);
   •
      out:
```

of\_node\_put(cn);
return ret;

```
/*看下解析cluster怎么做的*/
   static int __init parse_cluster(struct device_node *cluster, int depth)
•
       char name[10];
       bool leaf = true;
•
       bool has_cores = false;
       struct device_node *c;
       static int cluster_id __initdata;
       int core id = 0;
       int i, ret;
        \star First check for child clusters; we currently ignore any
        ^{\star} information about the nesting of clusters and present the
        * scheduler with a flat list of them.
        */
       i = 0;
       do { /*多个cluster,迭代遍历*/
           snprintf(name, sizeof(name), "cluster%d", i);
•
           c = of_get_child_by_name(cluster, name);
           if (c) {
               leaf = false;
               ret = parse cluster(c, depth + 1);
               of_node_put(c);
               if (ret != 0)
                   return ret;
•
           i++:
       } while (c);
       /* Now check for cores */
       i = 0;
       do { /*遍历cluster下面core的节点*/
           snprintf(name, sizeof(name), "core%d", i);
           c = of_get_child_by_name(cluster, name);
           if (c) {
               has cores = true;
               if (depth == 0) {
                   pr_err("%s: cpu-map children should be clusters\n",
                          c->full name);
                   of_node_put(c);
                   return -EINVAL;
               /*如果是叶子cluster节点,继续遍历core中的cpu节点*/
               if (leaf) {
                   ret = parse_core(c, cluster_id, core_id++);
•
               } else {
                   pr err("%s: Non-leaf cluster with core %s\n",
                         cluster->full name, name);
                   ret = -EINVAL;
               }
               of_node_put(c);
•
               if (ret != 0)
                   return ret;
           i++;
       } while (c);
       if (leaf && !has_cores)
           pr warn("%s: empty cluster\n", cluster->full name);
       if (leaf)
         cluster id++;
```

```
return 0;
   }
   static int __init parse_core(struct device_node *core, int cluster_id,
                    int core id)
       char name[10];
•
       bool leaf = true;
       int i = 0;
       int cpu;
       struct device node *t;
       do { /*如果存在thread层级,解析thread和cpu层级*/
           snprintf(name, sizeof(name), "thread%d", i);
           t = of_get_child_by_name(core, name);
           if (t) {
               leaf = false;
               cpu = get_cpu_for_node(t);
               if (cpu >= 0) {
                   cpu_topology[cpu].cluster_id = cluster_id;
                   cpu_topology[cpu].core_id = core id;
                   cpu_topology[cpu].thread_id = i;
               } else {
                   pr err("%s: Can't get CPU for thread\n",
                          t->full name);
                   of node put(t);
                   return -EINVAL;
               of node put(t);
           i++;
       } while (t);
       /*否则直接解析cpu层级*/
       cpu = get_cpu_for_node(core);
       if (cpu >= 0) {
           if (!leaf) {
               pr err("%s: Core has both threads and CPU\n",
                     core->full name);
               return -EINVAL;
           /*得到了cpu的cluster id/core id*/
           cpu topology[cpu].cluster id = cluster id;
           cpu_topology[cpu].core_id = core_id;
       } else if (leaf) {
           pr_err("%s: Can't get CPU for leaf core\n", core->full_name);
           return -EINVAL;
•
       return 0;
   static int __init get_cpu_for_node(struct device_node *node)
•
       struct device node *cpu node;
       int cpu;
       /*解析cpu层级*/
       cpu_node = of_parse_phandle(node, "cpu", 0);
       if (!cpu_node)
           return -1;
•
       for each possible cpu(cpu) {
           if (of_get_cpu_node(cpu, NULL) == cpu_node) {
               of_node_put(cpu_node);
               return cpu;
           }
       }
```

```
pr_crit("Unable to find CPU node for %s\n", cpu_node->full_name);

of_node_put(cpu_node);
return -1;
}
```

cpu同一层次的关系cpu\_topology[cpu].core\_sibling/thread\_sibling会在 update\_siblings\_masks()中更新

```
• kernel init() -> kernel_init_freeable() -> smp_prepare_cpus()
  -> store_cpu_topology() -> update_siblings_masks()
  static void update_siblings_masks(unsigned int cpuid)
      struct cpu topology *cpu topo, *cpuid topo =
  &cpu topology[cpuid];
      int cpu;
      /* update core and thread sibling masks */
      for each possible cpu(cpu) {
          cpu topo = &cpu topology[cpu];
          if (cpuid topo->cluster id != cpu topo->cluster id)
              continue;
          cpumask set cpu(cpuid, &cpu topo->core sibling);
          if (cpu != cpuid)
              cpumask set cpu(cpu, &cpuid topo->core sibling);
          if (cpuid topo->core id != cpu topo->core id)
              continue;
          cpumask set cpu(cpuid, &cpu topo->thread sibling);
          if (cpu != cpuid)
              cpumask set cpu(cpu,
  &cpuid topo->thread sibling);
```

#### 以我现在的手机平台为例,cpu相关的dts如下:

```
cpus {
    #address-cells = <2>;
    #size-cells = <0>;

    cpu-map {
        cluster0 {
            core0 {
                cpu = <&CPU0>;
            };
            core1 {
                    cpu = <&CPU1>;
            };
            core2 {
                    cpu = <&CPU2>;
            };
}
```

```
core3 {
            cpu = <&CPU3>;
        } ;
    };
    cluster1 {
        core0 {
           cpu = <&CPU4>;
        } ;
        core1 {
         cpu = < &CPU5>;
        } ;
        core2 {
           cpu = <&CPU6>;
        } ;
        core3 {
           cpu = <&CPU7>;
        };
    } ;
};
CPUO: cpu@0 {
    device_type = "cpu";
    compatible = "arm, cortex-a55", "arm, armv8";
    reg = <0x0 0x0>;
    enable-method = "psci";
    cpu-supply = <&fan53555 dcdc>;
    cpufreq-data-v1 = <&cpufreq clus0>;
    cpu-idle-states = <&CORE PD>;
    sched-energy-costs = <&CPU COST 0 &CLUSTER COST 0>;
} ;
CPU1: cpu@100 {
    device_type = "cpu";
    compatible = "arm, cortex-a55", "arm, armv8";
    reg = <0x0 0x100>;
    enable-method = "psci";
    cpu-supply = <&fan53555_dcdc>;
    cpufreq-data-v1 = <&cpufreq_clus0>;
    cpu-idle-states = <&CORE_PD>;
    sched-energy-costs = <&CPU_COST_0 &CLUSTER_COST_0>;
CPU2: cpu@200 {
    device_type = "cpu";
    compatible = "arm, cortex-a55", "arm, armv8";
    reg = <0x0 0x200>;
    enable-method = "psci";
    cpu-supply = <&fan53555 dcdc>;
    cpufreq-data-v1 = <&cpufreq clus0>;
    cpu-idle-states = <&CORE PD>;
    sched-energy-costs = <&CPU_COST_0 &CLUSTER_COST_0>;
};
CPU3: cpu@300 {
    device type = "cpu";
    compatible = "arm, cortex-a55", "arm, armv8";
    reg = <0x0 0x300>;
```

```
enable-method = "psci";
              cpu-supply = <&fan53555_dcdc>;
              cpufreq-data-v1 = <&cpufreq_clus0>;
              cpu-idle-states = <&CORE PD>;
              sched-energy-costs = <&CPU COST 0 &CLUSTER COST 0>;
          };
          CPU4: cpu@400 {
              device_type = "cpu";
              compatible = "arm, cortex-a55", "arm, armv8";
              reg = <0x0 0x400>;
              enable-method = "psci";
              cpu-supply = <&vddcpu>;
              cpufreq-data-v1 = <&cpufreq clus1>;
              cpu-idle-states = <&CORE PD>;
              sched-energy-costs = <&CPU COST 1 &CLUSTER COST 1>;
          } ;
          CPU5: cpu@500 {
              device_type = "cpu";
              compatible = "arm, cortex-a55", "arm, armv8";
              reg = <0x0 0x500>;
              enable-method = "psci";
              cpu-supply = <&vddcpu>;
              cpufreq-data-v1 = <&cpufreq clus1>;
              cpu-idle-states = <&CORE PD>;
              sched-energy-costs = <&CPU_COST_1 &CLUSTER_COST_1>;
          } ;
          CPU6: cpu@600 {
              device type = "cpu";
              compatible = "arm, cortex-a55", "arm, armv8";
              reg = <0x0 0x600>;
              enable-method = "psci";
              cpu-supply = <&vddcpu>;
              cpufreq-data-v1 = <&cpufreq clus1>;
              cpu-idle-states = <&CORE PD>;
              sched-energy-costs = <&CPU_COST_1 &CLUSTER COST 1>;
          } ;
          CPU7: cpu@700 {
             device_type = "cpu";
              compatible = "arm, cortex-a55", "arm, armv8";
              reg = <0x0 0x700>;
              enable-method = "psci";
              cpu-supply = <&vddcpu>;
              cpufreq-data-v1 = <&cpufreq clus1>;
              cpu-idle-states = <&CORE PD>;
              sched-energy-costs = <&CPU COST 1 &CLUSTER COST 1>;
          };
     } ;
经过parse_dt_topology()、update_siblings_masks()解析后得到cpu_topology[}的值为:
     cpu 0 cluster id = 0, core id = 0, core sibling = 0xf
```

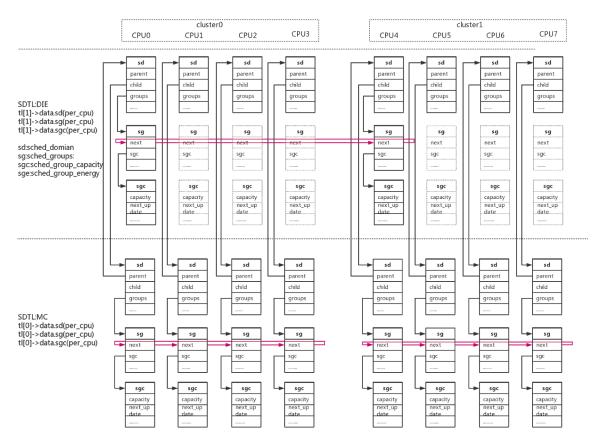
```
cpu 1 cluster_id = 0, core_id = 1, core_sibling = 0xf
cpu 2 cluster_id = 0, core_id = 2, core_sibling = 0xf
cpu 3 cluster_id = 0, core_id = 3, core_sibling = 0xf
cpu 4 cluster id = 1, core id = 0, core sibling = 0xf0
cpu 5 cluster id = 1, core id = 1, core sibling = 0xf0
```

```
cpu 6 cluster_id = 1, core_id = 2, core_sibling = 0xf0
cpu 7 cluster_id = 1, core_id = 3, core_sibling = 0xf0
//adb 查看cpu topology信息
:/sys/devices/system/cpu/cpu0/topology # 1s -1
total 0
-r--r--- 1 root root 4096 2018-09-05 16:10 core_id //0
-r--r--- 1 root root 4096 2018-09-05 16:10 core_siblings //0f
-r--r--- 1 root root 4096 2018-09-05 16:10 core_siblings_list//0-3
-r--r---- 1 root root 4096 2018-09-05 16:10 physical_package_id //0
-r--r---- 1 root root 4096 2018-09-05 16:10 thread_siblings //01
-r--r---- 1 root root 4096 2018-09-05 16:10 thread_siblings_list//0
```

## 2 调度域,调度组以及调度组capacity的初始化

## 2.1 SDTL 概述

先整体了解整个topology关系, 好对着code学习:



#### 内核中有预先定义的调度域的结构体struct sched\_domain\_topology\_level:

```
typedef const struct cpumask *(*sched_domain_mask_f)(int cpu);
typedef int (*sched_domain_flags_f)(void);
typedef
const struct sched_group_energy * const(*sched_domain_energy_f)(int cpu);
```

```
struct sched domain topology level {
      sched domain mask f mask;
      sched_domain_flags_f sd_flags;
      sched_domain_energy_f energy;
     int flags;
int numa_level;
     struct sd data data;
 #ifdef CONFIG_SCHED_DEBUG
     char
  #endif
  };
 struct sd data {
      struct sched_domain **__percpu sd;
      struct sched group ** percpu sg;
      struct sched_group_capacity **__percpu sgc;
  };
  * Topology list, bottom-up.
static struct sched domain topology level default topology[] = {
 #ifdef CONFIG SCHED SMT
      { cpu smt mask, cpu smt flags, SD INIT NAME(SMT) },
 #endif
  #ifdef CONFIG SCHED MC
  { cpu coregroup mask, cpu core flags, SD INIT NAME(MC) },
     { cpu_cpu_mask, SD INIT NAME(DIE) },
      { NULL, },
 };
  static struct sched domain topology level *sched domain topology =
      default topology;
```

我们根据default\_topology[]这个结构体数组来解析sched\_domain\_topology\_level(简称SDTL) 结构体成员变量的含义

- sched\_domain\_mask\_f mask:函数指针,用于指定某个SDTL层级的cpumask位图
- sched\_domain\_flags\_f sd\_flags:函数指针,用于指定某个SDTL层级的标志位
- sched\_domain\_energy\_f energy:函数指针,用于指定某个SDTL层级的energy信息,包括 在active和idle状态下的capacity和power信息,具体获取是从dts(kernel/sched/energy.c)
- struct sd data:表示SDTL层级关系,包括domain/group/group capacity

Mdefault\_topology结构体数组看,DIE是标配,MC和SMT是可选择的.目前ARM不支持SMT超线程技术,目的只有两种topology,MC和DIE.

由于在建立topology的时候,涉及到cpumask的使用,下面几个是比较常用的cpumask:

```
#ifdef CONFIG_INIT_ALL_POSSIBLE

static DECLARE_BITMAP(cpu_possible_bits, CONFIG_NR_CPUS) __read_mostly

= CPU_BITS_ALL;

#else

static DECLARE_BITMAP(cpu_possible_bits, CONFIG_NR_CPUS) __read_mostly;

#endif
```

```
const struct cpumask *const cpu_possible_mask =
   to_cpumask(cpu_possible_bits);
EXPORT_SYMBOL(cpu_possible_mask);

static DECLARE_BITMAP(cpu_online_bits, CONFIG_NR_CPUS) __read_mostly;
const struct cpumask *const cpu_online_mask = to_cpumask(cpu_online_bits);
EXPORT_SYMBOL(cpu_online_mask);

static DECLARE_BITMAP(cpu_present_bits, CONFIG_NR_CPUS) __read_mostly;
const struct cpumask *const cpu_present_mask = to_cpumask(cpu_present_bits);
EXPORT_SYMBOL(cpu_present_mask);

static DECLARE_BITMAP(cpu_active_bits, CONFIG_NR_CPUS) __read_mostly;
const struct cpumask *const cpu_active_mask = to_cpumask(cpu_active_bits);
EXPORT_SYMBOL(cpu_active_mask);
```

上面的信息通过他们的名字就可以理解,需要注意的一点就是.online mask与active mask区别是:

- cpu\_online\_mask:表示当前系统online的cpu,包括idle+active cpu
- cpu\_active\_mask:表示当前系统online并且active的cpu

## 2.2 sched\_domain的初始化

下面看看cpu topology怎么建立起来并经过初始化建立起sched domain和sched group的关系的.当boot cpu启动丛cpu的时候,cpu topology就开始建立:

start\_kernel-->rest\_init-->kernel\_init-->kernel\_init\_freeable-->sched\_init\_smp-->init\_sched\_d omains:

```
* Set up scheduler domains and groups. Callers must hold the hotplug lock.
 * For now this just excludes isolated cpus, but could be used to
 * exclude other special cases in the future.
static int init sched domains (const struct cpumask *cpu map)
    int err;
    /*ARM没有定义*/
    arch_update_cpu_topology();
    ndoms cur = 1;
    /*分配一个cpumask结构体变量*/
    doms cur = alloc sched domains(ndoms cur);
    if (!doms cur)
        doms cur = &fallback doms;
    /*doms curr[0] = cpu map & (~cpu isolated map),cpumask的与非的计算方式
    cpu_isolated_map表示有独立的domain的cpu,当前在建立的cpu topology过程中需要
   剔除cpu isolated map cpu*/
    cpumask andnot(doms cur[0], cpu map, cpu isolated map);
    /*开始建立cpu topology*/
    err = build sched domains(doms cur[0], NULL);
    /*注册sched domain的系统控制接口*/
    register_sched_domain_sysctl();
    return err;
```

```
* arch_update_cpu_topology lets virtualized architectures update the
•
    * cpu core maps. It is supposed to return 1 if the topology changed
    * or 0 if it stayed the same.
•
   int __weak arch_update_cpu_topology(void)
•
       return 0;
.
   cpumask var t *alloc sched domains(unsigned int ndoms)
•
       int i:
       cpumask var t *doms;
       doms = kmalloc(sizeof(*doms) * ndoms, GFP_KERNEL);
       if (!doms)
          return NULL;
       for (i = 0; i < ndoms; i++) {</pre>
           if (!alloc_cpumask_var(&doms[i], GFP_KERNEL)) {
               free sched domains (doms, i);
               return NULL;
           }
       return doms;
•
   }
  /*上面的cpu map是active cpu mask,那么active cpumask在哪里设置的呢?*/
  /* Called by boot processor to activate the rest. */
  /*arm dt init cpu maps()函数会初始化若干个cpumask变量比如possible和present
   cpumask这个函数会将所有的cpu online起来,同时会等到online cpumask和active cpumask*/
   void __init smp_init(void)
•
       unsigned int cpu;
•
       idle_threads_init();
       /\star FIXME: This should be done in userspace --RR \star/
       for_each_present_cpu(cpu) {
           if (num_online_cpus() >= setup_max_cpus)
               break;
           if (!cpu_online(cpu))
               cpu_up(cpu);
       /* Any cleanup work */
       smp announce();
       smp cpus done(setup max cpus);
•
```

## 2.2.1 核心函数build\_sched\_domians分析

### 接下来解析真正构建cpu topology结构的函数:build\_sched\_domians

```
struct sched domain *sd;
struct s_data d;
int i, ret = -ENOMEM;
alloc_state = __visit_domain_allocation_hell(&d, cpu_map);
if (alloc state != sa rootdomain)
    goto error;
/* Set up domains for cpus specified by the cpu map. */
for_each_cpu(i, cpu_map) {
    struct sched domain topology level *tl;
    sd = NULL;
   for_each_sd_topology(tl) {
        sd = build_sched_domain(tl, cpu_map, attr, sd, i);
        if (tl == sched_domain_topology)
            *per_cpu_ptr(d.sd, i) = sd;
        if (tl->flags & SDTL OVERLAP || sched feat(FORCE SD OVERLAP))
            sd->flags |= SD OVERLAP;
    }
}
/* Build the groups for the domains */
for_each_cpu(i, cpu_map) {
    for (sd = *per cpu ptr(d.sd, i); sd; sd = sd->parent) {
       sd->span weight = cpumask weight(sched domain span(sd));
        if (sd->flags & SD OVERLAP) {
            if (build_overlap_sched_groups(sd, i))
                goto error;
        } else {
            if (build_sched_groups(sd, i))
               goto error;
        }
   }
}
/* Calculate CPU capacity for physical packages and nodes */
for (i = nr_cpumask_bits-1; i >= 0; i--) {
    struct sched domain topology level *tl = sched domain topology;
    if (!cpumask test cpu(i, cpu map))
        continue;
    for (sd = *per_cpu_ptr(d.sd, i); sd; sd = sd->parent, tl++) {
        init sched energy(i, sd, tl->energy);
        claim_allocations(i, sd);
        init sched groups capacity(i, sd);
   }
/* Attach the domains */
rcu_read_lock();
for each cpu(i, cpu map) {
```

对构建cpu topology函数分如下几个部分来分析:

#### 2.2.1.1 为调度域/调度组/调度组capacity分配空间

#### 分配空间:在build\_sched\_domains函数里面调用\_\_visit\_domain\_allocation\_hell函数

```
static enum s_alloc __visit_domain_allocation_hell(struct s_data *d,
                           const struct cpumask *cpu_map)
    memset(d, 0, sizeof(*d));
    /*核心函数:创建调度域等数据结构,详细看下面的解析*/
    if ( sdt alloc(cpu map))
        return sa sd storage;
    d->sd = alloc percpu(struct sched domain *);
    if (!d->sd)
        return sa_sd_storage;
    d->rd = alloc rootdomain();
    if (!d->rd)
        return sa sd;
    return sa rootdomain;
static int      sdt alloc(const struct cpumask *cpu map)
    struct sched_domain_topology_level *tl;
    int j;
static struct sched domain topology level *sched domain topology =
      default topology;
#define for each sd topology(tl)
      for (tl = sched_domain_topology; tl->mask; tl++)
*/ /*对default_topology结构体数据进行遍历*/
    for each sd topology(tl) {
        /*获取每个SDTL层级的sd data数据结构指针*/
```

```
struct sd data *sdd = &tl->data;
       /*下面三个alloc percpu为每一个SDTL层级的实体数据结构sd data分配空间
        1.sched domain
        2. sched group
        sched group capacity*/
       sdd->sd = alloc_percpu(struct sched_domain *);
       if (!sdd->sd)
           return -ENOMEM;
       sdd->sg = alloc percpu(struct sched group *);
       if (!sdd->sg)
           return -ENOMEM;
       sdd->sgc = alloc_percpu(struct sched_group_capacity *);
       if (!sdd->sgc)
           return -ENOMEM;
       /*针对每个active cpu mask进行遍历,每个cpu上都需要为sd/sg/sgc分配空间,并存放
       在percpu变量中.注意到sg->next指针,有两个不同的用途:
       1.对于MC 层级,不同cluster的每个cpu core sched group会组成一个链表,比如两个
       cluster,每个cluster 四个core,则每个cluster的sched group链表长度都为4,每个
       core的sched domain都有一个sched group.
       2. DIE层级,不同cluster的sched group会链接起来.一个cluster所有core
        的sched domain都共享一个sched group,后面会以图表说明*/
       for_each_cpu(j, cpu_map) {
           struct sched_domain *sd;
           struct sched group *sg;
           struct sched group capacity *sgc;
           sd = kzalloc node(sizeof(struct sched domain) + cpumask_size(),
                  GFP_KERNEL, cpu_to_node(j));
           if (!sd)
              return -ENOMEM;
           *per cpu ptr(sdd->sd, j) = sd;
           sg = kzalloc_node(sizeof(struct sched_group) + cpumask_size(),
                  GFP_KERNEL, cpu_to_node(j));
           if (!sg)
              return -ENOMEM;
           sg->next = sg;
           *per cpu ptr(sdd->sg, j) = sg;
           sgc = kzalloc_node(sizeof(struct sched_group_capacity) +
cpumask size(),
                  GFP_KERNEL, cpu_to_node(j));
           if (!sgc)
              return -ENOMEM;
           *per_cpu_ptr(sdd->sgc, j) = sgc;
   }
```

```
return 0;
} static int __sdt_alloc(const struct cpumask *cpu_map)
    struct sched_domain_topology_level *tl;
    int j;
    for each sd topology(tl) {
        struct sd_data *sdd = &tl->data;
        sdd->sd = alloc_percpu(struct sched_domain *);
        if (!sdd->sd)
            return -ENOMEM;
        sdd->sg = alloc_percpu(struct sched_group *);
        if (!sdd->sg)
            return -ENOMEM;
        sdd->sgc = alloc_percpu(struct sched_group_capacity *);
        if (!sdd->sgc)
            return -ENOMEM;
        for_each_cpu(j, cpu_map) {
            struct sched domain *sd;
            struct sched_group *sg;
            struct sched_group_capacity *sgc;
            sd = kzalloc node(sizeof(struct sched domain) + cpumask size(),
                    GFP_KERNEL, cpu_to_node(j));
            if (!sd)
                return -ENOMEM;
            *per_cpu_ptr(sdd->sd, j) = sd;
            sg = kzalloc node(sizeof(struct sched group) + cpumask size(),
                    GFP_KERNEL, cpu_to_node(j));
            if (!sg)
                return -ENOMEM;
            sg->next = sg;
            *per cpu ptr(sdd->sg, j) = sg;
            sgc = kzalloc node(sizeof(struct sched group capacity) +
cpumask size(),
                    GFP_KERNEL, cpu_to_node(j));
            if (!sgc)
                return -ENOMEM;
            *per_cpu_ptr(sdd->sgc, j) = sgc;
        }
    }
    return 0;
```

#### 说明如下:

- 每个SDTL层级都有一个struct sched\_domain\_topology\_level数据结构来描述,并且内嵌了一个struct sd\_data数据结构,包含
   sched domain,sched group,sched group capacity的二级指针
- 每个SDTL层级都分配一个percpu变量 sched domain,sched group,sched group capacity数据结构
- 在每个SDTL层级中为每个cpu都分配 sched\_domain,sched\_group,sched\_group\_capacity数据结构,即每个cpu在没给SDTL 层级中都有对应的调度域和调度组.

#### 2.2.1.2 为cpu map指定的cpu设定调度域

初始化sched\_domain:build\_sched\_domain函数,\_\_visit\_domain\_allocation\_hell函数已经为每个SDTL层级分配了sched\_domain,sched\_group/sched\_group\_capacity空间了,有空间之后,就开始为cpu\_map建立调度域关系了:

```
build sched domains--->build sched domain
    /* Set up domains for cpus specified by the cpu map. */
     /*对每个cpu map进行遍历,并对每个CPU的SDTL层级进行遍历,相当于每个CPU都有一套SDTL对
应的调度域,为每个CPU都初始化一整套SDTL对应的调度域和调度组,每个
  CPU的每个SDTL都调用build sched domain函数来建立调度域和调度组*/
    for each cpu(i, cpu map) {
        struct sched domain topology level *tl;
        sd = NULL;
        for each sd topology(tl) {
            sd = build sched domain(tl, cpu map, attr, sd, i);
            if (tl == sched domain topology)
               *per cpu ptr(d.sd, i) = sd;
            if (tl->flags & SDTL OVERLAP || sched feat(FORCE SD OVERLAP))
                sd->flags |= SD OVERLAP;
        }
    }
|->
static struct sched domain *
sd_init(struct sched_domain_topology_level *tl,
    struct sched domain *child, int cpu)
{ /*获取cpu的sched domain实体*/
    struct sched domain *sd = *per cpu ptr(tl->data.sd, cpu);
    int sd weight, sd flags = 0;
#ifdef CONFIG NUMA
    /*
     * Ugly hack to pass state to sd numa mask()...
    sched domains curr level = tl->numa level;
    /*通过default topology[]结构体数据填充对应的参数,涉及到一些cpumask,这个上面已经
    sd weight = cpumask weight(tl->mask(cpu));
    if (tl->sd flags)
```

```
sd flags = (*tl->sd flags)();
    if (WARN_ONCE(sd_flags & ~TOPOLOGY_SD_FLAGS,
          "wrong sd_flags in topology description\n"))
        sd_flags &= ~TOPOLOGY_SD_FLAGS;
     /*填充sched domain一些成员变量*/
    *sd = (struct sched_domain) {
       .min_interval = sd_weight,
.max_interval = 2*sd_weight,
.busy_factor = 32,
        .imbalance_pct
                          = 125,
        .cache_nice_tries = 0,
        .busy_idx = 0,
.idle_idx = 0,
        .newidle_idx = 0,
        .wake_idx = 0,
        .forkexec_idx = 0,
                      = 1*SD LOAD BALANCE
                   | 1*SD BALANCE NEWIDLE
                   | 1*SD BALANCE EXEC
                   | 1*SD BALANCE FORK
                   | 0*SD BALANCE WAKE
                   | 1*SD WAKE AFFINE
                   | 0*SD_SHARE_CPUCAPACITY
                   | 0*SD SHARE PKG RESOURCES
                    | 0*SD SERIALIZE
                    | 0*SD PREFER SIBLING
                    | 0*SD NUMA
#ifdef CONFIG_INTEL_DWS
                   | 0*SD_INTEL_DWS
#endif
                   | sd flags
       .last_balance = jiffies,
       .balance_interval = sd_weight,
       .smt_gain = 0,
        .max_newidle_lb_cost = 0,
        .next_decay_max_lb_cost = jiffies,
        .child = child,
#ifdef CONFIG INTEL DWS
       .dws_tf = 0,
#ifdef CONFIG SCHED DEBUG
 .name = tl->name,
#endif
   };
    * Convert topological properties into behaviour.
    if (sd->flags & SD ASYM CPUCAPACITY) {
```

```
struct sched domain *t = sd;
        for_each_lower_domain(t)
            t->flags |= SD_BALANCE_WAKE;
    }
    if (sd->flags & SD SHARE CPUCAPACITY) {
        sd->flags |= SD_PREFER_SIBLING;
        sd->imbalance pct = 110;
        sd->smt_gain = 1178; /* ~15% */
    } else if (sd->flags & SD SHARE PKG RESOURCES) {
        sd->imbalance pct = 117;
        sd->cache_nice_tries = 1;
        sd->busy_idx = 2;
#ifdef CONFIG NUMA
    } else if (sd->flags & SD_NUMA) {
       sd->cache nice tries = 2;
        sd->busy idx = 3;
        sd->idle idx = 2;
        sd->flags |= SD SERIALIZE;
        if (sched_domains_numa_distance[tl->numa_level] > RECLAIM_DISTANCE)
            sd->flags &= ~(SD BALANCE EXEC |
                      SD BALANCE FORK |
                       SD_WAKE_AFFINE);
#endif
    } else {
       sd->flags |= SD PREFER SIBLING;
       sd->cache nice tries = 1;
       sd->busy idx = 2;
        sd->idle_idx = 1;
    }
#ifdef CONFIG_INTEL_DWS
    if (sd->flags & SD INTEL DWS)
        sd->dws tf = 120;
    if (sd->flags & SD INTEL DWS && sd->flags & SD SHARE PKG RESOURCES)
        sd->dws tf = 160;
#endif
    sd->private = &tl->data;
    return sd;
}
struct sched domain *build sched domain(struct sched domain topology level
*tl,
        const struct cpumask *cpu map, struct sched domain attr *attr,
```

```
struct sched domain *child, int cpu)
   /*上面解释了sd init函数*/
   struct sched_domain *sd = sd_init(tl, child, cpu);
   cpumask and(sched domain span(sd), cpu map, tl->mask(cpu));
   if (child) {
       sd->level = child->level + 1;
       sched_domain_level_max = max(sched_domain_level_max, sd->level);
       child->parent = sd;
       if (!cpumask subset(sched domain span(child),
                   sched domain span(sd))) {
           pr err("BUG: arch topology borken\n");
#ifdef CONFIG SCHED DEBUG
          pr err("
                       the %s domain not a subset of the %s domain\n",
                   child->name, sd->name);
#endif
            /* Fixup, ensure @sd has at least @child cpus. */
            cpumask or (sched domain span(sd),
                  sched domain span(sd),
                  sched domain span(child));
        }
    set domain attribute(sd, attr);
   return sd;
```

#### 说明如下:

- sd\_init函数通过default\_topology结构体填充sched\_domain结构体并填充相关的一些参数
- cpumask\_and(sched\_domain\_span(sd), cpu\_map, tl->mask(cpu)); tl->mask(cpu)返回 该cpu某个SDTL层级下兄弟cpu的bitmap,cpumask\_and则将tl->mask(cpu)的bitmap复 制到span数组中.
- 我们知道遍历的顺序是SMT-->MC-->DIE,可以看成父子关系或者上下级关系,struct sched\_domain数据结构中有parent和child成员用于描述此关系.
- 后面完成了对调度域的初始化.

#### 2.2.1.3 为调度域建立调度组

```
} else {
                if (build_sched_groups(sd, i))
                   goto error;
   }
/*
 * build sched groups will build a circular linked list of the groups
 * covered by the given span, and will set each group's ->cpumask correctly,
* and ->cpu capacity to 0.
 * Assumes the sched domain tree is fully constructed
 * 核心函数
 */
static int
build_sched_groups(struct sched_domain *sd, int cpu)
    struct sched group *first = NULL, *last = NULL;
    struct sd data *sdd = sd->private;
    const struct cpumask *span = sched domain span(sd);
    struct cpumask *covered;
    int i;
    get_group(cpu, sdd, &sd->groups);
    atomic inc(&sd->groups->ref);
    if (cpu != cpumask_first(span))
        return 0;
    lockdep assert held(&sched domains mutex);
    covered = sched_domains_tmpmask;
    cpumask clear(covered);
    /*span是某个SDTL层级的cpu bitmap,实质某个sched domain包含多少个cpu*/
    /*两个for循环依次设置了该调度域sd中不同CPU对应的调度组的包含关系,这些调度组通过next
   指针串联起来*/
    for_each_cpu(i, span) {
        struct sched_group *sg;
        int group, j;
        if (cpumask test cpu(i, covered))
            continue;
        group = get_group(i, sdd, &sg);
        cpumask_setall(sched_group_mask(sg));
        for each cpu(j, span) {
           if (get_group(j, sdd, NULL) != group)
               continue;
            cpumask_set_cpu(j, covered);
            cpumask_set_cpu(j, sched_group_cpus(sg));
```

```
if (!first)
              first = sg;
           if (last)
               last->next = sg;
           last = sg;
       /*将一个sched domain里面的所有sched group串成一组链表*/
       last->next = first;
       return 0;
   static int get group (int cpu, struct sd data *sdd, struct sched group **sg)
       struct sched domain *sd = *per cpu ptr(sdd->sd, cpu);
       struct sched domain *child = sd->child;
       /*如果是SDTL=DIE,那么child为true*/
      if (child)
           cpu = cpumask_first(sched_domain_span(child));
       if (sg) {
           *sg = *per_cpu_ptr(sdd->sg, cpu);
           (*sg)->sgc = *per cpu ptr(sdd->sgc, cpu);
           atomic set(&(*sg)->sgc->ref, 1); /* for claim allocations */
•
      return cpu;
```

#### 2.2.1.4 为调度域建立cpu capacity

```
/* Calculate CPU capacity for physical packages and nodes */
for (i = nr cpumask bits-1; i >= 0; i--) {
    struct sched domain topology level *tl = sched domain topology;
    if (!cpumask test cpu(i, cpu map))
        continue;
    for (sd = *per cpu ptr(d.sd, i); sd; sd = sd->parent, tl++) {
       init_sched_energy(i, sd, tl->energy);
        claim allocations(i, sd);
       init sched groups capacity(i, sd);
/*上面的函数目的是填充下面的结构体每个cpu的每个SDTL层级的sched group capacity*/
struct sched_group_capacity {
   atomic t ref;
    * CPU capacity of this group, SCHED LOAD SCALE being max capacity
    * for a single CPU.
    * /
    unsigned long capacity;
    unsigned long max_capacity; /* Max per-cpu capacity in group */
    unsigned long min capacity; /* Min per-CPU capacity in group */
   unsigned long next update;
```

```
int imbalance; /* XXX unrelated to capacity but shared group state */
    /*
    * Number of busy cpus in this group.
    */
    atomic_t nr_busy_cpus;

unsigned long cpumask[0]; /* iteration mask */
};
```

#### 2.2.1.5. 将cpu调度域与rg的root domain建立起联系

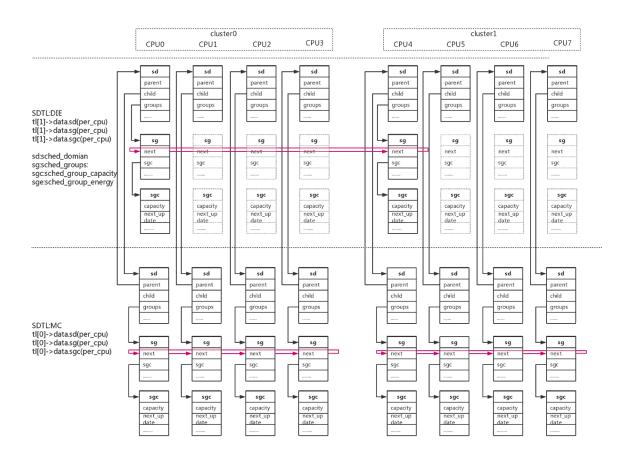
#### 将每个cpu的调度域与每个cpu的struct rq root domain成员关联起来

```
/* Attach the domains */
     rcu read lock();
     for each cpu(i, cpu map) {
         int max cpu = READ ONCE(d.rd->max cap orig cpu);
         int min cpu = READ ONCE(d.rd->min cap orig cpu);
         if ((max cpu < 0) || (cpu rq(i)->cpu capacity orig >
             cpu rq(max cpu)->cpu capacity orig))
             WRITE ONCE (d.rd->max cap orig cpu, i);
         if ((min cpu < 0) || (cpu rq(i)->cpu capacity orig <</pre>
             cpu rq(min cpu) ->cpu capacity orig))
             WRITE ONCE(d.rd->min cap orig cpu, i);
         sd = *per cpu ptr(d.sd, i);
         /*将每个cpu的调度域关联到每个cpu的rq的root domain上*/
         cpu attach domain(sd, d.rd, i);
     rcu read unlock();
 * Attach the domain 'sd' to 'cpu' as its base domain.
Callers must
  * hold the hotplug lock.
 * /
static void
cpu attach domain(struct sched domain *sd, struct root domain
 *rd, int cpu)
     struct rq *rq = cpu rq(cpu);
     struct sched domain *tmp;
     /* Remove the sched domains which do not contribute to
 scheduling. */
     for (tmp = sd; tmp; ) {
         struct sched domain *parent = tmp->parent;
         if (!parent)
            break;
```

```
if (sd_parent_degenerate(tmp, parent)) {
            tmp->parent = parent->parent;
            if (parent->parent)
                parent->parent->child = tmp;
            /*
             * Transfer SD_PREFER_SIBLING down in case of a
             * degenerate parent; the spans match for this
             * so the property transfers.
             * /
            if (parent->flags & SD_PREFER_SIBLING)
                tmp->flags |= SD_PREFER_SIBLING;
            destroy_sched_domain(parent, cpu);
        } else
            tmp = tmp->parent;
    }
    if (sd && sd degenerate(sd)) {
        tmp = sd;
        sd = sd->parent;
        destroy_sched_domain(tmp, cpu);
        if (sd)
            sd->child = NULL;
    }
    sched domain debug(sd, cpu);
    rq attach root(rq, rd);
    tmp = rq->sd;
    rcu assign pointer(rq->sd, sd);
    destroy_sched_domains(tmp, cpu);
    update top cache domain(cpu);
#ifdef CONFIG INTEL DWS
    update dws domain(sd, cpu);
#endif
```

通过调度域,调度组的建立过程,可以通过下面的图来直观的说明SDTL不同层级对应关系:

## 3 两层SDTL 调度域调度组topology关系图



## 4 若干个全局调度域变量简介

在看cfs调度算法中,在函数find\_best\_target看到全局调度域变量sd\_ea,在函数 sched\_group\_energy函数中看到sd\_scs全局变量等。我们看下几个与调度域相关的全局变量

```
/*
    * Keep a special pointer to the highest sched_domain that has
    * SD_SHARE_PKG_RESOURCE set (Last Level Cache Domain) for this
    * allows us to avoid some pointer chasing select_idle_sibling().
    *
    * Also keep a unique ID per domain (we use the first cpu number in
    * the cpumask of the domain), this allows us to quickly tell if
    * two cpus are in the same cache domain, see cpus_share_cache().
    */
    DEFINE_PER_CPU(struct sched_domain *, sd_llc);
    DEFINE_PER_CPU(int, sd_llc_size);
    DEFINE_PER_CPU(int, sd_llc_id);
    DEFINE_PER_CPU(struct sched_domain *, sd_numa);
    DEFINE_PER_CPU(struct sched_domain *, sd_busy);
    DEFINE_PER_CPU(struct sched_domain *, sd_asym);
```

```
DEFINE_PER_CPU(struct sched_domain *, sd_ea);DEFINE_PER_CPU(struct sched_domain *, sd_scs);
```

上面变量赋值的地方如下(调用路径如下: sched\_init\_smp ---> init sched domains--->build sched domains--->cpu attach domain--->upda

init\_sched\_domains--->build\_sched\_domains--->cpu\_attach\_domain--->update\_top\_cache\_domain即在将各个cpu附着在调度域上面实现的。):

```
static void update_top_cache_domain(int cpu)
•
   {
       struct sched domain *sd;
      struct sched_domain *busy_sd = NULL, *ea sd = NULL;
      int id = cpu;
      int size = 1;
       /* 比较简单,就是根据sd->flags的标志位,确定调度域是那种类型并返回. */
  #ifdef CONFIG INTEL DWS
      sd = highest_flag_domain(cpu, SD_SHARE_PKG_RESOURCES, 1);
      sd = highest flag domain(cpu, SD SHARE PKG RESOURCES);
   #endif
      if (sd) {
          /* 获取此调度域所包含的cpu的第一个cpu id */
          id = cpumask first(sched domain span(sd));
          /* 获取此调度域所包含的cpu的数量 */
          size = cpumask weight(sched domain span(sd));
          busy sd = sd->parent; /* sd busy */
       /* 设定最顶层的domain为busy domain*/
       rcu assign pointer (per cpu (sd busy, cpu), busy sd);
       /* 将sd, size, id 赋值给per_cpu变量*/
       rcu_assign_pointer(per_cpu(sd_llc, cpu), sd);
      per cpu(sd llc size, cpu) = size;
      per cpu(sd llc id, cpu) = id;
       sd = lowest flag domain(cpu, SD NUMA);
       rcu assign pointer(per cpu(sd numa, cpu), sd);
       /* sd->flags 在sd init已经初始化了。没有设置SD ASYM PACKING flag */
   #ifdef CONFIG INTEL DWS
      sd = highest flag domain(cpu, SD ASYM PACKING, 1);
   #else
      sd = highest flag domain(cpu, SD ASYM PACKING);
   #endif
       rcu_assign_pointer(per_cpu(sd_asym, cpu), sd);
       /* 对sd进行变量,从底层到顶层SDTL进行遍历,看调度组是否初始化了sched group energy
       结构体。定义的话,将sd赋值给变量ea sd,最后,ea sd赋值给per cpu变量sd ea */
       for each domain(cpu, sd) {
          if (sd->groups->sge)
              ea sd = sd;
          else
              break:
       }
       rcu_assign_pointer(per_cpu(sd_ea, cpu), ea_sd);
      /* flas SD SHARE CAP STATES没有定义 */
   #ifdef CONFIG INTEL DWS
      sd = highest flag domain(cpu, SD SHARE CAP STATES, 1);
   #else
      sd = highest_flag_domain(cpu, SD_SHARE_CAP_STATES);
```

```
#endif
    /* 将sd 赋值给per cpu变量sd scs, 按照调度域初始化流程看, sd scs==sd ea(采用
    EAS调度算法才是). 当然sd llc = sd ea = sd sd scs*/
    rcu_assign_pointer(per_cpu(sd_scs, cpu), sd);
 * highest flag domain - Return highest sched domain containing flag.
 * @cpu: The cpu whose highest level of sched domain is to
 * be returned.
 * @flag: The flag to check for the highest sched domain
       for the given cpu.
 ^{\star} @all:   

The flag is contained by all sched_domains from the hightest
down
 * Returns the highest sched_domain of a cpu which contains the given flag.
#ifdef CONFIG INTEL DWS
static inline struct
sched domain *highest flag domain(int cpu, int flag, int all)
static inline struct sched domain *highest flag domain(int cpu, int flag)
#endif
    struct sched_domain *sd, *hsd = NULL;
    for each domain(cpu, sd) {
       if (!(sd->flags & flag)) {
#ifdef CONFIG_INTEL_DWS
            if (all)
#endif
                break;
#ifdef CONFIG INTEL DWS
            else
                continue;
#endif
        hsd = sd;
    return hsd;
```

#### 通过打印来确定各个全局per cpu变量是什么关系和数值,打印patch如下:

```
void test_sd_func(void)

{
    struct sched_domain *sd;
    struct sched_group *sg;
    int cpu = cpumask_first(cpu_online_mask);

/*sd_scs sched_domain*/
    sd = rcu_dereference(per_cpu(sd_scs, cpu));

for_each_domain(0, sd) {
    sg = sd->groups;
    printk("sd_scs->name=%s sd_span=%d
",sd->name,cpumask_weight(sched_domain_span(sd)));
    do {
        printk(" first bit: %u",cpumask_first(sched_group_cpus(sg)));
    }

while (sg = sg->next, sg != sd->groups);
```

```
printk("\n");
    }
    for_each_domain(4, sd) {
        sg = sd->groups;
        printk("sd_scs->name=%s sd_span=%d
",sd->name,cpumask weight(sched domain span(sd)));
        do {
            printk("first bit: %u",cpumask_first(sched_group_cpus(sg)));
        } while (sg = sg->next, sg != sd->groups);
        printk("\n");
    }
/*sd_ea sched_domain*/
    sd = rcu_dereference(per_cpu(sd_ea, 0));
    for_each_domain(0, sd) {
        sg = sd->groups;
        printk("sd ea->name=%s sd span=%d
",sd->name,cpumask weight(sched domain span(sd)));
        do {
            printk(" first bit: %u ",cpumask_first(sched_group_cpus(sg)));
        } while (sg = sg->next, sg != sd->groups);
        printk("\n");
    for_each_domain(4, sd) {
        sg = sd->groups;
        printk("sd ea->name=%s sd span=%d
",sd->name,cpumask_weight(sched_domain_span(sd)));
        do {
            printk(" first bit: %u ",cpumask_first(sched_group_cpus(sg)));
        } while (sg = sg->next, sg != sd->groups);
        printk("\n");
/*sd llc sched domain*/
    sd = rcu_dereference(per_cpu(sd_llc, 0));
    for each domain(0, sd) {
        sg = sd->groups;
        printk("sd llc->name=%s sd span=%d
",sd->name,cpumask_weight(sched_domain_span(sd)));
        do {
            printk(" first bit: %u ",cpumask first(sched group cpus(sg)));
        } while (sg = sg->next, sg != sd->groups);
        printk("\n");
```

```
for_each_domain(4, sd) {
    sg = sd->groups;
    printk("sd_llc->name=%s sd_span=%d
",sd->name,cpumask_weight(sched_domain_span(sd)));
    do {
        printk(" first bit: %u ",cpumask_first(sched_group_cpus(sg)));

    } while (sg = sg->next, sg != sd->groups);
    printk("\n");
}

/*print sd_llc_size and sd_llc_id value for different cpu.*/
    printk("sd_llc_size=%d\n",this_cpu_read(sd_llc_size));
    printk("sd_llc_id(cpu=0)=%d,sd_llc_id(cpu=4)=%d\n",per_cpu(sd_llc_id,0),per_cpu(sd_llc_id,4));
}
```

#### 打印结果如下:

```
sd_scs->name=MC sd_span=4 first bit: 0 first bit: 1 first bit: 2 first bit: 3
sd_scs->name=DIE sd_span=8 first bit: 0 first bit: 4

sd_scs->name=MC sd_span=4 first bit: 4 first bit: 5 first bit: 6 first bit: 7
sd_scs->name=DIE sd_span=8 first bit: 4 first bit: 0

sd_ea->name=MC sd_span=4 first bit: 0 first bit: 1 first bit: 2 first bit: 3
sd_ea->name=DIE sd_span=8 first bit: 0 first bit: 4

sd_ea->name=MC sd_span=4 first bit: 4 first bit: 5 first bit: 6 first bit: 7
sd_ea->name=DIE sd_span=8 first bit: 4 first bit: 1 first bit: 2 first bit: 3
sd_llc->name=MC sd_span=4 first bit: 0 first bit: 1 first bit: 2 first bit: 3
sd_llc->name=DIE sd_span=8 first bit: 0 first bit: 4

sd_llc->name=MC sd_span=4 first bit: 4 first bit: 5 first bit: 6 first bit: 7
sd_llc->name=DIE sd_span=8 first bit: 4 first bit: 5 first bit: 6 first bit: 7
sd_llc->name=DIE sd_span=8 first bit: 4 first bit: 0

sd_llc_size=4
sd_llc_id(cpu=0)=0,sd_llc_id(cpu=4)=4
```

- 1. 上面数值每个两秒打印一次,调度域肯定是常量,每隔两秒打印目的是确定最后两个参数的数值是否是不变的,当然,对于没有cpuhotplug的情况下是常量,如果存在hotplug,那么上面的所有的数值都是动态变化的,除了sd\_llc\_id的数值。
- 2. 可以看到无论是DIE还是MC tl, 如果从中间遍历的话,它还是会通过next指针遍历其内部所有的sg。与第三章的topology图吻合。