# The Collection Tree Protocol (CTP)

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#### Note

This memo documents a part of TinyOS for the TinyOS Community, and requests discussion and suggestions for improvements. Distribution of this memo is unlimited. This memo is in full compliance with TEP 1.

### **Abstract**

This memo documents the Collection Tree Protocol (CTP), which provides best-effort anycast datagram communication to one of the collection roots in a network.

### 1. Introduction

A collection protocol delivers data to one of possibly several data sinks, providing a many-to-one network layer. Collection is a fundamental component of most sensor network applications. The Collection Tree Protocol (CTP) is a reference Collection protocol in TinyOS 2.x. The users use Collection interfaces described in TEP 119<sup>3</sup> to use CTP in their applications.

In this TEP, after a brief discussion of Collection and CTP, we specify the CTP routing and data frames. CTP uses routing frames to update and build collection tree in the network. CTP uses data frames to deliver application payload to the sink and to probe topology inconsistencies.

All fields in this specification are in network byte order.

## 2. Assumptions and Limitations

CTP is a tree-based collection protocol. Some number of nodes in a network advertise themselves as tree roots. Nodes form a set of routing trees to these roots. CTP is **address-free** in that a node does not send a packet to a particular root; instead, it implicitly chooses a root by choosing a next hop. Nodes generate routes to roots using a routing gradient.

The CTP protocol assumes that the data link layer provides four things:

- 1) Provides an efficient local broadcast address.
- 2) Provides synchronous acknowledgments for unicast packets.
- 3) Provides a protocol dispatch field to support multiple higher-level protocols.
- 4) Has single-hop 16-bit source and destination fields.

CTP assumes that it has link quality estimates of some number of nearby neighbors. These provide an estimate of the number of transmissions it takes for the node to send a unicast packet whose acknowledgment is successfully received.

CTP has several mechanisms in order to achieve high delivery reliability, but it does not promise 100% reliable delivery. It is a best effort protocol.

CTP is designed for relatively low traffic rates such that there is enough space in the channel to transmit and receive routing frames even when the network is forwarding collection data frames. Bandwidth-limited systems or high data rate applications might benefit from a different protocol, which can, for example, pack multiple small frames into a single data-link packet or employ rate control mechanisms.

### 3. Collection and CTP

CTP uses expected transmissions (ETX) as its routing gradient. A root has an ETX of 0. The ETX of a node is the ETX of its parent plus the ETX of its link to its parent. This additive measure assumes that nodes use link-level retransmissions. Given a choice of valid routes, CTP SHOULD choose the one with the lowest ETX value. CTP represents ETX values as 16-bit decimal fixed-point real numbers with a precision of tenths. An ETX value of 45, for example, represents an ETX of 4.5, while an ETX value of 10 represents an ETX of 1.

Routing loops are a problem that can emerge in a CTP network. Routing loops generally occur when a node choose a new route that has a significantly higher ETX than its old one, perhaps in response to losing connectivity with a candidate parent. If the new route includes a node which was a descendant, then a loop occurs.

CTP addresses loops through two mechanisms. First, every CTP packet contains a node's current gradient value. If CTP receives a data frame with a gradient value lower than its own, then this indicates that there is an inconsistency in the tree. CTP tries to resolve the inconsistency by broadcasting a beacon frame, with the hope that the node which sent the data frame will hear it and adjust its routes accordingly. If a collection of nodes is separated from the rest of the network, then they will form a loop whose ETX increases forever. CTP's second mechanism is to not consider routes with an ETX higher than a reasonable constant. The value of this constant is implementation dependent.

Packet duplication is an additional problem that can occur in CTP. Packet duplication occurs when a node receives a data frame successfully and transmits an ACK, but the ACK is not received. The sender retransmits the packet, and the receiver receives it a second time. This can have disasterous effects over multiple hops, as the duplication is exponential. For example, if each hop on average produces one duplicate, then on the first hop there will be two packets, on the second there will be four, on the third there will be eight, etc. CTP keeps a small cache of packet signature for the packets it has seen to detect packet duplicates. When a new packet arrives, if its signature results in cache hit, CTP drops the packet because it is a duplicate.

Routing loops complicate duplicate suppression, as a routing loop may cause a node to legitimately receive a packet more than once. Therefore, if a node suppresses duplicates based solely on originating address and sequence number, packets in routing loops may be dropped. CTP data frames therefore have an additional time has lived (THL) field, which the routing layer increments on each hop. A link-level retransmission has the same THL value, while a looped version of the packet is unlikely to do so.

### 4. CTP Data Frame

The CTP data frame format is as follows:

1
0 1 2 3 4 5 6 7 8 9 0 1 2 3 4 5
+-
P C  reserved   THL
+-+-+-+-+-+-+-+-+-+-+-+-+-+-+-+-+-+-+-
ETX
+-
origin
+-
seqno   collect_id
+-
data
+-

Field definitions are as follows:

- P: Routing pull. The P bit allows nodes to request routing information from other nodes. If the unicast destination of the data frame with a valid route hears a packet with the P bit set, it SHOULD transmit a routing frame in the near future. Nodes other than the link-layer destination of the data frame MAY respond to the P bit in the data frame.
- C: Congestion notification. If a node drops a CTP data frame, it MUST set the C field on the next data frame it transmits.
- THL: Time Has Lived. When a node generates a CTP data frame, it MUST set THL to 0. When a node receives a CTP data frame, it MUST increment the THL. If a node receives a THL of 255, it increments it to 0.

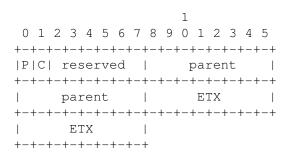
- ETX: The ETX routing metric of the single-hop sender. When a node transmits a CTP data frame, it MUST put the ETX value of its route through the single-hop destination in the ETX field. If a node receives a packet with a lower gradient than its own, then it MUST schedule a routing frame in the near future.
- origin: The originating address of the packet. A node forwarding a data frame MUST NOT modify the origin field.
- seqno: Origin sequence number. The originating node sets this field, and a node forwarding a data frame MUST NOT modify it.
- collect\_id: Higher-level protocol identifier. The origin sets this field, and a node forwarding a data frame MUST NOT modify it.
- data: the data payload, of zero or more bytes. A node forwarding a
  data frame MUST NOT modify the data payload. The length of the
  data field is computed by subtracting the size of the CTP header from
  the size of the link layer payload provided by the link layer.

Together, the origin, seqno and collect\_id fields denote a unique \*origin packet.\* Together, the origin, seqno, collect\_id, and THL denote a unique \*packet instance\* within the network. The distinction is important for duplicate suppression in the presence of routing loops. If a node suppresses origin packets, then if asked to forward the same packet twice due to a routing loop, it will drop the packet. However, if it suppresses packet instances, then it will route successfully in the presence of transient loops unless the THL happens to wrap around to a forwarded packet instance.

A node MUST send CTP data frames as unicast messages with link-layer acknowledgments enabled.

## **5. CTP Routing Frame**

The CTP routing frame format is as follows:



The fields are as follows:

- P: Same as data frame with one difference: Routing frames are broadcast so multiple nodes respond to the P bit in the routing frame.
- C: Congestion notification. If a node drops a CTP data frame, it MUST set the C field on the next routing frame it transmits.
- parent: The node's current parent.
- metric: The node's current routing metric value.

When a node hears a routing frame, it MUST update its routing table to reflect the address' new metric. If a node's ETX value changes significantly, then CTP SHOULD transmit a broadcast frame soon thereafter to notify other nodes, which might change their routes. The parent field acts as a surrogate for the single-hop destination field of a data packet: a parent can detect when a child's ETX is significantly below its own. When a parent hears a child advertise an ETX below its own, it MUST schedule a routing frame for transmission in the near future.

A node MUST send CTP routing frames as broadcast messages.

### 6. Implementation

An implementation of CTP can be found in the tos/lib/net/ctp directory of TinyOS 2.0. This section describes the structure of that implementation and is not in any way part of the specification of CTP.

This implementation has three major subcomponents:

- 1) A **link estimator**, which is responsible for estimating the single-hop ETX of communication with single-hop neighbors.
- 2) A **routing engine**, which uses link estimates as well as network-level information to decide which neighbor is the next routing hop.
- 3) A **forwarding engine**, which maintains a queue of packets to send. It decides when and if to send them. The name is a little misleading: the forwarding engine is responsible for forwarded traffic as well as traffic generated on the node.

#### **6.1 Link Estimation**

The implementation uses two mechanisms to estimate the quality of a link: periodic LEEP<sup>1</sup> packets and data packets. The implementation sends routing beacons as LEEP packets. These packets seed the neighbor table with bidirectional ETX values. The implementation adapts its beaconing rate based on network dynamics using an algorithm similar to the trickle dissemination protocol<sup>2</sup>. Beacons are sent on an exponentially increasing randomized timer. The implementation resets the timer to a small value when one or more of the following conditions are met:

- 1) The routing table is empty (this also sets the P bit)
- 2) The node's routing ETX increases by  $\geq 1$  transmission
- 3) The node hears a packet with the P bit set

The implementation augments the LEEP link estimates with data transmissions. This is a direct measure of ETX. Whenever the data path transmits a packet, it tells the link estimator the destination and whether it was successfully acknowledged. The estimator produces an ETX estimate every 5 such transmissions, where 0 successes has an ETX of 6.

The estimator combines the beacon and data estimates by incorporating them into an exponentially weighted moving average. Beacon-based estimates seed the neighbor table. The expectation is that the low beacon rate in a stable network means that for a selected route, data estimates will outweigh beacon estimates. Additionally, as the rate at which CTP collects data estimates is proportional to the transmission rate, then it can quickly detect a broken link and switch to another candidate neighbor.

The component tos/lib/net/4bitle/LinkEstimatorP implements the link estimator. It couples LEEP-based and data-based estimates as described in<sup>4</sup>.

### **6.2 Routing Engine**

The implementation's routing engine is responsible for picking the next hop for a data transmission. It keeps track of the path ETX values of a subset of the nodes maintained by the link estimation table. The minimum cost route has the smallest sum the path ETX from that node and the link ETX of that node. The path ETX is therefore the sum of link ETX values along the entire route. The component tos/lib/net/ctp/CtpRoutingEngineP implements the routing engine.

### 6.3 Forwarding Engine

The component tos/lib/net/ctp/CtpForwardingEngineP implements the forwarding engine. It has five responsibilities:

- Transmitting packets to the next hop, retransmitting when necessary, and passing acknowledgment based information to the link estimator
- 2) Deciding when to transmit packets to the next hop
- 3) Detecting routing inconsistencies and informing the routing engine
- 4) Maintaining a queue of packets to transmit, which are a mix of locally generated and forwarded packets
- Detecting single-hop transmission duplicates caused by lost acknowledgments

The four key functions of the forwading engine are packet reception (SubReceive.receive()), packet forwarding (forward()), packet transmission (sendTask()) and deciding what to do after a packet transmission (SubSend.sendDone()).

The receive function decides whether or not the node should forward a packet. It checks for duplicates using a small cache of recently received packets. If it decides a packet is not a duplicate, it calls the forwading function.

The forwarding function formats the packet for forwarding. It checks the received packet to see if there is possibly a loop in the network. It checks if there is space in the transmission queue. If there is no space, it drops the packet and sets the C bit. If the transmission queue was empty, then it posts the send task.

The send task examines the packet at the head of the transmission queue, formats it for the next hop (requests the route from the routing layer, etc.), and submits it to the AM layer.

When the send completes, sendDone examines the packet to see the result. If the packet was acknowledged, it pulls the packet off the transmission queue. If the packet was locally generated, it signals sendDone() to the client above. If it was forwarded, it returns the packet to the forwarding message pool. If there are packets remaining in the queue (e.g., the packet was not acknowledged), it starts a randomized timer that reposts this task. This timer essentially rate limits CTP so that it does not stream packets as quickly as possible, in order to prevent self-collisions along the path.

### 7. Citations

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# 8. Citations

<sup>&</sup>lt;sup>1</sup>TEP 124: Link Estimation Extension Protocol

<sup>&</sup>lt;sup>2</sup>Philip Levis, Neil Patel, David Culler and Scott Shenker. "A Self-Regulating Algorithm for Code Maintenance and Propagation in Wireless Sensor Networks." In Proceedings of the First USENIX Conference on Networked Systems Design and Implementation (NSDI), 2004.

<sup>&</sup>lt;sup>3</sup>TEP 119: Collection.

<sup>&</sup>lt;sup>4</sup>Rodrigo Fonseca, Omprakash Gnawali, Kyle Jamieson, and Philip Levis. "Four Bit Wireless Link Estimation." In Proceedings of the Sixth Workshop on Hot Topics in Networks (HotNets VI), November 2007.