

# SeCloak: ARM Trustzone-based Mobile Peripheral Control

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## ABSTRACT

Reliable on-off control of peripherals on smart devices is a key to security and privacy in many scenarios. Journalists want to reliably turn off radios to protect their sources during investigative reporting. Users wish to ensure cameras and microphones are reliably off during private meetings. In this paper, we present SeCloak, an ARM TrustZone-based solution that ensures reliable on-off control of peripherals even when the platform software is compromised. We design a secure kernel that co-exists with software running on mobile devices (e.g., Android and Linux) without requiring any code modifications. An Android prototype demonstrates that mobile peripherals like radios, cameras, and microphones can be controlled reliably with a very small trusted computing base and with minimal performance overhead.

## CCS CONCEPTS

• **Security and privacy** → **Mobile platform security**; *Privacy protections*;

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## 1 INTRODUCTION

Personal smart devices are now central to communication, productivity, health, and education habits of their owners. Whether they are carried in a purse or pocket, or worn on a wrist, these devices form a hub for location, activities, social encounters, and even health status. As more people incorporate these devices in to their daily lives, more personal data resides in these devices.

With the increasing reach of these devices has emerged new classes of attacks on personal privacy in the form of data breaches from malicious apps and OS compromises. Data available to these devices are often of a highly sensitive nature, including biometrics [64], health information [28, 46], user location and unique

device ID [21, 25, 26], user activity [11, 38] including conversations [50] and video [17], all of which have been subject of attacks and leaks. Beyond explicitly gathered data, the sensors on these devices can often be configured or coaxed into providing sensitive information such as user conversation, location, and activity beyond their original design [42, 43, 51, 59]. The fact that such attacks are now common is not surprising: as vendors add more functionality, the software base that, often, must be trusted has grown to millions of lines of code, and the data that can be stolen is highly lucrative. As a result, there is a perceived loss of trust in these devices: sophisticated (and increasingly regular) users are no longer certain *exactly* what their device is monitoring or what data is being gathered. Worse, there are many situations when the loss of privacy translates to loss of security (or worse), and these users need unambiguous and reliable methods to control their devices. Currently, the only fully reliable control is to remove the battery if possible (or place the device in a Faraday cage.)

At the same time however, these devices have highly sophisticated hardware security built into their architecture, which is commonly used to store biometric information and for financial transactions. In this paper, we address the following question:

What is minimally required atop existing hardware primitives to give users secure and direct control over the sensors and radios in their devices, without affecting the functionality of the rest of the device, or changing the installed large software base?

The system we present, SeCloak, short for “Secure Cloak” would allow users to, for example, verifiably<sup>1</sup> turn off all radios (e.g., WiFi, Bluetooth, cellular) and sensors (e.g., GPS, microphone), using hardware mechanisms. This guarantee would hold even if apps were malicious, the framework (e.g., Android) was buggy, or the kernel (e.g., Linux) was compromised.

An independent layer addresses an important part of the general security and privacy problem by enabling users to reliably control the availability of certain I/O devices, regardless of the state of vendor or third-party supplied software (in our prototype: apps, Android, and Linux). It is easy to make the case for SeCloak with regards to privacy: SeCloak can be used to reliably turn off recording devices such as cameras, microphones, and other sensors whenever users require such privacy; users would continue to be able to use the rest of the functionality of their device. There are other

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<sup>1</sup>“Verifiably” in our context does not refer to a formal proof of correctness, but to the fact that the secure software can (1) unambiguously notify users of the state of the hardware, and (2) allow users to reliably control the hardware state of their device. We believe the small size of our TCB makes it (more) amenable to formal analysis, but such verification is out of scope for this paper.

situations where SeCloak is useful that is perhaps even more critical: for example, SeCloak would enable a journalist to reliably place their phone into a mode where their physical whereabouts cannot be traced. Given the importance and ubiquity of mobile devices, we believe that a capability such as SeCloak, which enables secure and robust control over hardware, is not simply an option but a necessity in many use cases.

SeCloak is built using the ARM TrustZone hardware security extension. In order, our design goals are to:

- (1) Allow users to securely and verifiably control peripherals on their device
- (2) Maintain system usability and stability
- (3) Minimize the trusted code base
- (4) Not change existing software including the apps, frameworks or OS kernels

As we will explain later, TrustZone provides extensive support for running individual CPU cores in “secure” and “non-secure” modes, and allows for dynamic partitioning of the hardware into secure and non-secure components. An isolated trusted OS kernel can run in secure mode, and control all memory/peripheral accesses and interrupts received by the non-secure kernel. The facilities provided by TrustZone makes satisfying (1) and (3) relatively trivial. However, since the non-secure software (in our case: Linux, Android, and all apps) are not written for such dynamic system partitioning, satisfying (1)-(4) simultaneously is surprisingly difficult.

The primary contribution of this paper is the design and implementation of an end-to-end system that (nearly) satisfies all four of our stated goals. SeCloak employs a small custom kernel, called the s-kernel, to securely place the device in a user-approved state. The s-kernel traps and emulates load and store operations to protected devices by the untrusted Android platform to enforce the user’s policy with a very small trusted computing base.

Users can set preferences using an untrusted Android app. These preferences are conveyed to the s-kernel by the app, and then confirmed by the user to the s-kernel directly. Beyond control of individual devices, the app identifies different modes of operation (e.g., Airplane mode that turns off all transmitters) for convenience. Even with parts of the hardware not available to the non-secure kernel, Android remains usable, and the device performs as expected. While the app itself is rudimentary, we believe our proof-of-concept demonstrates that goals (1) and (2) can be simultaneously satisfied. The entire s-kernel, including secure device initialization, setting device state per user preference, user interaction for confirmation, and instruction emulation, is only 15k lines of code. (In comparison, the Linux kernel is roughly 13m lines of code.) We believe our s-kernel TCB size satisfies the third goal. Finally, SeCloak requires 1 source line to be changed in the Linux kernel (the change can be applied directly to the kernel binary if the source is not available), introduces a new kernel module (for calls into the s-kernel), and no change whatsoever to other software layers, including Android. Thus, we get very close to satisfying the last goal of not having to change existing software.

The rest of this paper is organized as follows. We cover related work and background in ARM TrustZone in Section 2 and describe the design of the s-kernel in Section 3. We describe our secure kernel

in Section 4 and non-secure software in Section 5. We present an evaluation of SeCloak in Section 6, and conclude in Section 7.

## 2 BACKGROUND AND RELATED WORK

Motivated by the security and privacy problems in mobile devices, recent work envisions many different solutions for malicious apps, including novel permission models [8, 19, 47, 61, 65–67] and sandboxing [7, 9, 48, 55]. Reference monitors and security kernels [2, 15, 24, 32, 39, 45, 53, 63] provide fine-grained access-control mechanisms that can contain application misbehavior. However, these solutions assume that the kernel itself is not compromised. To address problems with compromised or malicious kernels, we have to consider approaches that use hardware-based containment of peripherals. Hence, in this section, we focus on hardware techniques that can be used to implement an isolated software component that controls peripherals.

Peripherals can be isolated from a platform OS using virtualization extensions [12, 14] or hardware security extensions [5, 14, 27, 30, 35]. We discuss a subset of such prior works, specifically focusing on secure peripheral control.

*Controlling peripherals via Virtualization.* One approach is to run the platform OS as a guest within a virtual machine, leaving a hypervisor in control of peripheral devices. Existing work uses hypervisors to isolate applications from untrusted OSs [12, 29, 33, 40], protect integrity and confidentiality of the application memory and provide support for managing cryptographic keys. Beyond memory integrity, Inktag [29] and Sego [33] provide trusted access to the filesystem. These systems are designed for isolating individual applications from the OS, but don’t provide a mechanism to reliably control generic peripherals like SeCloak.

Zhou et al. [68, 69] propose trusted path schemes using a hypervisor to host the untrusted OS and all trusted program endpoints (PEs) of applications in separate VMs, with the PEs supplying all of the necessary device drivers. DriverGuard [13] protects I/O data flows by using a hypervisor to ensure that only privileged code blocks (PCBs) can operate on the raw, unencrypted I/O data. BitVisor [58] is a hypervisor that implements “para-virtualization” for enforcing security on I/O control and data. SGXIO [62] posits a system in which a hypervisor hosts the untrusted OS (running in a VM) as well as the trusted I/O drivers (running in Intel SGX [30] enclaves). Lacuna [20] ensures that I/O flows can be securely erased from memory once they terminate, by relying on virtualization, encryption, and direct NIC access.

These approaches seek to protect the integrity and confidentiality of I/O data paths while maintaining full functionality, which comes at the expense of a large TCB. SeCloak, on the other hand, provides reliable on/off control of smart device peripherals based on a very small TCB.

*Hardware Security Extensions.* Beyond virtualization, modern architectures offer trusted hardware components e.g., Intel SGX [30] and ARM TrustZone [5], which can be used to isolate software components from an untrusted platform OS. These techniques go beyond Trusted Platform Modules (TPM), which enable secure boot, or Intel Trusted eXecution Technology (TXT) [31] and AMD Secure Virtual Machine (SVM) [1], which allow for attested execution of the

OS or smaller code segments [41]. Of particular interest to mobile smart devices is TrustZone, because ARM is the dominant CPU architecture in this market and TrustZone supports the isolation of peripheral device access.

ARM TrustZone [5] is a set of hardware security extensions that supports isolation of two “worlds” of execution: non-secure and secure. TrustZone differs from SGX in two important ways: TrustZone does not address hardware memory attacks (i.e., it does not encrypt the secure world’s RAM), and unlike SGX, TrustZone addresses peripheral device security as described next.

Each processor core executes in the context of a single world at any time; a core can “switch” worlds using a privileged instruction (and, if configured, upon exceptions or interrupts). All accesses to memory and I/O devices are tagged with an additional bit, the ‘NS’ bit, which specifies whether the access was issued while the core was in non-secure mode. Components in the system (e.g., bus and memory controllers) can be configured, in hardware, to only allow secure accesses.

By default, TrustZone supports a single isolated execution environment (the secure world), with a secure boot process that can be used to verify the bootloader and the secure-world kernel. Komodo [23] provably extends TrustZone to support attested isolated execution environments similar to Intel SGX enclaves (though physical memory snooping remains out of scope.) Cho et al. [14] explore a hybrid approach to supporting isolated execution environments with both a hypervisor and ARM TrustZone. During the lifetime of a secure application, the hypervisor is active and provides isolation; otherwise, the hypervisor is disabled (reducing overhead) and TrustZone hardware protections are used to protect sensitive memory regions. Neither of these systems address peripheral access control.

*Controlling peripherals using TrustZone.* Prior work has built trusted path using TrustZone, with much focus on balancing the size of the secure TCB versus functionality. For instance, TrustUI [34] enables trusted paths without trusting device drivers by splitting drivers into an untrusted backend and trusted frontend that runs within the secure kernel. TrustUI uses ad-hoc techniques, such as randomizing keys on the on-screen keyboard after every touch, for ensuring that the information available to the non-secure kernel does not leak device data. ShrodiText [3] is a system for displaying text while preserving its confidentiality from the untrusted OS. ShrodiText establishes a secure path between a remote (trusted) server and the local framebuffer/display for this purpose, relying on TrustZone and a hypervisor (for MMU and IOMMUs) to secure parts of the rendering stack. Liu et al. [36] uses trusted device and bus drivers, implemented in TrustZone and hypervisors, to attest and encrypt sensor readings. SeCloak instead focuses on reliable on/off control of peripherals on mobile platforms with a very small TCB.

TrustZone is the basis for commercial products [35, 54, 56, 60] that implement support for isolated execution of secure applications and for secure IO. Many of these systems provide specific applications for secure data input (e.g., PIN and fingerprint input, biometric identification) [54, 60]. Unlike SeCloak, these systems provide no device configuration controls. OP-TEE [35] is a small TCB OS for

implementing secure applications over TrustZone. Our prototype SeCloak is built on a much pared-down version of OP-TEE.

Brasser et al. [10] enable on/off control of peripheral devices that are in restricted spaces (e.g., where the use of the camera is not allowed). The system relies on a local, TrustZone-isolated policy enforcement service that grants a remote policy server read/write access to system memory. To protect against rogue accesses, the user relies on a separate vetting server that determines whether to allow or deny each of the policy server’s memory access requests. The policy server uses this remote memory access capability to query the state of the platform OS and modify the OS’s device configuration according to the desired policy. The policy server must be able to handle any platform OS version, configuration, and state, which increases its TCB and requisite maintenance over time. Also, the policy server cannot tolerate any vulnerability in the platform OS that is not known to the policy server (e.g., zero-day exploits), and must periodically re-check the state to ensure continued compliance. Like this work, SeCloak provides reliable on/off control of peripheral devices; however, it does so under a stronger threat model that includes a compromised platform OS. Additionally, SeCloak has a smaller TCB as it does not depend on any details of the platform OS in order to meet the requisite security properties.

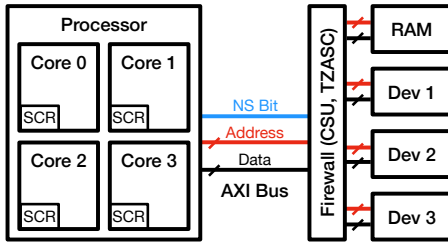
Santos et al. [16, 57] present “trust leases”, which allow applications to request (with user approval) leases to place the device in a restricted mode until some terminal condition is met (e.g., after 4 hours). The trust lease model could be used to implement a settings application that allows the users on/off control over peripheral I/O devices. Their threat model assumes that the platform OS is trusted and correct; their prototype implementation lives inside the Android framework and Linux kernel. In contrast, SeCloak has a stronger threat model that includes a malicious platform OS, and operates as a separate, minimal secure kernel that runs alongside the existing platform OS.

PROTC [37] is a system for safeguarding flight control systems on drones from non-essential but malicious software. PROTC runs applications in the TrustZone non-secure world, and a kernel with access to protected peripherals in secure world. PROTC’s secure kernel communicates with ground control using an encrypted channel. Compared to SeCloak, PROTC is designed for a different application domain, and does not allow for dynamic modification of protected peripherals. Untrusted applications are always isolated, and the secure kernel contains all of the protected device drivers.

Viola [44] enables custom, per-peripheral notifications whenever the I/O peripheral device is being used; for example, blinking the notification LED when the camera is active. Viola employs formal verification techniques to provide guarantees that the user will be notified. SeCloak and Viola are complementary: the user could use SeCloak to disable devices and rely on Viola to notify them when specific enabled devices are in use.

### 3 DESIGN OVERVIEW

As we have described, many prior approaches have ported (parts of) device drivers into a secure kernel to provide robust access to peripherals, and for limiting the access given to the NS-kernel.



**Figure 1: High-level overview of SoC architecture, focusing on the security components that SeCloak relies on.**

However, none of them satisfy the goals of SeCloak. Our work departs from these systems in two major ways: we do not modify the NS-kernel—the NS-kernel device drivers, interfaces, etc. remain completely unchanged. Next, our secure kernel TCB is extremely small (see Section 6.1). Since the s-kernel we describe here focuses entirely on providing the SeCloak functionality (as opposed to more general secure device access or control), we do not require large device drivers or complicated mechanisms within the s-kernel. In fact, the bulk of the functionality provided by the s-kernel relies on instruction trapping and emulation of ARM load and store instructions to enable selective access to peripherals.

Figure 1 shows a schematic of the ARM TrustZone architecture (and associated hardware components provided by the SoC we use to implement SeCloak). Recall that the TrustZone security model posits that the CPU can be in a “Non-Secure” (NS) mode or “Secure” mode, and all memory and bus accesses are tagged with the CPU mode using an extra “NS-bit” bus line. (There are, in fact, many different privileged modes the processor can be in, including a secure “monitor” mode that we use extensively.) Different peripherals, including parts of RAM, IO devices and interrupts, can be configured to be available only in Secure mode. In our design, Linux runs as the NS-kernel, and SeCloak (with its secure kernel) controls the secure modes of the CPU<sup>2</sup>.

The ARM Security Configuration Register (SCR) contains the “NS” bit that describes whether the core executing code is in the non-secure or secure mode. The SCR also contains a bit that determines whether a hardware exceptions not raised by the CPU (so called “external aborts” in ARM, e.g., a data abort raised from a memory access) cause the processor to switch to the secure monitor mode. As we shall see, it is this setting of the SCR that enables SeCloak to trap and emulate instructions issued by the Linux kernel. The SCR also contains similar configuration bits for interrupts, which SeCloak uses to listen for user input and support secure system reboot. ARM supports two types of interrupts: IRQs and FIQs. Traditionally, the secure world exclusively uses FIQs and the non-secure world uses IRQs; therefore, the SCR is set to trap FIQs to the secure monitor mode.

ARM provides a TrustZone Address Space Controller (TZASC) that can partition portions of RAM such that they are available only to secure mode accesses, enabling isolation of the s-kernel memory from Linux.

Our SeCloak prototype is built using a i.MX6 SoC. i.MX provides a TrustZone compatible component, the Central Security Unit (CSU), that extends the secure/non-secure access distinction to peripherals. The CSU can be used to enable secure-only access for different peripherals (which SeCloak uses), and also for programming access to various bus DMA masters (e.g., the GPU). The CSU contains a set of registers, called the “Config Security Level” (CSL) registers, which can be set to mandate secure-only access to various peripherals, e.g., GPIO controllers, PWM devices, etc. While our implementation programs the i.MX-specific CSU, the design is general, and can be ported to other SoCs which provide similar functionality.

In Figure 1, we encapsulate the TZASC and CSU as a virtual “firewall” on the control path to RAM and devices. In hardware implementation, these components are not necessarily on the control bus or the bus path, but may further program other hardware components that control access. For our purposes and for SeCloak software, this logical view of an intercepting firewall is sufficient (and accurate).

SeCloak uses a purpose-built kernel (the s-kernel) that runs in TrustZone secure mode. The s-kernel programs each of these components (the SCR, the TZASC, the CSU) as required, both at initialization and runtime to enable SeCloak. We next discuss a user’s typical workflow with SeCloak before describing how the s-kernel is configured to enable SeCloak.

### 3.1 Threat Model

We assume that the device hardware is not malicious, and that the state of the hardware (number and type of IO devices, their physical addresses and buses, interrupts, etc.) is encapsulated in a “device tree” file that is signed by a trusted source, as explained later in Section 4.1. (The hardware on modern embedded- and small-devices is usually described in such a device tree, and existing kernels already provide library routines to parse this format.)

Beyond the hardware, we assume that the boot ROM and boot-loader is trusted and correctly loads the s-kernel. The s-kernel is also trusted and assumed correct.

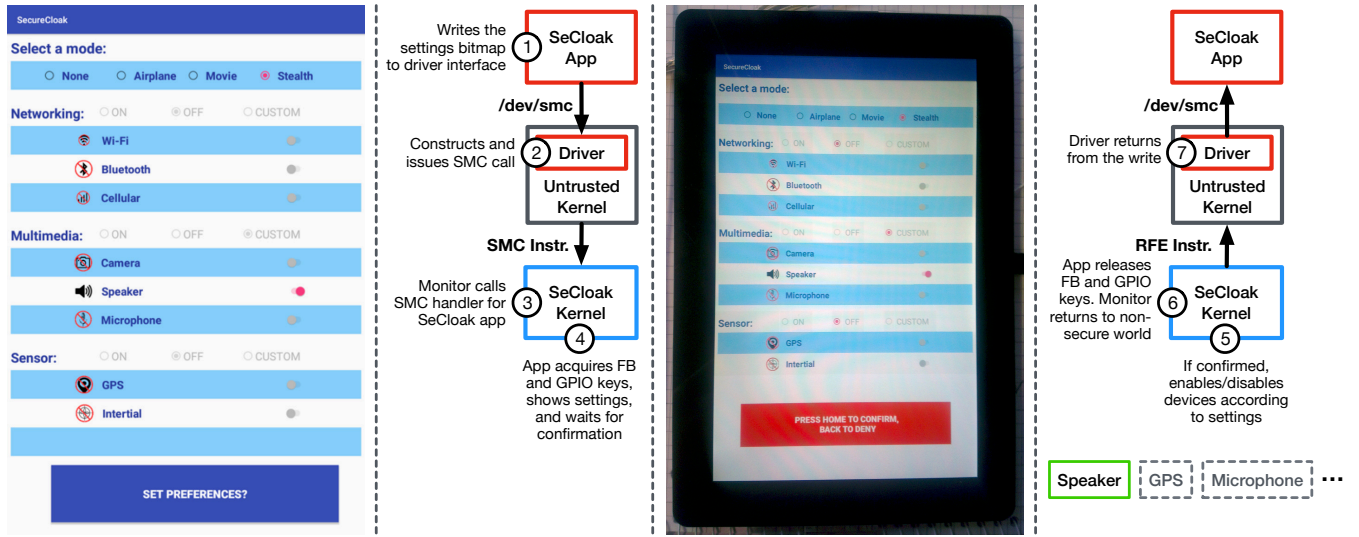
All other software in the system may be faulty or malicious. This includes any app the user may run, any framework layer (such as Android), any kernel modules, and the NS-kernel itself.

### 3.2 SeCloak Workflow

Figure 2 shows the SeCloak workflow. Users interact with a regular Android app (leftmost screenshot), and choose On or Off settings for various IO devices and peripherals. This app is similar to the “Settings” apps that are already available on smartphones and tablets.

An implicit assumption is that users understand which peripherals should be turned off (or on) under different circumstances. Towards this end, the SeCloak app helps users by providing predefined operating modes (e.g. Airplane mode or Stealth mode) and associated settings for the appropriate groups of peripherals. As we shall see next, SeCloak ensures that for any mode or sets of individual devices that the user chooses in this step, the user receives an unambiguous confirmation of their state.

<sup>2</sup>Note that it is also possible to implement SeCloak on top of hardware virtualization mechanisms (i.e., nested page tables and IOMMUs).



**Figure 2: Overview of the SeCloak workflow.** The first panel (leftmost) shows a screenshot of the non-secure Android app. The second panel shows the steps taken after the user pushes the button to apply the settings. The third panel shows a photograph of the secure SeCloak app, which (re-)displays the settings to the user and waits for user confirmation. (Screenshots are not possible in secure mode.) The fourth panel shows the steps taken if the user confirms the settings, such as disabling/enabling devices and returning control back to the non-secure world (and app).

Once the user chooses “Set Preferences?”, the app uses a Linux device driver to invoke a cross-kernel call, called a SMC call in TrustZone (second panel from left in Figure 2). The argument to this call encodes the user’s preferences. The s-kernel receives these preferences as part of the SMC call handler. Note that malicious software (the app, system services, the NS-kernel) could have changed the preferences prior to the SMC call!

User preferences, possibly modified, are received within the s-kernel as part of the SMC call. At this point, the s-kernel takes exclusive access of the framebuffer and hardware buttons. The s-kernel parses the preferences, and recreates an image that exactly corresponds to the settings chosen by the user, and copies this images to the framebuffer. *If* the preferences had been modified, the image on the framebuffer would *not* correspond to the settings chosen by the user, and the user would notice a setting that does not correspond to their choice. The user is thus notified of malicious software on their device.

The s-kernel changes the “Set Preferences?” button to one that allows the user to confirm the settings by pressing a hard button (the “Home” button), or to go back (using the Back key) to the app and continue changing settings. We show a photograph of this screen (with a red secure confirm button) in the third panel of Figure 2.

A malicious app could display the preferences screen and then spoof the confirmation screen. It is imperative that during the confirmation phase, the user is unambiguously notified that she is interacting with the s-kernel. Thus, during this phase, the s-kernel lights a protected LED which ensures the user that she is interacting with the s-kernel. This LED is never accessible to the NS-kernel.

Assuming the settings were as the user intended, she may confirm the settings by pressing the “Home” button. The s-kernel disables (or enables) various IO devices and peripherals as instructed (rightmost panel in Figure 2).

## 4 SECLOAK SECURE KERNEL

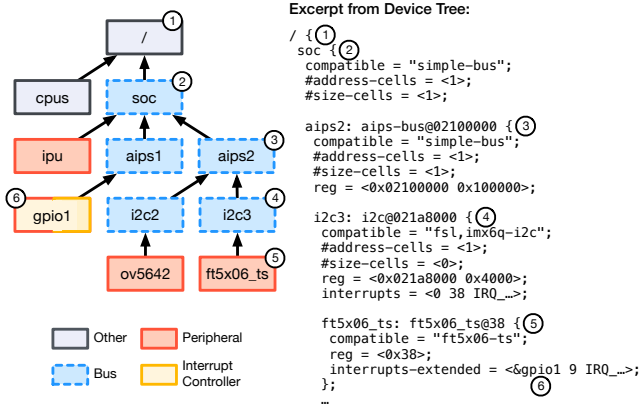
We describe SeCloak’s secure kernel, called the s-kernel, in this section. A signed device tree describes available hardware and protections to the s-kernel. Prior to describing the kernel itself, we discuss how it is securely booted (next), and the device tree.

Modern devices are equipped with secure, tamper-proof, non-volatile storage, into which device manufacturers embed (hashes of) public keys. The devices contain a one-time programmable Boot ROM that has access to these keys, which are “fused” onto the hardware.

In bootstrapping SeCloak, we assume that a trusted principal (either the hardware manufacturer or the user) has performed the following steps:

- Generated a trusted key, and stored the key onto the tamper-proof non-volatile storage. For convenience, modern devices often allow multiple such keys to be “fused” onto the hardware; once installed, these cannot be removed or modified by software.
- Program the boot ROM to load a signed bootloader image. The boot ROM verifies the signature against the fused key(s) and then executes the bootloader if successful.
- The bootloader (U-Boot [22] in our case) contains a set of public keys which it uses to verify signatures on all loaded images. The bootloader will locate and load a signed s-kernel image and signed device tree blob (explained next). After





**Figure 3: Visualization of the device tree with a corresponding excerpt from the device tree file for the Boundary Devices Nitrogen6Q SoC. The labeled nodes correspond to parents and dependencies of the “ft5x06\_ts” touchscreen device.**

verifying the signatures, the bootloader will execute the s-kernel. Modern bootloaders already support such verified booting.

#### 4.1 Device Tree

The device tree structure [18] describes the hardware devices present in a given system and how they are interconnected, with each node representing an individual device. It is important to note that the device tree, by our assumptions, must be an accurate and complete description of the hardware. Otherwise, there may be other peripherals in the system that can completely violate any and all security properties, since the s-kernel would not know of their existence, and would not be able to control the NS-kernel’s access to these “rogue” peripherals.

Figure 3 shows an excerpt from the device tree of our prototype board, showing the arrangement of the touchscreen device (ft5x06\_ts), the camera device (ov5642), the image processing unit (ipu), and one of the gpio controllers (gpio1). This is a typical arrangement of buses and devices on a modern SoC: for example, we see that the touchscreen device and the camera are attached to I<sup>2</sup>C buses, which themselves are slaves of the AIPS (AHB-to-IP-Bridge) which is a hardware bridge between the system bus and third-party IP blocks such as the I<sup>2</sup>C controllers.

Each node has named properties along with a set of child nodes; some properties might also express non-parental dependencies on other devices in the system (e.g., touchscreen relying on GPIO pin for interrupts). Some devices, such as buses, clocks, and interrupt controllers, have required properties that denote how their children (for buses) or dependents (for clocks and interrupt controllers) can reference their resources.

In addition to the standard device tree, we add several properties to device nodes. First, we add a “class” property that maps low-level components (such as interrupts and pins) to user-understandable names, such as “microphone”, “WiFi”, etc. These class strings correspond to individual devices that can be controlled via SeCloak.

Second, we add a “protect” property that identifies hardware protection bits that must be set to protect the device. On our prototype, these map devices to their associated CSU registers.

#### 4.2 SeCloak Kernel

Upon boot, the s-kernel initializes hardware defaults prior to launching the NS-kernel. Specific steps include setting control and security registers to appropriate defaults, and setting memory protections such that the NS-kernel cannot overwrite the s-kernel’s state.

The s-kernel initializes its internal data structures by initializing the system MMU with virtual memory page table mappings for various regions, including regions for non-secure RAM, s-kernel heap, and for MMIO devices. The s-kernel also starts the non-boot CPUs, and initializes per-core threads and their contexts. Faults and calls from the NS-kernel transition the CPU into a monitor mode, and the s-kernel initializes the secure monitor with its stack pointer and call vector. Finally, the s-kernel opens and parses the device tree.

**4.2.1 s-kernel Device Drivers.** The s-kernel itself contains minimal drivers for three devices: GIC (generic interrupt controller), GPIO controller, and the framebuffer. The GIC driver isolates interrupts that can be received by the NS-kernel, the GPIO controller allows the s-kernel to directly interact with hardware buttons, and the framebuffer driver allows the s-kernel to render the confirmation screen. Together, they enable the secure part of SeCloak. We explain these drivers next.

**GIC Driver.** The Generic Interrupt Controller (GIC) chip handles the distribution of interrupts to CPU cores and enables isolated control and handling of non-secure and secure interrupts. The s-kernel GIC driver supports functions to (1) enable or disable specific interrupts, (2) set cpu mask and interrupt priority, (3) assign interrupts to security groups, and (4) registering interrupt handlers. These functions allow isolating interrupts associated with specific devices to be either completely disabled or to be delivered to the s-kernel. The s-kernel can receive hardware interrupts and optionally re-deliver them to the NS-kernel; for example, this functionality is used by the GPIO and GPIO keys drivers that we describe next.

**GPIO Driver.** The general-purpose input-output (GPIO) controller supports input and output operations on individual hardware pins. In addition, the GPIO controller can also act as an interrupt controller on a per-pin basis. When an interrupt condition is triggered for a pin, the GPIO controller triggers a (chained) interrupt which is handled by the GIC.

The s-kernel GPIO driver supports acquiring/releasing pins for exclusive s-kernel use, registering an interrupt handler for a given pin, and reading (or writing) values from (or to) a pin. The GPIO driver relies on the GIC driver to register its own interrupt handler, which (when invoked) will read the GPIO device state in order to determine which pins raised the interrupt, and then invoke handlers corresponding to these pins. The driver protects and emulates accesses to the GPIO controllers in order to allow the non-secure world to continue to use any non-acquired pins while preventing it from inferring any information about the acquired (secured) pins.

Building on the GPIO driver, the GPIO keys driver supports hardware buttons/keys connected to GPIO pins (e.g., power and

volume buttons). The GPIO keys handler translates hardware button presses into a key code that is specified in the device tree (e.g., KEY\_BACK) and passes it on to any s-kernel listeners. The listeners can choose to consume the key press or allow it to be passed back to the non-secure world. We use the GPIO keys driver to register listeners for a secure shutdown sequence (see Section 5.2), and also for the cloak application to wait for the user to confirm or deny the displayed settings.

**Framebuffer Driver.** The s-kernel framebuffer driver uses the image processing unit (IPU) device to display images. When the s-kernel application acquires the framebuffer, the driver allocates a single buffer in the secure region of memory and sets the buffer format (RGB24) in the IPU. Additionally, the driver protects access to the IPU and emulates accesses in order to prevent the non-secure world from overwriting the settings (see Section 4.6.1 for emulation policy details). When the s-kernel application releases the framebuffer, the driver restores the previous settings of the non-secure world and unprotects the IPU. Additionally, the framebuffer driver provides helper functions for clearing the buffer with a single color and for blitting images onto the display at specified locations. We rely on the framebuffer driver for (re-)displaying the settings in the SeCloak app. The images displayed by the s-kernel framebuffer driver cannot be modified by the NS-kernel.

### 4.3 SMC Handlers

The s-kernel supports two SMC calls, CLOAK\_SET and CLOAK\_GET, from the NS-kernel to enable SeCloak.

The NS-kernel invokes the CLOAK\_SET call with a bitvector as the argument. Individual bits in the bitvector correspond to the settings for different device classes. The bitvector contains “special” bits that encode modes (e.g., Airplane, Movie, Stealth), and groups (e.g., Networking) as displayed by the app.

The CLOAK\_SET handler executes the following steps:

- It starts by acquiring the framebuffer and GPIO keypad (via GPIO). As described in Section 4.2.1, acquiring devices applies necessary hardware protection settings, emulation policy, and initial settings for the secure use of the device.
- The CLOAK\_SET handler parses the bitvector and checks to see if it is valid; if so, it uses framebuffer driver routines to blit corresponding images to the screen in order to (re-)display the settings to the user.
- Next, the notification LED, which is persistently acquired for exclusive use by the s-kernel, is turned on by the handler (via GPIO) to notify the user that the s-kernel is in control.
- The CLOAK\_SET handler then waits for the user to confirm (via the ‘Home’ button) or deny (via the ‘Back’ button) the settings via its registered GPIO keypad listener. If the user confirms the settings, the handler will issue calls to enable or disable each device class; otherwise, if the user denies the settings, the handler does not take any action.
- Finally, the handler releases the acquired devices (which resets per-device state as necessary, e.g., framebuffer formatting and addresses) and returns.

In order to disable (or re-enable) a device class, the CLOAK\_SET handler first identifies all devices that belong to the given class (as

described in the device tree). For each of those devices, the handler locates any “protect” properties, which identify the hardware protection that must be set to isolate the device. In some cases, the device itself may not have hardware protection, but the bus it is located on may. Thus, the code must search for possible hardware isolation not just at the device node, but recursively up the device tree as well. In this way, the s-kernel applies the hardware isolation for each device as described in the device tree.

The NS-kernel can use the CLOAK\_GET call to receive a bitvector that encodes the current protection state of device classes (and which mode is active or which groups are enabled or disabled). Upon launch, the non-secure Android app uses this call to render an initial setting.

### 4.4 Non-Secure and Secure Device Sharing

We rely on the ability to share devices between the non-secure and secure worlds, such as for providing a secure shutdown sequence via the GPIO keypad (e.g., power and volume buttons) while still allowing the non-secure world to handle button presses. Two underlying mechanisms enable such sharing: 1) interrupt (re-)delivery to the non-secure world, and 2) emulation policy to control the non-secure view of the device. While explaining the mechanisms, we will focus on the example of the GPIO controller. The GPIO controller uses a GIC interrupt in order to signal that the interrupt condition is met for one (or more) pins.

In order to share interrupts with the non-secure world, we modify the device tree such that the s-kernel operates on the actual hardware interrupt line of the device that is connected to the GIC, while the NS-kernel operates on a (previously unused) interrupt line. When the s-kernel receives an interrupt that should be shared, it sets the corresponding non-secure world interrupt line pending via the GIC.

### 4.5 DMA

Devices that are DMA masters can issue memory accesses on the system bus. For example, the Image Processing Unit (IPU) will perform periodic DMA transfers to read from framebuffers (whose addresses are specified in the IPU’s registers). Each DMA master has permissions assigned for its bus accesses (i.e., non-secure or secure), which (on our platform) are configured in the CSU registers. In order to prevent the DMA masters from reading (or even modifying) the s-kernel memory, we must configure their accesses as non-secure. However, this presents a problem for the IPU device: since we need to present a secure framebuffer to the screen, it must be able to perform DMA accesses to secure memory regions. To address this, we use the TZASC to configure the region that contains the framebuffer as non-secure read and secure read/write. While this lets the NS-kernel inspect the secure framebuffer, we do not require confidentiality of this framebuffer for any of our security goals (only the integrity of its contents).

### 4.6 Instruction Faults and Emulation

The s-kernel configures TrustZone such that accesses by the NS-kernel to memory regions that belong to protected devices cause a fault. This fault is trapped by the monitor mode handler of the

s-kernel. We need these traps to be able to selectively allow or deny NS-kernel accesses to devices.

For a rudimentary SeCloak app, it is sufficient to simply configure TrustZone protections, and ignore these faults. However, such a solution is unworkable if we want the device to remain usable, as per our original goals, when specific peripherals are protected. In general, the s-kernel has to trap the faulting instructions, and selectively emulate them based on hardware state as we describe in this section.

There are two main reasons to intercept non-secure accesses to protected resources and emulate these accesses in the secure world. First, there can be a mismatch between the granularity of hardware protection and that of individual devices that are being protected. For instance, on the i.MX 6 [49], the Central Security Unit (CSU) contains Config Security Level (CSL) registers that restrict access to peripheral devices according to whether the accesses are made by the non-secure or secure world. These CSL registers group multiple devices into a single register (e.g., GPIO1 & GPIO2 or PWM1 through PWM4). If we want to disable a single (or subset of) devices, we must allow accesses to all others that are protected by the CSL group. Dependencies in the device tree can also cause mismatches in hardware–software protection granularity. For example, the ft5x06\_ts touchscreen uses a GPIO pin to signal an interrupt to the processor when the user is touching the screen; in order to secure the touchscreen, we must also secure the *individual* GPIO pin, but not all the 64 pins that are protected by the corresponding CSL register.

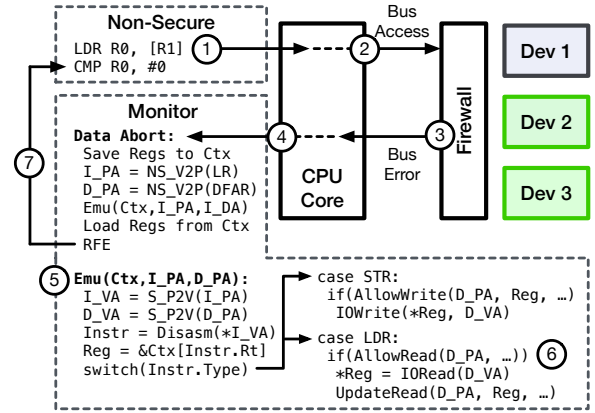
Second, we can use emulation for efficiently acquiring devices for (temporary) exclusive use by secure applications, as well as to share devices between the secure and non-secure worlds. This can reduce the trusted codebase in the s-kernel, e.g., by allowing NS-kernel writes to the device for non-critical accesses. We use this technique to reduce the driver code size for the framebuffer driver.

**4.6.1 Instruction Emulation: Detail.** Each access to a device ultimately performs a memory-mapped Input/Output (MMIO) read or write operation to a region of memory associated with the device. (The mapping of memory region to device is obtained from the device tree.) When hardware protections are enabled for a particular device, MMIO accesses produce data abort exceptions; these are traditionally handled by the NS-kernel.

**Hardware setup.** In order to intercept these accesses, s-kernel sets up the Secure Configuration Register (SCR) in the CPU to specify that all external aborts should be handled by the monitor. This setting causes data aborts to signal a fault that transitions the CPU into the secure monitor mode. The faulting address and related information is available to the monitor fault handler.

In the s-kernel, the secure monitor fault handler invokes a routine that determines whether to emulate or deny the access and, if emulated, whether to modify the value being read or written. The s-kernel maintains a data structure that contains regions of memory (physical base address and size) corresponding to different devices, along with the prevailing policy for each.

The policy associated with each region may choose to deny a read or write. If a read is allowed, the value that is read can be modified prior to being returned to the NS-kernel. If a write is allowed, the value to be written can be modified prior to the write.



**Figure 4: Components and steps involved in intercepting and emulating accesses made by the non-secure world.**

The s-kernel code decodes the instruction that cause the original fault: these instructions are of the form ldr (load register for reads) or str (store register for writes). By default, the s-kernel emulates the instruction exactly and returns control back to the NS-kernel.

**NS-kernel Execution.** Figure 4 shows this process. Here a non-secure driver attempts to read from a device (“Dev 1”) that is disabled by SeCloak. Specifically, the NS-kernel code issues a LDR R0, [R1] instruction to load from the address pointed to by R1 into R0. The R1 register contains a memory address that belongs to “Dev 1”.

Upon executing this instruction (1), the CPU issues a read on the system bus (2). This memory read is intercepted by the hardware firewall (CSU/TZASC) responsible for protecting “Dev 1”. The firewall checks to see if the access should be allowed; if not, the firewall returns a bus error to the CPU (which interprets this as an external data abort). In this case, since “Dev 1” is disabled by SeCloak, the firewall will deny the read and report a bus error to the CPU (3).<sup>3</sup> The CPU receives this bus error which corresponds to an external data abort. Given the SCR configuration, the CPU switches to monitor mode and invokes the monitor mode’s data abort handler (4).

The data abort handler saves (and later restores) the current register set<sup>4</sup> and preserves the location to return to (i.e., the instruction following the faulting instruction).

**Fault Handling.** At this point, the fault handler has to determine two items: what was the instruction that caused the fault, and what was the faulting address? By convention, the Data Fault Address Register (DFAR) contains the virtual address of the access that caused the fault, and the LR register contains the virtual address of the instruction that caused the fault. However, these virtual addresses are *non-secure* virtual addresses, and the fault handler uses an ARM co-processor routine to resolve them into physical addresses (“D\_PA” from the DFAR, and “I\_PA” from the LR). The

<sup>3</sup>The system can be configured to also issue an interrupt to the CPU upon such an error; we do not use this option in our implementation.

<sup>4</sup>To be precise, some registers in ARM are “banked” (e.g., the link register LR), in that each mode has its own copy of the register. The abort handler saves the non-banked registers as well as the LR corresponding to the mode that caused the abort.



fault handler then passes control to the s-kernel emulation routine with the saved register context of the non-secure world (called “Ctx”) and these two addresses as arguments.

The emulation routine (5) begins by translating these physical addresses to secure-world virtual addresses, and checks to make sure that they are in appropriate regions: the non-secure RAM for the instruction and a device MMIO region for the data address. Next, the emulation routine invokes a custom instruction decoder we have written to decode the instruction and determine the type of instruction (whether it is a load or store) and the register involved in the transfer.

Once the instruction and the physical address is decoded, the prevailing policy (e.g., deny or allow with modifications) is implemented as described above. In this case, the access is made by a load instruction, so the emulation first checks to see if the policy allows the read, performs the IO read operation, and finally checks to see if the policy wants to modify the result (6). If allowed, the final result is stored in the NS-context structure (that contains the non-secure registers).

In order to handle the case where multiple slave devices share a bus, a bus-specific policy must be provided. The device tree contains resource information that specifies how each device will be addressed on the bus; for instance, in the case of I<sup>2</sup>C, this corresponds to the 7-bit slave address assigned to each device. The policy operates over the accesses to the bus’s MMIO region to determine which device is being accessed, such that it can deny accesses to disabled devices (while allowing all others).

*NS-kernel resume.* The emulation routine then returns control back to the data abort handler, which restores the registers for the non-secure world from the NS-context data structure. Note that for reads, one of these registers may now be updated as a result. Once the data abort handler terminates, the NS-kernel continues by executing the instruction directly after the one that caused the data abort (7).

## 5 NON-SECURE KERNEL

Figure 2 shows a screenshot of the SeCloak Android app in the left-most panel. The current version of the app is simple, allowing users to set ON/OFF preferences for the devices on our prototype board. Along with individual devices, the app allows users to choose different operating modes (e.g., Airplane, Stealth) and also provides the state of groups of peripherals (e.g., all networking devices.)

Once the user presses the “Set Preferences?” button, the app invokes a JNI call with a bitvector that encodes the user preferences. The JNI module uses a Linux `ioctl` call to pass the bitvector to the SeCloak kernel module which, in turn, issues the SMC call to the s-kernel with the bitvector as an argument.

### 5.1 A modification to the NS-kernel

Recall that our design goals were not to modify the NS-kernel or existing software if at all possible. Unfortunately, without a single byte modification, as we describe next, we can only provide the security guarantee, but not maintain system stability.

SeCloak requires that the s-kernel be able to trap individual accesses to protected devices and selectively emulate these instructions. However, as normally compiled, a Linux binary on ARM does

not raise data aborts that identify the *specific* instruction that cause the abort.

Whether an instruction raises a precise or imprecise abort depends on the page table entry (PTE) attributes of the memory that the instruction attempts to access. Precise data aborts are triggered for `ldr` and `str` instructions that access “strongly-ordered memory”. Strongly ordered memory does not allow accesses to be buffered by either the processor or bus interconnect [6].

As a result, we must modify Linux such that it configures its device memory mappings to raise precise aborts. While we do this step directly in the source, it is a simple change that can, in fact, be applied on the binary kernel image itself.

In our design, the s-kernel assumes that the NS-kernel is “compliant” in setting device memory to be strongly-ordered. However, a non-compliant NS-kernel can still not access protected devices. It will, however, likely not receive any useful service from protected device groups due to faulty emulation.

*Kernel module.* The SeCloak app requires a kernel module to invoke SMC calls, and we have added such a module to Linux. (Later versions of the Linux/ARM kernels already provide a standard SMC interface like our kernel module does, though even these kernels would require a module to export a userspace interface.) The kernel module provides a `ioctl` interface, which is used to communicate the user-selected bitvector to the NS-kernel.

*Framework Calls.* Along with the single change to the NS-kernel, the SeCloak app also issues Android calls to address application and system stability. Note that these are not *changes* to the framework, but instead, extra calls that are invoked by the SeCloak app.

When the user elects to disable certain devices, the s-kernel configures hardware firewall mechanisms to prevent all accesses to the disabled devices. If the hardware device is attached to the system bus, then MMIO writes are discarded and reads return 0; otherwise, if attached to a peripheral bus, then bus access functions will return an error. Ultimately, device drivers are responsible for handling these errors, which typically involve several retries before abort. These errors will further propagate to system services (and applications) that are attempting to use the device; for example, when the camera is disabled and the user attempts to run the camera app, an error message appears after a few seconds.

Within the kernel, power management (PM) routines in device drivers rely on the ability to communicate with their devices in order to save relevant state and direct it to enter a low-power mode. When a device is disabled by the s-kernel, these PM routines will fail and thus keep the device in a high-power active mode. In adverse cases, the inability to transition individual devices into low power states can prevent the entire system from being able to transition to a low-power state, such as suspend-to-RAM. Second, some device drivers may not contain appropriate error handling to gracefully recover from errors resulting from the denied accesses.

Therefore, the SeCloak app makes use of available system services (e.g., `WifiManager` with `setWifiEnabled`) to disable devices prior to configuring the hardware firewall mechanisms (and likewise enable devices after removing the hardware firewall restrictions).

## 5.2 Device Reset

After a peripheral has been secured, malicious software inside the NS-kernel or framework can try to subvert security by rebooting the entire device. Such a reboot could happen without the user necessarily noticing (while the device was idle) and could even be remotely triggered.

One option is to make device policies persistent in the s-kernel, such that they would be applied whenever the device is booted. While technically feasible (and indeed quite trivial), this option affects usability. Upon boot, the NS-kernel (Linux) probes available devices based on the device tree, and may not set up the device files and other software correctly if the probe fails (which it would if the device were secured upon boot.) In turn, parts of the Android framework may not initialize, leaving the device in a unstable/unusable state. Without a kernel rewrite or support, it is difficult (if not impossible) to uniformly re-enable devices that were protected at boot.

Instead, we adopt the following policy: the NS-kernel can reset the device only if there are no disabled devices. Otherwise, the s-kernel does not allow the NS-kernel to invoke PSCI [4] calls that are used to reset the processor.

This design choice has the following implications: first, no code, including remote exploits, in the NS-kernel can reboot the device if any peripheral is protected. On the other hand, when the device is rebooted, the regular NS-kernel probes can proceed as usual, and the device reboots in a fully usable state. Further, the s-kernel does not need to keep persistent state about policies, since the device always reboots with all peripherals accessible to the NS-kernel. When the NS-kernel needs to reset the device (e.g., after OS or software updates), the user must first run the SeCloak app and remove all protections.

The user may, at times, need to reboot the device after protection has been applied. For instance, the NS-kernel or Android may become unresponsive due to bugs or attacks. To address this scenario, within the s-kernel, we recognize a hardware key sequence that the user can input to initiate a reset. Since physical user input is necessary for the device to be reset, this is a safe option, in that the user is aware that the device is booting into a unprotected state.

## 6 EVALUATION

We use the Boundary Devices Nitrogen6Q development board to run our experiments, which contains an i.MX6 SoC with a quad-core ARM A9 processor with TrustZone security extensions. We use Android Nougat 7.1.1 with the Linux kernel version 4.1.15, both of which are provided by Boundary Devices. The s-kernel implementation is based on our custom fork of OP-TEE [35]. OP-TEE is a OS for implementing secure applications over TrustZone; s-kernel heavily modifies and reduces the OP-TEE codebase. Specifically, s-kernel retains OP-TEEs kernel threading and debugging support. s-kernel's MMU code is also based on OP-TEE. The device drivers required for SeCloak (e.g., framebuffer and GPIO keypad), device tree parsing, instruction interception and emulation, and the code for securing device state was developed specifically for the s-kernel.

We first present results to quantify the size of the TCB, both in terms of the lines of code as well as the interface exposed to the NS-kernel. Next, we evaluate the overhead due to intercepting

Type	LOC Breakdown				Stmt
	C Src	C Hdr	ASM	Total	
Core	3233	2357	1391	6981	3781
Drivers					
CSU	45	9	0	54	29
Device Tree	401	57	0	458	261
Frame Buffer	146	29	0	175	113
GPIO	562	15	0	577	284
GPIO Keypad	169	14	0	183	89
<Other>	579	167	0	746	265
Drivers Total	1902	291	0	2193	1041
Libraries					
libfdt	1220	350	0	1570	840
bget/malloc	1421	68	0	1489	797
<Other>	1479	1182	81	2742	1212
Libraries Total	4120	1600	81	5801	2849
Total	9255	4248	1472	14975	7671

**Table 1: Breakdown of the lines of code (LOC) for different parts of our s-kernel implementation. We list the LOC according to the language used (and source vs. header) along with the total LOC. “Stmt” refers to number of statements, which counts lines in assembly (ASM) and semi-colons in C source and headers.**

and emulating accesses and show that, while there is a fair amount of overhead for individual instructions, the reduction in overall system performance is negligible.

### 6.1 Size of TCB

In Table 1, we show a breakdown of the lines of code for our s-kernel implementation. “Core” consists of all non-driver and non-library code in the s-kernel. This code handles core s-kernel functionality, such as: memory management, threading, the secure monitor, SMC handling (e.g., PSCI and CLOAK). “Drivers” consists of all driver code, which is further broken down into specific drivers that we added to OP-TEE. The “<Other>” category contains pre-existing drivers, such as the UART (i.e., console), GIC, and TZASC-380 drivers. The “Frame Buffer”, “GPIO”, and “GPIO Keypad” drivers are smaller than their Linux counterparts since the secure drivers do not need to support all device functionality.

As listed under “Libraries”, our device tree parsing code relies on libfdt to extract information from the flattened device tree file that the bootloader places into RAM. Additionally, the s-kernel uses the bget and malloc support for dynamic memory allocation. Finally, there are several other libraries and sets of functions that are aggregated as “<Other>”, such as: snprintf and trace functions (for printing debug info), qsort (for sorting memory regions data structures), and common standard library functions (e.g., memcpy, strcmp). In general, we could further reduce our reliance on these libraries but leave this for future work.

In total, our s-kernel comes to just under 15k LOC (~7.7k statements). The s-kernel has a limited attack surface in terms of the

Execution	Instruction Time ( $\mu$ s)	
	Load (ldr)	Store (str)
Linux	0.11	0.29
Linux+SOM	0.27	0.33
Emulated	1.14	1.19

**Table 2: Time to execute ARM instructions in the non-secure world that make device accesses. “Linux” execution uses the baseline Linux kernel without any changes. “Linux+SOM” execution uses the baseline Linux kernel but changing the device memory regions to enforce strong ordering of accesses. For “Emulated” execution, we configure the s-kernel to protect access to the WiFi controller and emulate the instructions that result in data aborts.**

interfaces that the s-kernel provides to the NS-kernel, namely CLOAK\_SET and CLOAK\_GET. CLOAK\_SET takes one argument, which is a bit vector containing the modes, groups, and classes that the user wishes to enable or disable; CLOAK\_GET takes no arguments.

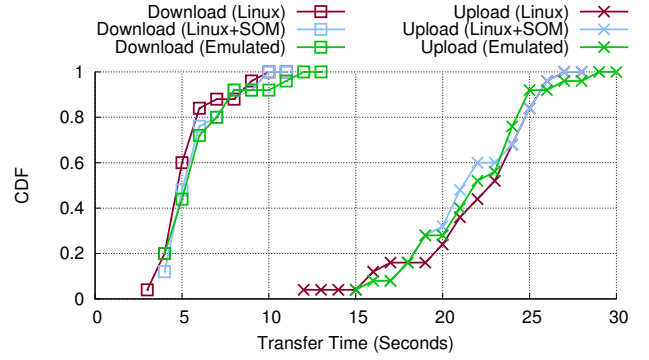
## 6.2 Emulation Overhead

We perform two experiments to analyze the performance overhead introduced by emulating non-secure instructions that access devices. We focus on the case where the emulation is allowed, such as when devices are shared between the non-secure and secure world (e.g., GPIO) or when multiple devices (one of which is disabled) belong to the same hardware firewall protection group.

In Table 2, we show the time taken to execute a single ARM load (ldr) or store (str) instruction that access a 32-bit device register on the WiFi controller. We issued each instruction one million times to compute the time taken for each individual instruction, and averaged this time over five trials. We varied the execution between “Linux”, “Linux+SOM”, and “Emulated” modes. For “Linux” execution, we use the baseline Linux kernel without any changes, while for “Linux+SOM” we change the attributes for device memory regions to enforce strong ordering of memory accesses (required for interception and emulation, see Section 4.6). For “Emulated” execution, we configure the s-kernel to protect access to the WiFi controller via the hardware firewall (i.e., CSU) registers and set the emulation policy to allow accesses to the WiFi controller’s MMIO registers.

The requirement of strongly-ordered memory accesses imposes some overhead as expected, increasing the time taken by 2.45x and 1.14x, respectively. As expected, we see an increase in the time taken due to trapping and emulating the instructions is 4.22x and 3.61x for loads and stores respectively. Note that, even though intercepting and emulating accesses incurs a fair amount of overhead, high-throughput devices (e.g., camera, network, and display) rely heavily on DMA transfers for performance and should remain largely unaffected by emulation overhead (which only affects the control path for DMA). To that end, we next take a look at a macro-level benchmark involving the WiFi controller.

Figure 5 show the time taken to transfer files over WiFi when the controller accesses are emulated vs. not. We used the WiFi Speed Test [52] application to perform the experiments and log the time



**Figure 5: Time taken for upload and download transfers of a 10 MB file to complete over WiFi. “Linux”, “Linux+SOM”, and “Emulated” correspond execution modes evaluated in Table 2**

taken for each of the trials; we used a laptop as the other endpoint for the file transfers.

The x-axis shows the time taken by the transfer in seconds, and the y-axis shows the cumulative fraction of transfers that completed within a given time. Each CDF in Figure 5 is computed over 25 runs.

The download and upload performance shows that there is no visible impact of interception and emulation on WiFi transfers, despite an appreciable increase in execution time for individual load and store instructions (as shown in Table 2). This is because the WiFi driver and controller, like all modern bulk data transfer devices, uses DMA to transfer packets. Once the controller firmware is loaded, and the DMA tables configured, each packet transfer (which can be many thousand bytes) requires very few (tens) MMIO instructions to initiate the DMA. We believe this result indicates that SeCloak can be used, even for high performance peripherals, without significant impact on user-perceived performance.

## 7 CONCLUSION

In this paper, we have described a system, SeCloak, that uses a small-TCB kernel to allow users to unambiguously and verifiably control peripherals on their mobile devices. Such a capability has many uses, e.g., it can allow users to ensure they are not being recorded, or journalists to ensure that they are not being tracked by using radio or other means.

The main technical challenge in designing SeCloak was to ensure that existing mobile device software, in particular Android and Linux, could co-exist with the secure kernel without code modification and without affecting device stability and usability. Towards this end, we have described an instruction emulation mechanism that enables SeCloak without changing existing software using a very small secure kernel.

SeCloak is a system that allows users to assert binary control over peripheral availability. It is easy to imagine situations where finer grained control is more appropriate, e.g., controlling the GPS device to provide city-level location to specific apps, and true location to others. In future work, we will extend our architecture to support non-binary control over peripheral devices. In addition, we plan to explore more cooperation between the two kernels for

enabling device power management operations and for improving performance by requiring strongly-ordered accesses only for protected devices.

The source code for our implementation is publicly available at:

<http://www.cs.umd.edu/projects/secureio>

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