Deep Video Analytics A data-centric approach to Computer Vision

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Developments over last 5 years High quality libraries & pre-trained models

- Theano
- Torch
- ROS
- Caffe
- Tensor Flow
- MXNET
- PyTorch
- Deeplearnjs

- Recognition
 - Inception / VGG / Resnet
- Detection
 - R-CNN / YOLO / SSD
- Face detection / recognition
 - MTCNN / Facenet
- Semantic Segmentation
 - Multipathnet / FCN / CRFasRNN

Developments over last 5 years A deluge of datasets!

- Open Images
- Yahoo Flickr Creative Com. 100M
- MSCOCO
- ViCom
- Visual Genome
- YouTube-BoundingBoxes / 8M
- AMOS

- imSitu, Charades by AllenAl
- KITTI /Toronto City
- Udacity car dataset
- Caltech, INRIA, ETH Pedestrians
- Stanford Drone Dataset
- Uber text
- THUMOS

Number of datasets ≅ Number of research groups With each dataset having its own JSON or XML format, incompatible with all others.

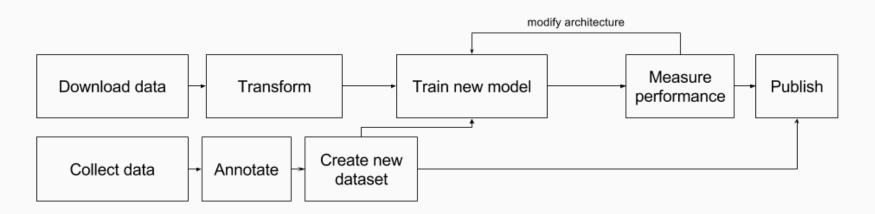
What else changed over last 5 years?

- Container ecosystem (Docker, Kubernetes) enables deployment of complex applications.
- Ability to scale quickly by adding compute capability (including GPUs) billed at minutes / seconds resolution. E.g. AWS Spot / GCP preemptible, AWS Lambda / GCP Cloud functions.
- Flexible cloud storage options. E.g. S3, EBS & EFS.

What is hidden in plain sight?

Model-centric approach

Libraries & frameworks are designed with **goal of training and evaluation of models for individual tasks**.



Unsuitable for building systems that learn in interactive manner, or leverage data from multiple sources or combine multiple tasks.

We need a data-centric approach that allows us to combine

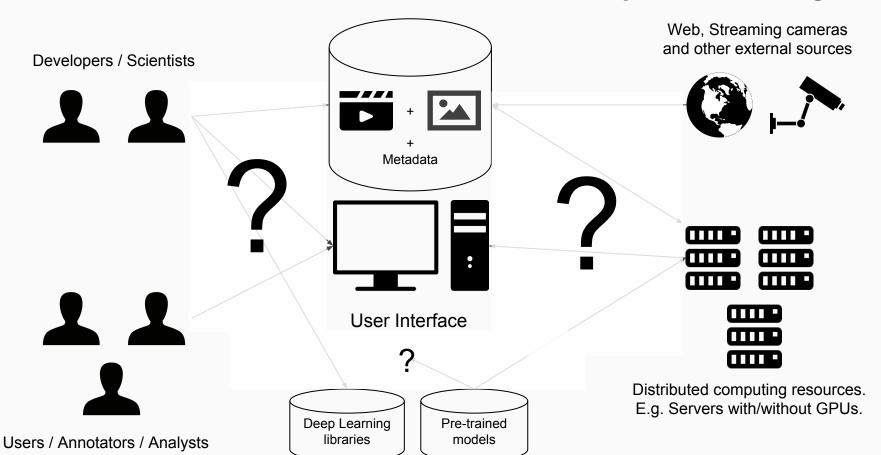
- Models for multiple tasks
- Data from multiple sources
- User Interaction / interface

A Relational Model of Data for Large Shared Data Banks. By Edgar F. Codd

Can we develop an equivalent of relational model for visual data?

Relational data: Postgres, MYSQL, SQLite
::
Text, HTML: Lucene/Solr, Elasticsearch
::
Videos & Images:

How do we structure Visual Data processing?



Previous attempts: LIRE project

- LIRE: Lucene Image Retrieval
 - http://www.lire-project.net/
- Developed pre-Deep Learning
- Functionality limited to computing & storing feature
 vectors such as Color Layout, Edge Histogram, etc.

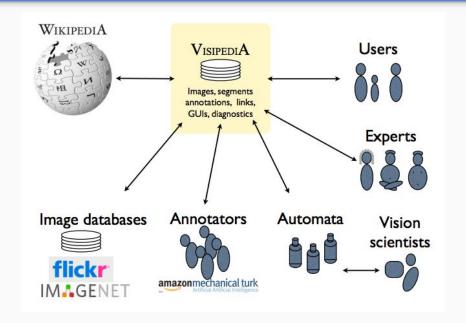
Previous attempts: CloudCV

- Large Scale Distributed Computer Vision as a Cloud Service
- Support for OpenCV, Graphlab, Cafe
- Image Classification, VQA, stitching, etc
- Does not retains state. E.g. you cannot store images.

Previous attempts: NVidia DIGITS

- "DIGITS (the Deep Learning GPU Training System) is a webapp for training deep learning models."
- Load/create datasets, train models, deploy models.
- Aimed at researchers
- Written in Python/Flask with Torch & Caffe supported

Previous attempts: Visipedia



Previous attempts: Visipedia

- Collaborative creation of visual data
- Pre-defined set of concepts E.g. Birds, Trees
- Different type of participants
 - Experts, Annotators, Citizen Scientists, Users, Computer scientists
- Retains state

Previous attempts: VMX.ai

- Underfunded Kickstarter project Circa Jan 2014
- by Tomasz Malisiewicz
- Pre Tensor Flow, Pre Deep Learning
- Allow developers to create real time detectors
- Support for training model

Quick summary

- LIRE: limited functionality (Lucene add-on)
- CloudCV: Provides a service, cannot retain "state"
- NVidia Digits: Intended for training not inference
- Visipedia: Intended to be a monolithic deployment

Few ongoing attempts

- Scanner by Alex Poms (CMU) & Will Crichton (Stanford)
 - https://github.com/scanner-research/scanner
- Kitware Image and Video Exploitation and Retrieval
 - https://github.com/Kitware/kwiver
- VISE project by Oxford VGG group
 - https://gitlab.com/vgg/vise

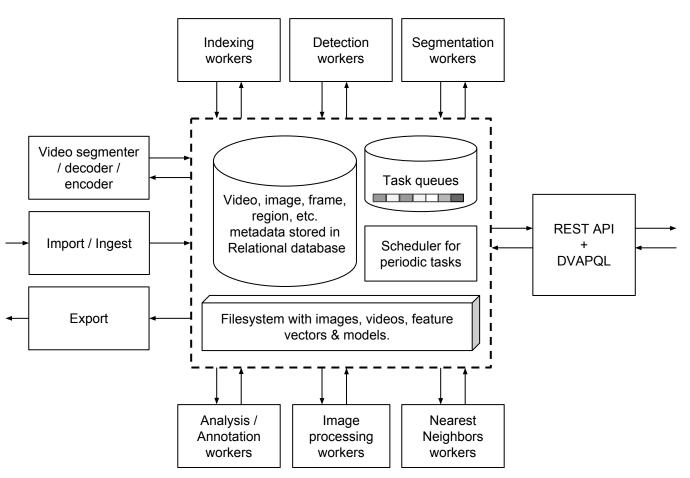
Relational data : Postgres, MYSQL, SQLite ::

Text, HTML: Lucene/Solr, Elasticsearch

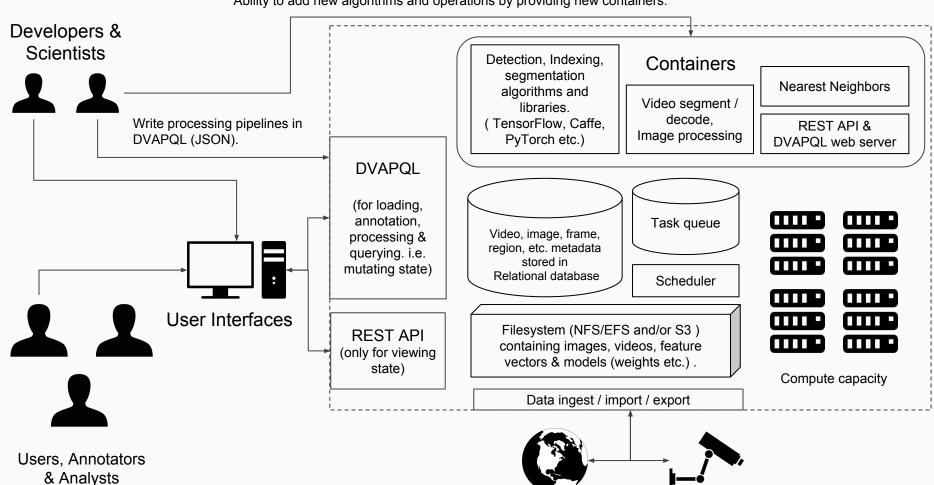
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Videos & Images: Deep Video Analytics

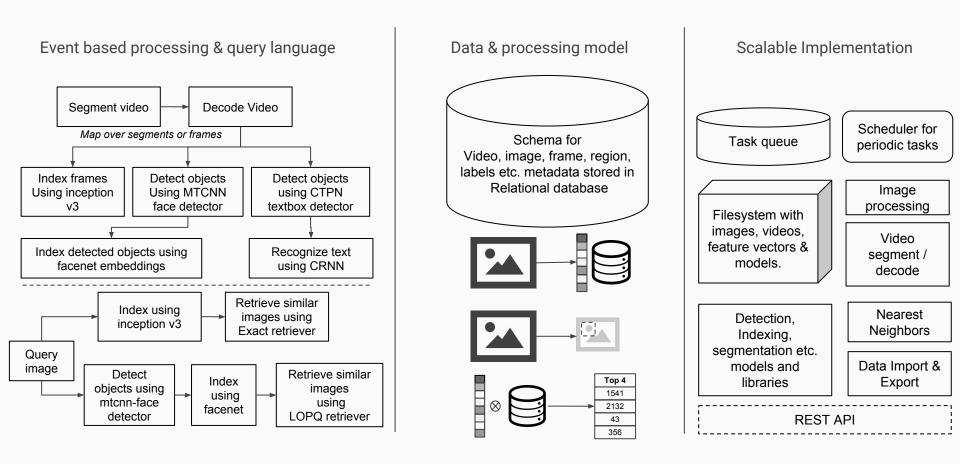
Model-centric to **Data-centric**

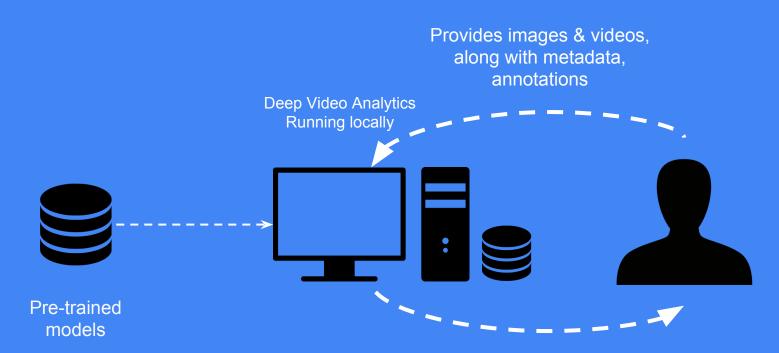


Ability to add new algorithms and operations by providing new containers.

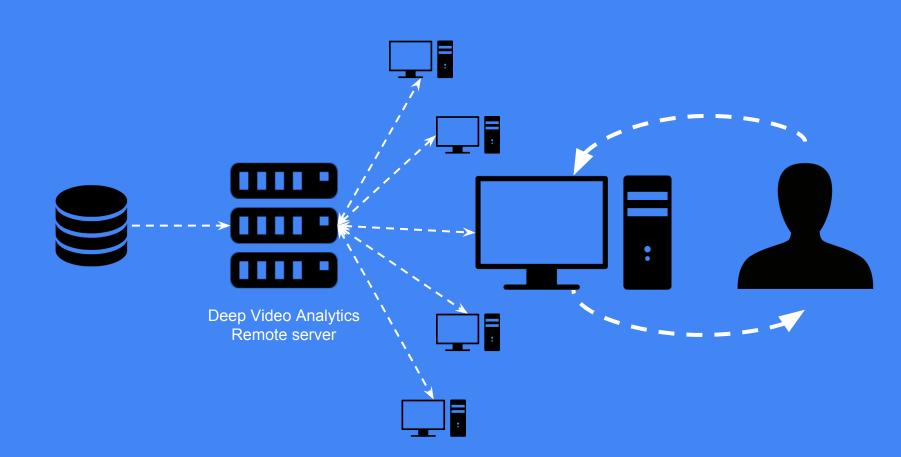


We provide all three components!





Analyzes information about detected objects, performs queries to retrieve similar images / objects.



Design goals

- Usable by non-researchers
- Visual Search as a "Primary User Interface"
- Users can provide data easily (via upload, youtube-dl, annotation UI etc.)
- Batteries-included approach with an indexing and detection pipeline
 - o Tensor Flow Inception v3, VGG-16, Single Shot Detector trained on COCO
 - Face detection / alignment / recognition
 - Deep OCR using CRNN & CTPN. Train new detectors using YOLO+Keras.
- Pre-indexed datasets from different domains can be quickly loaded
- Can be easily customized by developers & researchers.

Technical goals

- Useful without having to write code or config
- Works on machines with and without GPUs
 - Works (albeit slowly) without a GPU, tested on Linode VPS with 8Gb RAM & 4 Cores
- Handles uploads and continuous index updates
- Data can be easily imported, exported and shared
- Can be easily modified by technical users
 - o E.g. Adding more operations to processing pipeline
- Can be scaled out by adding more GPUs / Machines

Frameworks & libraries used

- Django, Postgres, Celery, RabbitMQ, Docker, NVidia-Docker
- Tensorflow (primary), PyTorch, OpenCV, FFmpeg, LOPQ & Caffe



What are the core primitives for Visual Data Analytics?

Visual Data

E

{ Images, Videos, Annotations, Features}

Data & Processing

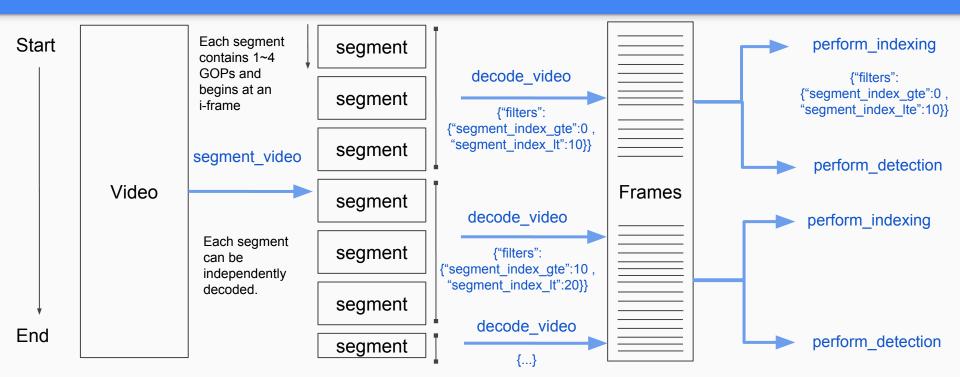
Data

- Video / Segment
- Dataset
- Frame / Image
- Regions over an image
- Tubes over sequence of images
- Feature vectors
- Audio

Processing

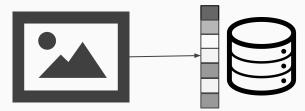
- Video Segmentation + Decode
- Image processing
 - Indexing / Detection / Segmentation / Analysis
- Vector processing
 - Retrieve nearest neighbor / Build K-NN graph
- Image transformation
 - Crop / Resize / Align / Apply segmentation mask

Video processing Parallelized segment + decode pipeline



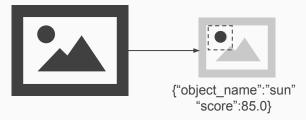
Frame/Region processing operations

Indexing



Compute feature vector such as Inception pool, embedding, RGB histogram etc.

Detection



Detect objects and return bounding boxes

Analysis



Analyze image/region and generate metadata (E.g. text description) and/or label

Segmentation



Compute pixel-wise mask using semantic segmentation, superpixels etc.

Vector processing operations



Given feature vector find K-Nearest Neighbors

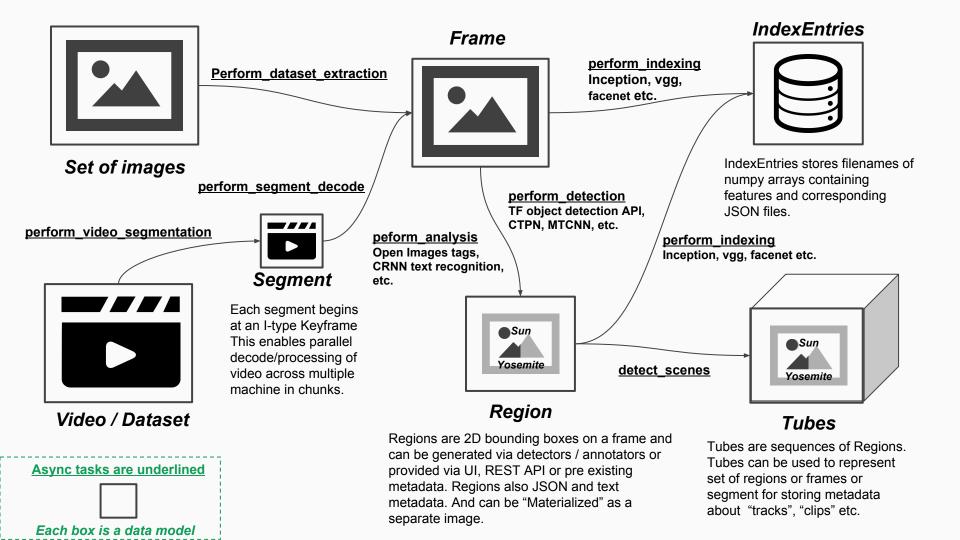
Given a set of vectors generate K-NN graph

Leverage latest open source implementations for approximate & exact Nearest Neighbors

- Yahoo Locally Optimized Product Quantization (Apache)
- Facebook Al Similarity Search (BSD + PATENTS restrictions)

Data & Processing Key insights

- Different operations have different requirements
 - In terms of number of computations and memory
 - Segmentation > Detection > Indexing / Analysis
- Also different I/O access patterns
 - Detection & Analysis does not requires writing to file system only DB and read
 - Indexing requires writing to filesystem to store computed vectors
 - Segmentation requires writing to filesystem to store computed masks as .png files
- By separating operations we can reason about hardware requirements



DVAPQL

Deep Video Analytics Processing & Query Language

- Specified in JSON
- Launch multiple hierarchical tasks
- Three types of processes
 - Query
 - Retrieve similar images, etc.
 - Process
 - Import video, index images, detect, etc.
 - Schedule
 - Monitor video stream, etc.
- REST API for viewing state & submitting DVAPQL

```
Example
{ "process_type" : "V", "tasks": [
{"operation": "perform_video_segmentation", ... ]}
{ "process_type": "Q", "b64_image_data":".....",
"tasks": [ {"operation":"perform_indexing", ...
{ "process_type" : "S", "tasks": [
{"operation":"ingest_video", ... ]}
```

An event / task based hierarchical processing model

```
{"operation": "perform_detection", "arguments": { "filters": "__parent__", "next_tasks": [] }}
             {"operation": "perform_transformation", "arguments": { "op":"crop", "filters":
                           {"event_id":"__parent_event__"}, "next_tasks": [] }}
{"operation": "perform_indexing", "arguments": {
                                                        {"operation": "perform_indexing", "arguments":
"filters": {"event_id": "__grant_parent_event__",
                                                        { "filters": {"event_id" :
"w_gte" : 50, "h_gte" : 50 }, "indexer": "vgg" }}
                                                         "__grant_parent_event__", "w_gte": 50, "h_gte"
                                                        : 50 }, "indexer": "inception" }}
```

All above tasks run on a specific video / dataset which is not shown for brevity.

Queues for optimal task processing

- Different tasks have different requirements
 - Retrieval / Nearest neighbors: High Memory for storing Index / Approximate index
 - Indexing : GPU for computing embeddings
 - Detection / Segmentation : GPU with higher memory
 - Video decode: GPU optional
 - Crop / Transform / Extract : CPU
- Primitives for Queue management
 - launching queues
 - Monitoring GPU Memory utilization / allocation

Routing tasks Two methods according to memory use

Routing by task name

- Used for routing task without persistent state / memory used between tasks.
- E.g. perform_dataset_extraction, perform_video_decode, perform_clustering etc.
- There is no state/memory that persists between tasks.
- Queue name is task name.
 E.g. q_extract, q_clusterer, q_trainer

Routing by model & task name

- Used for routing task with persistent state / memory used between tasks.
- E.g. perform_retrieval, perform_indexing, perform_detection
- Above tasks require keeping model, index in memory. Crucial to avoid model loading overhead and memory use under control.
- Queue named scoped by model id / pk.
 E.g. q_indexer_1, q_retriever_1, q_detector_3

Global model & retriever queues

Global retriever queue

- Optional + can be sharded by retriever_pk
- Slow
- workers processes all retrieval tasks.
- Used when there are no workers processing retriever specific queue.
- Used for determining worker to launch next.

Global model queue

- Optional + can be sharded by model_pk
- Very slow since each task typically results in model being loaded (possibly relaxed in future)
- Processes all models
- Used when there are no workers processing retriever specific queue.
- Used for determining worker to launch next.

Launching workers at container launch vs. dynamically

Via **environment variables** at container launch

- Launch by queue_name
 E.g. LAUNCH_Q_qextract=1
- Launch by model name and task type (indexer/retriever/detector, etc.) E.g. LAUNCH_BY_NAME_indexer_inception, LAUNCH_BY_NAME_retriever_inception, LAUNCH_BY_NAME_detector_coco
- Model name gets replaced by the primary_key in the database at launch.

Dynamically via **perform_host_management**

- Launch dynamically by sending message to any host on q_manager
- Launch task "perform_host_management"
 With arguments specifying host_name and queue_name to consume.
- Used when new detector, indexer, analyzer, etc. models are created. Also to dynamically shutdown workers to free GPU memory.

Code organization dvaui, dvaapp & dvalib

dvaui: a django app

Search, Annotation & Admin UI

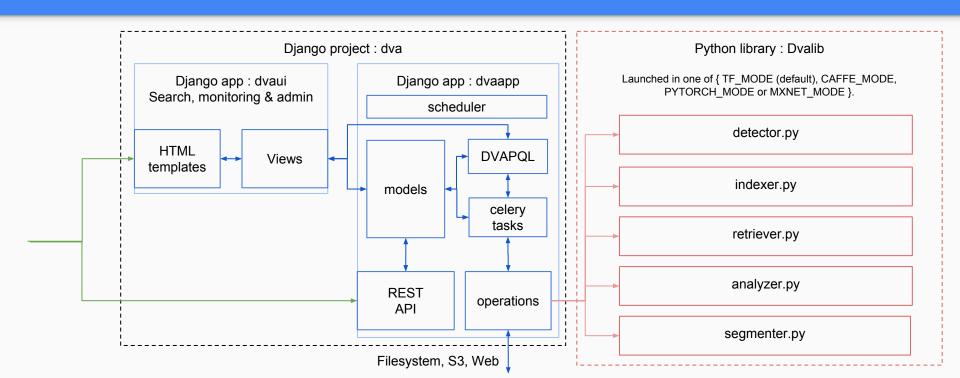
dvaapp: a django app

- Data model / REST API
 - Video, Frame, Region, Query Event, Process etc.
- DVAPQL processing using Celery
 - o Perform tasks, manage queues
 - Monitor resource use
- Uses dvalib to carry out tasks

dvalib: library with implemented model

- Goal: ensure uniform interface
- Database & Message queue agnostic
- Defines interface & implementations for
 - Detection / Indexing / Segmentation / Analysis
 - Retrieval & training
- Implements models that use TensorFlow (Default), PyTorch, MXNet and Caffe
- Can be tested independently

Code organization: dvaui, dvaapp & dvalib All in a single container



Emulating datacenter on a machine

Docker enables same codebase across all configurations (a laptop, multi-GPU machine, datacenter)

Docker-compose used for simulating distributed environment for testing and single machine deployment

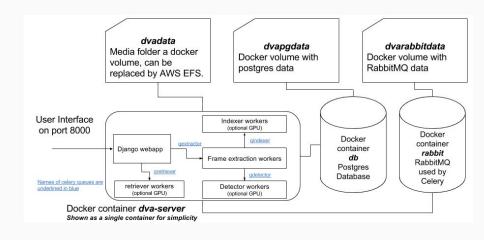
Docker container image and :tags

- dva-auto:latest (CPU Tensorflow + PyTorch + MXNet)
- dva-auto:gpu (GPU Tensorflow + PyTorch + MXNet)

All images are automatically built on docker hub

Docker volumes

- dvadata / (optional shared file-system/volume)
- 2. dvapgdata (when DB is containerized)
- 3. dvarabbitdata (when rabbitmq is containerized)



Three deployment configurations

Single machine without GPU

- Docker
- Useful for development
- Personal use
- Can optionally use S3 or GCS in addition to shared docker volume

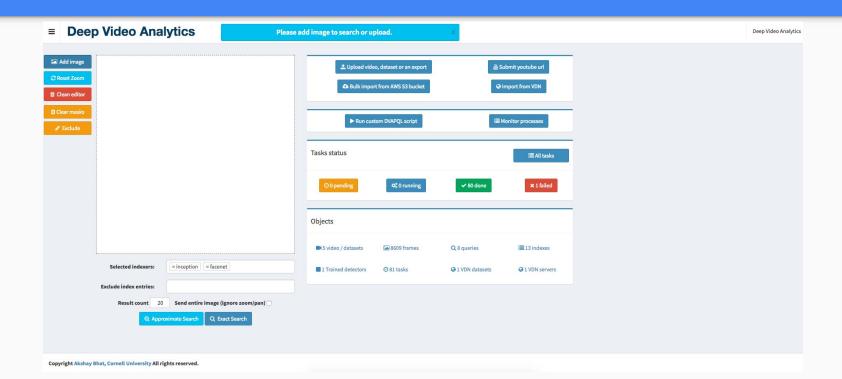
Single machine with GPUs

- nvidia-docker2
- Useful for training models
- Small research groups
- Can optionally use S3 or GCS in addition to shared docker volume

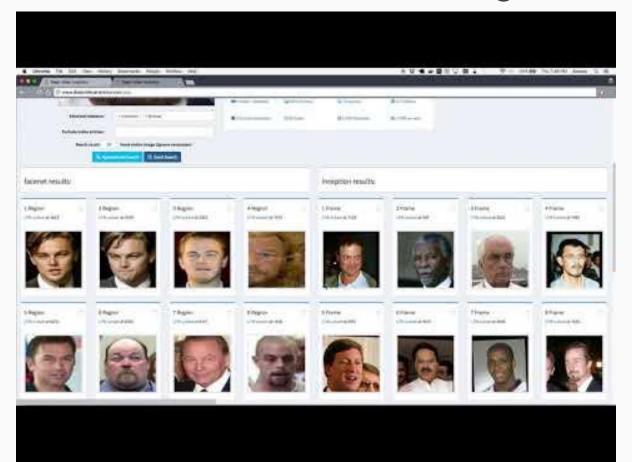
Kubernetes with GCS or S3

- Deploy on any Kubernetes cluster
- Currently supports GCP. AWS EKE coming soon!
- Leverages preemptible & spot
- Plan to leverage AWS lambda & Google Cloud functions in future.
- For production applications
- For large scale projects

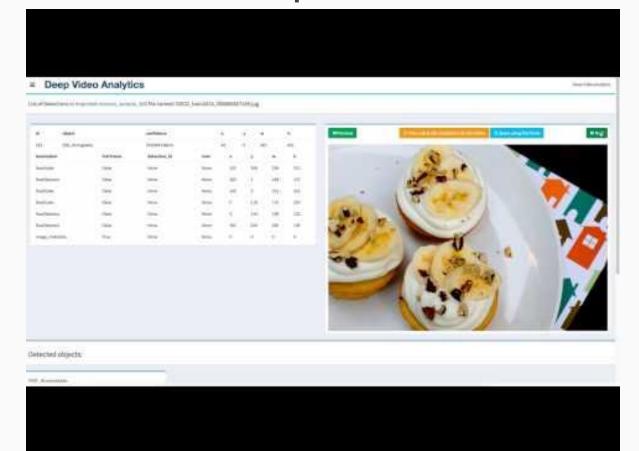
User Interface



Latest version beta, 17th August 2017



7th April 2017



15th March 2017



People: Facebook

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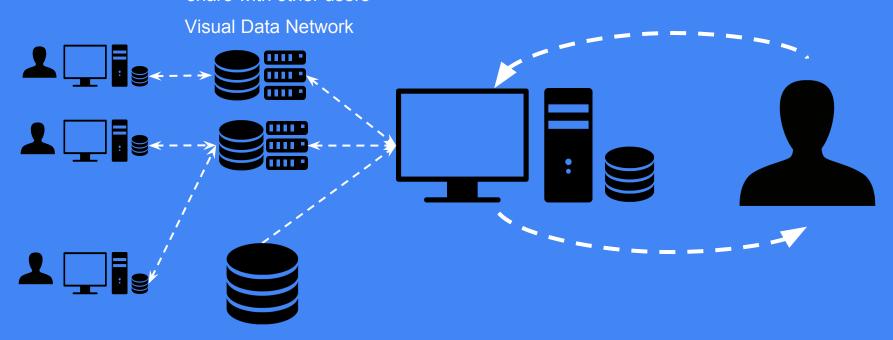
Code: Git / GitHub, GitLab

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Visual Data: Visual Data Network

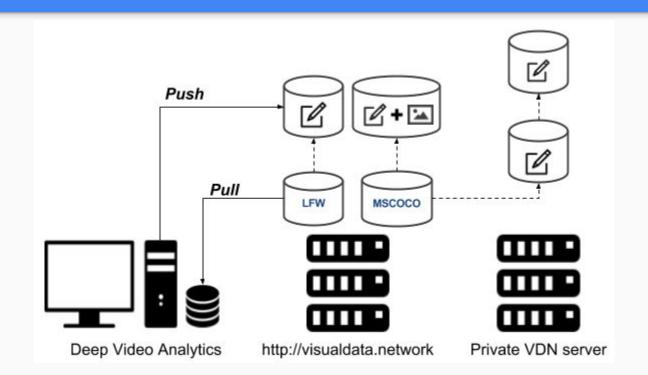
Sharing data using Visual Data Network

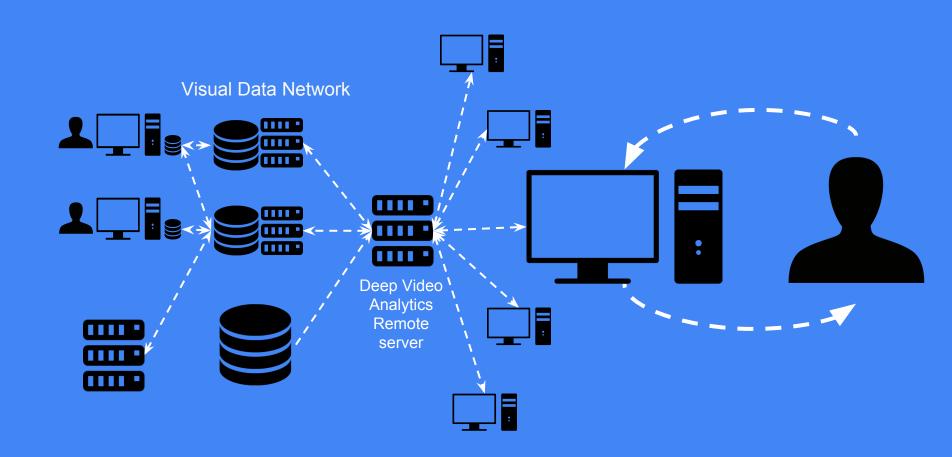
Import & export new datasets / annotations share with other users



Visual Data Network enables seamless sharing

Push, Pull video / dataset, Annotations, just like you would with GitHub





Open questions: A work in progress

- How to effectively manage GPU memory & utilization?
- How to balance fast/static vs slow/dynamic indexes?
- How to learn continuously from annotations/feedback?
- How to minimize storage requirements via compaction?
- How to enable Real time processing?

Thanks!

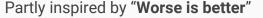
Contact me

akshayubhat@gmail.com

www.akshaybhat.com



Software Development approach or "How I developed Deep Video Analytics"



- Start at "final scale" at which it's intended to be used
 - Easy to optimize each component, difficult to change architecture.
- Write "high level" tests rather than "unit tests"
 - E.g load video -> extract frames -> build index -> query
- Observability is crucial, develop UI for visual inspection
- Create start-from-zero config and use it for manual verification
- Keep everything in a single repo (including User Interface)
- DO NOT write a new database or roll your own message queue
 - Both Postgres and RabbitMQ are natively / cheaply supported in Travis / Heroku
 - o It's a nightmare to debug concurrency primitives also difficult to convince others to trust / maintain your code.
- Optimize for one goal (Features, Correctness, Consistency, Simplicity) at a time (over days / week)
 - E.g. Trade consistency/quality when adding new features. Once feature is done/verified/popular improve code quality.
 Once code quality has improved, transition to a more consistent / simple model. Use consistency to add new features.

