Deep Video Analytics

A data-centric approach to Computer Vision

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Developments over last 5 years
High quality libraries & pre-trained models

- Theano
- Torch
- ROS
- Caffe
- Tensor Flow
- MXNET
- PyTorch
- Deeplearnjs

- Recognition
  - Inception / VGG / Resnet
- Detection
  - R-CNN / YOLO / SSD
- Face detection / recognition
  - MTCNN / Facenet
- Semantic Segmentation
  - Multipathnet / FCN / CRFasRNN

Developments over last 5 years
A deluge of datasets!

- Open Images
- Yahoo Flickr Creative Com. 100M
- MSCOCO
- ViCom
- Visual Genome
- YouTube-BoundingBoxes / 8M
- AMOS
- imSitu, Charades by AllenAI
- KITTI /Toronto City
- Udacity car dataset
- Caltech, INRIA, ETH Pedestrians
- Stanford Drone Dataset
- Uber text
- THUMOS

Number of datasets ≅ Number of research groups

With each dataset having its own JSON or XML format, incompatible with all others.

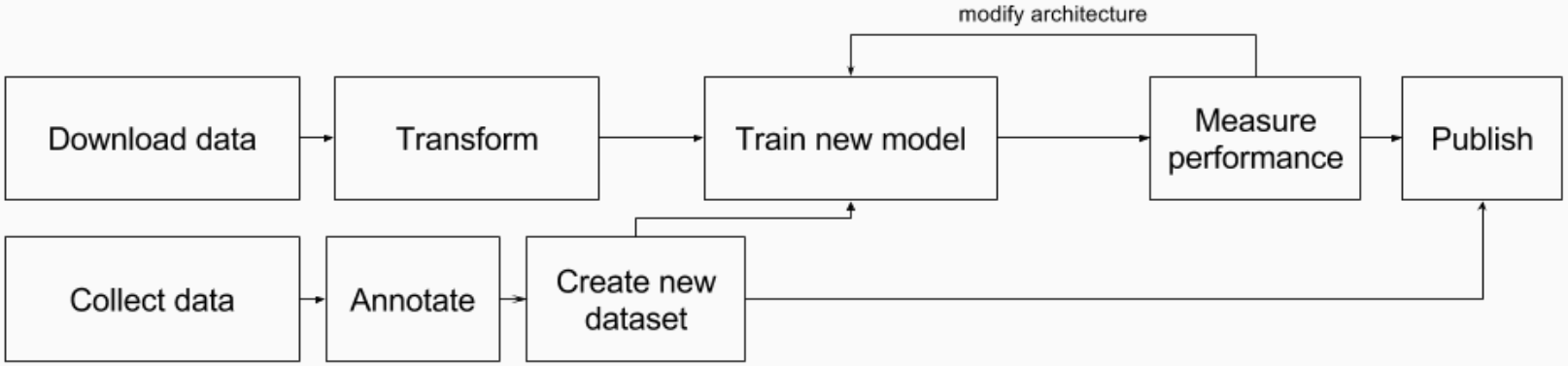
What else changed over last 5 years?

- Container ecosystem (Docker, Kubernetes) enables deployment of complex applications.
- Ability to scale quickly by adding compute capability (including GPUs) billed at minutes / seconds resolution. E.g. AWS Spot / GCP preemptible , AWS Lambda / GCP Cloud functions.
- Flexible cloud storage options. E.g. S3, EBS & EFS.

What is hidden in plain sight?

Model-centric approach

Libraries & frameworks are designed with **goal of training and evaluation of models for individual tasks**.



Unsuitable for building systems that learn in interactive manner, or leverage data from multiple sources or combine multiple tasks.

We need a data-centric approach that allows us to combine

- Models for multiple tasks
- Data from multiple sources
- User Interaction / interface

A Relational Model of Data for Large Shared Data Banks. By Edgar F. Codd

Can we develop an equivalent of relational model for visual data?

Relational data : Postgres, MYSQL, SQLite

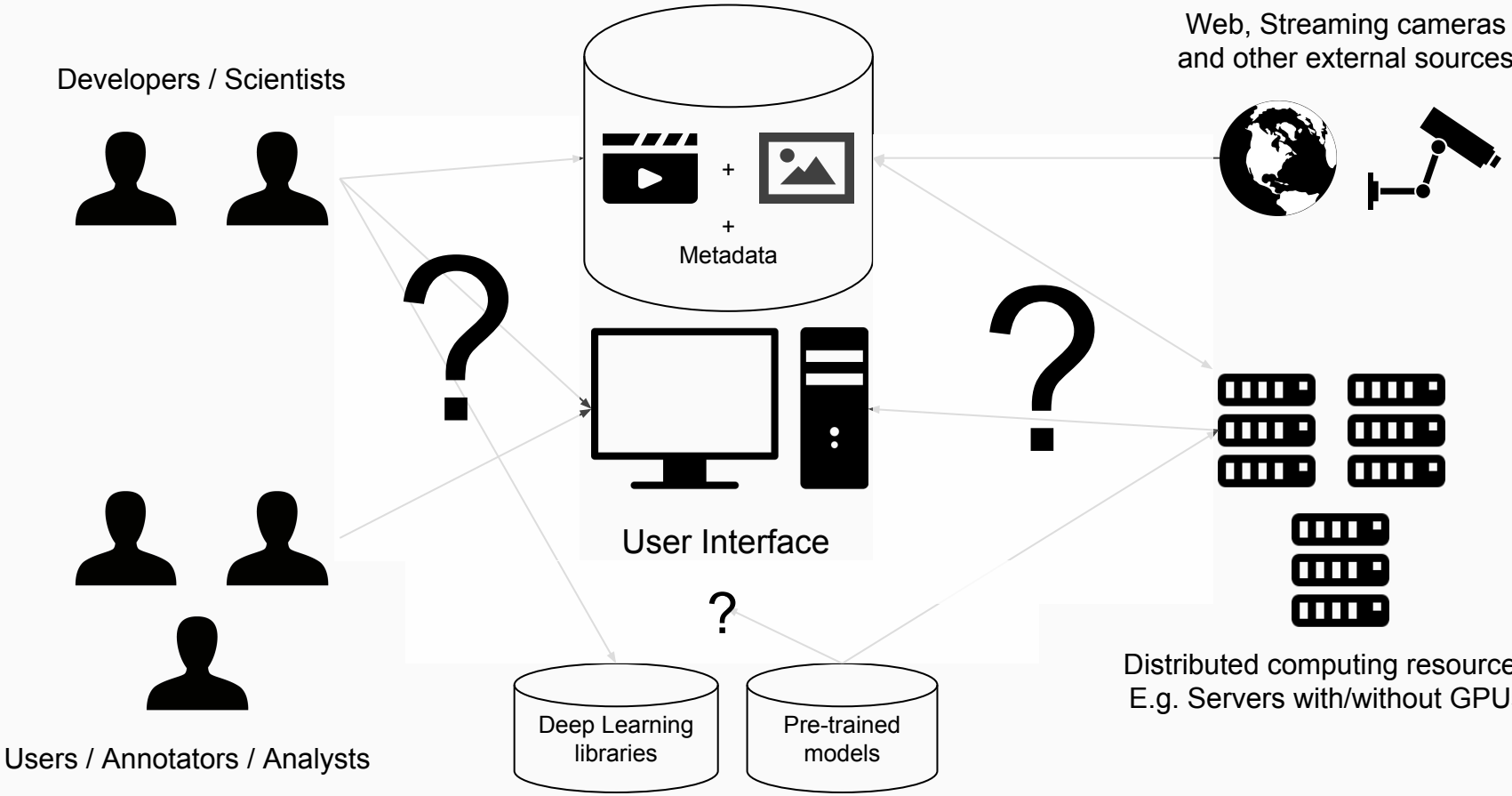
::

Text, HTML : Lucene/Solr, Elasticsearch

::

Videos & Images : _____

How do we structure Visual Data processing?



Previous attempts: LIRE project

- LIRE: Lucene Image Retrieval
  - http://www.lire-project.net/
- Developed pre-Deep Learning
- Functionality limited to computing & storing feature vectors such as Color Layout, Edge Histogram, etc.

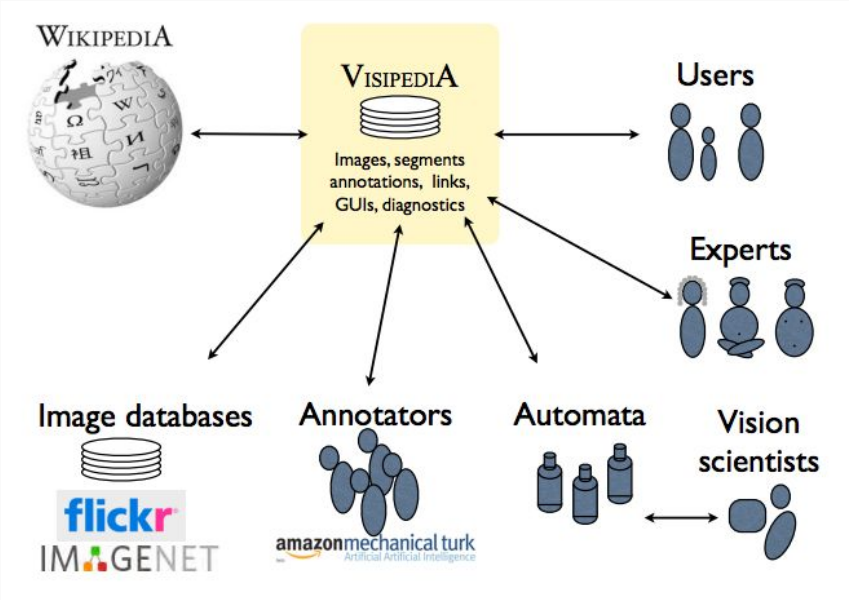
Previous attempts: CloudCV

- Large Scale Distributed Computer Vision as a Cloud Service
- Support for OpenCV, Graphlab, Cafe
- Image Classification, VQA, stitching, etc
- Does not retains state. E.g. you cannot store images.

Previous attempts: NVidia DIGITS

- ”DIGITS (the Deep Learning GPU Training System) is a webapp for training deep learning models. ”
- Load/create datasets, train models, deploy models.
- Aimed at researchers
- Written in Python/Flask with Torch & Caffe supported

Previous attempts: Visipedia



Taken from Vision of a Visipedia, Perona et. al.

Previous attempts: Visipedia

- Collaborative creation of visual data
- Pre-defined set of concepts E.g. Birds, Trees
- Different type of participants
  - Experts, Annotators, Citizen Scientists, Users, Computer scientists
- Retains state

Previous attempts: VMX.ai

- Underfunded Kickstarter project Circa Jan 2014
- by Tomasz Malisiewicz
- Pre Tensor Flow, Pre Deep Learning
- Allow developers to create real time detectors
- Support for training model

Quick summary

- LIRE: limited functionality (Lucene add-on)
- CloudCV: Provides a service, cannot retain “state”
- NVidia Digits: Intended for training not inference
- Visipedia: Intended to be a monolithic deployment

Few ongoing attempts

- Scanner by Alex Poms (CMU) & Will Crichton (Stanford)
  - https://github.com/scanner-research/scanner
- Kitware Image and Video Exploitation and Retrieval
  - https://github.com/Kitware/kwiver
- VISE project by Oxford VGG group
  - https://gitlab.com/vgg/vise

Relational data : Postgres, MYSQL, SQLite

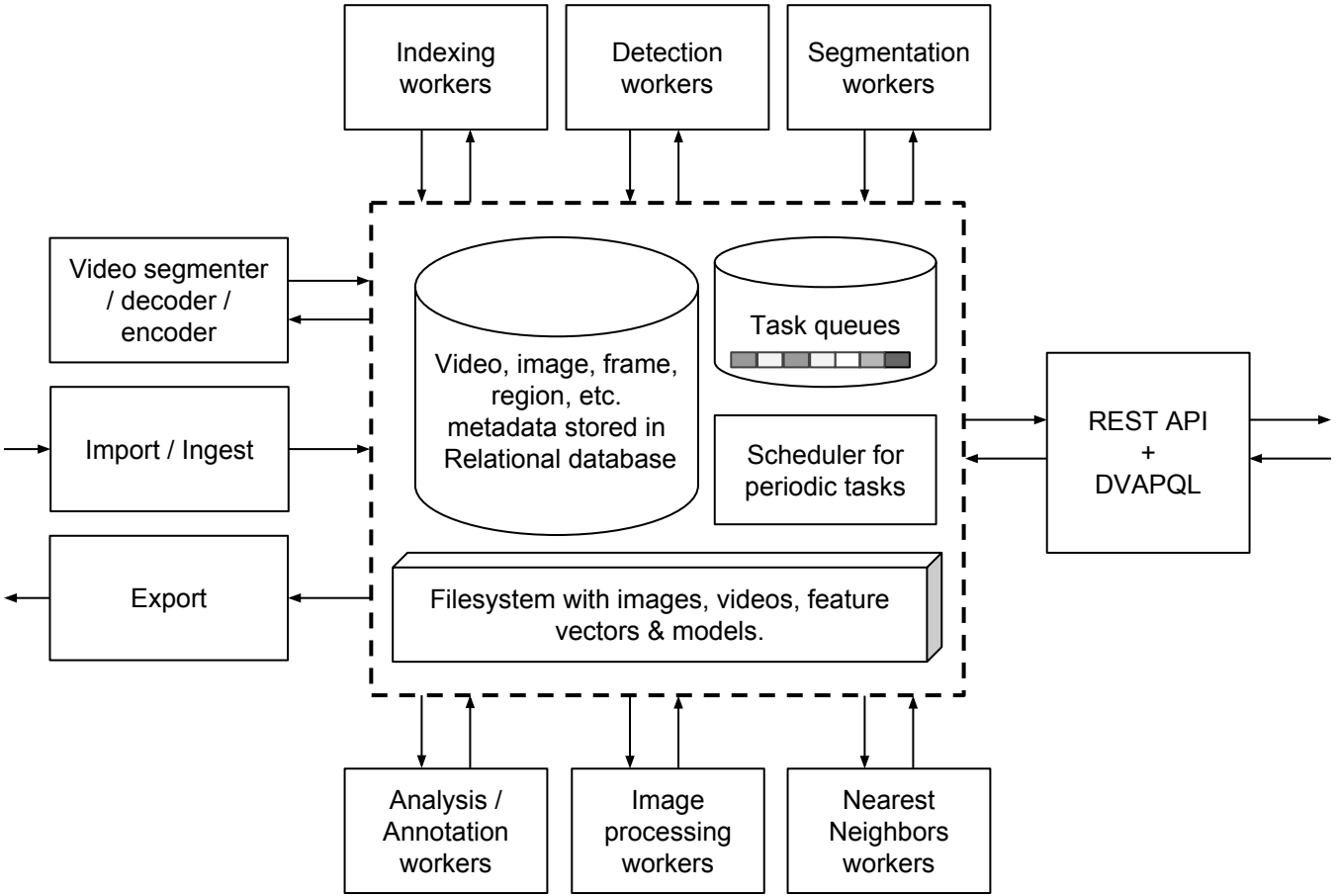
::

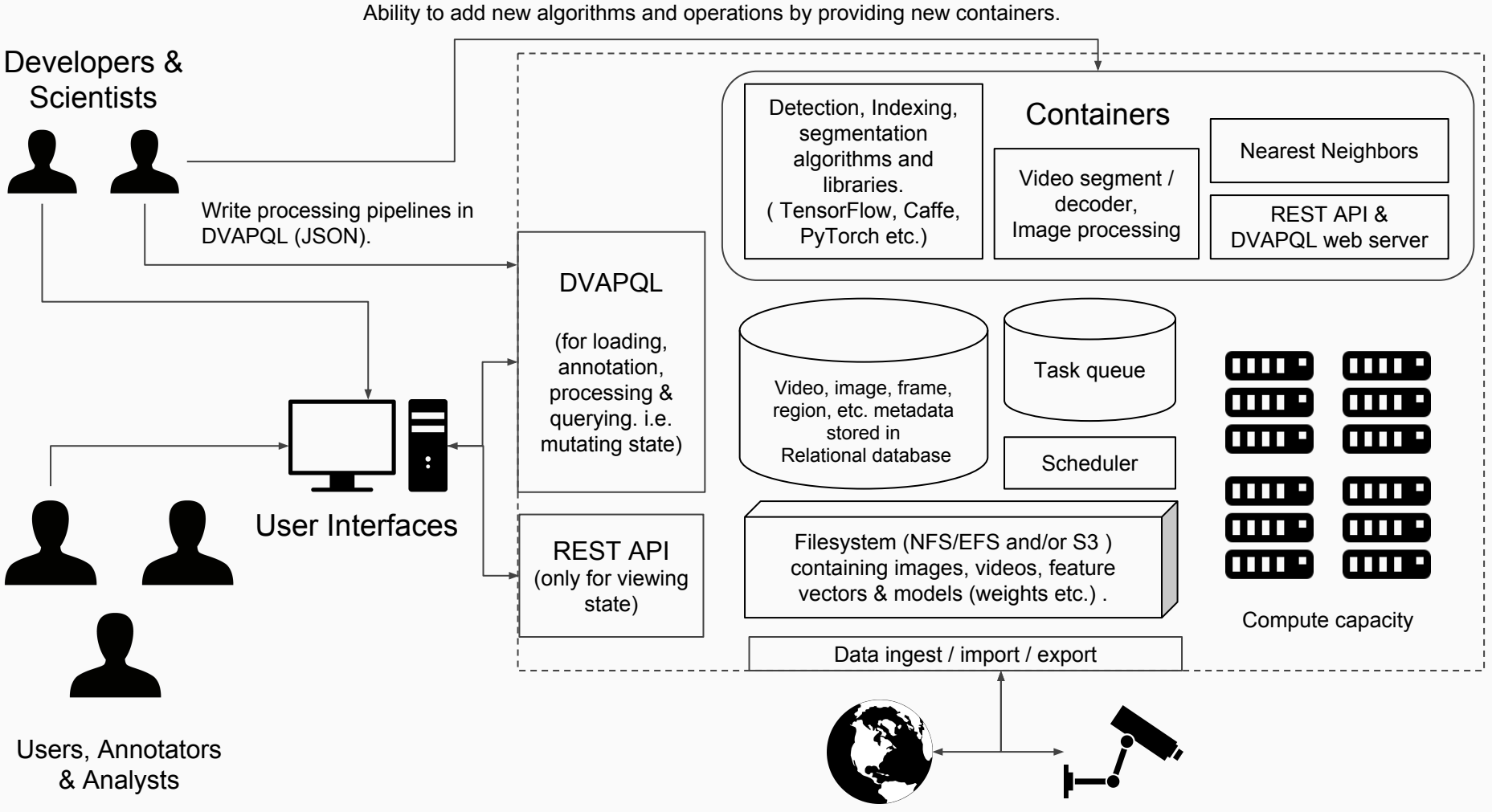
Text, HTML : Lucene/Solr, Elasticsearch

::

Videos & Images : ***Deep Video Analytics***

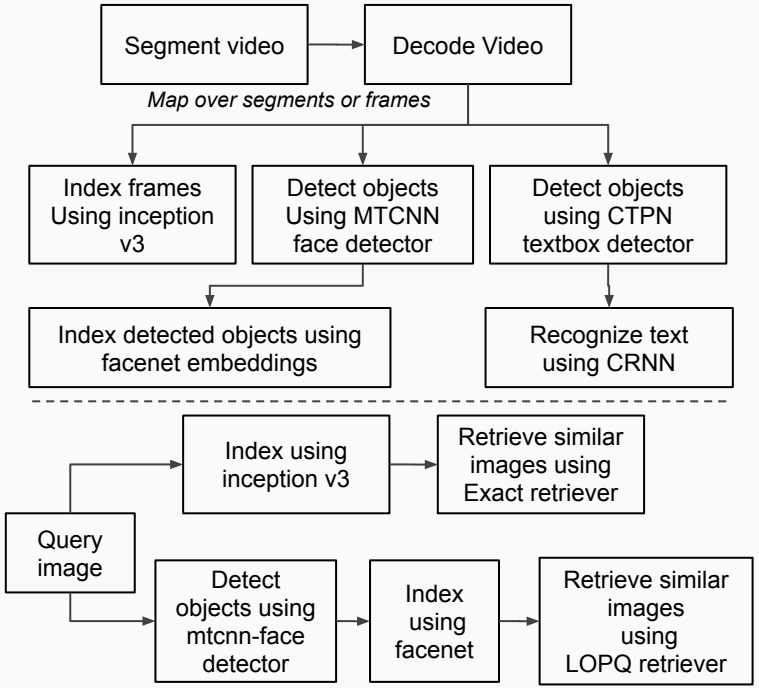
Model-centric to **Data-centric**



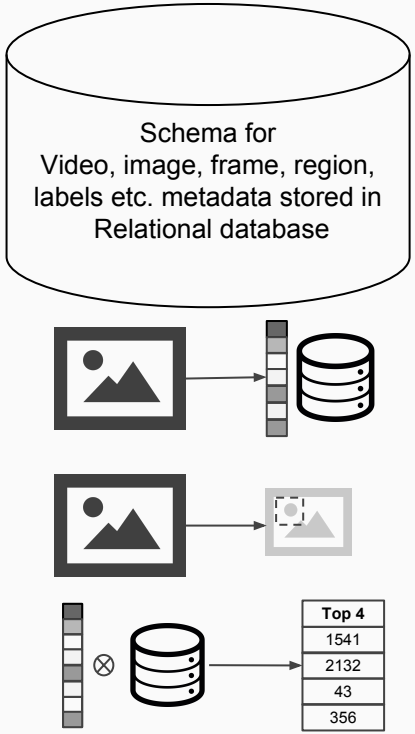

Ability to add new algorithms and operations by providing new containers.
Developers & Scientists
Write processing pipelines in DVAPQL (JSON).
Containers
Detection, Indexing, segmentation algorithms and libraries. (TensorFlow, Caffe, PyTorch etc.)
Video segment / decoder, Image processing
Nearest Neighbors
REST API & DVAPQL web server
DVAPQL
(for loading, annotation, processing & querying. i.e. mutating state)
Video, image, frame, region, etc. metadata stored in Relational database
Task queue
Scheduler
User Interfaces
REST API
(only for viewing state)
Filesystem (NFS/EFS and/or S3) containing images, videos, feature vectors & models (weights etc.) .
Compute capacity
Data ingest / import / export
Users, Annotators & Analysts

We provide all three components !

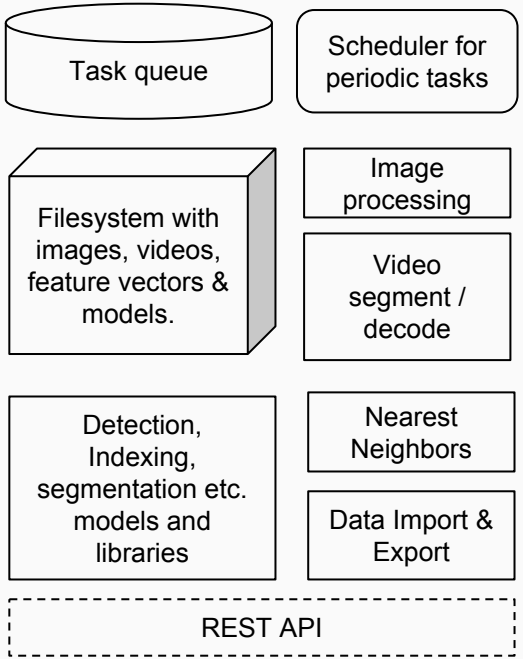
Event based processing & query language

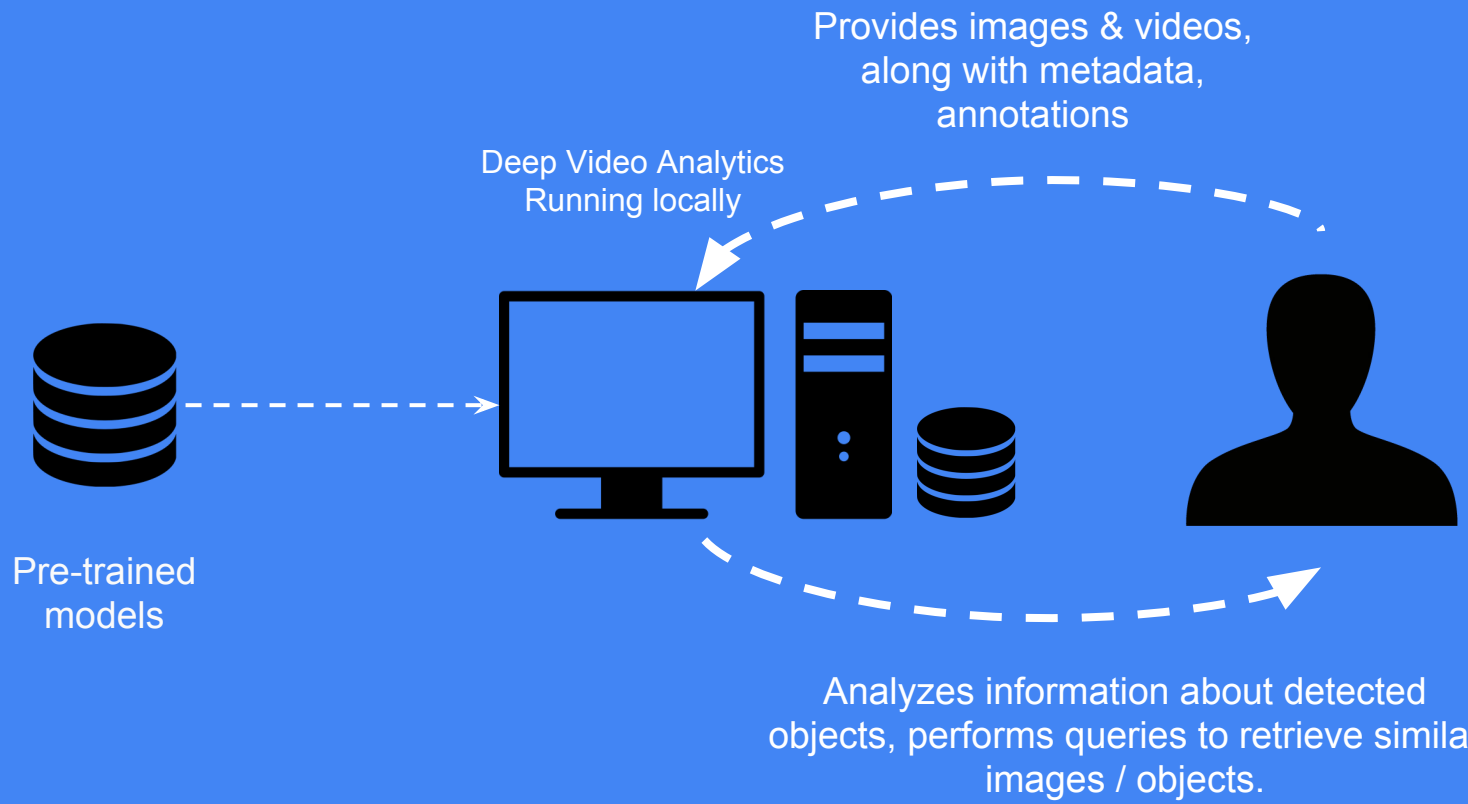


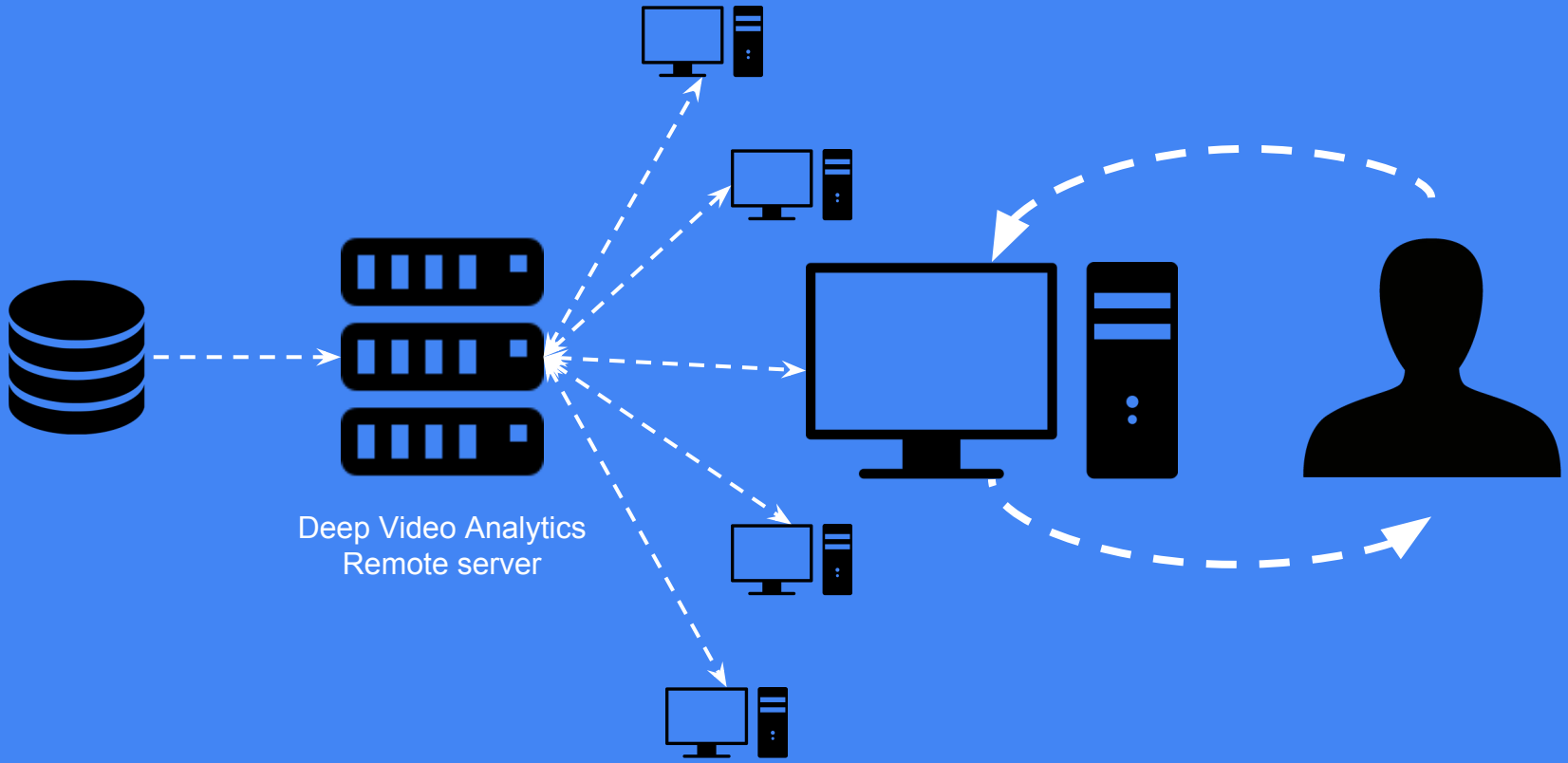
Data & processing model



Scalable Implementation




Provides images & videos,
along with metadata,
annotations
Deep Video Analytics
Running locally
Pre-trained
models
Analyzes information about detected
objects, performs queries to retrieve similar
images / objects.


Deep Video Analytics
Remote server

Design goals

- Usable by non-researchers
- Visual Search as a “Primary User Interface”
- Users can provide data easily (via upload, youtube-dl, annotation UI etc.)
- Batteries-included approach with an indexing and detection pipeline
  - Tensor Flow Inception v3, VGG-16, Single Shot Detector trained on COCO
  - Face detection / alignment / recognition
  - Deep OCR using CRNN & CTPN. Train new detectors using YOLO+Keras.
- Pre-indexed datasets from different domains can be quickly loaded
- Can be easily customized by developers & researchers.

Technical goals

- Useful without having to write code or config
- Works on machines with and without GPUs
  - Works (albeit slowly) without a GPU, tested on Linode VPS with 8Gb RAM & 4 Cores
- Handles uploads and continuous index updates
- Data can be easily imported, exported and shared
- Can be easily modified by technical users
  - E.g. Adding more operations to processing pipeline
- Can be scaled out by adding more GPUs / Machines

Frameworks & libraries used

- Django, Postgres, Celery, RabbitMQ, Docker, NVidia-Docker
- Tensorflow (primary), PyTorch, OpenCV, FFmpeg, LOPQ & Caffe

What are the core primitives for Visual Data Analytics?

Visual Data

=

{ Images, Videos, Annotations, Features}

Data & Processing

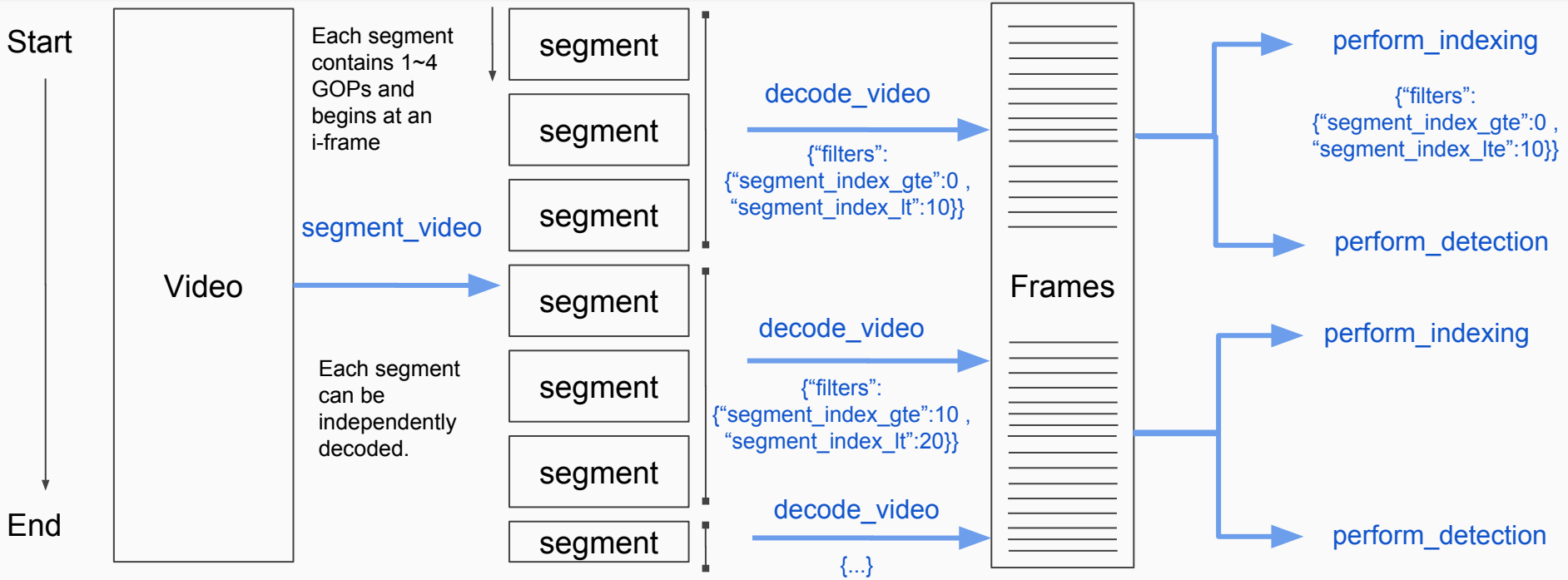
Data

- Video / Segment
- Dataset
- Frame / Image
- Regions over an image
- Tubes over sequence of images
- Feature vectors
- Audio

Processing

- Video Segmentation + Decode
- Image processing
  - Indexing / Detection / Segmentation / Analysis
- Vector processing
  - Retrieve nearest neighbor / Build K-NN graph
- Image transformation
  - Crop / Resize / Align / Apply segmentation mask

Video processing
Parallelized segment + decode pipeline



Map-Reduce processing on videos & datasets

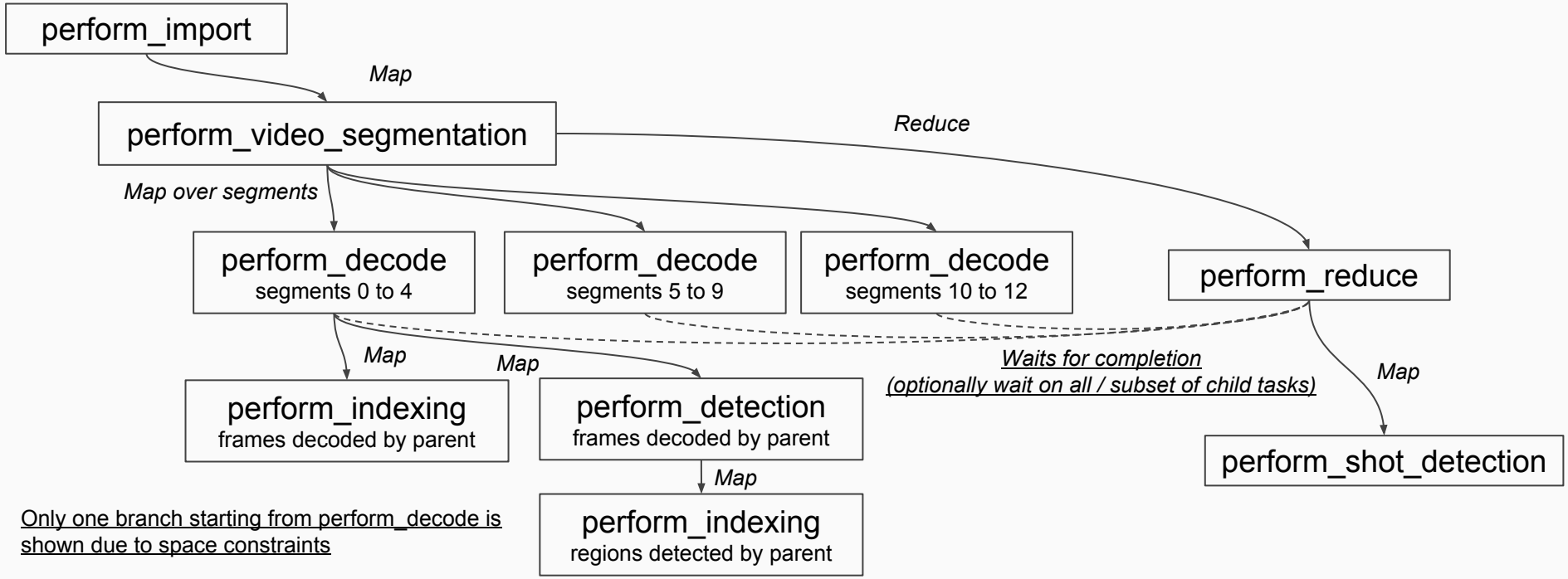
Map tasks over

- Entire videos / dataset
- Set of segments
- Set of frames ordered by frame_index

Reduce (“wait”) on

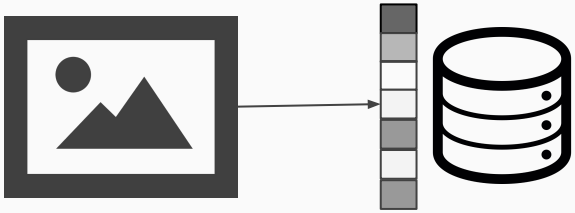
- All tasks launched by map
- Only immediate children task
- Groups of tasks + their parent tasks
- Consecutive segments / frames

Map-Reduce over videos/datasets



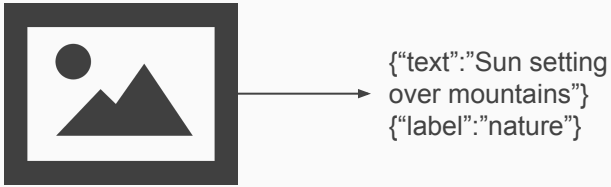
Frame/Region processing operations

Indexing



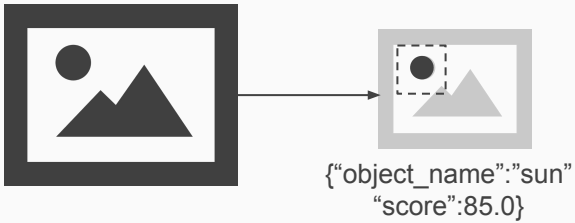
Compute feature vector such as Inception pool, embedding, RGB histogram etc.

Analysis



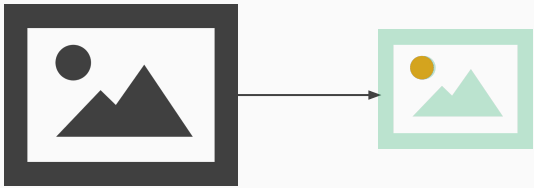
Analyze image/region and generate metadata (E.g. text description) and/or label

Detection



Detect objects and return bounding boxes

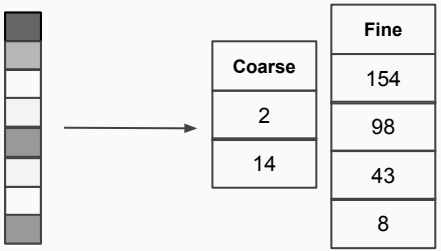
Segmentation



Compute pixel-wise mask using semantic segmentation, superpixels etc.

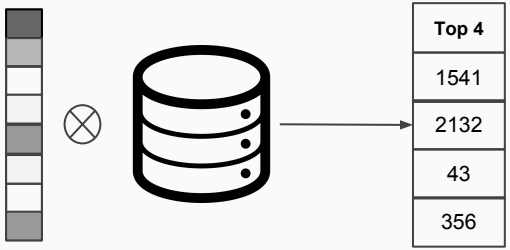
Vector processing operations

Approximation



Given feature vector compute approximate index using an LOPQ model or quantized PCA

Retrieval



Given feature vector, approximate sketch find K-Nearest Neighbors

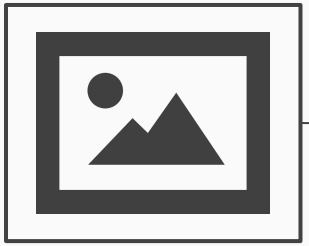
Matching

Node	1st NN	2nd NN	3rd NN
1	213	114	7761
2	762	132	42
3	2133	673	1233
4	2344	234	9364

Given a set of vectors generate K-NN graph

Data & Processing
Key insights

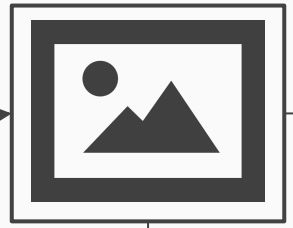
- Different operations have different requirements
  - In terms of number of computations and memory
  - Segmentation > Detection > Indexing / Analysis
- Also different I/O access patterns
  - Detection & Analysis does not requires writing to file system only DB and read
  - Indexing requires writing to filesystem to store computed vectors
  - Segmentation requires writing to filesystem to store computed masks as .png files
- By separating operations we can reason about hardware requirements



Set of images

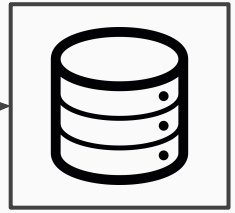
Perform_dataset_extraction

Frame



perform_indexing
Inception, vgg,
facenet etc.

IndexEntries



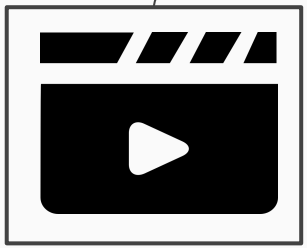
IndexEntries stores filenames of numpy arrays containing features and corresponding JSON files.

perform_segment_decode

perform_video_segmentation

Segment

Each segment begins at an I-type Keyframe This enables parallel decode/processing of video across multiple machine in chunks.

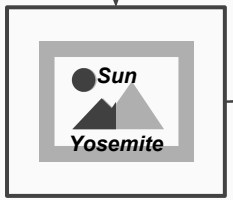


Video / Dataset

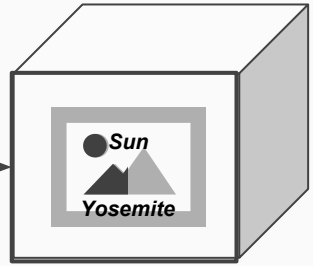
perform_detection
TF object detection API,
CTPN, MTCNN, etc.

peform_analysis
Open Images tags,
CRNN text recognition,
etc.

perform_indexing
Inception, vgg, facenet etc.



detect_scenes



Region

Regions are 2D bounding boxes on a frame and can be generated via detectors / annotators or provided via UI, REST API or pre existing metadata. Regions also JSON and text metadata. And can be “Materialized” as a separate image.

Tubes

Tubes are sequences of Regions. Tubes can be used to represent set of regions or frames or segment for storing metadata about “tracks”, “clips” etc.

Async tasks are underlined

Each box is a data model

DVAPQL
Deep Video Analytics Processing & Query Language

- Specified in JSON
- Launch multiple hierarchical tasks
- Three types of processes
  - Query
    - Retrieve similar images, etc.
  - Process
    - Import video, index images, detect, etc.
  - Schedule
    - Monitor video stream, etc.
- REST API for viewing state & submitting DVAPQL

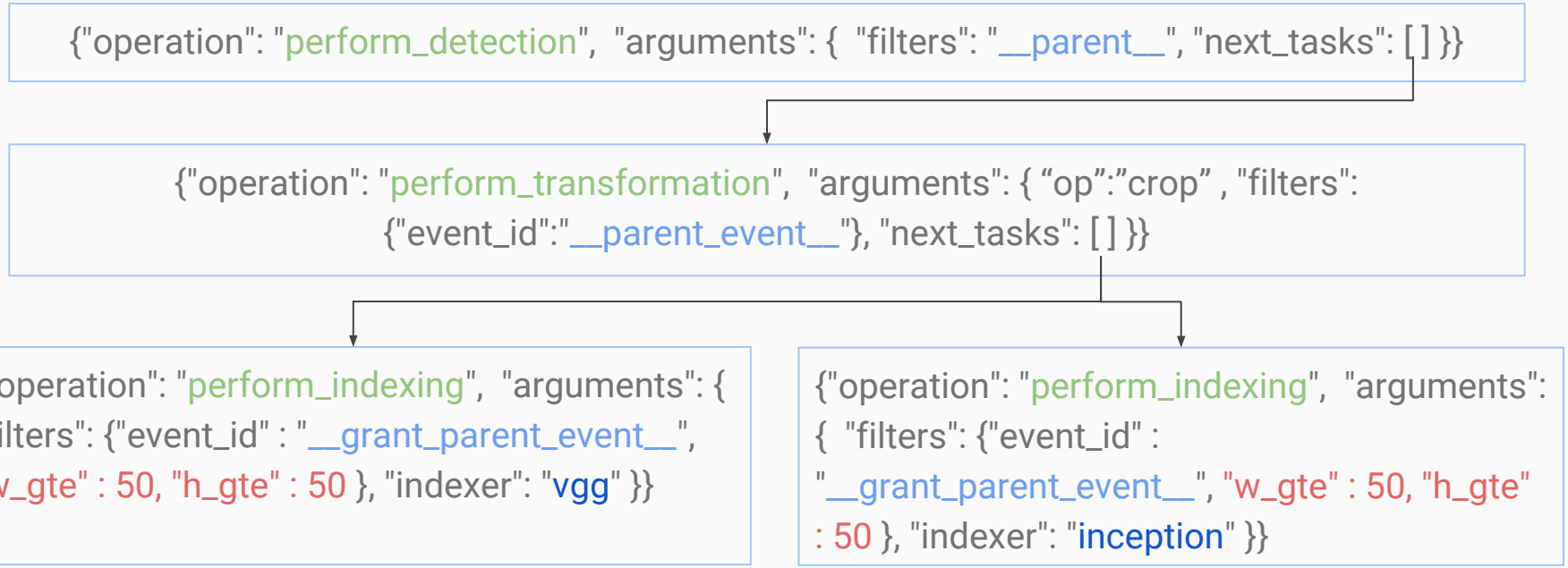
Example

```
{ “process_type” : “V”, “tasks”: [
{“operation”:”perform_video_segmentation”, ... ]}

{ “process_type” : “Q”, “b64_image_data”:”.....”,
“tasks”: [ {“operation”:”perform_indexing”, ...
]}

{ “process_type” : “S”, “tasks”: [
{“operation”:”ingest_video”, ... ]}
```

An event / task based hierarchical processing model



All above tasks run on a specific video / dataset which is not shown for brevity.

Queues for optimal task processing

- Different tasks have different requirements
  - Retrieval / Nearest neighbors: High Memory for storing Index / Approximate index
  - Indexing : GPU for computing embeddings
  - Detection / Segmentation : GPU with higher memory
  - Video decode: GPU optional
  - Crop / Transform / Extract : CPU
- Primitives for Queue management
  - launching queues
  - Monitoring GPU Memory utilization / allocation

Routing tasks
Two methods according to memory use

Routing by task name

- Used for routing task **without** persistent state / memory used between tasks.
- E.g. perform_dataset_extraction, perform_video_decode, perform_clustering etc.
- There is no state/memory that persists between tasks.
- Queue name is task name.
  E.g. q_extract, q_clusterer, q_trainer

Routing by model & task name

- Used for routing task **with** persistent state / memory used between tasks.
- E.g. perform_retrieval, perform_indexing, perform_detection
- Above tasks require keeping model, index in memory. Crucial to avoid model loading overhead and memory use under control.
- Queue named scoped by model id / pk.
  E.g. q_indexer_1, q_retriever_1, q_detector_3

Global model & retriever queues

Global retriever queue

- Used when there are no workers processing retriever specific queue.
- can be sharded by “retriever_pk % shard_count”
- Slow
- Re-routes the task if a new worker become available between initial assignment and task run.

Global model queue

- Used when there are no workers processing model specific queue.
- Can be sharded by “ model_pk % shard_count “
- Very slow due to model being loaded on each task. Possibly slightly relaxed in future using LRU
- Re-routes the task if a new worker become available between initial assignment and task run.

Launching workers at container launch vs. dynamically

Via **environment variables** at container launch

- Launch by queue_name
  E.g. LAUNCH_Q_qextract=1
- Launch by model name and task type (indexer/retriever/detector, etc.) E.g. LAUNCH_BY_NAME_indexer_inception, LAUNCH_BY_NAME_retriever_inception, LAUNCH_BY_NAME_detector_coco
- Model name gets replaced by the primary_key in the database at launch.

Dynamically via **perform_host_management**

- Launch dynamically by sending message to any host on q_manager
- Launch task “perform_host_management” With arguments specifying host_name and queue_name to consume.
- Used when new detector, indexer, analyzer, etc. models are created. Also to dynamically shutdown workers to free GPU memory.

Code organization
dvaui, dvaapp & dvalib

dvaui: a django app

- Search, Annotation & Admin UI

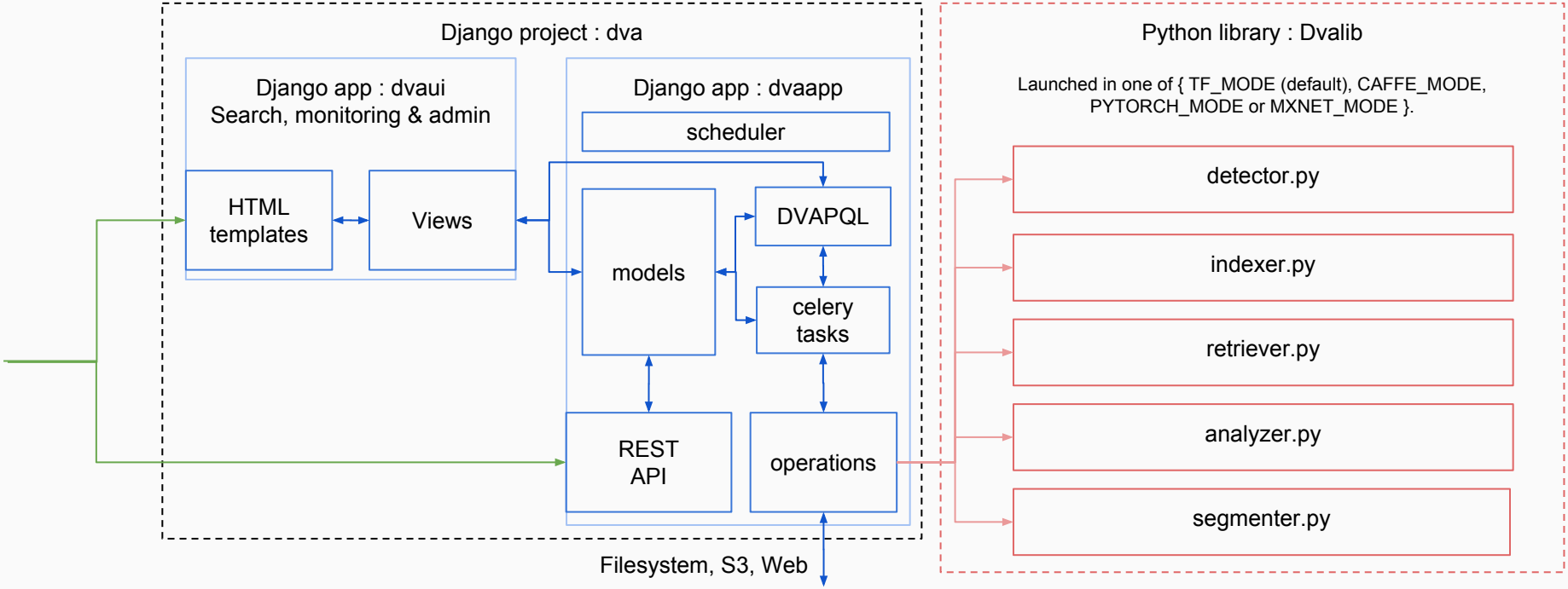
dvaapp: a django app

- Data model / REST API
  - Video, Frame, Region, Query Event, Process etc.
- DVAPQL processing using Celery
  - Perform tasks, manage queues
  - Monitor resource use
- Uses dvalib to carry out tasks

dvalib: library with implemented model

- Goal: ensure uniform interface
- Database & Message queue agnostic
- Defines interface & implementations for
  - Detection / Indexing / Segmentation / Analysis
  - Retrieval & training
- Implements models that use TensorFlow (Default), PyTorch, MXNet and Caffe
- Can be tested independently

Code organization: dvaui, dvaapp & dvalib
All in a single container



Emulating datacenter on a machine

Docker enables same codebase across all configurations {a laptop, multi-GPU machine, datacenter}
Docker-compose used for simulating distributed environment for testing and single machine deployment

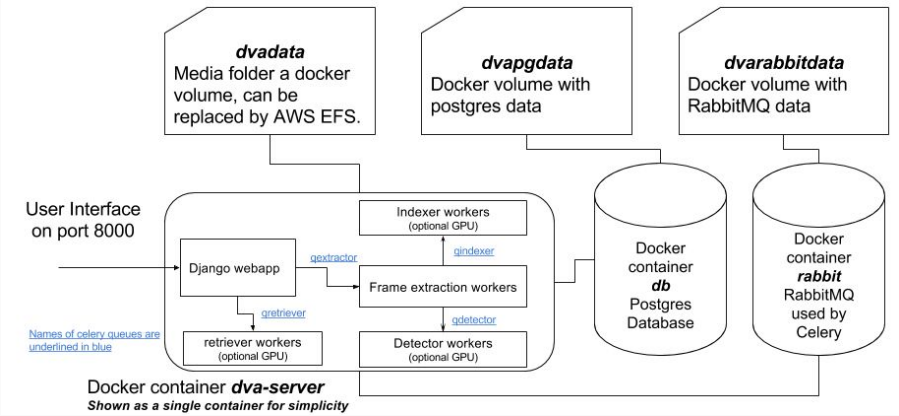
Docker container image and :tags

- dva-auto:latest (CPU Tensorflow + PyTorch + MXNet)
- dva-auto:gpu (GPU Tensorflow + PyTorch + MXNet)

All images are automatically built on docker hub

Docker volumes

1. dvadata / (optional shared file-system/volume)
2. dvapgdata (when DB is containerized)
3. dvarabbitdata (when rabbitmq is containerized)



Three deployment configurations

Single machine without GPU

- Docker
- Useful for development
- Personal use
- Can optionally use S3 or GCS in addition to shared docker volume

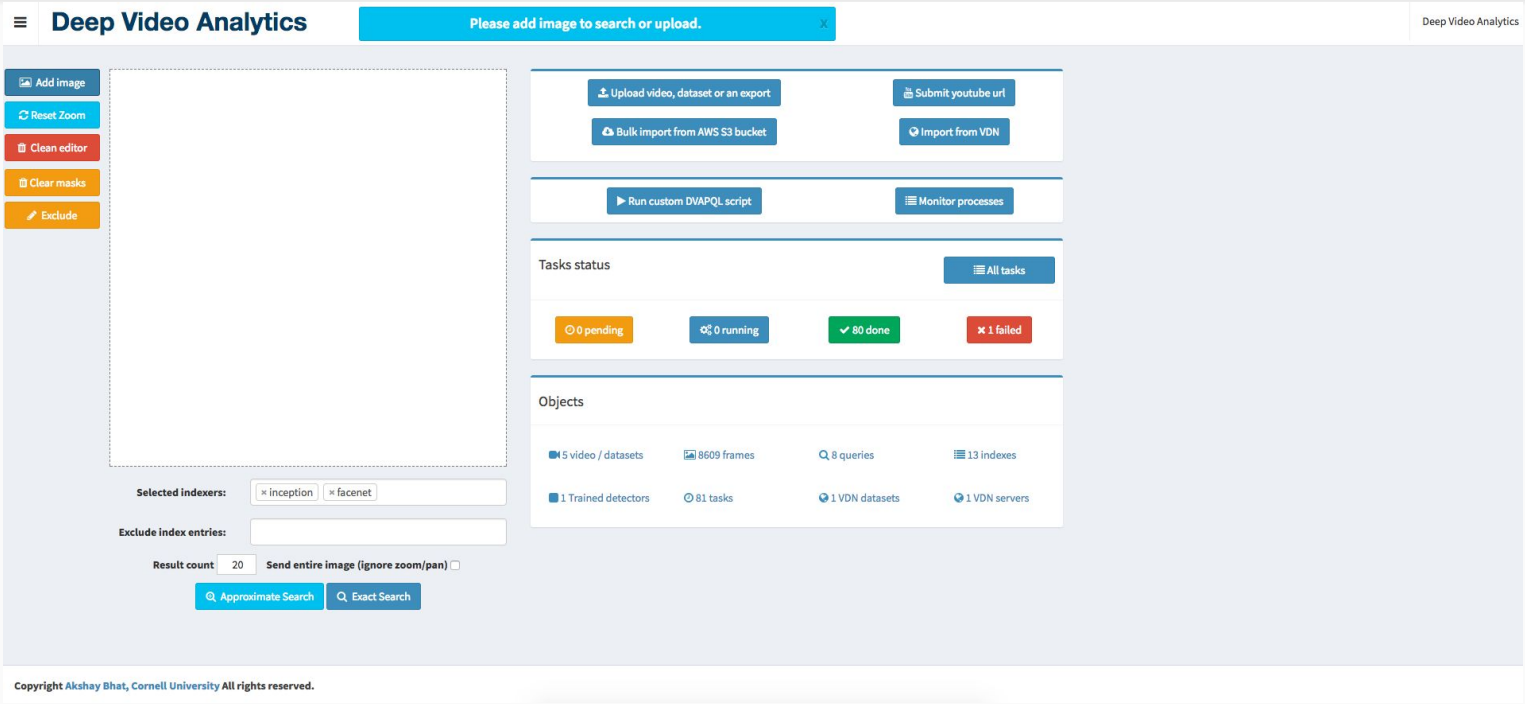
Single machine with GPUs

- nvidia-docker2
- Useful for training models
- Small research groups
- Can optionally use S3 or GCS in addition to shared docker volume

Kubernetes with GCS or S3

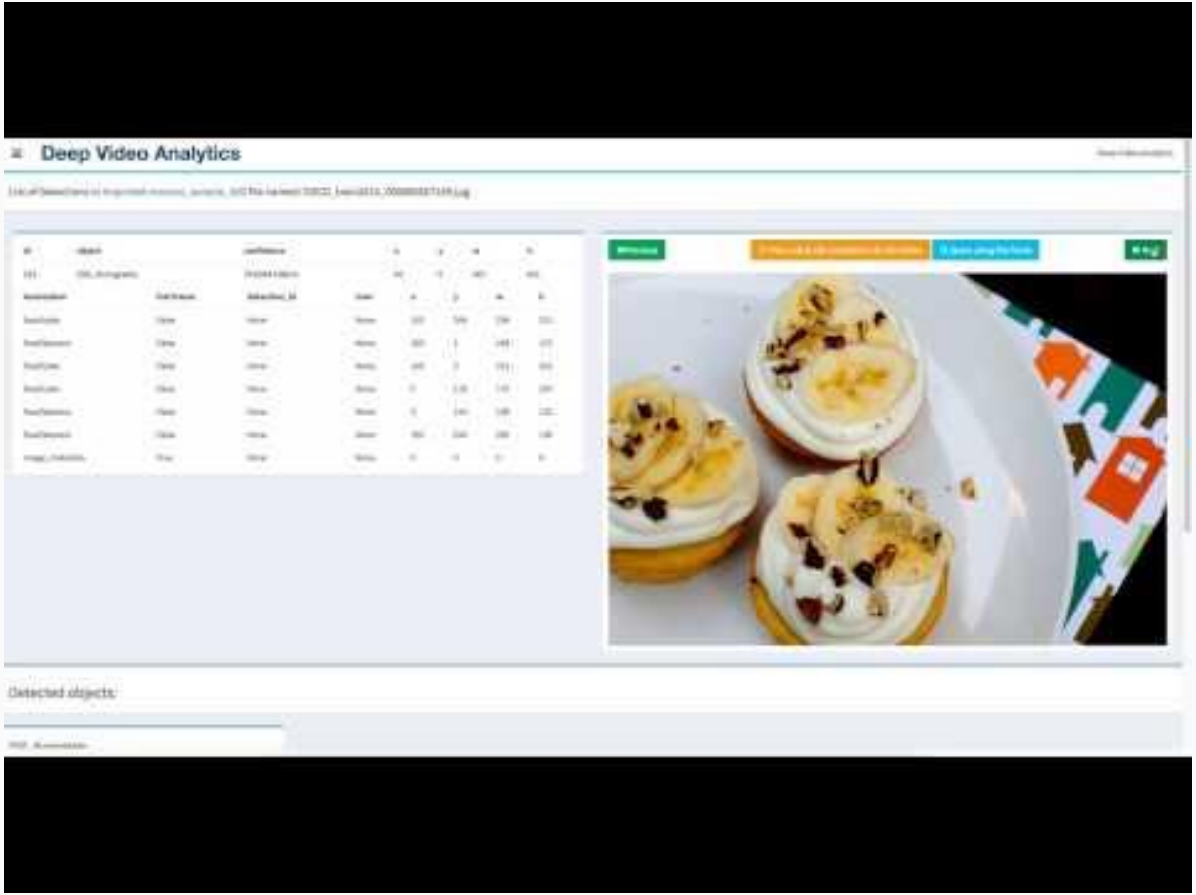
- Deploy on any Kubernetes cluster
- Currently supports GCP. AWS EKE coming soon!
- Leverages preemptible & spot
- Plan to leverage AWS lambda & Google Cloud functions in future.
- For production applications
- For large scale projects

User Interface

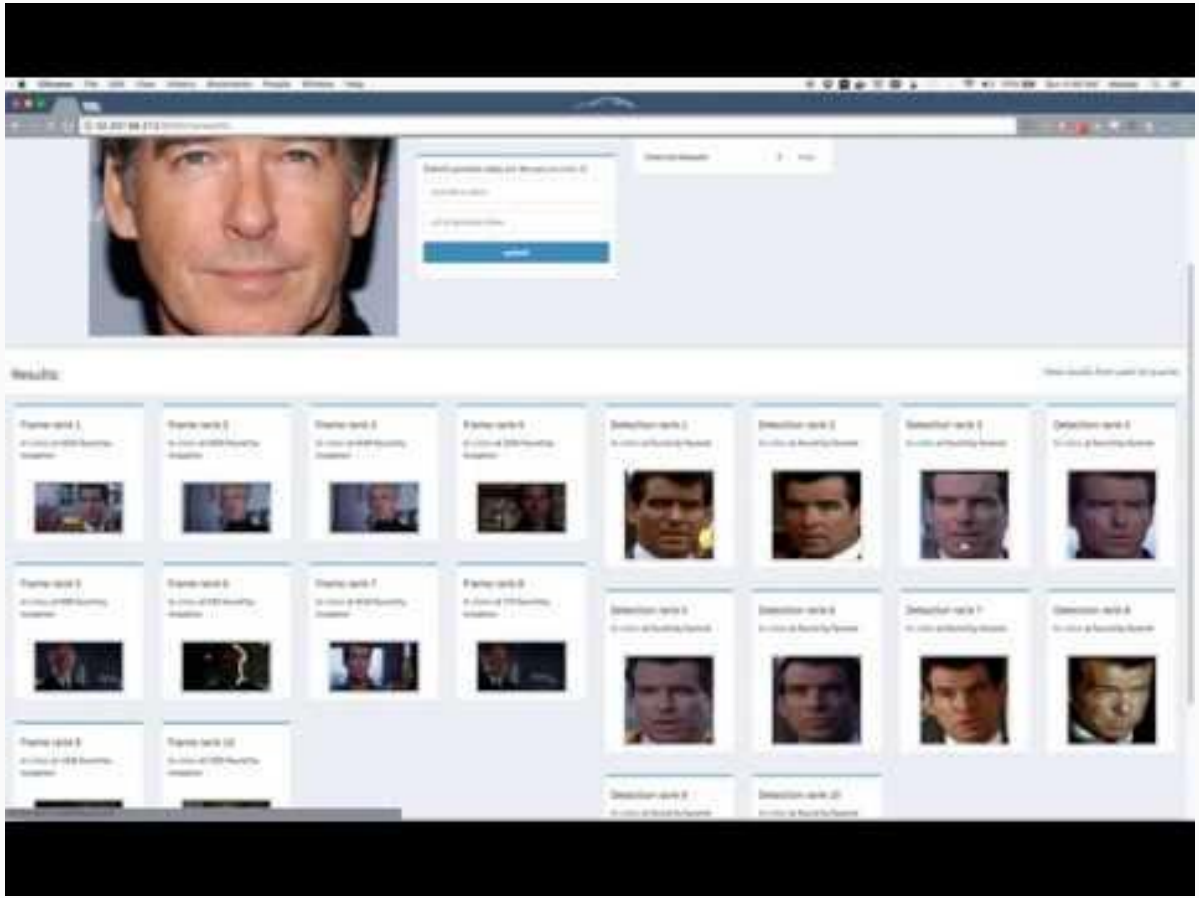


Latest version beta, 17th August 2017

7th April 2017



15th March 2017



People : Facebook

::

Code : Git / GitHub, GitLab

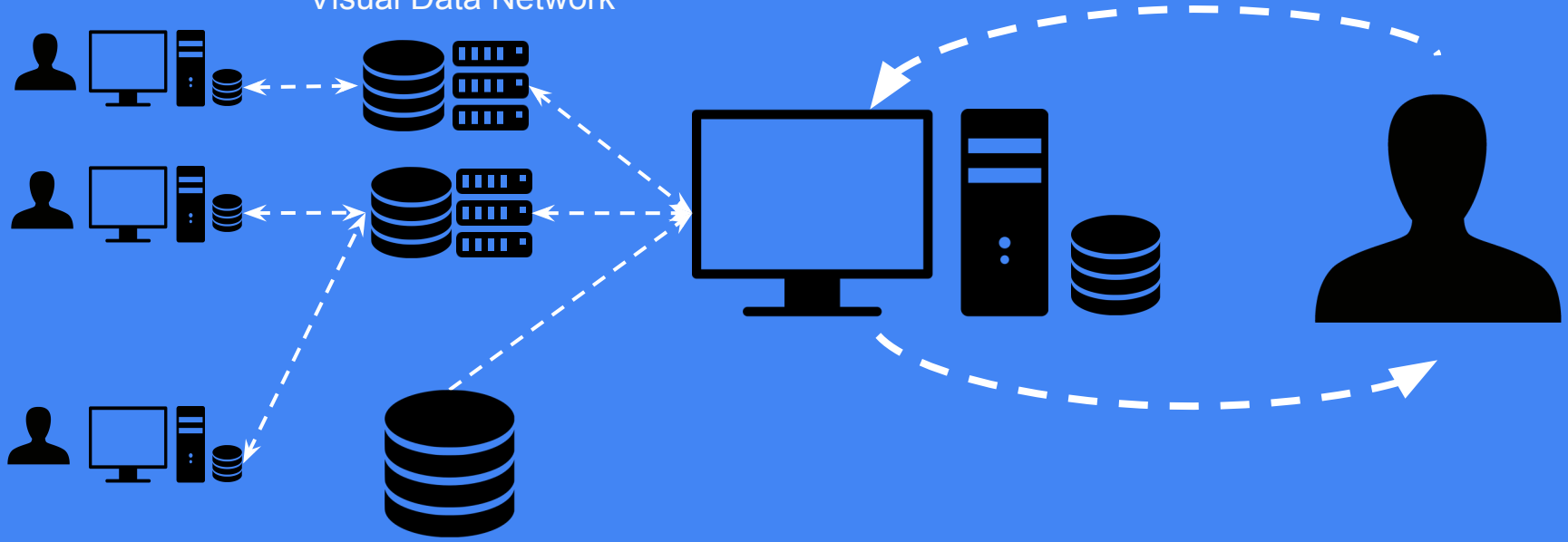
::

Visual Data: ***Visual Data Network***

Sharing data using Visual Data Network

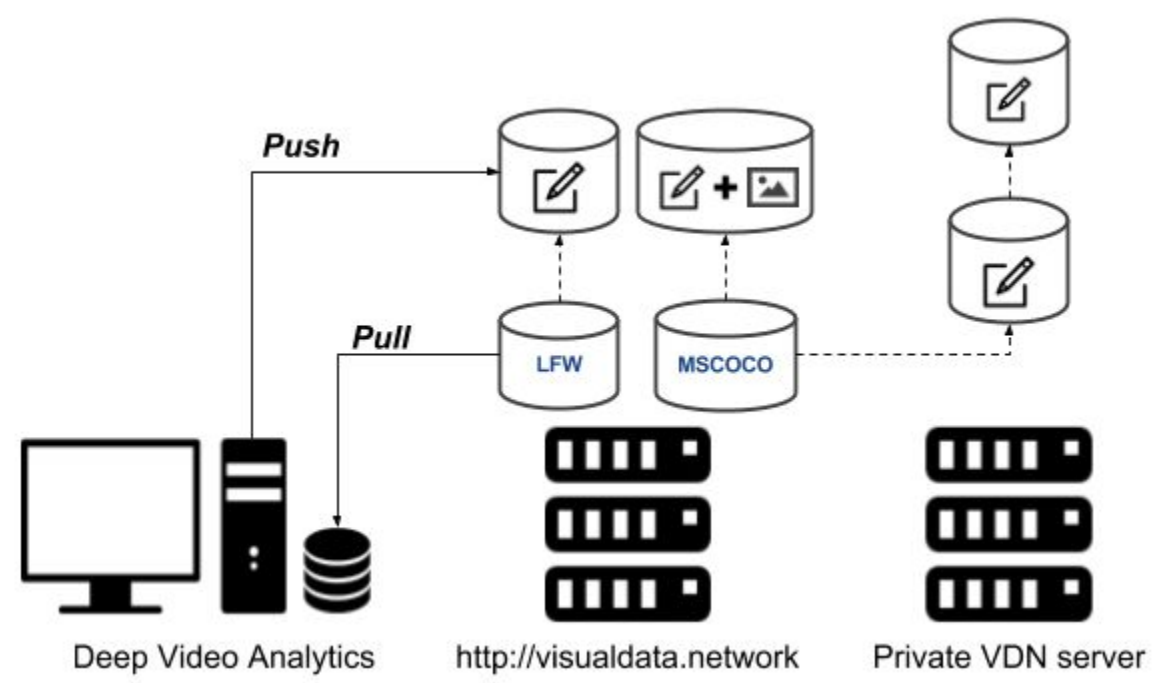
Import & export new datasets / annotations
share with other users

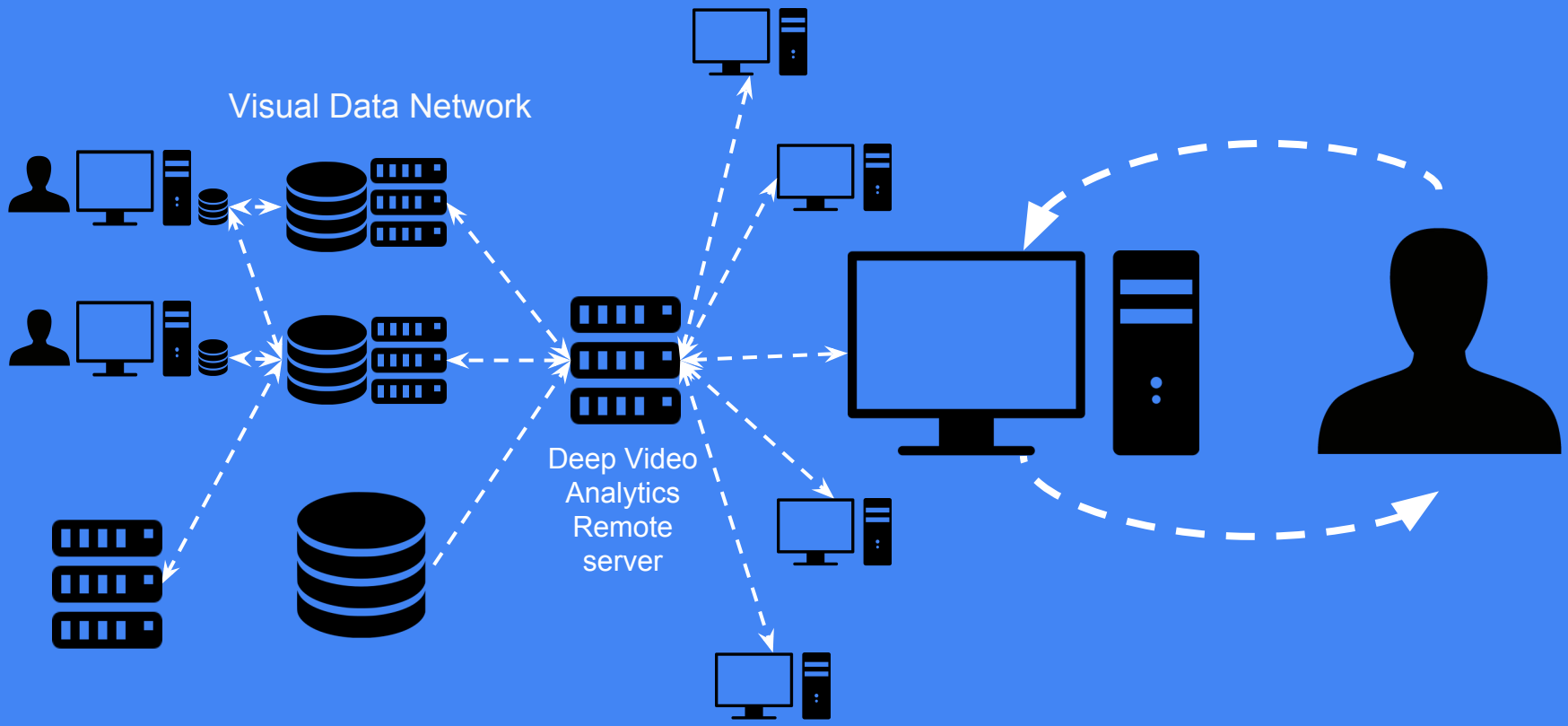
Visual Data Network



Visual Data Network enables seamless sharing

Push, Pull video / dataset, Annotations, just like you would with GitHub




Visual Data Network
Deep Video
Analytics
Remote
server

Open questions:
A work in progress

- How to effectively manage GPU memory & utilization?
- How to balance fast/static vs slow/dynamic indexes?
- How to learn continuously from annotations/feedback?
- How to minimize storage requirements via compaction?
- How to enable Real time processing?

Thanks!

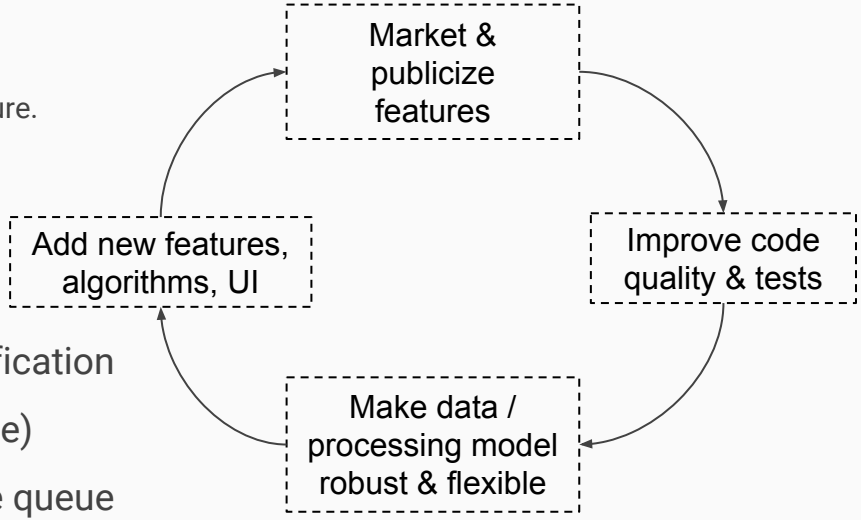
Contact me

akshayubhat@gmail.com

www.akshaybhat.com

Software Development approach or “How I developed Deep Video Analytics”

Partly inspired by “**Worse is better**”



- Start at “final scale” at which it's intended to be used
  - Easy to optimize each component, difficult to change architecture.
- Write “high level” tests rather than “unit tests”
  - E.g load video -> extract frames -> build index -> query
- Observability is crucial, develop UI for visual inspection
- Create start-from-zero config and use it for manual verification
- Keep everything in a single repo (including User Interface)
- **DO NOT** write a new database or roll your own message queue
  - Both Postgres and RabbitMQ are natively / cheaply supported in Travis / Heroku
  - It’s a nightmare to debug concurrency primitives also difficult to convince others to trust / maintain your code.
- Optimize for one goal (Features, Correctness, Consistency, Simplicity) at a time (over days / week)
  - E.g. Trade consistency/quality when adding new features. Once feature is done/verified/popular improve code quality. Once code quality has improved, transition to a more consistent / simple model. Use consistency to add new features.