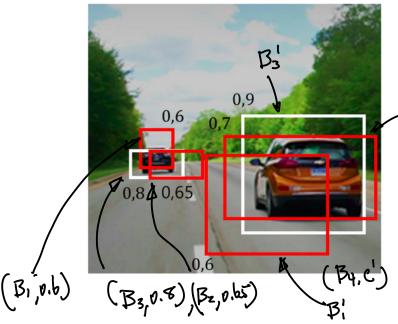
Handont On Bounding Box Selection Algorithm



B: (B, p.b), (Bz, p.b5) (B3,08)

Griven Image with Z Objects,

Multiple Bounding Boxes. B=

(B, p.b), (Bz, p.b5), (B3,0.8); (B1,p.b),

(B2,0.7), (B3,0.9) }, e.g. (B1,C1)

Sol: Stepl. Pick the Bi or Bi with

the Highest Confidence
level, so

(\$3,C3)=(\$3,0.9)

StepZ. Find IM.

JOU<sub>B'sB</sub>=p, KeepB1 in the Callectian Similarly, JOU<sub>B'sB2</sub>=JOU<sub>B'sB3</sub>=φ, Since KeepB2,B3, JOU<sub>B'sB2</sub>=Δ>JOU<sub>B'sB1</sub>=Δ-Δ'

Delete Bishom the collection.

IDU B'B! # \$ But Smaller Confidence

C' < C' , So B's is selected And placed
in the final Collection, And Delecte

B'.

Bums = { (B'3,C's)}

Step 3, Select Bi or Bi with the Next Righest Confidence Ci ov Ci, from Updated Collection B= {(B1,C1),(B2,C2),(B3,C3)} So (B3,P.8) = (B3,C3) is selected.

Step4. Consule IDU3,1 = 0, IDV372=0+01

: IDN32> IDN3,1 - Discoul Bz,

And .: C1<C3, Delete C1, plane

B, into the final Selection

Bnns={(B3,C3),(B3,C3)}, update the collection

B= 203. Done,

## Algorithm 1 Non-Max Suppression

```
1: procedure NMS(B,c)
                  B_{nms} \leftarrow \emptyset Initialize empty set
  2:
                  for b_i \in B do \Rightarrow Iterate over all the boxes Take boolean variable and set it as false. This variable indicates whether b(i)
  3:
                            discard \leftarrow \text{False} should be kept or discarded
  4:
                           \mathbf{for}\ b_i \in B\ \mathbf{do} Start another loop to compare with b(i)
  5:
                                                                                                                  If both boxes having same IOU
                                     if same(b_i, b_j) > \lambda_{nms} then
  6:
                                              \begin{array}{l} \textbf{if} \ \text{score}(c,b_j) > \text{score}(c,b_i) \ \textbf{then} \\ discard \leftarrow \text{True} \quad \text{\tiny Compare the scores. If score of b(i) is less than that} \\ discard \leftarrow \text{True} \quad \text{\tiny of b(j), b(i) should be discarded, so set the flag to} \end{array}
  7:
  8:
                           if not discard then
  9:
                                                                                           Once b(i) is compared with all other boxes and still the
                                     B_{nms} \leftarrow B_{nms} \cup b_i discarded flag is False, then b(i) should be considered. So add it to the final list.
10:
                                                          Do the same procedure for remaining boxes and return the final list
                  return B_{nms}
11:
```

https://towardsdatascience.com/non-maximum-suppression-nms-93ce178e177c

(END)