

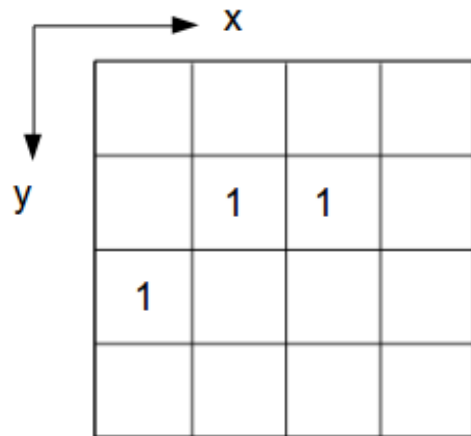
CMPE 258 Final Exam
HL S2020

First Name: _____ **Last Name:** _____

Student ID: _____ **Email:** _____ **(Total 20 points)**

QUESTION 1 (5 points) In deep-face CNN improvement with object tracker as the preprocessing function, shown the following figure is an object tracker tuned for pedestrian localization. Answer the following design questions:

1.1 (3 pts) Compute the \bar{x} and \bar{y} (centroid of the ROI bounding box)



QUESTION 3 (5 Points) Given below is one CNN, answering the following questions:

3.1 (1 pts) Based on CNN architecture given below, explain what is the input image format? (number of channels? Color or gray scale?)

3.2 (2 pts) Find the number of kernels from input 149x149x1 to 75x75x32?

3.3 (2 pts) Explain the function of Max Pooling, given an example how to compute it?

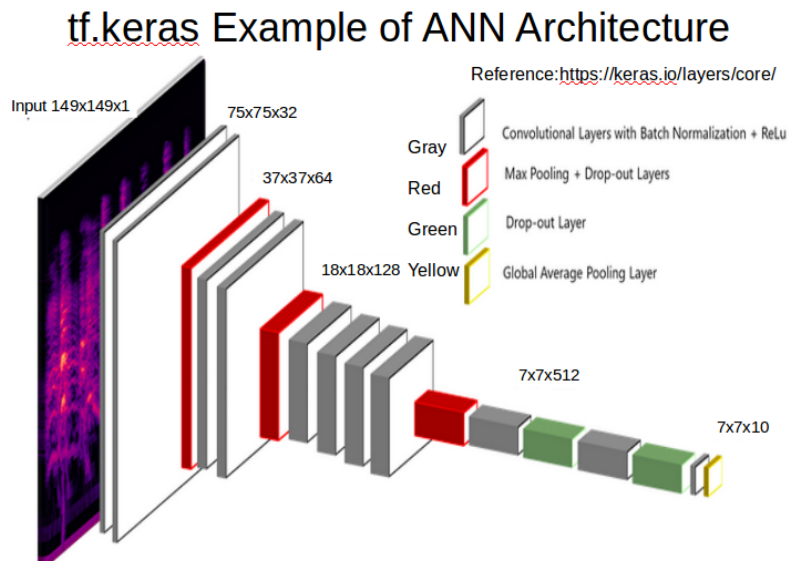
3.4 (1 pt) write one line of python code for TF module to construct a convolutional layer, suppose the size is 28 by 28?

3.5 (1 pt) write one line of python code for TF module to construct a convolutional layer, suppose the size is 28 by 28?

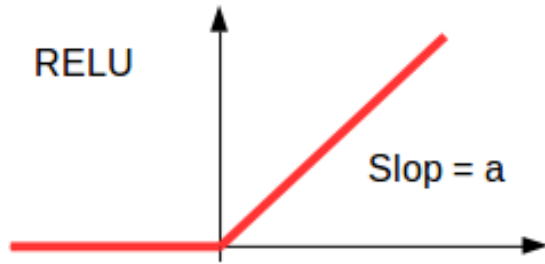
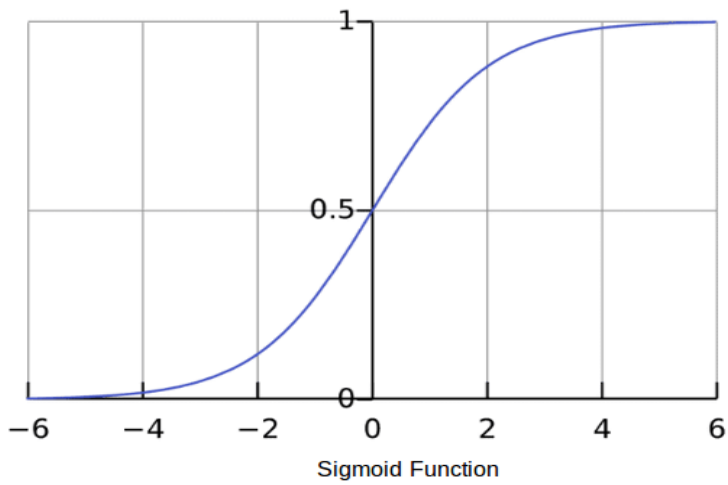
3.6 (1 pt) write one line of python code for TF module to save trained CNN?

3.7 (1 pt) write one line of python code for TF module to load trained CNN?

3.8 (1 pt) write one line of python code for TF module to predict input image for recognition?



$$\text{MSE} = \frac{1}{n} \sum_{i=1}^n (y_{\text{true}} - y_{\text{pred}})^2$$



(END)