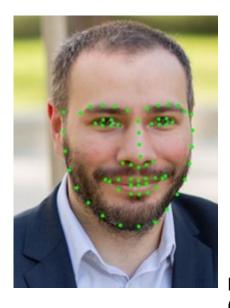
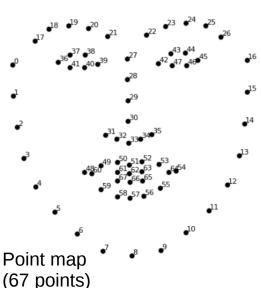


Sample Detecting Facial Features

https://towardsdatascience.com/detecting-face-features-with-python-30385aee4a8e

Feature Vectors





.16 .15 .14 Jaw Points = 0–16

Right Brow Points = 17–21

Left Brow Points = 22–26

Nose Points = 27–35

Right Eye Points = 36–41

Left Eye Points = 42–47

Mouth Points = 48–60

Lips Points = 61–67

Jaw Points (17 pts) Left Brow Right Brow (5 pts) (5 pts) Left Eye (6) Right Eye (6) **Nose Points** Lips (7) Mouth (13)

\$pip -V (to check your pip version)

Note this model is simplified version with no upper face



Using http://dlib.net/ For Feature Extraction

Dlib is a modern C++ toolkit containing machine learning algorithms and tools for creating complex software in C++ to solve real world problems. It is used in both industry and academia in a wide range of domains including robotics, embedded devices, mobile phones, and large high performance computing environments. Dlib's open source licensing allows you to use it in any application, free of charge.

Sample code:

import cv2
import numpy as np
import dlib #for facial feature extraction

- 1. Machine learning
- 2. Numerical algorithms
- 3. Graphical model inference algorithms
- 4. Image processing
- 5. Threading
- 6. Networking
- 7. GUI
- 8. Testing (Unit testing framework)
- 9. XML Parser etc.

```
# Load the predictor
predictor = dlib.shape_predictor("shape_predictor_68_face_landmarks.dat")
```

From dlib, additional

features are possible



Pycharm IDE for Python

PyCharm is probably the only Python dedicated IDE that supports the vast expanse of features Python has. Sublime, Atom and Sypder do exist, but they only exist! The integrated development environment experience that PyCharm provides is way better than the others.



To install pycharm:

https://medium.com/@singh.shreya8/how-to-install-pycharm-in-ubuntu-16-04-ubuntu-14-04-ubuntu-18-04-linux-easiest-way-5ae19d052693

To start pycharm: \$sh pycharm.sh

https://www.youtube.com/watch?v=BPC-bGdBSM8&list=PLQ176FUIyIUZ1mwB-uImQE-gmkwzjNLjP

Pycharm hello the world

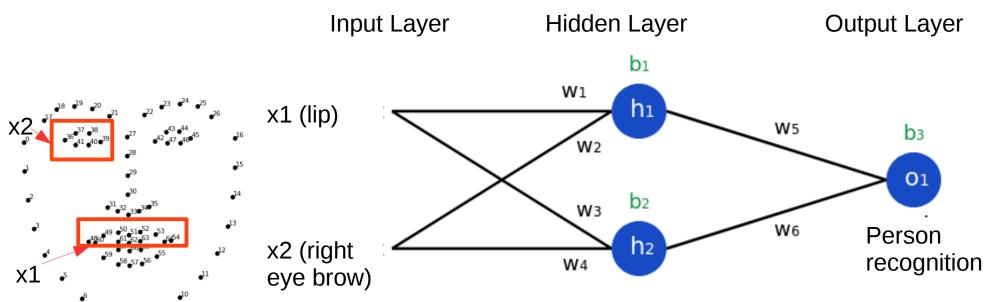
https://www.jetbrains.com/help/pycharm/cr eating-and-running-your-first-pythonproject.html#summary

use Cmake to build and install OpenCV and Extra Modules from source and configure your Pycharm IDE

https://towardsdatascience.com/how-to-install-opencvand-extra-modules-from-source-using-cmake-and-thenset-it-up-in-your-pycharm-7e6ae25dbac5



Simple Feed Forward Neural Networks



To do: (1) add h3 hidden layer, (2) add o2 at output layer, modify the code

def feedforward(self, x):

x is a numpy array with 2 elements.

h1 = sigmoid(self.w1 * x[0] + self.w2 * x[1] + self.b1)

h2 = sigmoid(self.w3 * x[0] + self.w4 * x[1] + self.b2)

o1 = sigmoid(self.w5 * h1 + self.w6 * h2 + self.b3)

return o1

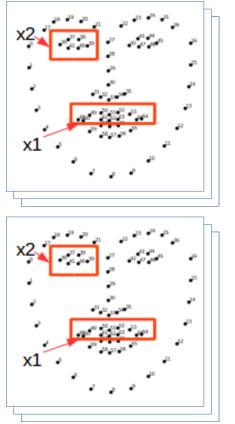


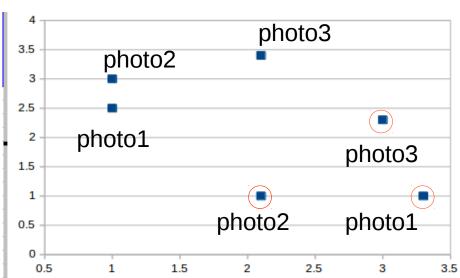
For 2 persons

```
# Define dataset and all y trues
data = np.array([
 [1, 2.5], # person A
 [1, 3], # person A
 [2.1, 3.4], # Person A
 [2.1, 1], # person B
 [3.3, 1], # person B
 [3, 2.3], # person B
all y trues = np.array([
 1, # person A
 1, # person A
 1, # person A
 0, # person B
 0, # person B
 0, # person B
```

Prepare the Data Set

For 2 persons





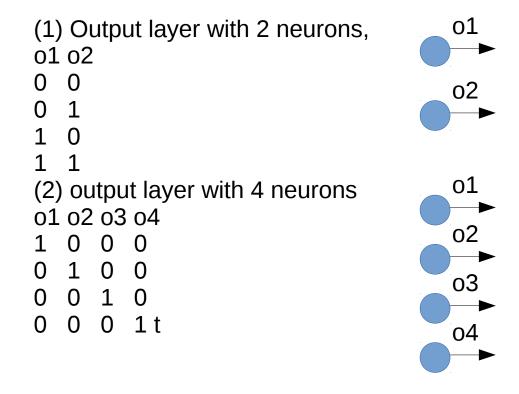


Prepare the Output Layer

For 2 persons

```
# Define dataset and all y trues
data = np.array([
 [1, 2.5], # person A
 [1, 3], # person A
 [2.1, 3.4], # Person A
 [2.1, 1], # person B
 [3.3, 1], # person B
 [3, 2.3], # person B
all y trues = np.array([
 1, # person A
 1, # person A
 1, # person A
 0, # person B
 0, # person B
 0, # person B
```

For 4 persons





Output Layer from ImageNet

https://www2.eecs.berkeley.edu/Pubs/TechRpts/2020/EECS-2020-18.html

ImageNet Training in Minutes

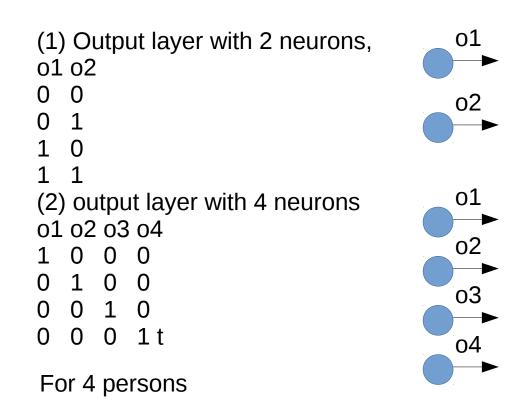
Yang You, Zhao Zhang, Cho-Jui Hsieh, James Demmel and Kurt Keutzer

EECS Department

University of California, Berkeley

Technical Report No. UCB/EECS-2020-18

January 25, 2020



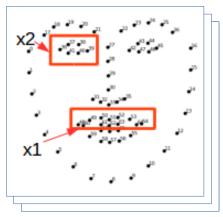


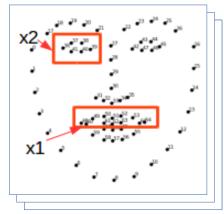
For 2 persons

```
# Define dataset and all y trues
data = np.array([
 [1, 2.5], # person A
 [1, 3], # person A
 [2.1, 3.4], # Person A
 [2.1, 1], # person B
 [3.3, 1], # person B
 [3, 2.3], # person B
all_y_trues = np.array([
 1, # person A
 1, # person A
 1, # person A
 0, # person B
 0, # person B
 0, # person B
```

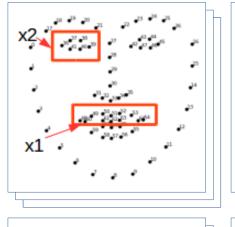
Prepare the Data Set

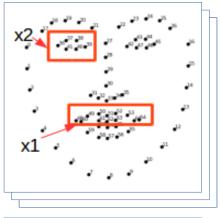
For 2 persons

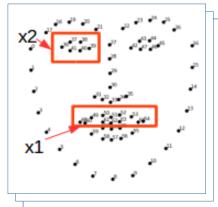


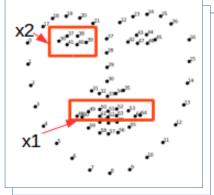


For 4 persons











For 4 persons

Define dataset and all y trues data = np.array([[1, 2.5], # person A [1, 3], # person A [2.1, 3.4], # Person A [2.1, 1], # person B [3.3, 1], # person B [3, 2.3], # person B [3, 2.5], # person C [3, 3.6], # person C [4.1, 5.4], # Person C [4.5, 3.1], # person D [3.3, 1.9], # person D [5.9, 2.3], # person D

4 Person Data Set

```
all y trues = np.array([
 01, # person A
 01, # person A
 01, # person A
 00, # person B
 00, # person B
 00, # person B
 11, # person C
 11, # person C
 11, # person C
 10, # person D
 10, # person D
 10, # person D
```

For 4 persons

