

# 10-26-2018 Keras API Functions

1  
`model.add(layers.Conv2D(32, (3, 3), activation='relu', input_shape=(28, 28, 1)))`

2  
`model.add(layers.MaxPooling2D((2, 2)))`

3  
`model.add(layers.Flatten())`

4  
`model.add(layers.Dense(64, activation='relu'))`

5  
`tf.keras.layers.Dropout(0.2)(fc_1)`

6  
`model.summary()`

# 10-26-2018 ConvNet Architecture Design

Deep Learning Oct. 26, 2018. 1/

Today's Topics:

1<sup>st</sup> Hands-On Programming ON Convnet.py.

Ref: [github/fualdi/opencv/IP120-AI-DL](https://github.com/fualdi/opencv/IP120-AI-DL)

Convnet.py. (Chollet's Style)

Compilation & Build this Program.

Keras API  
Architect

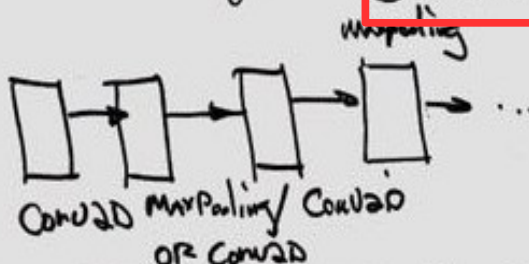
Network Architecture → The Projects Assignment.

Objectives: Design And Prototype A DL Convnet.

Approach: ① Network Diagram (from Examples) CAT I  
Ref: CAT Video & Image. 2018F-3-~ CAT II  
II & I CAT III

Basic Building Blocks

- ② 2D Conv. Layer
- ③ Flatten
- ④ Max Pooling
- ⑤ Dense (layer)



Observation I: To Design Convnet for Deep Learning  
we start with Convolution Layer followed very often by  
Max Pooling layer, then these layers can be repeated...

Step 1. Repeating  
conv2D( ) layer and  
MaxPooling( ) layer

Example

```
1 model.add(layers.Conv2D(32, (3, 3),  
activation='relu', input_shape=(28, 28, 1)))
```

```
2 model.add(layers.MaxPooling2D((2, 2)))
```

```
6 model.summary()
```

↖  
To display the  
network architecture

# 10-26-2018 3 ConvNet Examples

Example ①: from Smodel.py. Architecture

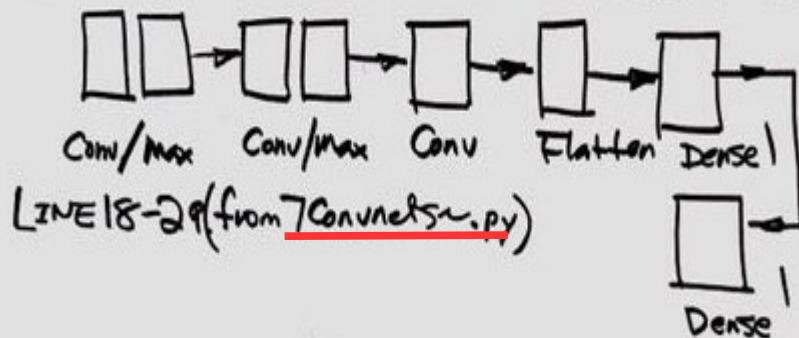
40K photos



Example: ② NIST For Digits (0-9) Recognition.  
60K photos

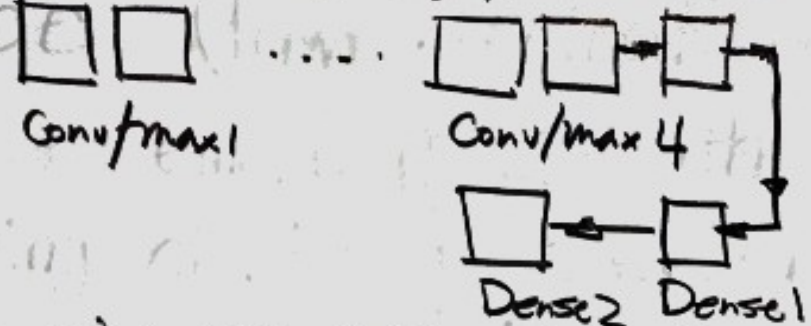
Note: Architecture

Conv/max → Conv/max → Dense → Dense → Flatten



Example ③: For 1000 Cats & Dogs Photos.

Ref: 8convnets.py. Flatten



Note: The tool to verify (Print) model is modelSummary()

Jerry On Python File Manipulations.  
Sample Code: 8convnet ~.py file manipulation.

Observation II: Generally, Deep Learning Architecture can be classified as convolutional layer(s) and NeuralNet layers.

Example: from the Summary of Example 1 to Example 3.

# 10-26-2018 Comparison of 3 ConvNets

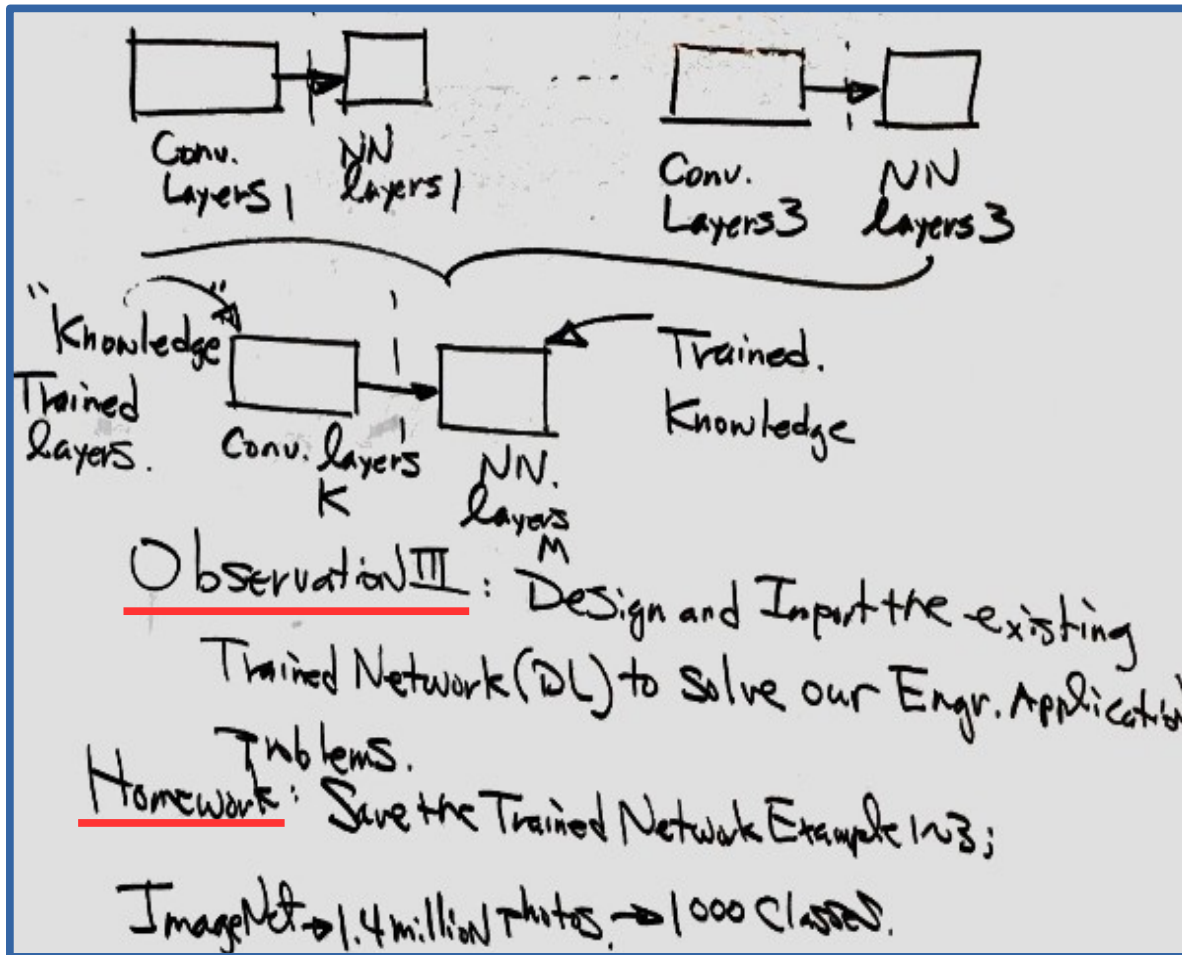
Table 1. Three well trained convnet examples

|            |                   |            |  |
|------------|-------------------|------------|--|
|            |                   |            |  |
| 1 convnet1 | Satellite imagery | 40K images | ConvPool1+ConvPool2+Flatten+Den1+Den2                          |
| 2 convnet2 | NIST digits 0-9   | 60K images | ConvPool1+ConvPool2+Conv+Flatten+Den1+Den2                     |
| 3 convnet3 | Chollet cat-dog   | 1K images  | ConvPool1+ConvPool2+ConvPool3 +ConvPool4<br>+Flatten+Den1+Den2 |

Table 2. Sample code for 3 well trained convnets

| Network  | Programs                              |
|----------|---------------------------------------|
| convnet1 | 5model.py                             |
| convnet2 | 7convnets-NumeralDetection-ch05.py    |
| convnet3 | 8convnets-SmallData-cats-dogs-ch05.py |

# 10-26-2018 3 ConvNet Examples



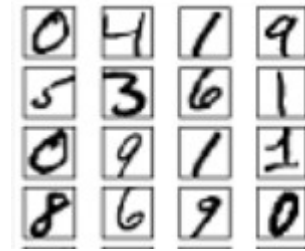


# 10-26-2018 Dense Layer Output Design

Example: NIST 10 digits (0-9) convnet Dense layer

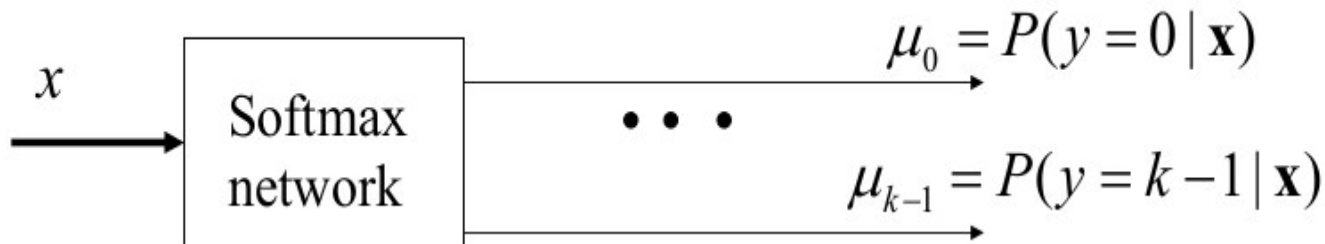
```
from keras import models
from keras import layers
```

```
network = models.Sequential()
network.add(layers.Dense(512, activation='relu', input_shape=(28 * 28,)))
network.add(layers.Dense(10, activation='softmax'))
```



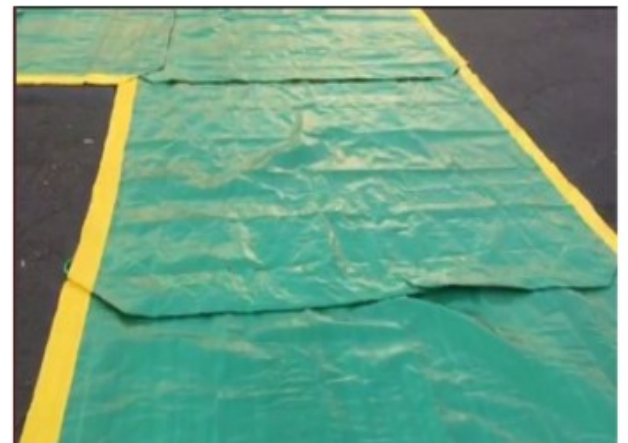
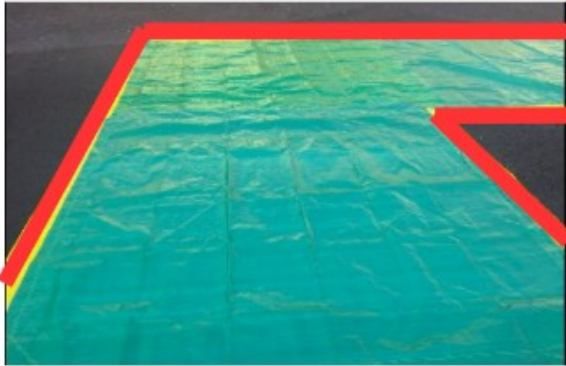
Sample code :  
<https://github.com/fchollet/deep-learning-with-python-notebooks>

The network consists of 2 Dense layers, densely-connected ("fully-connected") neural layers. The output layer is a 10-way "softmax" layer, it returns an array of 10 probability scores (summing to 1). Each score will be the probability that the current digit image belongs to one of our 10 digit classes.

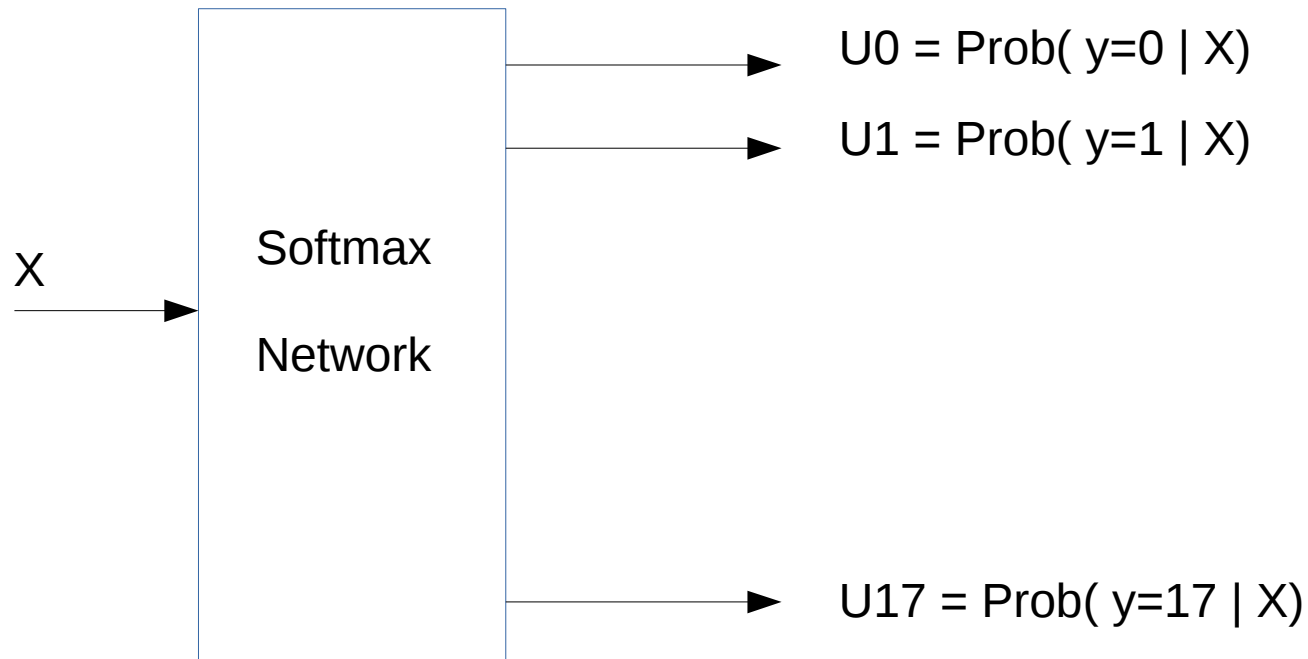


*Illustration of the softmax block diagram from Milos Hauskrecht,  
milos@cs.pitt.edu, 5329 Sennott Square*

# CAT-II Path Primitives

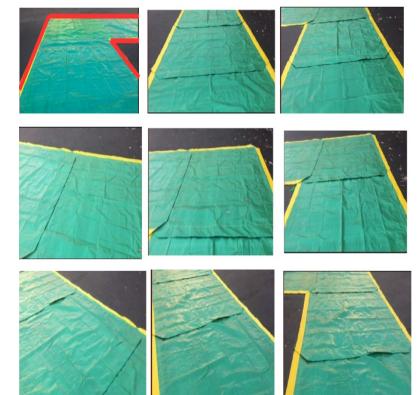
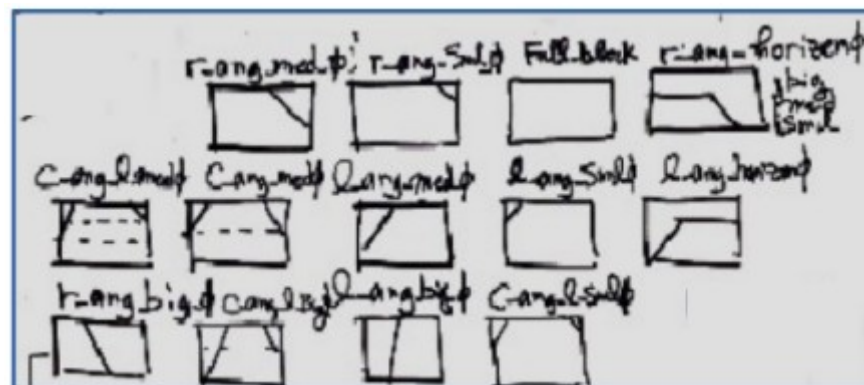


# 10-26-2018 Softmax Output Design for CATIII



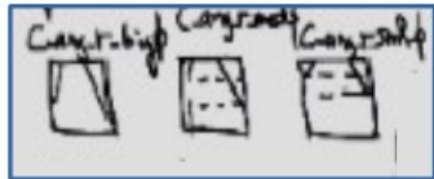
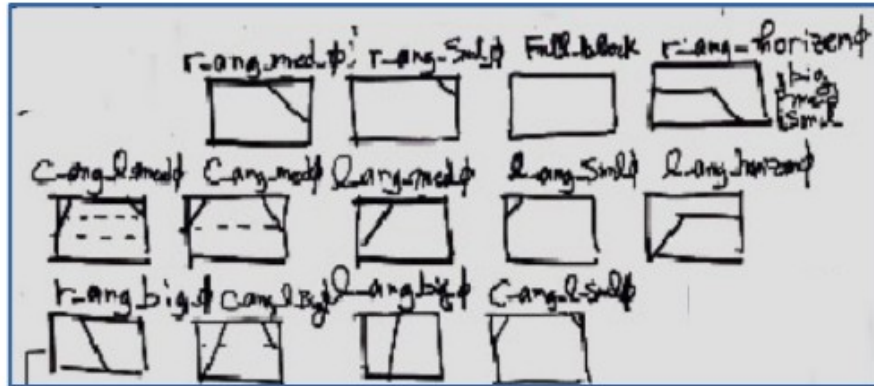
|                |                      |
|----------------|----------------------|
| 1. r_ang_big   | right angle big      |
| 2. r_ang_med   | right angle medium   |
| 3. r_ang_sml   | right angle small    |
| 4. r_ang_hor   | right angle horizon  |
| 5. l_ang_big   | left angle big       |
| 6. l_ang_med   | left angle medium    |
| 7. l_ang_sml   | left angle small     |
| 8. l_ang_hor   | left angle horizon   |
| 9. cr_ang_big  | central-right big    |
| 10. cr_ang_med | central angle medium |
| 11. cr_ang_sml | central angle small  |
| 12. cl_ang_big | central-left big     |
| 13. cl_ang_med | central angle medium |
| 14. cl_ang_sml | central angle small  |
| 15. c_ang_big  | central-angle big    |
| 16. c_ang_med  | central-angle medium |
| 17. c_ang_sml  | central-angle small  |
| 18. full       | full block           |

Where  $\text{Prob}(y=0 | X) + \text{Prob}(y=1 | X) + \dots + \text{Prob}(y=17 | X) = 1$



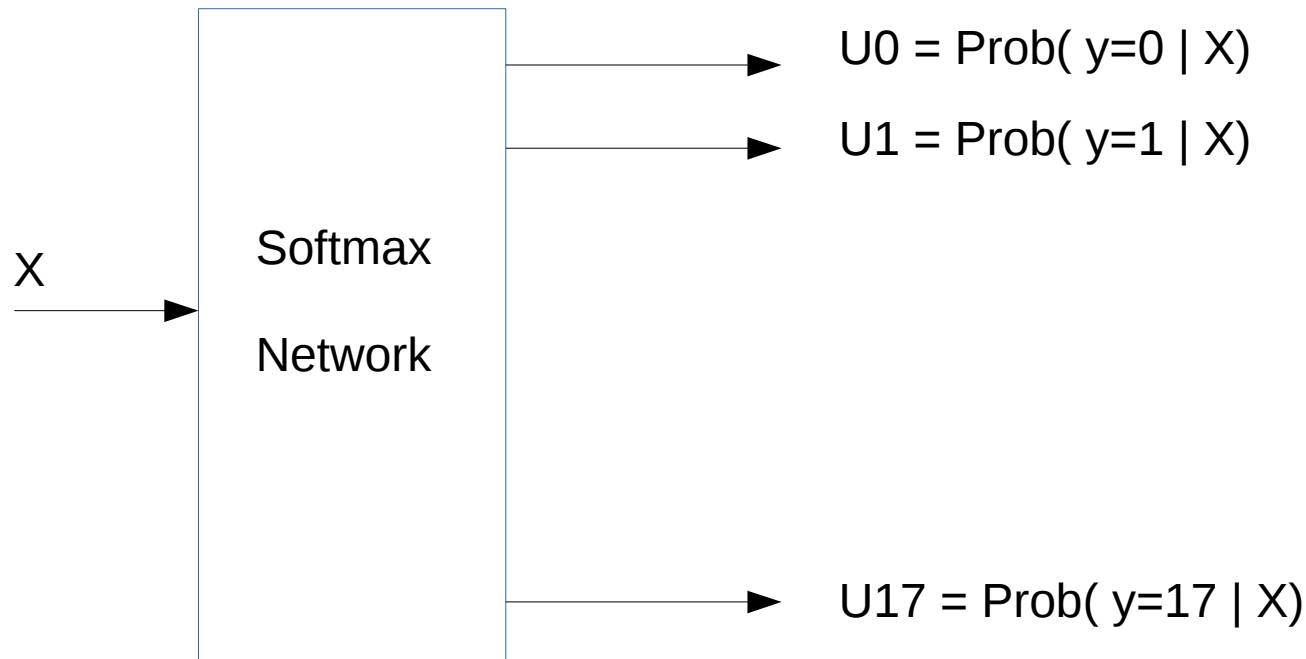


# 9-25-2018 Primitive Features for CAT-II Path Classification



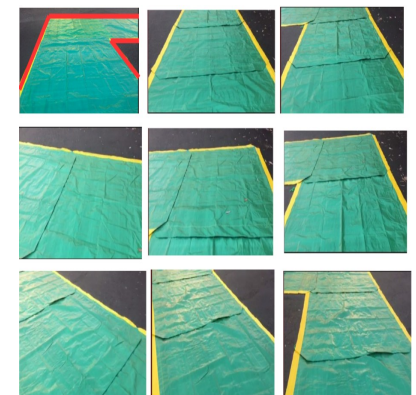
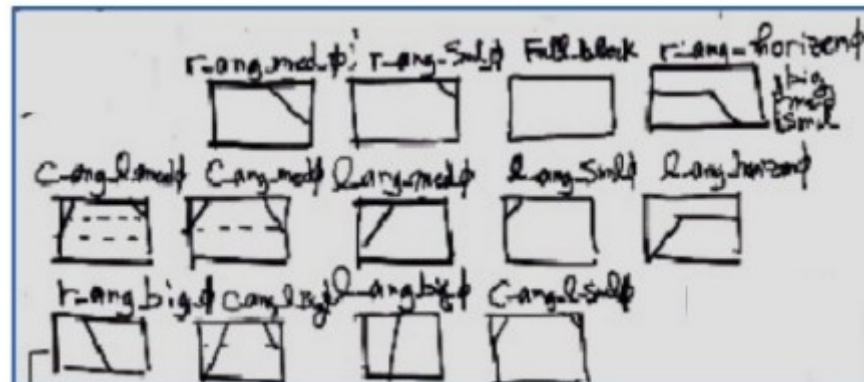
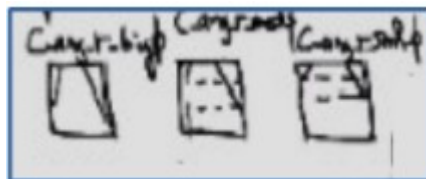
|                |                      |
|----------------|----------------------|
| 1. r_ang_big   | right angle big      |
| 2. r_ang_med   | right angle medium   |
| 3. r_ang_sml   | right angle small    |
| 4. r_ang_hor   | right angle horizon  |
| 5. l_ang_big   | left angle big       |
| 6. l_ang_med   | left angle medium    |
| 7. l_ang_sml   | left angle small     |
| 8. l_ang_hor   | left angle horizon   |
| 9. cr_ang_big  | central-right big    |
| 10. cr_ang_med | central angle medium |
| 11. cr_ang_sml | central angle small  |
| 12. cl_ang_big | central-right angle  |
| 13. cl_ang_med | central angle medium |
| 14. cl_ang_sml | central angle small  |
| 15. c_ang_big  | central-angle big    |
| 16. c_ang_med  | central-ang medium   |
| 17. c_ang_sml  | central-ang small    |
| 18. full       | full block           |

# 10-26-2018 Softmax Output Design for CATIII

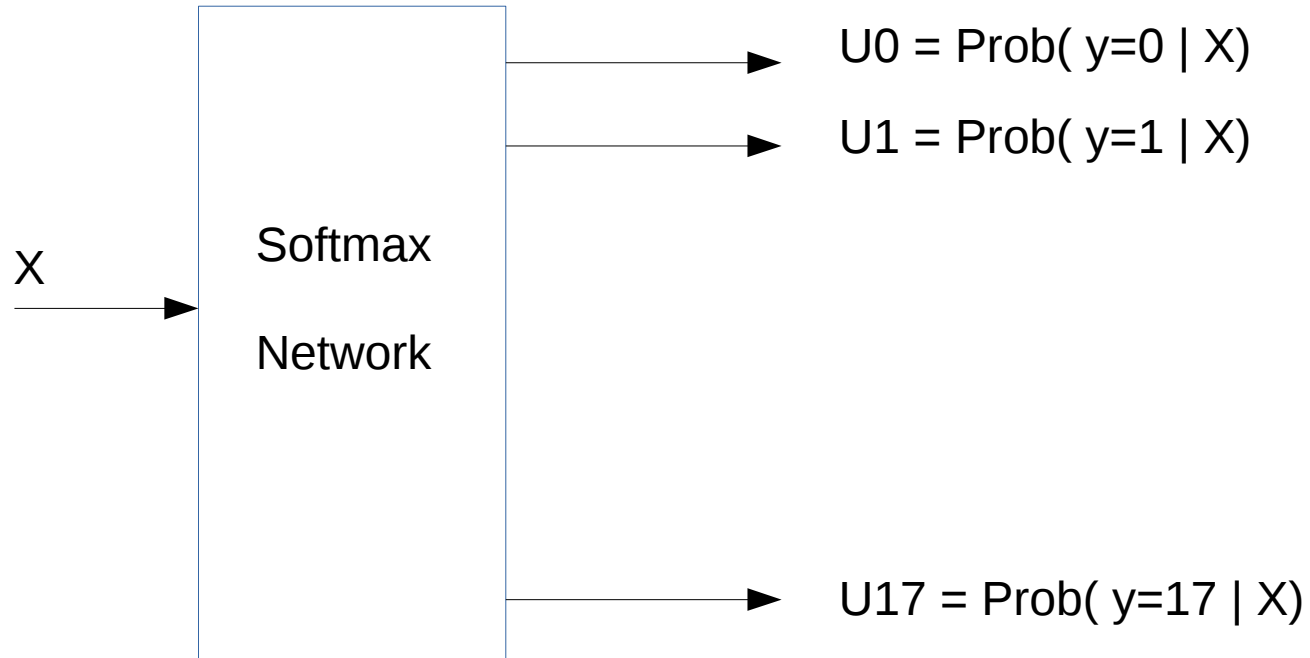


|                |                      |
|----------------|----------------------|
| 1. r_ang_big   | right angle big      |
| 2. r_ang_med   | right angle medium   |
| 3. r_ang_sml   | right angle small    |
| 4. r_ang_hor   | right angle horizon  |
| 5. l_ang_big   | left angle big       |
| 6. l_ang_med   | left angle medium    |
| 7. l_ang_sml   | left angle small     |
| 8. l_ang_hor   | left angle horizon   |
| 9. cr_ang_big  | central-right big    |
| 10. cr_ang_med | central angle medium |
| 11. cr_ang_sml | central angle small  |
| 12. cl_ang_big | central-left big     |
| 13. cl_ang_med | central angle medium |
| 14. cl_ang_sml | central angle small  |
| 15. c_ang_big  | central-angle big    |
| 16. c_ang_med  | central-angle medium |
| 17. c_ang_sml  | central-angle small  |
| 18. full       | full block           |

Where  $\text{Prob}(y=0 | X) + \text{Prob}(y=1 | X) + \dots + \text{Prob}(y=17 | X) = 1$



# 10-26-2018 Softmax Output Design for CATIII



Where  $\text{Prob}(y=0 | X) + \text{Prob}(y=1 | X) + \dots + \text{Prob}(y=17 | X) = 1$