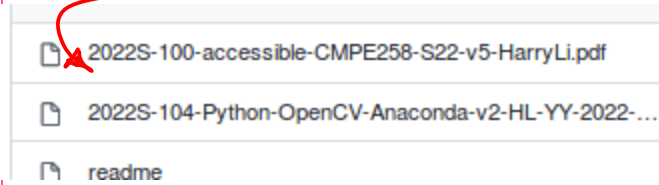


CMPE258 Spring 2022

1/

Feb 1st. Organizational meeting.

1. Today's Topics "green sheet"



Naming Convention Yr + Semester + ID
+ Name + Date

Contact Information: E-mail: hua.li@sjsu.edu

Text message to (650) 400-1116.

Office Hours: M.W. 4:30-5:30pm.

Zoom (link to be shared in the email)

Join from PC, Mac, Linux, iOS or Android: [https://sjsu.zoom.us/j/85616325978?](https://sjsu.zoom.us/j/85616325978?pwd=MzlRbDJXVHBDQ2g1U0RPM2tYc045Zz09)

pwd=MzlRbDJXVHBDQ2g1U0RPM2tYc045Zz09

Password: 451032

On-Line materials on github

<https://github.com/hualili/opencv/tree/master/deep-learning-2020S>

<https://github.com/hualili/opencv/tree/master/deep-learning-2022s>

Also, CANVAS → mostly for Assignments and projects.

All Assignment/Projects are posted on Both github & SJSU CANVAS.

Lecture Material consists of PPT. posted on github, and Lecture Notes (White-Board Written Notes)

CORE Emphases of the Class: Deep Convolutional

Neural Networks, And their Application in Image Analysis, Video Analysis.

1. Text Book:

<https://github.com/hualili/opencv/blob/master/IP120-AI-DL/2018F/2018F-6-DeepLearningCh02.pdf>

2. Computer Vision Book By Horn as a reference for Convolution & Image Segmentation, Continuous Analysis (Binary Image).

3. OpenCV Reference Book (2nd Edition) together with On-Line Document (OpenCV).

Note: OpenGL (GL: Graphics Library) is just for Reference purpose, no need for this class. (but maybe helpful for the future research).

Unity is game Development platform, interactive 3D Graphics Design platform.

Programming Languages:

1. Python. 3.6 or 3.7

2. C/C++ Feb. 8th.

Homework (Due A week from today) No Submission. Submit A Screen

Capture that shows OpenCV installed successfully, with Jpg or png file with Naming of the file as follows:

First Name _ Last Name _ SID _ OpenV. jpg

This Homework will be posted on CANVAS, Submission is on CANVAS.

Homework, Installation of Tensor Flow, Due 2 weeks Feb 15th.

Submission: Screen Capture that shows the installation is successful. Submission on CANVAS.

Submit jpg, png file with the Naming convention as follows:

First Name _ Last Name _ SID _ TF. jpg

Note: Optional, for Edge AI Computing, Consider using NVIDIA Jetson Nano (4GB) version.

50% Bonus

Grading:

Homework, projects : 30%
5% 25%

Project 1. Computer Vision for Preprocessing. plus Deep Convolutional Neural Nets To give Real Time Detection Result of Last 4 Digits of a Student ID.

10%.

Project 2. "Semester Long" project, with technical requirements (List)

Team project. 4 person team.

Each person has clear Definition of the tasks (Programming/Coding) And Balanced Contribution.

Final TPT, Demo Presentation 15%.

Midterm Exam: 30%.

Need to use your Laptop Computer, to Run/Execute code, modify the Code.

Final 40%

Introduction

Topics { Neural Networks formulation (Basic Building Blocks)
Digital Images/Videos.

Example: A Single Neuron Formulation (Some kind Brain Cell)

Step 1. Summation function.

Σ

Fig 1.

" Σ " Summation function.

Note: $\sum_{k=1}^N x_k = x_1 + x_2 + \dots + x_N$

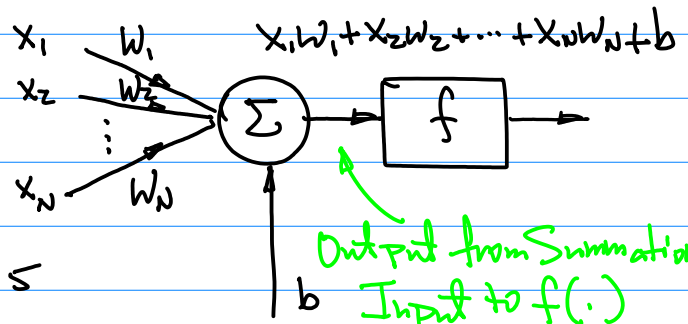


Fig 5

Step 2. Inputs

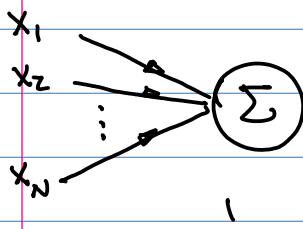


Fig 2.

Step 3. Weights (Knowledge)

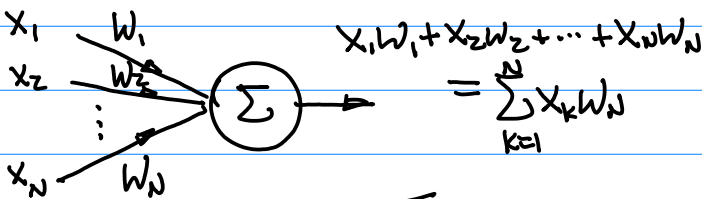


Fig 3.

$$\sum_{k=1}^N x_k w_k = x_1 w_1 + x_2 w_2 + \dots + x_N w_N \dots (1)$$

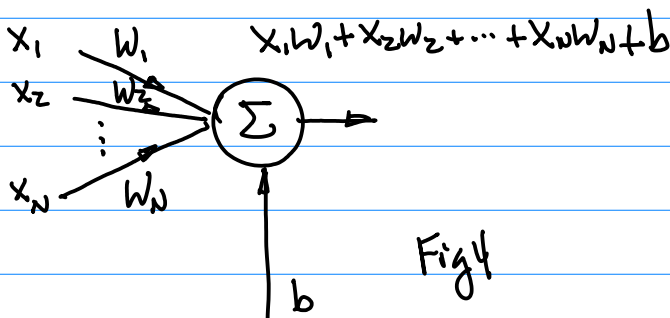


Fig 4

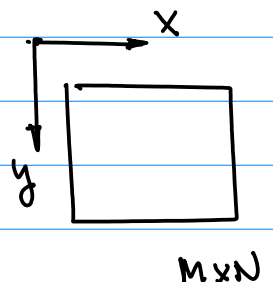
$$\sum_{k=1}^N x_k w_k = x_1 w_1 + x_2 w_2 + \dots + x_N w_N + \underline{b} \dots (1b)$$

Note: Activation function f , denoted as $f(\cdot)$ (A function of Independent Variable " \cdot ", or A function of Input " \cdot ")

$$f(\cdot) = f(x_1 w_1 + x_2 w_2 + \dots + x_N w_N + b) \\ = f\left(\sum_{k=1}^N w_k x_k + b\right) \dots (2)$$

Summary: The output of a Single is given by Eqn (2). Where Activation function $f(\cdot)$ can take different forms, it affects the Learning, Learning Speed.

Example: Digital Image, $I(x, y)$



$I(x, y)$
 ↑
 Intensity, And/OR
 Color of An Image
 (x, y) Location of A picture
 element, "pixel"

Example: Notations & Formulation

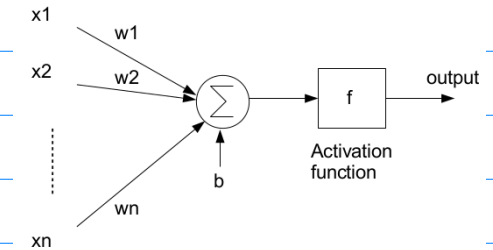


Fig.1

In Case of a Single pixel, (x, y) is
 the location of this pixel, I is
 Color/Intensity of the pixel

Note: For An Image $I(x, y)$

its features include Resolution $M \times N$

Pixel Depth:

bpp (Bit per pixel)

$I(x, y)_{max}$ OR $I(x, y)$
 1024×768
pixels/row ← Rows

For A color Image, A pixel
 depth very often is equal to 24 (bpp)

r, g, b Primitive color of red (r),
 green (g), blue (b) has
 8 bits quantization level, e.g.

r: [0, 255], g: [0, 255], b: [0, 255].

Feb 8th (Tue)

Today's Topics: 1° Introduction, Basic
 Building Blocks, Math Formulation.
 2° Sample Python Code for Opencv.

1. Notation for Input $x_i, i=1, 2, \dots, N$

$\{x_i | i=1, 2, \dots, N\}$... (1a)

Vector form,

(x_1, x_2, \dots, x_N) ... (1b)

↖ \mathbf{x}

Introduce Superscript j for
 Experiment j

Input $x_i^j, i=1, 2, \dots, N; j=1, 2, \dots, P$

Hence Eqn (1) Becomes

$\{x_i^j | i=1, 2, \dots, N; j=1, 2, \dots, P\}$

$(x_1^j, x_2^j, \dots, x_N^j)$ for Experiment j

2. Notation for Weight

w_i , for $i=1, 2, \dots, N$

hence,

(w_1, w_2, \dots, w_N) ... (2)

↖ \mathbf{w}

3. Inputs & weights

 x_i w_i $w_i x_i$ for $i=1, 2, \dots, N$

$$(x_1, x_2, \dots, x_N) \cdot (w_1, w_2, \dots, w_N)$$

$$= w_1 x_1 + w_2 x_2 + \dots + w_N x_N = \sum_{i=1}^N w_i x_i$$

$$(w_1, w_2, \dots, w_N) \cdot (x_1, x_2, \dots, x_N)$$

$$= w_1 x_1 + w_2 x_2 + \dots + w_N x_N = \sum_{i=1}^N w_i x_i$$

4. Transfer Function, Denoted as

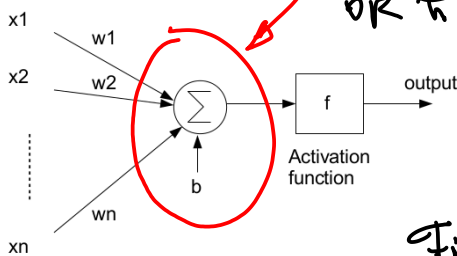
 h
OR $h(\cdot)$ 

Fig. 2

$$h = \sum_{i=1}^N w_i x_i + b = W \cdot X + b$$

Offset ("Bias")

... (3)

h , or $h(\cdot)$, or $E_{gnt}(\cdot)$, or
 $h(w_i; b)$, or $h(w_i)$

5. Activation Function. f

Acts Like a Switch, ON/OFF &
 Attenuate the Output

$$f, f\left(\sum_{i=1}^N w_i x_i + b\right), \text{ OR}$$

$$f(h(w_i; b)), \text{ OR } f(h(\cdot))$$

The output of A Neuron is
 denoted as

$$y, \text{ and } y = f\left(\sum_{i=1}^N w_i x_i + b\right)$$

$$= f(h(w_i; b)) \dots (4)$$

5. Outputs for A Neural Network

$$y_k, \text{ for } k=1, 2, \dots, Q$$

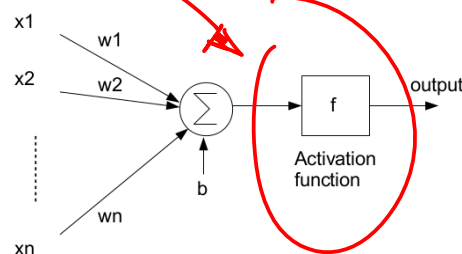
if $Q=1$, y_1 , also better to just
 y_1 for a Single Neuron as y

Question: What output? whose output?

Output from the Neuron (OR Network)

\tilde{y} (Tilde)

Ground Truth is denoted as y

6. Loss function, objective Function,
OR difference

"Supervised Learning"

For Experiment j (multiple experiments)

$$\tilde{y}^j - y^j, \quad j=1, 2, \dots, P \quad \dots (5)$$

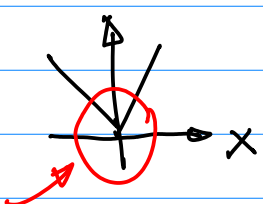
Output from the NN (Neuron or Network) Ground Truth for the experiment

for $j=1, \quad \tilde{y}^1 - y^1$
 $j=2, \quad \tilde{y}^2 - y^2$
 \vdots
 $j=P, \quad \tilde{y}^P - y^P$

Therefore, put all these differences (Loss) together

$$(\tilde{y}^1 - y^1) + (\tilde{y}^2 - y^2) + \dots + (\tilde{y}^P - y^P)$$

$$= \sum_{k=1}^P (\tilde{y}^k - y^k) \quad \dots (b)$$

Note:  $y = |x|$

To deal with the issue of Absolute Value of a function, Let's square it.

Hence Eqn (b) becomes

$$\sum_{k=1}^P (\tilde{y}^k - y^k)^2 \quad \dots (bb)$$

7. Objective function

$$L \triangleq \sum_{k=1}^P (\tilde{y}^k - y^k)^2 \quad \dots (7)$$

OR,

$$L(w_i) \triangleq \sum_{k=1}^P (\tilde{y}^k - y^k) \quad \dots (7b)$$

$$= \sum_{k=1}^P (\tilde{y}^k(h(w_i)) - y^k) \quad \dots (7c)$$

8. To generalize the result in Eqn (7c) for multiple output, we have the following formulation.

From Eqn (7)

$$\sum_{k=1}^P (\tilde{y}_{k_2}^k - y_{k_2}^k)^2$$

 k_2 : Output k_2 for multiple output

$$y_j, j=1, 2, \dots, k_2, k_2+1, \dots, M$$

We can count All outputs loss.

$$\sum_{k=1}^P (\tilde{y}_1^k - y_1^k), \sum_{k=1}^P (\tilde{y}_2^k - y_2^k), \dots$$

$$\dots \sum_{k=1}^P (\tilde{y}_M^k - y_M^k)$$

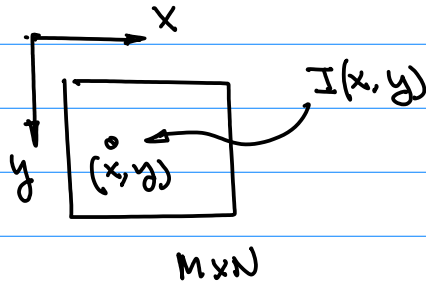
Hence

$$\sum_{k_2=1}^M \sum_{k=1}^P (\tilde{y}_{k_2}^k - y_{k_2}^k)^2 \quad \dots (8)$$

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$$L(w_i) = \frac{1}{2} \sum_{h_2=1}^m \sum_{h_1=1}^p (\tilde{y}_{h_2}^{h_1} - y_{h_2}^{h_1})^2 \dots (8b)$$

Example: Digital Image $I(x, y)$

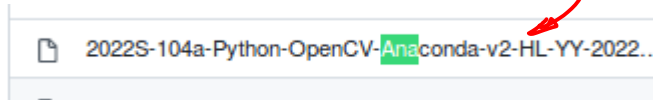


Installation of OpenCV \rightarrow Python OR
(C/C++, But Python is Better)

Different Packages
for ML/DL, may need different version
of Python, And different Packages

Anaconda is a well developed,
Adopted tool for Package management.

1. Check github class Reference



Note: For installation of Anaconda,
Check github document,
2022S-104-~

Once Anaconda is installed, then
Let's take a look the configuration for

Tensorflow & OpenCV Environment

Step 1.

Running O

Step 1. Create configuration
file .yaml for CPU and GPU
version

```
conda-cpu.yaml
1 name: yolov4-cpu
2
3 dependencies:
4   - python==3.7
5   - pip
6   - matplotlib
7   - opencv
8   - pip:
9     - opencv-python==4.1.1.26
10    - lxml
11    - tqdm
12    - tensorflow==2.3.0rc0
13    - absl-py
14    - easydict
15    - pillow
```

Name of the environment

```
17 lines (16 sloc) | 269 Bytes
1 name: yolov4-gpu
2
3 dependencies:
4   - python==3.7
5   - pip
6   - matplotlib
7   - opencv
8   - cudnn
9   - cudatoolkit==10.1.243
10  - pip:
11    - tensorflow-gpu==2.3.0rc0
12    - opencv-python==4.1.1.26
13    - lxml
14    - tqdm
15    - absl-py
16    - easydict
17    - pillow
```

Step 2. Create the environment

Step 2. Configure/create the environment in the folder you will
run your openCV program by

```
$conda env create -f conda-cpu.yaml #for CPU
$conda env create -f conda-gpu.yaml #for GPU
```

file Name to Be used

Step 3 Activate the environment

Step 4. Run Your Python Code (OpenCV or T.F.)

Running OpenCV with Conda Environment

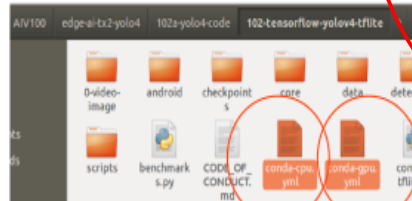
Step 1. Create configuration file .yaml for CPU and GPU version

```
conda-cpu.yaml
1 name: yolov4-cpu
2
3 dependencies:
4 - python==3.7
5 - pip
6 - matplotlib
7 - opencv
8 - pip:
9 - opencv-python==4.1.1.26
10 - lxml
11 - tqdm
12 - tensorflow==2.3.0rc0
13 - absl-py
14 - easydict
15 - pillow
```

```
conda-cpu.yaml
name: yolov4-cpu

dependencies:
- python==3.7
- pip
- matplotlib
- opencv
- pip:
- opencv-python==4.1.1.26
- lxml
- tqdm
- tensorflow==2.3.0rc0
- absl-py
- easydict
- pillow
```

Name of the environment to be created



```
conda-gpu.yaml
1 name: yolov4-gpu
2
3 dependencies:
4 - python==3.7
5 - pip
6 - matplotlib
7 - opencv
8 - cudnn
9 - cudatoolkit==10.1.243
10 - pip:
11 - tensorflow-gpu==2.3.0rc0
12 - opencv-python==4.1.1.26
13 - lxml
14 - tqdm
15 - absl-py
16 - easydict
17 - pillow
```

Step 2. Configure/create the environment in the folder you will run your openCV program by

```
$conda env create -f conda-cpu.yaml #for CPU
$conda env create -f conda-gpu.yaml #for GPU
```

Step 3. Activate the environment with the name that you have created by

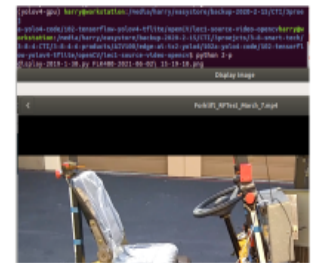
```
$ conda activate yolov4-cpu #for CPU
$ conda activate yolov4-gpu #for GPU
```

Name of the environment in the .yaml file

```
V100/edge-ai-tx2-yolo4/102a-yolo4-code/102-tensorflow-yolo4-tfutils$ conda activate yolov4-gpu
(yolov4-gpu) harry@workstation: /media/harry/easystore/backup-2020-2-15/CTI/3projects/3-8-smart-V100/edge-ai-tx2-yolo4/102a-yolo4-code/102-tensorflow-yolo4-tfutils$
```

Step 4. Now run your Python OpenCV program

\$python myOpenCV.py image.png



Note: Install Anaconda → Create the environment for T.F. & OpenCV

Execute OpenCV → Activate the environment
Sample Code (From the class github)

2022S-104d-#2-pdisplay-2019-1-30.py

a. Program Header

```
1 """
2 pdisplay.py
3 Demo read and display image
4 """
```

b. cv2 OpenCV

```
5 import sys
6 import cv2
7 import numpy as np
8
9 #main(sys.argv[1:])
10 window_name = 'Display Image'
11
12 imageName = sys.argv[1] #get file name from command line
13
14 src = cv2.imread(imageName, cv2.IMREAD_COLOR)
15
16 if src is None:
17     print ('Error opening image!')
18     print ('Usage: pdisplay.py image_name\n')
19
```

Caption of the window

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2nd Ref on the github

9

2022S-103a-notation-neuro-loss-function-2022-2-8-1.pdf

```
22 while True: ③
23     cv2.imshow(window_name, src)
24
25     c = cv2.waitKey(500)
26     if c == 27: #ESC ← Keyboard input
27         break
28
29     ind += 1
```

Keyboard input to exit.

VIII. MINIMIZE THE LOSS FUNCTION

$$\frac{\partial L}{\partial w_{i,k}} = \frac{\partial}{\partial w_{i,k}} \frac{1}{2} \sum_{j=1}^P \sum_{i=1}^M (\hat{y}_i^j - y_i^j)^2 \quad (24)$$

Now, consider to Optimize Neural Network Performance By minimizing the Loss function.

Mathematical Background

Derivatives → Partial Derivatives

a.

c. Gradient

A special Kind of Gradient. Descent d. To Reduce Loss

"Steepest" ~

Training A Neural Network

Generalize the concept "Learning" (Supervised Learning)

Derivatives.

Definition $\frac{d}{dx} f(x) \triangleq \lim_{\Delta x \rightarrow 0} \frac{\Delta f}{\Delta x}$

$$= \frac{f(x+\Delta x) - f(x)}{\Delta x} \Big|_{\Delta x \rightarrow 0} \quad \dots (1)$$

Note Eqn(1) is Based on "Forward Difference".

$f(x+\Delta x)$
↑
forward of x

Note: These Python functions are required. (memorize them!)

① import cv2 ② cv2.imread()

③ cv2.imshow().

Homework (Due A week from today)
Feb 15

1° Installation of OpenCV.

2° Installation of Anaconda.

3° Use your Smartphone to take photo, and save it for OpenCV Program

4° Write A Python Program (Ref. Code from the class github is ok)

to Display:

a. Your Name + SID (4 Digits)

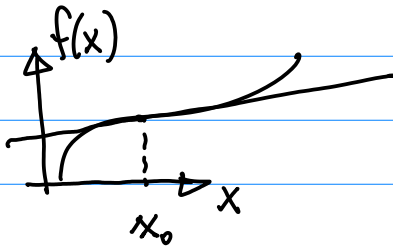
b. Your Smartphone picture.

5° Submission: One pdf file And Zipred. On CANVAS.

Feb 15

Ref: 1° 2022S-103a-Notation

2° 2022S-103C



if $f'(x) = \frac{d}{dx} f(x) > 0$, then $f(x)$ at $x = x_0$ will increase

if $f'(x) < 0$, then $f(x)$ will decrease

if $f'(x) = 0$, then $f(x)$ is unchanged.

For a function $f(x_1, x_2)$, the partial Derivative of $f(x_1, x_2)$

$$\frac{\partial f}{\partial x_1}, \frac{\partial f}{\partial x_2} \dots (2)$$

$$\frac{\partial f(x_1, x_2)}{\partial x_1} \triangleq \lim_{\Delta x_1 \rightarrow 0} \frac{f(x_1 + \Delta x_1, x_2) - f(x_1, x_2)}{\Delta x_1} \dots (2a)$$

$$\frac{\partial f(x_1, x_2)}{\partial x_2} \triangleq \lim_{\Delta x_2 \rightarrow 0} \frac{f(x_1, x_2 + \Delta x_2) - f(x_1, x_2)}{\Delta x_2} \dots (2b)$$

$$\frac{\partial f}{\partial x_1} > 0, f \uparrow \text{ as } x_1 \uparrow$$

$$\frac{\partial f}{\partial x_2} > 0, f \uparrow, \text{ as } x_2 \uparrow$$

Define gradient of a function $f(x_1, x_2)$

(Note: Connection to Neural Network, And a Single Neuron. inputs x_1, x_2, \dots, x_n And weights w_1, w_2, \dots, w_n)

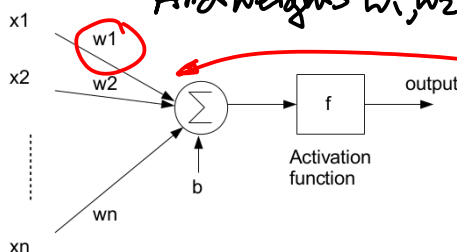


Fig 1.

Defined a vector

$$\begin{pmatrix} \frac{\partial f(x_1, x_2)}{\partial x_1} \\ \frac{\partial f(x_1, x_2)}{\partial x_2} \end{pmatrix} \text{ or } \begin{pmatrix} \frac{\partial f}{\partial x_1} \\ \frac{\partial f}{\partial x_2} \end{pmatrix}$$

We can use github Lecture ... (3)

Notes to expand Eqn (3) to N-Dimensional Case

$$\nabla f = \begin{bmatrix} \frac{\partial f}{\partial x_1} \\ \frac{\partial f}{\partial x_2} \\ \vdots \\ \frac{\partial f}{\partial x_n} \end{bmatrix} \dots (3b)$$

For A Single Neuron, we have gradient function as follows.

$$\nabla f = \begin{bmatrix} \frac{\partial f}{\partial w_1} \\ \frac{\partial f}{\partial w_2} \\ \vdots \\ \frac{\partial f}{\partial w_n} \end{bmatrix} \dots (3c)$$

Guideline for the Development of "Training" Technique :

Negative Gradient gives the Steepest Descent of a loss function f .

Note: Negative gradient gives the Best way to adjust w_i in a Neural Net

to make the Neural Net to
Reach to optimal solution.
e.g. minimized loss function.

The Approach to verify the
Above Technique:

Generalized loss function, as f , or
 $f(\cdot)$, or $f(x_1, x_2, \dots, x_n)$, or
 $f(\mathbf{X})$, or $f(w_1, w_2, \dots, w_n)$, or
 $f(w)$

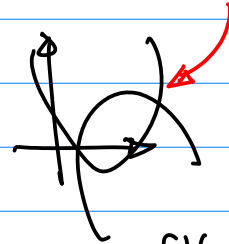
Simple/Generalized Descriptor
to connect independent Variable
 x_1, x_2, \dots, x_n (or w_1, w_2, \dots, w_n) to the function f (loss
function)

Taylor Expansion for $f(x)$

$$f(x) = f(x_0) + \frac{f'(x_0)}{1!}(x-x_0) + \frac{f''(x_0)}{2!}(x-x_0)^2 + \dots + \frac{f^{(k)}(x_0)}{k!}(x-x_0)^k + \dots \quad (4)$$

\Rightarrow Constant + 2nd (Linear function) +

$$\frac{f''(x_0)}{2!}(x-x_0)^2 \text{ Quadratic Term.}$$



$$f(x) = f(x_0) + \frac{f'(x_0)}{1!}(x-x_0) + R_n(x)$$

Higher Order Terms

$$f(x) \approx f(x_0) + \frac{f'(x_0)}{1!}(x-x_0)$$

Linear function

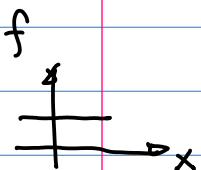
$$f(x) = f(x_0) + \frac{f'(x_0)}{1!} \Delta x \quad \dots (5)$$

We expand function f (loss) into
multi-dimensional case, e.g. x_1, x_2, \dots
(or w_1, w_2, \dots).

Choose work on 2D case. e.g.

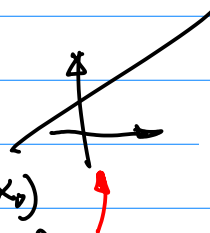
$$f(x_1, x_2) = f(x_{10}, x_{20}) + \frac{\partial f}{\partial x_1}(x-x_{10}) + \frac{\partial f}{\partial x_2}(x-x_{20}) + \dots \quad (6)$$

$$f(x_1, x_2) \approx f(x_{10}, x_{20}) + \frac{\partial f}{\partial x_1}(x-x_{10}) + \frac{\partial f}{\partial x_2}(x-x_{20}) \quad \dots (7)$$



$$\frac{f'(x_0)}{1!}(x-x_0)$$

Coefficient, Slope. $a(x-x_0)$
 $y = ax + b$ Linear function



$$f(x_1, x_2) \approx f(a, b) + \frac{\partial f}{\partial x_1}(x_1 - a) + \frac{\partial f}{\partial x_2}(x_2 - b) \quad (6)$$

Question, if we change independent Variable x_1 and x_2 by the negative gradient of f , then the function f is decreased or increased?

Based on the Theory, we should have loss function f decreased in an optimized way, e.g., "Steepest Descent."

$$(x_1^{k+1}, x_2^{k+1}) = (x_1^k, x_2^k) + [-\eta(\nabla f)^T] \quad (5)$$

$$\nabla f = \begin{pmatrix} \frac{\partial f}{\partial x_1} \\ \frac{\partial f}{\partial x_2} \end{pmatrix}$$

$$(\nabla f)^T = \left(\frac{\partial f}{\partial x_1}, \frac{\partial f}{\partial x_2} \right)$$

Step @ $k+1$ at step k

$$\begin{cases} x_1^{k+1} = x_1^k + (-\eta) \frac{\partial f}{\partial x_1} & \dots (8a) \\ x_2^{k+1} = x_2^k + (-\eta) \frac{\partial f}{\partial x_2} & \dots (8b) \end{cases}$$

If we use Eqn (8a), (8b) to update the independent Variables x_1, x_2 (or weights w_1, w_2), then you are sure to be able to find loss function f at this step $k+1$, is smaller than itself, e.g. f function at step k .

$$f(x_1, x_2) - f(a, b) = (x_1 - a, x_2 - b) \nabla f \quad (10)$$

The Above equation, eqn (10), is Taylor Expansion

Note: from the Analysis below, we have:

$$f(x_1, x_2) - f(a, b) = (\Delta x_1, \Delta x_2) \nabla f = -(\Delta x_1^2 + \Delta x_2^2) \quad (12)$$

$$f_{x_1} = \frac{\partial f}{\partial x_1}$$

$$f_{x_1}^2 = \left(\frac{\partial f}{\partial x_1} \right)^2 \geq 0$$

Similarly $f_{x_2} = \frac{\partial f}{\partial x_2}$, $f_{x_2}^2 = \left(\frac{\partial f}{\partial x_2} \right)^2 \geq 0$

Therefore $\left[\left(\frac{\partial f}{\partial x_1} \right)^2 + \left(\frac{\partial f}{\partial x_2} \right)^2 \right] \leq 0$

Hence $f(x_1, x_2) - f(a, b) \leq 0$

$$f(x_1, x_2) \leq f(a, b) //$$

$$x_1 - a = -\eta \frac{\partial f}{\partial x_1}$$

$$x_1^{k+1} - x_1^k = -\eta \frac{\partial f}{\partial x_1}$$

$$f(x_1, x_2) - f(a, b) = \frac{\partial f}{\partial x_1} (x_1 - a) + \frac{\partial f}{\partial x_2} (x_2 - b)$$

$$x_1^k = a, x_2^k = b \quad f(a, b)$$

$$f(x_1, x_2) \approx f(x_{10}, x_{20}) + \frac{\partial f}{\partial x_1} (x - x_{10}) +$$

$$\frac{\partial f}{\partial x_2} (x - x_{20}) \quad \text{Eqn (7) PP. 11}$$

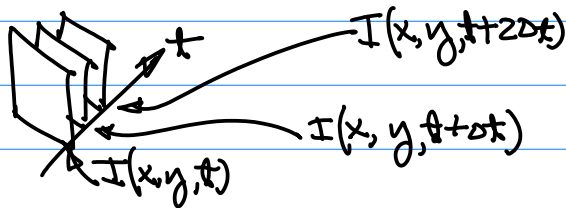
OpenCV

Note: One of the tools for Python

Programming for this class
is Pycharm.

Create A New Project \rightarrow Configuration
of the environment
& packages needed

Example: OpenCV for Video.



Exercise Use your Smartphone to
Capture a video clip which
has the following Feature:

1. White Background, Such as
Printer Paper or white Board,
then, write your last 4 Digits
on this white Background Paper/Board.
2. Be sure to use a marker to give
adequate contrast and width for
each mark. (720P or 1080P Resolution)
3. Save the video (may have 20 or 60
seconds video clip) for the future
use By Next Lecture.

Note: We will discuss Computer
Vision preprocessing techniques
in the next Lecture.