

Epistemic Action Logic

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February 11, 2022

Epistemic Action Logic

- ▶ Epistemic Action Logic (EAL) is a kind of dynamic epistemic logic to describe updating agents' epistemic states.
- ▶ An action are described by an action model, which is a structure of the action.
- ▶ An action model makes it possible to treat more complex communicative actions than PAL.

Example: Misleading Private Announcement

Example 1

Agent a is secretly informed that p is true, but the other agents misunderstand that a secretly received the information that p is false.

- ▶ Let \mathcal{P} be a set of atomic propositions, and \mathcal{G} be a set of agents. The language \mathcal{L} of EAL is the set of formulas generated by the following grammar:

$$\mathcal{L} \ni \varphi ::= p \mid \neg\varphi \mid \varphi \wedge \varphi \mid K_i\varphi \mid [A, e]\varphi,$$

where $p \in \mathcal{P}$, $i \in \mathcal{G}$, and (A, e) is a pointed action model with

- (1) a finite domain E , and
- (2) for all $e \in E$, $\text{pre}(e)$ is in \mathcal{L} that is already constructed in the previous stage of the inductively defined hierarchy.

Other connectives \vee , \rightarrow , and \leftrightarrow are defined in the usual manner.

- ▶ A Kripke model and an action model give semantics.
- ▶ A Kripke model is a tuple $\langle W, \{R_i\}_{i \in \mathcal{G}}, V \rangle$ where a non-empty set of possible worlds W , an accessibility relation R on W , and a valuation V .

Action Model

Definition 1

An action model is a tuple $A = \langle E, \{R_i\}_{i \in \mathcal{G}}, \text{pre} \rangle$, where:

- E is a non-empty finite set of possible communicative events;*
- R_i is a binary possibility relation on E ;*
- $\text{pre} : E \rightarrow \mathcal{L}$ is a function that assigns a precondition to each event.*

- ▶ A pair (A, e) is called a pointed action model. It refers to an action itself.
- ▶ $\{E, \{R_i\}_{i \in \mathcal{G}}, \text{pre}\}$ in A is denoted by $\{E^A, \{R_i^A\}_{i \in \mathcal{G}}, \text{pre}^A\}$.

Satisfaction Relation

Definition 2

For any Kripke model M and possible worlds $w \in W$, the satisfaction relation \models is given as follows:

$$M, w \models p :\Leftrightarrow w \in V(p);$$

$$M, w \models \neg\varphi :\Leftrightarrow M, w \not\models \varphi;$$

$$M, w \models \varphi \wedge \psi :\Leftrightarrow M, w \models \varphi \text{ and } M, w \models \psi;$$

$$M, w \models K_i\varphi :\Leftrightarrow \text{for all } v \text{ such that } (w, v) \in R_i, M, v \models \varphi;$$

$$M, w \models [A, e]\varphi :\Leftrightarrow (M, w \models \text{pre}^A(e) \Rightarrow M[A], (w, e) \models \varphi).$$

Product Update

Definition 3

The Kripke model $M[A] = \langle W', \{R'_i\}_{i \in \mathcal{P}}, V' \rangle$ via the product update operation is defined as follows:

- $W' := \{(w, e) \in W \times E \mid M, w \models \text{pre}^A(e)\};$
- $((w, e), (w', e')) \in R'_i :\Leftrightarrow (w, w') \in R_i \text{ and } ((e, e')) \in R_i^A;$
- $V'(p) := V(p) \times E.$

Representation of the Example

Example 1

Agent a is secretly informed that p is true, but the other agents misunderstand that a secretly received the information that p is false.

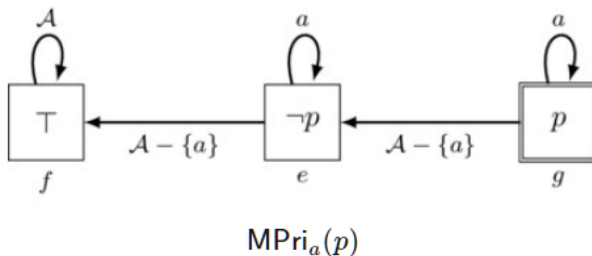


Figure: The pointed action model $(\text{MPri}_a(p), g)$ (Baltag and Renne, 2016).

Proof System **EAL**

Table: Axiom schemas and inference rules of **EAL**.

Axiom schemas			
TAUT	The set of propositional tautologies	AK	$[A, e]K_i\varphi \leftrightarrow (\text{pre}(e) \rightarrow \bigwedge_{(e,f) \in R_i^A} K_i[A, f]\varphi)$
K	$K_i(\varphi \rightarrow \psi) \rightarrow (K_i\varphi \rightarrow K_i\psi)$	ACM	$[A, e][B, f]\varphi \leftrightarrow [(A, e); (B, f)]\varphi$
T	$K_i\varphi \rightarrow \varphi$	Inference rules	
5	$\neg K_i\varphi \rightarrow K_i\neg K_i\varphi$	MP	If $\vdash \varphi$ and $\vdash \varphi \rightarrow \psi$, then $\vdash \psi$
AP	$[A, e]p \leftrightarrow (\text{pre}(e) \rightarrow p)$	KG	If $\vdash \varphi$ then $\vdash K_i\varphi$
AN	$[A, e]\neg\varphi \leftrightarrow (\text{pre}(e) \rightarrow \neg[A, e]\varphi)$	AG	If $\vdash \varphi$ then $\vdash [A, e]\varphi$
ACN	$[A, e](\varphi \wedge \psi) \leftrightarrow ([A, e]\varphi \wedge [A, e]\psi)$		

- [1] A. Baltag and B. Renne. (2016). Dynamic epistemic logic.
<https://plato.stanford.edu/entries/dynamic-epistemic>.
- [2] Hans Van Ditmarsch, Wiebe van Der Hoek, and Barteld Kooi. (2007). *Dynamic epistemic logic*. Springer Science & Business Media.