## **Image Processing**

# Project Documentation

**Project Name** 

Secure Door

**Project Group** 

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Algorithm 1	Algorithm2
It is built using open cv and numpy modules	Built using face_recognition module
Accuracy less than 75%	High accuracy reaches 95%
Longer, a little bit more complicated and a bit faster	Shorter, less complicated and a little bit slower
The module used doesn't contain deep learning in its implementation,a training code is needed	The module used contains deep learning in its implementation
Source: https://docs.opencv.org/2.4/modules/contrib/doc/facerec/facerec api.html	Source: <a href="https://pypi.org/project/face_recognition/">https://pypi.org/project/face_recognition/</a>

### Algorithms implementation:

#### 1.1.1 Algorithm 1

#### 1.1.1.1 Training code:

```
    import cv2

2. import os
3. import numpy as np
4. from PIL import Image
5. import pickle
6.
7. BASE_DIR = os.path.dirname(os.path.abspath(__file__))
8. #print(BASE_DIR)
9. image_dir = os.path.join(BASE_DIR, "images")
10. #print(image_dir)
11.
12. face_cascade = cv2.CascadeClassifier('cascades/data/haarcascade_frontalface_
    alt2.xml')
13. #print (face_cascade)
14. recognizer = cv2.face.LBPHFaceRecognizer_create()
15.
16. current id = 0
17. label_ids = {}
18. y_labels = []
19. x_train = []
20.
21. for root, dirs, files in os.walk(image_dir):
     for file in files:
22.
23.
           # print ("1")
            if file.endswith("png") or file.endswith("JPG") or file.endswith("jp
24.
    g"):
25.
                #print("0")
26.
                path = os.path.join(root, file)
27.
                label = os.path.basename(root).replace(" ", "-").lower()
28.
                #print(label, path)
29.
                if not label in label ids:
30.
                    label_ids[label] = current_id
                    current id += 1
31.
32.
                    id = label ids[label]
                    print("id_", id_)
33.
34.
                    #y_labels.append(label) # some number
35.
                    #x train.append(path) # verify this image, turn into a NUMPY
     arrray, GRAY
36.
                    pil_image = Image.open(path).convert("L") # grayscale
37.
                    size = (550, 550)
38.
                    final_image = pil_image.resize(size, Image.ANTIALIAS)
39.
                    image_array = np.array(final_image, "uint8")
40.
                    print(len(image_array))
```

```
41
                    faces = face_cascade.detectMultiScale(image_array, scaleFact
   or=1.5, minNeighbors=5)
42.
                    print(len(faces))
43.
                    for (x,y,w,h) in faces:
44
                            roi = image_array[y:y+h, x:x+w]
45.
                            x_train.append(roi)
                            y labels.append(id )
46.
47.
48.
49. print("y_labels",y_labels)
50. print("x train", x train)
52. with open("pickles/face-labels.pickle", 'wb') as f:
53.
        pickle.dump(label ids, f)
54.
55. recognizer.train(x_train, np.array(y_labels))
56. recognizer.save("recognizers/face-trainner.yml")
```

#### 1.1.1.2 Idenification code:

```
    import numpy as np

2. import cv2
import pickle
4.
5. face_cascade = cv2.CascadeClassifier('cascades/data/haarcascade_frontalface
    alt2.xml')
6. eye_cascade = cv2.CascadeClassifier('cascades/data/haarcascade_eye.xml')
7. smile cascade = cv2.CascadeClassifier('cascades/data/haarcascade smile.xml')
8. recognizer = cv2.face.LBPHFaceRecognizer_create()
9. recognizer.read("./recognizers/face-trainner.yml")
10.
11. labels = {"person_name": 1}
12. with open("pickles/face-labels.pickle", 'rb') as f:
13.
        og_labels = pickle.load(f)
14.
        labels = {v:k for k,v in og_labels.items()}
15.
16. cap = cv2.VideoCapture(0)
17.
18. while(True):
19.
        # Capture frame-by-frame
20
        ret, frame = cap.read()
        gray = cv2.cvtColor(frame, cv2.COLOR_BGR2GRAY)
21.
22.
        faces = face_cascade.detectMultiScale(gray, scaleFactor=1.5, minNeighbor
    s=5)
23.
        for (x, y, w, h) in faces:
24.
            #print(x,y,w,h)
25.
            roi_gray = gray[y:y+h, x:x+w] #(ycord_start, ycord_end)
            roi color = frame[y:y+h, x:x+w]
26.
27.
            # recognize? deep learned model predict keras tensorflow pytorch sci
28.
    kit learn
29.
            id_, conf = recognizer.predict(roi_gray)
            if conf>=4:# and conf <= 85:</pre>
30.
                print(id_)
31.
32.
                print(labels[id_])
33.
                font = cv2.FONT_HERSHEY_SIMPLEX
34.
                name = labels[id_]
35.
                color = (0, 0, 0)
36.
                stroke = 2
37.
                cv2.putText(frame, name, (x,y), font, 1, color, stroke, cv2.LINE
    AA)
38.
```

```
39.
            img_item = "7.png"
            cv2.imwrite(img_item, roi_color)
40.
41.
            color = (255, 0, 0) #BGR 0-255
42.
43.
            stroke = 2
            end\_cord\_x = x + w
44.
45.
            end\_cord\_y = y + h
46.
            cv2.rectangle(frame, (x, y), (end_cord_x, end_cord_y), color, stroke
47.
            #subitems = smile cascade.detectMultiScale(roi gray)
            #for (ex,ey,ew,eh) in subitems:
48.
49.
                cv2.rectangle(roi color,(ex,ey),(ex+ew,ey+eh),(0,255,0),2)
50.
        # Display the resulting frame
51.
        cv2.imshow('frame',frame)
52.
        if cv2.waitKey(20) & 0xFF == ord('q'):
53.
54.
55. # When everything done, release the capture
56. cap.release()
57. cv2.destroyAllWindows()
```

#### 1.1.2 Algorithm 2:

```
1. import cv2

    import face_recognition
    import time

4. import serial
5.
6. #establish connection with arduino on port COM4
7. arduino = serial.Serial('COM4', 9600)
8. time.sleep(2)
9. print("Connection to arduino...")
10.
                                       #training
11.
12. #reading my pic
13. person1 = face_recognition.load_image_file("C:/Users/Ebtesam/Desktop/Project
    /person1.jpg")
14. #encoding face features from my pic.
15. encoding_person1 = face_recognition.face_encodings(person1)[0]
16.
17. person2 = face recognition.load image file("C:/Users/Ebtesam/Desktop/Project
    /person2.jpg")
18. encoding person2 = face recognition.face encodings(person2)[0]
19.
20.
21. while(True):
22. # Capture frame by frame
23.
        cap = cv2.VideoCapture(0)
       ret, frame = cap.read()
24.
25.
       cv2.imshow('frame',frame)
26.
27.
        #saving a test frame
28.
       img = "test.png"
29.
        cv2.imwrite(img, frame)
30.
        #encode features of test pic.
31.
32.
        picture = face_recognition.load_image_file(img)
33.
        encoding_picture1 = face_recognition.face_encodings(picture)
34.
35.
        if len(encoding_picture1) > 0:
             encoding_picture = face_recognition.face_encodings(picture)[0]
36.
        else:
37.
38.
            encoding_picture = encoding_person1 + 1
39.
        #solved the problem of non-existing of any face in the frame
```

```
40. #close the door if no one is there
41.
                              #identifing
42.
       # compare features
        r = face_recognition.compare_faces([encoding_person1], encoding_picture)
43.
44.
45.
        if r[0] == True:
46.
           data = str.encode ('1')
47.
        else:
48.
            r = face_recognition.compare_faces([encoding_person2], encoding_pict
 ure)
49.
            if r[0] == True:
50.
                data = str.encode ('2')
51.
            else:
52.
                data = str.encode ('0')
53.
54.
        print (data)
55.
56.
        #sending data to arduino
57.
        arduino.write(data)
58.
59.
        #quit on pressing Q key
60.
        if cv2.waitKey(20) & 0xFF == ord('q'):
61.
62.
63. #close every thing
64. cap.release()
65. arduino.close()
66. cv2.destroyAllWindows()
```

#### Arduino code:

```
    #include<Servo.h>

2.
Servo Door;
4.
5. void setup() {
6. // put your setup code here, to run once:
Serial.begin(9600);
8. Door.attach(5); //Attach Vertical Servo to Pin 5
9
     Door.write(0);
10.}
11.
12. void loop() {
13. // put your main code here, to run repeatedly:
14. if(Serial.available() > 0) {
15.
          char data = Serial.parseInt();
16.
           Serial.print("py");
17.
       if (data == 0){
18.
       Serial.print("0");
19.
         Door.write (0);
20.
       }
21.
       else{
22.
       //if (data == 1) {
          Serial.print("1");
23.
24.
         Door.write (90);
25.
       }
26.}
27. }
```

P.S.: We used Algorithm 2 because of its high accuracy