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### Servo Motor Control Using ESP8266

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#### Virtual Pin Datastream

NAME: Servo1 ALIAS: Servo1

PIN: V0 DATA TYPE: Integer

UNITS: Degrees, °

MIN: 0 MAX: 180 DEFAULT VALUE: 0

ADVANCED SETTINGS

Cancel Create

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Region: blr1 Private Policy

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### Servo Motor Control Using ESP8266

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#### Virtual Pin Datastream

NAME: Servo2 ALIAS: Servo2

PIN: V1 DATA TYPE: Integer

UNITS: Degrees, °

MIN: 0 MAX: 180 DEFAULT VALUE: 0

ADVANCED SETTINGS

Cancel Create

Search datastream

1 Datastream

	Id	Name
	1	Servo1

New Datastream

bin Max Actions

180

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### Servo Motor Control Using ESP8266

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#### Virtual Pin Datastream

NAME: Servo Output1 ALIAS: Servo Output1

PIN: V2 DATA TYPE: Integer

UNITS: Degrees, °

MIN: 0 MAX: 180 DEFAULT VALUE: 0

ADVANCED SETTINGS

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2 Datastreams

Id	Name
1	Servo1
2	Servo2

Region: blr1 Private Policy

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### Servo Motor Control Using ESP8266

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#### Virtual Pin Datastream

NAME: Servo Output ALIAS: Servo Output

PIN: V3 DATA TYPE: Integer

UNITS: Degrees, °

MIN: 0 MAX: 180 DEFAULT VALUE: 0

ADVANCED SETTINGS

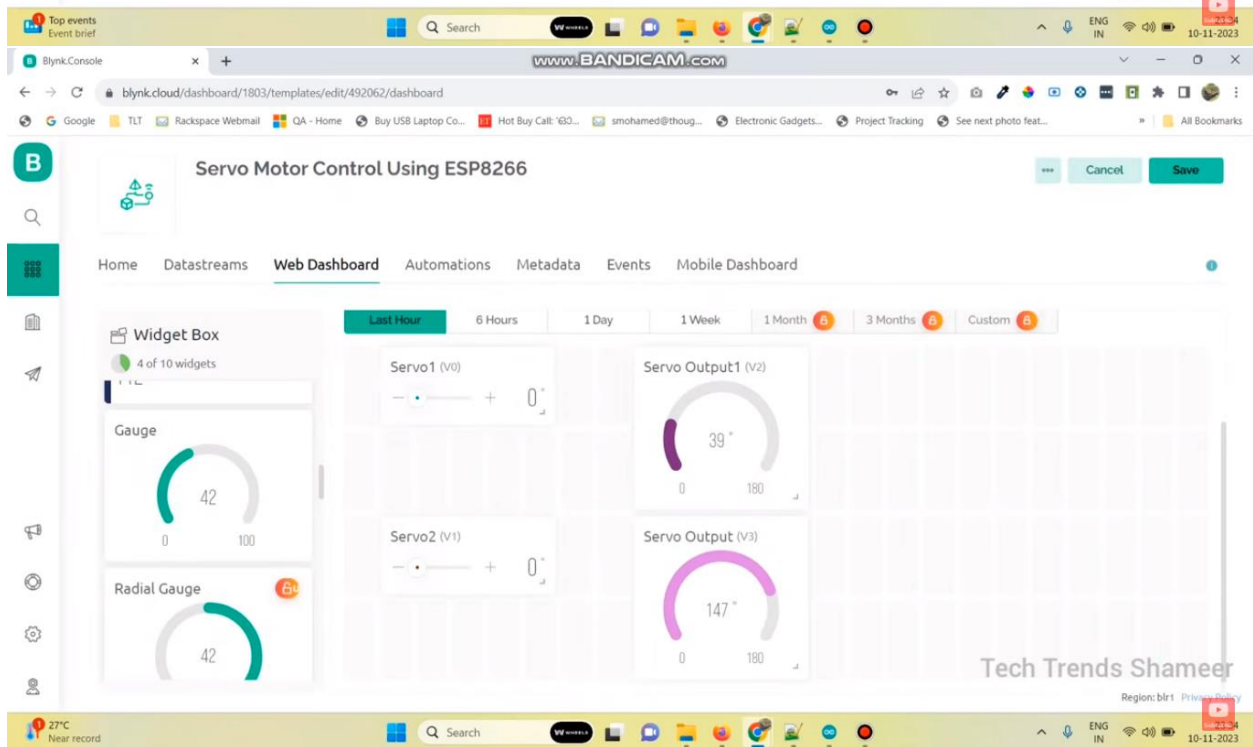
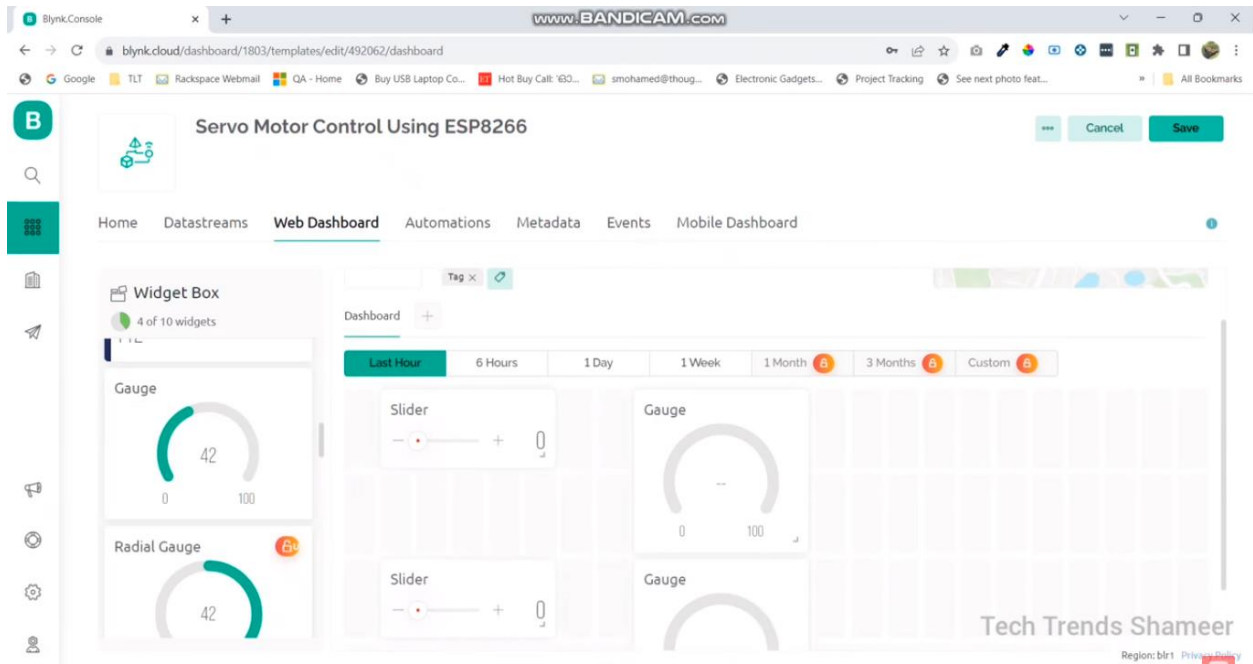
Cancel Create

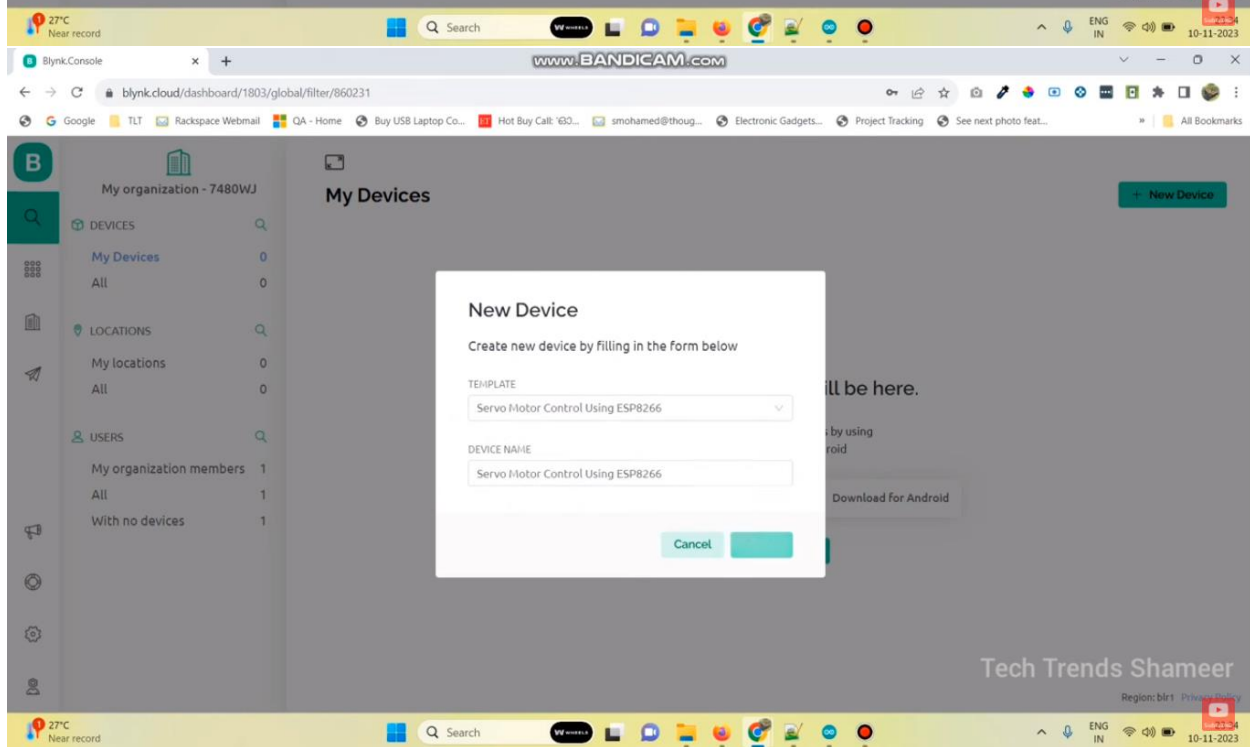
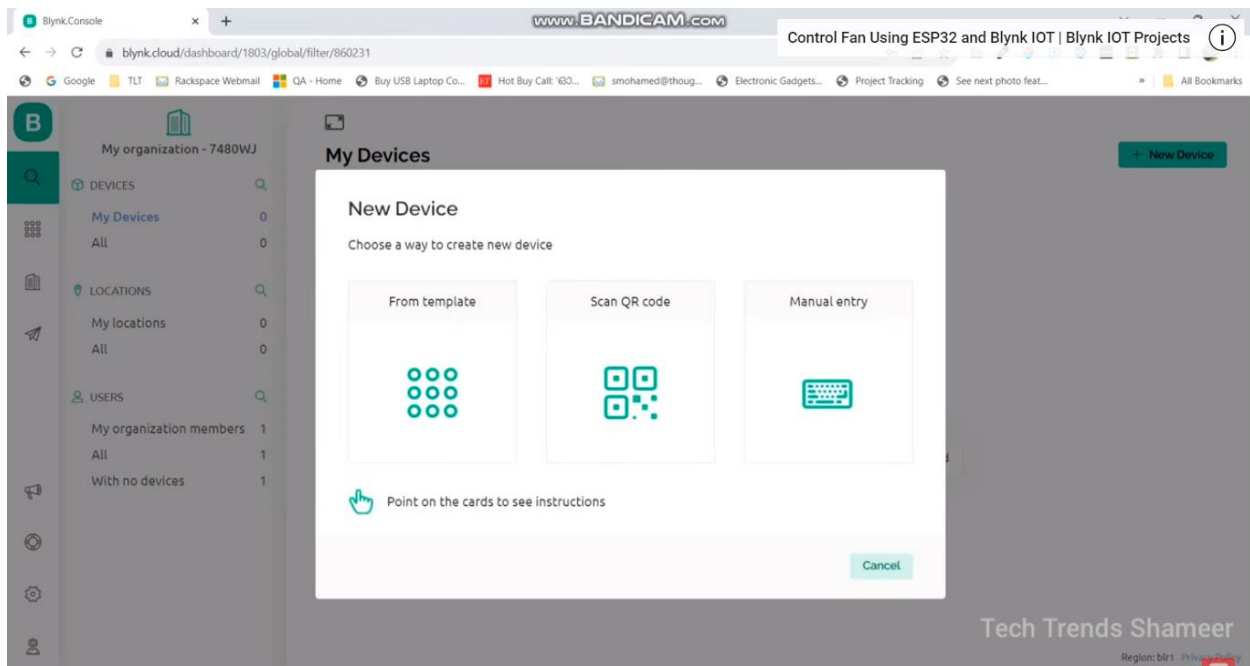
3 Datastreams

Id	Name
1	Servo1
2	Servo2
3	Servo Output1

Region: blr1 Private Policy

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How to Control Servo Motor Using Blynk IoT and ESP8266 | Servo Motor Control With Blynk

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```
#define BLYNK_TEMPLATE_ID "TMPL33_6wEqLr"
#define BLYNK_TEMPLATE_NAME "Servo Motor Control Using ESP8266"
#define BLYNK_AUTH_TOKEN
"3T3Dfts37akdFpVC2UfLTc2xKfZ1Udyb"
```

Template ID, Device Name, and AuthToken should be declared at the very top of the firmware code.

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4:17 / 6:29

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