



PIDController

- ❑ `kp_`: double
 - ❑ `ki_`: double
 - ❑ `kd_`: double
 - ❑ `prevError_`: double
 - ❑ `integral_`: double
-
- `PIDController(kp: double, ki: double, kd: double)`
 - `compute(target: double, actual: double): double`