



DEPARTMENT OF COMPUTER SCIENCE AND ENGINEERING

IV YEAR / VII SEMESTER (ODD)

BATCH: 2019-2023

ACADEMIC YEAR 2022-2023

ASSIGNMENT - IV

TEAM ID : PNT2022TMID48721

TITLE OF THE PROJECT : SIGNS WITH SMART CONNECTIVITY FOR BETTER ROAD SAFETY

DOMIN : INTERNET OF THINGS (IOT)

TEAM LEAD : AYYAPPAN S

TEAM MEMBER : VIGNESH K

TEAM MEMBER : PARTHIBAN M

TEAM MEMBER : JABAR SATHIK S

INDUSTRY MENTOR : MENTOR 11

FACULTY MENTOR(S) NAME : M GEETHAPRIYA

The screenshot displays the IBM Career Education Smart Internz portal. The browser address bar shows the URL: careereducation.smartinternz.com/Student/guided_project_workspace/43614. The page features a sidebar with navigation options: Profile, Dashboard, Projects (selected), Change Password, Support, Orientation Sessions, and Training Calendar. The main content area is titled 'Guided Project' and includes tabs for 'Project Workspace' and 'Chat with Mentor'. It displays project details: Project Title 'Signs with Smart Connectivity for Better Road Safety', Team members 'A', 'V', 'P', and 'JS', Industry Mentor 'Mentor 11', and Faculty Mentor 'M GEETHAPRIYA'. Progress indicators show 'Overall Project Progress' at 50% and 'Assigned Tasks Progress' at 50%. A 'GENERAL INSTRUCTION' section provides links for 'Git Repo', 'Project Doc', 'Demo Link', 'View Mentor Comments', 'View Industry Mentor Comments', and 'Assign Task'. A note specifies the password 'SsPuOgK' for accessing the project doc. The bottom section is divided into 'PROJECT DETAILS', 'TASK & PROGRESS', and 'MENTOR REVIEW', with the current task 'Signs With Smart Connectivity For Better Road Safety' marked as 'INTERMEDIATE'. The Windows taskbar at the bottom shows the system time as 02:40 PM on 26-10-2022.

ASSIGNMENT - IV

DISTANCE DETECTION USING ULTRASONIC SENSOR

Question-1:

Write code and connections in wokwi for ultrasonic sensor. Whenever distance is less than 100 cms send "alert" to ibm cloud and display in device recent events.

WOKWI LINK : <https://wokwi.com/projects/347552209985077842>

CODE:

```
#include <WiFi.h> //library for wifi
#include <PubSubClient.h> //library for MQTT

void callback(char* subscribetopic, byte* payload, unsigned int payloadLength);

//-----credentials of IBM Accounts-----

#define ORG "k0y7f8" //IBM ORGANITION ID
#define DEVICE_TYPE "ESP32_CONTROLLER" //Device type mentioned in ibm watson IOT Platform
#define DEVICE_ID "BME280_SENSOR" //Device ID mentioned in ibm watson IOT Platform
#define TOKEN "Md22fj*aovUH7gy60x" //Token
String data3;
float dist;

//----- Customise the above values -----
char server[] = ORG ".messaging.internetofthings.ibmcloud.com"; // Server Name
char publishTopic[] = "iot-2/evt/Data/fmt/json"; // topic name and type of event perform and format in which
data to be send
char subscribetopic[] = "iot-2/cmd/test/fmt/String"; // cmd REPRESENT command type AND COMMAND IS TEST OF
FORMAT STRING
char authMethod[] = "use-token-auth"; // authentication method
char token[] = TOKEN;
char clientId[] = "d:" ORG ":" DEVICE_TYPE ":" DEVICE_ID; //client id

//-----
WiFiClient wifiClient; // creating the instance for wificlient
PubSubClient client(server, 1883, callback, wifiClient); //calling the predefined client id by passing
parameter like server id, port and wificredential

int LED = 4;
int trig = 5;
int echo = 18;
void setup()
{
  Serial.begin(115200);
  pinMode(trig, OUTPUT);
  pinMode(echo, INPUT);
  pinMode(LED, OUTPUT);
  delay(10);
  wifiConnect();
  mqttConnect();
}
void loop() // Recursive Function
{
  digitalWrite(trig, LOW);
  digitalWrite(trig, HIGH);
  delayMicroseconds(10);
  digitalWrite(trig, LOW);
  float dur = pulseIn(echo, HIGH);
  float dist = (dur * 0.0343) / 2;
  Serial.print ("Distance in cm");
  Serial.println(dist);
```

```

PublishData(dist);
delay(1000);
if (!client.loop()) {
    mqttconnect();
}
}

/*.....retrieving to Cloud.....*/

void PublishData(float dist) {
    mqttconnect();//function call for connecting to ibm
    /*
        creating the String in in form JSON to update the data to ibm cloud
    */
    String object;
    if (dist <100)
    {
        digitalWrite(LED,HIGH);
        Serial.println("object is near");
        object = "Near";
    }
    else
    {
        digitalWrite(LED,LOW);
        Serial.println("no object found");
        object = "No";
    }

    String payload = "{\"distance\":";
    payload += dist;
    payload += "," "\"object\":";
    payload += object;
    payload += "\"}";

    Serial.print("Sending payload: ");
    Serial.println(payload);

    if (client.publish(publishTopic, (char*) payload.c_str())) {
        Serial.println("Publish ok");// if it sucessfully upload data on the cloud then it will print publish ok
in Serial monitor or else it will print publish failed
    } else {
        Serial.println("Publish failed");
    }
}

void mqttconnect() {
    if (!client.connected()) {
        Serial.print("Reconnecting client to ");
        Serial.println(server);
        while (!!!client.connect(clientId, authMethod, token)) {
            Serial.print(".");
            delay(500);
        }

        initManagedDevice();
        Serial.println();
    }
}

void wificonnect() //function defination for wificonnect
{
    Serial.println();
    Serial.print("Connecting to ");

    WiFi.begin("Wokwi-GUEST", "", 6);//passing the wifi credentials to establish the connection
    while (WiFi.status() != WL_CONNECTED) {
        delay(500);
        Serial.print(".");
    }
}

```

```

Serial.println("");
Serial.println("WiFi connected");
Serial.println("IP address: ");
Serial.println(WiFi.localIP());
}

void initManagedDevice() {
  if (client.subscribe(subscribetopic)) {
    Serial.println((subscribetopic));
    Serial.println("subscribe to cmd OK");
  } else {
    Serial.println("subscribe to cmd FAILED");
  }
}

void callback(char* subscribetopic, byte* payload, unsigned int payloadLength)
{

  Serial.print("callback invoked for topic: ");
  Serial.println(subscribetopic);
  for (int i = 0; i < payloadLength; i++) {
    //Serial.print((char)payload[i]);
    data3 += (char)payload[i];
  }

  //  Serial.println("data: "+ data3);
  //  if(data3=="Near")
  //  {
  //  Serial.println(data3);
  //  digitalWrite(LED,HIGH);

  //  }

  //  else
  //  {
  //  Serial.println(data3);
  //  digitalWrite(LED,LOW);

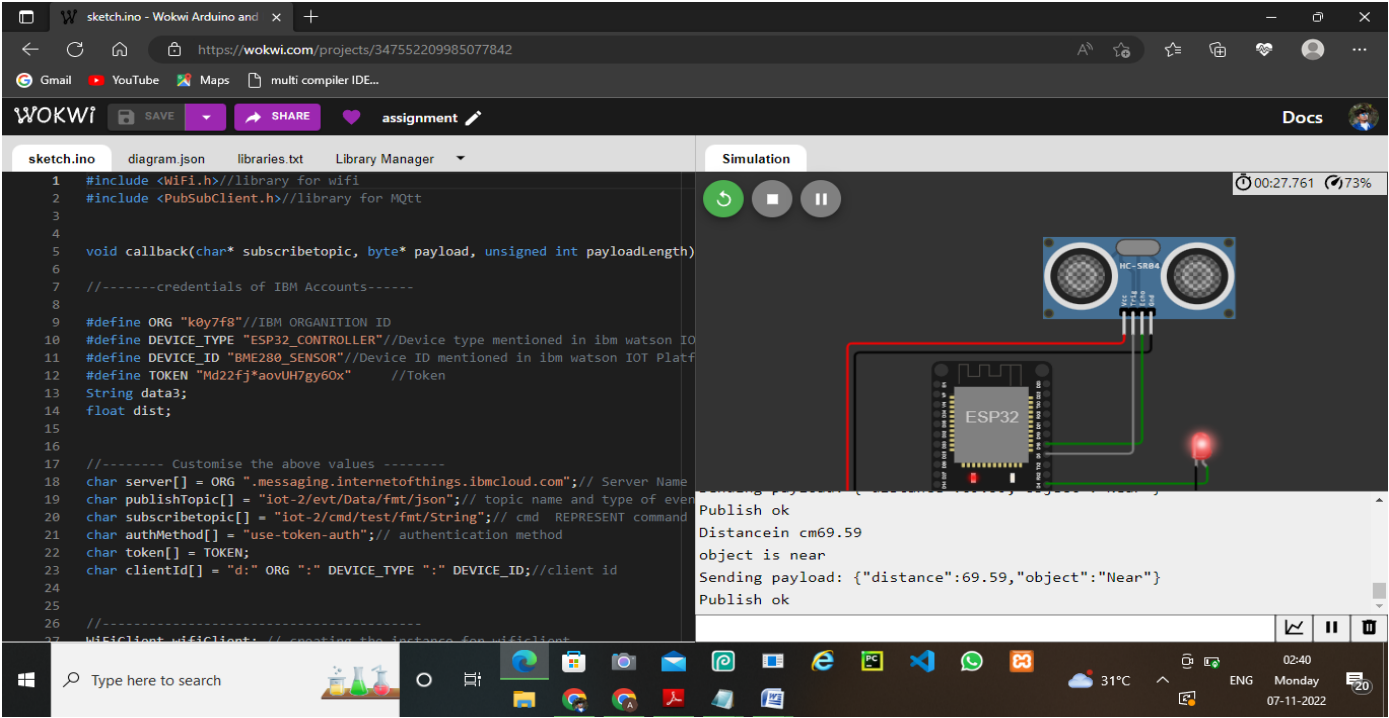
  //  }
  data3="";

}

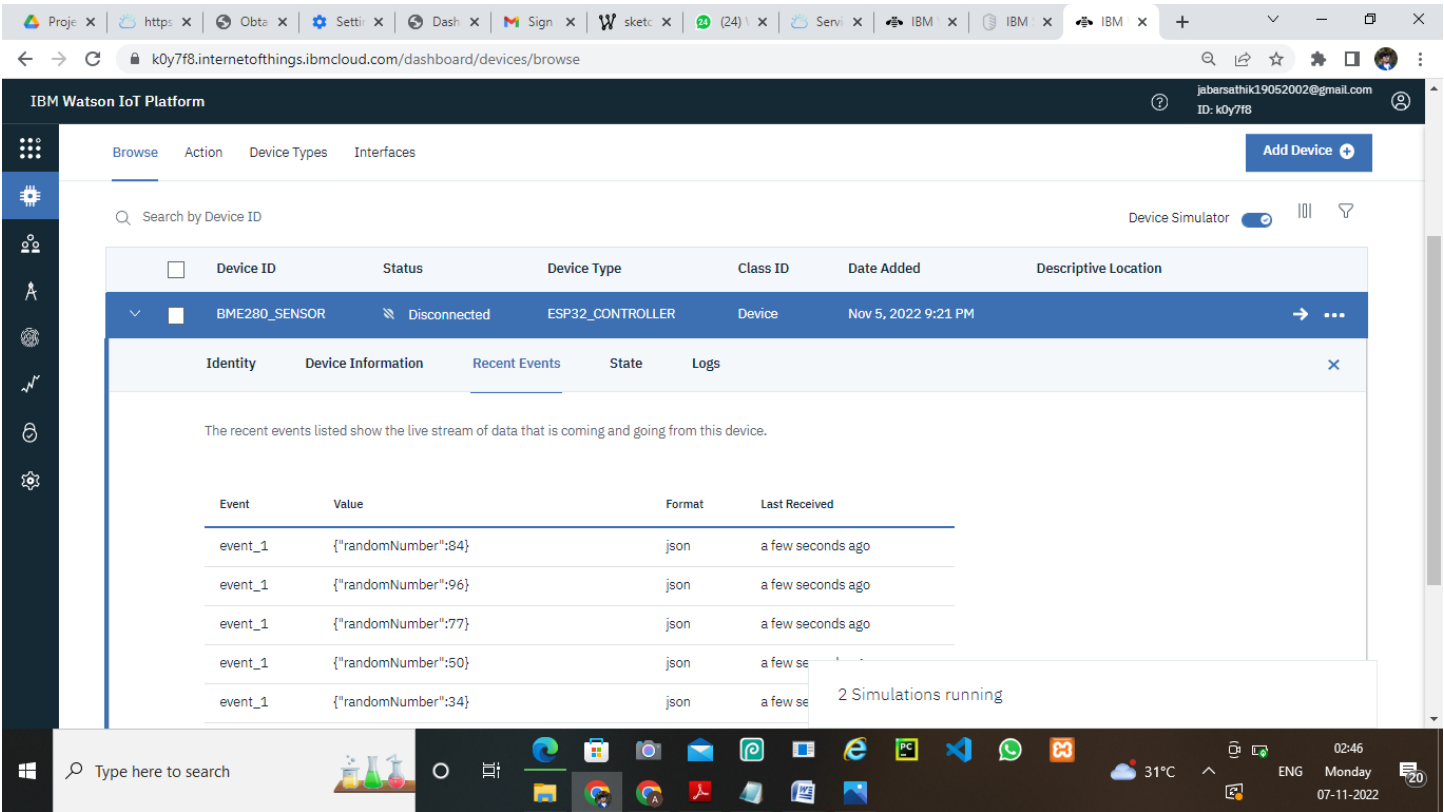
```

OUTPUT :

When object is not near to the ultrasonic sensor



Data sent to the IBM cloud device when the object is far



When object is nearer to the ultrasonic sensor

