\Downarrow

1 Motivation

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comes with instructions for android and linux. android preinstalled \downarrow
1 GHz, single-core
SOC for mm-applications
chips for decoding x264, 2d- and 3d-graphics
USB, eth, sound, HDMI, Display-Port, dev-stuff like JTAG, UART Can boot
from internal memory, or SD-card
   JWhy Do We Want This? RIOT-OS is not known for it's need to run on
phones. With i.MX6-support RIoT-OS could be used for ↓
automotive,
\downarrow
industrial,
\downarrow
handheld consoles, \downarrow
easy developement-; This often is underestimated. Most microprocessors are
painful to target for developing. The RIoTboard is aimed at developers: You can
have different programs on the board itself or on several SD-cards. Flashing can
be done to either targets via USB or directly to an SD-Card without having to
destroy the data on the partitions (after some preparation). The fully-developed
program can probably be used for any other i.MX6-board without too many
modifications, if any (maybe IOMux brrrrrrrrrr).
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2 Our original idea of how to do shit

Unitial Work-Model This was easy. Many documents. ↓

We have to documents from the manufacturer: One is a schematic and the other is specification for the hardware with instructions on flashing either the SD -card or the internal eMMC (micro-SD they forgot somehow) with ubuntu or android. Glad there were instructions for this. \downarrow

After having realised that we wouldn't be able to flash the ROM, we tried going through u-boot and loaded just a main() onto the board. \downarrow

We wanted to use u-boot but the IOMux-configuration would then have been fixed and it is usually a bad idea to change that (what RIoT would have ultimately done). Plus, the teaching staff convinced us that the i.MX6-SDK is much nicer. Somehow, we have got a working framework. \downarrow

Even though we could, in theory, start getting specific hardware to work with RIoT-OS, there is a significant problem.

3 Achievements

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\parallel The Original Plan: from the orinal slides: \downarrow
uart. erm. problems. everything set up, but no cigar
timers are running by default, but not yet usable by RIoT (or in fact: the
UART)
interrupts are enable, but no implementation for interface to RIoT
set-up stack, done (works nicely due to the SDK)
This worked after about a month
   Unfinished Work The slide should rather be called "The One Big Problem"
because there is this one thing that is really bugging us: \downarrow
We tried the default configuration from the SDK, diy-UART-init, inserted adapted
u-boot-code, tried configs for other boards and made some ourselves with the
IOMux-config-tool from the SDK which generates headers with register -definitions
and macro-implementations.
Then there is timers \downarrow
and interrupts
but with the only working debugging facilities being to LEDs, this is a rather
terrifying task
   Unterference This was initially a drawback because it took us significantly
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Unterference This was initially a drawback because it took us significantly longer to integrate the SDK than it would have with u-boot(mainly because the board- specific code from u-boot is squeezed into just 4 source-files. But after the make-process of the SDK was integrated into RIoT-OS it was really easy to adjust the start-process. So by then we were early. ↓ Nuff said on that.

4 Future Tense

∜Plans Other IOMux-confs might offer insight on what is going wrong ↓ Avoid the UART-related problems to allow getting to work on other components