## Fiducial Detection

Diane Lu

October 17, 2019

# Deformable Shape Detection

*Goal*: To detect the positions of a dense set of specific shape landmarks, or *fiducials*, in an image.











Figure 1: Shape Detection Applications

# Problems with Existing Solutions

- Require 3D database
- Find only salient landmarks



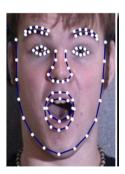


Figure 2: Only detect salient landmarks

## Proposed Method

*Goal*: To detect a dense set of salient and non-salient fiducials in an image using 2D image data set.

*Idea*: Build a probabilistic graphical model for the fiducials' positions, and then estiatme by MLE.

Reference: Benitez-Quiroz et al. (2014)

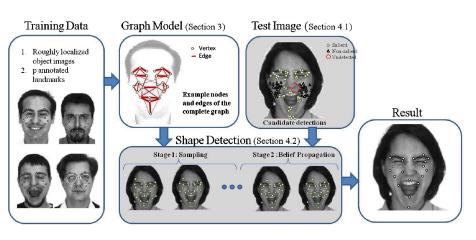


Figure 3: Worflow of the proposed method

Diane Lu Fiducial Detection October 17, 2019 5/22

# Probabilistic Graph Model

Let  $x_i$  be 2D coordinates of fiducial i with a total of p fiducials and denote a set of coordinates as  $X = (x_1, ..., x_p)$ .

$$P(X) = \frac{1}{Z} \beta(X) \prod_{i=1,j=1}^{i=p,j < i} \phi_{ij}(x_i, x_j) \prod_{k=1}^{p} \gamma_k(x_k)$$

 $\beta(X)$ : global configuration (shape)

 $\phi(.)$ : relationship between two fiducials

 $\gamma(.)$  : texture/appearance information

Z is the normalizing constant.

Diane Lu Fiducial Detection October 17, 2019

6/22

# Global Configuration

$$\beta(X) = e^{-\frac{\alpha}{2}(T(X)-\mu)^T \sum_{i=1}^{-1} (T(X)-\mu)}$$

T(X) is a normalizing transformation.

 $\mu, \sum$  are the sample mean and covariance of T(X) in the training samples.

Diane Lu Fiducial Detection October 17, 2019 7/22

# Relationship Between Two Fiducials

$$\phi_{ij}(x_i, x_i) = e^{-(1-\alpha)\overline{w}_{ij}(\Delta_{ij} - \mu_{ij})^T \sum_{ij}^{-1} (\Delta_{ij} - \mu_{ij})}$$

 $\Delta_{ij} = x_i - x_j$ : pair wise differences between fiducial i and j.

 $\alpha \in [0,1]$ : penalty of differing from mean shape.

 $\overline{w}_{ij} = \frac{1}{||\sum_{ij}||_F}$ : normalized relative importance of edges connecting fiducial i and j.

Diane Lu Fiducial Detection October 17, 2019 8/22

#### **Texture**

 $\gamma_{\it k}$  : k-th fiducial's local texture = normalized confidences of local detection.

This is needed to detect non-salient landmarks.

#### **Local Detection**

Evaluating a classifier for each fiducial at each image patch within the region expecteed tp contain the specific fiducial.

classifier: kernel Fisher discriminant analysis

Outputs a set of candidate positions  $D_i$  for each fiducial.

To be robust to occulusion,  $\tilde{D}_i = \{D_i, x_i^{MLE}\}$  where  $x_i^{MLE} = argmax_{x_i}\beta(X)\prod_{i=1}^{j< i}\phi_{ij}(x_i, x_j)$ 

# Sampling and Belief Propogation

*Problem*: Search space for maximizing P(X) might be too large.

Solution: Sampling and belief propogation

- Gibbs sampling:  $x_i^t \sim P(x_i|x_{-i}^{t-1})$  where  $x_i^0$  is initialized by a random sample from the  $\tilde{D}_i$ .
- **②** Belief propagation:  $x_i^{t'} = argmax_{x_i \in \tilde{D}_i} P(x_i | x_{-i}^{t'-1})$  where  $x^0 = argmax_{X_i^t} P(X_i^t)$

Through experiments, maxIter for t' and t is 100.

11/22

# Experiments

Face Data Set	AR	LFW	XM2VTS
Training Size (images)	448	1027	448
Testing Size (images)	448	500	350

Image size: 150x150 pixels.

Number of fiducials: 50

## Face Landmark Detection



Figure 4: Results on 3 data sets

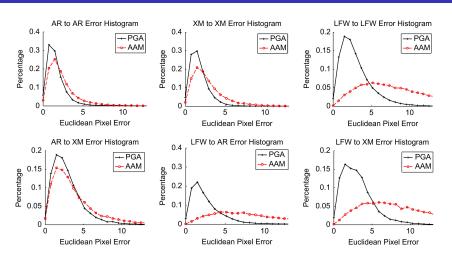


Figure 5: Error histograms. PGA is the proposed method and AAM is a method that utilizes global configuration and texture.

Diane Lu Fiducial Detection October 17, 2019 14 / 22

## Cardiac MRI

#### Data set:

160 MRI images of left-venricle from 8 subjects.

100 training images and 60 testing images.

Image size: 100x100 pixels Number of landmarks: 20

Goal: Detect contour of left-venricle.

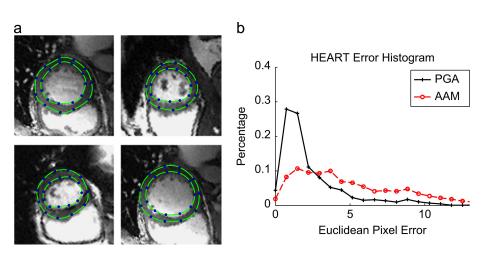


Figure 6: Heart experiment

# Hand Shapes

Data set:

40 images of 4 subjects' hands.

3-fold CV, each fold has 30 training images and 10 testing images.

Image size: 100x100 pixels

Number of landmarks: 52

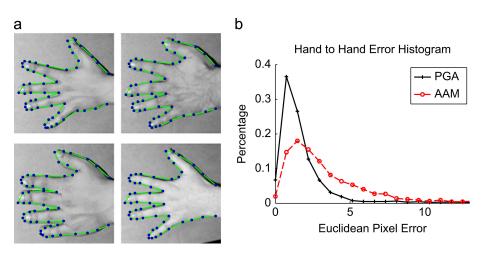


Figure 7: Hand experiment

Diane Lu Fiducial Detection October 17, 2019 18 / 22

# Inferring Additional Landmarks (Incremental Learning)

Goal: Infer m fiducials from p fiducials  $(m \gg p)$ .

*Idea*: Detected landmarks constrain the positions of undetected ones.

## Steps:

- 1. Learn the parameters for m node graph.
- 2.  $x_i^{MLE} = argmax_{x_i}\beta(X) \prod_{i=1}^{j < p} \phi_{ij}(x_i, x_j) \ \forall i \in \{p+1, ..., m\}$

Diane Lu Fiducial Detection October 17, 2019 19 / 22

# Inferring Additional Landmarks (Incremental Learning)



Figure 8: From 50 fiducials to 132 fiducials

Diane Lu Fiducial Detection October 17, 2019 20 / 22

## **Takeaway**

Exploiting the fact that each landmark positions constrains the position of otehr landmarks, a probablistic graph model is built for accurately detecting a denset set of salient and non-salient fiducials.

The face experiment shows that the algorithm can detect significant deformations of eyes and moith.

Also, the proposed method can be applied to many other fields (hand and heart experiments).

Diane Lu Fiducial Detection October 17, 2019 21 / 22

### References I

Benitez-Quiroz, Carlos F, Samuel Rivera, Paulo FU Gotardo, and Aleix M Martinez. 2014. "Salient and Non-Salient Fiducial Detection Using a Probabilistic Graphical Model." *Pattern Recognition* 47 (1). Elsevier: 208–15.