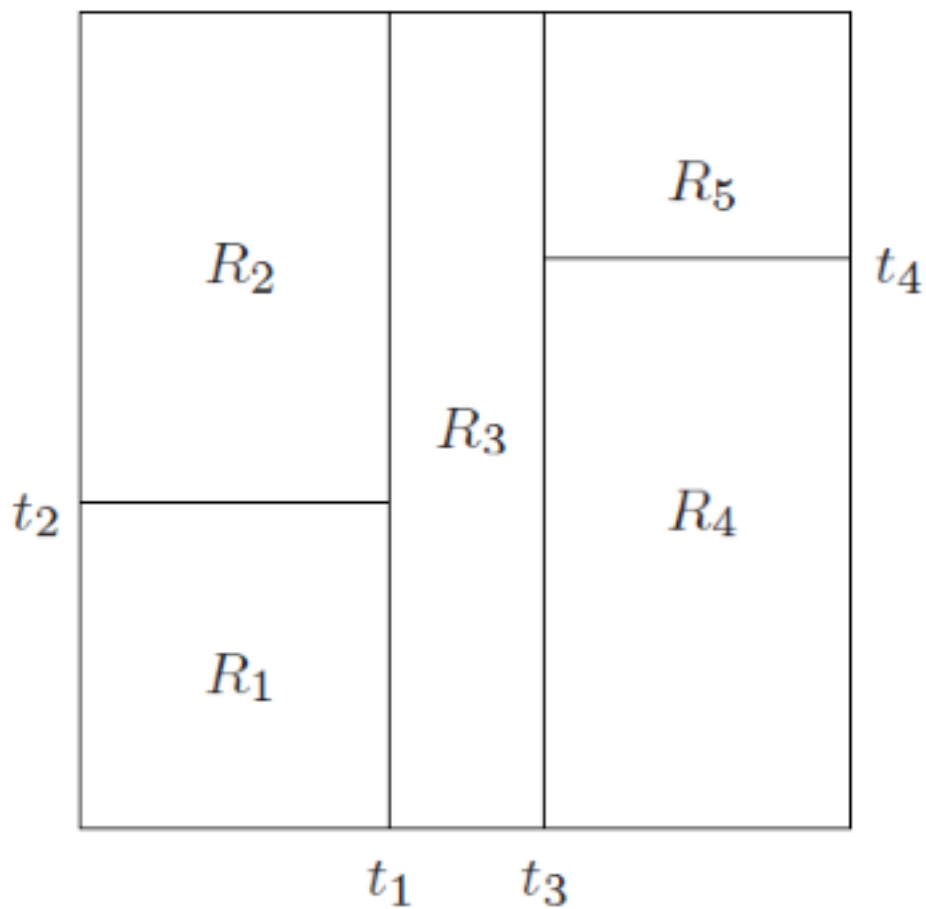
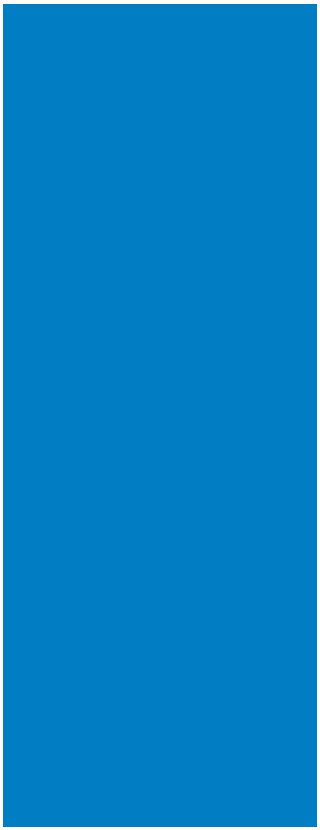
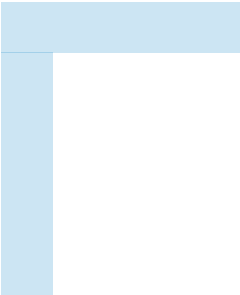
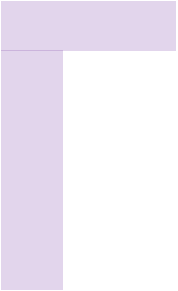


Decision Trees



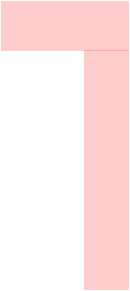






R₁

*R*₂



Hashe, Tibshirani, Friedman: Elements of Statistical Learning

- Decision tree is a recursive partition of the input space
- Most are *binary*













Hashe, Tibshirani, Friedman. Elements of Statistical Learning

Decision Tree Algorithms

- Breaks sample data into homogenous pieces
 - Sample means
- Handles categorical and continuous data
- Identifies interaction effects and important variables
- Has multiple algorithms
 - ID3
 - C4.5
 - CHAID

```
TreeGrowing (S,A,y,SplitCriterion,StoppingCriterion)
Where:
S - Training Set
A - Input Feature Set
y - Target Feature
SplitCriterion - the method for evaluating a certain split
StoppingCriterion - the criteria to stop the growing process
Create a new tree T with a single root node.
IF StoppingCriterion(S) THEN
    Mark T as a leaf with the most
    common value of y in S as a label.
ELSE
     $\forall a_i \in A$  find  $a$  that obtain the best SplitCriterion( $a_i, S$ ).
    Label  $t$  with  $a$ 
    FOR each outcome  $v_i$  of  $a$ :
        Set Subtree $_i$  = TreeGrowing ( $\sigma_{a=v_i} S, A, y$ ).
        Connect the root node of  $t_T$  to Subtree $_i$  with
        an edge that is labelled as  $v_i$ 
    END FOR
END IF
RETURN TreePruning (S,T,y)
TreePruning (S,T,y)
Where:
S - Training Set
y - Target Feature
T - The tree to be pruned
DO
    Select a node  $t$  in T such that pruning it
    maximally improve some evaluation criteria
    IF  $t \neq \emptyset$  THEN  $T = \text{pruned}(T, t)$ 
UNTIL  $t = \emptyset$ 
RETURN T
```

Decision Trees

- Decision tree is a recursive partition of the input space
- Most are *binary*

