

# Martingales



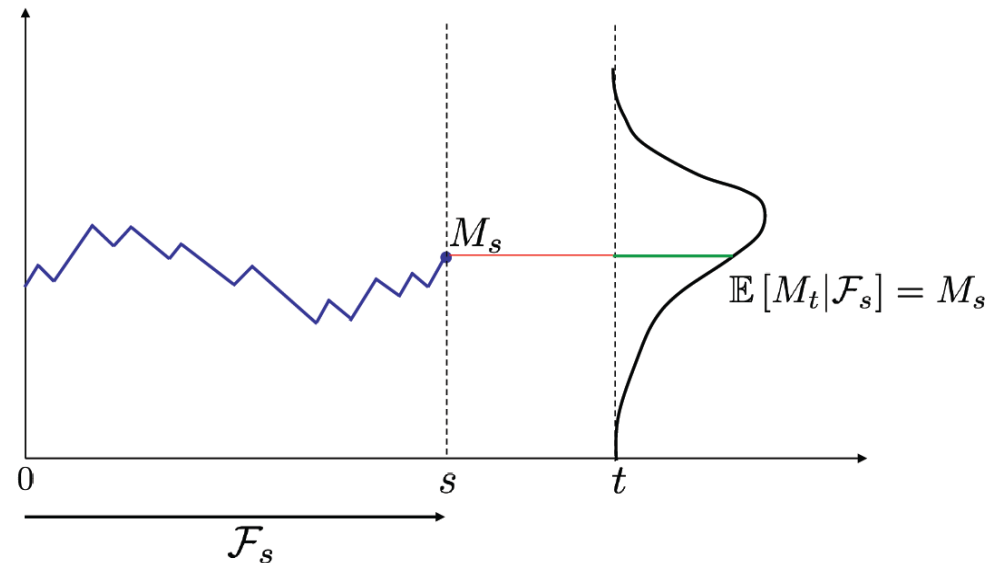
**Martingales** are a key concept in probability and in mathematical finance. The term ‘martingale’ may refer to very different ideas e.g. a stochastic process that has no drift. Essentially, this is the idea of a fair (random) game. We encounter Martingales through three distinct, but closely connected ideas:

1. *Martingales* as a class of stochastic process;
2. *Exponential martingales*, which are a specific and extremely useful example of a martingale;
3. *Equivalent martingale measures*, where we look for a probability measure  $\mathbb{Q}$  such that a given stochastic process  $S(t)$  is a martingale under  $\mathbb{Q}$  regardless of its nature under  $\mathbb{P}$ . The correspondence between the measures  $\mathbb{P}$  and  $\mathbb{Q}$  is done through a change of measure.

# Discrete Time Martingales

A discrete time stochastic process  $\{M_t : t = 0, \dots, T\}$  such that  $M_t$  is  $\mathcal{F}_t$ -measurable for  $\mathbb{T} = \{0, \dots, T\}$  is a **martingale** if  $\mathbb{E} |M_t| < \infty$  and

$$\mathbb{E} [M_{t+1} | \mathcal{F}_t] = M_t \quad (1)$$



The first equation represents a standard integrability condition.

The second equation tells you that the expected value of  $M$  at time  $t + 1$  conditional on all the information available up to time  $t$  is the value of  $M$  at time  $t$ . In short, a Martingale is a **driftless process**.

If we take expectation on both sides of eqn. 1, then

$$\mathbb{E}[M_{t+1}] = \mathbb{E}[M_t]$$

This is due to the **Tower Property** of conditional expectations.

Martingales are a very nice mathematical object. They “get rid of the drift” and enable us to focus on what probabilists consider is the most interesting part: the statistical properties of purely random processes.

In addition, Doob and Meyer have developed a powerful theory centred around martingales.

## Continuous Time Martingales

Next, we generalize our definitions to continuous time: A continuous time stochastic process

$$\{M_t : t \in \mathbb{R}^+\}$$

such that  $M_t$  is  $\mathcal{F}_t$ -measurable for  $t \in \mathbb{R}^+$  is a **martingale** if

$$\mathbb{E} |M_t| < \infty$$

and

$$\mathbb{E} [M_t | \mathcal{F}_s] = M_s, \quad 0 \leq s \leq t.$$

**Lévy's Martingale Characterisation:** Let  $X_t$ ,  $t > 0$  be a stochastic process and let  $\mathcal{F}_t$  be the filtration generated by it.  $X_t$  is a Brownian motion iff the following conditions are satisfied:

1.  $X_0 = 0$  a.s.;
2. the sample paths  $t \mapsto X_t$  are continuous a.s.;
3.  $X_t$  is a martingale with respect to the filtration  $\mathcal{F}_t$ ;
4.  $|X_t|^2 - t$  is a martingale with respect to the filtration  $\mathcal{F}_t$ .

The Lévy characterization can be contrasted with the classical definition of a Brownian motion as a stochastic process  $X_t$  satisfying:

1.  $X_0 = 0$  a.s.;
2. the sample paths  $t \mapsto X(t)$  are continuous a.s.;
3. **independent increments:** for  $t_1 < t_2 < t_3 < t_4$  the increments  $X_{t_4} - X_{t_3}$ ,  $X_{t_2} - X_{t_1}$  are independent;
4. **normally distributed increments:**  $X_t - X_s \sim N(0, |t - s|)$ .

Lévy's characterization neither mentions independent increments nor normally distributed increments.

Instead, Lévy introduces two easily verifiable martingale conditions.

# Itô Integrals and Martingales

Next, we explore the link between Itô integration and martingales.

Consider the stochastic process  $Y(t) = X^2(t)$ . By Itô, we have

$$X^2(T) = T + \int_0^T 2X(t)dX(t)$$

Taking the expectation, we get

$$\mathbb{E}[X^2(T)] = T + \mathbb{E} \left[ \int_0^T 2X(t)dX(t) \right]$$

Now, the quadratic variation property of Brownian motions implies that

$$\mathbb{E}[X^2(T)] = T$$

and hence

$$\mathbb{E} \left[ \int_0^T 2X(t)dX(t) \right] = 0$$



Therefore, the Itô integral

$$\int_0^T 2X(t)dX(t)$$

is a martingale.

In fact, this property is shared by all Itô integrals.

### **The Itô integral is a martingale**

Let  $g(t, X_t)$  be a function on  $[0, T]$  and satisfying the technical condition.  
Then the Itô integral

$$\int_0^T g(t, X_t)dX_t$$

is a martingale.

So, Itô integrals are martingales.

But does the converse hold? Can we represent any martingale as an Itô integral?

The answer is yes!

**Martingale Representation Theorem:** If  $M_t$  is a martingale, then there exists a function  $g(t, X_t)$  satisfying the technical condition such that

$$M_T = M_0 + \int_0^T g(t, X_t) dX_t$$

**Example** Using only Itô and the fact that Itô integrals are martingales, we will show that

$$\mathbb{E} [X^2(T)] = T.$$

Consider the function  $F(t, X_t) = X_t^2$ , then by Itô's lemma,

$$\begin{aligned} X_T^2 &= X_0^2 + \frac{1}{2} \int_0^T 2dt + \int_0^T 2X_t dX_t \\ &= \int_0^T dt + 2 \int_0^T X_t dX_t \end{aligned}$$

since  $X_0 = 0$

Taking the expectation,

$$\mathbb{E} [X_T^2] = \mathbb{E} \left[ \int_0^T dt \right] + 2\mathbb{E} \left[ \int_0^T X_t dX_t \right]$$

Now,

$$\int_0^T X_t dX_t$$

is an Itô integral and as a result  $\mathbb{E} \left[ \int_0^T X_t dX_t \right] = 0$

Moreover,

$$\mathbb{E} \left[ \int_0^T dt \right] = \mathbb{E} [T] = T$$

We can conclude that

$$\mathbb{E} [X^2(T)] = T$$

As an aside, we can usually exchange the order of integration between the time integral and the expectation so that

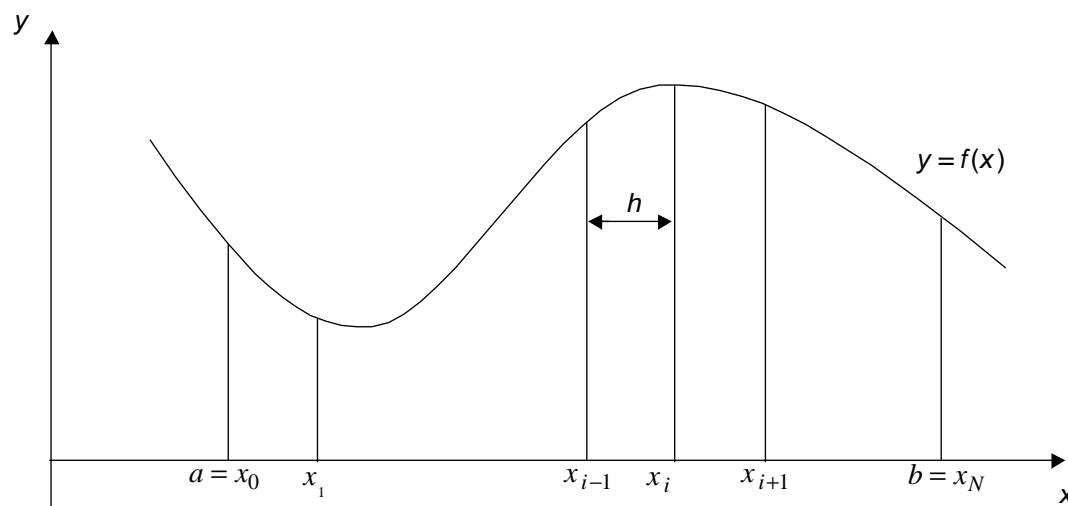
$$\mathbb{E} \left[ \int_0^T f(X_t) dt \right] = \int_0^T \mathbb{E} [f(X_t)] dt$$

This is due to an analysis result known as **Fubini's Theorem**.

# Itô Integral

Recall the usual Riemann definition of a definite integral

$$\int_a^b f(x) dx$$



which represents the area under the curve between  $x = a$  and  $x = b$ , where the curve is the graph of  $f(x)$  plotted against  $x$ .

Assuming  $f$  is a "well behaved" function on  $[a, b]$ , there are many different ways (which all lead to the same value for the definite integral).

Start by partitioning  $[a, b]$  into  $N$  intervals with end points  $x_0 = a < x_1 < x_2 < \dots < x_{N-1} < x_N = b$ , where the length of an interval  $dx = x_i - x_{i+1}$  tends to zero as  $N \rightarrow \infty$ . So there are  $N$  intervals and  $N + 1$  points  $x_i$ .

Discretising  $x$  gives

$$x_i = a + i dx$$

Now consider the definite integral

$$\int_0^T f(t) dt.$$

With Riemann integration there are a number of ways we can approximate this:

1. left hand rectangle rule;

$$\int_0^T f(t) dt = \lim_{N \rightarrow \infty} \sum_{i=0}^{N-1} f(t_i) (t_{i+1} - t_i)$$

2. right hand rectangle rule;

$$\int_0^T f(t) dt = \lim_{N \rightarrow \infty} \sum_{i=0}^{N-1} f(t_{i+1}) (t_{i+1} - t_i)$$

3. trapezium rule;

$$\int_0^T f(t) dt = \lim_{N \rightarrow \infty} \sum_{i=0}^{N-1} \frac{1}{2} (f(t_i) + f(t_{i+1})) (t_{i+1} - t_i)$$

#### 4. midpoint rule

$$\int_0^T f(t) dt = \lim_{N \rightarrow \infty} \sum_{i=0}^{N-1} f\left(\frac{1}{2}(t_i + t_{i+1})\right) (t_{i+1} - t_i)$$

In the limit  $N \rightarrow \infty$ ,  $f(t)$  we get the same value for each definition of the definite integral, provided the function is integrable.

Now consider the stochastic integral of the form

$$\int_0^T f(t, X) dX = \int_0^T f(t, X(t)) dX(t)$$

where  $X(t)$  is a Brownian motion. We can define this integral as

$$\lim_{N \rightarrow \infty} \sum_{i=0}^{N-1} f(t_i, X_i) (X_{i+1} - X_i),$$



where  $X_i = X(t_i)$ , or as

$$\lim_{N \rightarrow \infty} \sum_{i=0}^{N-1} f(t_{i+1}, X_{i+1}) (X_{i+1} - X_i),$$

or as

$$\lim_{N \rightarrow \infty} \sum_{i=0}^{N-1} f\left(t_{i+\frac{1}{2}}, X_{i+\frac{1}{2}}\right) (X_{i+1} - X_i),$$

where  $t_{i+\frac{1}{2}} = \frac{1}{2}(t_i + t_{i+1})$  and  $X_{i+\frac{1}{2}} = X\left(t_{i+\frac{1}{2}}\right)$  or in many other ways. So clearly drawing parallels with the above Riemann form.

**Very Important:** In the case of a stochastic variable  $dX(t)$  the value of the stochastic integral **does** depend on which definition we choose.

In the case of a stochastic integral, the definition

$$I = \lim_{N \rightarrow \infty} \sum_{i=0}^{N-1} f(t_i, X_i) (X_{i+1} - X_i),$$

is special. This definition results in the **Itô Integral**.

It is special because it is **non-anticipatory**; given that we are at time  $t_i$  we know  $X_i = X(t_i)$  and therefore we know  $f(t_i, X_i)$ . The only uncertainty is in the  $X_{i+1} - X_i$  term.

Compare this to a definition such as

$$\lim_{N \rightarrow \infty} \sum_{i=0}^{N-1} f(t_{i+1}, X_{i+1}) (X_{i+1} - X_i),$$

which is **anticipatory**; given that at time  $t_i$  we know  $X_i$  but are uncertain about the future value of  $X_{i+1}$ . Thus we are uncertain about *both* the value of

$$f(t_{i+1}, X_{i+1})$$

and the value of  $(X_{i+1} - X_i)$  — there exists uncertainty in both of these quantities. That is, evaluation of this integral requires us to anticipate the future value of  $X_{i+1}$  so that we may evaluate  $f(t_{i+1}, X_{i+1})$ .

The main thing to note about Itô integrals is that  $I$  is a random variable (unlike the deterministic case). Additionally, since  $I$  is essentially the limit of a sum of normal random variables, then by the CLT  $I$  is also normally distributed, and can be characterized by its mean and variance.

**Example:** Show that Itô's lemma implies that

$$3 \int_0^T X^2 dX = X(T)^3 - X(0)^3 - 3 \int_0^T X(t) dt.$$

Show that the result also can be found by writing the integral

$$3 \int_0^T X^2 dX = \lim_{N \rightarrow \infty} 3 \sum_{i=0}^{N-1} X_i^2 (X_{i+1} - X_i)$$

Hint: use  $3b^2(a - b) = a^3 - b^3 - 3b(a - b)^2 - (a - b)^3$ .

The Itô integral here is defined as

$$\int_0^T 3X^2(t) dX(t) = \lim_{N \rightarrow \infty} \sum_{i=0}^{N-1} 3X_i^2 (X_{i+1} - X_i)$$

Now note the hint:

$$3b^2(a-b) = a^3 - b^3 - 3b(a-b)^2 - (a-b)^3$$

hence

$$\begin{aligned} &\equiv 3X_i^2(X_{i+1} - X_i) \\ &= X_{i+1}^3 - X_i^3 - 3X_i(X_{i+1} - X_i)^2 - (X_{i+1} - X_i)^3, \end{aligned}$$

so that

$$\begin{aligned} &\sum_{i=0}^{N-1} 3X_i^2(X_{i+1} - X_i) = \\ &\sum_{i=0}^{N-1} X_{i+1}^3 - \sum_{i=0}^{N-1} X_i^3 - \sum_{i=0}^{N-1} 3X_i(X_{i+1} - X_i)^2 \\ &\quad - \sum_{i=0}^{N-1} (X_{i+1} - X_i)^3 \end{aligned}$$

Now the first two expressions above give

$$\begin{aligned} \sum_{i=0}^{N-1} X_{i+1}^3 - \sum_{i=0}^{N-1} X_i^3 &= X_N^3 - X_0^3 \\ &= X(T)^3 - X(0)^3. \end{aligned}$$

In the limit  $N \rightarrow \infty$ , i.e.  $dt \rightarrow 0$ ,  $(X_{i+1} - X_i)^2 \rightarrow dt$ , so

$$\lim_{N \rightarrow \infty} \sum_{i=0}^{N-1} 3X_i (X_{i+1} - X_i)^2 = \int_0^T 3X(t) dt$$

Finally  $(X_{i+1} - X_i)^3 = (X_{i+1} - X_i)^2 \cdot (X_{i+1} - X_i)$  which when  $N \rightarrow \infty$  behaves like  $dX^2 dX \sim O(dt^{3/2}) \rightarrow 0$ .

Hence putting together gives

$$X(T)^3 - X(0)^3 - \int_0^T 3X(t) dt$$

which is consistent with Itô's lemma.

The other important property that the Itô integral has is that it is a martingale. We know that

$$X_{i+1} - X_i$$

is a martingale; i.e. in the context

$$\mathbb{E} [X_{i+1} - X_i] = 0.$$

Since

$$\begin{aligned} \mathbb{E} \left[ \sum_{i=0}^{N-1} f(t_i, X_i) (X_{i+1} - X_i) \right] &= \\ \sum_{i=0}^{N-1} f(t_i, X_i) \mathbb{E} [X_{i+1} - X_i] &= 0 \end{aligned}$$

Thus

$$\mathbb{E} \left[ \int_0^T f(t, X(t)) dX(t) \right] = 0.$$

This is, essentially a consequence of the Itô integral being non-anticipatory, as discussed earlier. No other stochastic integral has this property.

**Exercise** We know from Itô's lemma that

$$4 \int_0^T X^3(t) dX(t) = X^4(T) - X^4(0) - 6 \int_0^T X^2(t) dt$$

Show from the definition of the Itô integral that the result can also be found by initially writing the integral

$$4 \int_0^T X^3 dX = \lim_{N \rightarrow \infty} 4 \sum_{i=0}^{N-1} X_i^3 (X_{i+1} - X_i)$$

**Hint:** use  $4b^3(a - b) = a^4 - b^4 - 4b(a - b)^3 - 6b^2(a - b)^2 - (a - b)^4$ .

# Proving that a Continuous Time Stochastic Process is a Martingale

Consider a stochastic process  $Y(t)$  solving the following SDE:

$$dY(t) = f(Y_t, t)dt + g(Y_t, t)dX(t), \quad Y(0) = Y_0$$

How can we tell whether  $Y(t)$  is a martingale?

The answer has to do with the fact that Itô integrals are martingales.

$Y(t)$  is a martingale if and only if it satisfies the martingale condition

$$\mathbb{E}[Y_t | \mathcal{F}_s] = Y_s, \quad 0 \leq s \leq t$$

Let's start by integrating the SDE between  $s$  and  $t$  to get an exact form for  $Y(t)$ :

$$Y(t) = Y(s) + \int_s^t f(Y_u, u)du + \int_s^t g(Y_u, u)dX(u)$$



Taking the expectation conditional on the filtration at time  $s$ , we get

$$\begin{aligned}\mathbb{E}[Y_t|\mathcal{F}_s] &= \mathbb{E}\left[Y(s) + \int_s^t f(Y_u, u)du + \int_s^t g(Y_u, u)dX(u)|\mathcal{F}_s\right] \\ &= Y(s) + \mathbb{E}\left[\int_s^t f(Y_u, u)du|\mathcal{F}_s\right]\end{aligned}$$

where the last line follows from the fact that a Itô integral is a martingale,  $\therefore$

$$\mathbb{E}\left[\int_s^t g(Y_u, u)dX(u)|\mathcal{F}_s\right] = \int_s^s g(Y_u, u)dX(u) = 0.$$

So,  $Y(t)$  is a martingale iff

$$\mathbb{E}\left[\int_s^t f(u)du|\mathcal{F}_s\right] = 0$$

This condition is satisfied only if  $f(Y_t, t) = 0$  for all  $t$ . Returning to our SDE, we conclude that  $Y(t)$  is a martingale iff it is of the form

$$dY(t) = g(Y_t, t)dX(t), \quad Y(0) = Y_0$$

# Exponential Martingales

Let's start with a motivating example.

Consider the stochastic process  $Y(t)$  satisfying the SDE

$$dY(t) = f(t)dt + g(t)dX(t), \quad Y(0) = Y_0 \quad (2)$$

where  $f(t)$  and  $g(t)$  are two time-dependent functions and  $X(t)$  is a standard Brownian motion.

Define a new process  $Z(t) = e^{Y(t)}$ .

How should we choose  $f(t)$  if we want the process  $Z(t)$  to be a martingale?

Consider the process  $Z(t) = e^{Y(t)}$ . Applying Itô to the function we obtain:

$$\begin{aligned}
 dZ(t) &= \frac{dZ}{dY} dY(t) + \frac{1}{2} \frac{d^2 Z}{dY^2} dY^2(t) \\
 &= \frac{dZ}{dY} (f(t)dt + g(t)dX(t)) + \frac{1}{2} \frac{d^2 Z}{dY^2} g^2(t)dt \\
 &= e^{Y(t)} \left( f(t) + \frac{1}{2} g^2(t) \right) dt + e^{Y(t)} g(t) dX(t) \\
 &= Z(t) \left[ \left( f(t) + \frac{1}{2} g^2(t) \right) dt + g(t) dX(t) \right]
 \end{aligned}$$

$Z(t)$  is a martingale if and only if it is a driftless process.

Therefore for  $Z(t)$  to be a martingale we must have

$$f(t) + \frac{1}{2} g^2(t) = 0$$

This is only possible if

$$f(t) = -\frac{1}{2} g^2(t)$$

Going back to the process  $Y(t)$ , we must have

$$dY(t) = -\frac{1}{2}g^2(t)dt + g(t)dX(t), \quad Y(0) = Y_0$$

implying that

$$Y(T) = Y_0 - \frac{1}{2} \int_0^T g^2(t)dt + \int_0^T g(t)dX(t)$$

Hence, in terms of  $Z(t)$ :

$$dZ(t) = Z(t)g(t)dX(t).$$

Using the earlier relationship, we can write  $Z(T) = e^{Y(T)}$ .

Let's simplify this  $Z(T) =$

$$\exp \left\{ Y_0 - \frac{1}{2} \int_0^T g^2(t)dt + \int_0^T g(t)dX(t) \right\}$$

to give

$$Z(T) = Z_0 \exp \left\{ -\frac{1}{2} \int_0^T g^2(t)dt + \int_0^T g(t)dX(t) \right\}$$

Because the stochastic process  $Z(t)$  is the exponential of another process (namely  $Y(t)$ ) and because it is a martingale, we call  $Z(t)$  an **exponential martingale**.

We have actually just stumbled upon a much more general and very important result.

## Key Condition (Novikov Condition)

A trading strategy  $(\phi, \psi) = \{(\phi_t, \psi_t); t \in [0, \dots, T]\}$  is a previsible process in that  $\phi_t \in \mathcal{F}_{t-}$ .

A stochastic process  $Y_t$  satisfies the *Novikov condition* if

$$\mathbb{E} \left[ \exp \left( \frac{1}{2} \int_0^T \gamma_s^2 ds \right) \right] < \infty$$

where  $\gamma_t$  is a previsible process.

## Key Fact

Given a process  $\gamma_t$  satisfying the Novikov condition, then the process  $M_t^\gamma$  defined as we can define the probability measure  $\mathbb{Q}$  on  $(\Omega, \mathcal{F})$  equivalent to  $\mathbb{P}$  through the Radon Nikodým derivative

$$M_t^\gamma = \exp \left( - \int_0^t \gamma_s dX_s - \frac{1}{2} \int_0^t \gamma_s^2 ds \right), \quad t \in [0, T]$$

is a martingale.

In our earlier example  $\gamma_t = -g(t)$ ;  $M_t^\gamma = Z(t)$ .

## Key Fact (Girsanov's Theorem)

Given a process  $\theta_t$  satisfying the Novikov condition, we can define the probability measure  $\mathbb{Q}$  on  $(\Omega, \mathcal{F})$  equivalent to  $\mathbb{P}$  through the Radon Nikodým derivative

$$\frac{d\mathbb{Q}}{d\mathbb{P}} = \exp \left( - \int_0^t \gamma_s dX_s - \frac{1}{2} \int_0^t \gamma_s^2 ds \right), \quad t \in [0, T]$$

In this case, the process  $X_t^{\mathbb{Q}}$  defined as

$$X_t^{\mathbb{Q}} = X_t^{\mathbb{P}} + \int_0^t \gamma_s dX_s$$

as is a standard Brownian motion on  $(\Omega, \mathcal{F}, \mathbb{Q})$ .