Midterm Exam

15-316 Software Foundations of Security & Privacy Frank Pfenning

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Instructions

- This exam is closed-book, closed-notes.
- There are several appendices for reference.
- Reference pages will not be scanned (you may tear them off).
- Try to keep your answers inside the answer boxes to ensure proper scanning.
- You have 80 minutes to complete the exam.
- There are 5 problems.
- The maximal exam score is 200.

	Sequent Calculus	Dynamic Logic	Loops & Invariants	Safety	Information Flow	
	Prob 1	Prob 2	Prob 3	Prob 4	Prob 5	Total
Score						
Max	30	50	35	35	50	200

1 Sequent Calculus (30 pts)

Either prove or refute the sequents in Tasks 1 and 2 by constructing a derivation where all leaves consist only of propositional variables. In case the sequent is not valid, give at least one countermodel. For reference, the rules are provided in Appendix A.

Task 1 (10 pts).	
	$(p \mathop{\rightarrow} q) \mathop{\rightarrow} r \vdash p \vee r$
Task 2 (10 pts).	
	$p \vee r \vdash (p \to q) \to r$

Task 3 (10 pts). Complete the following rule with one or more premises using only Γ , Δ , F , and Γ such that the resulting rule is invertible but not sound .					anc
- Juen mar me resum		e sat not sound.			
		$\Gamma, F \to G \vdash \Delta$			

2 Dynamic Logic (50 points)

For the remainder of the exam, we fix our base language SAFETINY to the following programs.

Programs
$$\alpha, \beta ::= x := e \mid \alpha \; ; \beta \mid \mathbf{skip} \mid \mathbf{if} \; P \; \mathbf{then} \; \alpha \; \mathbf{else} \; \beta \mid \mathbf{while} \; P \; \alpha \mid \; \mathbf{test} \; P$$

Consider an extension of SAFETINY with nondeterministic choice $\alpha \mid \beta$. This program may arbitrarily execute either α or β , perhaps based on some hidden input such as a coin flip. If a nondeterministic choice is encountered multiple times (say, in a loop), the branch executed may be different each time. We define its semantics as

$$\omega \llbracket \alpha \rrbracket \beta \rrbracket \nu \text{ iff } \omega \llbracket \alpha \rrbracket \nu \text{ or } \omega \llbracket \beta \rrbracket \nu$$

Also recall that in SAFETINY every construct is safe, so we define the meaning of $[\alpha]Q$ by

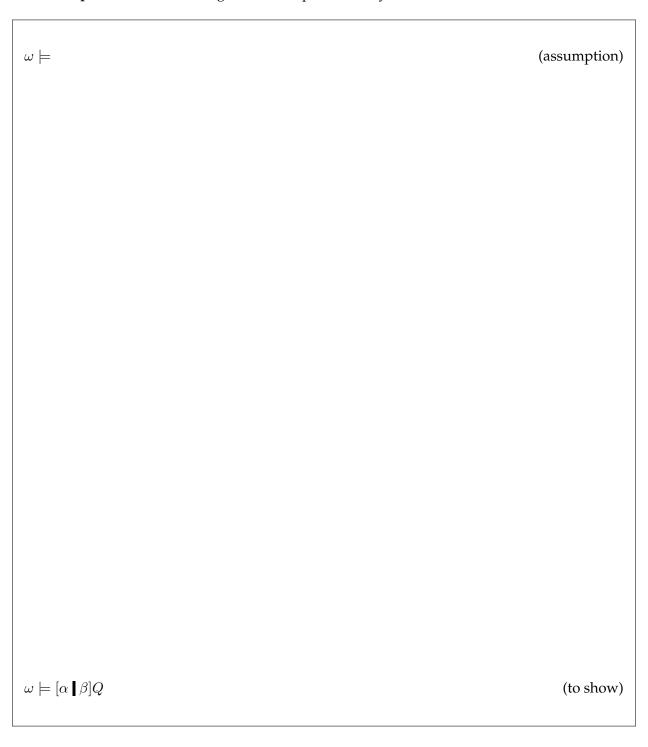
$$\omega \models [\alpha]Q$$
 iff for every ν such that $\omega \llbracket \alpha \rrbracket \nu$ we have $\nu \models Q$

Appendix C and Appendix D summarize some other relevant definitions.

Task 4 (10 pts). Complete the following axiom for reasoning about nondeterministic choice.

$$[\alpha \, | \! | \, \beta]Q \quad \leftrightarrow$$

Task 5 (20 pts). Prove that the right-to-left implication of your axiom is valid.



ask 7 (10 pts). Complete the rule for symbolic evaluation by providing one or more premises.		[]]R
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Task 6 (10 pts). Complete the new case in the definition of the weakest liberal precondition.

3 Loops and Invariants (35 points)

Consider adding a new form of loop to our language

repeat α until P

It should evaluate as follows:

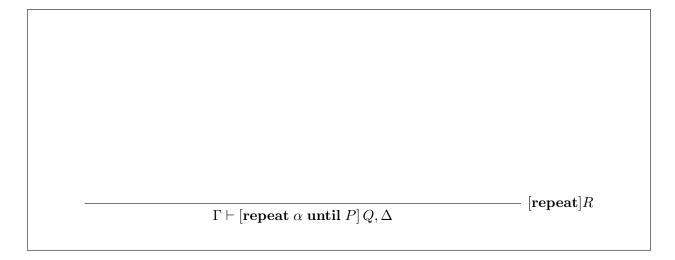
- 1. Execute α
- 2. If *P* is true in the poststate we exit the loop
- 3. If *P* is false in the poststate we repeat the loop

The *loop invariant* J should be checked **just before the exit condition** P. For example,

$$sum := 0$$
; $i := 0$; repeat $i := i + 1$; $sum := sum + i$ until $i = n$

should satisfy the postcondition 2 * sum = n * (n + 1). We should be able to prove this using the loop invariant J = (2 * sum = i * (i + 1)).

Task 8 (15 pts). Give a right rule for repeat in the sequent calculus using J as an invariant.



Task 9 (10 pts). Show how to define **repeat** α **until** P using only the existing language constructs (including **while**).

 $\mathbf{repeat} \; \alpha \; \mathbf{until} \; P \quad \triangleq$

	-	-	
while $P \alpha \triangleq$			

Task 10 (10 pts). Now imagine we had taken repeat loops as our primitive instead of while loops. Show how to define while loops using repeat, or briefly explain why you think this is not

possible. Your definition may use all the language constructs (except while, of course).

4 Safety (35 points)

In general, we analyze programs with uninitialized variables, which are considered inputs. However, before we actually run a program, it is important that every variable is defined by the time we use its value. The def/use analysis from Lab 1 ensures that this is always the case, but it is limited. For example,

$$\alpha_0 = (\mathbf{if} \perp \mathbf{then} \ y := 0 \ \mathbf{else} \ x := 1)$$

definitely defines the variable x, but our def/use analysis will not determine that.

Task 11 (5 pts). Show the computation of def α_0 . You may refer to the definition of this function in Appendix D.

$$\mathsf{def}\ (\mathbf{if}\perp\mathbf{then}\ y:=0\ \mathbf{else}\ x:=1)$$

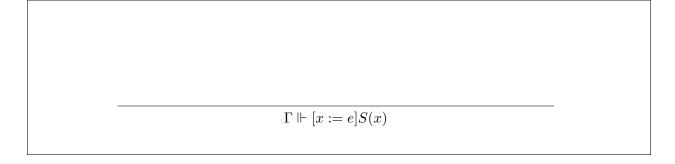
In order to improve on def/use analysis we define a new formula defd x which is true in a poststate if the variable x must have been assigned to (or it is already true) in the prestate. We then extend symbolic evaluation

$$P \Vdash [\alpha]Q$$

such that precondition P and postcondition Q may contain formulas of the form defd x. P declares the variables we assume to be defined *before* α executes, and Q checks the variables we would like to be defined *after* α executes. For example, we should be able to derive

$$\operatorname{\mathsf{defd}} z \Vdash [\mathbf{if} \perp \mathbf{then} \ y := 0 \ \mathbf{else} \ x := 1] \ (\operatorname{\mathsf{defd}} z \land \operatorname{\mathsf{defd}} x)$$

Task 12 (10 pts). Complete the following extended rule for assignment so it also accounts for the defd predicate. You can find the original rules in Appendix D.



The other annotated	rules remain unchanged, where loops are unrolled just once, that is, each while as \mathbf{while}^1 .	e lo
	ots). Using your rule from Task 12 and the remaining rules for symbolic evaluample above. You may assume any valid arithmetic sequents are proved by an o	
	$defd\ z \Vdash [\mathbf{if}\ \bot\ \mathbf{then}\ y := 0\ \mathbf{else}\ x := 1] (defd\ z \wedge defd\ x)$	
till possibl	ots). Assuming an arithmetic oracle proves every valid sequent of pure arithmele that a variable is definitely defined but symbolic evaluation cannot prove it? example (you don't need to show how it fails) or briefly explain why you believe exists.	Eit

5 Information Flow (50 points)

Consider the following program

$$\alpha_0 = (y := x - x)$$

with the security policy $\Sigma_0 = (x : \mathsf{H}, y : \mathsf{L})$ where $\mathsf{H} \sqsupset \mathsf{L}$.

Task 15 (15 pts). Complete the proof that this program is **semantically secure**, that is, $\Sigma_0 \models (y := x - x)$ secure.

$$\begin{array}{lll} \Sigma_0 \vdash \omega_1 \approx_{\mathsf{L}} \omega_2 & \text{(assumption)} \\ \text{eval } \omega_1 \ (y := x - x) = \nu_1 & \text{(assumption)} \\ \text{eval } \omega_2 \ (y := x - x) = \nu_2 & \text{(assumption)} \end{array}$$

 $\Sigma_0 \vdash \nu_1 \approx_{\mathsf{L}} \nu_2$ (to show)

_	$\Sigma_0 \vdash y$:	= x - x secure		

Give an encoding of information flow security for this example as a seque. Validity of the sequent should imply the program is secure, according to or
Using the weakest liberal precondition, calculate a proposition whose validing ogram α_0 satisfies our security policy Σ_0 . Is it valid?

A Propositional Sequent Calculus

$$\begin{array}{c} \overline{\Gamma, F \vdash F, \Delta} \quad \text{id} \\ \\ \frac{\Gamma \vdash F, \Delta \quad \Gamma \vdash G, \Delta}{\Gamma \vdash F \land G, \Delta} \land R \qquad \frac{\Gamma, F, G \vdash \Delta}{\Gamma, F \land G \vdash \Delta} \land L \\ \\ \frac{\Gamma, F \vdash G, \Delta}{\Gamma \vdash F \rightarrow G, \Delta} \rightarrow R \qquad \frac{\Gamma \vdash F, \Delta \quad \Gamma, G \vdash \Delta}{\Gamma, F \rightarrow G \vdash \Delta} \rightarrow L \\ \\ \frac{\Gamma \vdash F, G, \Delta}{\Gamma \vdash F \lor G, \Delta} \lor R \qquad \frac{\Gamma, F \vdash \Delta \quad \Gamma, G \vdash \Delta}{\Gamma, F \lor G \vdash \Delta} \lor L \\ \\ \frac{\Gamma, F \vdash \Delta}{\Gamma, F \vdash \neg F, \Delta} \neg R \qquad \frac{\Gamma \vdash F, \Delta}{\Gamma, \neg F \vdash \Delta} \neg L \end{array}$$

B Dynamic Logic, Semantics

Expressions

$$\begin{array}{lll} \omega\llbracket c\rrbracket & = & c \\ \omega\llbracket x\rrbracket & = & \omega(x) \\ \omega\llbracket e_1 + e_2 \rrbracket & = & \omega\llbracket e_1 \rrbracket + \omega\llbracket e_2 \rrbracket \end{array}$$

Formulas

$$\begin{split} \omega &\models e_1 \leq e_2 \quad \text{iff} \quad \omega \llbracket e_1 \rrbracket \leq \omega \llbracket e_2 \rrbracket \\ \omega &\models e_1 = e_2 \quad \text{iff} \quad \omega \llbracket e_1 \rrbracket = \omega \llbracket e_2 \rrbracket \end{split}$$

$$\begin{aligned} \omega &\models P \wedge Q \quad \text{iff} \quad \omega \models P \quad \text{and} \quad \omega \models Q \\ \omega &\models P \vee Q \quad \text{iff} \quad \omega \models P \quad \text{or} \quad \omega \models Q \\ \omega &\models P \rightarrow Q \quad \text{iff} \quad \omega \models P \quad \text{implies} \quad \omega \models Q \\ \omega &\models \neg P \quad \text{iff} \quad \omega \not\models P \\ \omega &\models P \leftrightarrow Q \quad \text{iff} \quad \omega \not\models P \end{aligned}$$

$$\omega \models P \leftrightarrow Q \quad \text{iff} \quad \omega \not\models P \quad \omega \models Q$$

$$\omega \models [\alpha]Q \quad \text{iff} \quad \text{for every } \nu \text{ with } \omega \llbracket \alpha \rrbracket \nu \text{ we have } \nu \models Q$$

Programs

$$\begin{split} \omega \llbracket x &:= e \rrbracket \nu & \text{iff} \quad \omega \llbracket x \mapsto c \rrbracket = \nu \text{ where } \omega \llbracket e \rrbracket = c \\ \omega \llbracket \alpha \ ; \beta \rrbracket \nu & \text{iff} \quad \omega \llbracket \alpha \rrbracket \mu \text{ and } \mu \llbracket \beta \rrbracket \nu \text{ for some state } \mu \\ \omega \llbracket \text{skip} \rrbracket \nu & \text{iff} \quad \nu = \omega \\ \omega \llbracket \text{iff} \quad P \text{ then } \alpha \text{ else } \beta \rrbracket \nu & \text{iff} \quad \omega \models P \text{ and } \omega \llbracket \alpha \rrbracket \nu & \text{or } \omega \not\models P \text{ and } \omega \llbracket \beta \rrbracket \nu \\ \omega \llbracket \text{while } P \alpha \rrbracket \nu & \text{iff} \quad \omega \llbracket \text{while } P \alpha \rrbracket^n \nu & \text{for some } n \in \mathbb{N} \\ \omega \llbracket \text{while } P \alpha \rrbracket^{n+1} \nu & \text{iff} \quad \omega \models P \text{ and } \omega \llbracket \alpha \rrbracket \mu \text{ and } \mu \llbracket \text{while } P \alpha \rrbracket^n \nu \\ \omega \llbracket \text{while } P \alpha \rrbracket^0 \nu & \text{iff} \quad \omega \not\models P \text{ and } \omega = \nu \\ \omega \llbracket \text{test } P \rrbracket \nu & \text{iff} \quad \omega \models P \text{ and } \nu = \omega \end{split}$$

C Dynamic Logic, Proofs

Sequent Calculus (Right Rules Only)

$$\begin{split} \frac{\Gamma, x' = e \vdash Q(x'), \Delta}{\Gamma \vdash [x := e]Q(x), \Delta} & [:=]R^{x'} & \frac{\Gamma, P \vdash [\alpha]Q, \Delta \quad \Gamma, \neg P \vdash [\beta]Q, \Delta}{\Gamma \vdash [\mathbf{if} \ P \ \mathbf{then} \ \alpha \ \mathbf{else} \ \beta]Q, \Delta} \ [\mathbf{if}]R \\ & \frac{\Gamma \vdash [\alpha]([\beta]Q), \Delta}{\Gamma \vdash [\alpha \ ; \beta]Q, \Delta} \ [:]R & \frac{\Gamma \vdash Q, \Delta}{\Gamma \vdash [\mathbf{skip}]Q, \Delta} \ [\mathbf{skip}]R \\ & \frac{\Gamma \vdash J, \Delta \quad J, P \vdash [\alpha]J \quad J, \neg P \vdash Q}{\Gamma \vdash [\mathbf{while}_J \ P \ \alpha]Q, \Delta} \ [\mathbf{while}]R & \frac{\Gamma, P \vdash Q, \Delta}{\Gamma \vdash [\mathbf{test} \ P]Q, \Delta} \ [\mathbf{test}]R \end{split}$$

Axioms

D Algorithms

Def/Use

The set def α consists of all variables that α **must** define. We omit use since it is not needed in this exam.

$$\begin{array}{lll} \operatorname{def}\;(x:=e) & = & \{x\} \\ \operatorname{def}\;(\alpha\,;\,\beta) & = & \operatorname{def}\;\alpha \cup \operatorname{def}\;\beta \\ \operatorname{def}\;(\operatorname{skip}) & = & \{\,\} \\ \operatorname{def}\;(\operatorname{\mathbf{if}}\;P\;\operatorname{\mathbf{then}}\;\alpha\;\operatorname{\mathbf{else}}\;\beta) & = & \operatorname{def}\;\alpha \cap \operatorname{\mathbf{def}}\;\beta \\ \operatorname{def}\;(\operatorname{\mathbf{while}}\;P\;\alpha) & = & \{\,\} \\ \operatorname{def}\;(\operatorname{\mathbf{test}}\;P) & = & \{\,\} \end{array}$$

Weakest Liberal Precondition wlp α Q

$$\begin{array}{lll} \mathsf{wlp}\;(x := e)\;Q(x) & = & Q(e) \\ \mathsf{wlp}\;(\alpha \;; \; \beta)\;Q & = & \mathsf{wlp}\;\alpha\;(\mathsf{wlp}\;\beta\;Q) \\ \mathsf{wlp}\;(\mathbf{skip})\;Q & = & Q \\ \mathsf{wlp}\;(\mathbf{if}\;P\;\mathbf{then}\;\alpha\;\mathbf{else}\;\beta)\;Q & = & (P \to \mathsf{wlp}\;\alpha\;Q) \land (\neg P \to \mathsf{wlp}\;\beta\;Q) \\ \mathsf{wlp}\;(\mathbf{while}_J\;P\;\alpha)\;Q & = & J \\ & & \land \Box(J \land P \to \mathsf{wlp}\;\alpha\;J) \\ & & \land \Box(J \land \neg P \to Q) \\ \\ \mathsf{wlp}\;(\mathbf{test}\;P)\;Q & = & P \to Q \end{array}$$

Symbolic Evaluation $\Gamma \Vdash [\alpha]S$

$$\frac{\Gamma \vdash Q \quad Q \text{ pure}}{\Gamma \Vdash Q} \text{ arith } \frac{\Gamma \vdash \bot}{\Gamma \Vdash S} \text{ infeasible}$$

$$\frac{\Gamma, x' = e \Vdash S(x') \quad x' \text{ fresh}}{\Gamma \Vdash [x := e]S(x)} [:=]R^{x'}$$

$$\frac{\Gamma \Vdash [\alpha]([\beta]S)}{\Gamma \Vdash [\alpha ; \beta]S} [:]R \qquad \frac{\Gamma \Vdash S}{\Gamma \Vdash [\mathbf{skip}]S} [\mathbf{skip}]R$$

$$\frac{\Gamma, P \Vdash [\alpha]S \quad \Gamma, \neg P \Vdash [\beta]S}{\Gamma \Vdash [\mathbf{if} \ P \ \mathbf{then} \ \alpha \ \mathbf{else} \ \beta]S} [\mathbf{if}]R$$

$$\frac{\Gamma \vdash J \quad J, P \Vdash [\alpha]J \quad J, \neg P \Vdash S}{\Gamma \Vdash [\mathbf{while}_J \ P \ \alpha]S} [\mathbf{while}]R \qquad \frac{\Gamma, P \Vdash S}{\Gamma \Vdash [\mathbf{test} \ P]S} [\mathbf{test}]R$$

$$\frac{\Gamma, P \Vdash [\alpha]([\mathbf{while}^n \ P \ \alpha]S) \quad \Gamma, \neg P \Vdash S}{\Gamma \Vdash [\mathbf{while}^{n+1} \ P \ \alpha]S} \quad \mathbf{unfold}^{n+1} \qquad \frac{\Gamma \Vdash S}{\Gamma \Vdash [\mathbf{while}^{0} \ P \ \alpha]S} \quad \mathbf{unfold}^{0}$$

E Information Flow

Semantic Definition

Definition [Equivalence at Security Level ℓ]

 $\Sigma \vdash \omega_1 \approx_{\ell} \omega_2 \text{ iff } \omega_1(x) = \omega_2(x) \text{ for all } x \text{ such that } \Sigma(x) \sqsubseteq \ell.$

Definition [Noninterference]

 $\Sigma \models \alpha$ secure iff for all $\omega_1, \omega_2, \nu_1, \nu_2$, and ℓ

 $\Sigma \vdash \omega_1 \approx_{\ell} \omega_2$, eval $\omega_1 \alpha = \nu_1$, and eval $\omega_2 \alpha = \nu_2$ implies $\Sigma \vdash \nu_1 \approx_{\ell} \nu_2$.

Information Flow Types