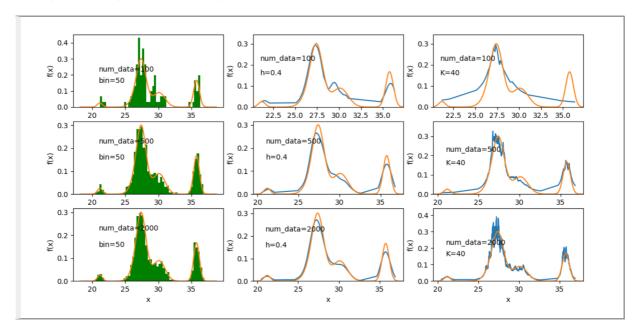
PRML Assignment-1 Report

RUN

```
from source import draw_histogram_estimation import matplotlib.pyplot as plt draw_histogram_estimation(200, 50) plt.show()
```

Question 1

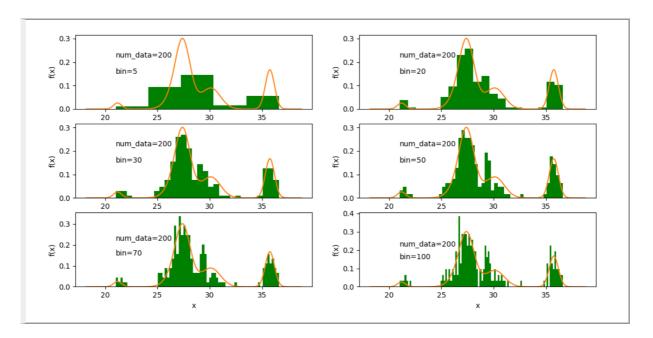
• The following picture is the comparison of three algorithms at different number of data used (constant parameter). The orange curve is the figure of true distribution.



- If I didn't print this picture, I may think the more number of data is used, the better result I can get, but it seems not totally right.
- For the histogram estimation, the guess is right. When <code>num_data = 2000</code>, the green histogram and the orange curve are almost completely cioncident; For the kernel density estimation, it seems not much changes when number of data used changes (maybe more dependent the parameter h); For the nearest neighbor estimation, althouth the two curves are more cioncident, the blue one looks very spiky (maybe related to parameter K).

Qustion 2

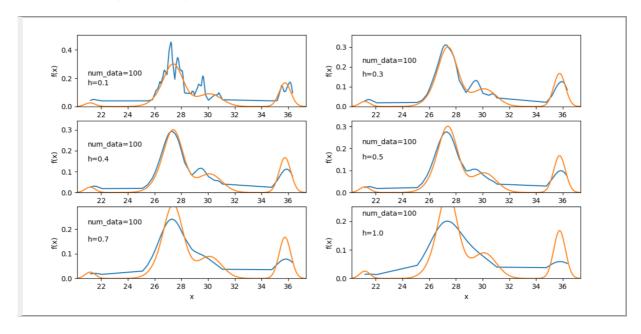
• The following picture is the comparison of histogram estimation at different parameter bins (constant number of data used). The orange curve is the figure of true distribution.



- From the picture above, we can see that when bins are too large, the resulting density model is spiky, with a lot of structure that is not present in the underlying distribution that generated the data set. If bins are small then the result is a model that too smooth and that consequently fails to capture the bimodal property of the orange curve.
- The best results are obtained for some intermediate value of bins. So I first chose a small one, about 10, found too small, then try 100, too large, then half of (10 + 100), then try the nearby numbers, last get property bins is about 50.
- According to the Wikipedia, depending on the actual data distribution, experimentation is needed to
 determine bins, but there also are some usefully rules, such as Square-root choice, Sturges' formula.

Question 3

• The following picture is the comparison of kernel density estimation at different parameter h (constant number of data used). The orange curve is the figure of true distribution.



- We can see that h acts as a smoothing parameter and that if it is set too small, the result is a very noisy density model, whereas if it is set too large, then the bimodal nature of the underlying distribution from which the data is generated is washed out.
- The best density model is obtained for some intermediate value of $\, {\rm h} \,$. The method I chose $\, {\rm h} \,$ is like the above I chose $\, {\rm bins} \,$. From 0.1 to 1, I used binary find and get the property $\, {\rm h} \,$ is about 0.4.

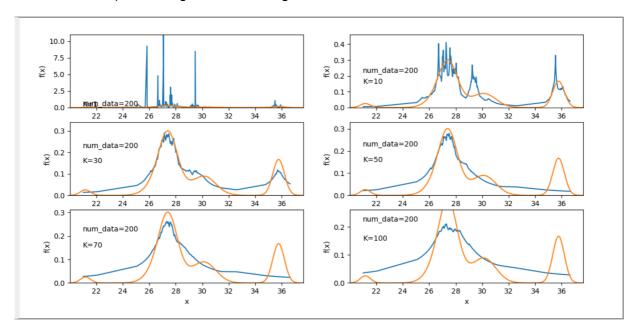
ullet According to the Wikipedia, there is a rule called Silverman's rule of thumb to estimate $\, {
m h} \, .$

$$h = \left(\frac{4\sigma^5}{3n}\right)^{\frac{1}{5}}$$

Get h is 1.465. However, at this value, the model didn't perform well.

Question 4

• The following picture is the comparison of nearest neighbor estimation at different parameter h (constant number of data used). The orange curve is the figure of true distribution.



- The model produced bu KNN is not a true density model because the integral over all space diverges.
- For the KNN, p(x) = K / (N * V) = (K / N) * 1/V, x takes any real number. Obviously, K/N is a constant c, but V linearly depends on the distance from x to its Kth nearest neighbor. Therefore the integration is

$$\int \frac{c}{kx+b}$$
, and it won't converge to 1.