

8: IIR Filter Transformations

- Continuous Time Filters
- Bilinear Mapping
- Continuous Time Filters
- Mapping Poles and Zeros
- Spectral Transformations
- Constantinides Transformations
- Impulse Invariance
- Summary
- MATLAB routines

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Classical continuous-time filters optimize tradeoff:
passband ripple v stopband ripple v transition width

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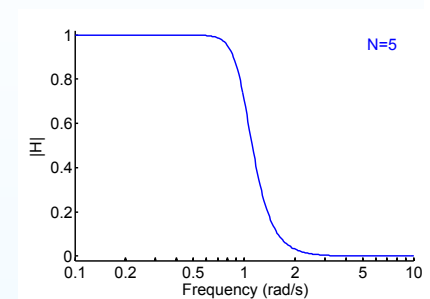
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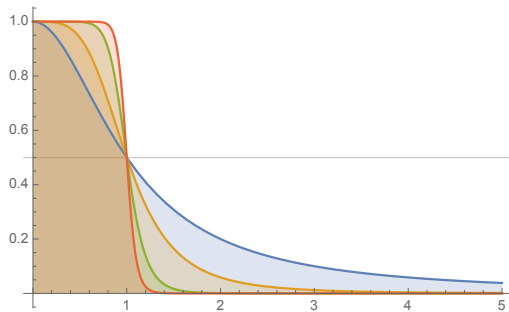
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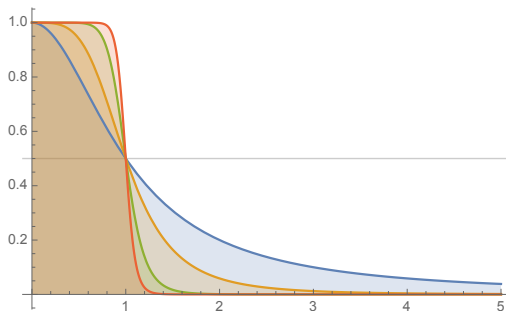
IIR Filter Design: Butterworth Filter

- Low-pass filter.



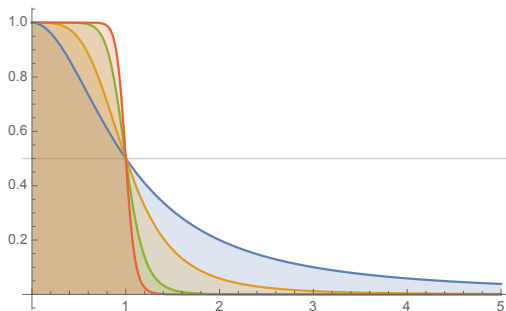
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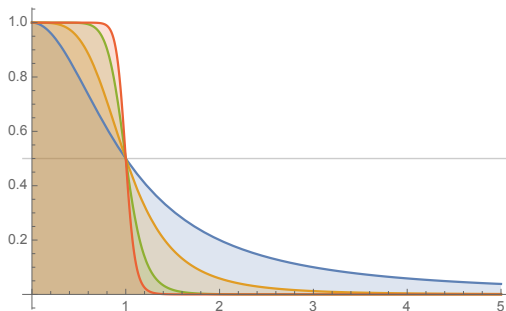
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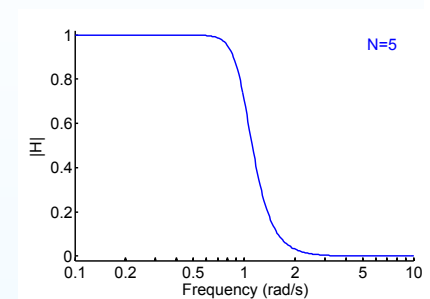
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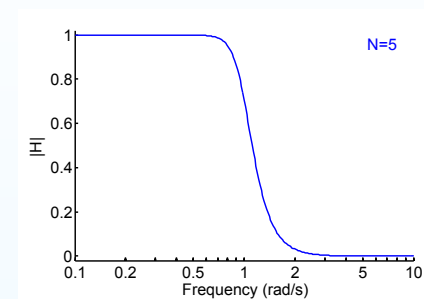
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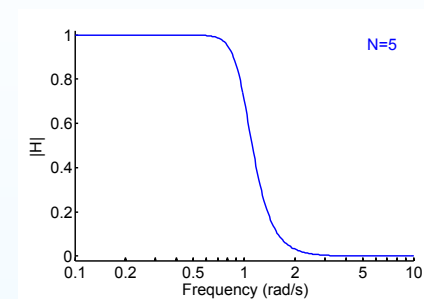
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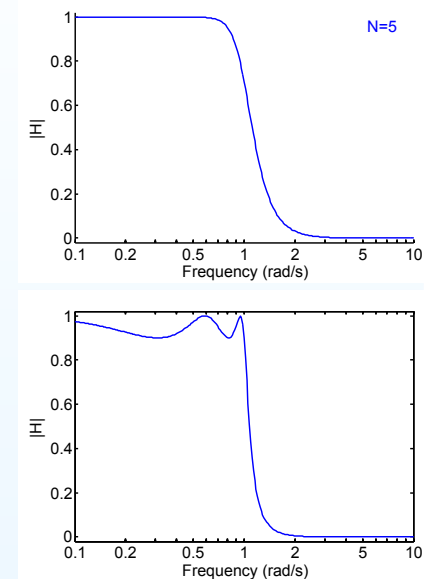
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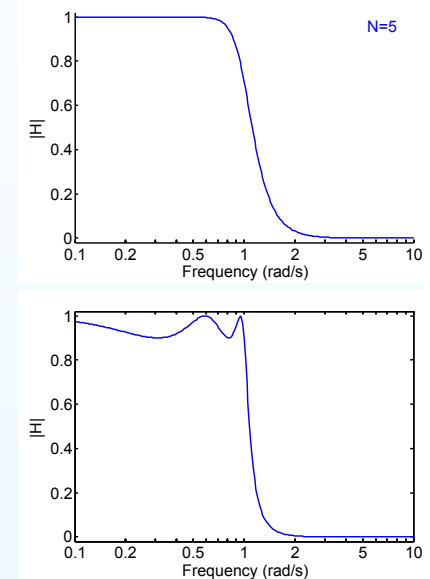
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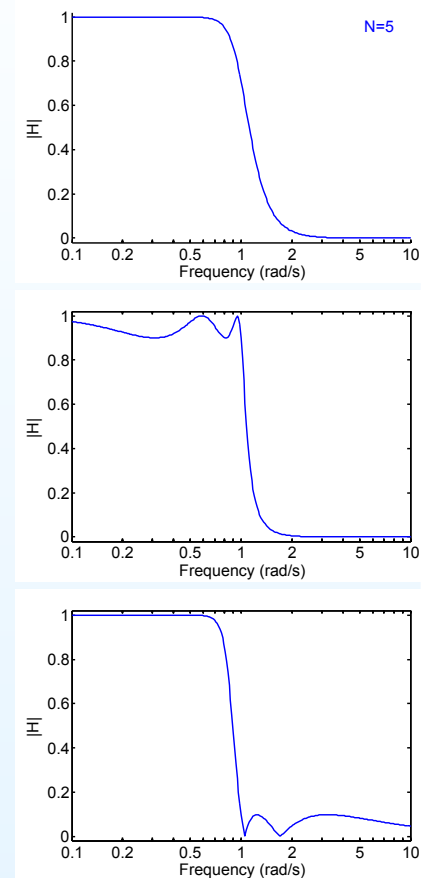
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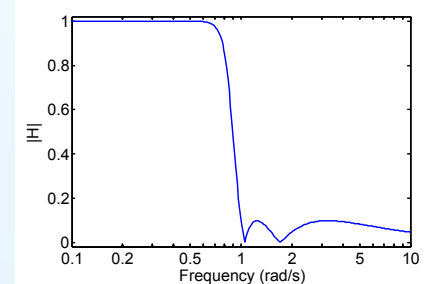
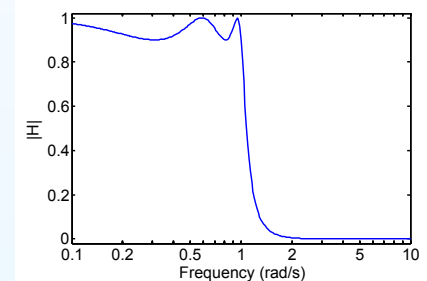
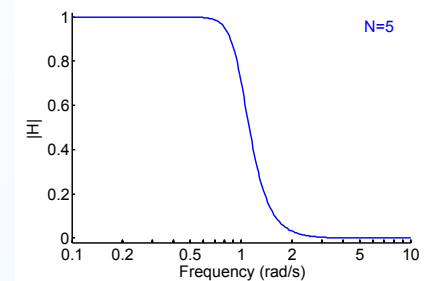
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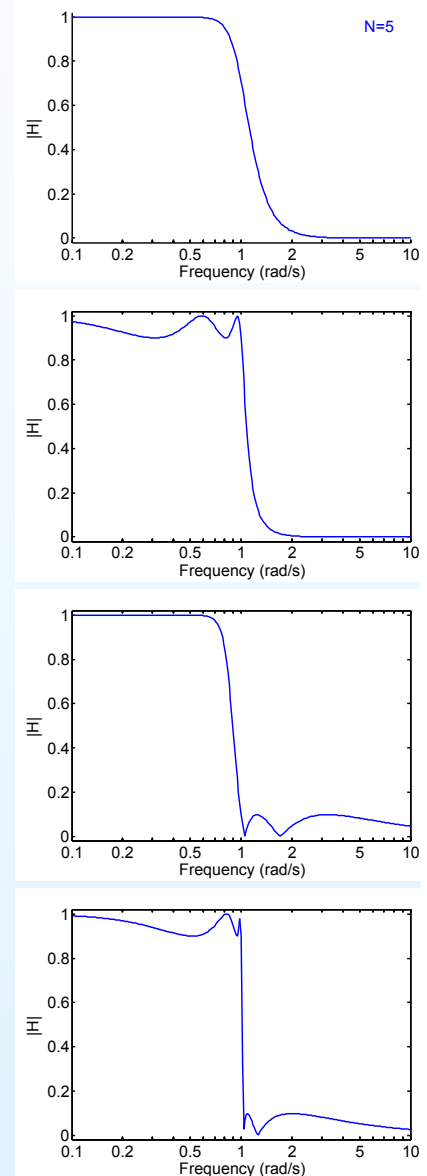
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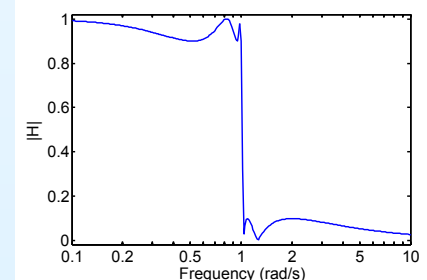
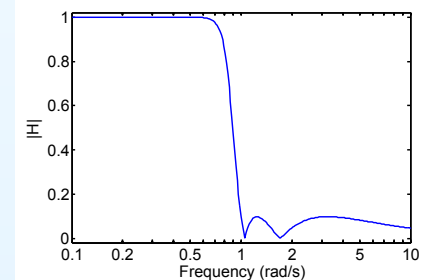
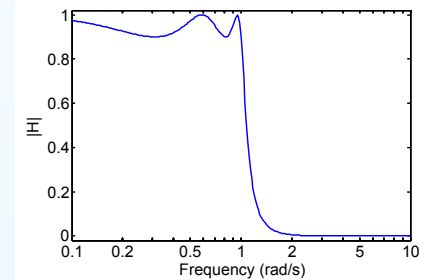
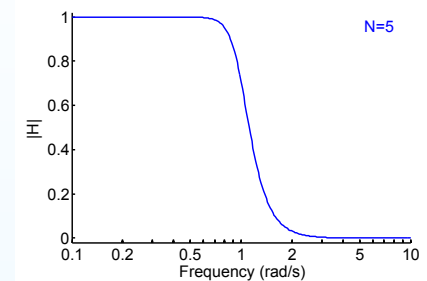
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Elliptic: [no nice formula]

- Very steep + equiripple in pass and stop bands



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There are explicit formulae for pole/zero positions.

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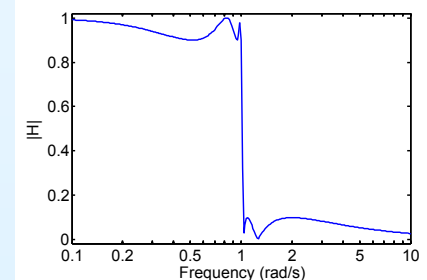
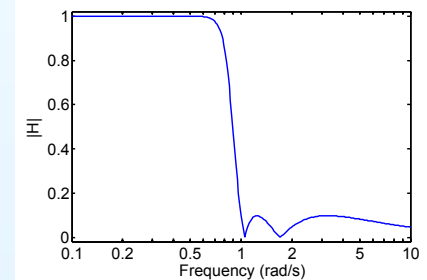
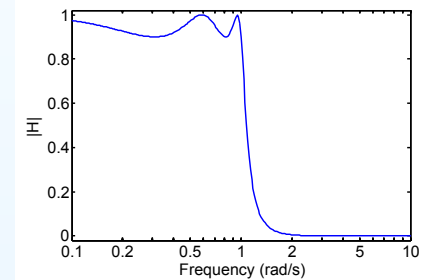
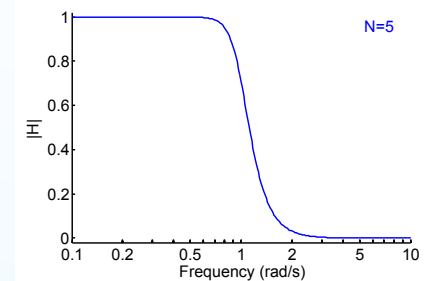
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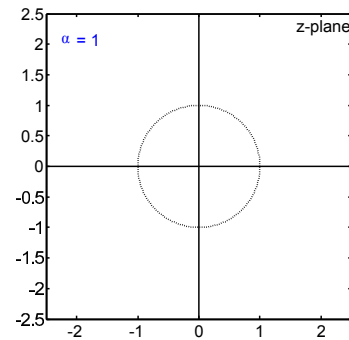
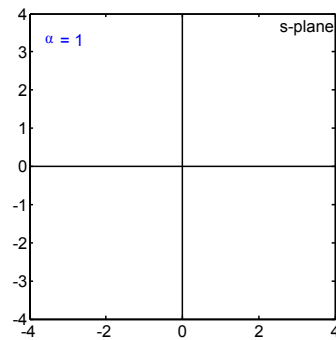


Bilinear Mapping

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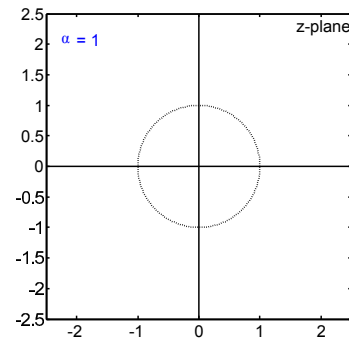
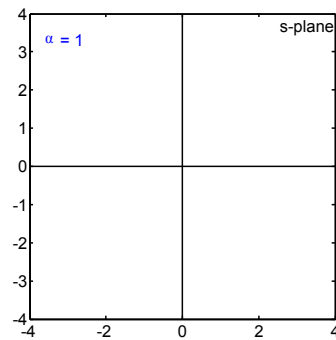


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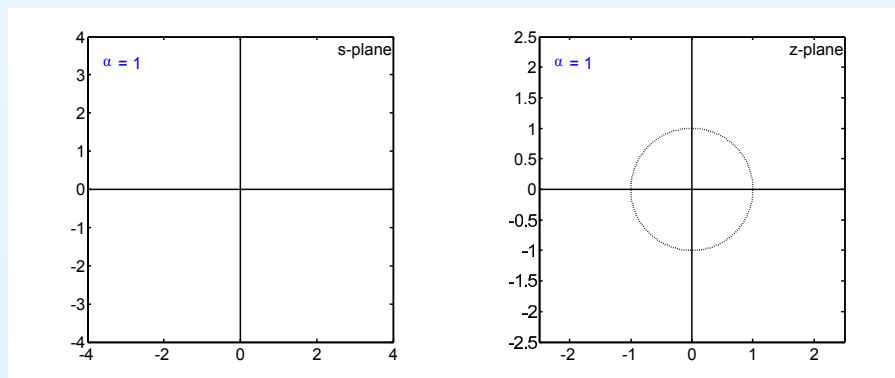


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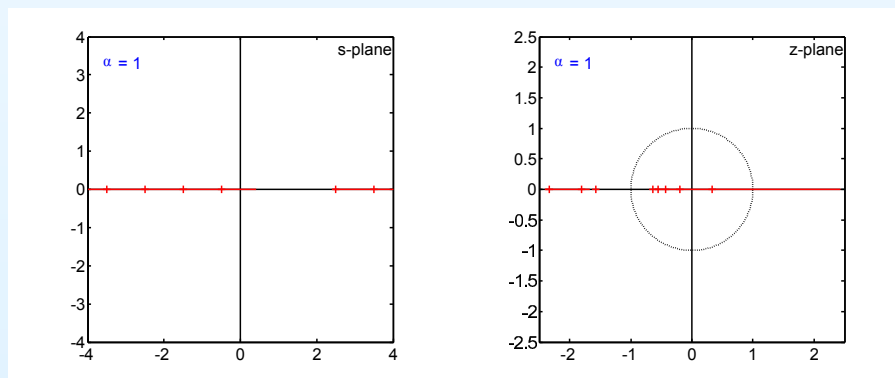
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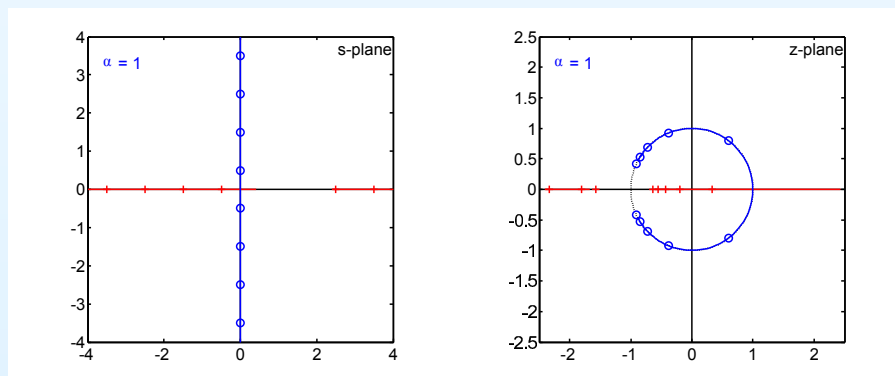
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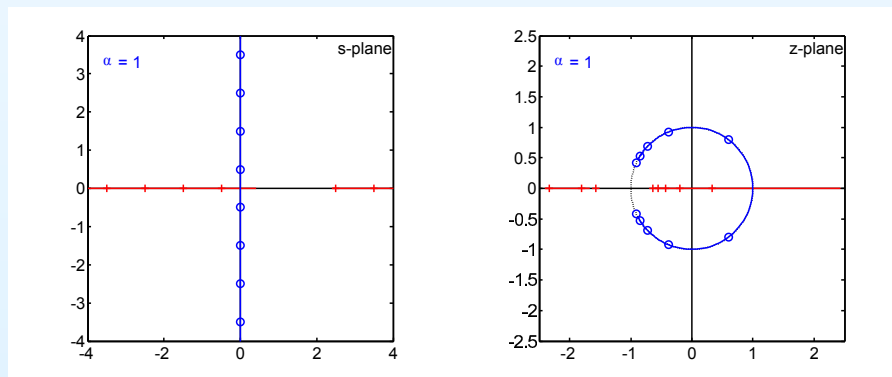
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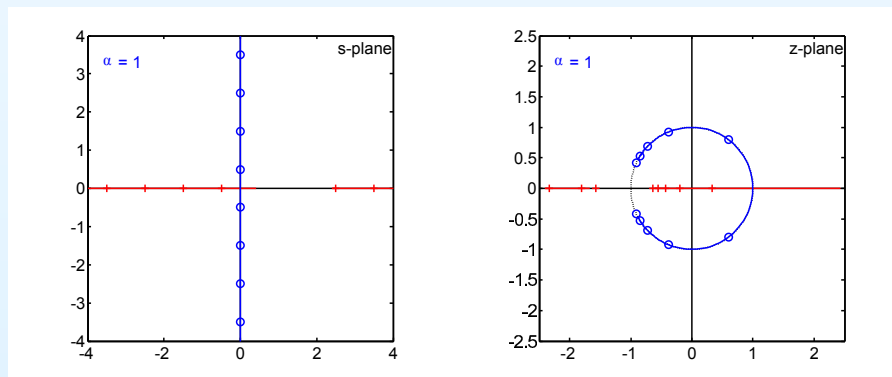
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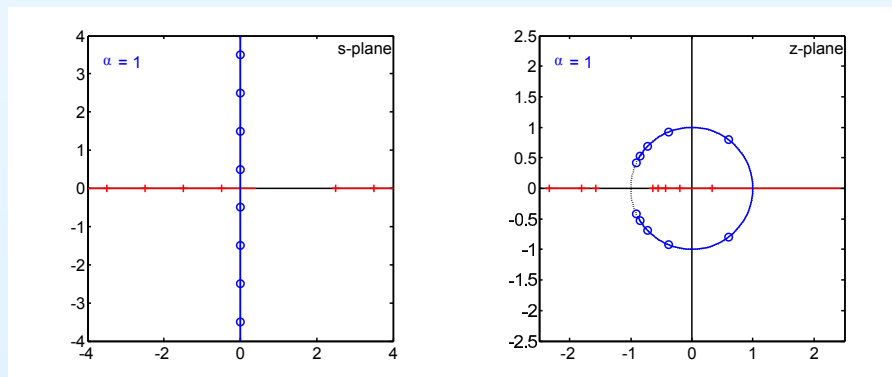
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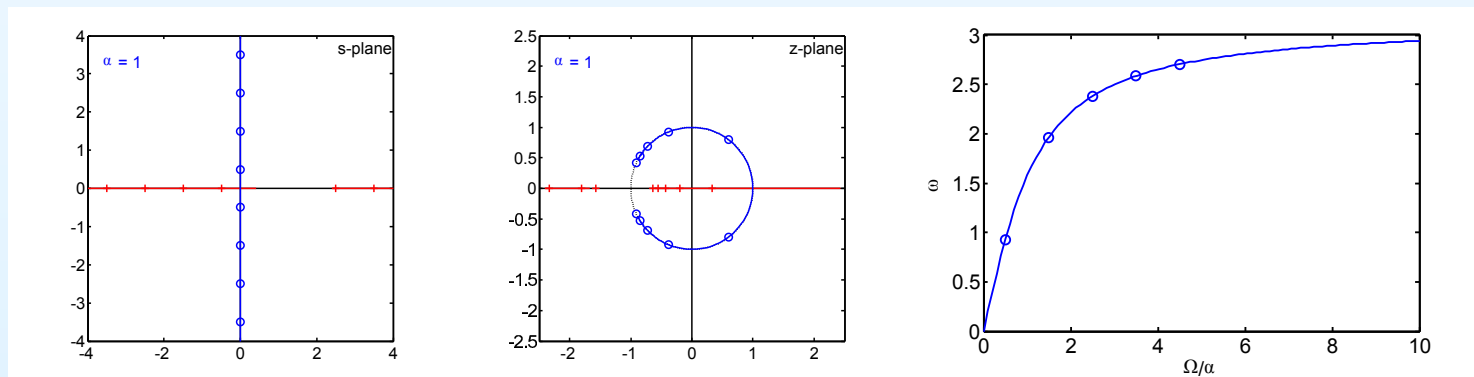
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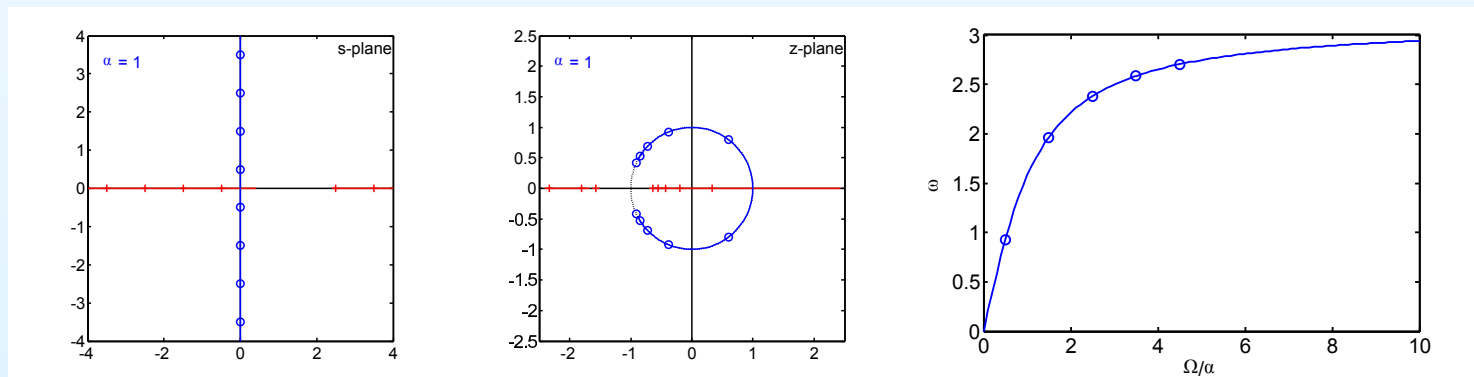
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Proof: $z = e^{j\omega} \Leftrightarrow s = \alpha \frac{e^{j\omega} - 1}{e^{j\omega} + 1} = \alpha \frac{e^{j\frac{\omega}{2}} - e^{-j\frac{\omega}{2}}}{e^{j\frac{\omega}{2}} + e^{-j\frac{\omega}{2}}} = j\alpha \tan \frac{\omega}{2} = j\Omega$

- Left half plane(s) \leftrightarrow inside of unit circle (z)



Bilinear Mapping

8: IIR Filter Transformations

- Continuous Time Filters
- **Bilinear Mapping**
- Continuous Time Filters
- Mapping Poles and Zeros
- Spectral Transformations
- Constantinides Transformations
- Impulse Invariance
- Summary
- MATLAB routines

Change variable: $z = \frac{\alpha+s}{\alpha-s} \Leftrightarrow s = \alpha \frac{z-1}{z+1}$: a one-to-one invertible mapping

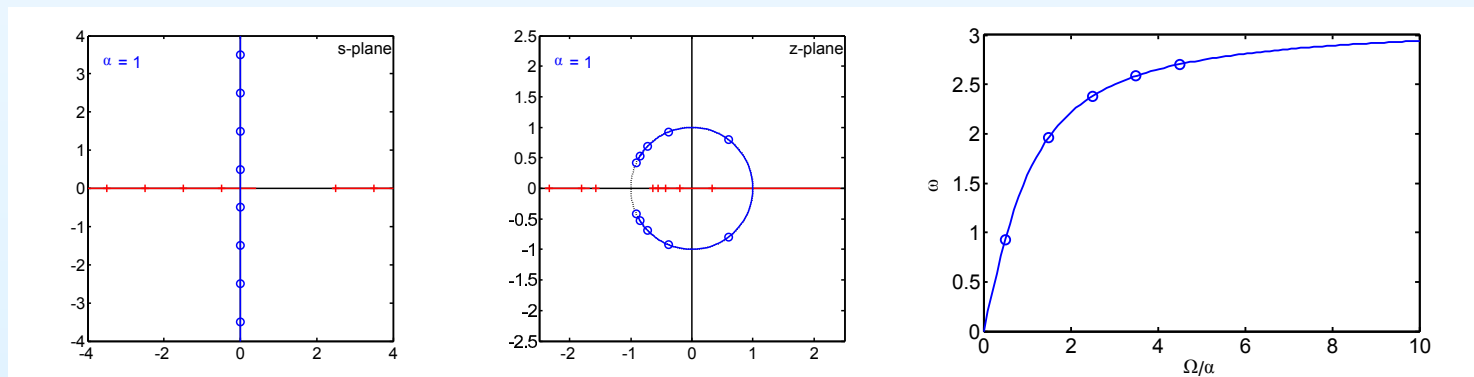
- \Re axis (s) $\leftrightarrow \Re$ axis (z)

- \Im axis (s) \leftrightarrow Unit circle (z)

Proof: $z = e^{j\omega} \Leftrightarrow s = \alpha \frac{e^{j\omega} - 1}{e^{j\omega} + 1} = \alpha \frac{e^{j\frac{\omega}{2}} - e^{-j\frac{\omega}{2}}}{e^{j\frac{\omega}{2}} + e^{-j\frac{\omega}{2}}} = j\alpha \tan \frac{\omega}{2} = j\Omega$

- Left half plane(s) \leftrightarrow inside of unit circle (z)

Proof: $s = x + jy \Leftrightarrow |z|^2 = \frac{|(\alpha+x)+jy|^2}{|(\alpha-x)-jy|^2}$



Bilinear Mapping

8: IIR Filter Transformations

- Continuous Time Filters
- **Bilinear Mapping**
- Continuous Time Filters
- Mapping Poles and Zeros
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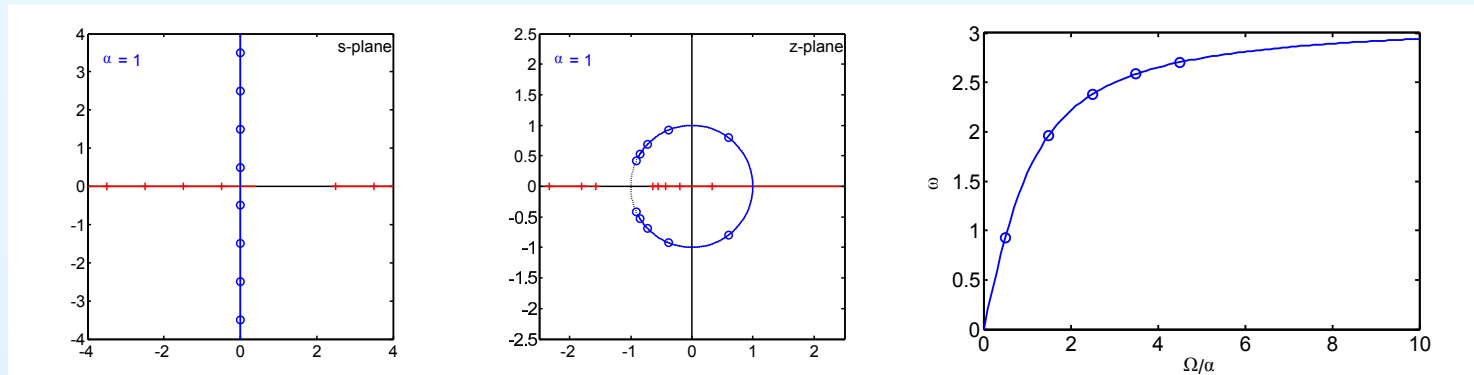
- \Re axis (s) $\leftrightarrow \Re$ axis (z)

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Proof: $z = e^{j\omega} \Leftrightarrow s = \alpha \frac{e^{j\omega} - 1}{e^{j\omega} + 1} = \alpha \frac{e^{j\frac{\omega}{2}} - e^{-j\frac{\omega}{2}}}{e^{j\frac{\omega}{2}} + e^{-j\frac{\omega}{2}}} = j\alpha \tan \frac{\omega}{2} = j\Omega$

- Left half plane(s) \leftrightarrow inside of unit circle (z)

Proof: $s = x + jy \Leftrightarrow |z|^2 = \frac{|(\alpha+x)+jy|^2}{|(\alpha-x)-jy|^2} = \frac{\alpha^2 + 2\alpha x + x^2 + y^2}{\alpha^2 - 2\alpha x + x^2 + y^2}$



Bilinear Mapping

8: IIR Filter Transformations

- Continuous Time Filters
- **Bilinear Mapping**
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- Mapping Poles and Zeros
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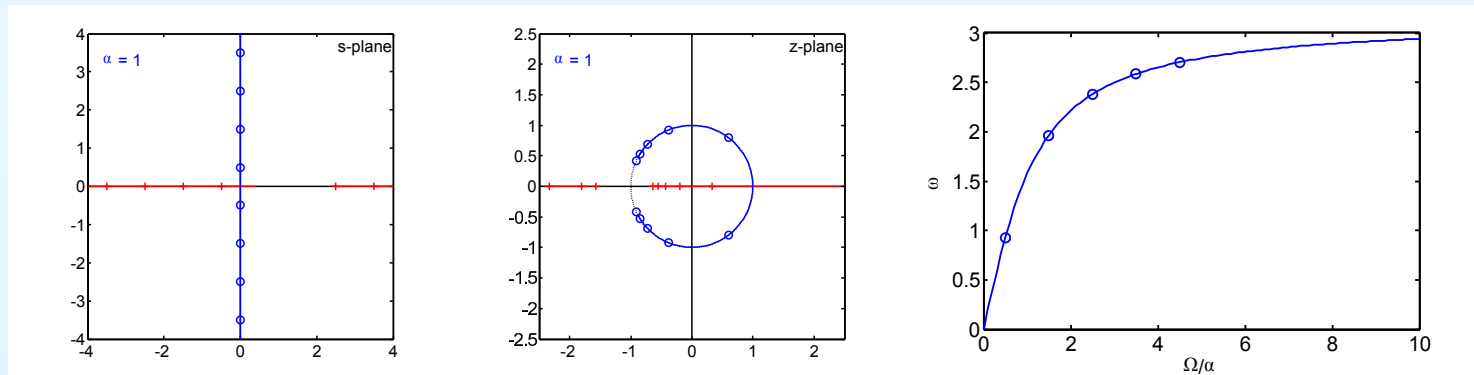
- \Re axis (s) $\leftrightarrow \Re$ axis (z)

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Proof: $s = x + jy \Leftrightarrow |z|^2 = \frac{|(\alpha+x)+jy|^2}{|(\alpha-x)-jy|^2} = \frac{\alpha^2 + 2\alpha x + x^2 + y^2}{\alpha^2 - 2\alpha x + x^2 + y^2} = 1 + \frac{4\alpha x}{(\alpha-x)^2 + y^2}$



Bilinear Mapping

8: IIR Filter Transformations

- Continuous Time Filters
- **Bilinear Mapping**
- Continuous Time Filters
- Mapping Poles and Zeros
- Spectral Transformations
- Constantinides Transformations
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- Summary
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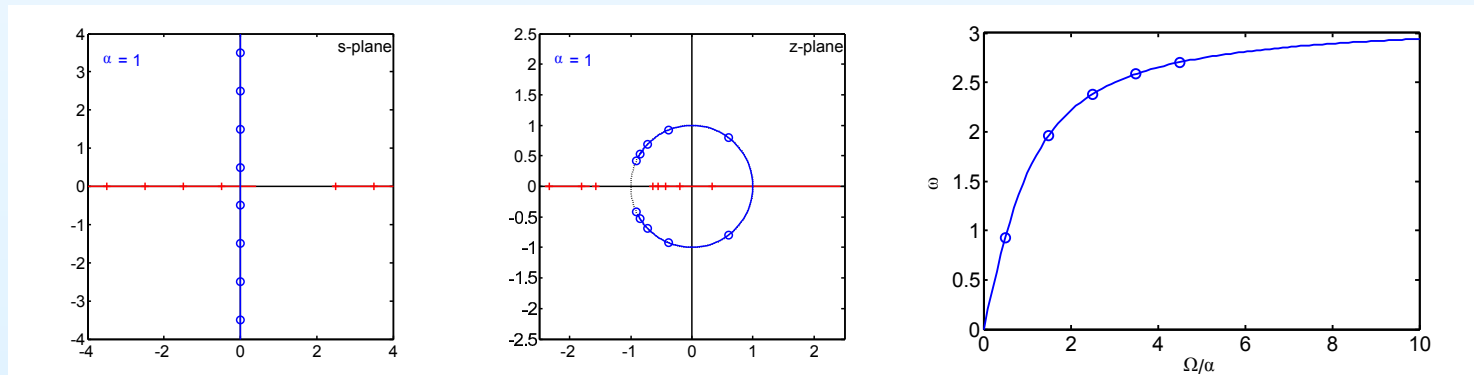
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Proof: $z = e^{j\omega} \Leftrightarrow s = \alpha \frac{e^{j\omega} - 1}{e^{j\omega} + 1} = \alpha \frac{e^{j\frac{\omega}{2}} - e^{-j\frac{\omega}{2}}}{e^{j\frac{\omega}{2}} + e^{-j\frac{\omega}{2}}} = j\alpha \tan \frac{\omega}{2} = j\Omega$

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Proof: $s = x + jy \Leftrightarrow |z|^2 = \frac{|(\alpha+x)+jy|^2}{|(\alpha-x)-jy|^2} = \frac{\alpha^2 + 2\alpha x + x^2 + y^2}{\alpha^2 - 2\alpha x + x^2 + y^2} = 1 + \frac{4\alpha x}{(\alpha-x)^2 + y^2}$

$$x < 0 \Leftrightarrow |z| < 1$$



Bilinear Mapping

8: IIR Filter Transformations

- Continuous Time Filters
- **Bilinear Mapping**
- Continuous Time Filters
- Mapping Poles and Zeros
- Spectral Transformations
- Constantinides Transformations
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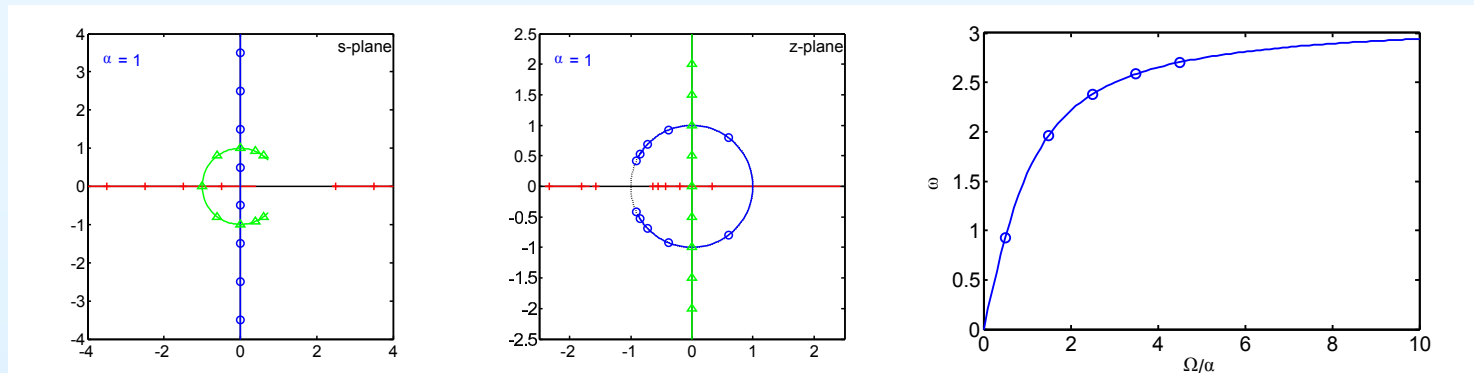
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Proof: $s = x + jy \Leftrightarrow |z|^2 = \frac{|(\alpha+x)+jy|^2}{|(\alpha-x)-jy|^2} = \frac{\alpha^2 + 2\alpha x + x^2 + y^2}{\alpha^2 - 2\alpha x + x^2 + y^2} = 1 + \frac{4\alpha x}{(\alpha-x)^2 + y^2}$

$$x < 0 \Leftrightarrow |z| < 1$$

- Unit circle (s) $\leftrightarrow \Im$ axis (z)

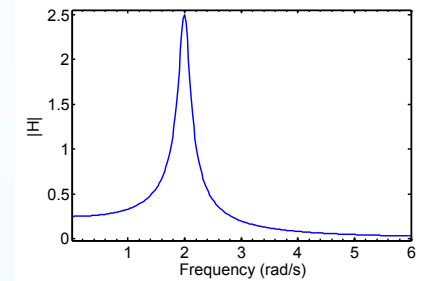


Continuous Time Filters

8: IIR Filter Transformations

- Continuous Time Filters
- Bilinear Mapping
- Continuous Time Filters
- Mapping Poles and Zeros
- Spectral Transformations
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- Summary
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Take $\tilde{H}(s) = \frac{1}{s^2 + 0.2s + 4}$ and choose $\alpha = 1$



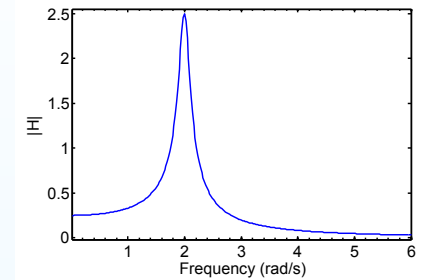
Continuous Time Filters

8: IIR Filter Transformations

- Continuous Time Filters
- Bilinear Mapping
- Continuous Time Filters
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Continuous Time Filters

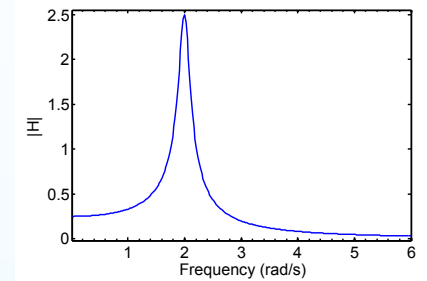
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- Continuous Time Filters
- Bilinear Mapping
- Continuous Time Filters
- Mapping Poles and Zeros
- Spectral Transformations
- Constantinides Transformations
- Impulse Invariance
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Substitute: $s = \alpha \frac{z-1}{z+1}$

$$H(z) = \frac{1}{\left(\frac{z-1}{z+1}\right)^2 + 0.2\frac{z-1}{z+1} + 4}$$



Continuous Time Filters

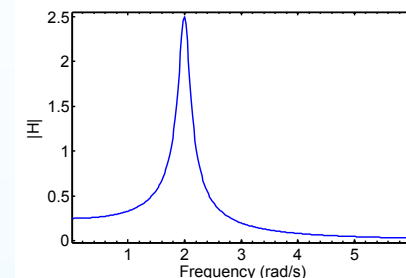
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- Continuous Time Filters
- Bilinear Mapping
- Continuous Time Filters
- Mapping Poles and Zeros
- Spectral Transformations
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- Impulse Invariance
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Substitute: $s = \alpha \frac{z-1}{z+1}$ [extra zeros at $z = -1$]

$$\begin{aligned} H(z) &= \frac{1}{\left(\frac{z-1}{z+1}\right)^2 + 0.2 \frac{z-1}{z+1} + 4} \\ &= \frac{(z+1)^2}{(z-1)^2 + 0.2(z-1)(z+1) + 4(z+1)^2} \end{aligned}$$



Continuous Time Filters

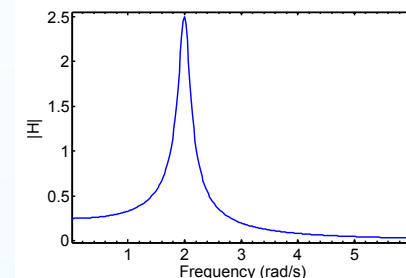
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- Continuous Time Filters
- Bilinear Mapping
- Continuous Time Filters
- Mapping Poles and Zeros
- Spectral Transformations
- Constantinides Transformations
- Impulse Invariance
- Summary
- MATLAB routines

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Continuous Time Filters

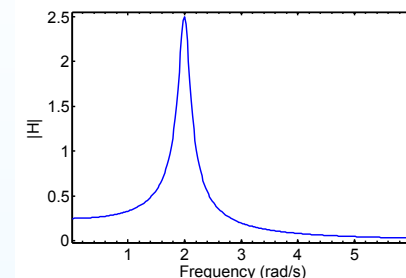
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- Continuous Time Filters
- Bilinear Mapping
- Continuous Time Filters
- Mapping Poles and Zeros
- Spectral Transformations
- Constantinides Transformations
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 &= \frac{z^2 + 2z + 1}{5.2z^2 + 6z + 4.8} = 0.19 \frac{1 + 2z^{-1} + z^{-2}}{1 + 1.15z^{-1} + 0.92z^{-2}}
 \end{aligned}$$



Continuous Time Filters

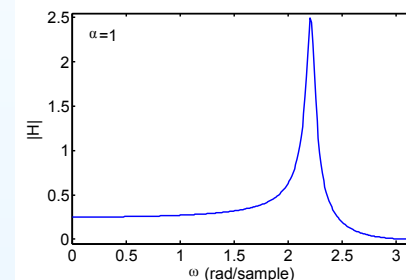
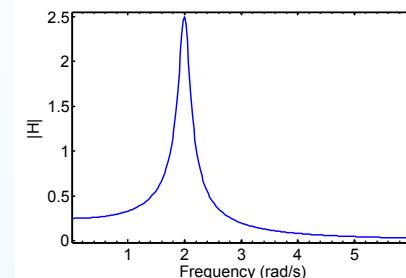
8: IIR Filter Transformations

- Continuous Time Filters
- Bilinear Mapping
- Continuous Time Filters
- Mapping Poles and Zeros
- Spectral Transformations
- Constantinides Transformations
- Impulse Invariance
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Continuous Time Filters

8: IIR Filter Transformations

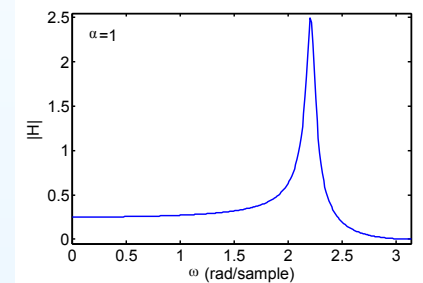
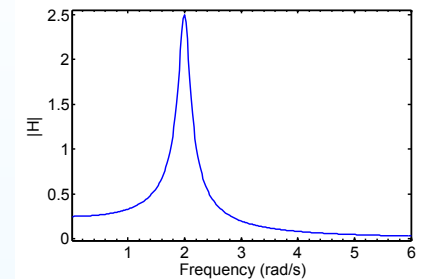
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- Continuous Time Filters
- Mapping Poles and Zeros
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Frequency response is identical (both magnitude and phase) but with a distorted frequency axis:



Continuous Time Filters

8: IIR Filter Transformations

- Continuous Time Filters
- Bilinear Mapping
- Continuous Time Filters
- Mapping Poles and Zeros
- Spectral Transformations
- Constantinides Transformations
- Impulse Invariance
- Summary
- MATLAB routines

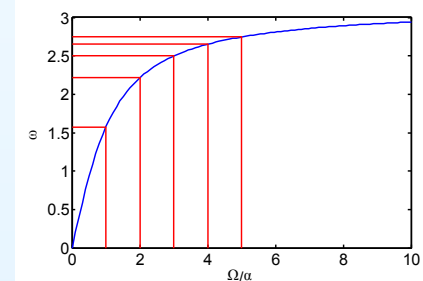
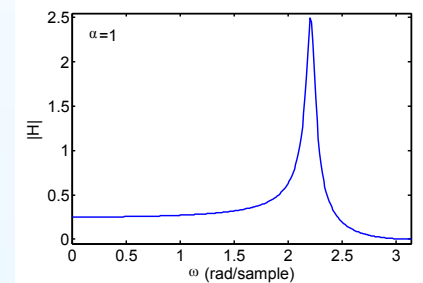
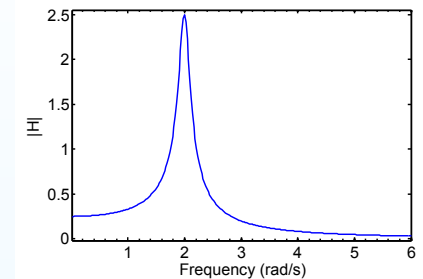
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 H(z) &= \frac{1}{\left(\frac{z-1}{z+1}\right)^2 + 0.2\frac{z-1}{z+1} + 4} \\
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 \end{aligned}$$

Frequency response is identical (both magnitude and phase) but with a distorted frequency axis:

Frequency mapping: $\omega = 2 \tan^{-1} \frac{\Omega}{\alpha}$



Continuous Time Filters

8: IIR Filter Transformations

- Continuous Time Filters
- Bilinear Mapping
- Continuous Time Filters
- Mapping Poles and Zeros
- Spectral Transformations
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- Impulse Invariance
- Summary
- MATLAB routines

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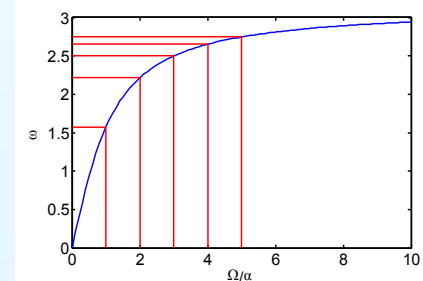
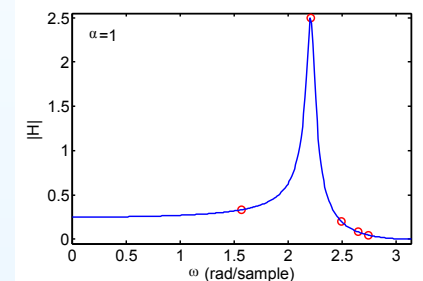
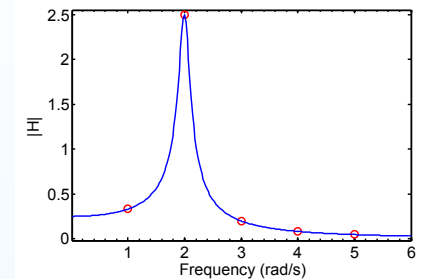
Substitute: $s = \alpha \frac{z-1}{z+1}$ [extra zeros at $z = -1$]

$$\begin{aligned}
 H(z) &= \frac{1}{\left(\frac{z-1}{z+1}\right)^2 + 0.2\frac{z-1}{z+1} + 4} \\
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 \end{aligned}$$

Frequency response is identical (both magnitude and phase) but with a distorted frequency axis:

Frequency mapping: $\omega = 2 \tan^{-1} \frac{\Omega}{\alpha}$

$$\begin{aligned}
 \Omega &= [\alpha \quad 2\alpha \quad 3\alpha \quad 4\alpha \quad 5\alpha] \\
 \rightarrow \omega &= [1.6 \quad 2.2 \quad 2.5 \quad 2.65 \quad 2.75]
 \end{aligned}$$



Continuous Time Filters

8: IIR Filter Transformations

- Continuous Time Filters
- Bilinear Mapping
- Continuous Time Filters
- Mapping Poles and Zeros
- Spectral Transformations
- Constantinides Transformations
- Impulse Invariance
- Summary
- MATLAB routines

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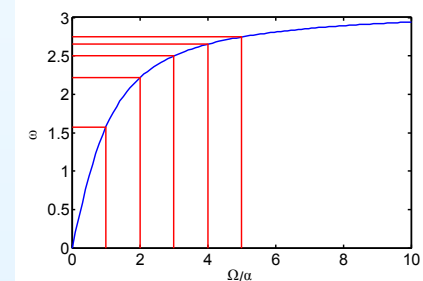
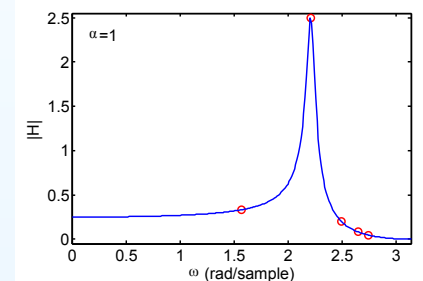
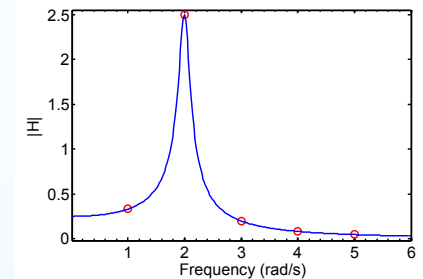
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Frequency response is identical (both magnitude and phase) but with a distorted frequency axis:

Frequency mapping: $\omega = 2 \tan^{-1} \frac{\Omega}{\alpha}$

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Choosing α : Set $\alpha = \frac{\Omega_0}{\tan \frac{1}{2}\omega_0}$ to map $\Omega_0 \rightarrow \omega_0$



Continuous Time Filters

8: IIR Filter Transformations

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- Bilinear Mapping
- Continuous Time Filters
- Mapping Poles and Zeros
- Spectral Transformations
- Constantinides Transformations
- Impulse Invariance
- Summary
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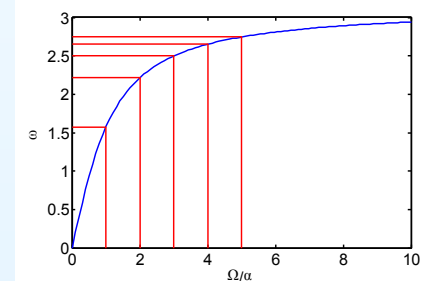
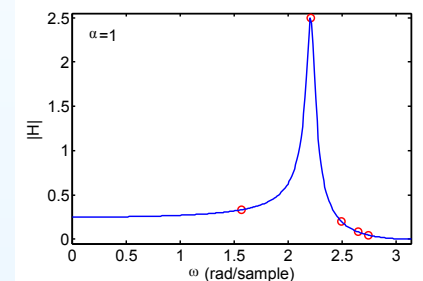
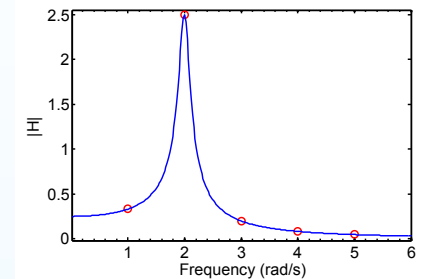
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Choosing α : Set $\alpha = \frac{\Omega_0}{\tan \frac{1}{2}\omega_0}$ to map $\Omega_0 \rightarrow \omega_0$

Set $\alpha = 2f_s = \frac{2}{T}$ to map low frequencies to themselves

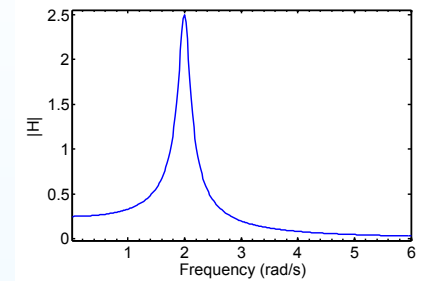


Mapping Poles and Zeros

8: IIR Filter Transformations

- Continuous Time Filters
- Bilinear Mapping
- Continuous Time Filters
- Mapping Poles and Zeros
- Spectral Transformations
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- Impulse Invariance
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Alternative method: $\tilde{H}(s) = \frac{1}{s^2 + 0.2s + 4}$



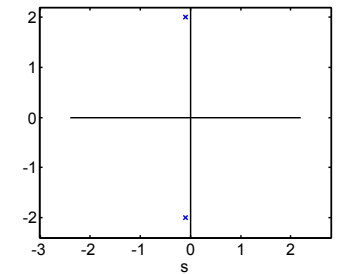
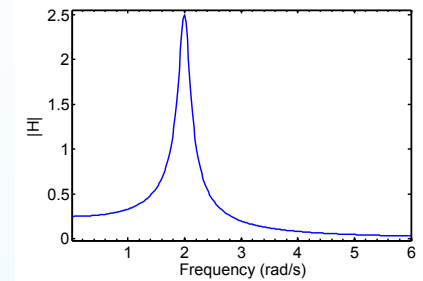
Mapping Poles and Zeros

8: IIR Filter Transformations

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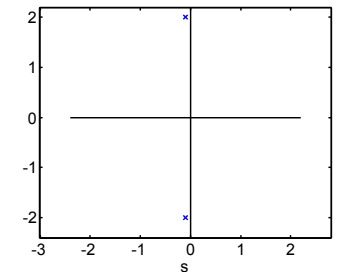
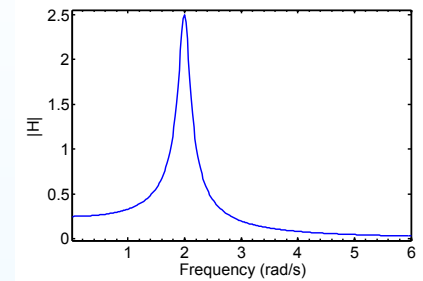
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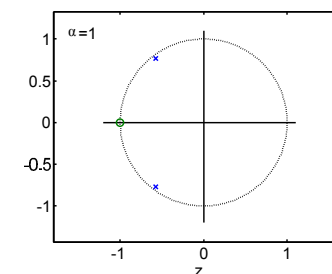
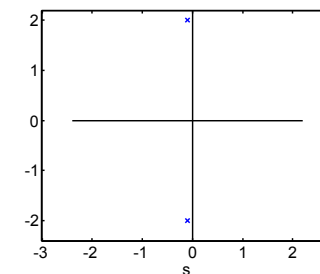
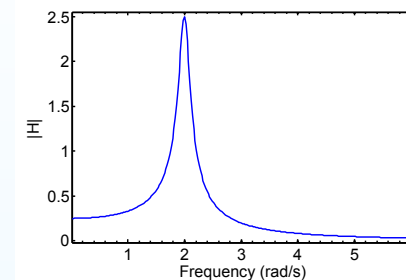
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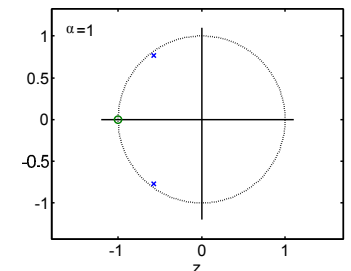
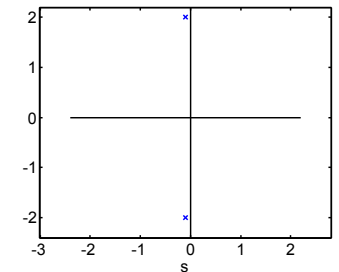
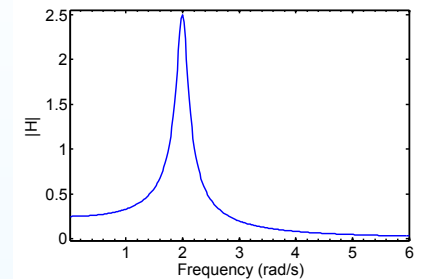
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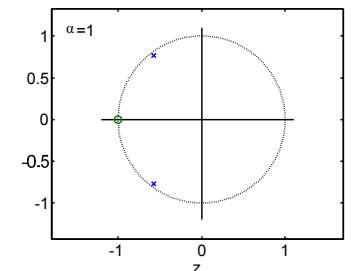
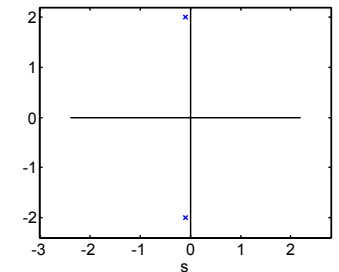
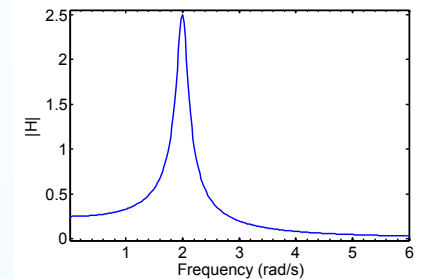
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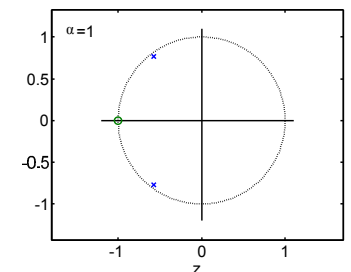
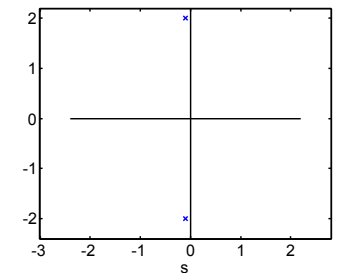
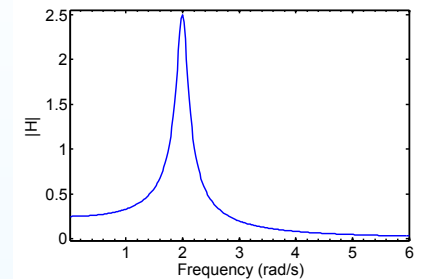
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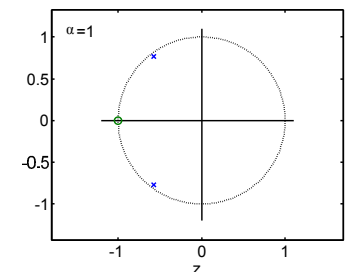
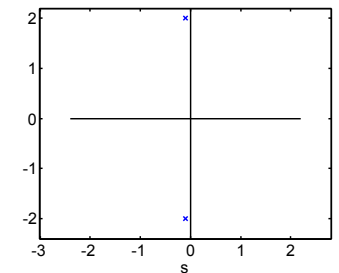
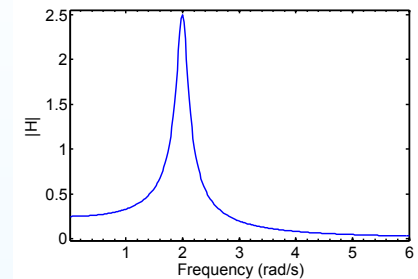
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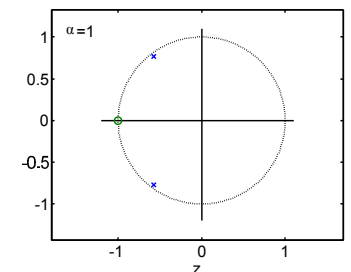
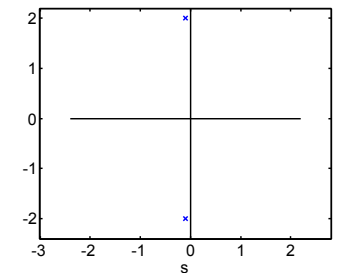
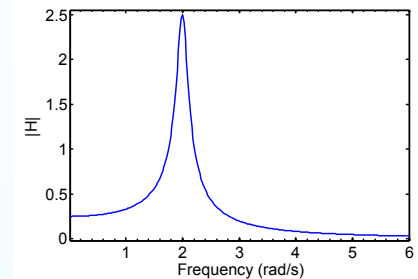
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Mapping Poles and Zeros

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- Bilinear Mapping
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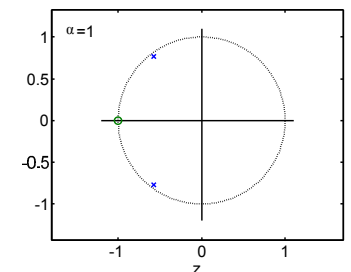
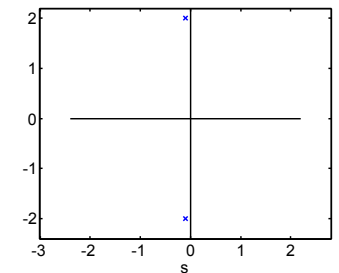
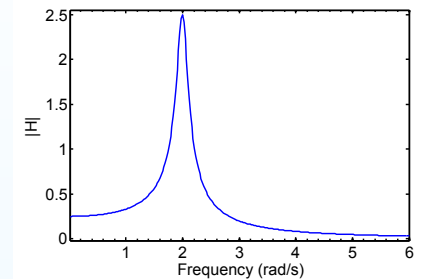
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Mapping Poles and Zeros

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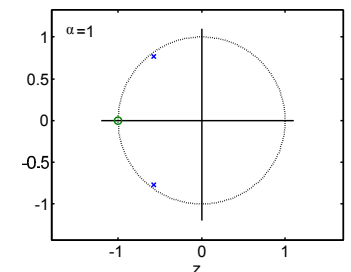
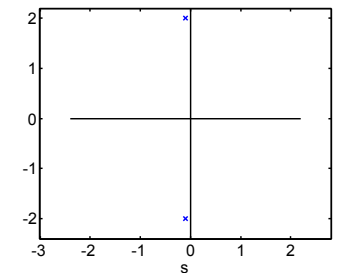
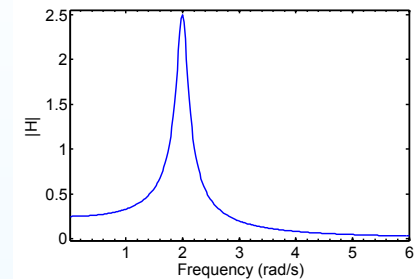
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Mapping Poles and Zeros

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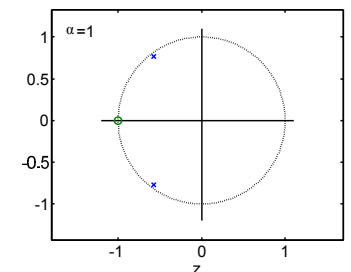
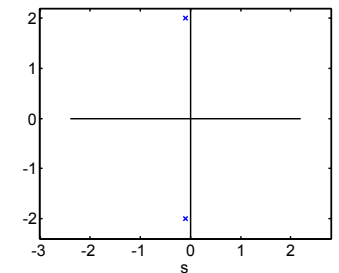
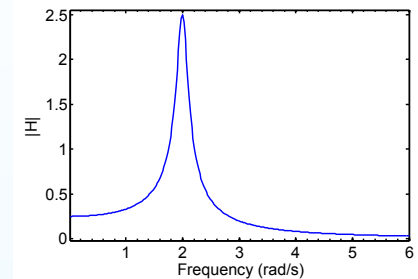
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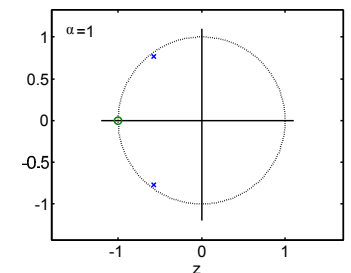
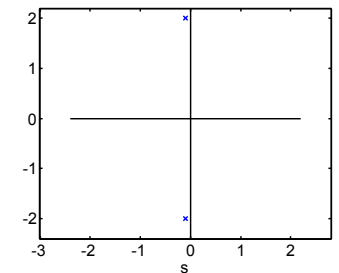
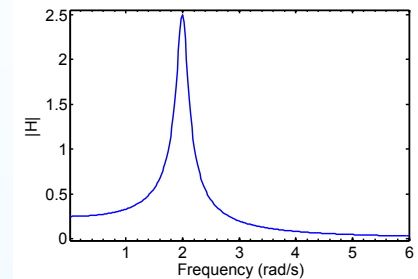
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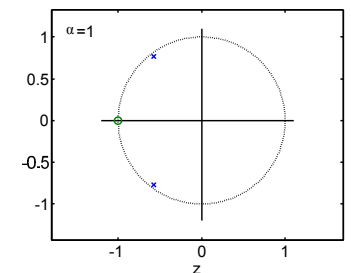
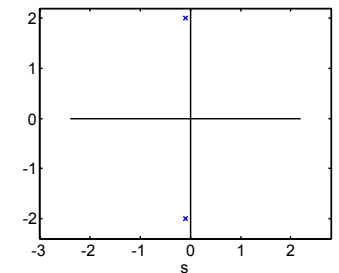
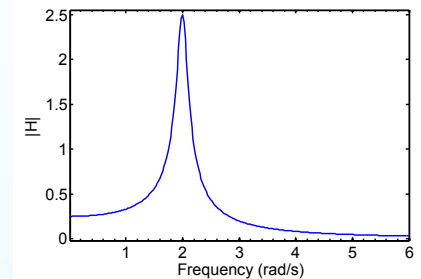
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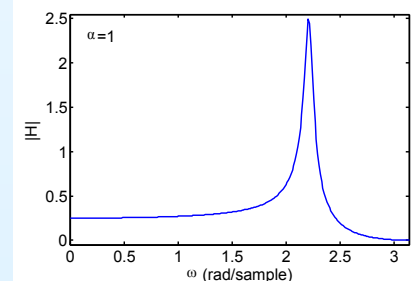
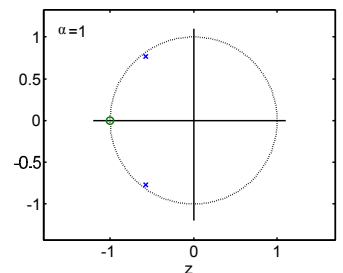
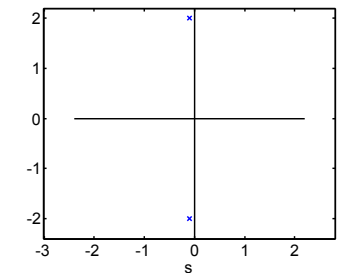
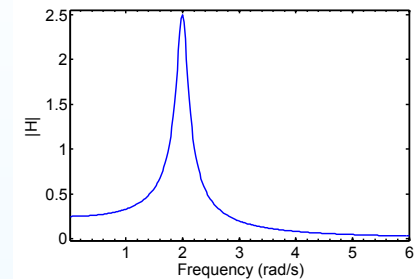
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- Bilinear Mapping
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- Constantinides Transformations
- Impulse Invariance
- Summary
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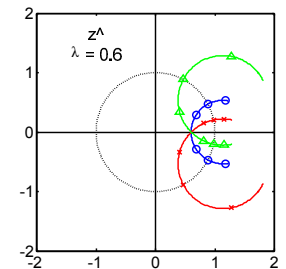
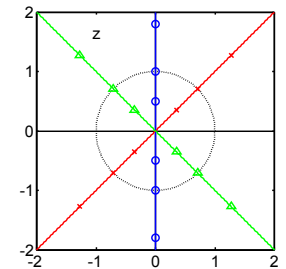
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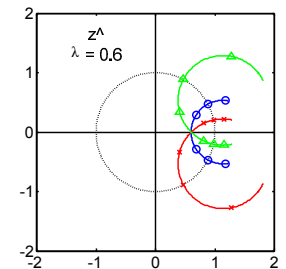
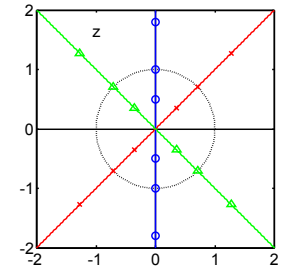
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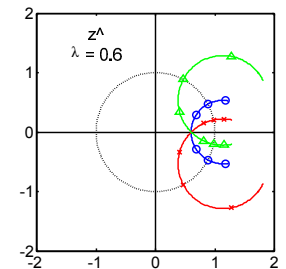
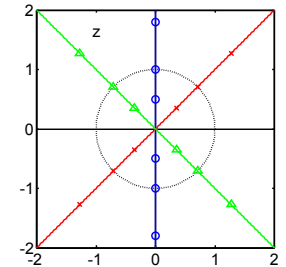
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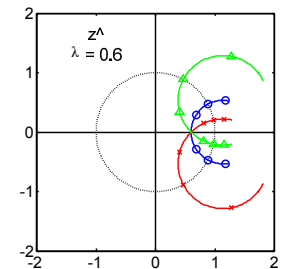
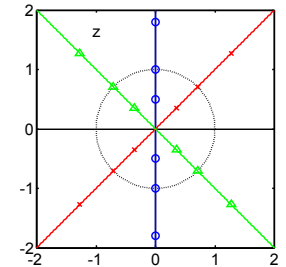
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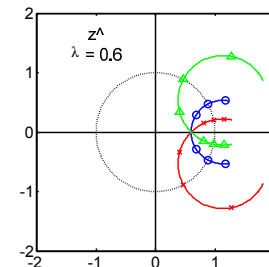
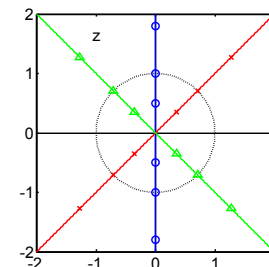
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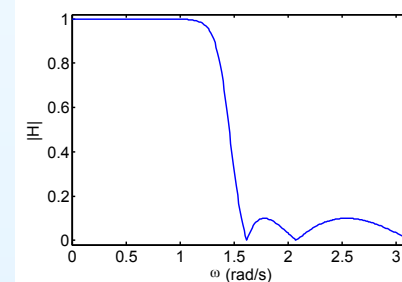
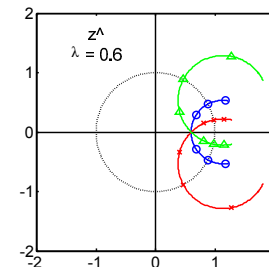
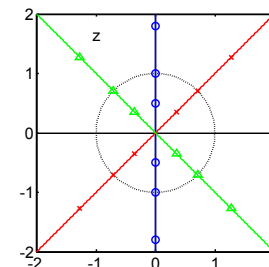
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Lowpass Filter example:

Inverse Chebyshev

$$\omega_0 = \frac{\pi}{2} = 1.57$$



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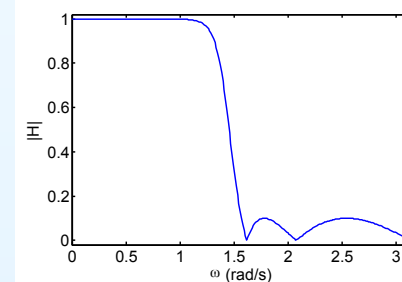
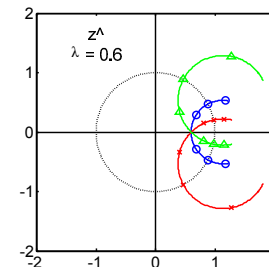
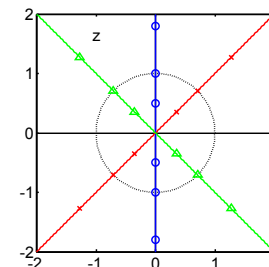
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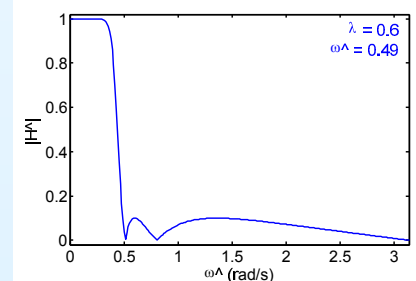
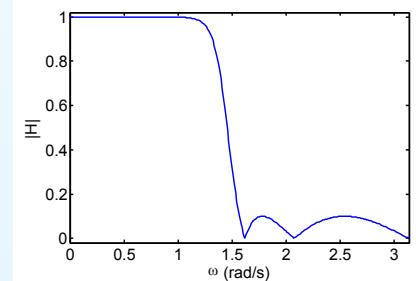
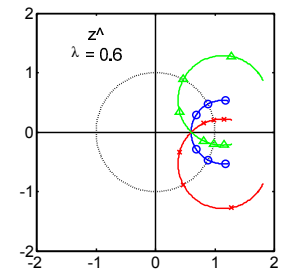
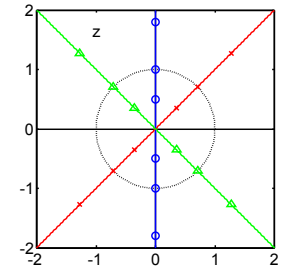
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Explicit Computation

$\lambda = 4/10$ and $\omega_0 = \pi/2$.

$$\tan\left(\frac{\omega}{2}\right) = \frac{1+\lambda}{1-\lambda} \tan\left(\frac{\hat{\omega}}{2}\right)$$

$$\rightarrow \underbrace{\tan\left(\frac{\pi}{4}\right)}_{=1} = \underbrace{\frac{1+0.6}{0.4}}_{=4} \tan\left(\frac{\hat{\omega}}{2}\right)$$

$$\Rightarrow \hat{\omega} = 2 \tan^{-1}\left(\frac{1}{4}\right) \approx \frac{49}{100}$$

Constantinides Transformations

Transform any lowpass filter with cutoff frequency ω_0 to:

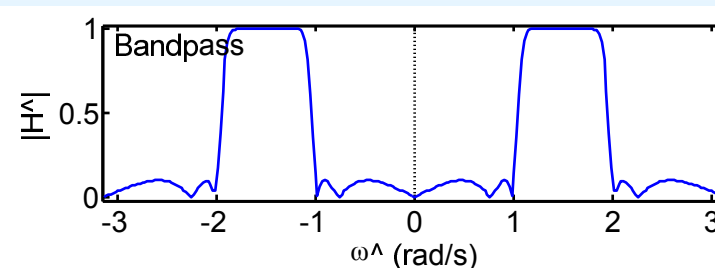
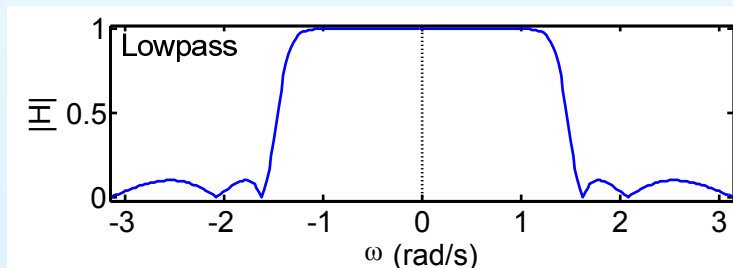
Target	Substitute	Parameters
Lowpass $\hat{\omega} < \hat{\omega}_1$	$z^{-1} = \frac{\hat{z}^{-1} - \lambda}{1 - \lambda \hat{z}^{-1}}$	$\lambda = \frac{\sin\left(\frac{\omega_0 - \hat{\omega}_1}{2}\right)}{\sin\left(\frac{\omega_0 + \hat{\omega}_1}{2}\right)}$
Highpass $\hat{\omega} > \hat{\omega}_1$	$z^{-1} = -\frac{\hat{z}^{-1} + \lambda}{1 + \lambda \hat{z}^{-1}}$	$\lambda = \frac{\cos\left(\frac{\omega_0 + \hat{\omega}_1}{2}\right)}{\cos\left(\frac{\omega_0 - \hat{\omega}_1}{2}\right)}$
Bandpass $\hat{\omega}_1 < \hat{\omega} < \hat{\omega}_2$	$z^{-1} = -\frac{(\rho-1) - 2\lambda\rho\hat{z}^{-1} + (\rho+1)\hat{z}^{-2}}{(\rho+1) - 2\lambda\rho\hat{z}^{-1} + (\rho-1)\hat{z}^{-2}}$	$\lambda = \frac{\cos\left(\frac{\hat{\omega}_2 + \hat{\omega}_1}{2}\right)}{\cos\left(\frac{\hat{\omega}_2 - \hat{\omega}_1}{2}\right)}$ $\rho = \cot\left(\frac{\hat{\omega}_2 - \hat{\omega}_1}{2}\right) \tan\left(\frac{\omega_0}{2}\right)$
Bandstop $\hat{\omega}_1 \not< \hat{\omega} \not< \hat{\omega}_2$	$z^{-1} = \frac{(1-\rho) - 2\lambda\hat{z}^{-1} + (\rho+1)\hat{z}^{-2}}{(\rho+1) - 2\lambda\hat{z}^{-1} + (1-\rho)\hat{z}^{-2}}$	$\lambda = \frac{\cos\left(\frac{\hat{\omega}_2 + \hat{\omega}_1}{2}\right)}{\cos\left(\frac{\hat{\omega}_2 - \hat{\omega}_1}{2}\right)}$ $\rho = \tan\left(\frac{\hat{\omega}_2 - \hat{\omega}_1}{2}\right) \tan\left(\frac{\omega_0}{2}\right)$

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Bandpass and bandstop transformations are quadratic and so will double the order:



Impulse Invariance

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Bilinear transform works well for a lowpass filter but the non-linear compression of the frequency distorts any other response.

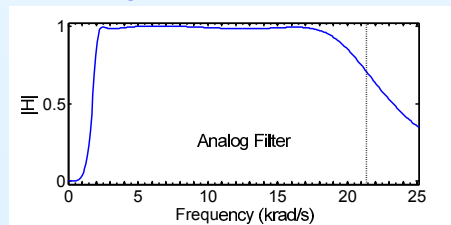
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Example: Standard telephone filter - 300 to 3400 Hz bandpass



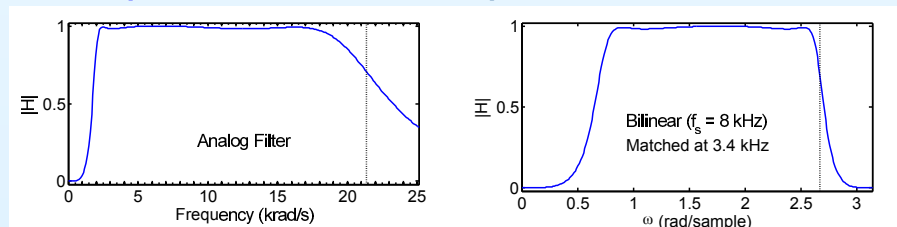
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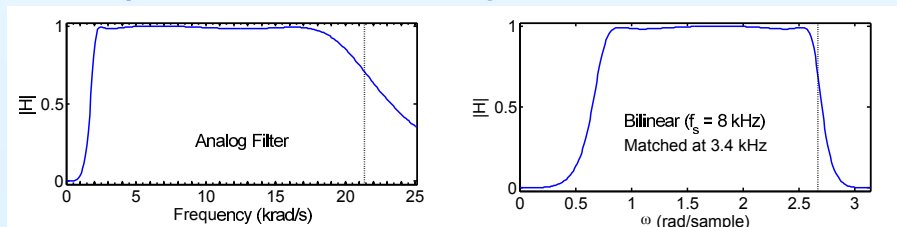
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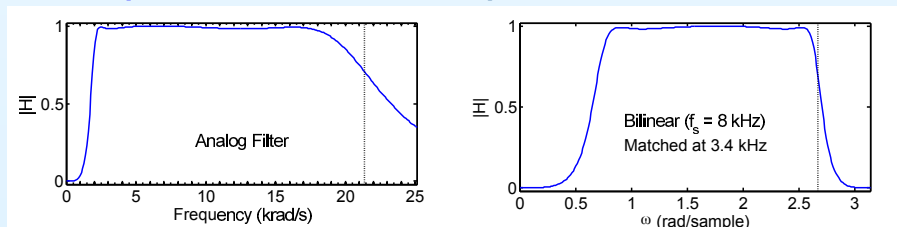
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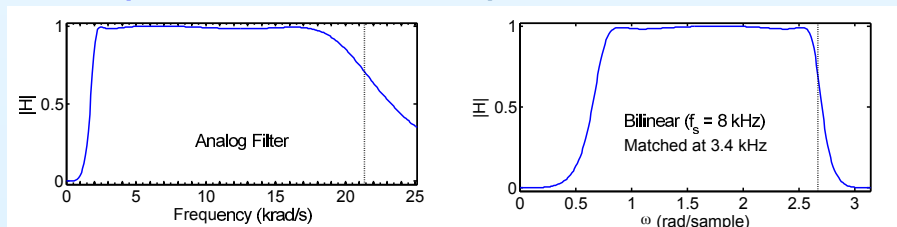
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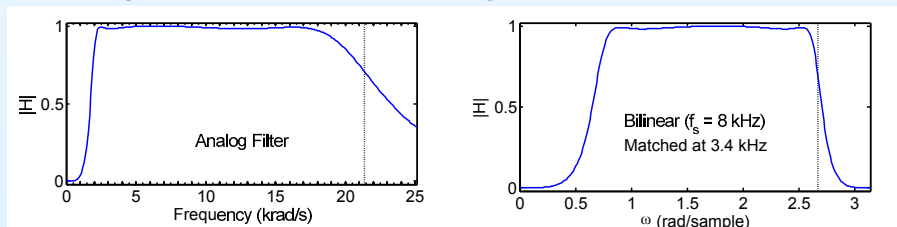
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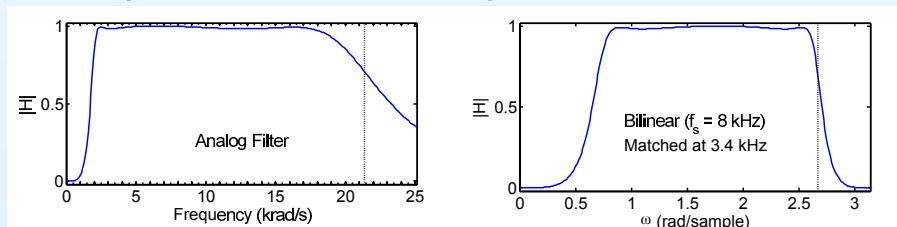
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Zeros do not map in a simple way

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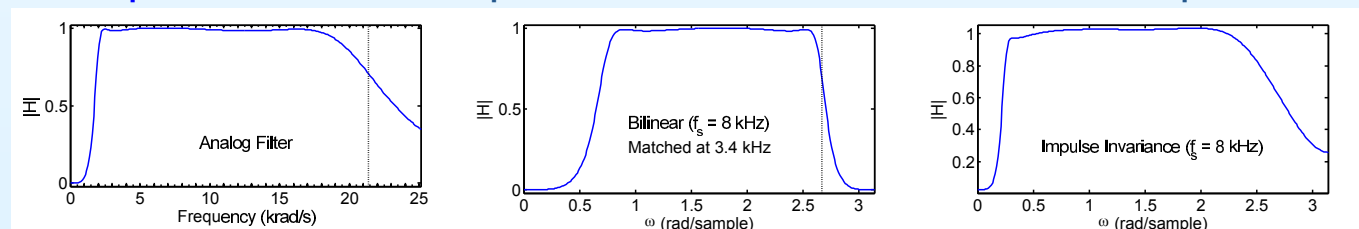
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Digital filter $\frac{H(z)}{T} = \sum_{i=1}^N \frac{g_i}{1 - e^{\tilde{p}_i T} z^{-1}}$ has identical impulse response

Poles of $H(z)$ are $p_i = e^{\tilde{p}_i T}$ (where $T = \frac{1}{f_s}$ is sampling period)

Zeros do not map in a simple way

Example: Standard telephone filter - 300 to 3400 Hz bandpass



Impulse Invariance

8: IIR Filter Transformations

- Continuous Time Filters
- Bilinear Mapping
- Continuous Time Filters
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- Constantinides Transformations
- **Impulse Invariance**
- Summary
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Bilinear transform works well for a lowpass filter but the non-linear compression of the frequency distorts any other response.

Alternative method:

$$\tilde{H}(s) \xrightarrow{\mathcal{L}^{-1}} h(t) \xrightarrow{\text{sample}} h[n] = T \times h(nT) \xrightarrow{\mathcal{Z}} H(z)$$

Express $\tilde{H}(s)$ as a sum of partial fractions $\tilde{H}(s) = \sum_{i=1}^N \frac{g_i}{s - \tilde{p}_i}$

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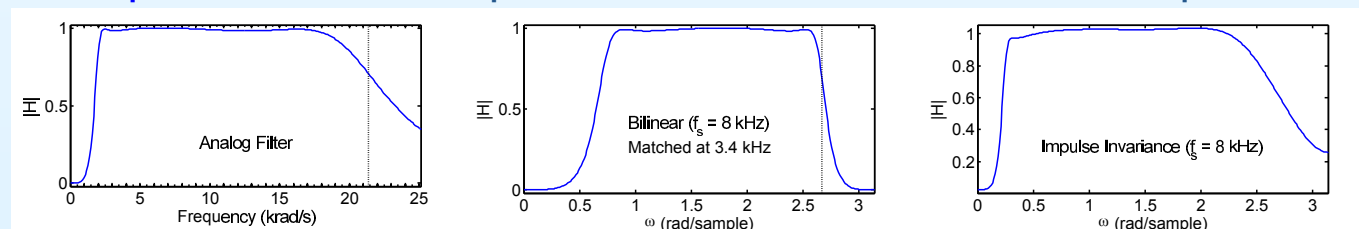
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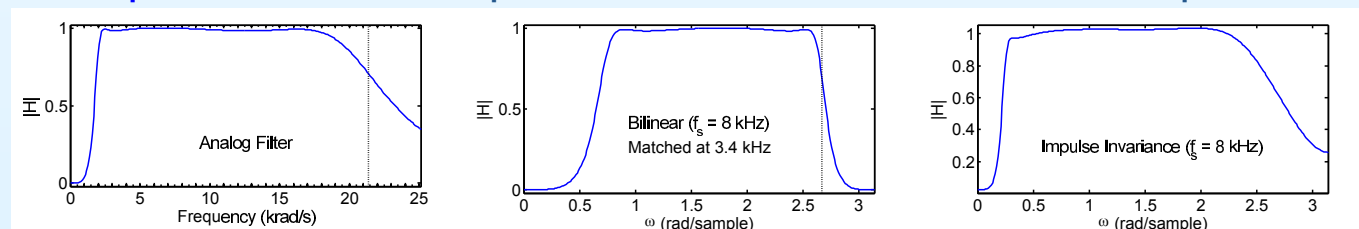
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😊 **Impulse response correct.**

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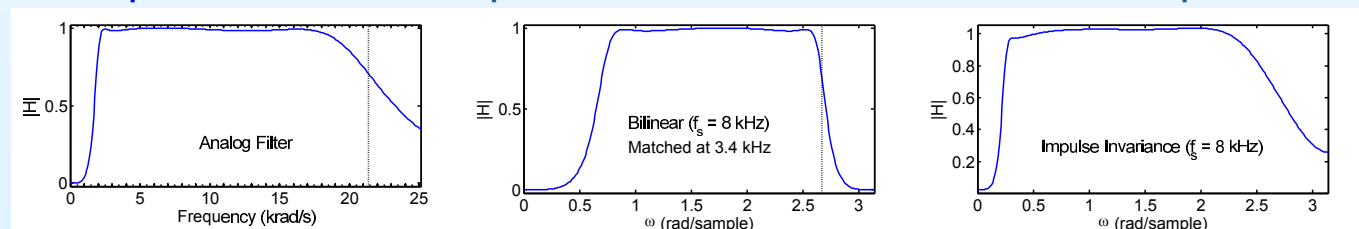
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Zeros do not map in a simple way

Properties:

- ☺ Impulse response correct.
- ☺ No distortion of frequency axis.

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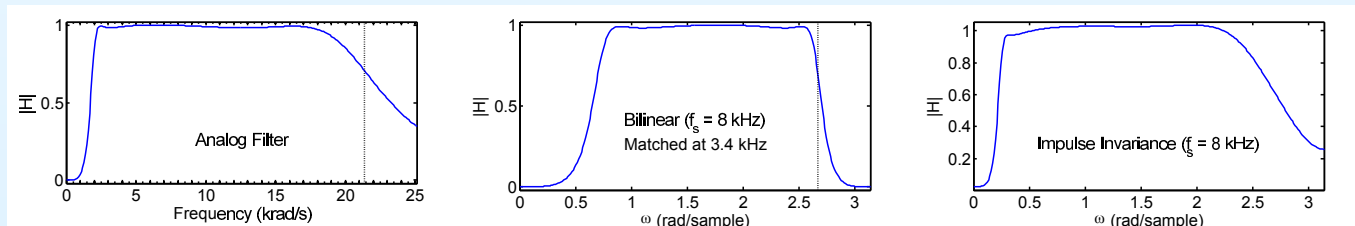
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Zeros do not map in a simple way

Properties:

- ☺ Impulse response correct.
- ☺ No distortion of frequency axis.
- ☹ Frequency response is aliased.

Example: Standard telephone filter - 300 to 3400 Hz bandpass



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 - Order \leftrightarrow transition width \leftrightarrow pass ripple \leftrightarrow stop ripple
 - Monotonic passband and/or stopband

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- **Classical filters** have optimal tradeoffs in continuous time domain
 - Order \leftrightarrow transition width \leftrightarrow pass ripple \leftrightarrow stop ripple
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- **Bilinear mapping**
 - Exact preservation of frequency response (mag + phase)
 - non-linear frequency axis distortion
 - can choose α to map $\Omega_0 \rightarrow \omega_0$ for one specific frequency

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For further details see Mitra: 9.

MATLAB routines

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bilinear	Bilinear mapping
impinvar	Impulse invariance
butter butterord	Analog or digital Butterworth filter
cheby1 cheby1ord	Analog or digital Chebyshev filter
cheby2 cheby2ord	Analog or digital Inverse Chebyshev filter
ellip ellipord	Analog or digital Elliptic filter