

3: Discrete Cosine Transform

- DFT Problems
- DCT +
- Basis Functions
- DCT of sine wave
- DCT Properties
- Energy Conservation
- Energy Compaction
- Frame-based coding
- Lapped Transform +
- MDCT (Modified DCT)
- MDCT Basis Elements
- Summary
- MATLAB routines

3: Discrete Cosine Transform

3: Discrete Cosine Transform

● DFT Problems

- DCT +
- Basis Functions
- DCT of sine wave
- DCT Properties
- Energy Conservation
- Energy Compaction
- Frame-based coding
- Lapped Transform +
- MDCT (Modified DCT)
- MDCT Basis Elements
- Summary
- MATLAB routines

DFT Problems

For processing 1-D or 2-D signals (especially coding), a common method is to divide the signal into “frames” and then apply an invertible transform to each frame that compresses the information into few coefficients.

The DFT has some problems when used for this purpose:

● DFT Problems

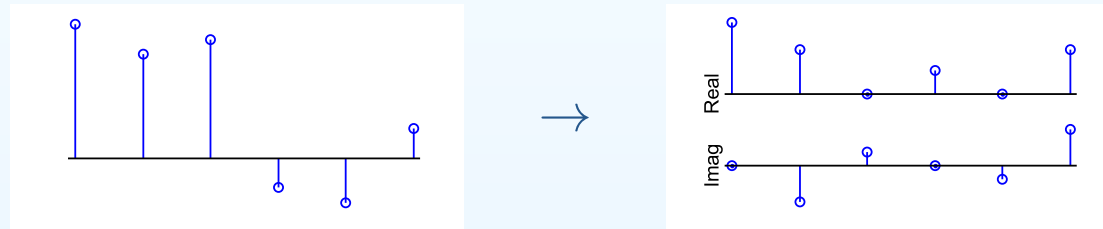
- DCT +
- Basis Functions
- DCT of sine wave
- DCT Properties
- Energy Conservation
- Energy Compaction
- Frame-based coding
- Lapped Transform +
- MDCT (Modified DCT)
- MDCT Basis Elements
- Summary
- MATLAB routines

DFT Problems

For processing 1-D or 2-D signals (especially coding), a common method is to divide the signal into “frames” and then apply an invertible transform to each frame that compresses the information into few coefficients.

The DFT has some problems when used for this purpose:

- N real $x[n] \leftrightarrow N$ complex $X[k] : 2 \text{ real}, \frac{N}{2} - 1 \text{ conjugate pairs}$



● DFT Problems

- DCT +
- Basis Functions
- DCT of sine wave
- DCT Properties
- Energy Conservation
- Energy Compaction
- Frame-based coding
- Lapped Transform +
- MDCT (Modified DCT)
- MDCT Basis Elements
- Summary
- MATLAB routines

DFT Problems

For processing 1-D or 2-D signals (especially coding), a common method is to divide the signal into “frames” and then apply an invertible transform to each frame that compresses the information into few coefficients.

The DFT has some problems when used for this purpose:

- N real $x[n] \leftrightarrow N$ complex $X[k] : 2 \text{ real}, \frac{N}{2} - 1 \text{ conjugate pairs}$



- $\text{DFT} \propto \text{the DTFT of a periodic signal formed by replicating } x[n]$.

● DFT Problems

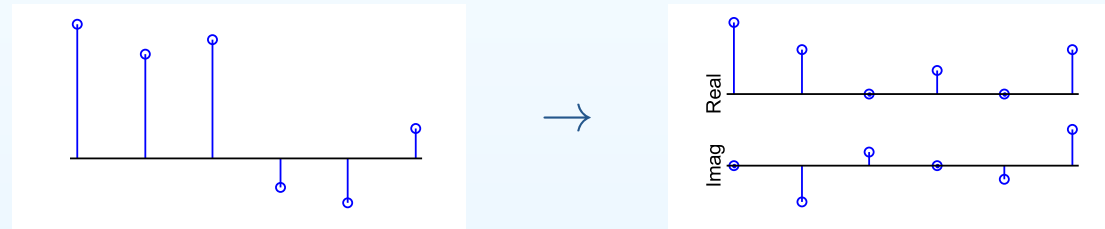
- DCT +
- Basis Functions
- DCT of sine wave
- DCT Properties
- Energy Conservation
- Energy Compaction
- Frame-based coding
- Lapped Transform +
- MDCT (Modified DCT)
- MDCT Basis Elements
- Summary
- MATLAB routines

DFT Problems

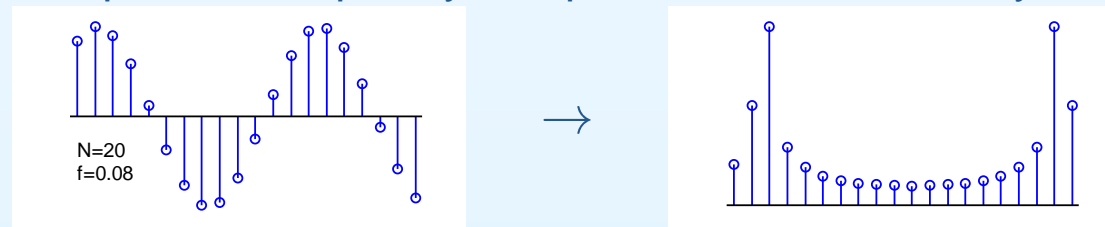
For processing 1-D or 2-D signals (especially coding), a common method is to divide the signal into “frames” and then apply an invertible transform to each frame that compresses the information into few coefficients.

The DFT has some problems when used for this purpose:

- N real $x[n] \leftrightarrow N$ complex $X[k] : 2 \text{ real}, \frac{N}{2} - 1 \text{ conjugate pairs}$



- $\text{DFT} \propto \text{the DTFT of a periodic signal formed by replicating } x[n]$.
 \Rightarrow Spurious frequency components from boundary discontinuity.



● DFT Problems

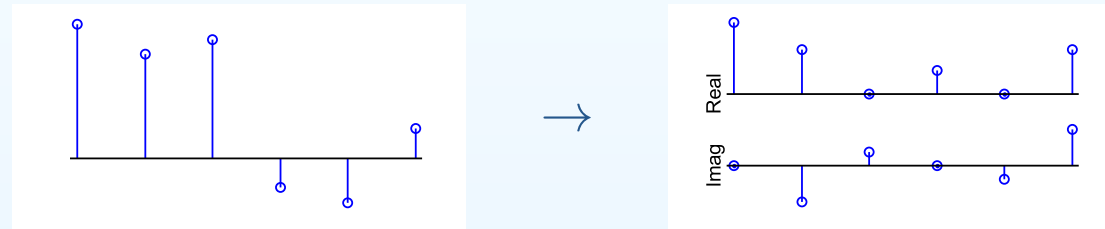
- DCT +
- Basis Functions
- DCT of sine wave
- DCT Properties
- Energy Conservation
- Energy Compaction
- Frame-based coding
- Lapped Transform +
- MDCT (Modified DCT)
- MDCT Basis Elements
- Summary
- MATLAB routines

DFT Problems

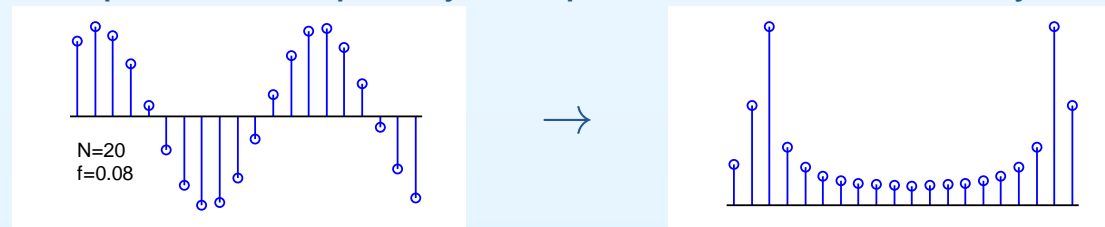
For processing 1-D or 2-D signals (especially coding), a common method is to divide the signal into “frames” and then apply an invertible transform to each frame that compresses the information into few coefficients.

The DFT has some problems when used for this purpose:

- N real $x[n] \leftrightarrow N$ complex $X[k] : 2 \text{ real}, \frac{N}{2} - 1 \text{ conjugate pairs}$



- $\text{DFT} \propto \text{the DTFT of a periodic signal formed by replicating } x[n]$.
 \Rightarrow Spurious frequency components from boundary discontinuity.



The Discrete Cosine Transform (DCT) overcomes these problems.

DCT

3: Discrete Cosine Transform

- DFT Problems

- **DCT**

- Basis Functions

- DCT of sine wave

- DCT Properties

- Energy Conservation

- Energy Compaction

- Frame-based coding

- Lapped Transform

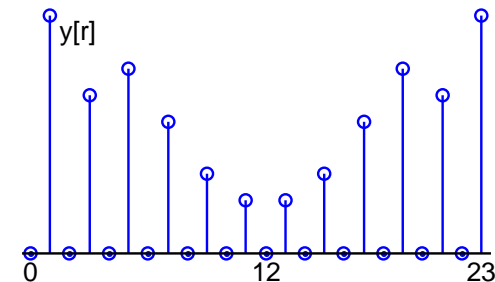
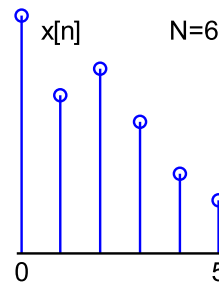
- MDCT (Modified DCT)

- MDCT Basis Elements

- Summary

- MATLAB routines

To form the Discrete Cosine Transform (DCT), replicate $x[0 : N - 1]$ but in reverse order and insert a zero between each pair of samples:



Take the DFT of length $4N$ real, symmetric, odd-sample-only sequence.

DCT

3: Discrete Cosine Transform

• DFT Problems

• DCT

• Basis Functions

• DCT of sine wave

• DCT Properties

• Energy Conservation

• Energy Compaction

• Frame-based coding

• Lapped Transform

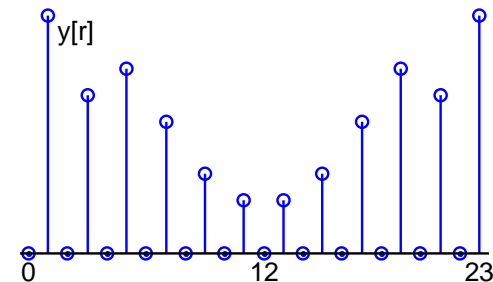
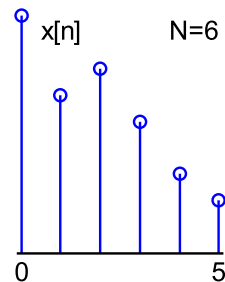
• MDCT (Modified DCT)

• MDCT Basis Elements

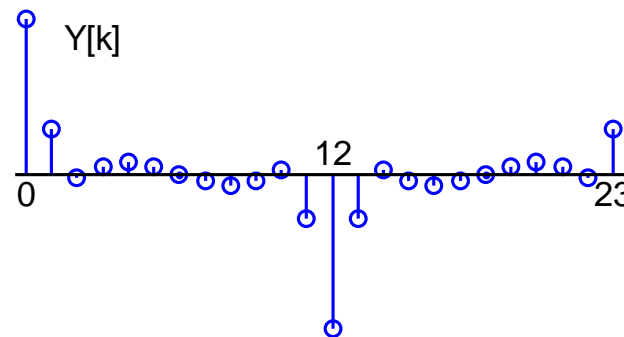
• Summary

• MATLAB routines

To form the Discrete Cosine Transform (DCT), replicate $x[0 : N - 1]$ but in reverse order and insert a zero between each pair of samples:



Take the DFT of length $4N$ real, symmetric, odd-sample-only sequence. Result is real, symmetric and anti-periodic:



DCT

3: Discrete Cosine Transform

• DFT Problems

• DCT

• Basis Functions

• DCT of sine wave

• DCT Properties

• Energy Conservation

• Energy Compaction

• Frame-based coding

• Lapped Transform

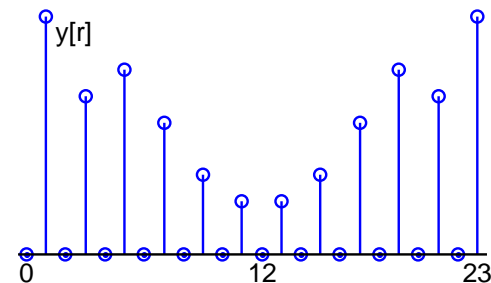
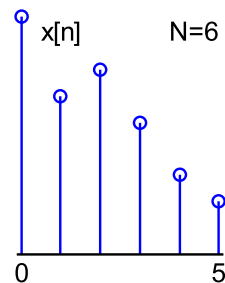
• MDCT (Modified DCT)

• MDCT Basis Elements

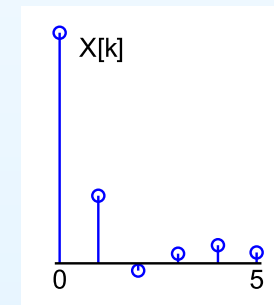
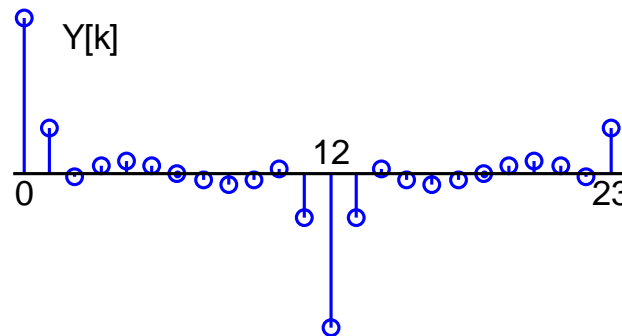
• Summary

• MATLAB routines

To form the Discrete Cosine Transform (DCT), replicate $x[0 : N - 1]$ but in reverse order and insert a zero between each pair of samples:



Take the DFT of length $4N$ real, symmetric, odd-sample-only sequence. Result is real, symmetric and anti-periodic: only need first N values



DCT

3: Discrete Cosine Transform

• DFT Problems

• DCT

• Basis Functions

• DCT of sine wave

• DCT Properties

• Energy Conservation

• Energy Compaction

• Frame-based coding

• Lapped Transform

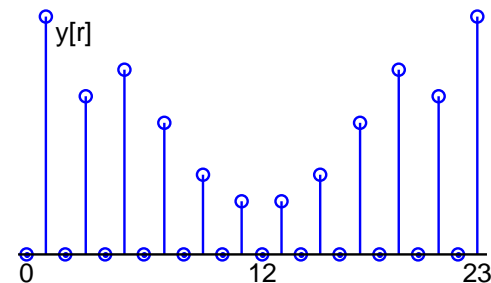
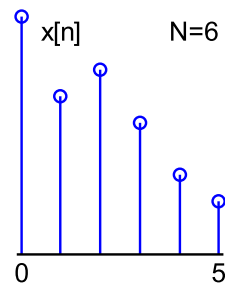
• MDCT (Modified DCT)

• MDCT Basis Elements

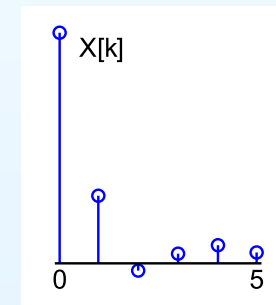
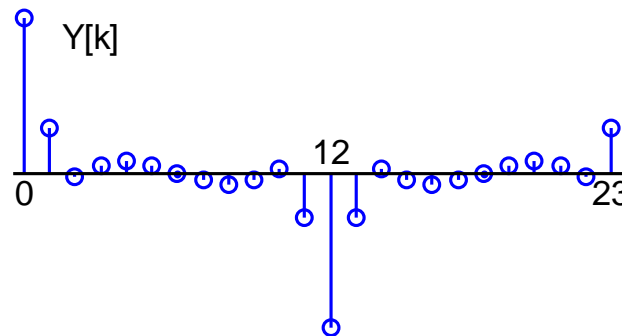
• Summary

• MATLAB routines

To form the Discrete Cosine Transform (DCT), replicate $x[0 : N - 1]$ but in reverse order and insert a zero between each pair of samples:



Take the DFT of length $4N$ real, symmetric, odd-sample-only sequence. Result is real, symmetric and anti-periodic: only need first N values



Forward DCT: $X_C[k] = \sum_{n=0}^{N-1} x[n] \cos \frac{2\pi(2n+1)k}{4N}$ for $k = 0 : N - 1$

DCT

3: Discrete Cosine Transform

• DFT Problems

• DCT

• Basis Functions

• DCT of sine wave

• DCT Properties

• Energy Conservation

• Energy Compaction

• Frame-based coding

• Lapped Transform

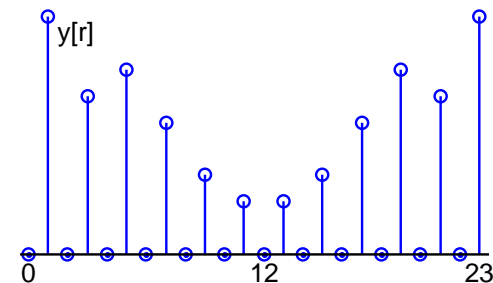
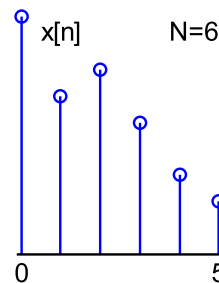
• MDCT (Modified DCT)

• MDCT Basis Elements

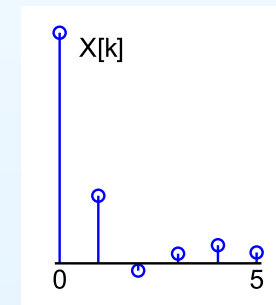
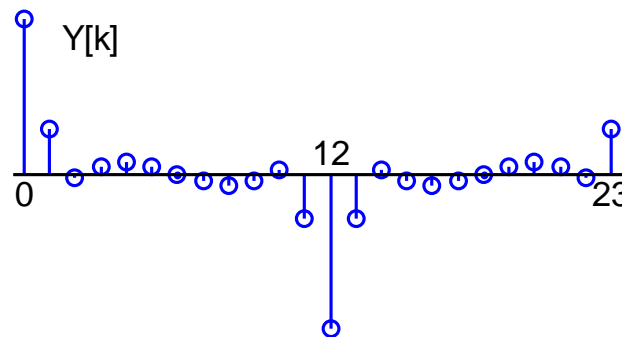
• Summary

• MATLAB routines

To form the Discrete Cosine Transform (DCT), replicate $x[0 : N - 1]$ but in reverse order and insert a zero between each pair of samples:



Take the DFT of length $4N$ real, symmetric, odd-sample-only sequence. Result is real, symmetric and anti-periodic: only need first N values



$$\text{Forward DCT: } X_C[k] = \sum_{n=0}^{N-1} x[n] \cos \frac{2\pi(2n+1)k}{4N} \text{ for } k = 0 : N - 1$$

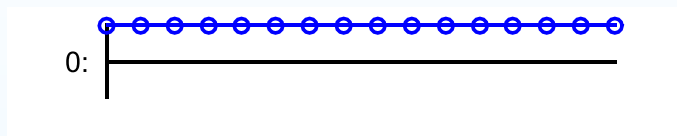
$$\text{Inverse DCT: } x[n] = \frac{1}{N} X[0] + \frac{2}{N} \sum_{k=1}^{N-1} X[k] \cos \frac{2\pi(2n+1)k}{4N}$$

Basis Functions

3: Discrete Cosine Transform

- DFT Problems
- DCT +
- Basis Functions
- DCT of sine wave
- DCT Properties
- Energy Conservation
- Energy Compaction
- Frame-based coding
- Lapped Transform +
- MDCT (Modified DCT)
- MDCT Basis Elements
- Summary
- MATLAB routines

DFT basis functions: $x[n] = \frac{1}{N} \sum_{k=0}^{N-1} X[k] e^{j2\pi \frac{kn}{N}}$

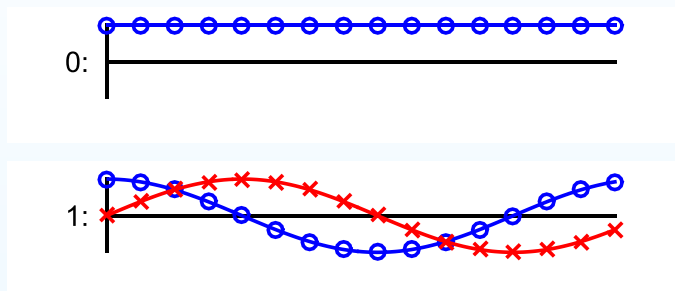


Basis Functions

3: Discrete Cosine Transform

- DFT Problems
- DCT +
- **Basis Functions**
- DCT of sine wave
- DCT Properties
- Energy Conservation
- Energy Compaction
- Frame-based coding
- Lapped Transform +
- MDCT (Modified DCT)
- MDCT Basis Elements
- Summary
- MATLAB routines

DFT basis functions: $x[n] = \frac{1}{N} \sum_{k=0}^{N-1} X[k] e^{j2\pi \frac{kn}{N}}$

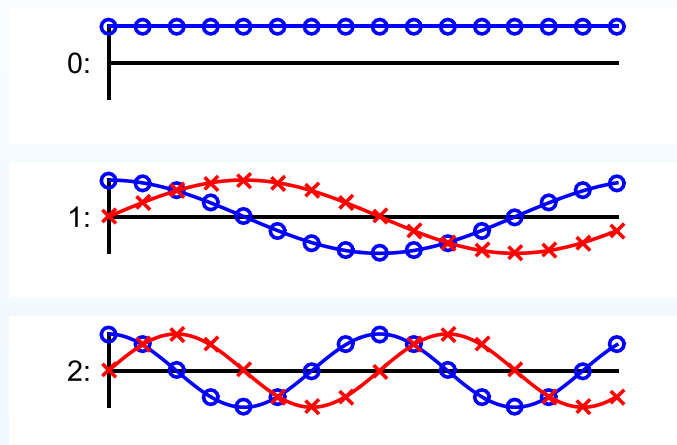


Basis Functions

3: Discrete Cosine Transform

- DFT Problems
- DCT +
- Basis Functions
- DCT of sine wave
- DCT Properties
- Energy Conservation
- Energy Compaction
- Frame-based coding
- Lapped Transform +
- MDCT (Modified DCT)
- MDCT Basis Elements
- Summary
- MATLAB routines

DFT basis functions: $x[n] = \frac{1}{N} \sum_{k=0}^{N-1} X[k] e^{j2\pi \frac{kn}{N}}$

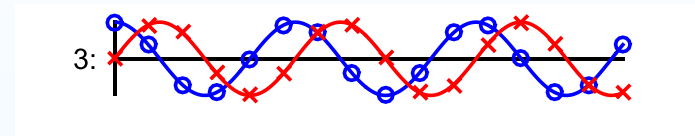
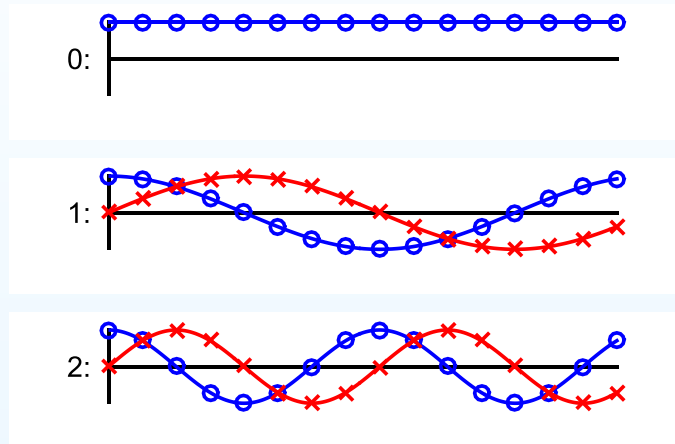


Basis Functions

3: Discrete Cosine Transform

- DFT Problems
- DCT +
- Basis Functions
- DCT of sine wave
- DCT Properties
- Energy Conservation
- Energy Compaction
- Frame-based coding
- Lapped Transform +
- MDCT (Modified DCT)
- MDCT Basis Elements
- Summary
- MATLAB routines

DFT basis functions: $x[n] = \frac{1}{N} \sum_{k=0}^{N-1} X[k] e^{j2\pi \frac{kn}{N}}$

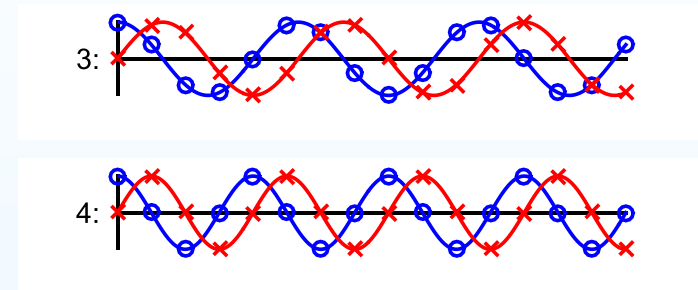
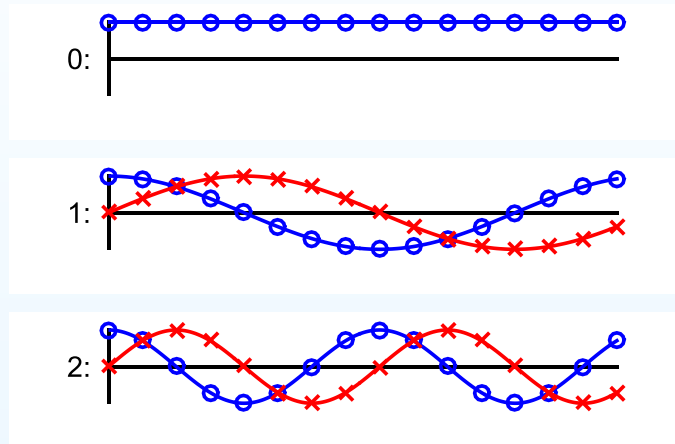


Basis Functions

3: Discrete Cosine Transform

- DFT Problems
- DCT +
- Basis Functions
- DCT of sine wave
- DCT Properties
- Energy Conservation
- Energy Compaction
- Frame-based coding
- Lapped Transform +
- MDCT (Modified DCT)
- MDCT Basis Elements
- Summary
- MATLAB routines

DFT basis functions: $x[n] = \frac{1}{N} \sum_{k=0}^{N-1} X[k] e^{j2\pi \frac{kn}{N}}$

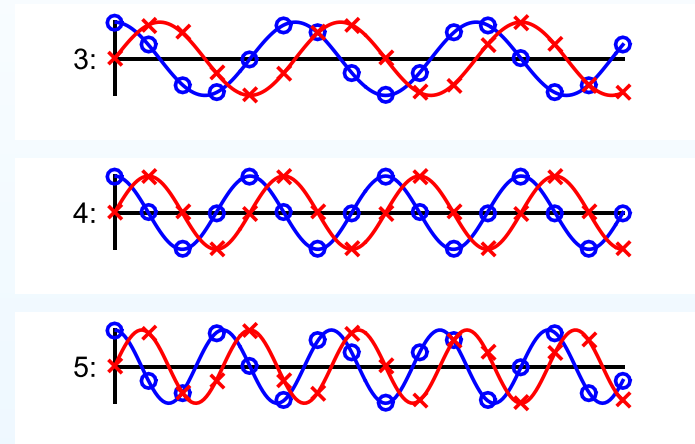
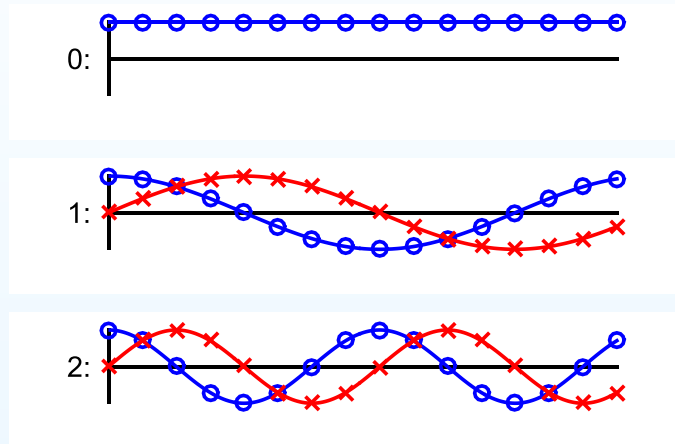


Basis Functions

3: Discrete Cosine Transform

- DFT Problems
- DCT +
- Basis Functions
- DCT of sine wave
- DCT Properties
- Energy Conservation
- Energy Compaction
- Frame-based coding
- Lapped Transform +
- MDCT (Modified DCT)
- MDCT Basis Elements
- Summary
- MATLAB routines

DFT basis functions: $x[n] = \frac{1}{N} \sum_{k=0}^{N-1} X[k] e^{j2\pi \frac{kn}{N}}$

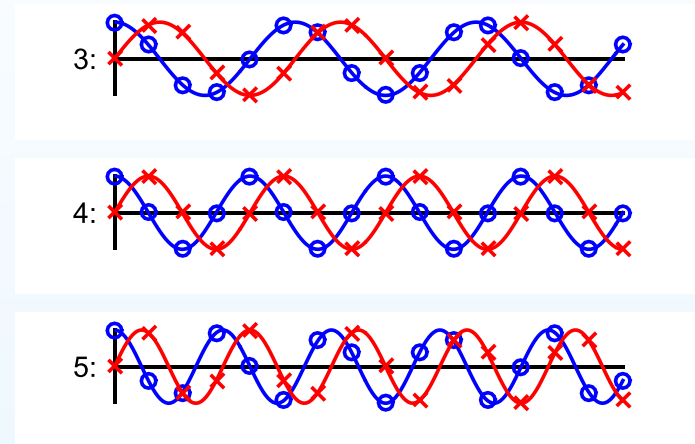
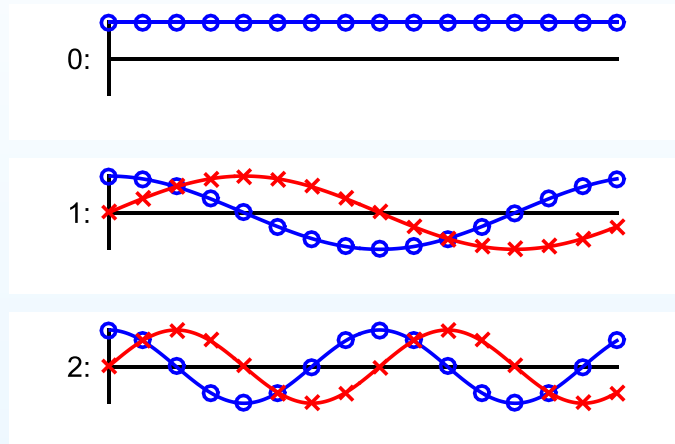


Basis Functions

3: Discrete Cosine Transform

- DFT Problems
- DCT +
- Basis Functions
- DCT of sine wave
- DCT Properties
- Energy Conservation
- Energy Compaction
- Frame-based coding
- Lapped Transform +
- MDCT (Modified DCT)
- MDCT Basis Elements
- Summary
- MATLAB routines

DFT basis functions: $x[n] = \frac{1}{N} \sum_{k=0}^{N-1} X[k] e^{j2\pi \frac{kn}{N}}$



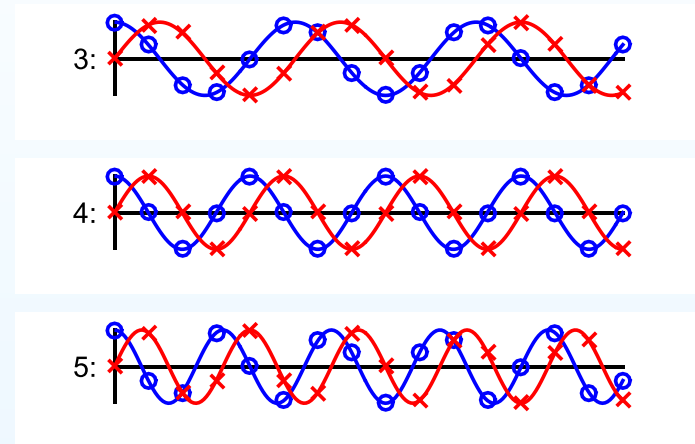
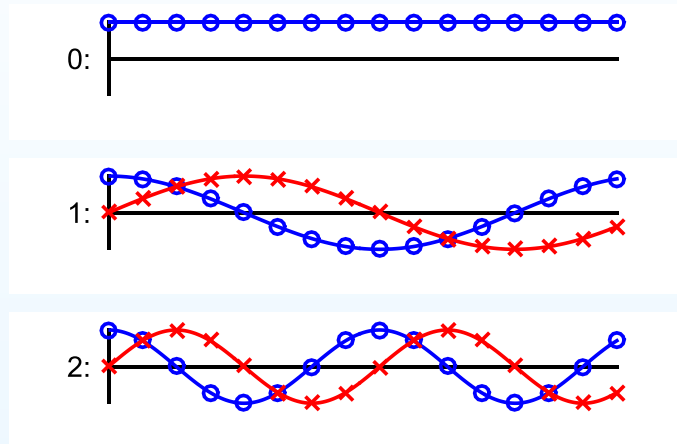
DCT basis functions: $x[n] = \frac{1}{N} X[0] + \frac{2}{N} \sum_{k=1}^{N-1} X[k] \cos \frac{2\pi(2n+1)k}{4N}$

Basis Functions

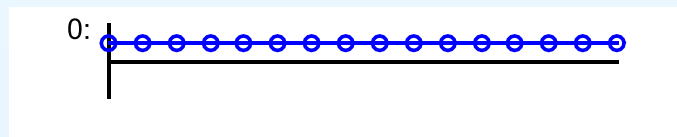
3: Discrete Cosine Transform

- DFT Problems
- DCT
- **Basis Functions**
- DCT of sine wave
- DCT Properties
- Energy Conservation
- Energy Compaction
- Frame-based coding
- Lapped Transform
- MDCT (Modified DCT)
- MDCT Basis Elements
- Summary
- MATLAB routines

DFT basis functions: $x[n] = \frac{1}{N} \sum_{k=0}^{N-1} X[k] e^{j2\pi \frac{kn}{N}}$



DCT basis functions: $x[n] = \frac{1}{N} X[0] + \frac{2}{N} \sum_{k=1}^{N-1} X[k] \cos \frac{2\pi(2n+1)k}{4N}$

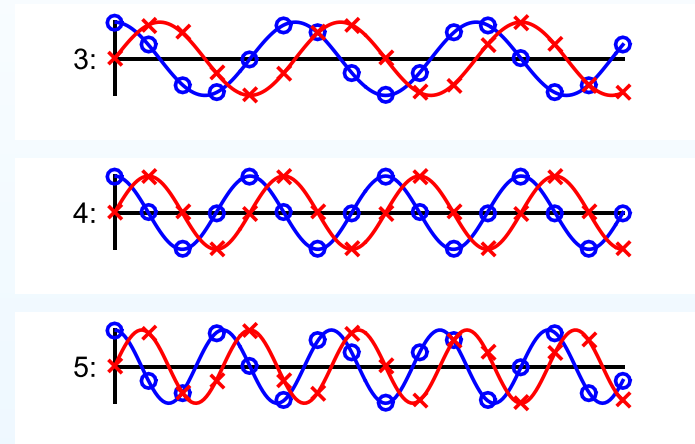
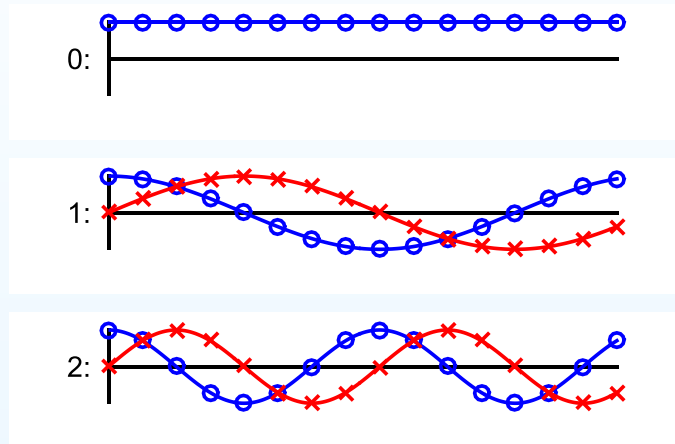


Basis Functions

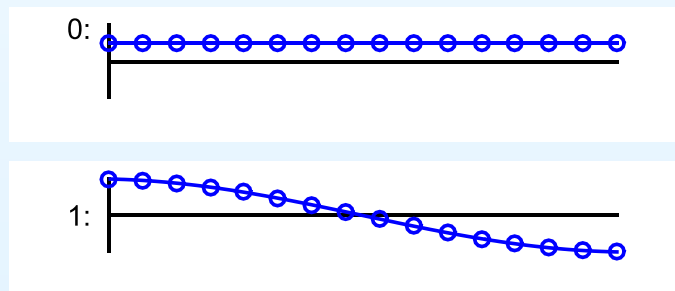
3: Discrete Cosine Transform

- DFT Problems
- DCT
- Basis Functions
- DCT of sine wave
- DCT Properties
- Energy Conservation
- Energy Compaction
- Frame-based coding
- Lapped Transform
- MDCT (Modified DCT)
- MDCT Basis Elements
- Summary
- MATLAB routines

DFT basis functions: $x[n] = \frac{1}{N} \sum_{k=0}^{N-1} X[k] e^{j2\pi \frac{kn}{N}}$



DCT basis functions: $x[n] = \frac{1}{N} X[0] + \frac{2}{N} \sum_{k=1}^{N-1} X[k] \cos \frac{2\pi(2n+1)k}{4N}$

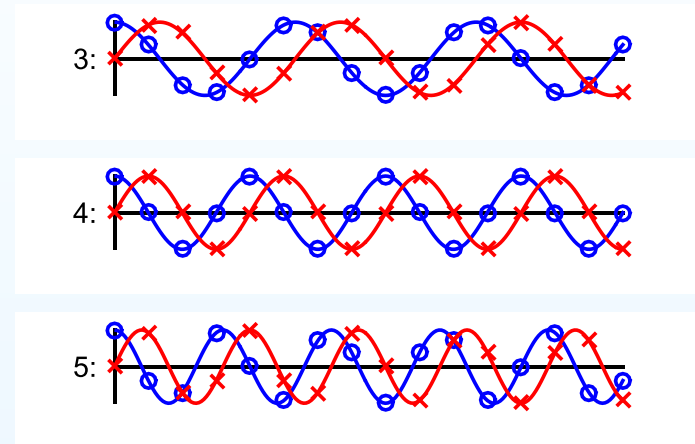
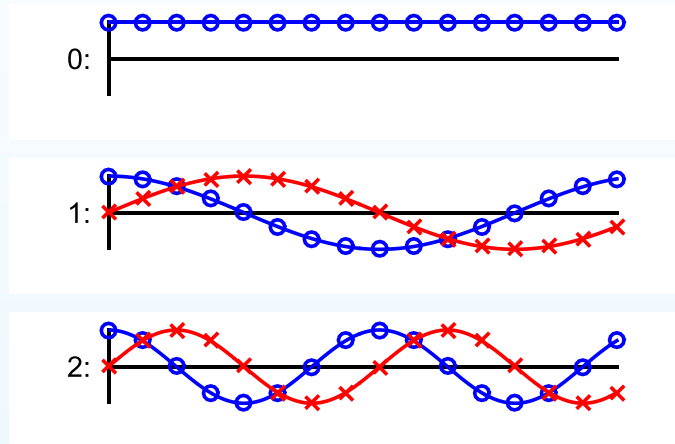


Basis Functions

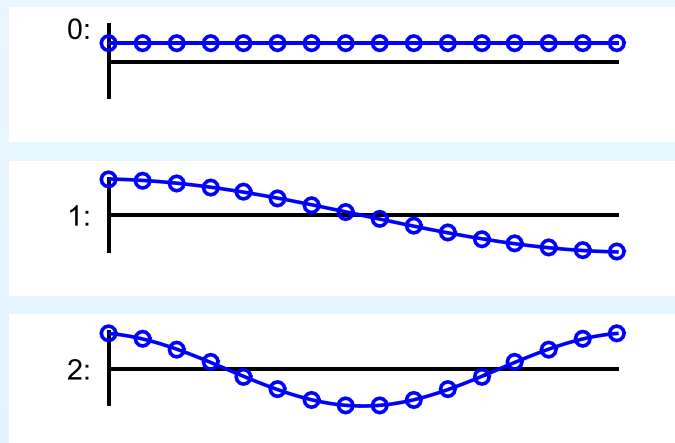
3: Discrete Cosine Transform

- DFT Problems
- DCT
- Basis Functions
- DCT of sine wave
- DCT Properties
- Energy Conservation
- Energy Compaction
- Frame-based coding
- Lapped Transform
- MDCT (Modified DCT)
- MDCT Basis Elements
- Summary
- MATLAB routines

DFT basis functions: $x[n] = \frac{1}{N} \sum_{k=0}^{N-1} X[k] e^{j2\pi \frac{kn}{N}}$



DCT basis functions: $x[n] = \frac{1}{N} X[0] + \frac{2}{N} \sum_{k=1}^{N-1} X[k] \cos \frac{2\pi(2n+1)k}{4N}$

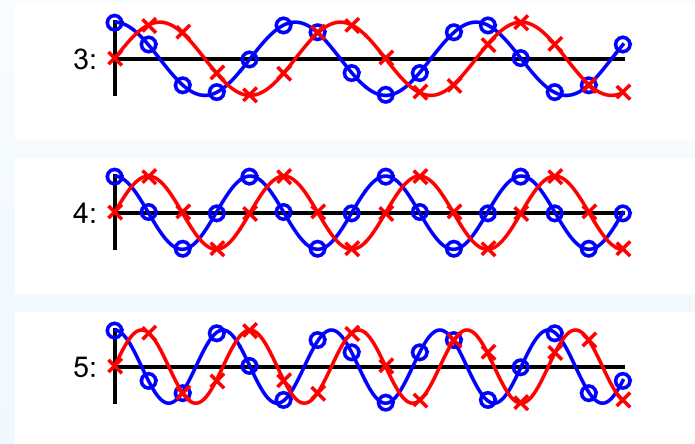
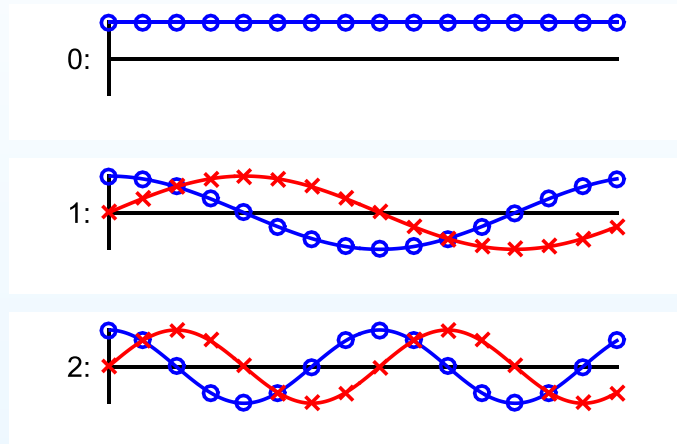


Basis Functions

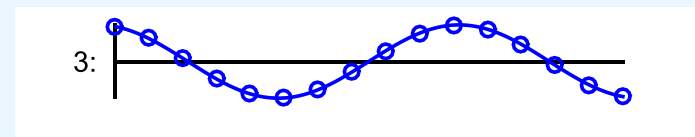
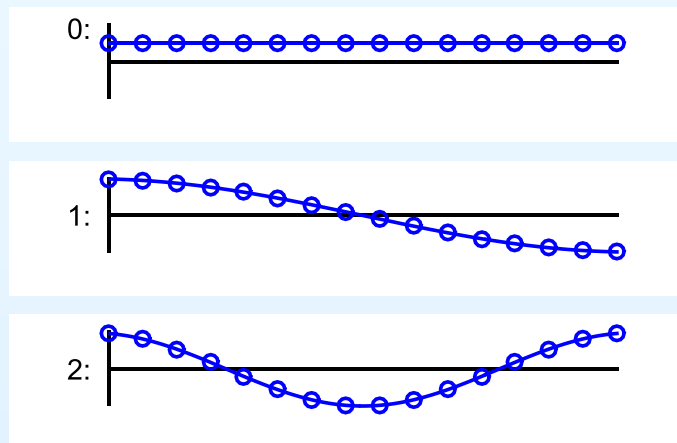
3: Discrete Cosine Transform

- DFT Problems
- DCT
- Basis Functions
- DCT of sine wave
- DCT Properties
- Energy Conservation
- Energy Compaction
- Frame-based coding
- Lapped Transform
- MDCT (Modified DCT)
- MDCT Basis Elements
- Summary
- MATLAB routines

DFT basis functions: $x[n] = \frac{1}{N} \sum_{k=0}^{N-1} X[k] e^{j2\pi \frac{kn}{N}}$



DCT basis functions: $x[n] = \frac{1}{N} X[0] + \frac{2}{N} \sum_{k=1}^{N-1} X[k] \cos \frac{2\pi(2n+1)k}{4N}$

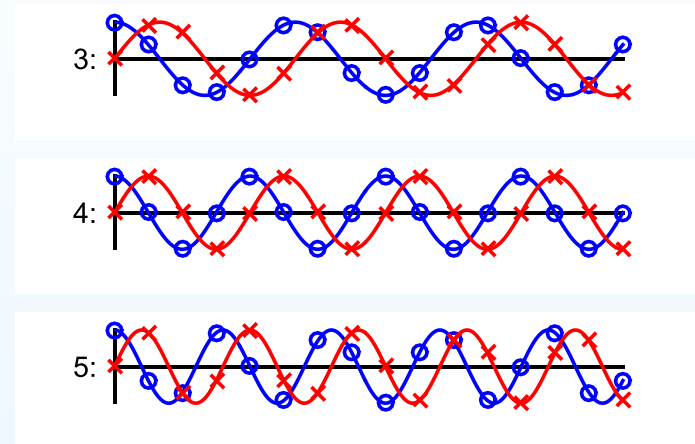
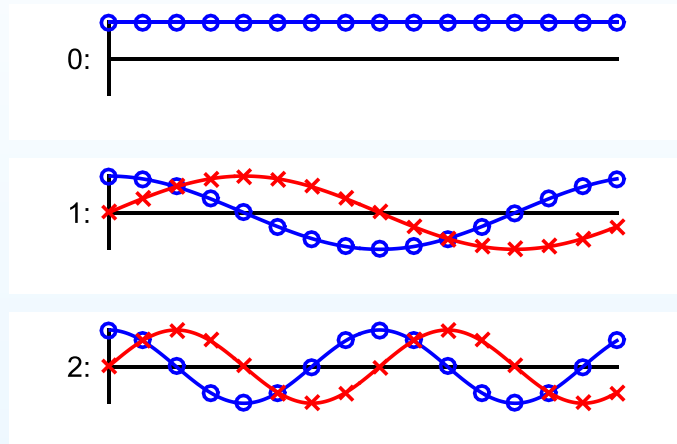


Basis Functions

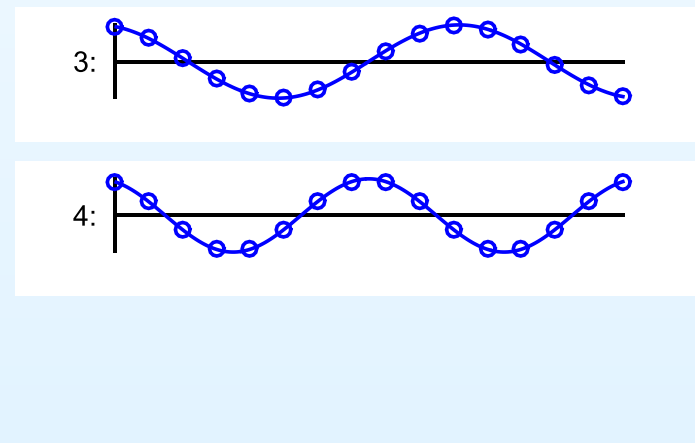
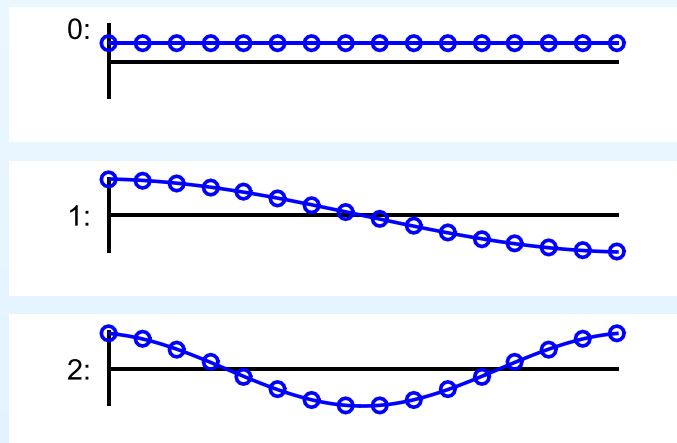
3: Discrete Cosine Transform

- DFT Problems
- DCT
- Basis Functions
- DCT of sine wave
- DCT Properties
- Energy Conservation
- Energy Compaction
- Frame-based coding
- Lapped Transform
- MDCT (Modified DCT)
- MDCT Basis Elements
- Summary
- MATLAB routines

DFT basis functions: $x[n] = \frac{1}{N} \sum_{k=0}^{N-1} X[k] e^{j2\pi \frac{kn}{N}}$



DCT basis functions: $x[n] = \frac{1}{N} X[0] + \frac{2}{N} \sum_{k=1}^{N-1} X[k] \cos \frac{2\pi(2n+1)k}{4N}$

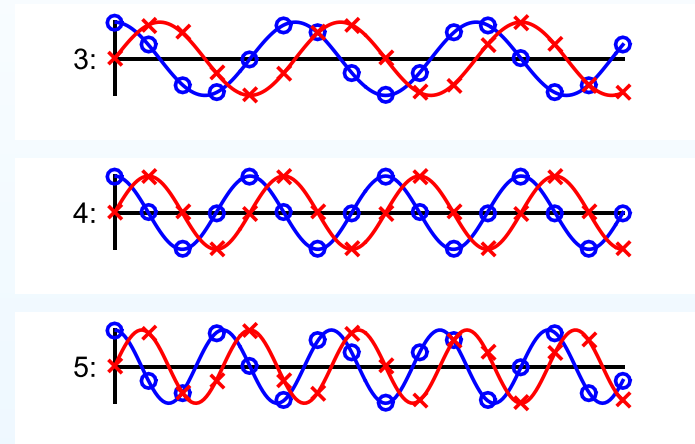
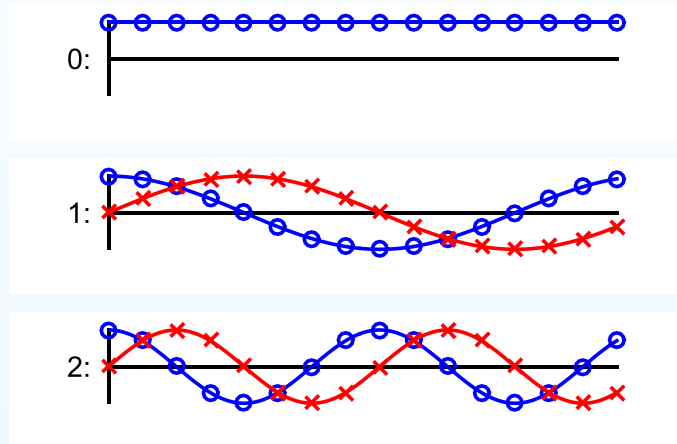


Basis Functions

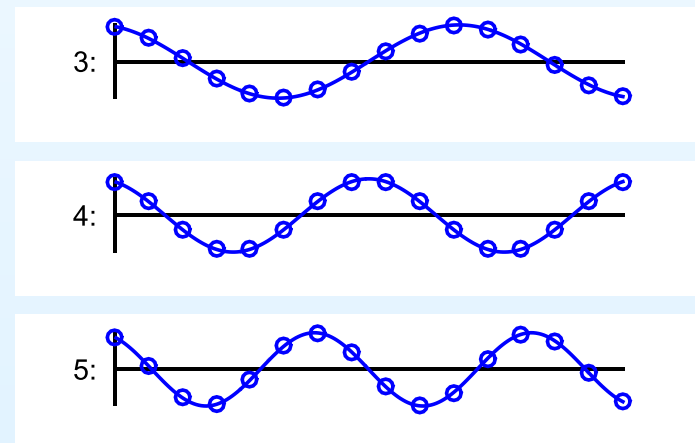
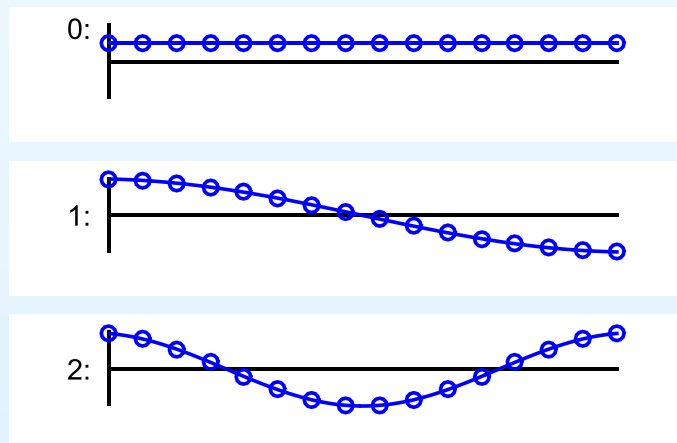
3: Discrete Cosine Transform

- DFT Problems
- DCT
- Basis Functions
- DCT of sine wave
- DCT Properties
- Energy Conservation
- Energy Compaction
- Frame-based coding
- Lapped Transform
- MDCT (Modified DCT)
- MDCT Basis Elements
- Summary
- MATLAB routines

DFT basis functions: $x[n] = \frac{1}{N} \sum_{k=0}^{N-1} X[k] e^{j2\pi \frac{kn}{N}}$



DCT basis functions: $x[n] = \frac{1}{N} X[0] + \frac{2}{N} \sum_{k=1}^{N-1} X[k] \cos \frac{2\pi(2n+1)k}{4N}$



DCT of sine wave

3: Discrete Cosine Transform

- DFT Problems
- DCT +
- Basis Functions
- **DCT of sine wave**
- DCT Properties
- Energy Conservation
- Energy Compaction
- Frame-based coding
- Lapped Transform +
- MDCT (Modified DCT)
- MDCT Basis Elements
- Summary
- MATLAB routines

$$\text{DCT: } X_C[k] = \sum_{n=0}^{N-1} x[n] \cos \frac{2\pi(2n+1)k}{4N}$$

DCT of sine wave

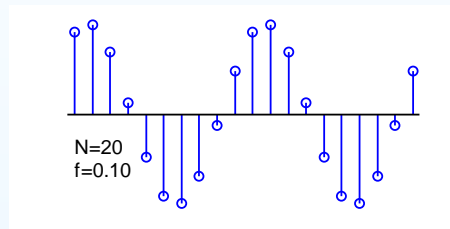
3: Discrete Cosine Transform

- DFT Problems
- DCT +
- Basis Functions
- DCT of sine wave
- DCT Properties
- Energy Conservation
- Energy Compaction
- Frame-based coding
- Lapped Transform +
- MDCT (Modified DCT)
- MDCT Basis Elements
- Summary
- MATLAB routines

$$\text{DCT: } X_C[k] = \sum_{n=0}^{N-1} x[n] \cos \frac{2\pi(2n+1)k}{4N}$$

$$f = \frac{m}{N}$$

$x[n]$



DCT of sine wave

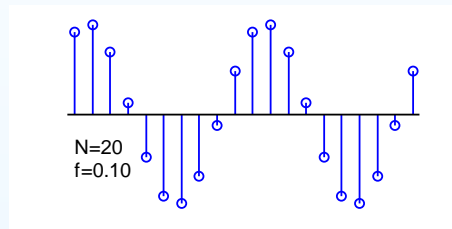
3: Discrete Cosine Transform

- DFT Problems
- DCT +
- Basis Functions
- DCT of sine wave
- DCT Properties
- Energy Conservation
- Energy Compaction
- Frame-based coding
- Lapped Transform +
- MDCT (Modified DCT)
- MDCT Basis Elements
- Summary
- MATLAB routines

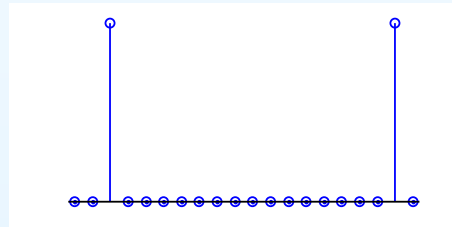
$$\text{DCT: } X_C[k] = \sum_{n=0}^{N-1} x[n] \cos \frac{2\pi(2n+1)k}{4N}$$

$$f = \frac{m}{N}$$

$x[n]$



$|X_F[k]|$



DCT of sine wave

3: Discrete Cosine Transform

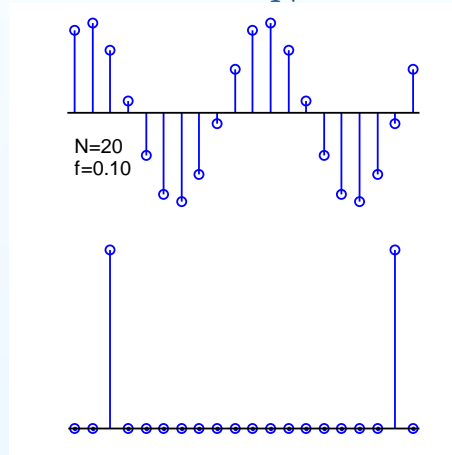
- DFT Problems
- DCT
- Basis Functions
- DCT of sine wave
- DCT Properties
- Energy Conservation
- Energy Compaction
- Frame-based coding
- Lapped Transform
- MDCT (Modified DCT)
- MDCT Basis Elements
- Summary
- MATLAB routines

$$\text{DCT: } X_C[k] = \sum_{n=0}^{N-1} x[n] \cos \frac{2\pi(2n+1)k}{4N}$$

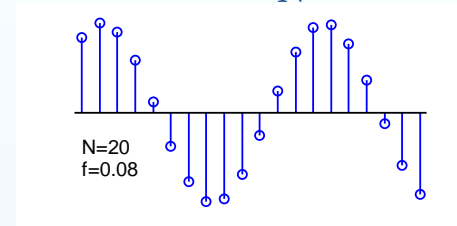
$x[n]$

$|X_F[k]|$

$$f = \frac{m}{N}$$



$$f \neq \frac{m}{N}$$



DCT of sine wave

3: Discrete Cosine Transform

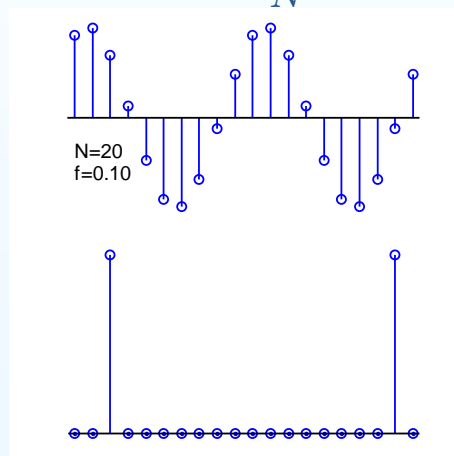
- DFT Problems
- DCT
- Basis Functions
- DCT of sine wave
- DCT Properties
- Energy Conservation
- Energy Compaction
- Frame-based coding
- Lapped Transform
- MDCT (Modified DCT)
- MDCT Basis Elements
- Summary
- MATLAB routines

$$\text{DCT: } X_C[k] = \sum_{n=0}^{N-1} x[n] \cos \frac{2\pi(2n+1)k}{4N}$$

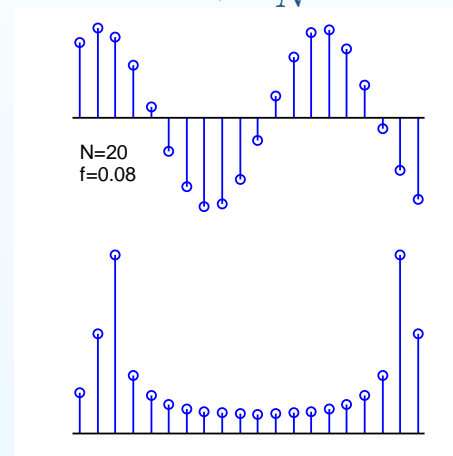
$x[n]$

$|X_F[k]|$

$$f = \frac{m}{N}$$



$$f \neq \frac{m}{N}$$



DCT of sine wave

3: Discrete Cosine Transform

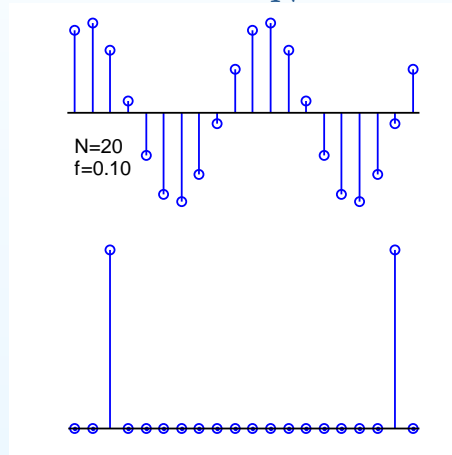
- DFT Problems
- DCT
- Basis Functions
- DCT of sine wave
- DCT Properties
- Energy Conservation
- Energy Compaction
- Frame-based coding
- Lapped Transform
- MDCT (Modified DCT)
- MDCT Basis Elements
- Summary
- MATLAB routines

$$\text{DCT: } X_C[k] = \sum_{n=0}^{N-1} x[n] \cos \frac{2\pi(2n+1)k}{4N}$$

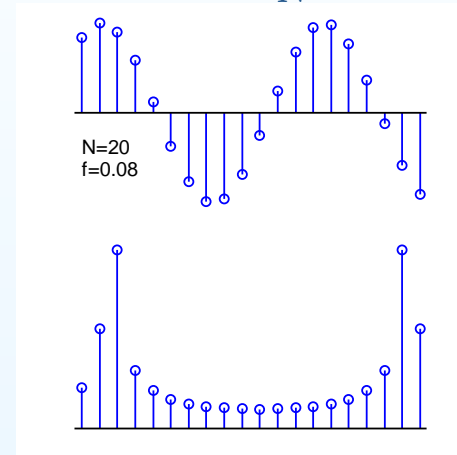
$x[n]$

$|X_F[k]|$

$$f = \frac{m}{N}$$



$$f \neq \frac{m}{N}$$



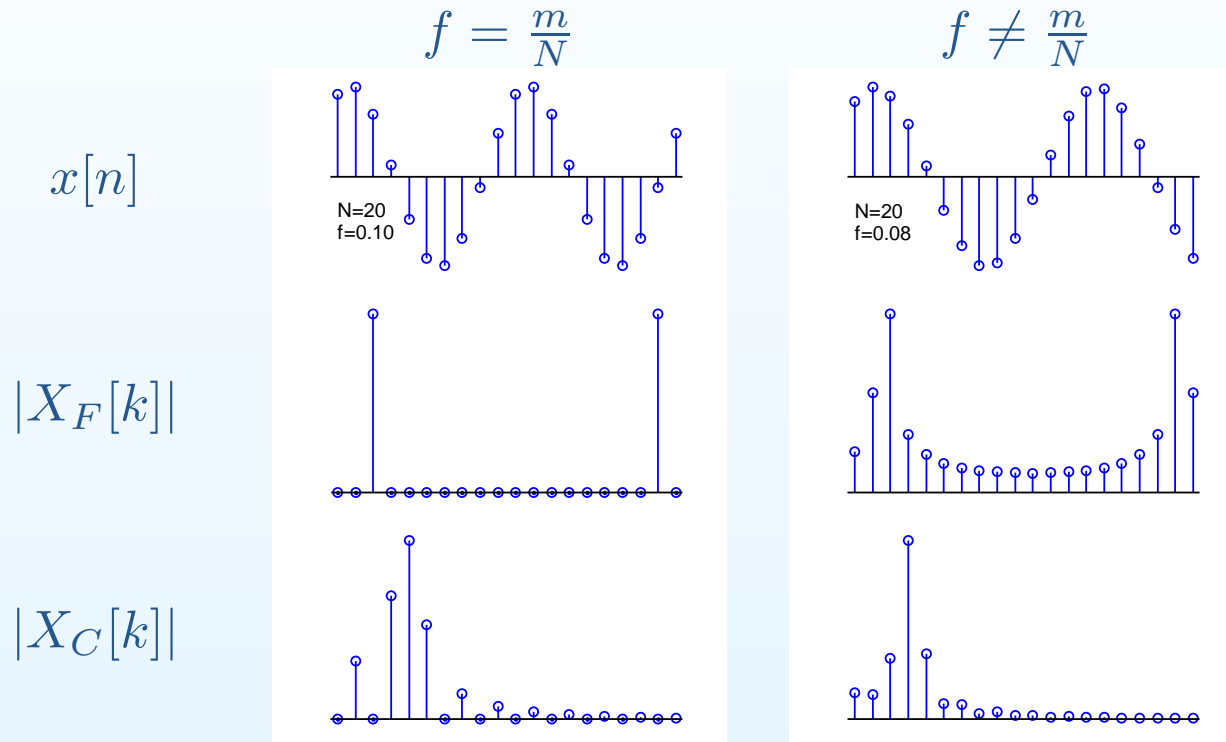
DFT: Real \rightarrow Complex; Freq range $[0, 1]$; Poorly localized unless $f = \frac{m}{N}$; $|X_F[k]| \propto k^{-1}$ for $Nf < k \ll \frac{N}{2}$

DCT of sine wave

3: Discrete Cosine Transform

- DFT Problems
- DCT
- Basis Functions
- DCT of sine wave
- DCT Properties
- Energy Conservation
- Energy Compaction
- Frame-based coding
- Lapped Transform
- MDCT (Modified DCT)
- MDCT Basis Elements
- Summary
- MATLAB routines

$$\text{DCT: } X_C[k] = \sum_{n=0}^{N-1} x[n] \cos \frac{2\pi(2n+1)k}{4N}$$



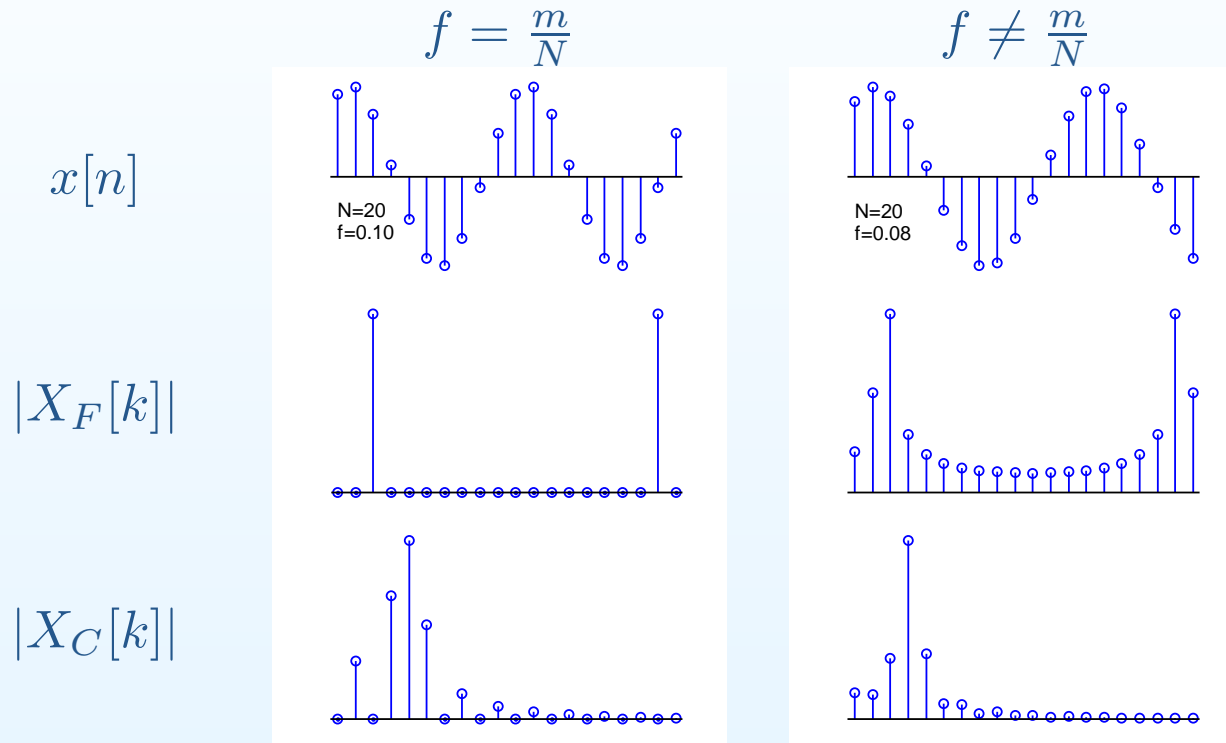
DFT: Real \rightarrow Complex; Freq range $[0, 1]$; Poorly localized unless $f = \frac{m}{N}$; $|X_F[k]| \propto k^{-1}$ for $Nf < k \ll \frac{N}{2}$

DCT of sine wave

3: Discrete Cosine Transform

- DFT Problems
- DCT
- Basis Functions
- DCT of sine wave
- DCT Properties
- Energy Conservation
- Energy Compaction
- Frame-based coding
- Lapped Transform
- MDCT (Modified DCT)
- MDCT Basis Elements
- Summary
- MATLAB routines

$$\text{DCT: } X_C[k] = \sum_{n=0}^{N-1} x[n] \cos \frac{2\pi(2n+1)k}{4N}$$



- DFT:** Real \rightarrow Complex; Freq range $[0, 1]$; Poorly localized unless $f = \frac{m}{N}$; $|X_F[k]| \propto k^{-1}$ for $Nf < k \ll \frac{N}{2}$
- DCT:** Real \rightarrow Real; Freq range $[0, 0.5]$; Well localized $\forall f$; $|X_C[k]| \propto k^{-2}$ for $2Nf < k < N$

DCT Properties

3: Discrete Cosine Transform

- DFT Problems
- DCT +
- Basis Functions
- DCT of sine wave
- **DCT Properties**
- Energy Conservation
- Energy Compaction
- Frame-based coding
- Lapped Transform +
- MDCT (Modified DCT)
- MDCT Basis Elements
- Summary
- MATLAB routines

Definition:
$$X[k] = \sum_{n=0}^{N-1} x[n] \cos \frac{2\pi(2n+1)k}{4N}$$

DCT Properties

3: Discrete Cosine Transform

- DFT Problems
- DCT +
- Basis Functions
- DCT of sine wave
- **DCT Properties**
- Energy Conservation
- Energy Compaction
- Frame-based coding
- Lapped Transform +
- MDCT (Modified DCT)
- MDCT Basis Elements
- Summary
- MATLAB routines

Definition: $X[k] = \sum_{n=0}^{N-1} x[n] \cos \frac{2\pi(2n+1)k}{4N}$

- **Linear:** $\alpha x[n] + \beta y[n] \rightarrow \alpha X[k] + \beta Y[k]$

3: Discrete Cosine Transform

- DFT Problems
- DCT +
- Basis Functions
- DCT of sine wave
- **DCT Properties**
- Energy Conservation
- Energy Compaction
- Frame-based coding
- Lapped Transform +
- MDCT (Modified DCT)
- MDCT Basis Elements
- Summary
- MATLAB routines

DCT Properties

Definition: $X[k] = \sum_{n=0}^{N-1} x[n] \cos \frac{2\pi(2n+1)k}{4N}$

- **Linear:** $\alpha x[n] + \beta y[n] \rightarrow \alpha X[k] + \beta Y[k]$
- **“Convolution \longleftrightarrow Multiplication”** property of DFT does not hold ☹

3: Discrete Cosine Transform

- DFT Problems
- DCT +
- Basis Functions
- DCT of sine wave
- **DCT Properties**
- Energy Conservation
- Energy Compaction
- Frame-based coding
- Lapped Transform +
- MDCT (Modified DCT)
- MDCT Basis Elements
- Summary
- MATLAB routines

DCT Properties

Definition: $X[k] = \sum_{n=0}^{N-1} x[n] \cos \frac{2\pi(2n+1)k}{4N}$

- **Linear:** $\alpha x[n] + \beta y[n] \rightarrow \alpha X[k] + \beta Y[k]$
- **“Convolution \longleftrightarrow Multiplication” property of DFT does not hold** ☹
- **Symmetric:** $X[-k] = X[k]$ since $\cos -\alpha k = \cos +\alpha k$

DCT Properties

3: Discrete Cosine Transform

- DFT Problems
- DCT +
- Basis Functions
- DCT of sine wave
- **DCT Properties**
- Energy Conservation
- Energy Compaction
- Frame-based coding
- Lapped Transform +
- MDCT (Modified DCT)
- MDCT Basis Elements
- Summary
- MATLAB routines

Definition: $X[k] = \sum_{n=0}^{N-1} x[n] \cos \frac{2\pi(2n+1)k}{4N}$

- **Linear:** $\alpha x[n] + \beta y[n] \rightarrow \alpha X[k] + \beta Y[k]$
- **“Convolution \longleftrightarrow Multiplication” property of DFT does not hold** ☹
- **Symmetric:** $X[-k] = X[k]$ since $\cos -\alpha k = \cos +\alpha k$
- **Anti-periodic:** $X[k + 2N] = -X[k]$

3: Discrete Cosine Transform

- DFT Problems
- DCT +
- Basis Functions
- DCT of sine wave
- **DCT Properties**
- Energy Conservation
- Energy Compaction
- Frame-based coding
- Lapped Transform +
- MDCT (Modified DCT)
- MDCT Basis Elements
- Summary
- MATLAB routines

DCT Properties

Definition: $X[k] = \sum_{n=0}^{N-1} x[n] \cos \frac{2\pi(2n+1)k}{4N}$

- **Linear:** $\alpha x[n] + \beta y[n] \rightarrow \alpha X[k] + \beta Y[k]$
- **“Convolution \longleftrightarrow Multiplication” property of DFT does not hold** ☹
- **Symmetric:** $X[-k] = X[k]$ since $\cos -\alpha k = \cos +\alpha k$
- **Anti-periodic:** $X[k + 2N] = -X[k]$ because:
 - $2\pi(2n+1)(k+2N) = 2\pi(2n+1)k + 8\pi Nn + 4N\pi$
 - $\cos(\theta + \pi) = -\cos \theta$

DCT Properties

3: Discrete Cosine Transform

- DFT Problems
- DCT +
- Basis Functions
- DCT of sine wave
- **DCT Properties**
- Energy Conservation
- Energy Compaction
- Frame-based coding
- Lapped Transform +
- MDCT (Modified DCT)
- MDCT Basis Elements
- Summary
- MATLAB routines

Definition: $X[k] = \sum_{n=0}^{N-1} x[n] \cos \frac{2\pi(2n+1)k}{4N}$

- **Linear:** $\alpha x[n] + \beta y[n] \rightarrow \alpha X[k] + \beta Y[k]$
- **“Convolution \longleftrightarrow Multiplication” property of DFT does not hold** ☹
- **Symmetric:** $X[-k] = X[k]$ since $\cos -\alpha k = \cos +\alpha k$
- **Anti-periodic:** $X[k + 2N] = -X[k]$ because:
 - $2\pi(2n+1)(k+2N) = 2\pi(2n+1)k + 8\pi Nn + 4N\pi$
 - $\cos(\theta + \pi) = -\cos \theta$

$\Rightarrow X[N] = 0$ since $\underbrace{X[N] = X[-N] = -X[-N + 2N]}$

$$X[N] = -X[N]$$

$$\Rightarrow X[N] = 0$$

DCT Properties

3: Discrete Cosine Transform

- DFT Problems
- DCT +
- Basis Functions
- DCT of sine wave
- **DCT Properties**
- Energy Conservation
- Energy Compaction
- Frame-based coding
- Lapped Transform +
- MDCT (Modified DCT)
- MDCT Basis Elements
- Summary
- MATLAB routines

Definition: $X[k] = \sum_{n=0}^{N-1} x[n] \cos \frac{2\pi(2n+1)k}{4N}$

- **Linear:** $\alpha x[n] + \beta y[n] \rightarrow \alpha X[k] + \beta Y[k]$
 - **“Convolution \longleftrightarrow Multiplication” property of DFT does not hold** ☹
 - **Symmetric:** $X[-k] = X[k]$ since $\cos -\alpha k = \cos +\alpha k$
 - **Anti-periodic:** $X[k + 2N] = -X[k]$ because:
 - $2\pi(2n+1)(k+2N) = 2\pi(2n+1)k + 8\pi Nn + 4N\pi$
 - $\cos(\theta + \pi) = -\cos \theta$
- $\Rightarrow X[N] = 0$ since $X[N] = X[-N] = -X[-N + 2N]$
- **Periodic:** $X[k + 4N] = -X[k + 2N] = X[k]$

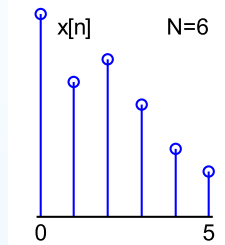
Energy Conservation

3: Discrete Cosine Transform

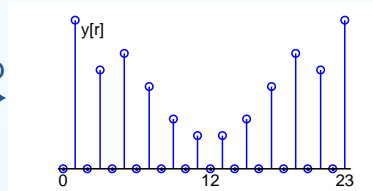
- DFT Problems
- DCT
- Basis Functions
- DCT of sine wave
- DCT Properties
- **Energy Conservation**
- Energy Compaction
- Frame-based coding
- Lapped Transform
- MDCT (Modified DCT)
- MDCT Basis Elements
- Summary
- MATLAB routines

$$\text{DCT: } X[k] = \sum_{n=0}^{N-1} x[n] \cos \frac{2\pi(2n+1)k}{4N}$$

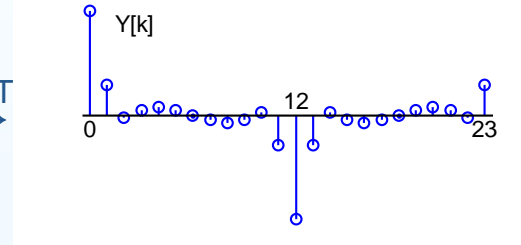
$$\text{IDCT: } x[n] = \frac{1}{N} X[0] + \frac{2}{N} \sum_{k=1}^{N-1} X[k] \cos \frac{2\pi(2n+1)k}{4N}$$



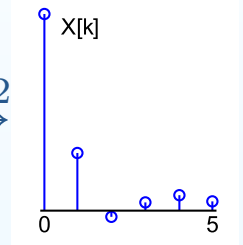
rep
→



DFT
→



$\div 2$
→



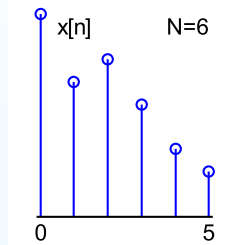
Energy Conservation

3: Discrete Cosine Transform

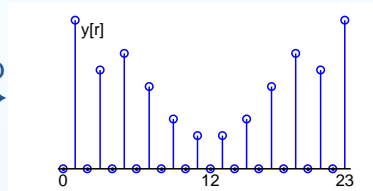
- DFT Problems
- DCT
- Basis Functions
- DCT of sine wave
- DCT Properties
- **Energy Conservation**
- Energy Compaction
- Frame-based coding
- Lapped Transform
- MDCT (Modified DCT)
- MDCT Basis Elements
- Summary
- MATLAB routines

$$\text{DCT: } X[k] = \sum_{n=0}^{N-1} x[n] \cos \frac{2\pi(2n+1)k}{4N}$$

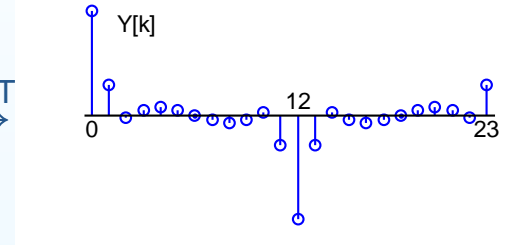
$$\text{IDCT: } x[n] = \frac{1}{N} X[0] + \frac{2}{N} \sum_{k=1}^{N-1} X[k] \cos \frac{2\pi(2n+1)k}{4N}$$



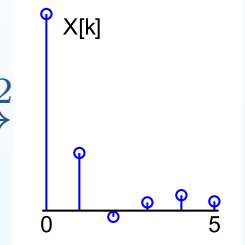
rep
→



DFT
→



÷2
→



$$\text{Energy: } E = \sum_{n=0}^{N-1} |x[n]|^2$$

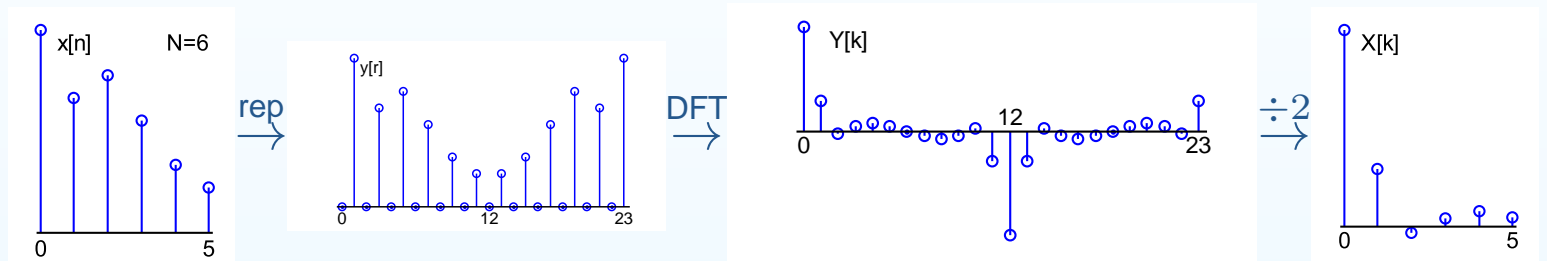
Energy Conservation

3: Discrete Cosine Transform

- DFT Problems
- DCT
- Basis Functions
- DCT of sine wave
- DCT Properties
- **Energy Conservation**
- Energy Compaction
- Frame-based coding
- Lapped Transform
- MDCT (Modified DCT)
- MDCT Basis Elements
- Summary
- MATLAB routines

$$\text{DCT: } X[k] = \sum_{n=0}^{N-1} x[n] \cos \frac{2\pi(2n+1)k}{4N}$$

$$\text{IDCT: } x[n] = \frac{1}{N} X[0] + \frac{2}{N} \sum_{k=1}^{N-1} X[k] \cos \frac{2\pi(2n+1)k}{4N}$$



$$\text{Energy: } E = \sum_{n=0}^{N-1} |x[n]|^2 = \frac{1}{N} |X[0]|^2 + \frac{2}{N} \sum_{n=1}^{N-1} |X[n]|^2$$

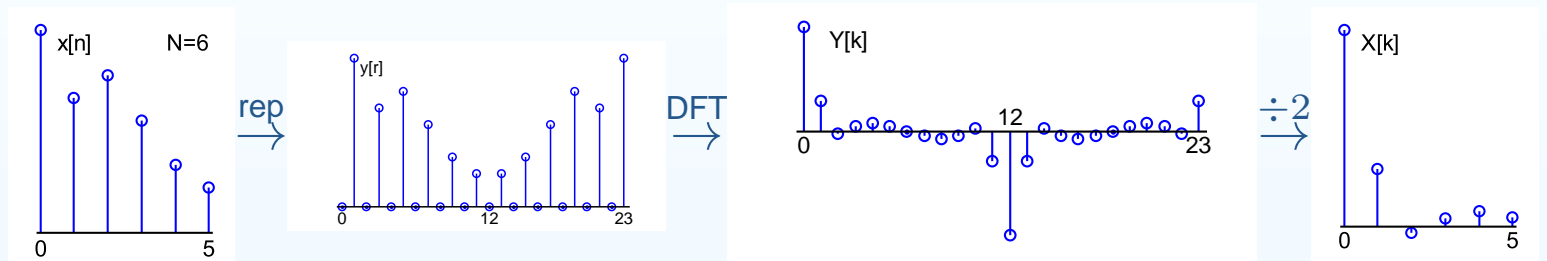
Energy Conservation

3: Discrete Cosine Transform

- DFT Problems
- DCT
- Basis Functions
- DCT of sine wave
- DCT Properties
- **Energy Conservation**
- Energy Compaction
- Frame-based coding
- Lapped Transform
- MDCT (Modified DCT)
- MDCT Basis Elements
- Summary
- MATLAB routines

$$\text{DCT: } X[k] = \sum_{n=0}^{N-1} x[n] \cos \frac{2\pi(2n+1)k}{4N}$$

$$\text{IDCT: } x[n] = \frac{1}{N} X[0] + \frac{2}{N} \sum_{k=1}^{N-1} X[k] \cos \frac{2\pi(2n+1)k}{4N}$$



$$\text{Energy: } E = \sum_{n=0}^{N-1} |x[n]|^2 = \frac{1}{N} |X[0]|^2 + \frac{2}{N} \sum_{n=1}^{N-1} |X[n]|^2$$

In diagram above: $E \rightarrow 2E \rightarrow 8NE \rightarrow \approx 0.5NE$

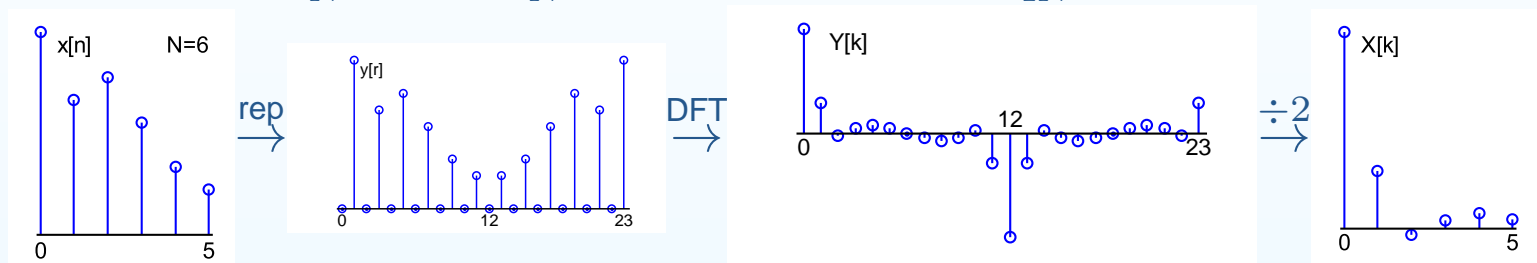
Energy Conservation

3: Discrete Cosine Transform

- DFT Problems
- DCT
- Basis Functions
- DCT of sine wave
- DCT Properties
- **Energy Conservation**
- Energy Compaction
- Frame-based coding
- Lapped Transform
- MDCT (Modified DCT)
- MDCT Basis Elements
- Summary
- MATLAB routines

$$\text{DCT: } X[k] = \sum_{n=0}^{N-1} x[n] \cos \frac{2\pi(2n+1)k}{4N}$$

$$\text{IDCT: } x[n] = \frac{1}{N} X[0] + \frac{2}{N} \sum_{k=1}^{N-1} X[k] \cos \frac{2\pi(2n+1)k}{4N}$$



$$\text{Energy: } E = \sum_{n=0}^{N-1} |x[n]|^2 = \frac{1}{N} |X[0]|^2 + \frac{2}{N} \sum_{n=1}^{N-1} |X[n]|^2$$

In diagram above: $E \rightarrow 2E \rightarrow 8NE \rightarrow \approx 0.5NE$

Orthogonal DCT (preserves energy: $\sum |x[n]|^2 = \sum |X[n]|^2$)

Note: MATLAB dct() calculates the ODCT

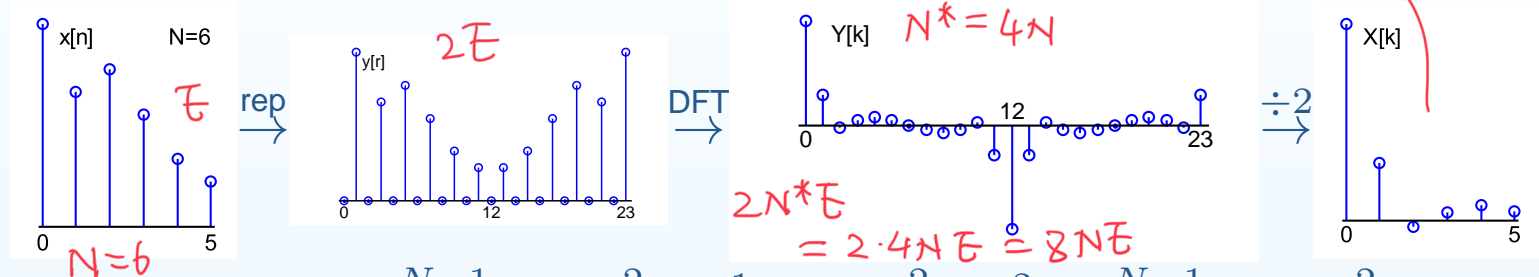
3: Discrete Cosine Transform

- DFT Problems
- DCT
- Basis Functions
- DCT of sine wave
- DCT Properties
- **Energy Conservation**
- Energy Compaction
- Frame-based coding
- Lapped Transform
- MDCT (Modified DCT)
- MDCT Basis Elements
- Summary
- MATLAB routines

Energy Conservation

$$\text{DCT: } X[k] = \sum_{n=0}^{N-1} x[n] \cos \frac{2\pi(2n+1)k}{4N}$$

$$\text{IDCT: } x[n] = \frac{1}{N} X[0] + \frac{2}{N} \sum_{k=1}^{N-1} X[k] \cos \frac{2\pi(2n+1)k}{4N}$$



$$\text{Energy: } E = \sum_{n=0}^{N-1} |x[n]|^2 = \frac{1}{N} |X[0]|^2 + \frac{2}{N} \sum_{n=1}^{N-1} |X[n]|^2$$

In diagram above: $E \rightarrow 2E \rightarrow 8NE \rightarrow \approx 0.5NE$

Orthogonal DCT (preserves energy: $\sum |x[n]|^2 = \sum |X[n]|^2$)

$$\text{ODCT: } X[k] = \begin{cases} \sqrt{\frac{1}{N}} \sum_{n=0}^{N-1} x[n] & k = 0 \\ \sqrt{\frac{2}{N}} \sum_{n=0}^{N-1} x[n] \cos \frac{2\pi(2n+1)k}{4N} & k \neq 0 \end{cases}$$

Note: MATLAB `dct()` calculates the ODCT

3: Discrete Cosine Transform

- DFT Problems
- DCT
- Basis Functions
- DCT of sine wave
- DCT Properties
- **Energy Conservation**
- Energy Compaction
- Frame-based coding
- Lapped Transform
- MDCT (Modified DCT)
- MDCT Basis Elements
- Summary
- MATLAB routines

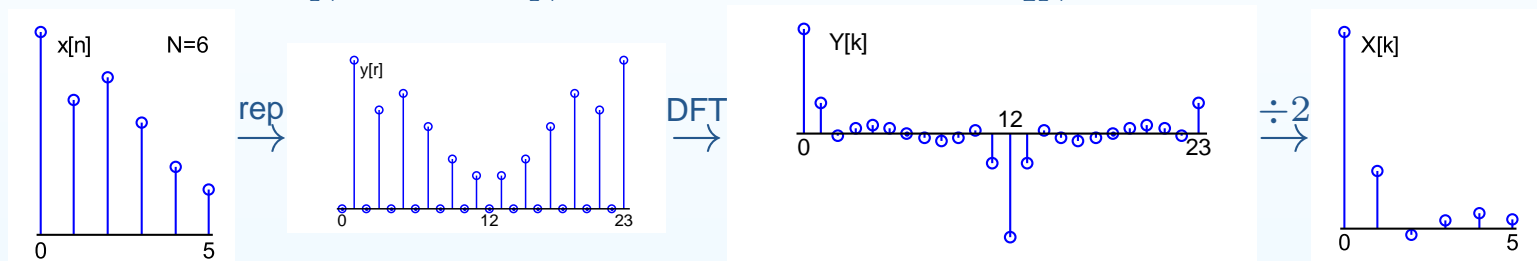
+

+

Energy Conservation

$$\text{DCT: } X[k] = \sum_{n=0}^{N-1} x[n] \cos \frac{2\pi(2n+1)k}{4N}$$

$$\text{IDCT: } x[n] = \frac{1}{N} X[0] + \frac{2}{N} \sum_{k=1}^{N-1} X[k] \cos \frac{2\pi(2n+1)k}{4N}$$



$$\text{Energy: } E = \sum_{n=0}^{N-1} |x[n]|^2 = \frac{1}{N} |X[0]|^2 + \frac{2}{N} \sum_{n=1}^{N-1} |X[n]|^2$$

In diagram above: $E \rightarrow 2E \rightarrow 8NE \rightarrow \approx 0.5NE$

Orthogonal DCT (preserves energy: $\sum |x[n]|^2 = \sum |X[n]|^2$)

$$\text{ODCT: } X[k] = \begin{cases} \sqrt{\frac{1}{N}} \sum_{n=0}^{N-1} x[n] & k = 0 \\ \sqrt{\frac{2}{N}} \sum_{n=0}^{N-1} x[n] \cos \frac{2\pi(2n+1)k}{4N} & k \neq 0 \end{cases}$$

$$\text{IODCT: } x[n] = \sqrt{\frac{1}{N}} X[0] + \sqrt{\frac{2}{N}} \sum_{k=1}^{N-1} X[k] \cos \frac{2\pi(2n+1)k}{4N}$$

Note: MATLAB dct() calculates the ODCT

Energy Compaction

3: Discrete Cosine Transform

- DFT Problems
- DCT +
- Basis Functions
- DCT of sine wave
- DCT Properties
- Energy Conservation
- Energy Compaction
- Frame-based coding
- Lapped Transform +
- MDCT (Modified DCT)
- MDCT Basis Elements
- Summary
- MATLAB routines

If consecutive $x[n]$ are positively correlated, DCT concentrates energy in a few $X[k]$ and decorrelates them.

3: Discrete Cosine Transform

- DFT Problems
- DCT
- Basis Functions
- DCT of sine wave
- DCT Properties
- Energy Conservation
- **Energy Compaction**
- Frame-based coding
- Lapped Transform
- MDCT (Modified DCT)
- MDCT Basis Elements
- Summary
- MATLAB routines

Energy Compaction

If consecutive $x[n]$ are positively correlated, DCT concentrates energy in a few $X[k]$ and decorrelates them.

Example: Markov Process: $x[n] = \rho x[n-1] + \sqrt{1-\rho^2}u[n]$

where $u[n]$ is i.i.d. unit Gaussian.

Then $\langle x^2[n] \rangle = 1$ and $\langle x[n]x[n-1] \rangle = \rho$.

Covariance of vector \mathbf{x} is $\mathbf{S}_{i,j} = \langle \mathbf{x}\mathbf{x}^H \rangle_{i,j} = \rho^{|i-j|}$.

3: Discrete Cosine Transform

- DFT Problems
- DCT
- Basis Functions
- DCT of sine wave
- DCT Properties
- Energy Conservation
- **Energy Compaction**
- Frame-based coding
- Lapped Transform
- MDCT (Modified DCT)
- MDCT Basis Elements
- Summary
- MATLAB routines

Energy Compaction

If consecutive $x[n]$ are positively correlated, DCT concentrates energy in a few $X[k]$ and decorrelates them.

Example: Markov Process: $x[n] = \rho x[n-1] + \sqrt{1-\rho^2}u[n]$
where $u[n]$ is i.i.d. unit Gaussian.

Then $\langle x^2[n] \rangle = 1$ and $\langle x[n]x[n-1] \rangle = \rho$.

Covariance of vector \mathbf{x} is $\mathbf{S}_{i,j} = \langle \mathbf{x}\mathbf{x}^H \rangle_{i,j} = \rho^{|i-j|}$.

Suppose ODCT of \mathbf{x} is $\mathbf{C}\mathbf{x}$ and DFT is $\mathbf{F}\mathbf{x}$.

Covariance of $\mathbf{C}\mathbf{x}$ is $\langle \mathbf{C}\mathbf{x}\mathbf{x}^H\mathbf{C}^H \rangle = \mathbf{C}\mathbf{S}\mathbf{C}^H$ (similarly $\mathbf{F}\mathbf{S}\mathbf{F}^H$)

Diagonal elements give mean coefficient energy.

Energy Compaction

3: Discrete Cosine Transform

- DFT Problems
- DCT
- Basis Functions
- DCT of sine wave
- DCT Properties
- Energy Conservation
- Energy Compaction
- Frame-based coding
- Lapped Transform
- MDCT (Modified DCT)
- MDCT Basis Elements
- Summary
- MATLAB routines

If consecutive $x[n]$ are positively correlated, DCT concentrates energy in a few $X[k]$ and decorrelates them.

Example: Markov Process: $x[n] = \rho x[n-1] + \sqrt{1-\rho^2}u[n]$
where $u[n]$ is i.i.d. unit Gaussian.

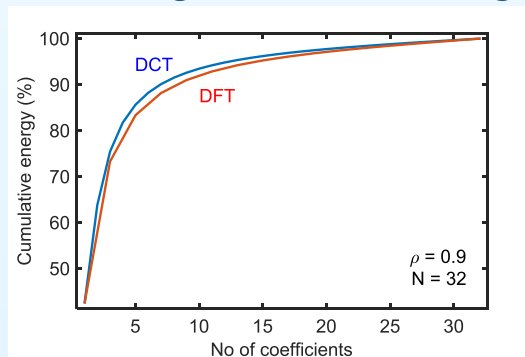
Then $\langle x^2[n] \rangle = 1$ and $\langle x[n]x[n-1] \rangle = \rho$.

Covariance of vector \mathbf{x} is $\mathbf{S}_{i,j} = \langle \mathbf{x}\mathbf{x}^H \rangle_{i,j} = \rho^{|i-j|}$.

Suppose ODCT of \mathbf{x} is $\mathbf{C}\mathbf{x}$ and DFT is $\mathbf{F}\mathbf{x}$.

Covariance of $\mathbf{C}\mathbf{x}$ is $\langle \mathbf{C}\mathbf{x}\mathbf{x}^H\mathbf{C}^H \rangle = \mathbf{C}\mathbf{S}\mathbf{C}^H$ (similarly $\mathbf{F}\mathbf{S}\mathbf{F}^H$)

Diagonal elements give mean coefficient energy.



3: Discrete Cosine Transform

- DFT Problems
- DCT
- Basis Functions
- DCT of sine wave
- DCT Properties
- Energy Conservation
- Energy Compaction
- Frame-based coding
- Lapped Transform
- MDCT (Modified DCT)
- MDCT Basis Elements
- Summary
- MATLAB routines

Energy Compaction

If consecutive $x[n]$ are positively correlated, DCT concentrates energy in a few $X[k]$ and decorrelates them.

Example: Markov Process: $x[n] = \rho x[n-1] + \sqrt{1-\rho^2}u[n]$
where $u[n]$ is i.i.d. unit Gaussian.

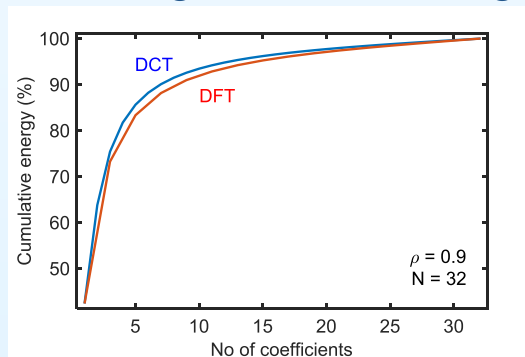
Then $\langle x^2[n] \rangle = 1$ and $\langle x[n]x[n-1] \rangle = \rho$.

Covariance of vector \mathbf{x} is $\mathbf{S}_{i,j} = \langle \mathbf{x}\mathbf{x}^H \rangle_{i,j} = \rho^{|i-j|}$.

Suppose ODCT of \mathbf{x} is $\mathbf{C}\mathbf{x}$ and DFT is $\mathbf{F}\mathbf{x}$.

Covariance of $\mathbf{C}\mathbf{x}$ is $\langle \mathbf{C}\mathbf{x}\mathbf{x}^H\mathbf{C}^H \rangle = \mathbf{C}\mathbf{S}\mathbf{C}^H$ (similarly $\mathbf{F}\mathbf{S}\mathbf{F}^H$)

Diagonal elements give mean coefficient energy.



- Used in MPEG and JPEG (superseded by JPEG2000 using wavelets)
- Used in speech recognition to decorrelate spectral coefficients: DCT of log spectrum

Energy Compaction

3: Discrete Cosine Transform

- DFT Problems
- DCT
- Basis Functions
- DCT of sine wave
- DCT Properties
- Energy Conservation
- **Energy Compaction**
- Frame-based coding
- Lapped Transform
- MDCT (Modified DCT)
- MDCT Basis Elements
- Summary
- MATLAB routines

If consecutive $x[n]$ are positively correlated, DCT concentrates energy in a few $X[k]$ and decorrelates them.

Example: Markov Process: $x[n] = \rho x[n-1] + \sqrt{1-\rho^2}u[n]$
where $u[n]$ is i.i.d. unit Gaussian.

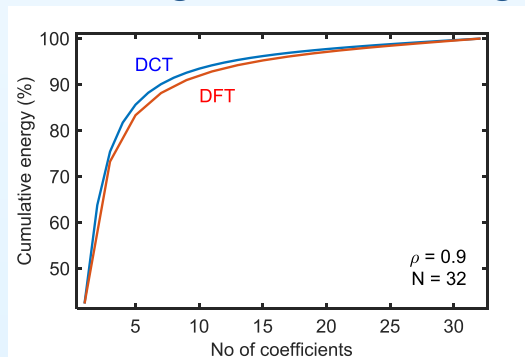
Then $\langle x^2[n] \rangle = 1$ and $\langle x[n]x[n-1] \rangle = \rho$.

Covariance of vector \mathbf{x} is $\mathbf{S}_{i,j} = \langle \mathbf{x}\mathbf{x}^H \rangle_{i,j} = \rho^{|i-j|}$.

Suppose ODCT of \mathbf{x} is $\mathbf{C}\mathbf{x}$ and DFT is $\mathbf{F}\mathbf{x}$.

Covariance of $\mathbf{C}\mathbf{x}$ is $\langle \mathbf{C}\mathbf{x}\mathbf{x}^H\mathbf{C}^H \rangle = \mathbf{C}\mathbf{S}\mathbf{C}^H$ (similarly $\mathbf{F}\mathbf{S}\mathbf{F}^H$)

Diagonal elements give mean coefficient energy.



- Used in MPEG and JPEG (superseded by JPEG2000 using wavelets)
- Used in speech recognition to decorrelate spectral coefficients: DCT of log spectrum

Energy compaction good for coding (low-valued coefficients can be set to 0)

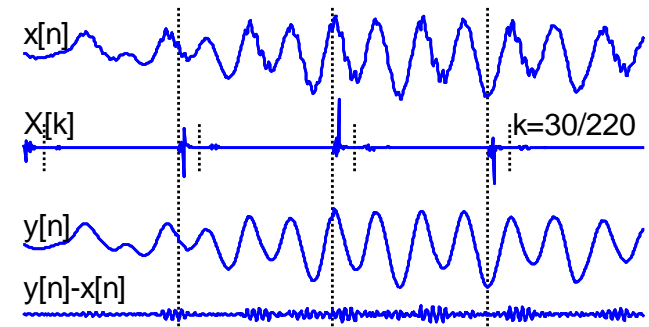
Decorrelation good for coding and for probability modelling

Frame-based coding

3: Discrete Cosine Transform

- DFT Problems
- DCT +
- Basis Functions
- DCT of sine wave
- DCT Properties
- Energy Conservation
- Energy Compaction
- **Frame-based coding**
- Lapped Transform +
- MDCT (Modified DCT)
- MDCT Basis Elements
- Summary
- MATLAB routines

- Divide continuous signal into frames

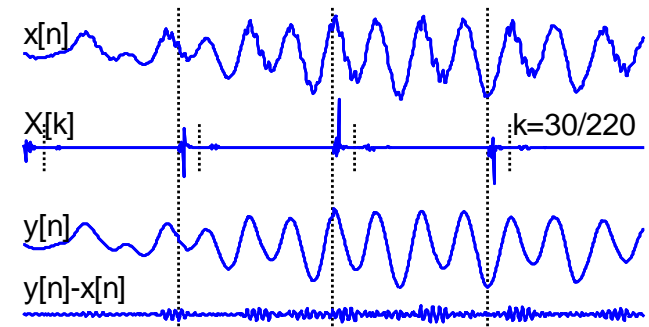


3: Discrete Cosine Transform

- DFT Problems
- DCT
- Basis Functions
- DCT of sine wave
- DCT Properties
- Energy Conservation
- Energy Compaction
- **Frame-based coding**
- Lapped Transform
- MDCT (Modified DCT)
- MDCT Basis Elements
- Summary
- MATLAB routines

Frame-based coding

- Divide continuous signal into frames
- Apply DCT to each frame

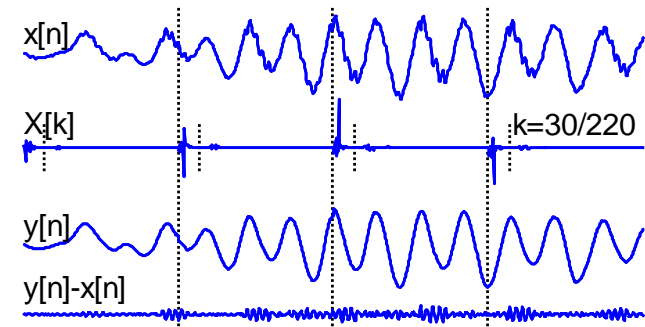


3: Discrete Cosine Transform

- DFT Problems
- DCT
- Basis Functions
- DCT of sine wave
- DCT Properties
- Energy Conservation
- Energy Compaction
- **Frame-based coding**
- Lapped Transform
- MDCT (Modified DCT)
- MDCT Basis Elements
- Summary
- MATLAB routines

Frame-based coding

- Divide continuous signal into frames
- Apply DCT to each frame
- Encode DCT
 - e.g. keep only 30 $X[k]$

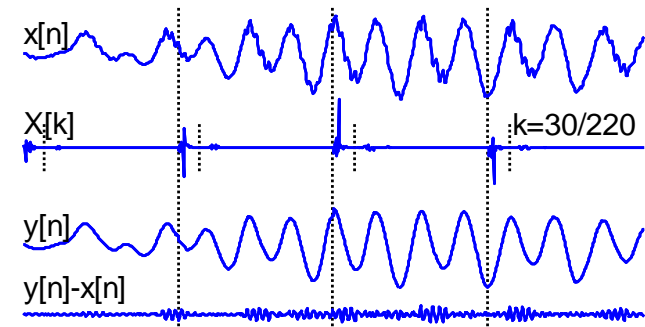


3: Discrete Cosine Transform

- DFT Problems
- DCT
- Basis Functions
- DCT of sine wave
- DCT Properties
- Energy Conservation
- Energy Compaction
- **Frame-based coding**
- Lapped Transform
- MDCT (Modified DCT)
- MDCT Basis Elements
- Summary
- MATLAB routines

Frame-based coding

- Divide continuous signal into frames
- Apply DCT to each frame
- Encode DCT
 - e.g. keep only 30 $X[k]$
- Apply IDCT $\rightarrow y[n]$

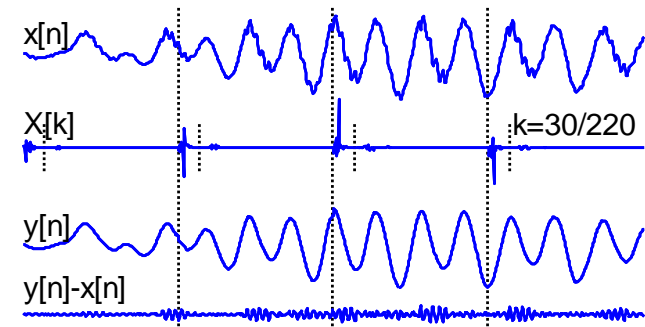


3: Discrete Cosine Transform

- DFT Problems
- DCT
- Basis Functions
- DCT of sine wave
- DCT Properties
- Energy Conservation
- Energy Compaction
- **Frame-based coding**
- Lapped Transform
- MDCT (Modified DCT)
- MDCT Basis Elements
- Summary
- MATLAB routines

Frame-based coding

- Divide continuous signal into frames
- Apply DCT to each frame
- Encode DCT
 - e.g. keep only 30 $X[k]$
- Apply IDCT $\rightarrow y[n]$



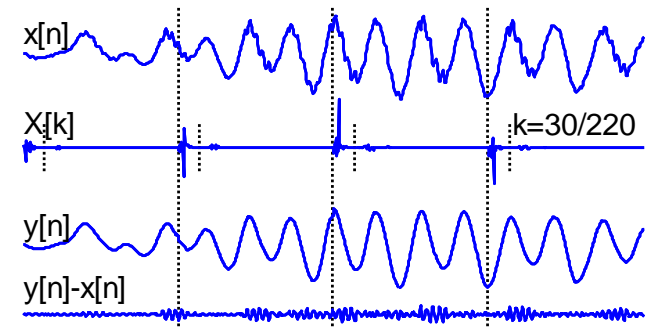
Problem: Coding may create discontinuities at frame boundaries

3: Discrete Cosine Transform

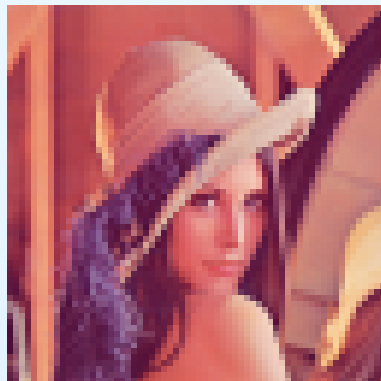
- DFT Problems
- DCT
- Basis Functions
- DCT of sine wave
- DCT Properties
- Energy Conservation
- Energy Compaction
- **Frame-based coding**
- Lapped Transform
- MDCT (Modified DCT)
- MDCT Basis Elements
- Summary
- MATLAB routines

Frame-based coding

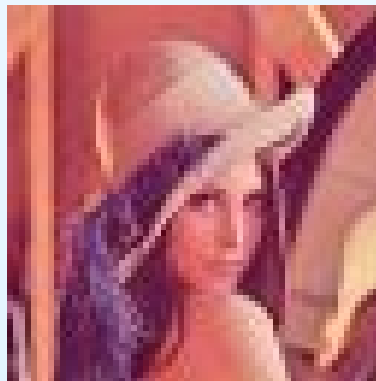
- Divide continuous signal into frames
- Apply DCT to each frame
- Encode DCT
 - e.g. keep only 30 $X[k]$
- Apply IDCT $\rightarrow y[n]$



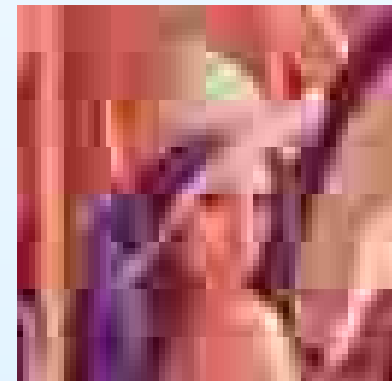
Problem: Coding may create discontinuities at frame boundaries
e.g. JPEG, MPEG use 8×8 pixel blocks



8.3 kB (PNG)



1.6 kB (JPEG)



0.5 kB (JPEG)

Lapped Transform

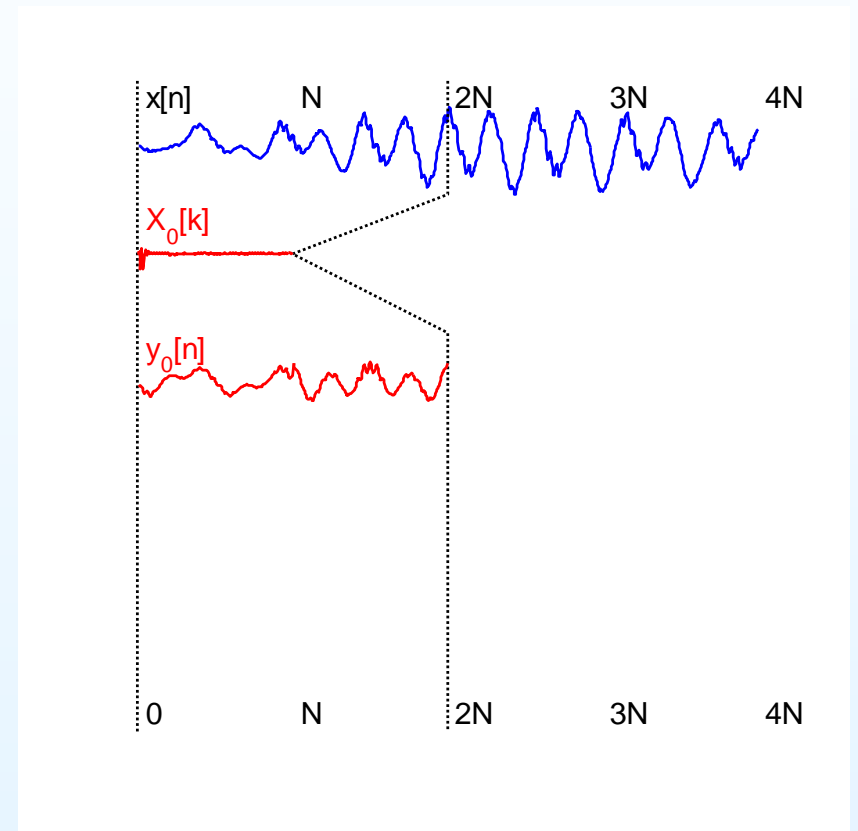


3: Discrete Cosine Transform

- DFT Problems
- DCT
- Basis Functions
- DCT of sine wave
- DCT Properties
- Energy Conservation
- Energy Compaction
- Frame-based coding
- **Lapped Transform**
- MDCT (Modified DCT)
- MDCT Basis Elements
- Summary
- MATLAB routines

Modified Discrete Cosine Transform (MDCT): overlapping frames $2N$ long

$$x[0 : 2N - 1]$$



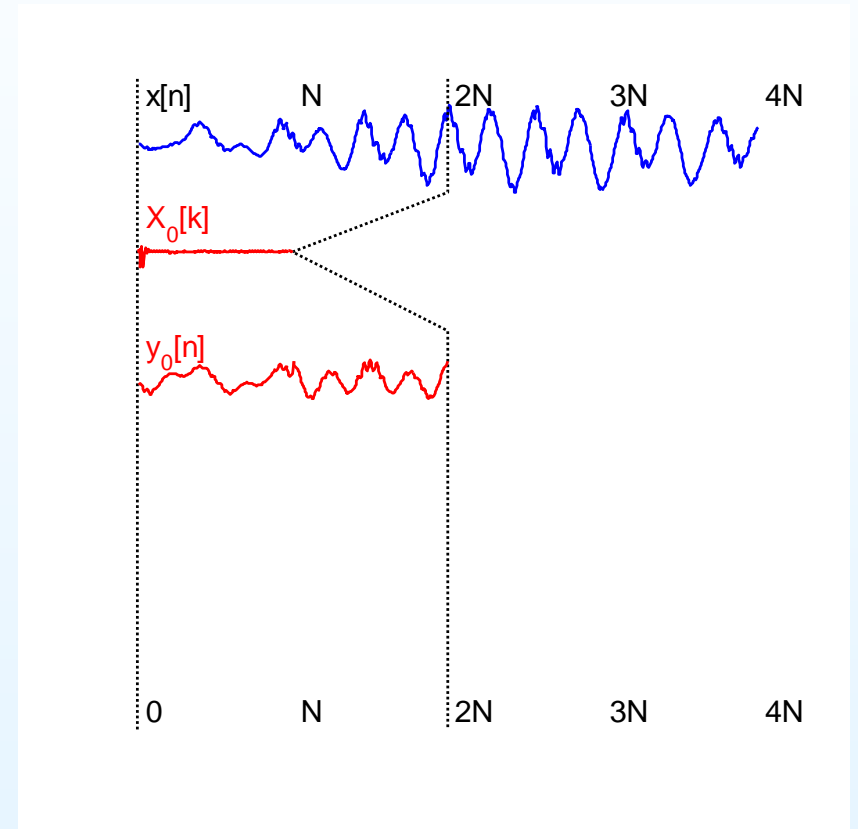
Lapped Transform

3: Discrete Cosine Transform

- DFT Problems
- DCT
- Basis Functions
- DCT of sine wave
- DCT Properties
- Energy Conservation
- Energy Compaction
- Frame-based coding
- **Lapped Transform**
- MDCT (Modified DCT)
- MDCT Basis Elements
- Summary
- MATLAB routines

Modified Discrete Cosine Transform (MDCT): overlapping frames $2N$ long

$$x[0 : 2N - 1] \xrightarrow{\text{MDCT}} X_0[0 : N - 1]$$



MDCT: $2N \rightarrow N$ coefficients

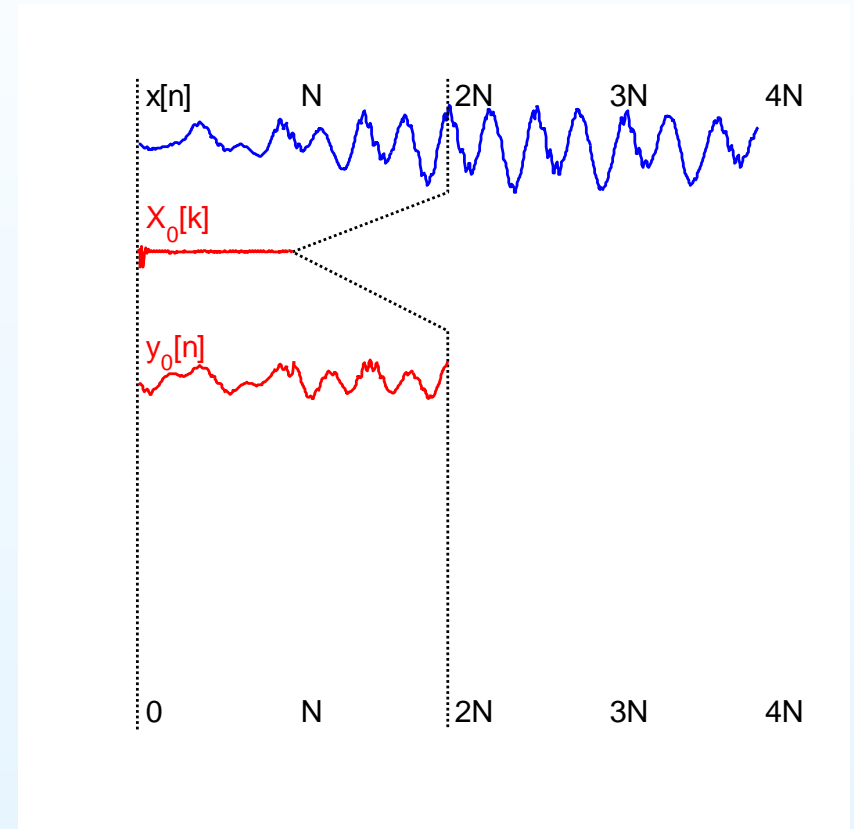
Lapped Transform

3: Discrete Cosine Transform

- DFT Problems
- DCT
- Basis Functions
- DCT of sine wave
- DCT Properties
- Energy Conservation
- Energy Compaction
- Frame-based coding
- Lapped Transform
- MDCT (Modified DCT)
- MDCT Basis Elements
- Summary
- MATLAB routines

Modified Discrete Cosine Transform (MDCT): overlapping frames $2N$ long

$$\begin{aligned}
 x[0 : 2N - 1] &\xrightarrow{\text{MDCT}} X_0[0 : N - 1] \\
 &\xrightarrow{\text{IMDCT}} y_0[0 : 2N - 1]
 \end{aligned}$$



MDCT: $2N \rightarrow N$ coefficients, IMDCT: $N \rightarrow 2N$ samples

Lapped Transform

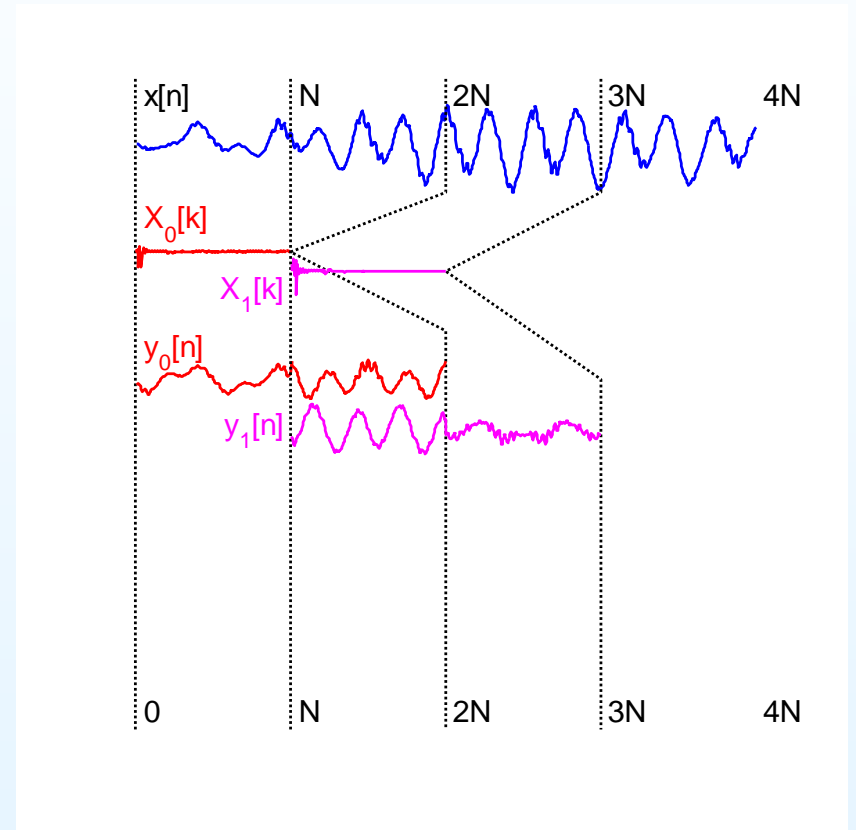
3: Discrete Cosine Transform

- DFT Problems
- DCT
- Basis Functions
- DCT of sine wave
- DCT Properties
- Energy Conservation
- Energy Compaction
- Frame-based coding
- Lapped Transform
- MDCT (Modified DCT)
- MDCT Basis Elements
- Summary
- MATLAB routines

Modified Discrete Cosine Transform (MDCT): overlapping frames $2N$ long

$$\begin{aligned} x[0 : 2N - 1] \\ \xrightarrow{\text{MDCT}} X_0[0 : N - 1] \\ \xrightarrow{\text{IMDCT}} y_0[0 : 2N - 1] \end{aligned}$$

$$\begin{aligned} x[N : 3N - 1] \\ \xrightarrow{\text{MDCT}} X_1[N : 2N - 1] \end{aligned}$$



MDCT: $2N \rightarrow N$ coefficients, IMDCT: $N \rightarrow 2N$ samples

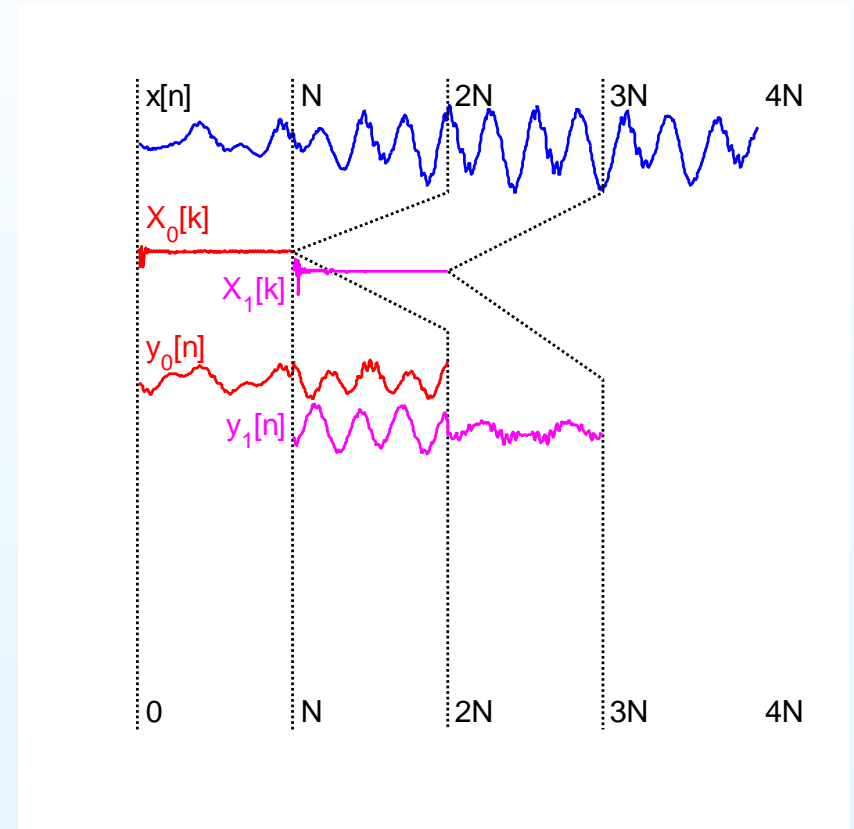
Lapped Transform

3: Discrete Cosine Transform

- DFT Problems
- DCT
- Basis Functions
- DCT of sine wave
- DCT Properties
- Energy Conservation
- Energy Compaction
- Frame-based coding
- **Lapped Transform**
- MDCT (Modified DCT)
- MDCT Basis Elements
- Summary
- MATLAB routines

Modified Discrete Cosine Transform (MDCT): overlapping frames $2N$ long

$$\begin{aligned}
 x[0 : 2N - 1] &\xrightarrow{\text{MDCT}} X_0[0 : N - 1] \\
 &\xrightarrow{\text{IMDCT}} y_0[0 : 2N - 1] \\
 x[N : 3N - 1] &\xrightarrow{\text{MDCT}} X_1[N : 2N - 1] \\
 &\xrightarrow{\text{IMDCT}} y_1[N : 3N - 1]
 \end{aligned}$$



MDCT: $2N \rightarrow N$ coefficients, IMDCT: $N \rightarrow 2N$ samples

Lapped Transform

3: Discrete Cosine Transform

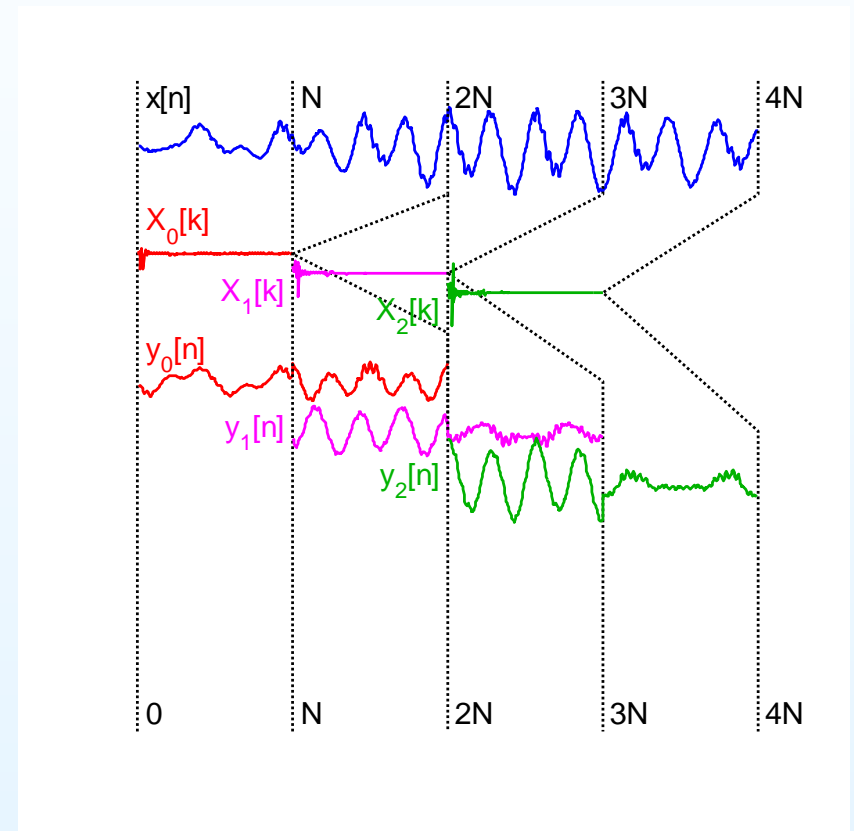
- DFT Problems
- DCT
- Basis Functions
- DCT of sine wave
- DCT Properties
- Energy Conservation
- Energy Compaction
- Frame-based coding
- Lapped Transform
- MDCT (Modified DCT)
- MDCT Basis Elements
- Summary
- MATLAB routines

Modified Discrete Cosine Transform (MDCT): overlapping frames $2N$ long

$$\begin{aligned} x[0 : 2N - 1] \\ \xrightarrow{\text{MDCT}} X_0[0 : N - 1] \\ \xrightarrow{\text{IMDCT}} y_0[0 : 2N - 1] \end{aligned}$$

$$\begin{aligned} x[N : 3N - 1] \\ \xrightarrow{\text{MDCT}} X_1[N : 2N - 1] \\ \xrightarrow{\text{IMDCT}} y_1[N : 3N - 1] \end{aligned}$$

$$\begin{aligned} x[2N : 4N - 1] \\ \xrightarrow{\text{MDCT}} X_2[2N : 3N - 1] \end{aligned}$$



MDCT: $2N \rightarrow N$ coefficients, IMDCT: $N \rightarrow 2N$ samples

Lapped Transform

3: Discrete Cosine Transform

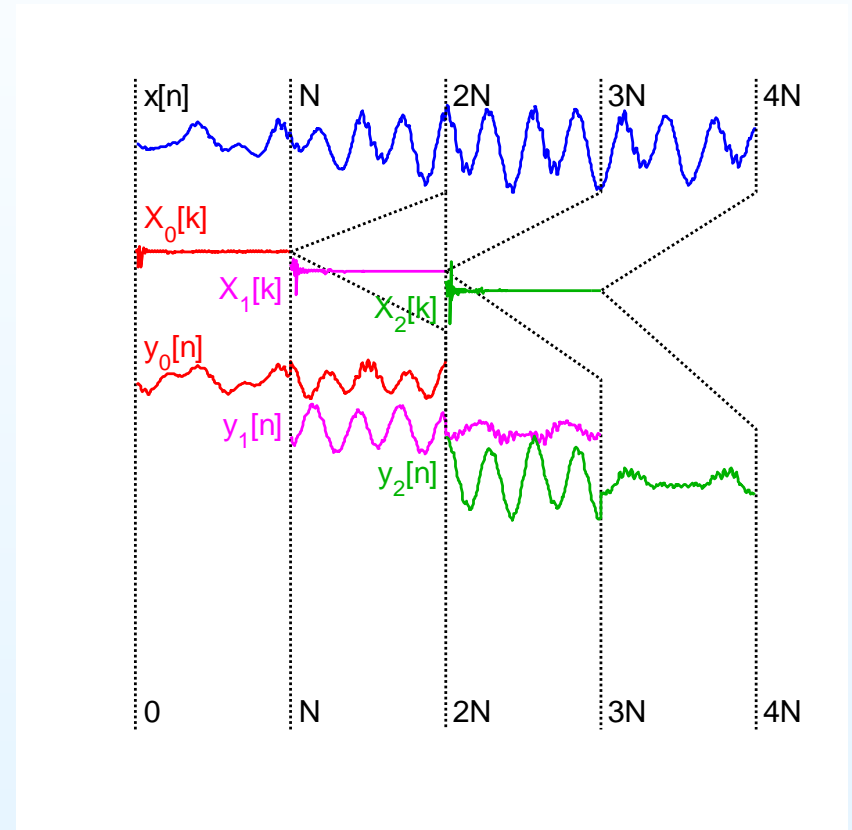
- DFT Problems
- DCT
- Basis Functions
- DCT of sine wave
- DCT Properties
- Energy Conservation
- Energy Compaction
- Frame-based coding
- Lapped Transform
- MDCT (Modified DCT)
- MDCT Basis Elements
- Summary
- MATLAB routines

Modified Discrete Cosine Transform (MDCT): overlapping frames $2N$ long

$$\begin{aligned} x[0 : 2N - 1] \\ \xrightarrow{\text{MDCT}} X_0[0 : N - 1] \\ \xrightarrow{\text{IMDCT}} y_0[0 : 2N - 1] \end{aligned}$$

$$\begin{aligned} x[N : 3N - 1] \\ \xrightarrow{\text{MDCT}} X_1[N : 2N - 1] \\ \xrightarrow{\text{IMDCT}} y_1[N : 3N - 1] \end{aligned}$$

$$\begin{aligned} x[2N : 4N - 1] \\ \xrightarrow{\text{MDCT}} X_2[2N : 3N - 1] \\ \xrightarrow{\text{IMDCT}} y_2[2N : 4N - 1] \end{aligned}$$



MDCT: $2N \rightarrow N$ coefficients, IMDCT: $N \rightarrow 2N$ samples

Lapped Transform

3: Discrete Cosine Transform

- DFT Problems
- DCT
- Basis Functions
- DCT of sine wave
- DCT Properties
- Energy Conservation
- Energy Compaction
- Frame-based coding
- Lapped Transform
- MDCT (Modified DCT)
- MDCT Basis Elements
- Summary
- MATLAB routines

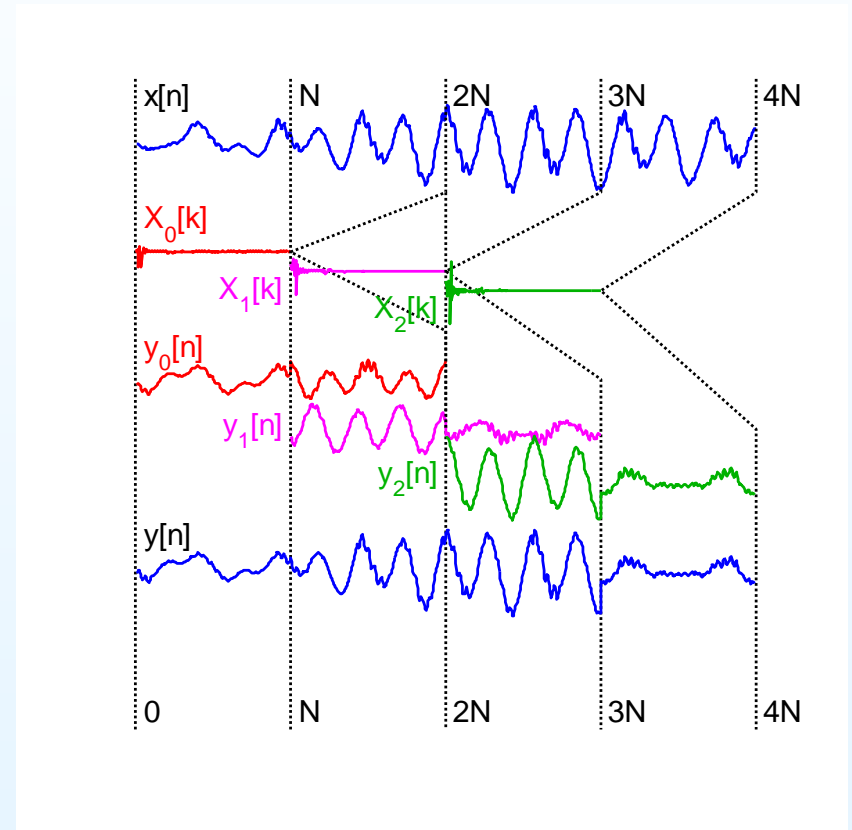
Modified Discrete Cosine Transform (MDCT): overlapping frames $2N$ long

$$\begin{aligned} x[0 : 2N - 1] \\ \xrightarrow{\text{MDCT}} X_0[0 : N - 1] \\ \xrightarrow{\text{IMDCT}} y_0[0 : 2N - 1] \end{aligned}$$

$$\begin{aligned} x[N : 3N - 1] \\ \xrightarrow{\text{MDCT}} X_1[N : 2N - 1] \\ \xrightarrow{\text{IMDCT}} y_1[N : 3N - 1] \end{aligned}$$

$$\begin{aligned} x[2N : 4N - 1] \\ \xrightarrow{\text{MDCT}} X_2[2N : 3N - 1] \\ \xrightarrow{\text{IMDCT}} y_2[2N : 4N - 1] \end{aligned}$$

$$y[n] = y_0[n] + y_1[n] + y_2[n]$$



MDCT: $2N \rightarrow N$ coefficients, **IMDCT:** $N \rightarrow 2N$ samples

Add $y_i[n]$ together to get $y[n]$. Only two non-zero terms for any n .

Lapped Transform

3: Discrete Cosine Transform

- DFT Problems
- DCT
- Basis Functions
- DCT of sine wave
- DCT Properties
- Energy Conservation
- Energy Compaction
- Frame-based coding
- Lapped Transform
- MDCT (Modified DCT)
- MDCT Basis Elements
- Summary
- MATLAB routines

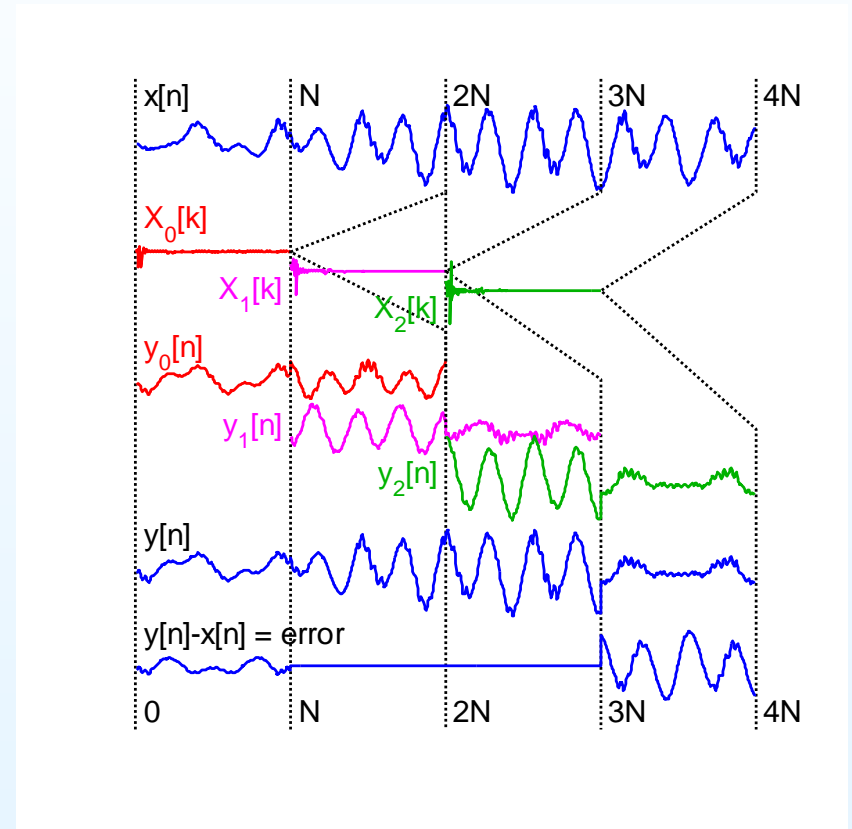
Modified Discrete Cosine Transform (MDCT): overlapping frames $2N$ long

$$\begin{aligned} x[0 : 2N - 1] \\ \xrightarrow{\text{MDCT}} X_0[0 : N - 1] \\ \xrightarrow{\text{IMDCT}} y_0[0 : 2N - 1] \end{aligned}$$

$$\begin{aligned} x[N : 3N - 1] \\ \xrightarrow{\text{MDCT}} X_1[N : 2N - 1] \\ \xrightarrow{\text{IMDCT}} y_1[N : 3N - 1] \end{aligned}$$

$$\begin{aligned} x[2N : 4N - 1] \\ \xrightarrow{\text{MDCT}} X_2[2N : 3N - 1] \\ \xrightarrow{\text{IMDCT}} y_2[2N : 4N - 1] \end{aligned}$$

$$y[n] = y_0[n] + y_1[n] + y_2[n]$$



MDCT: $2N \rightarrow N$ coefficients, **IMDCT:** $N \rightarrow 2N$ samples

Add $y_i[n]$ together to get $y[n]$. Only two non-zero terms for any n .

Errors cancel exactly: Time-domain alias cancellation (TDAC)

MDCT (Modified DCT)

$$\text{MDCT: } X[k] = \sum_{n=0}^{2N-1} x[n] \cos \frac{2\pi(2n+1+N)(2k+1)}{8N} \quad 0 \leq k < N$$

MDCT (Modified DCT)

$$\text{MDCT: } X[k] = \sum_{n=0}^{2N-1} x[n] \cos \frac{2\pi(2n+1+N)(2k+1)}{8N} \quad 0 \leq k < N$$

If \mathbf{x} and \mathbf{X} are column vectors, then $\mathbf{X} = \mathbf{M}\mathbf{x}$

where \mathbf{M} is an $N \times 2N$ matrix with $m_{k,n} = \cos \frac{2\pi(2n+1+N)(2k+1)}{8N}$.

MDCT (Modified DCT)

$$\text{MDCT: } X[k] = \sum_{n=0}^{2N-1} x[n] \cos \frac{2\pi(2n+1+N)(2k+1)}{8N} \quad 0 \leq k < N$$

$$\text{IMDCT: } y[n] = \frac{1}{N} \sum_{k=0}^{N-1} X[k] \cos \frac{2\pi(2n+1+N)(2k+1)}{8N} \quad 0 \leq n < 2N$$

If \mathbf{x} and \mathbf{X} are column vectors, then $\mathbf{X} = \mathbf{M}\mathbf{x}$

where \mathbf{M} is an $N \times 2N$ matrix with $m_{k,n} = \cos \frac{2\pi(2n+1+N)(2k+1)}{8N}$.

MDCT (Modified DCT)

$$\text{MDCT: } X[k] = \sum_{n=0}^{2N-1} x[n] \cos \frac{2\pi(2n+1+N)(2k+1)}{8N} \quad 0 \leq k < N$$

$$\text{IMDCT: } y[n] = \frac{1}{N} \sum_{k=0}^{N-1} X[k] \cos \frac{2\pi(2n+1+N)(2k+1)}{8N} \quad 0 \leq n < 2N$$

If \mathbf{x} , \mathbf{X} and \mathbf{y} are column vectors, then $\mathbf{X} = \mathbf{M}\mathbf{x}$ and $\mathbf{y} = \frac{1}{N}\mathbf{M}^T\mathbf{X}$

where \mathbf{M} is an $N \times 2N$ matrix with $m_{k,n} = \cos \frac{2\pi(2n+1+N)(2k+1)}{8N}$.

MDCT (Modified DCT)

$$\text{MDCT: } X[k] = \sum_{n=0}^{2N-1} x[n] \cos \frac{2\pi(2n+1+N)(2k+1)}{8N} \quad 0 \leq k < N$$

$$\text{IMDCT: } y[n] = \frac{1}{N} \sum_{k=0}^{N-1} X[k] \cos \frac{2\pi(2n+1+N)(2k+1)}{8N} \quad 0 \leq n < 2N$$

If \mathbf{x} , \mathbf{X} and \mathbf{y} are column vectors, then $\mathbf{X} = \mathbf{M}\mathbf{x}$ and $\mathbf{y} = \frac{1}{N}\mathbf{M}^T\mathbf{X} = \frac{1}{N}\mathbf{M}^T\mathbf{M}\mathbf{x}$

where \mathbf{M} is an $N \times 2N$ matrix with $m_{k,n} = \cos \frac{2\pi(2n+1+N)(2k+1)}{8N}$.

MDCT (Modified DCT)

$$\text{MDCT: } X[k] = \sum_{n=0}^{2N-1} x[n] \cos \frac{2\pi(2n+1+N)(2k+1)}{8N} \quad 0 \leq k < N$$

$$\text{IMDCT: } y[n] = \frac{1}{N} \sum_{k=0}^{N-1} X[k] \cos \frac{2\pi(2n+1+N)(2k+1)}{8N} \quad 0 \leq n < 2N$$

If \mathbf{x} , \mathbf{X} and \mathbf{y} are column vectors, then $\mathbf{X} = \mathbf{M}\mathbf{x}$ and $\mathbf{y} = \frac{1}{N}\mathbf{M}^T\mathbf{X} = \frac{1}{N}\mathbf{M}^T\mathbf{M}\mathbf{x}$

where \mathbf{M} is an $N \times 2N$ matrix with $m_{k,n} = \cos \frac{2\pi(2n+1+N)(2k+1)}{8N}$.

Quasi-Orthogonality: The $2N \times 2N$ matrix, $\frac{1}{N}\mathbf{M}^T\mathbf{M}$, is almost the identity:

$$\frac{1}{N}\mathbf{M}^T\mathbf{M} = \frac{1}{2} \begin{bmatrix} \mathbf{I} - \mathbf{J} & \mathbf{0} \\ \mathbf{0} & \mathbf{I} + \mathbf{J} \end{bmatrix} \text{ with } \mathbf{I} = \begin{bmatrix} 1 & \cdots & 0 \\ \vdots & \ddots & \vdots \\ 0 & \cdots & 1 \end{bmatrix}, \mathbf{J} = \begin{bmatrix} 0 & \cdots & 1 \\ \vdots & \ddots & \vdots \\ 1 & \cdots & 0 \end{bmatrix}$$

MDCT (Modified DCT)

$$\text{MDCT: } X[k] = \sum_{n=0}^{2N-1} x[n] \cos \frac{2\pi(2n+1+N)(2k+1)}{8N} \quad 0 \leq k < N$$

$$\text{IMDCT: } y[n] = \frac{1}{N} \sum_{k=0}^{N-1} X[k] \cos \frac{2\pi(2n+1+N)(2k+1)}{8N} \quad 0 \leq n < 2N$$

If \mathbf{x} , \mathbf{X} and \mathbf{y} are column vectors, then $\mathbf{X} = \mathbf{M}\mathbf{x}$ and $\mathbf{y} = \frac{1}{N}\mathbf{M}^T\mathbf{X} = \frac{1}{N}\mathbf{M}^T\mathbf{M}\mathbf{x}$

where \mathbf{M} is an $N \times 2N$ matrix with $m_{k,n} = \cos \frac{2\pi(2n+1+N)(2k+1)}{8N}$.

Quasi-Orthogonality: The $2N \times 2N$ matrix, $\frac{1}{N}\mathbf{M}^T\mathbf{M}$, is almost the identity:

$$\frac{1}{N}\mathbf{M}^T\mathbf{M} = \frac{1}{2} \begin{bmatrix} \mathbf{I} - \mathbf{J} & \mathbf{0} \\ \mathbf{0} & \mathbf{I} + \mathbf{J} \end{bmatrix} \text{ with } \mathbf{I} = \begin{bmatrix} 1 & \cdots & 0 \\ \vdots & \ddots & \vdots \\ 0 & \cdots & 1 \end{bmatrix}, \mathbf{J} = \begin{bmatrix} 0 & \cdots & 1 \\ \vdots & \ddots & \vdots \\ 1 & \cdots & 0 \end{bmatrix}$$

When two consecutive \mathbf{y} frames are overlapped by N samples, the second half of the first frame has thus been multiplied by $\frac{1}{2}(\mathbf{I} + \mathbf{J})$ and the first half of the second frame by $\frac{1}{2}(\mathbf{I} - \mathbf{J})$. When these \mathbf{y} frames are added together, the corresponding \mathbf{x} samples have been multiplied by $\frac{1}{2}(\mathbf{I} + \mathbf{J}) + \frac{1}{2}(\mathbf{I} - \mathbf{J}) = \mathbf{I}$ giving **perfect reconstruction**.

from first frame from second frame

MDCT (Modified DCT)

$$\text{MDCT: } X[k] = \sum_{n=0}^{2N-1} x[n] \cos \frac{2\pi(2n+1+N)(2k+1)}{8N} \quad 0 \leq k < N$$

$$\text{IMDCT: } y[n] = \frac{1}{N} \sum_{k=0}^{N-1} X[k] \cos \frac{2\pi(2n+1+N)(2k+1)}{8N} \quad 0 \leq n < 2N$$

If \mathbf{x} , \mathbf{X} and \mathbf{y} are column vectors, then $\mathbf{X} = \mathbf{M}\mathbf{x}$ and $\mathbf{y} = \frac{1}{N}\mathbf{M}^T\mathbf{X} = \frac{1}{N}\mathbf{M}^T\mathbf{M}\mathbf{x}$

where \mathbf{M} is an $N \times 2N$ matrix with $m_{k,n} = \cos \frac{2\pi(2n+1+N)(2k+1)}{8N}$.

Quasi-Orthogonality: The $2N \times 2N$ matrix, $\frac{1}{N}\mathbf{M}^T\mathbf{M}$, is almost the identity:

$$\frac{1}{N}\mathbf{M}^T\mathbf{M} = \frac{1}{2} \begin{bmatrix} \mathbf{I} - \mathbf{J} & \mathbf{0} \\ \mathbf{0} & \mathbf{I} + \mathbf{J} \end{bmatrix} \text{ with } \mathbf{I} = \begin{bmatrix} 1 & \cdots & 0 \\ \vdots & \ddots & \vdots \\ 0 & \cdots & 1 \end{bmatrix}, \mathbf{J} = \begin{bmatrix} 0 & \cdots & 1 \\ \vdots & \ddots & \vdots \\ 1 & \cdots & 0 \end{bmatrix}$$

When two consecutive \mathbf{y} frames are overlapped by N samples, the second half of the first frame has thus been multiplied by $\frac{1}{2}(\mathbf{I} + \mathbf{J})$ and the first half of the second frame by $\frac{1}{2}(\mathbf{I} - \mathbf{J})$. When these \mathbf{y} frames are added together, the corresponding \mathbf{x} samples have been multiplied by $\frac{1}{2}(\mathbf{I} + \mathbf{J}) + \frac{1}{2}(\mathbf{I} - \mathbf{J}) = \mathbf{I}$ giving **perfect reconstruction**.

Normally the $2N$ -long \mathbf{x} and \mathbf{y} frames are windowed before the MDCT and again after the IMDCT to avoid any discontinuities; if the window is symmetric and satisfies $w^2[i] + w^2[i + N] = 2$ the perfect reconstruction property is still true.

3: Discrete Cosine Transform

- DFT Problems
- DCT +
- Basis Functions
- DCT of sine wave
- DCT Properties
- Energy Conservation
- Energy Compaction
- Frame-based coding
- Lapped Transform +
- MDCT (Modified DCT)
- **MDCT Basis Elements**
- Summary
- MATLAB routines

MDCT Basis Elements

$$\text{MDCT: } X[k] = \sum_{n=0}^{2N-1} x[n] \cos \frac{2\pi(2n+1+N)(2k+1)}{8N} \quad 0 \leq k < N$$

$$\text{IMDCT: } y[n] = \frac{1}{N} \sum_{k=0}^{N-1} X[k] \cos \frac{2\pi(2n+1+N)(2k+1)}{8N} \quad 0 \leq n < 2N$$

3: Discrete Cosine Transform

- DFT Problems
- DCT +
- Basis Functions
- DCT of sine wave
- DCT Properties
- Energy Conservation
- Energy Compaction
- Frame-based coding
- Lapped Transform +
- MDCT (Modified DCT)
- **MDCT Basis Elements**
- Summary
- MATLAB routines

MDCT Basis Elements

$$\text{MDCT: } X[k] = \sum_{n=0}^{2N-1} x[n] \cos \frac{2\pi(2n+1+N)(2k+1)}{8N} \quad 0 \leq k < N$$

$$\text{IMDCT: } y[n] = \frac{1}{N} \sum_{k=0}^{N-1} X[k] \cos \frac{2\pi(2n+1+N)(2k+1)}{8N} \quad 0 \leq n < 2N$$

In vector notation: $\mathbf{X} = \mathbf{M}\mathbf{x}$ and $\mathbf{y} = \frac{1}{N}\mathbf{M}^T\mathbf{X} = \frac{1}{N}\mathbf{M}^T\mathbf{M}\mathbf{x}$

3: Discrete Cosine Transform

- DFT Problems
- DCT +
- Basis Functions
- DCT of sine wave
- DCT Properties
- Energy Conservation
- Energy Compaction
- Frame-based coding
- Lapped Transform +
- MDCT (Modified DCT)
- **MDCT Basis Elements**
- Summary
- MATLAB routines

MDCT Basis Elements

$$\text{MDCT: } X[k] = \sum_{n=0}^{2N-1} x[n] \cos \frac{2\pi(2n+1+N)(2k+1)}{8N} \quad 0 \leq k < N$$

$$\text{IMDCT: } y[n] = \frac{1}{N} \sum_{k=0}^{N-1} X[k] \cos \frac{2\pi(2n+1+N)(2k+1)}{8N} \quad 0 \leq n < 2N$$

In vector notation: $\mathbf{X} = \mathbf{M}\mathbf{x}$ and $\mathbf{y} = \frac{1}{N}\mathbf{M}^T\mathbf{X} = \frac{1}{N}\mathbf{M}^T\mathbf{M}\mathbf{x}$

The rows of \mathbf{M} form the MDCT basis elements.

3: Discrete Cosine Transform

- DFT Problems
- DCT +
- Basis Functions
- DCT of sine wave
- DCT Properties
- Energy Conservation
- Energy Compaction
- Frame-based coding
- Lapped Transform +
- MDCT (Modified DCT)
- **MDCT Basis Elements**
- Summary
- MATLAB routines

MDCT Basis Elements

$$\text{MDCT: } X[k] = \sum_{n=0}^{2N-1} x[n] \cos \frac{2\pi(2n+1+N)(2k+1)}{8N} \quad 0 \leq k < N$$

$$\text{IMDCT: } y[n] = \frac{1}{N} \sum_{k=0}^{N-1} X[k] \cos \frac{2\pi(2n+1+N)(2k+1)}{8N} \quad 0 \leq n < 2N$$

$$\text{In vector notation: } \mathbf{X} = \mathbf{M}\mathbf{x} \text{ and } \mathbf{y} = \frac{1}{N}\mathbf{M}^T\mathbf{X} = \frac{1}{N}\mathbf{M}^T\mathbf{M}\mathbf{x}$$

The rows of \mathbf{M} form the MDCT basis elements.

Example ($N = 4$):

$$\mathbf{M} = \begin{bmatrix} 0.56 & 0.20 & -0.20 & -0.56 & -0.83 & -0.98 & -0.98 & -0.83 \\ -0.98 & -0.56 & 0.56 & 0.98 & 0.20 & -0.83 & -0.83 & 0.20 \\ 0.20 & 0.83 & -0.83 & -0.20 & 0.98 & -0.56 & -0.56 & 0.98 \\ 0.83 & -0.98 & 0.98 & -0.83 & 0.56 & -0.20 & -0.20 & 0.56 \end{bmatrix}$$

3: Discrete Cosine Transform

- DFT Problems
- DCT
- Basis Functions
- DCT of sine wave
- DCT Properties
- Energy Conservation
- Energy Compaction
- Frame-based coding
- Lapped Transform
- MDCT (Modified DCT)
- MDCT Basis Elements
- Summary
- MATLAB routines

MDCT Basis Elements

$$\text{MDCT: } X[k] = \sum_{n=0}^{2N-1} x[n] \cos \frac{2\pi(2n+1+N)(2k+1)}{8N} \quad 0 \leq k < N$$

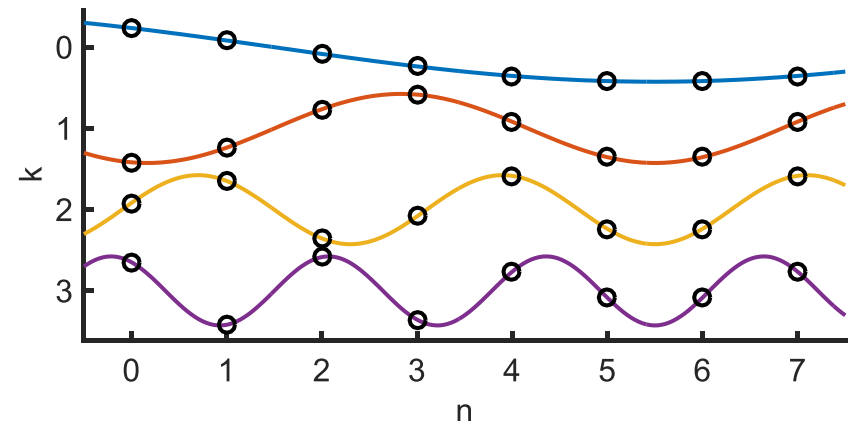
$$\text{IMDCT: } y[n] = \frac{1}{N} \sum_{k=0}^{N-1} X[k] \cos \frac{2\pi(2n+1+N)(2k+1)}{8N} \quad 0 \leq n < 2N$$

In vector notation: $\mathbf{X} = \mathbf{M}\mathbf{x}$ and $\mathbf{y} = \frac{1}{N}\mathbf{M}^T\mathbf{X} = \frac{1}{N}\mathbf{M}^T\mathbf{M}\mathbf{x}$

The rows of \mathbf{M} form the MDCT basis elements.

Example ($N = 4$):

$$\mathbf{M} = \begin{bmatrix} 0.56 & 0.20 & -0.20 & -0.56 & -0.83 & -0.98 & -0.98 & -0.83 \\ -0.98 & -0.56 & 0.56 & 0.98 & 0.20 & -0.83 & -0.83 & 0.20 \\ 0.20 & 0.83 & -0.83 & -0.20 & 0.98 & -0.56 & -0.56 & 0.98 \\ 0.83 & -0.98 & 0.98 & -0.83 & 0.56 & -0.20 & -0.20 & 0.56 \end{bmatrix}$$



3: Discrete Cosine Transform

- DFT Problems
- DCT
- Basis Functions
- DCT of sine wave
- DCT Properties
- Energy Conservation
- Energy Compaction
- Frame-based coding
- Lapped Transform
- MDCT (Modified DCT)
- MDCT Basis Elements
- Summary
- MATLAB routines

MDCT Basis Elements

$$\text{MDCT: } X[k] = \sum_{n=0}^{2N-1} x[n] \cos \frac{2\pi(2n+1+N)(2k+1)}{8N} \quad 0 \leq k < N$$

$$\text{IMDCT: } y[n] = \frac{1}{N} \sum_{k=0}^{N-1} X[k] \cos \frac{2\pi(2n+1+N)(2k+1)}{8N} \quad 0 \leq n < 2N$$

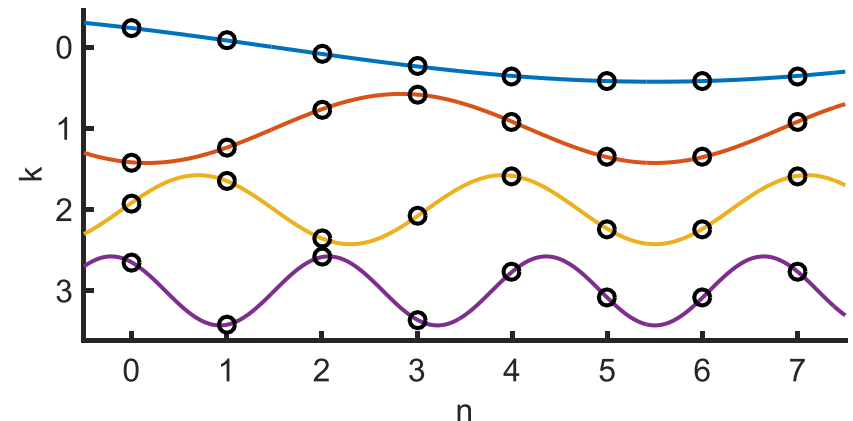
In vector notation: $\mathbf{X} = \mathbf{M}\mathbf{x}$ and $\mathbf{y} = \frac{1}{N}\mathbf{M}^T\mathbf{X} = \frac{1}{N}\mathbf{M}^T\mathbf{M}\mathbf{x}$

The rows of \mathbf{M} form the MDCT basis elements.

Example ($N = 4$):

$$\mathbf{M} = \begin{bmatrix} 0.56 & 0.20 & -0.20 & -0.56 & -0.83 & -0.98 & -0.98 & -0.83 \\ -0.98 & -0.56 & 0.56 & 0.98 & 0.20 & -0.83 & -0.83 & 0.20 \\ 0.20 & 0.83 & -0.83 & -0.20 & 0.98 & -0.56 & -0.56 & 0.98 \\ 0.83 & -0.98 & 0.98 & -0.83 & 0.56 & -0.20 & -0.20 & 0.56 \end{bmatrix}$$

The basis frequencies are $\{0.5, 1.5, 2.5, 3.5\}$ times the fundamental.



Summary

3: Discrete Cosine Transform

- DFT Problems
- DCT +
- Basis Functions
- DCT of sine wave
- DCT Properties
- Energy Conservation
- Energy Compaction
- Frame-based coding
- Lapped Transform +
- MDCT (Modified DCT)
- MDCT Basis Elements
- Summary
- MATLAB routines

DCT: Discrete Cosine Transform

- Equivalent to a DFT of time-shifted double-length $\left[\begin{array}{c} \mathbf{x} \\ \overleftarrow{\mathbf{x}} \end{array} \right]$

Summary

3: Discrete Cosine Transform

- DFT Problems
- DCT +
- Basis Functions
- DCT of sine wave
- DCT Properties
- Energy Conservation
- Energy Compaction
- Frame-based coding
- Lapped Transform +
- MDCT (Modified DCT)
- MDCT Basis Elements
- Summary
- MATLAB routines

DCT: Discrete Cosine Transform

- Equivalent to a DFT of time-shifted double-length $\left[\begin{matrix} \mathbf{x} & \overleftarrow{\mathbf{x}} \end{matrix} \right]$
- Often scaled to make an orthogonal transform (ODCT)

Summary

3: Discrete Cosine Transform

- DFT Problems
- DCT +
- Basis Functions
- DCT of sine wave
- DCT Properties
- Energy Conservation
- Energy Compaction
- Frame-based coding
- Lapped Transform +
- MDCT (Modified DCT)
- MDCT Basis Elements
- **Summary**
- MATLAB routines

DCT: Discrete Cosine Transform

- Equivalent to a DFT of time-shifted double-length $\left[\begin{matrix} \mathbf{x} & \overleftarrow{\mathbf{x}} \end{matrix} \right]$
- Often scaled to make an orthogonal transform (ODCT)
- Better than DFT for energy compaction and decorrelation 😊

Summary

3: Discrete Cosine Transform

- DFT Problems
- DCT +
- Basis Functions
- DCT of sine wave
- DCT Properties
- Energy Conservation
- Energy Compaction
- Frame-based coding
- Lapped Transform +
- MDCT (Modified DCT)
- MDCT Basis Elements
- Summary
- MATLAB routines

DCT: Discrete Cosine Transform

- Equivalent to a DFT of time-shifted double-length $\left[\begin{matrix} \mathbf{x} & \overleftarrow{\mathbf{x}} \end{matrix} \right]$
- Often scaled to make an orthogonal transform (ODCT)
- Better than DFT for energy compaction and decorrelation 😊
 - **Energy Compaction:** Most energy is in only a few coefficients

Summary

3: Discrete Cosine Transform

- DFT Problems
- DCT +
- Basis Functions
- DCT of sine wave
- DCT Properties
- Energy Conservation
- Energy Compaction
- Frame-based coding
- Lapped Transform +
- MDCT (Modified DCT)
- MDCT Basis Elements
- **Summary**
- MATLAB routines

DCT: Discrete Cosine Transform

- Equivalent to a DFT of time-shifted double-length $\left[\begin{matrix} \mathbf{x} & \overleftarrow{\mathbf{x}} \end{matrix} \right]$
- Often scaled to make an orthogonal transform (ODCT)
- Better than DFT for energy compaction and decorrelation 😊
 - **Energy Compaction:** Most energy is in only a few coefficients
 - **Decorrelation:** The coefficients are uncorrelated with each other

Summary

3: Discrete Cosine Transform

- DFT Problems
- DCT +
- Basis Functions
- DCT of sine wave
- DCT Properties
- Energy Conservation
- Energy Compaction
- Frame-based coding
- Lapped Transform +
- MDCT (Modified DCT)
- MDCT Basis Elements
- Summary
- MATLAB routines

DCT: Discrete Cosine Transform

- Equivalent to a DFT of time-shifted double-length $\left[\begin{matrix} \mathbf{x} & \overleftarrow{\mathbf{x}} \end{matrix} \right]$
- Often scaled to make an orthogonal transform (ODCT)
- Better than DFT for energy compaction and decorrelation 😊
 - **Energy Compaction:** Most energy is in only a few coefficients
 - **Decorrelation:** The coefficients are uncorrelated with each other
- Nice convolution property of DFT is lost 😞

3: Discrete Cosine Transform

- DFT Problems
- DCT +
- Basis Functions
- DCT of sine wave
- DCT Properties
- Energy Conservation
- Energy Compaction
- Frame-based coding
- Lapped Transform +
- MDCT (Modified DCT)
- MDCT Basis Elements
- **Summary**
- MATLAB routines

Summary

DCT: Discrete Cosine Transform

- Equivalent to a DFT of time-shifted double-length $\left[\begin{matrix} \mathbf{x} & \overleftarrow{\mathbf{x}} \end{matrix} \right]$
- Often scaled to make an orthogonal transform (ODCT)
- Better than DFT for energy compaction and decorrelation 😊
 - **Energy Compaction:** Most energy is in only a few coefficients
 - **Decorrelation:** The coefficients are uncorrelated with each other
- Nice convolution property of DFT is lost 😞

MDCT: Modified Discrete Cosine Transform

- **Lapped transform:** $2N \rightarrow N \rightarrow 2N$

3: Discrete Cosine Transform

- DFT Problems
- DCT +
- Basis Functions
- DCT of sine wave
- DCT Properties
- Energy Conservation
- Energy Compaction
- Frame-based coding
- Lapped Transform +
- MDCT (Modified DCT)
- MDCT Basis Elements
- **Summary**
- MATLAB routines

Summary

DCT: Discrete Cosine Transform

- Equivalent to a DFT of time-shifted double-length $\begin{bmatrix} \mathbf{x} & \overleftarrow{\mathbf{x}} \end{bmatrix}$
- Often scaled to make an orthogonal transform (ODCT)
- Better than DFT for energy compaction and decorrelation 😊
 - **Energy Compaction:** Most energy is in only a few coefficients
 - **Decorrelation:** The coefficients are uncorrelated with each other
- Nice convolution property of DFT is lost 😞

MDCT: Modified Discrete Cosine Transform

- **Lapped transform:** $2N \rightarrow N \rightarrow 2N$
- Aliasing errors cancel out when overlapping output frames are added

3: Discrete Cosine Transform

- DFT Problems
- DCT +
- Basis Functions
- DCT of sine wave
- DCT Properties
- Energy Conservation
- Energy Compaction
- Frame-based coding
- Lapped Transform +
- MDCT (Modified DCT)
- MDCT Basis Elements
- **Summary**
- MATLAB routines

Summary

DCT: Discrete Cosine Transform

- Equivalent to a DFT of time-shifted double-length $\left[\begin{matrix} \mathbf{x} & \overleftarrow{\mathbf{x}} \end{matrix} \right]$
- Often scaled to make an orthogonal transform (ODCT)
- Better than DFT for energy compaction and decorrelation 😊
 - **Energy Compaction:** Most energy is in only a few coefficients
 - **Decorrelation:** The coefficients are uncorrelated with each other
- Nice convolution property of DFT is lost 😞

MDCT: Modified Discrete Cosine Transform

- **Lapped transform:** $2N \rightarrow N \rightarrow 2N$
- Aliasing errors cancel out when overlapping output frames are added
- Similar to DCT for energy compaction and decorrelation 😊

3: Discrete Cosine Transform

- DFT Problems
- DCT +
- Basis Functions
- DCT of sine wave
- DCT Properties
- Energy Conservation
- Energy Compaction
- Frame-based coding
- Lapped Transform +
- MDCT (Modified DCT)
- MDCT Basis Elements
- **Summary**
- MATLAB routines

Summary

DCT: Discrete Cosine Transform

- Equivalent to a DFT of time-shifted double-length $\left[\begin{matrix} \mathbf{x} & \overleftarrow{\mathbf{x}} \end{matrix} \right]$
- Often scaled to make an orthogonal transform (ODCT)
- Better than DFT for energy compaction and decorrelation 😊
 - **Energy Compaction:** Most energy is in only a few coefficients
 - **Decorrelation:** The coefficients are uncorrelated with each other
- Nice convolution property of DFT is lost 😞

MDCT: Modified Discrete Cosine Transform

- **Lapped transform:** $2N \rightarrow N \rightarrow 2N$
- Aliasing errors cancel out when overlapping output frames are added
- Similar to DCT for energy compaction and decorrelation 😊
- Overlapping windowed frames can avoid edge discontinuities 😊

3: Discrete Cosine Transform

- DFT Problems
- DCT +
- Basis Functions
- DCT of sine wave
- DCT Properties
- Energy Conservation
- Energy Compaction
- Frame-based coding
- Lapped Transform +
- MDCT (Modified DCT)
- MDCT Basis Elements
- **Summary**
- MATLAB routines

Summary

DCT: Discrete Cosine Transform

- Equivalent to a DFT of time-shifted double-length $\left[\begin{matrix} \mathbf{x} & \overleftarrow{\mathbf{x}} \end{matrix} \right]$
- Often scaled to make an orthogonal transform (ODCT)
- Better than DFT for energy compaction and decorrelation 😊
 - **Energy Compaction:** Most energy is in only a few coefficients
 - **Decorrelation:** The coefficients are uncorrelated with each other
- Nice convolution property of DFT is lost 😞

MDCT: Modified Discrete Cosine Transform

- **Lapped transform:** $2N \rightarrow N \rightarrow 2N$
- Aliasing errors cancel out when overlapping output frames are added
- Similar to DCT for energy compaction and decorrelation 😊
- Overlapping windowed frames can avoid edge discontinuities 😊
- Used in audio coding: MP3, WMA, AC-3, AAC, Vorbis, ATRAC

3: Discrete Cosine Transform

- DFT Problems
- DCT +
- Basis Functions
- DCT of sine wave
- DCT Properties
- Energy Conservation
- Energy Compaction
- Frame-based coding
- Lapped Transform +
- MDCT (Modified DCT)
- MDCT Basis Elements
- **Summary**
- MATLAB routines

Summary

DCT: Discrete Cosine Transform

- Equivalent to a DFT of time-shifted double-length $\left[\begin{matrix} \mathbf{x} & \overleftarrow{\mathbf{x}} \end{matrix} \right]$
- Often scaled to make an orthogonal transform (ODCT)
- Better than DFT for energy compaction and decorrelation 😊
 - **Energy Compaction:** Most energy is in only a few coefficients
 - **Decorrelation:** The coefficients are uncorrelated with each other
- Nice convolution property of DFT is lost 😞

MDCT: Modified Discrete Cosine Transform

- **Lapped transform:** $2N \rightarrow N \rightarrow 2N$
- Aliasing errors cancel out when overlapping output frames are added
- Similar to DCT for energy compaction and decorrelation 😊
- Overlapping windowed frames can avoid edge discontinuities 😊
- Used in audio coding: MP3, WMA, AC-3, AAC, Vorbis, ATRAC

For further details see Mitra: 5.

MATLAB routines

3: Discrete Cosine Transform

- DFT Problems
- DCT +
- Basis Functions
- DCT of sine wave
- DCT Properties
- Energy Conservation
- Energy Compaction
- Frame-based coding
- Lapped Transform +
- MDCT (Modified DCT)
- MDCT Basis Elements
- Summary
- **MATLAB routines**

dct, idct

ODCT with optional zero-padding