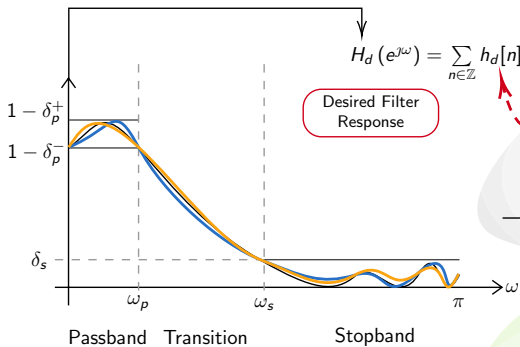


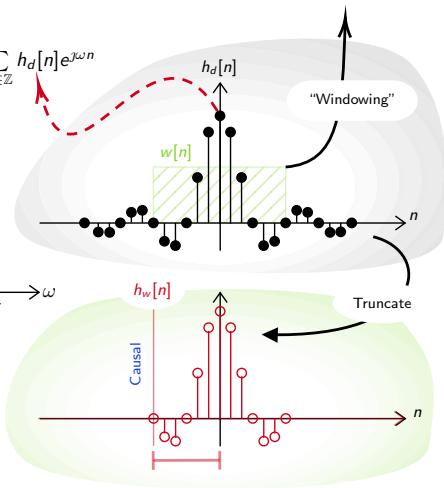
## 6: Window Filter Design

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- Rectangular window
- Dirichlet Kernel +
- Window relationships
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# 6: Window Filter Design



$$h_w[n] = h_d[n] w[n] \Leftrightarrow H_w(e^{j\omega}) = H_d(e^{j\omega}) *_{2\pi} W(e^{j\omega})$$



# Inverse DTFT

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For any BIBO stable filter,  $H(e^{j\omega})$  is the DTFT of  $h[n]$

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# Inverse DTFT

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## Inverse DTFT

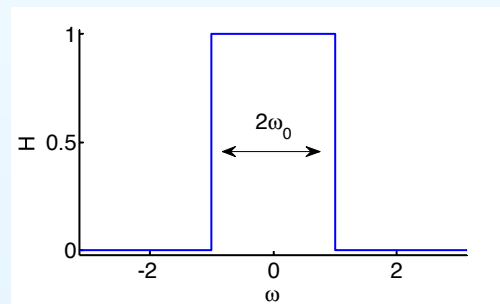
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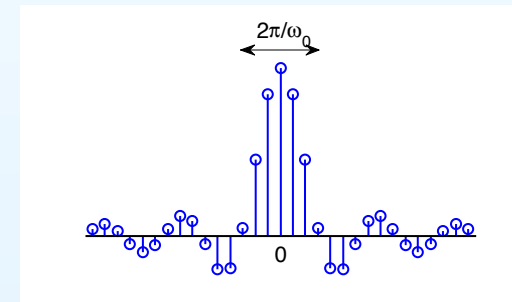
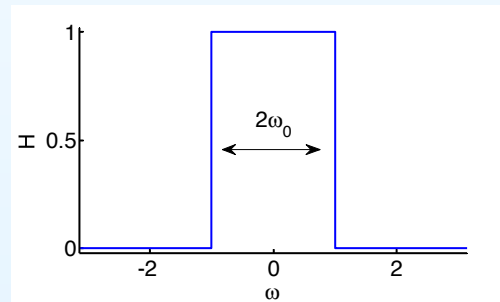
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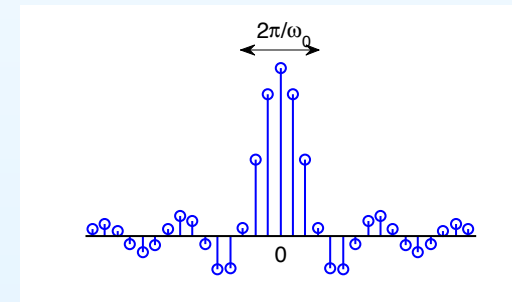
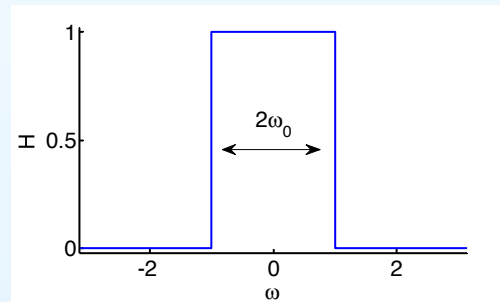
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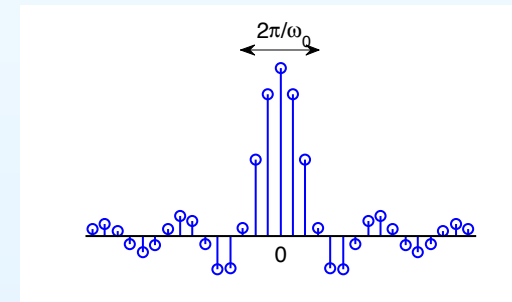
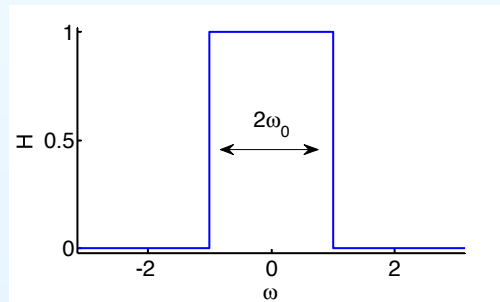
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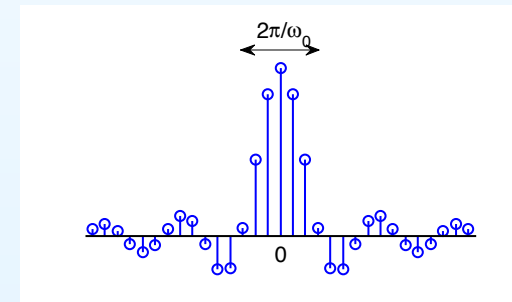
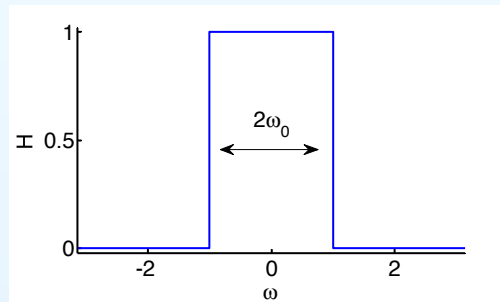
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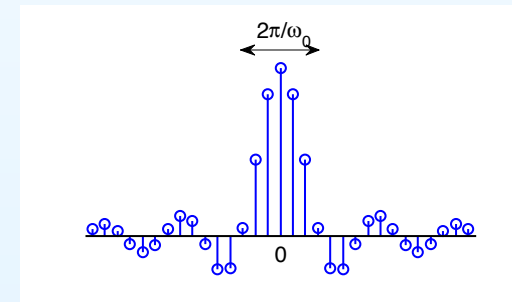
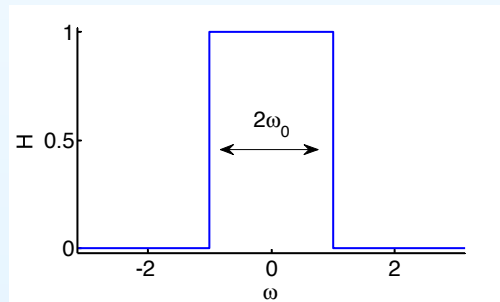
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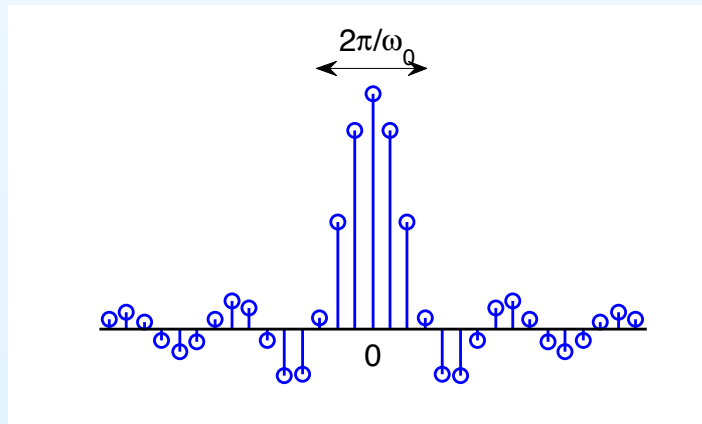
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 Sadly  $h[n]$  is **infinite** and **non-causal**. **Solution:** multiply  $h[n]$  by a window

# Rectangular window

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Truncate to  $\pm \frac{M}{2}$  to make finite

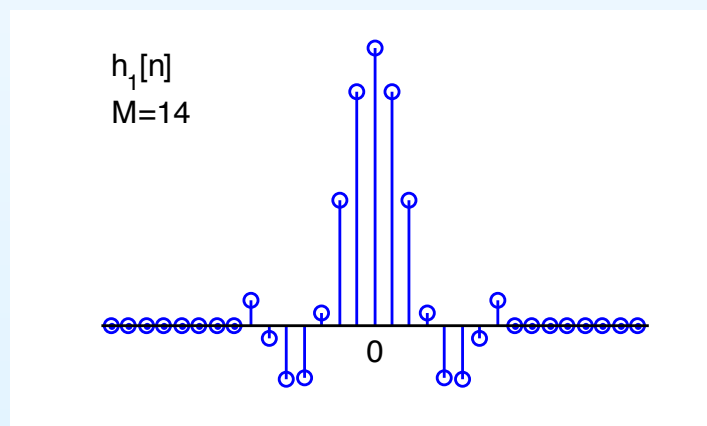


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Truncate to  $\pm \frac{M}{2}$  to make finite;  $h_1[n]$  is now of length  $M + 1$



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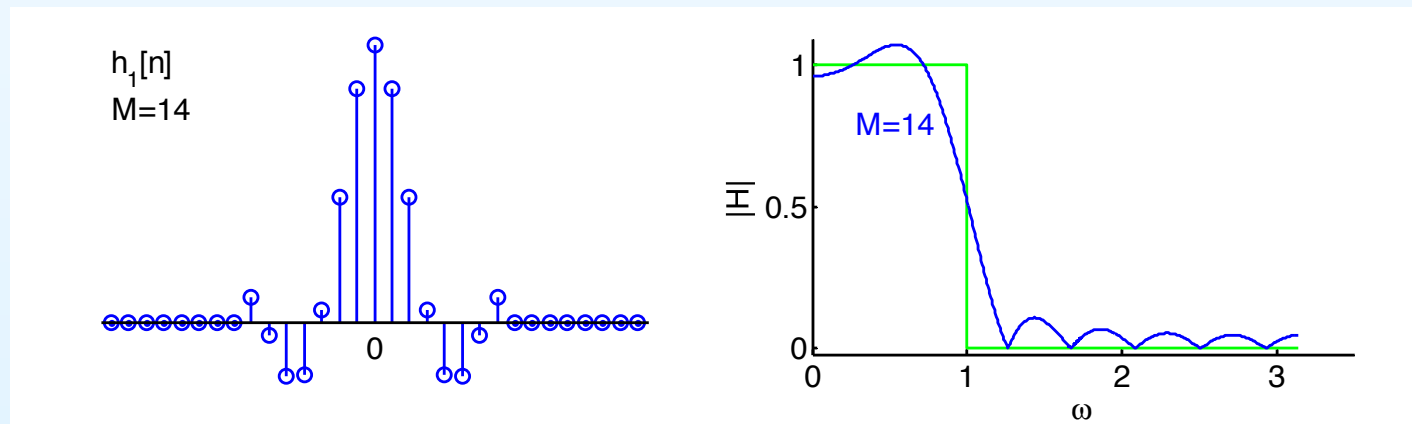
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Define mean square error (MSE) in frequency domain

$$E = \frac{1}{2\pi} \int_{-\pi}^{\pi} |H(e^{j\omega}) - H_1(e^{j\omega})|^2 d\omega$$



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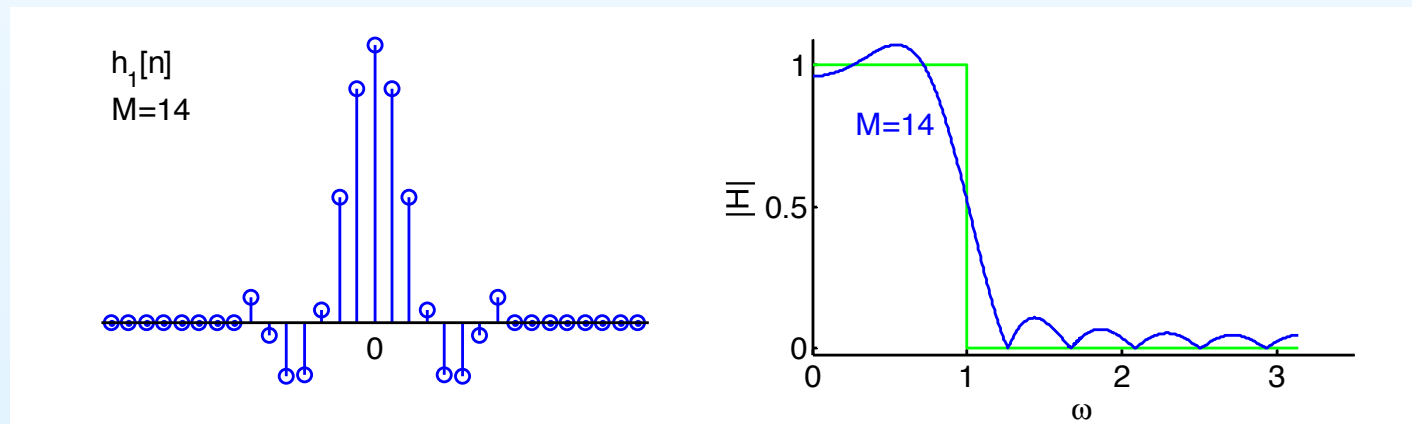
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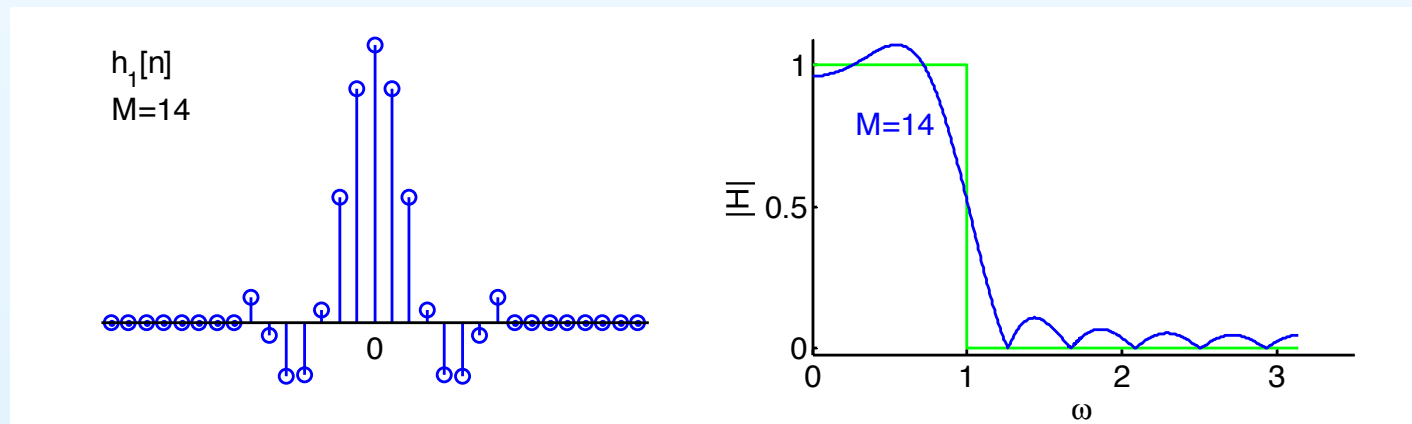
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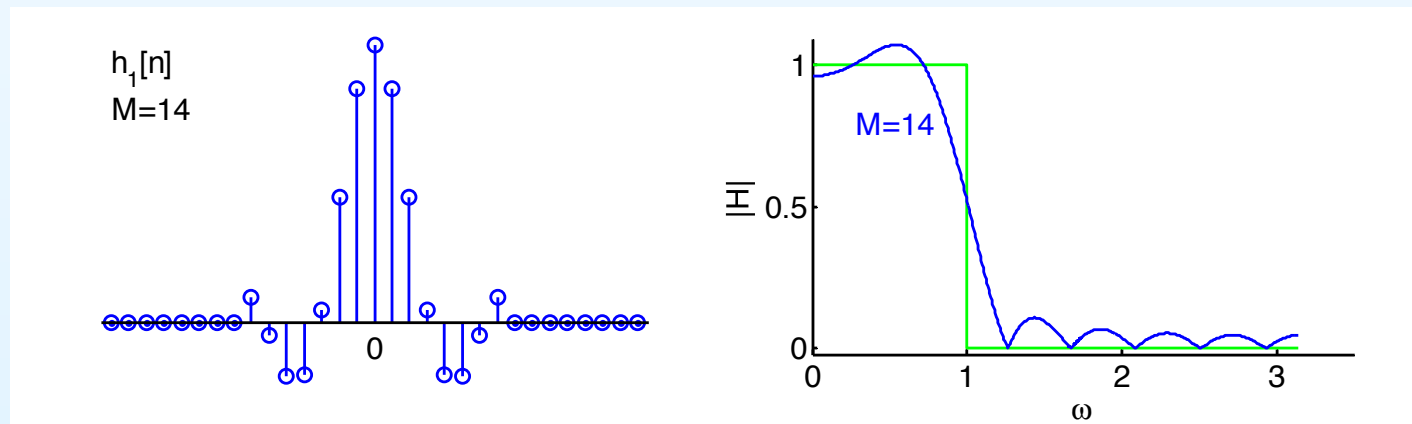
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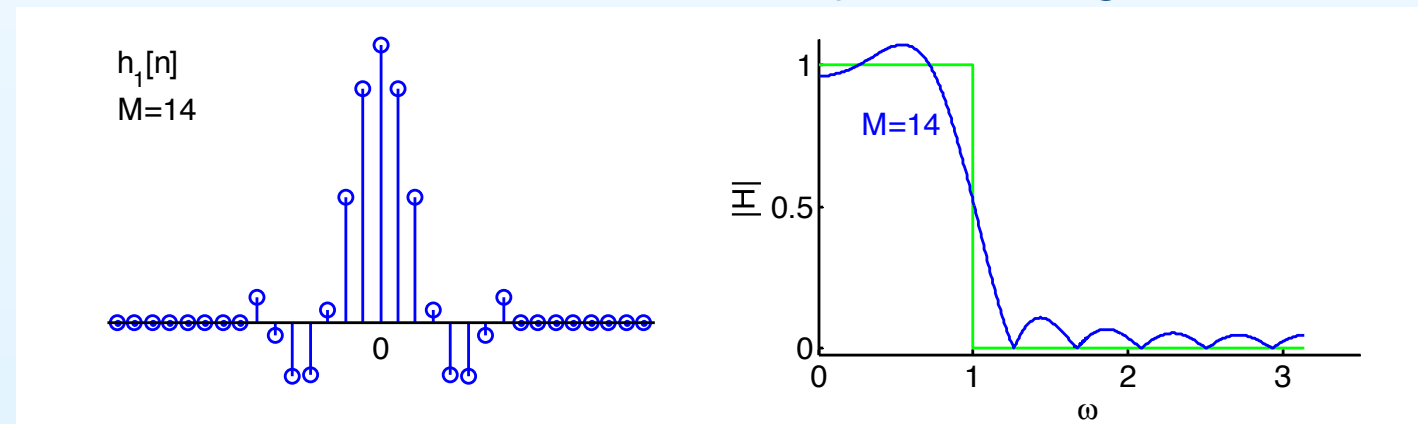
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**However:** 9% overshoot at a discontinuity even for large  $n$ .



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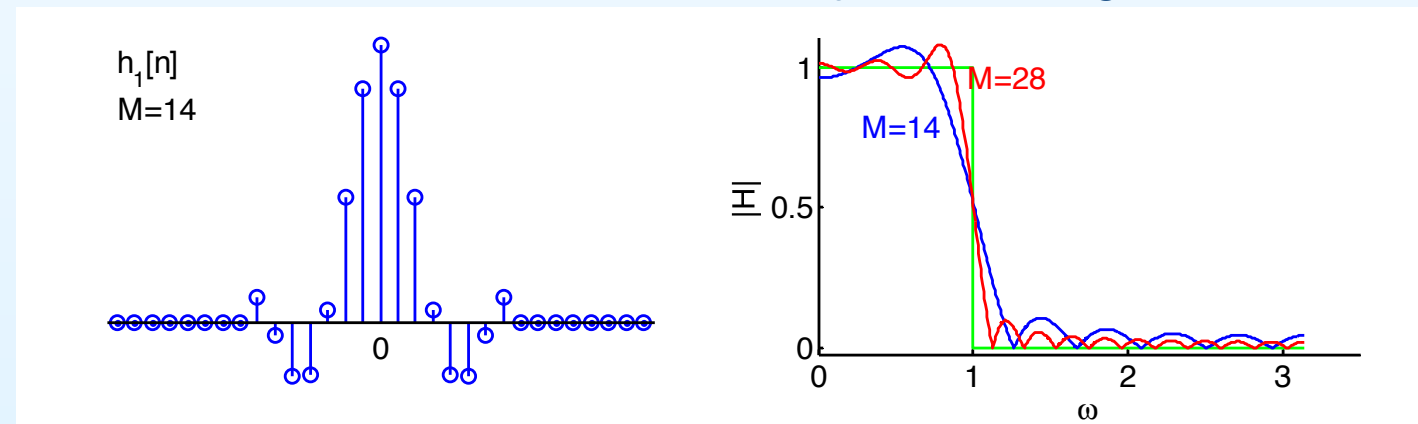
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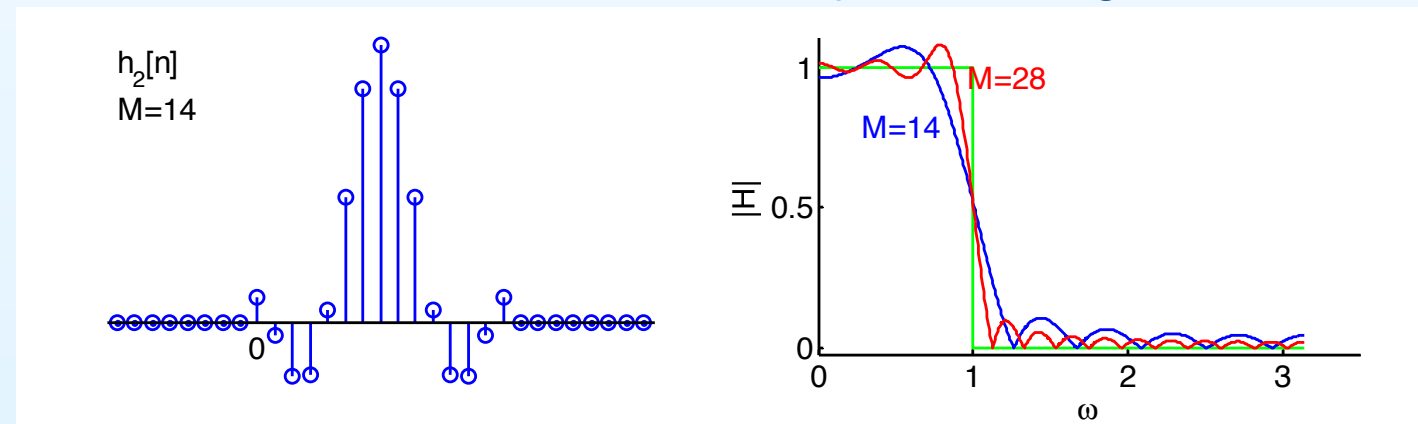
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Normal to delay by  $\frac{M}{2}$  to make causal. Multiplies  $H(e^{j\omega})$  by  $e^{-j\frac{M}{2}\omega}$ .

## Dirichlet Kernel

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Truncation  $\Leftrightarrow$  Multiply  $h[n]$  by a rectangular window,  $w[n] = \delta_{-\frac{M}{2} \leq n \leq \frac{M}{2}}$

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**Proof:** (i)  $e^{-j\omega(-n)} + e^{-j\omega(+n)} = 2 \cos(n\omega)$

## Dirichlet Kernel

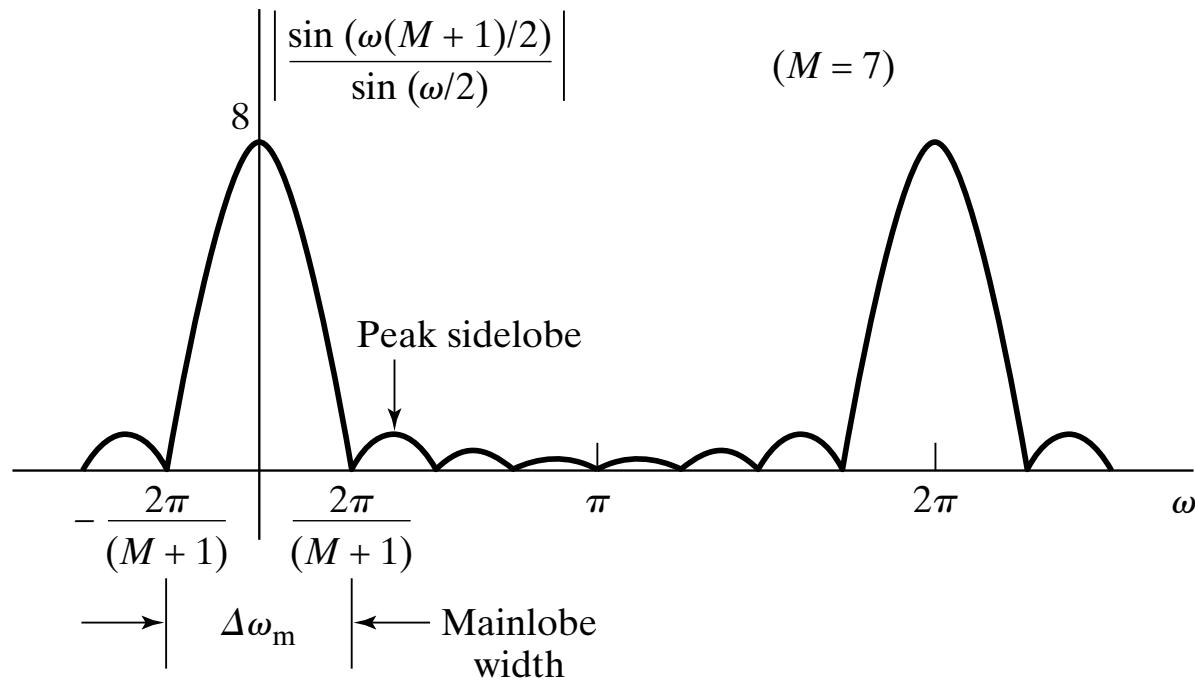
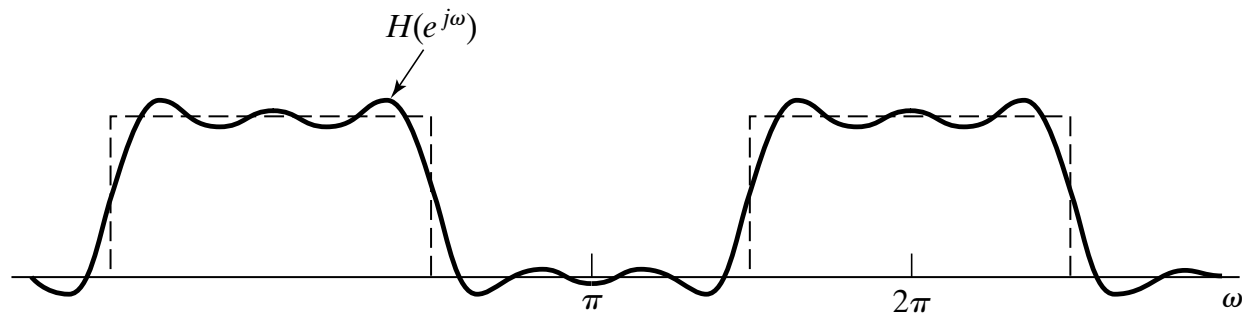
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## Dirichlet Kernel

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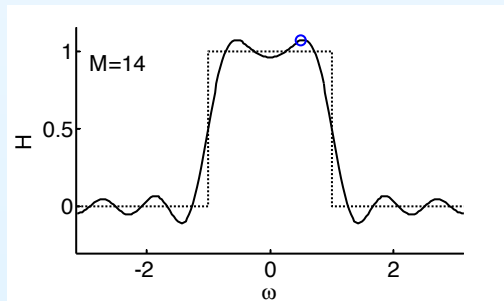
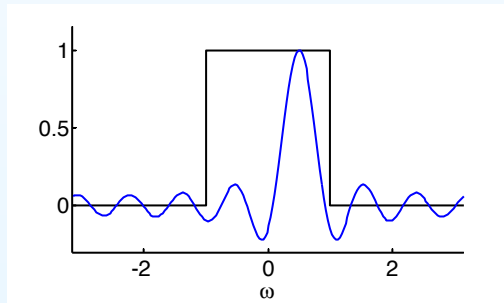
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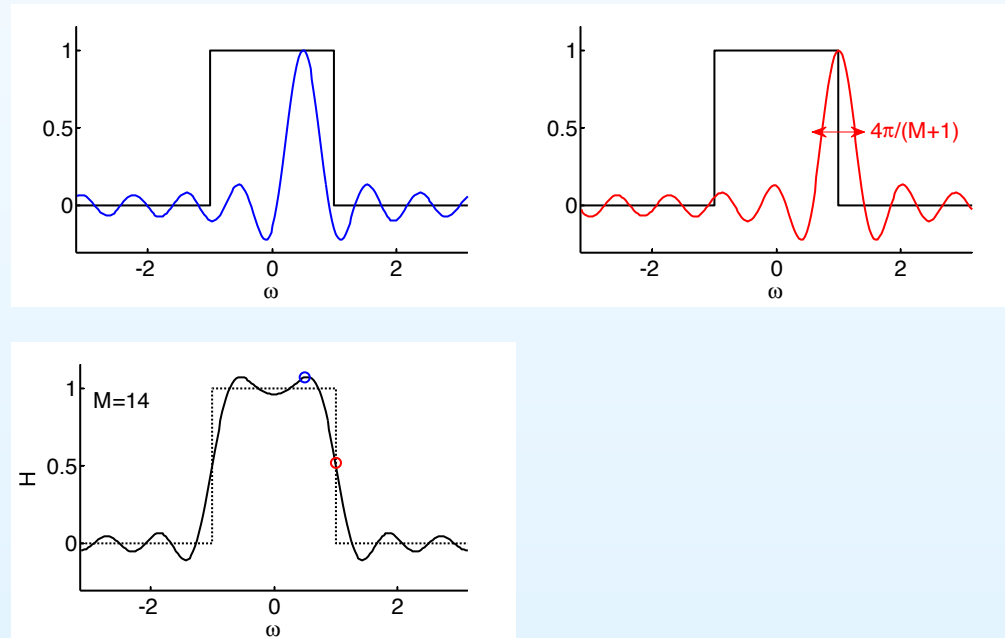
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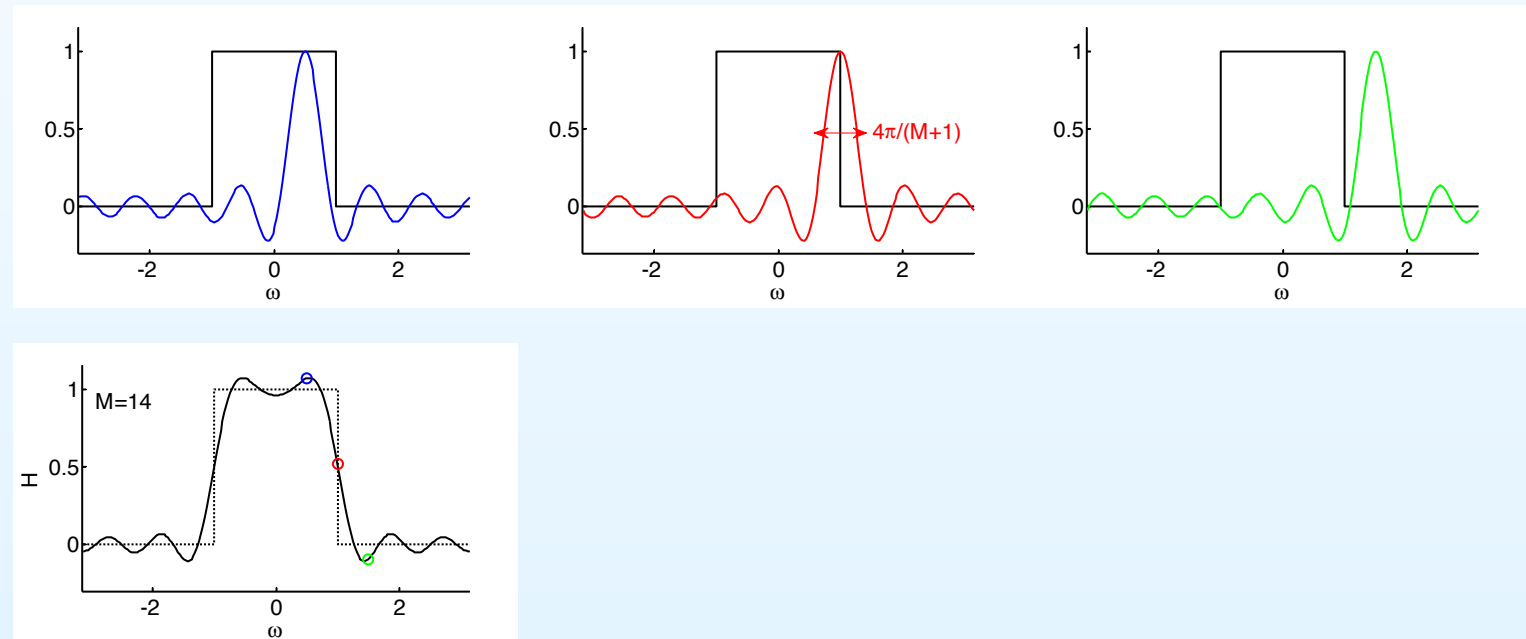
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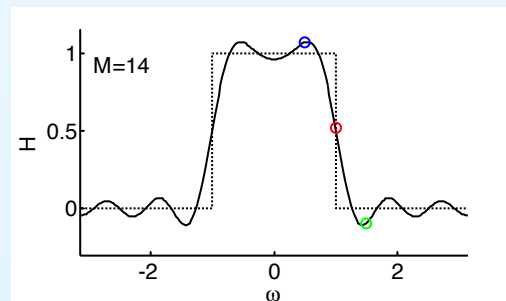
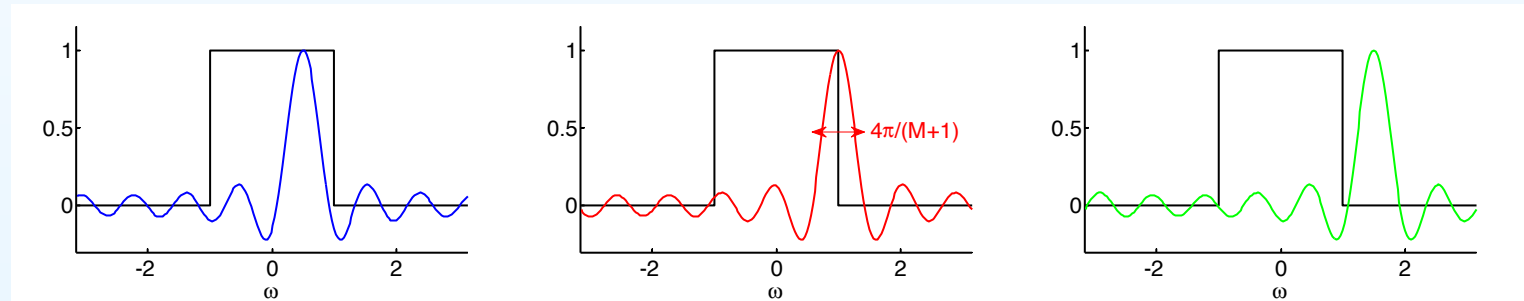
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# Dirichlet Kernel

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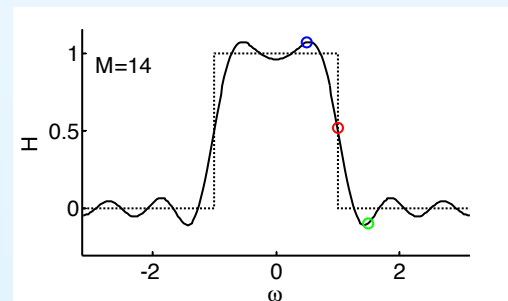
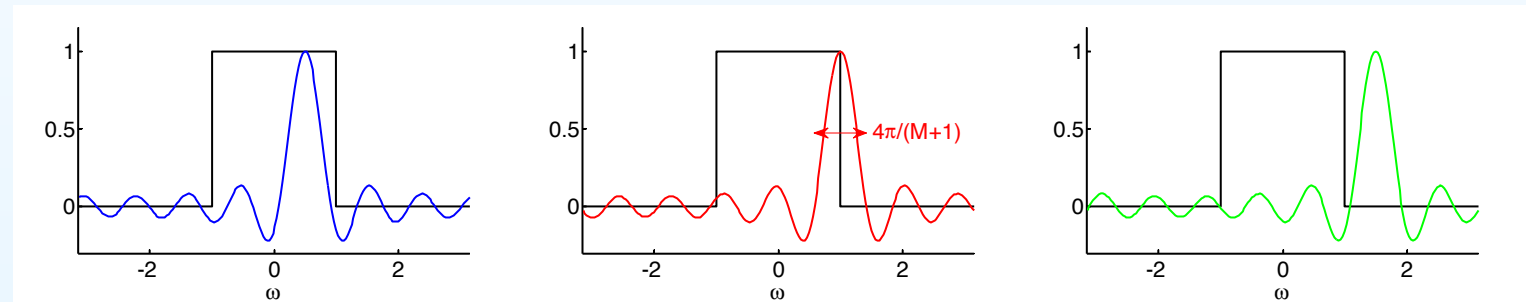
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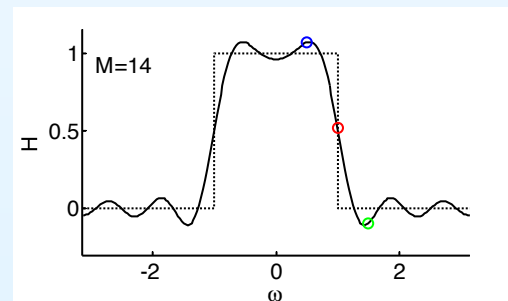
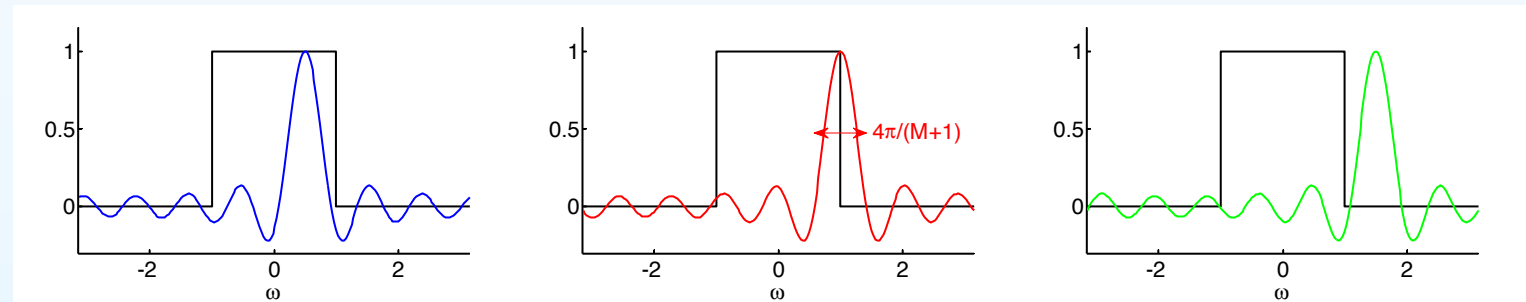
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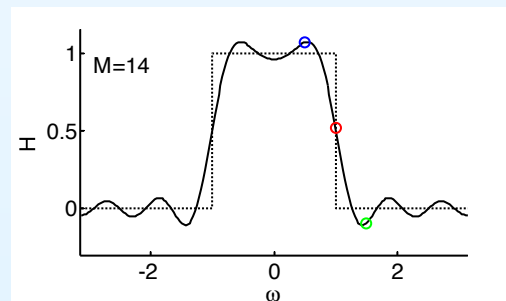
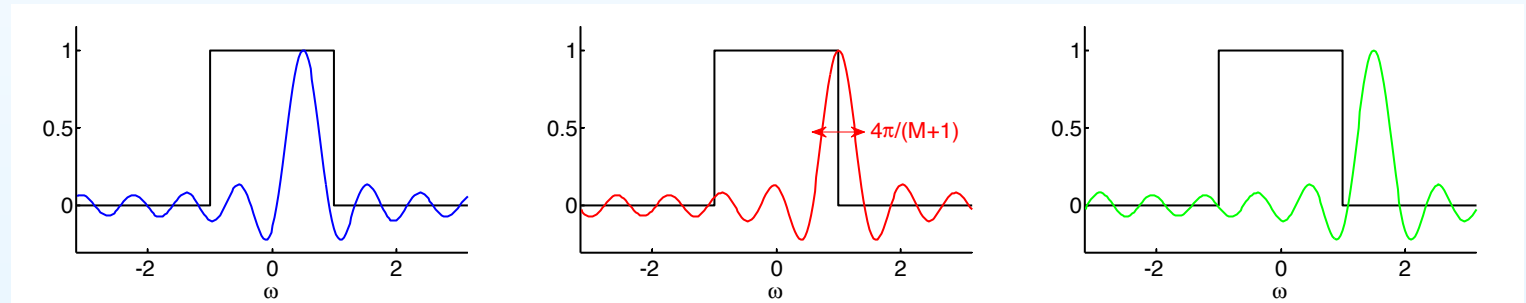
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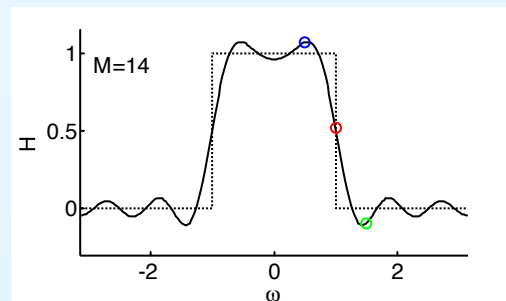
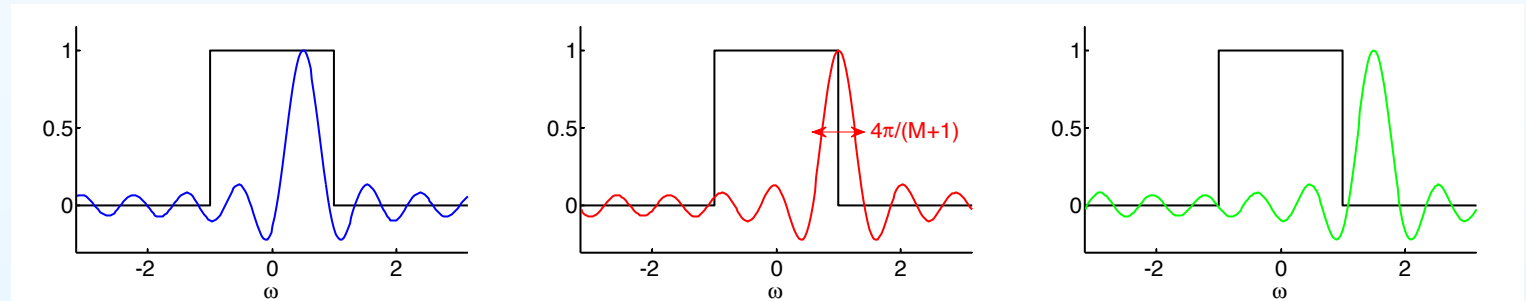
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Transition Gradient:  $\left. \frac{d|H|}{d\omega} \right|_{\omega=\omega_0} \approx \frac{M+1}{2\pi}$

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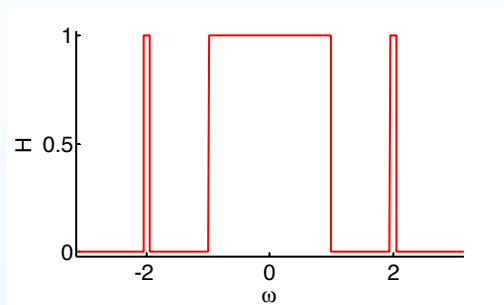
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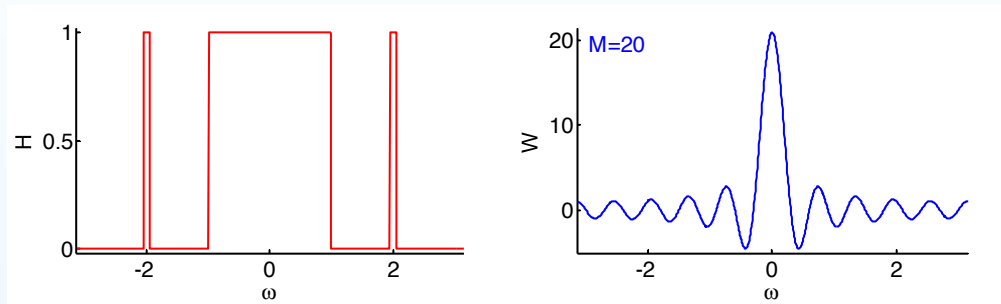
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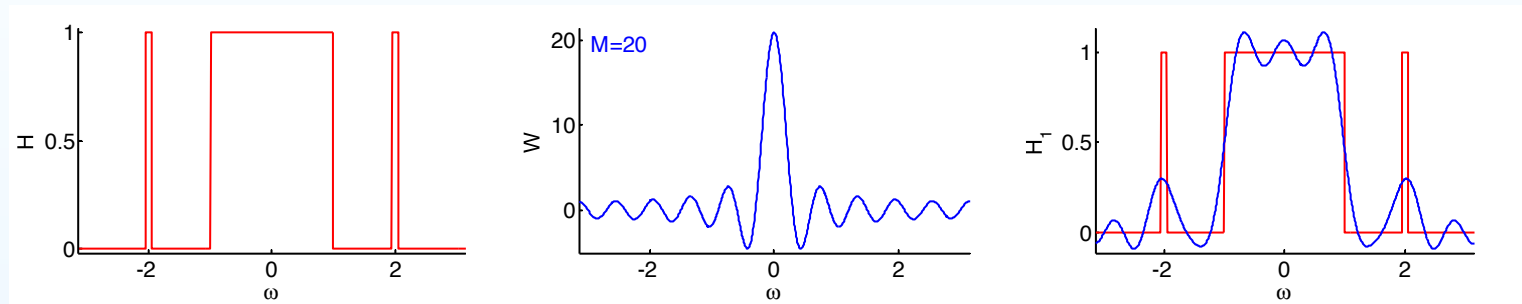
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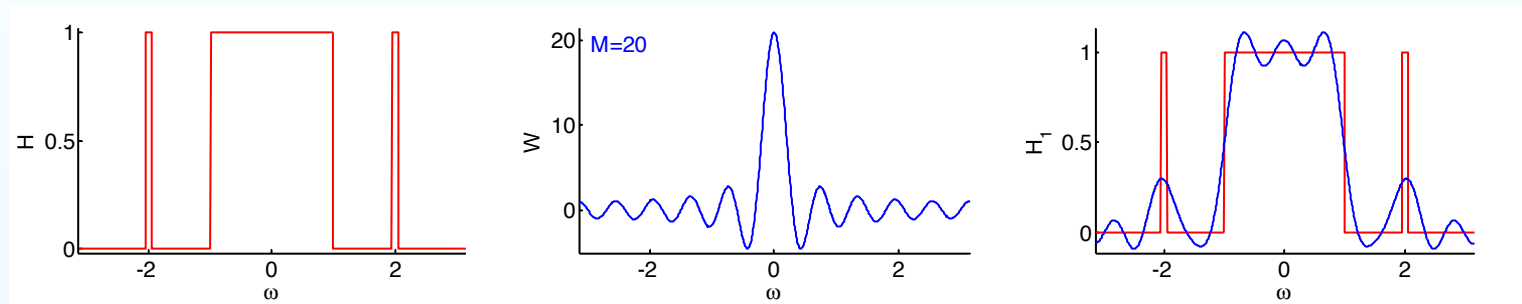
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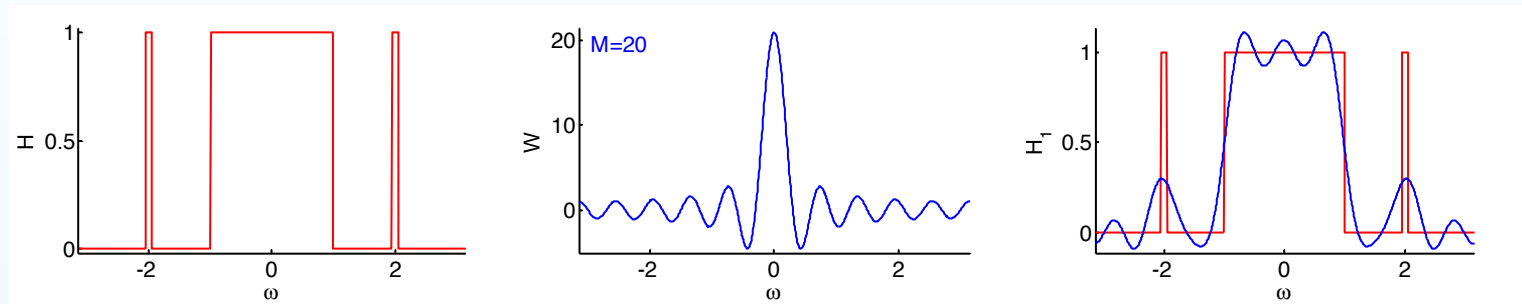
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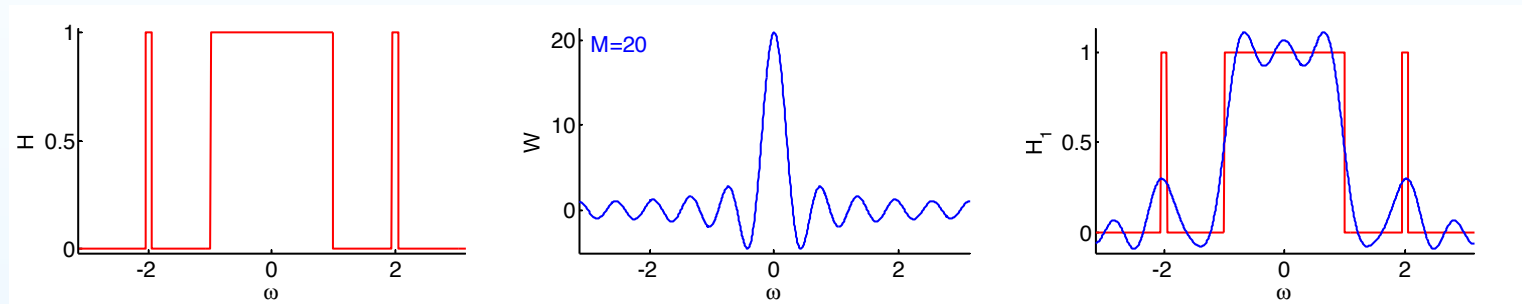
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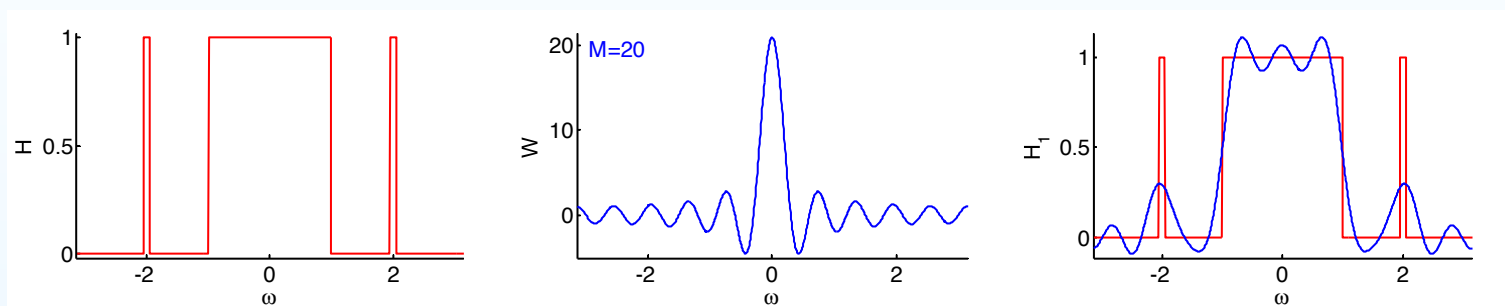
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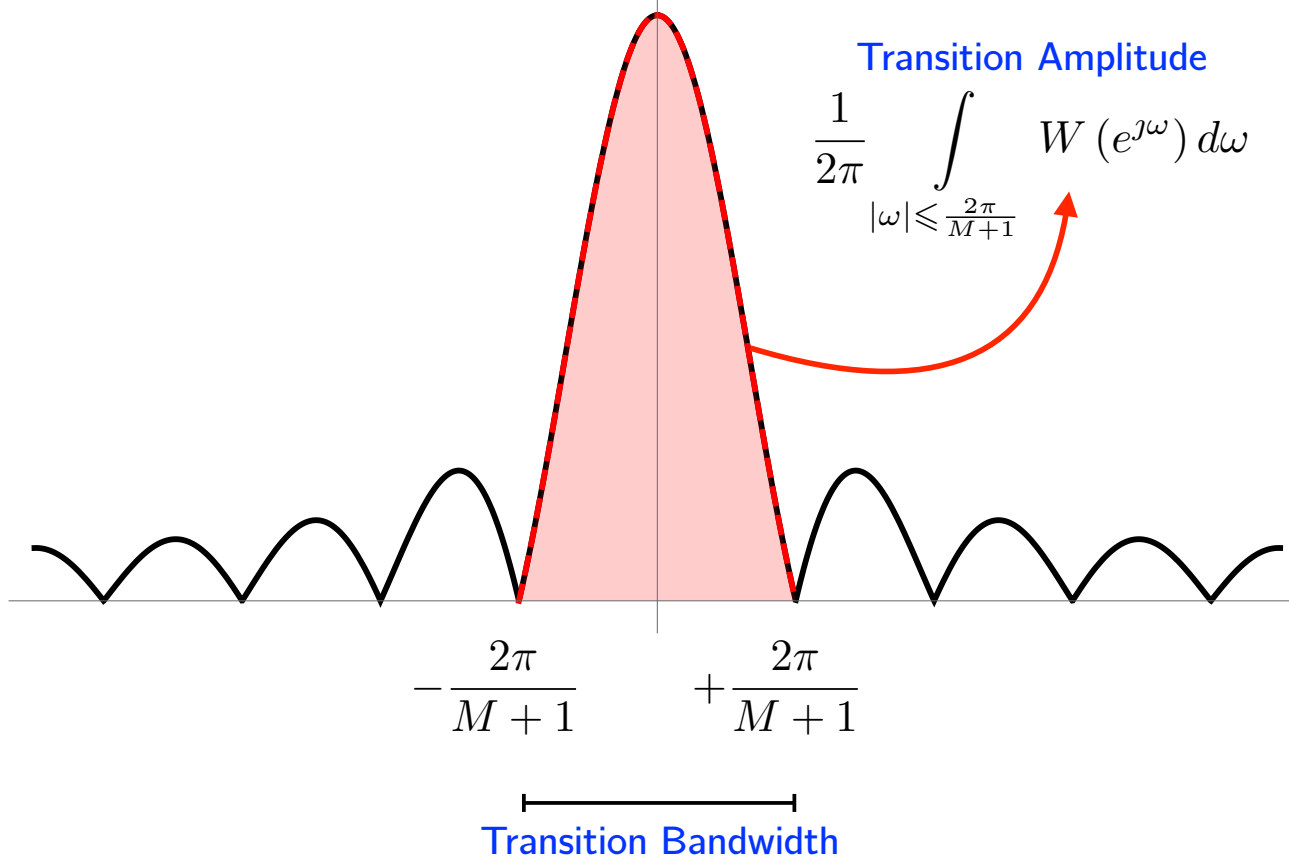
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Type of Window	Peak Side-Lobe Amplitude (Relative)	Approximate Width of Main Lobe	Peak Approximation Error, $20 \log_{10} \delta$ (dB)	Equivalent Kaiser Window, $\beta$	Transition Width of Equivalent Kaiser Window
Rectangular	-13	$4\pi/(M+1)$	-21	0	$1.81\pi/M$
Bartlett	-25	$8\pi/M$	-25	1.33	$2.37\pi/M$
Hann	-31	$8\pi/M$	-44	3.86	$5.01\pi/M$
Hamming	-41	$8\pi/M$	-53	4.86	$6.27\pi/M$
Blackman	-57	$12\pi/M$	-74	7.04	$9.19\pi/M$

$$\left| \frac{\sin(\omega(M+1)/2)}{\sin(\omega/2)} \right|$$

Transition Amplitude

$$\frac{1}{2\pi} \int_{|\omega| \leq \frac{2\pi}{M+1}} W(e^{j\omega}) d\omega$$



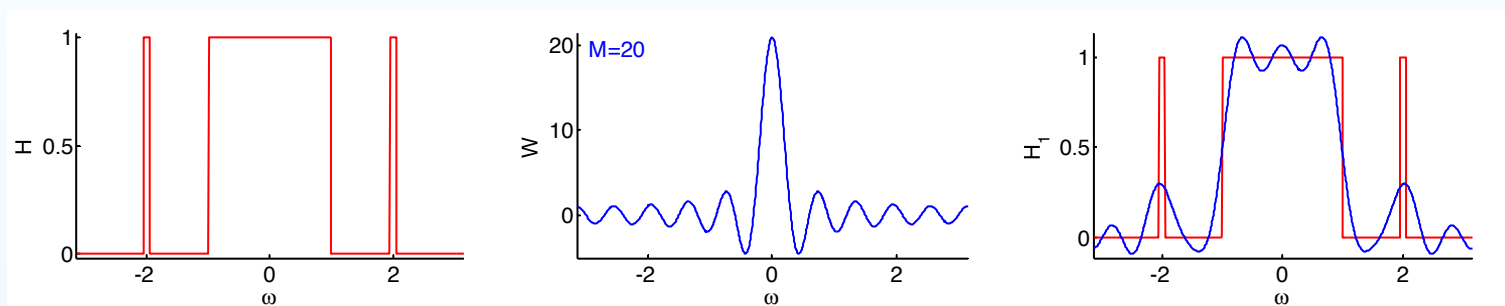
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(c) stopband gain is an integral over oscillating sidelobes of  $W(e^{j\omega})$



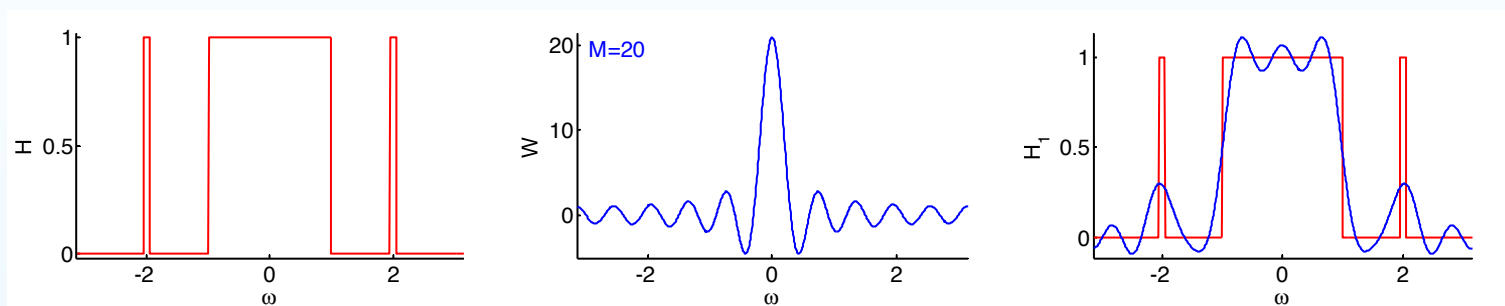
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- Rectangular window
- Dirichlet Kernel
- Window relationships
- Common Windows
- Order Estimation
- Example Design
- Frequency sampling
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- MATLAB routines

When you multiply an impulse response by a window  $M + 1$  long

$$H_{M+1}(e^{j\omega}) = \frac{1}{2\pi} H(e^{j\omega}) \circledast W(e^{j\omega})$$



(a) passband gain  $\approx w[0]$ ;  $\text{peak} \approx \frac{w[0]}{2} + \frac{0.5}{2\pi} \int_{\text{mainlobe}} W(e^{j\omega}) d\omega$   
 rectangular window: passband gain = 1; peak gain = 1.09

(b) transition bandwidth,  $\Delta\omega$  = width of the main lobe  
 transition amplitude,  $\Delta H$  = integral of main lobe  $\div 2\pi$   
 rectangular window:  $\Delta\omega = \frac{4\pi}{M+1}$ ,  $\Delta H \approx 1.18$

(c) stopband gain is an integral over oscillating sidelobes of  $W(e^{j\omega})$   
 rect window:  $|\min H(e^{j\omega})| = 0.09 \ll |\min W(e^{j\omega})| = \frac{M+1}{1.5\pi}$

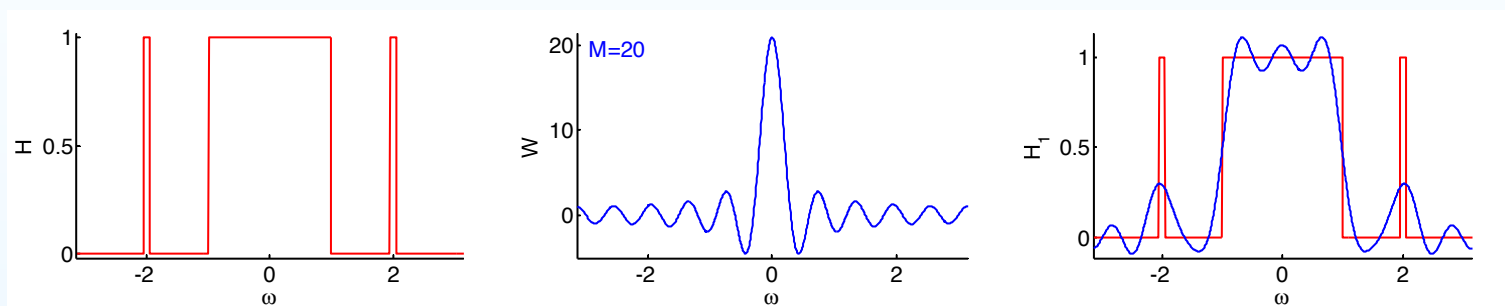
# Window relationships

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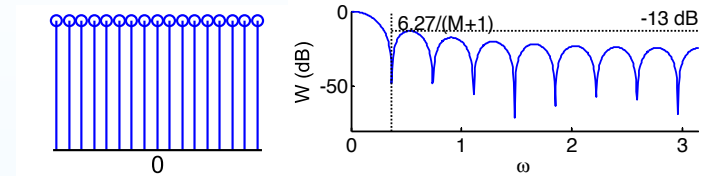
(d) features narrower than the main lobe will be broadened and attenuated

# Common Windows

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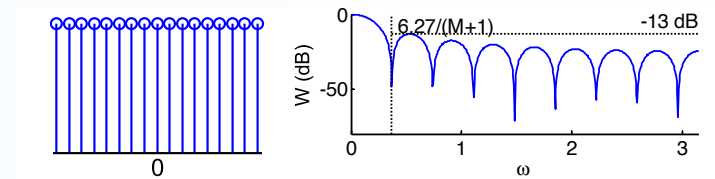


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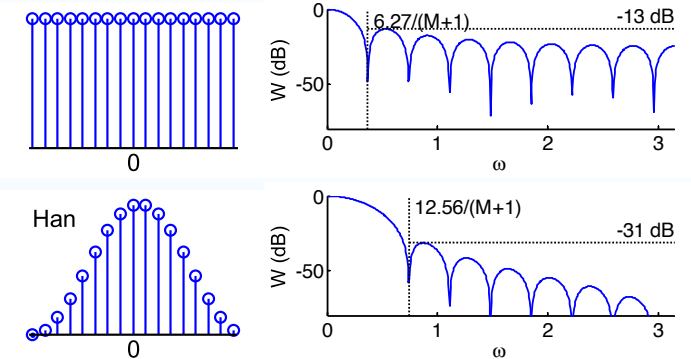
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Hanning:  $0.5 + 0.5c_1$   
 $c_k = \cos \frac{2\pi kn}{M+1}$



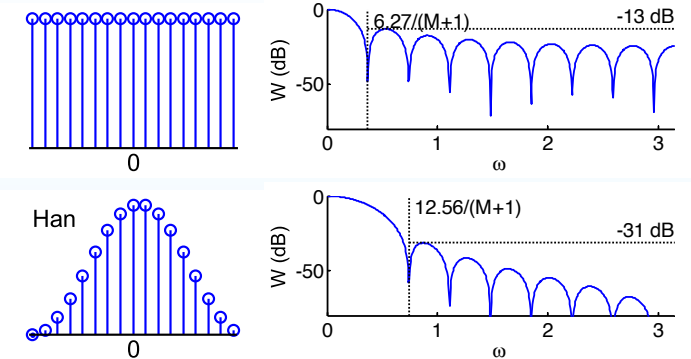
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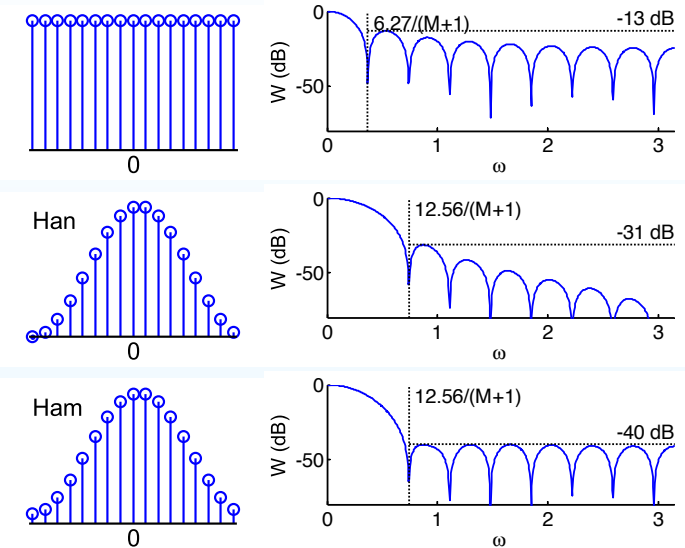
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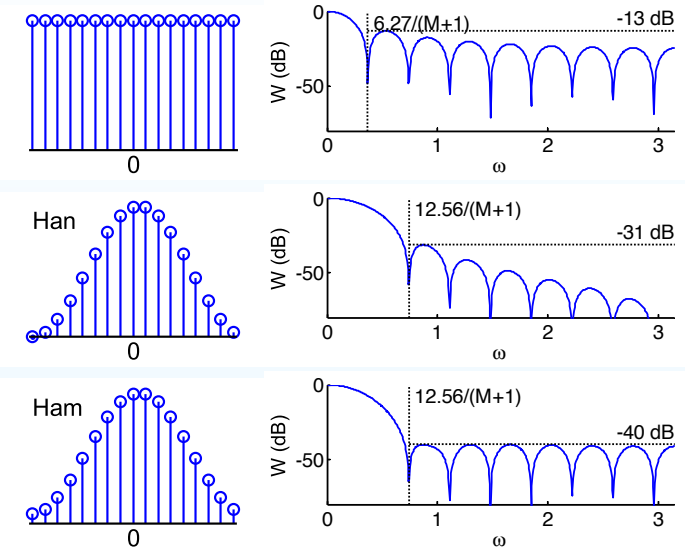
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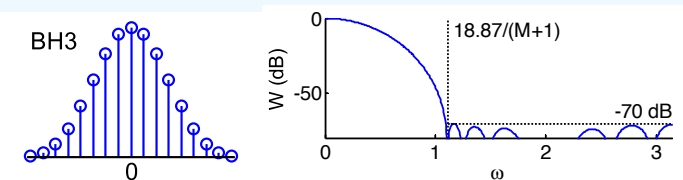
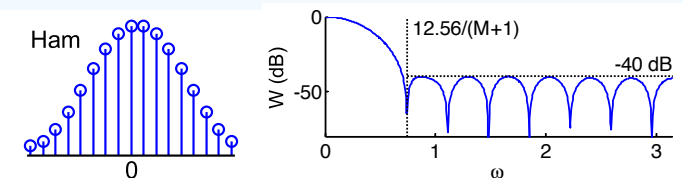
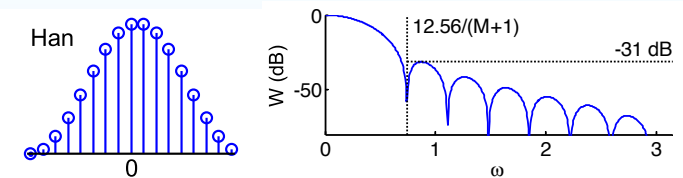
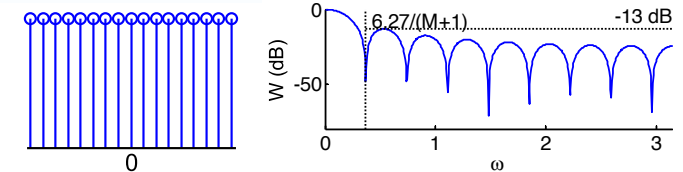
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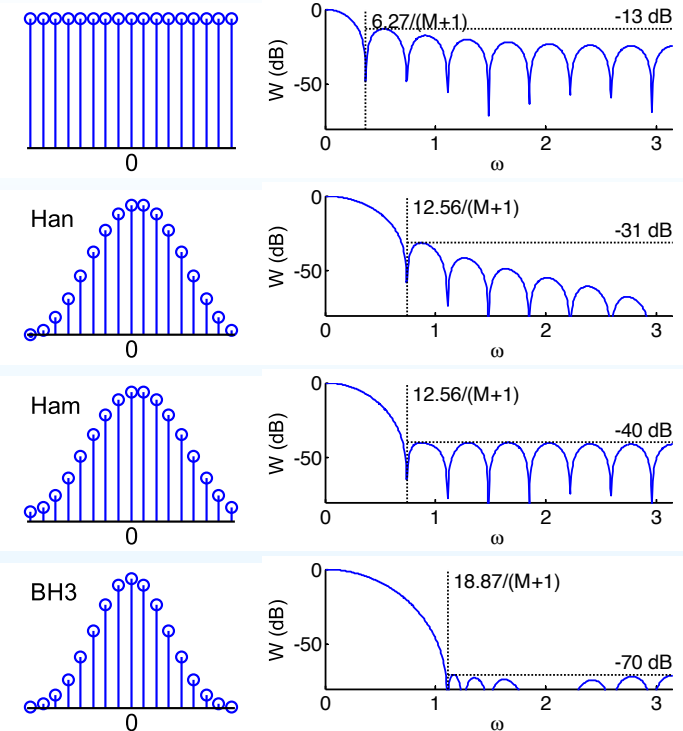
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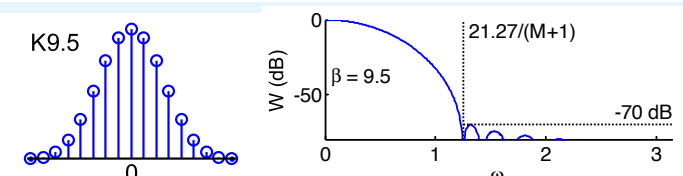
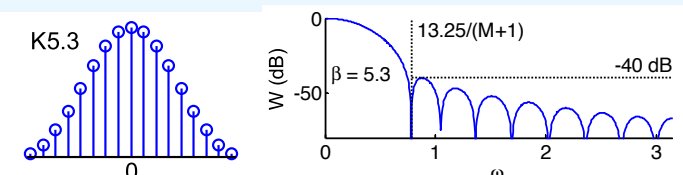
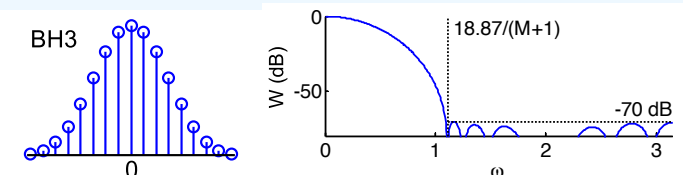
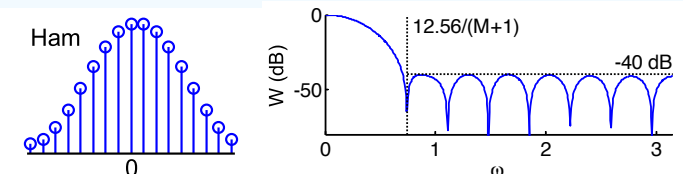
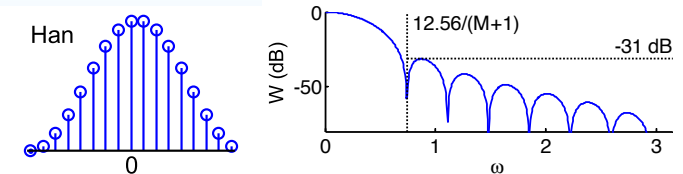
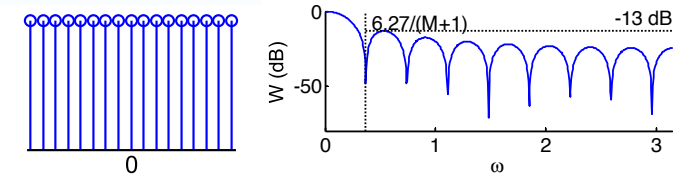
Blackman-Harris 3-term:

$$0.42 + 0.5c_1 + 0.08c_2$$

best peak sidelobe

Kaiser: 
$$\frac{I_0\left(\beta\sqrt{1-\left(\frac{2n}{M}\right)^2}\right)}{I_0(\beta)}$$

$\beta$  controls width v sidelobes



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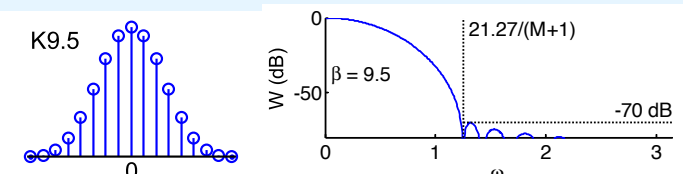
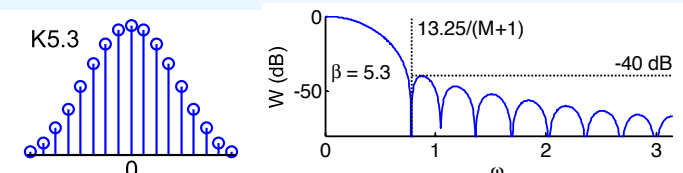
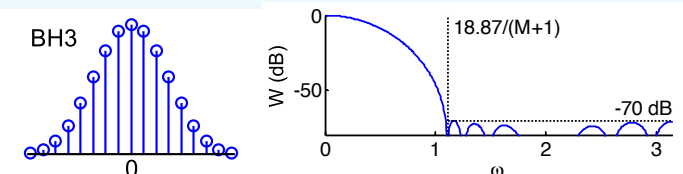
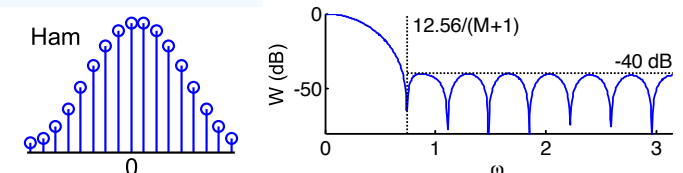
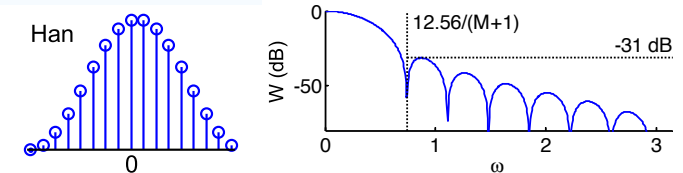
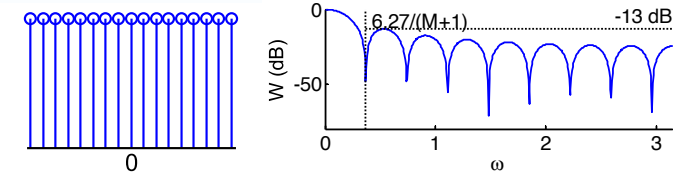
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$\beta$  controls width v sidelobes

Good compromise:

Width v sidelobe v decay



# Order Estimation

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Several formulae estimate the required order of a filter,  $M$ .

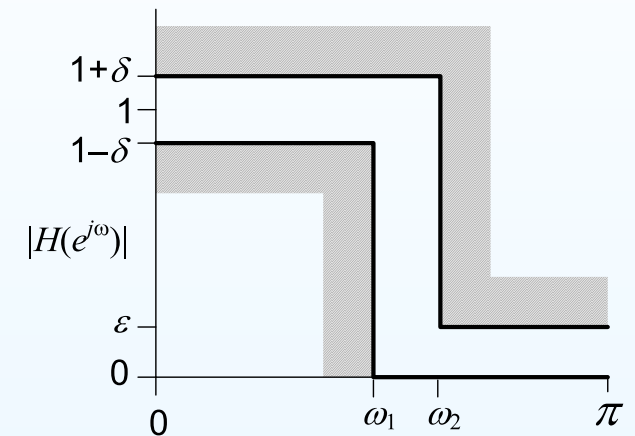
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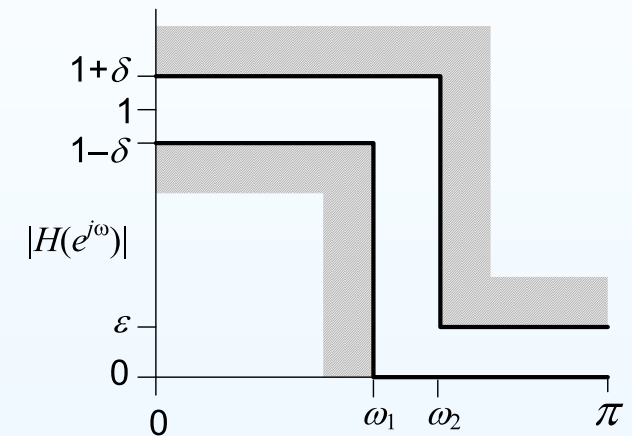
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Estimated order is

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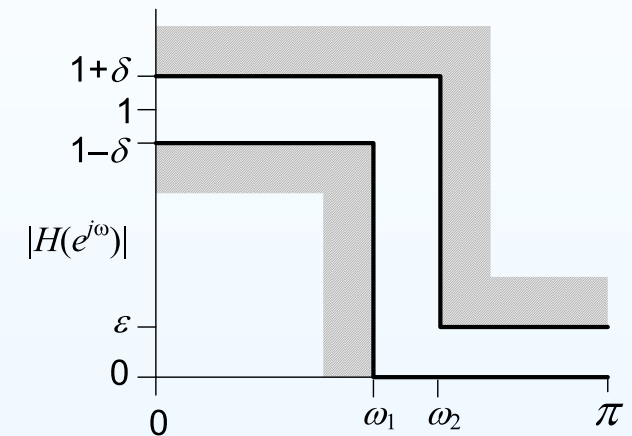
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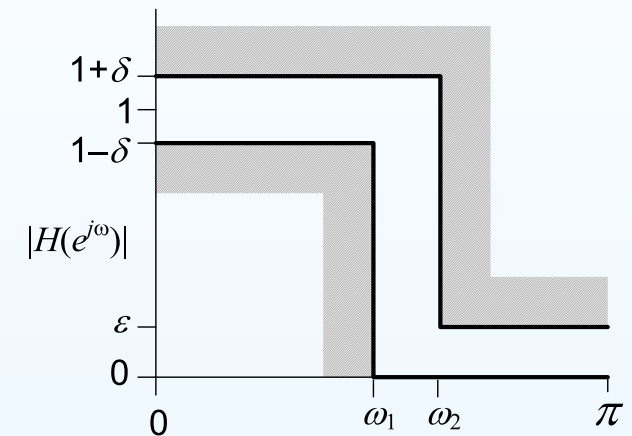
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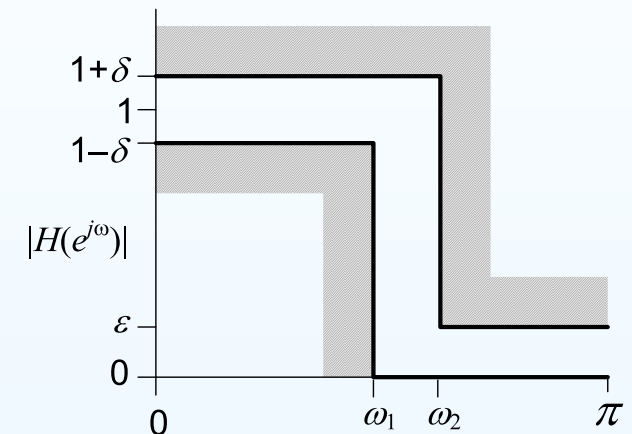
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Transition band:  $f_1 = 1.8$  kHz,  $f_2 = 2.0$  kHz,  $f_s = 12$  kHz,.

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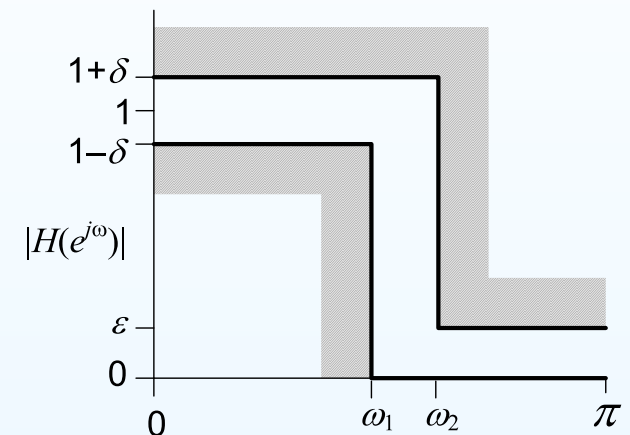
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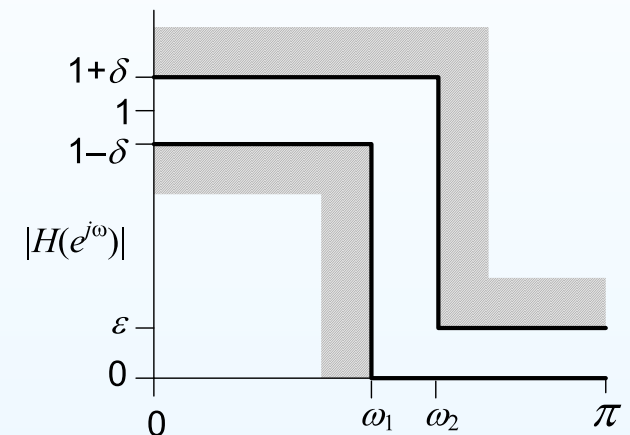
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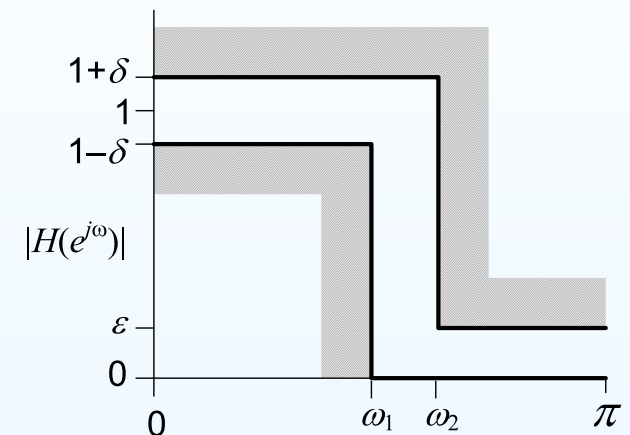
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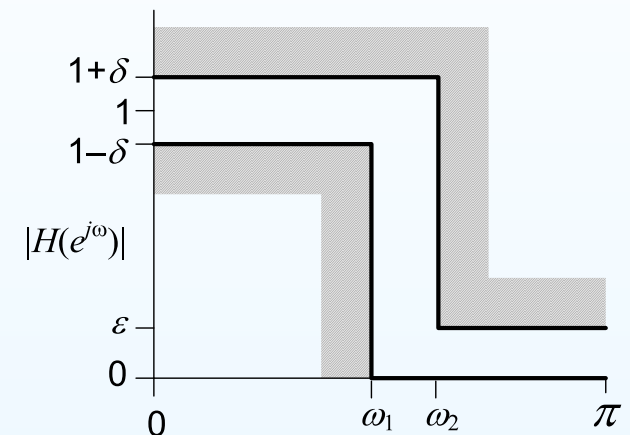
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$$M \approx \frac{-5.6 - 4.3 \log_{10}(2 \times 10^{-4})}{1.047 - 0.943} = \frac{10.25}{0.105} = 98$$

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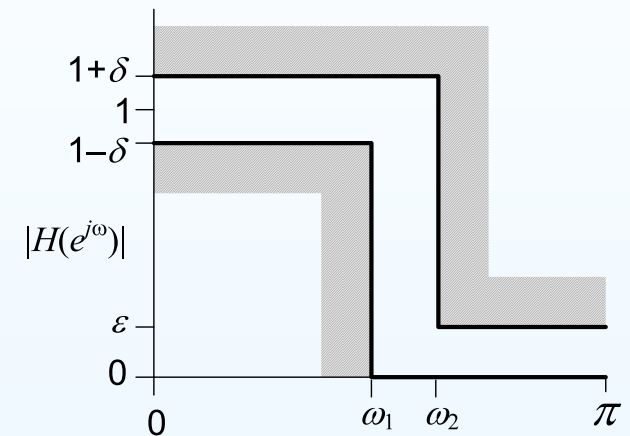
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## Order Estimation

Several formulae estimate the required order of a filter,  $M$ .

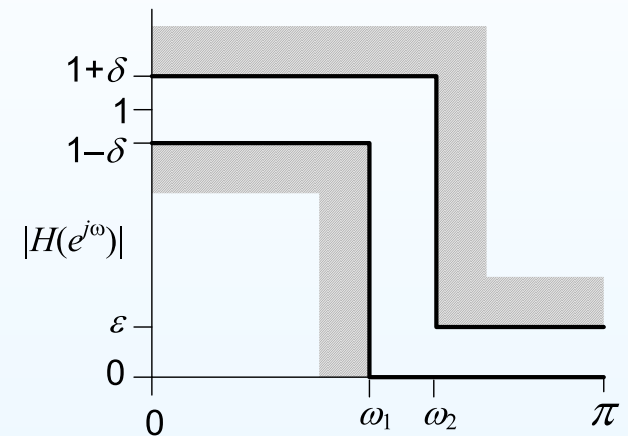
E.g. for lowpass filter

Estimated order is

$$M \approx \frac{-5.6 - 4.3 \log_{10}(\delta \epsilon)}{\omega_2 - \omega_1} \approx \frac{-8 - 20 \log_{10} \epsilon}{2.2 \Delta \omega}$$

Required  $M$  increases as either the transition width,  $\omega_2 - \omega_1$ , or the gain tolerances  $\delta$  and  $\epsilon$  get smaller.

**Only approximate.**



**Example:**

Transition band:  $f_1 = 1.8$  kHz,  $f_2 = 2.0$  kHz,  $f_s = 12$  kHz,.

$$\omega_1 = \frac{2\pi f_1}{f_s} = 0.943, \omega_2 = \frac{2\pi f_2}{f_s} = 1.047$$

Ripple:  $20 \log_{10}(1 + \delta) = 0.1$  dB,  $20 \log_{10} \epsilon = -35$  dB

$$\delta = 10^{\frac{0.1}{20}} - 1 = 0.0116, \epsilon = 10^{\frac{-35}{20}} = 0.0178$$

$$M \approx \frac{-5.6 - 4.3 \log_{10}(2 \times 10^{-4})}{1.047 - 0.943} = \frac{10.25}{0.105} = 98 \quad \text{or} \quad \frac{35 - 8}{2.2 \Delta \omega} = 117$$



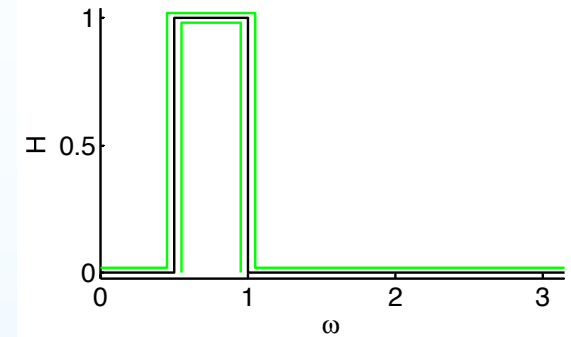
# Example Design

## 6: Window Filter Design

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## Specifications:

Bandpass:  $\omega_1 = 0.5, \omega_2 = 1$



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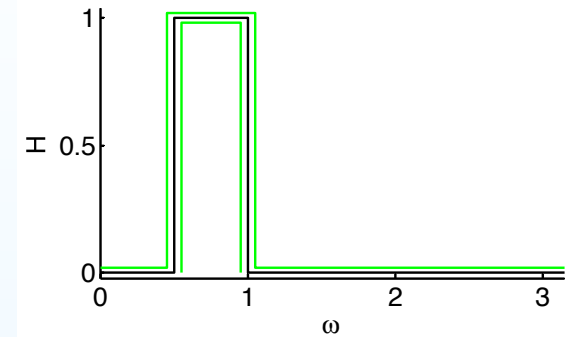
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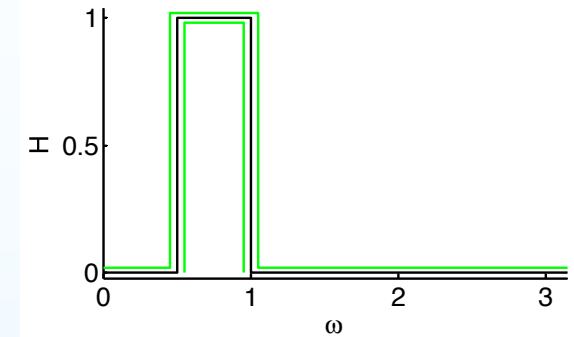
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## Specifications:

Bandpass:  $\omega_1 = 0.5, \omega_2 = 1$

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Ripple:  $\delta = \epsilon = 0.02$



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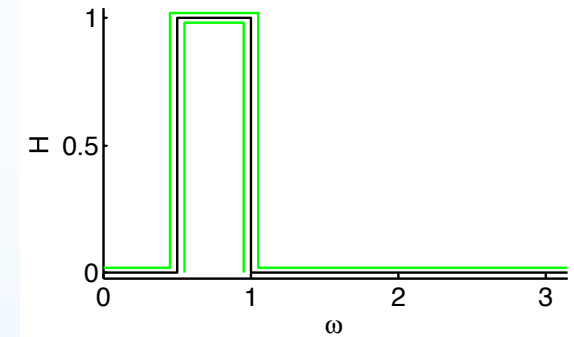
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$$20 \log_{10} \epsilon = -34 \text{ dB}$$



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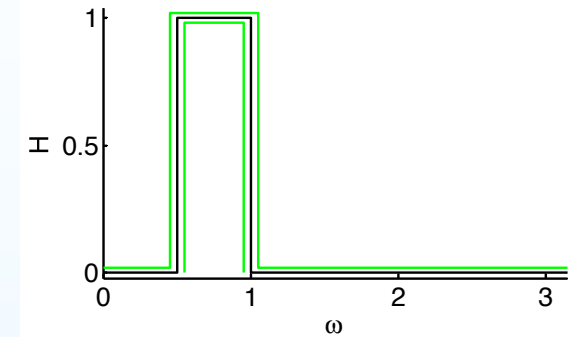
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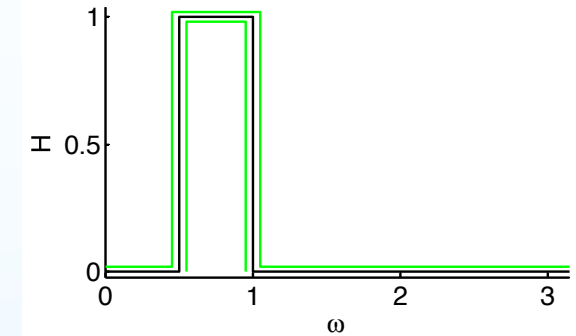
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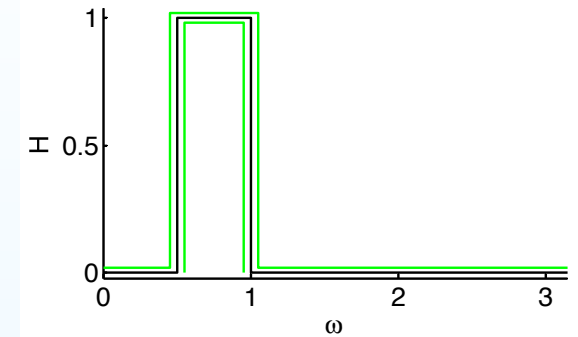
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Difference of two lowpass filters



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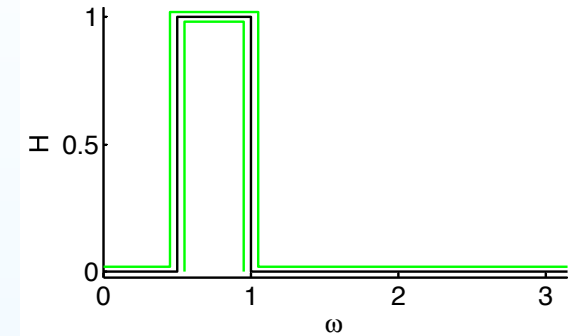
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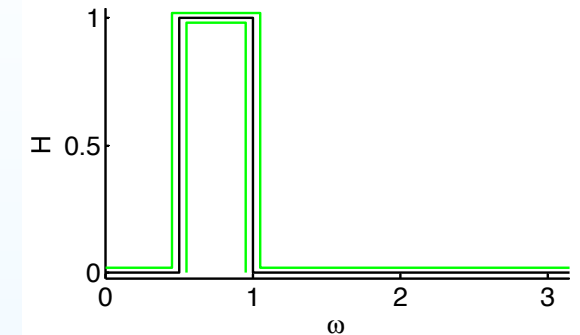
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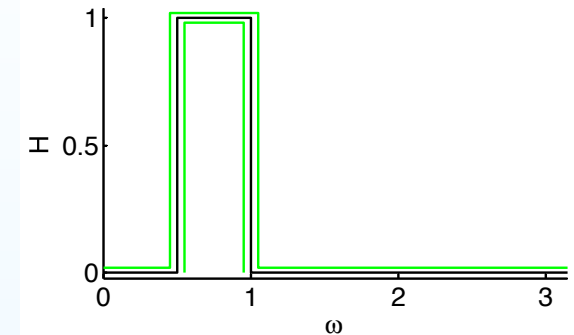
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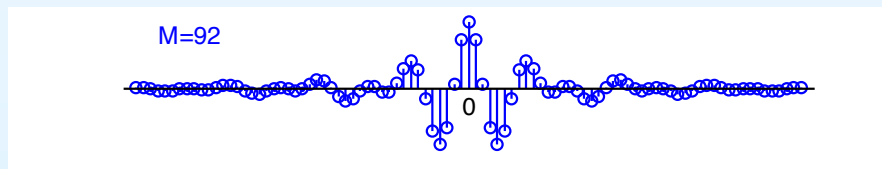
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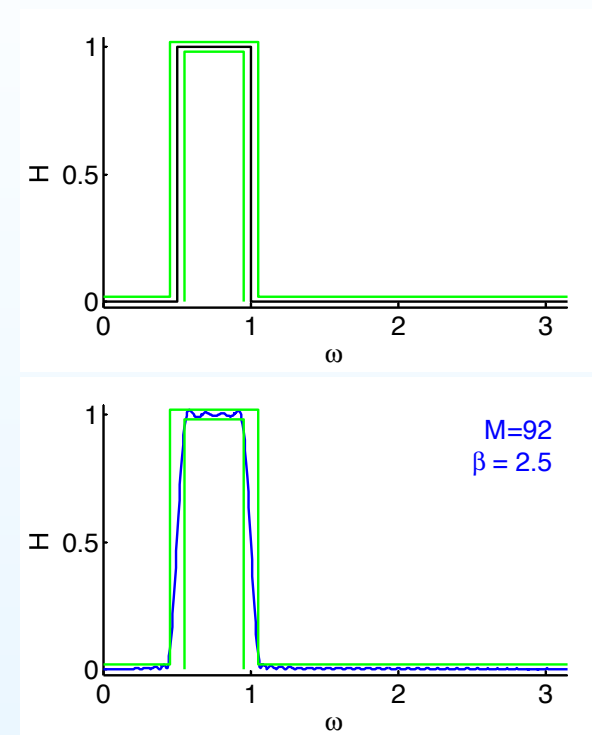
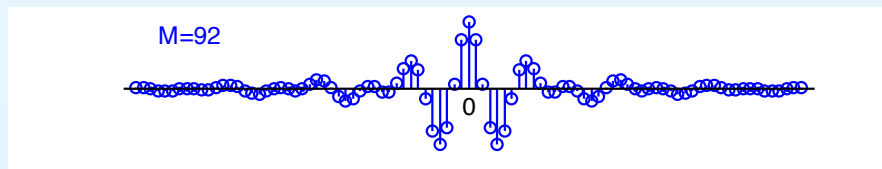
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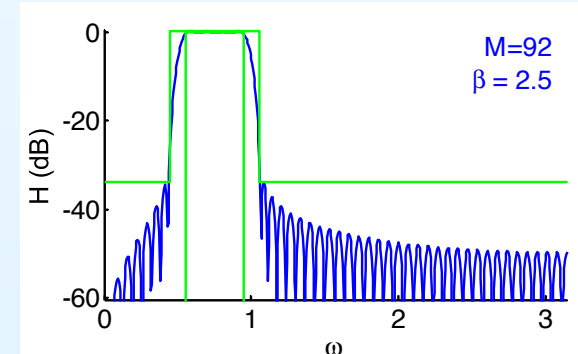
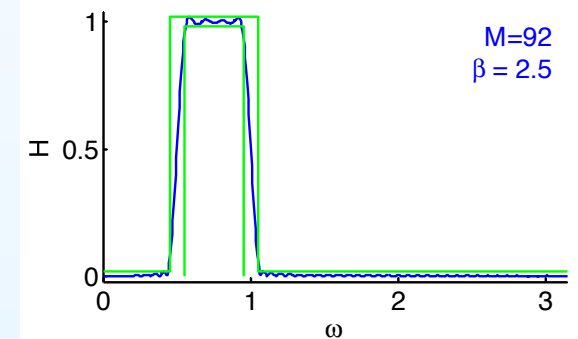
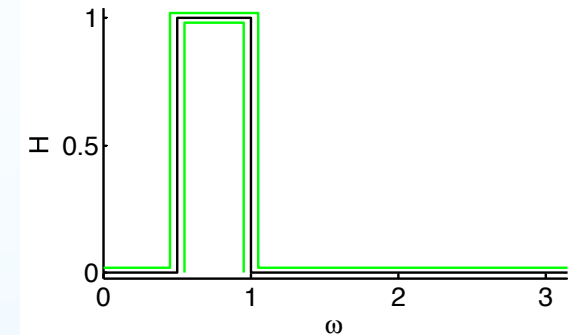
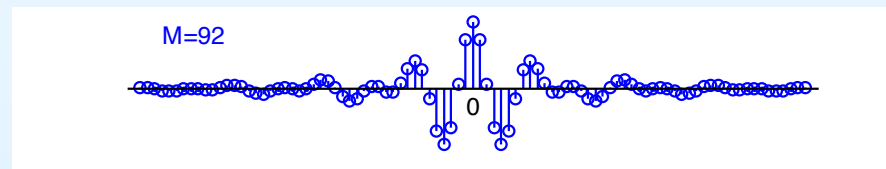
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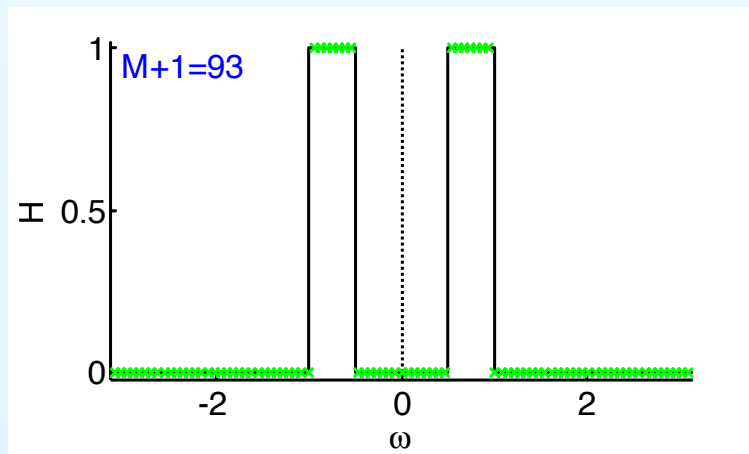
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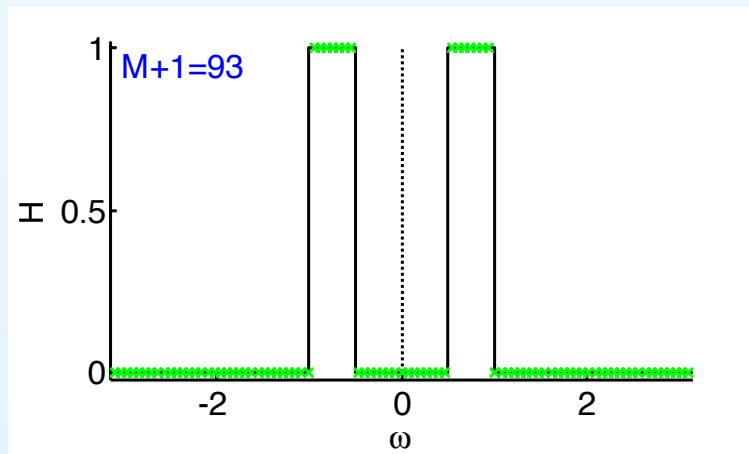


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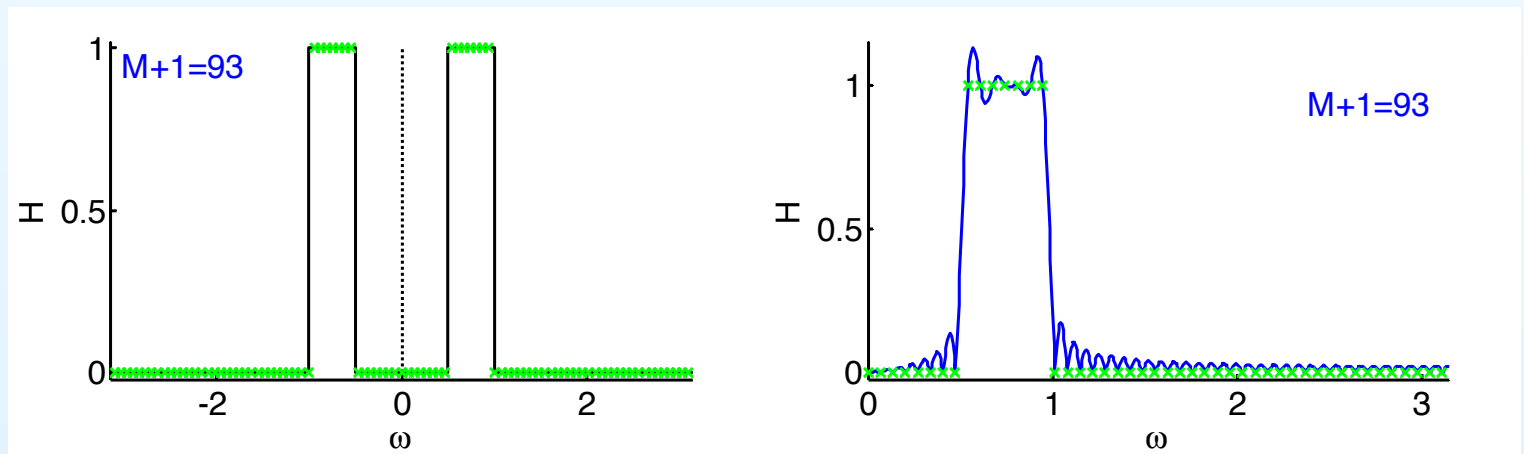


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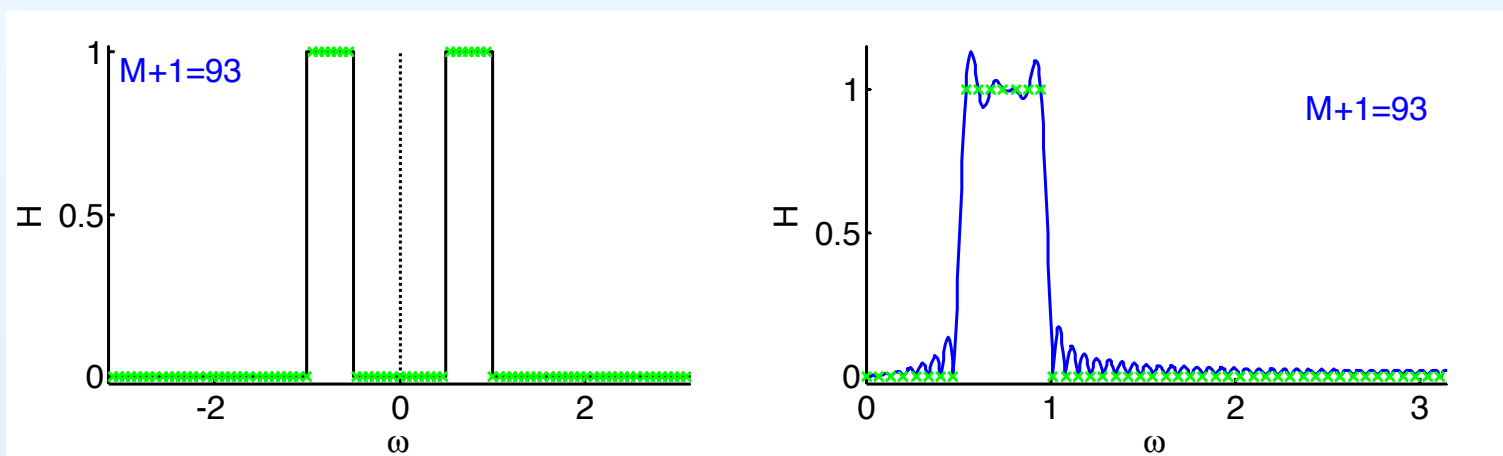
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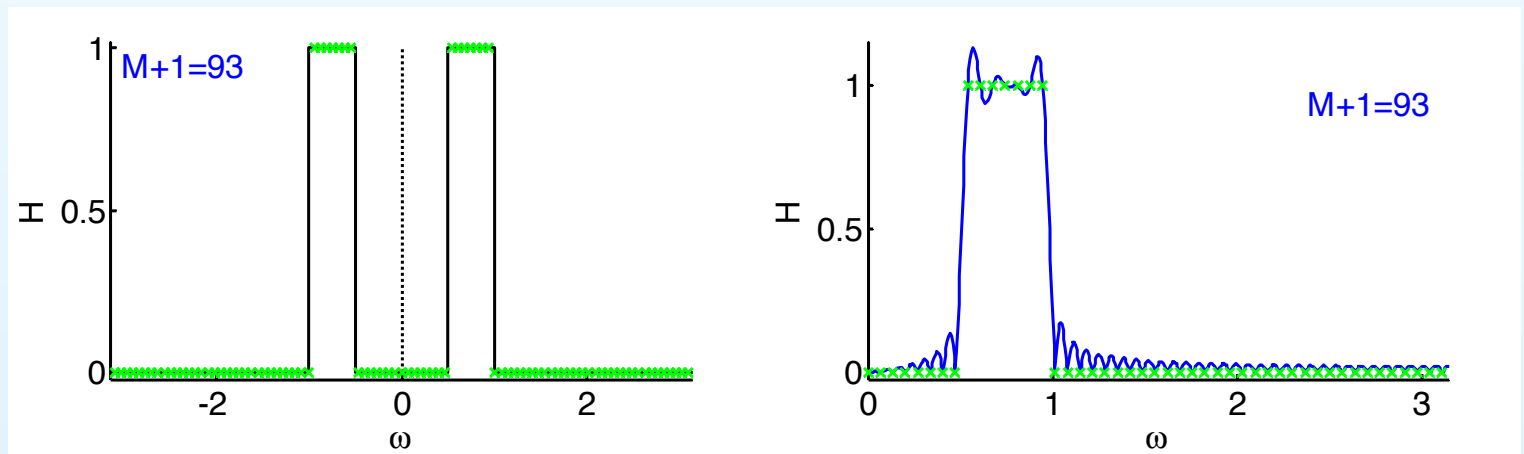
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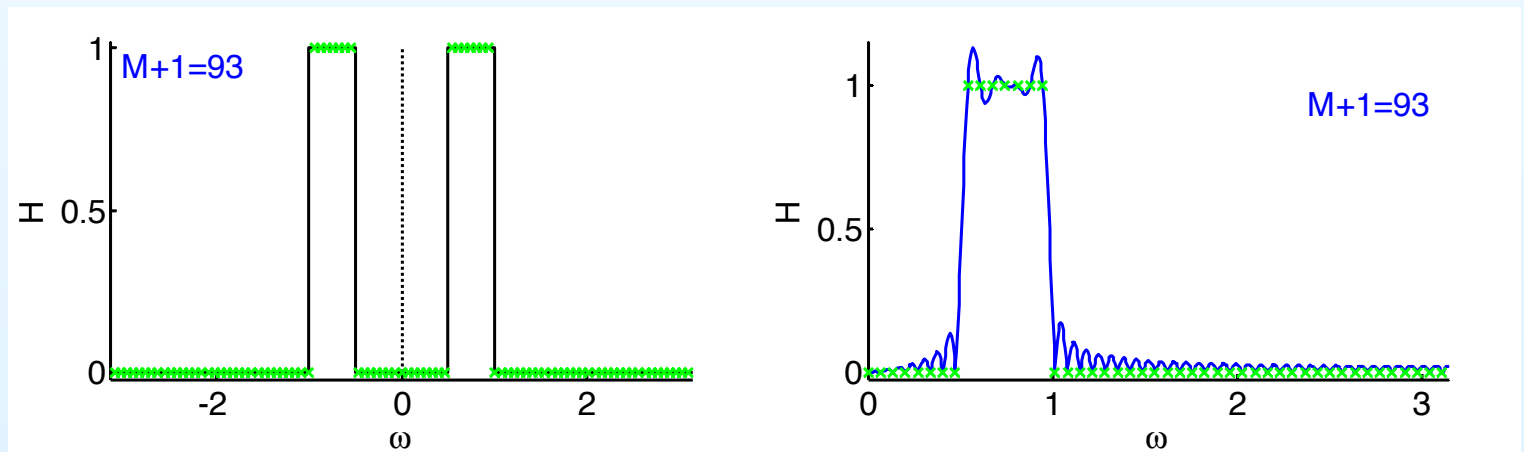
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(1) make the filter transitions smooth over  $\Delta\omega$  width



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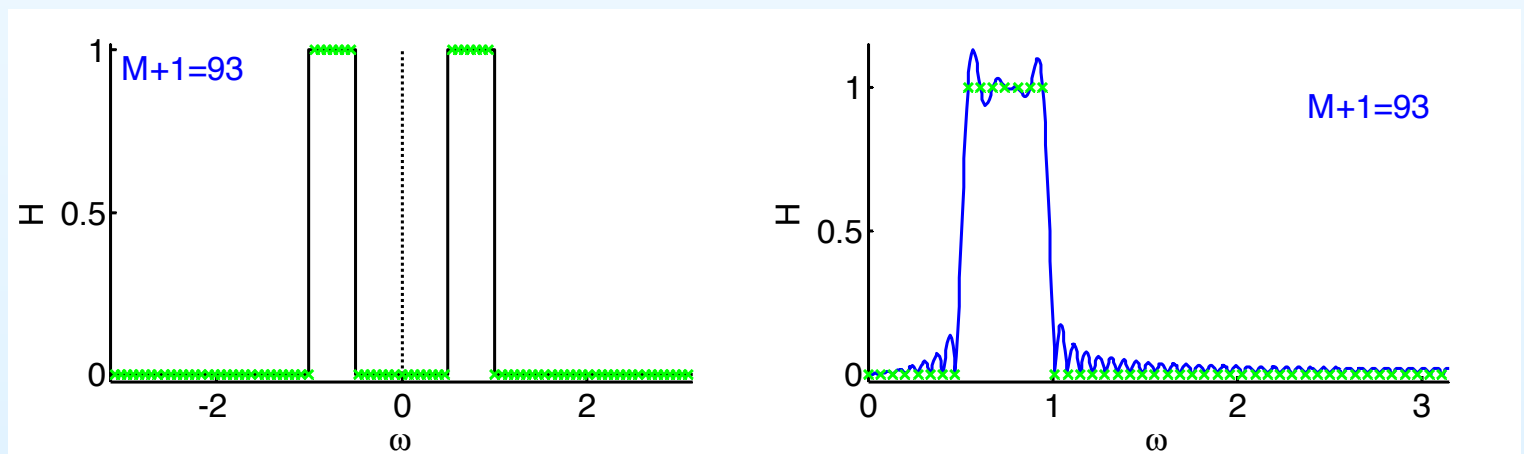
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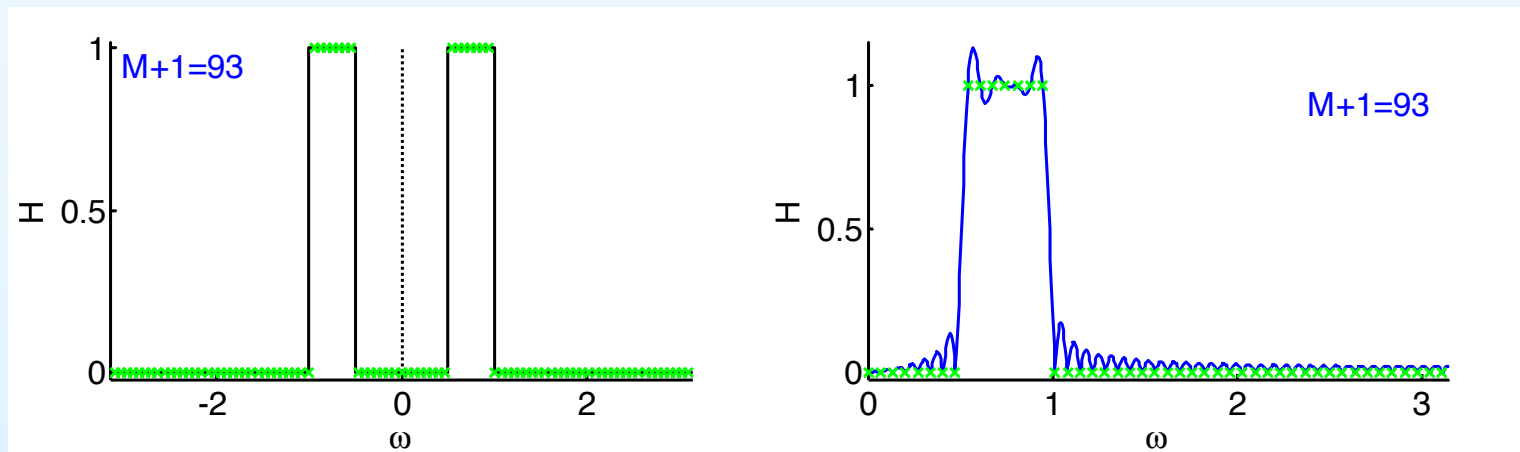
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**Solutions:**

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- (3) use non-uniform points with more near transition (can't use IDFT)



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For further details see Mitra: 7, 10.

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## MATLAB routines

diric(x,n)	Dirichlet kernel: $\frac{\sin 0.5nx}{\sin 0.5x}$
hanning hamming kaiser	Window functions (Note 'periodic' option)
kaiserord	Estimate required filter order and $\beta$