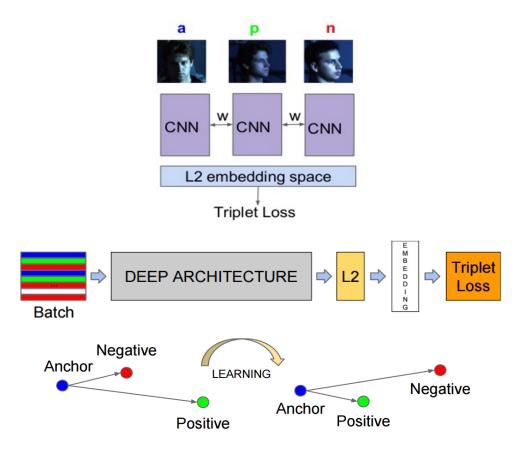
Triplet Loss

Introduction

The triplet loss is often used on person re-indentification or face recognition problems, the idea of triplet loss is to receive 3 scores, 1 anchor score, a related psoitive score and an extra negative score related to a "negative class". The training objective will minimize this loss by making related scores similar while making the difference between the anchor scores and the negative score larger.

$$Loss_{triplet} = \sum_{i=1}^{N} \left[L_{2_{distance}} (f_{anchor}[i] - f_{positive}[i])^{2} - L_{2_{distance}} (f_{anchor}[i] - f_{negative}[i])^{2} + \alpha \right]_{+}$$

The triplet loss has 3 inputs, which are the output of a neural network, a class called "anchor class", another class that is positive, and a negative class. On a face recognition problem the anchor class could be a person, and positive class could be the same person under other ilumination, and a negative class a different person.

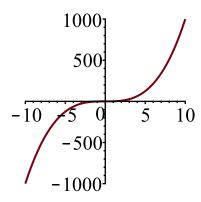


Sometimes the inputs of the triplet loss comes from 3 different networks that share the same weights, but this also can be achieved by using a single network and building the batch with the anchor, positive and negative class. This also implies that if the triplet loss has 3 inputs during backpropagation we should return 3 gradients.

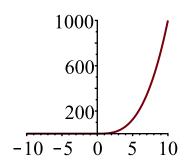
Hinge effect

Notice at the end of the Triplet loss function the "+" sign, this indicate that the loss that the function will not have negative values. This is done to avoid having a negative loss, and giving a loss of zero on the case that the distance (Anchor...negative + alpha) is bigger than (Anchor...Positive). This also will have effects on it's gradients. To illustrate better this process I will define some simple functions with this behaviour.

 $someFunc := x \rightarrow x^3 = x \rightarrow x^3 \rightarrow$



Now if we want that this function output only positive values we could say $someFunc_{max} := (x) \rightarrow max(0, someFunc(x)) = x \rightarrow max(0, someFunc(x)) \rightarrow$



This also implies that the gradient of this functions would be different

$$\frac{\mathrm{d}}{\mathrm{d}\,x}someFunc(x) = 3\,x^2$$

$$\frac{\mathrm{d}}{\mathrm{d}x} someFunc_{\max}(x) = \begin{cases} 0 & x \le 0\\ 3x^2 & 0 < x \end{cases}$$

Euclidian distance (Or L2 distance)

Like other distances (ie L1 distance) the L2 distance return a scalar that represent how 2 vectors(p,q) are similar to each other.

$$p := [1, 2, 3] = [1, 2, 3]$$

 $q := [1.1, 2, 3.3] = [1.1, 2, 3.3]$

$$L_2 := (a, b, N) \to \sqrt{\sum_{i=1}^{N} (a[i] - b[i])^2} = (a, b, N) \to \sqrt{\sum_{i=1}^{N} (a_i - b_i)^2}$$

 $L_2(p, q, 3) = 0.3162277660$

$$L_{2}(p_{v}, q_{v}, 3) = \sqrt{(p_{v_{1}} - q_{v_{1}})^{2} + (p_{v_{2}} - q_{v_{2}})^{2} + (p_{v_{3}} - q_{v_{3}})^{2}}$$

On the context of loss functions we use the square I2 distance to actually cancel the squar-root term.

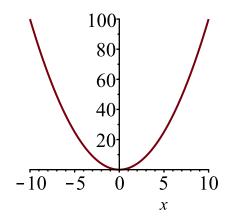
$$||p_i - q_i||_2^2 = \left(\sqrt{\sum_{i=1}^N (a[i] - b[i])^2}\right)^2$$

This sometimes causes confusion because now it will be called L2-norm loss

$$L_{2_{loss}} := (a, b, N) \rightarrow \sum_{i=1}^{N} (a[i] - b[i])^{2} = (a, b, N) \rightarrow \sum_{i=1}^{N} (a_{i} - b_{i})^{2}$$

$$\begin{split} &L_{2_{loss}}(p,q,3) = 0.10 \\ &L_{2_{loss}}(p_{_{_{\boldsymbol{V}}}},q_{_{_{\boldsymbol{V}}}},3) = (p_{_{\boldsymbol{v}_{1}}}-q_{_{\boldsymbol{v}_{1}}})^2 + (p_{_{\boldsymbol{v}_{2}}}-q_{_{\boldsymbol{v}_{2}}})^2 + (p_{_{\boldsymbol{v}_{3}}}-q_{_{\boldsymbol{v}_{3}}})^2 \end{split}$$

Also for illustration purposes this is how the plot of the L2-norm loss looks like $L_{2_{loss_{plot}}} := x^2 = x^2 \rightarrow 0$



There is a variant of the L2-norm loss called MSE (Mean squared error) loss which divide the L2-norm loss by the batch-size, the idea is to decouple the batch size from the loss value.

$$MSE_{loss} := (a, b, N) \rightarrow \frac{1}{N} \cdot \left(\sum_{i=1}^{N} (a[i] - b[i])^{2} \right) = (a, b, N) \rightarrow \frac{\sum_{i=1}^{N} (a_{i} - b_{i})^{2}}{N}$$

$$MSE_{loss} (p_{v}, q_{v}, 3) = \frac{1}{3} (p_{v_{1}} - q_{v_{1}})^{2} + \frac{1}{3} (p_{v_{2}} - q_{v_{2}})^{2} + \frac{1}{3} (p_{v_{3}} - q_{v_{3}})^{2}$$

Get the derivative of L2-norm loss w.r.t to input

Before we delve into the gradient of the triplet-loss let's investigate how to find the derivative of the L2norm function, by definition the idea of the norm function is to give a positive scalar number that represent the size of a vector, so we can consider the following simplification.

$$\sum_{i=1}^{N} (a[i] - b[i])^2 \Rightarrow \sum_{i=1}^{N} u^2, \text{ where u will be a function that calculate the difference } (a[i] - b[i]) \text{ vector}$$

Let's just lay out some derivatives rules, consider u as a function

Scalar multiple rule:
$$\frac{d}{dx} (\alpha \cdot u) = \alpha \frac{d}{dx} u$$

Sum Rule: $\frac{d}{dx} \sum u = \sum \frac{d}{dx} u$, this is nice because I don't know yet how to calculate derivatives with sum properly on maple

$$sum \cdot \frac{\partial}{\partial a} (a - b)^2 = sum (2 a - 2 b)$$

$$sum \cdot \frac{\partial}{\partial b} (a - b)^2 = sum (-2 a + 2 b)$$

Putting all together

Now let's put together the L2-norm inside the triplet loss, and also push outside all the Σ operators $f := (anchor, positive, negative, \alpha) \rightarrow [(anchor - positive)^2 - (anchor - negative)^2 + \alpha] = (anchor, positive, negative, \alpha) \rightarrow [(anchor - positive)^2 - (anchor - negative)^2 + \alpha]$ $\frac{d}{d \ anchor} f(anchor, positive, negative, \alpha) = [-2 \ positive + 2 \ negative]$ $\frac{d}{d \ positive} f(anchor, positive, negative, \alpha) = [-2 \ anchor + 2 \ positive]$ $\frac{d}{d \ negative} f(anchor, positive, negative, \alpha) = [2 \ anchor - 2 \ negative]$

Now I just isolate the factors from the expression:

```
factors(-2 positive + 2 negative) = [2, [[negative - positive, 1]]]

factors(-2 anchor + 2 positive) = [-2, [[anchor - positive, 1]]]

factors(2 anchor - 2 negative) = [2, [[anchor - negative, 1]]]
```

Gradients of Triplet loss

Due to the fact that the triplet loss wants to make the distance between $[f_{anchor}, f_{positive}]$ small while making the distance $[f_{anchor}, f_{negative}]$ big by an α factor the gradients will be zero if the expression:

$$\begin{bmatrix} L_{2_{distance}}(f_{anchor} - f_{positive})^2 - L_{2_{distance}}(f_{anchor} - f_{negative})^2 + \alpha \end{bmatrix}$$
 gives a negative number (<=0), because it would imply that
$$\begin{bmatrix} L_{2_{distance}}(f_{anchor} - f_{positive})^2 \end{bmatrix}$$
 is already bigger than
$$\begin{bmatrix} L_{2_{distance}}(f_{anchor} - f_{negative})^2 + \alpha \end{bmatrix}$$

Gradient w.r.t anchor input

$$\frac{\partial}{\partial f_{anchor}} Loss_{triplet} = \sum_{i=1}^{N} [2(f_{negative} - f_{positive})]$$

Gradient w.r.t positive input

$$\frac{\partial}{\partial f_{positive}} Loss_{triplet} = \sum_{i=1}^{N} \left[-2 \left(f_{anchor} - f_{positive} \right) \right]$$

Gradient w.r.t negative input

$$\frac{\partial}{\partial f_{negative}} Loss_{triplet} = \sum_{i=1}^{N} [2(f_{anchor} - f_{negative})]$$

References

- https://en.wikipedia.org/wiki/Loss_function
- https://arxiv.org/pdf/1503.03832.pdf
- http://stackoverflow.com/questions/33330779/whats-the-triplet-loss-back-propagation-gradientformula
- http://www.cnblogs.com/wangxiaocvpr/p/5452367.html
- https://en.wikipedia.org/wiki/Euclidean distance
- http://www.slideshare.net/xavigiro/deep-learning-for-computer-vision-image-retrieval-upc-2016
- https://www.physicsforums.com/threads/derivative-of-a-function-involving-square-root-of-sum-of-squares.643123/
- http://math.stackexchange.com/questions/84331/does-this-derivation-on-differentiating-theeuclidean-norm-make-sense
- http://math.stackexchange.com/questions/883016/gradient-of-l2-norm-squared
- https://davidrosenberg.github.io/ml2015/docs/3a.loss-functions.pdf
- https://davidrosenberg.github.io/ml2015/#home
- https://devblogs.nvidia.com/parallelforall/understanding-aesthetics-deep-learning/
- http://rishy.github.io/ml/2015/07/28/l1-vs-l2-loss/
- http://nbviewer.jupyter.org/github/rishy/rishy.github.io/blob/master/ipy_notebooks/L1%20vs. %20L2%20Loss.ipynb
- http://mccormickml.com/2014/03/04/gradient-descent-derivation/
- https://www.quora.com/What-is-the-difference-between-L1-and-L2-regularization
- http://www.chioka.in/differences-between-l1-and-l2-as-loss-function-and-regularization/
- http://www.cv-foundation.org/openaccess/content_cvpr_2016/papers/Cheng_Person_Re-Identification_by_CVPR_2016_paper.pdf
- https://github.com/davidsandberg/facenet
- https://arxiv.org/pdf/1605.07270.pdf