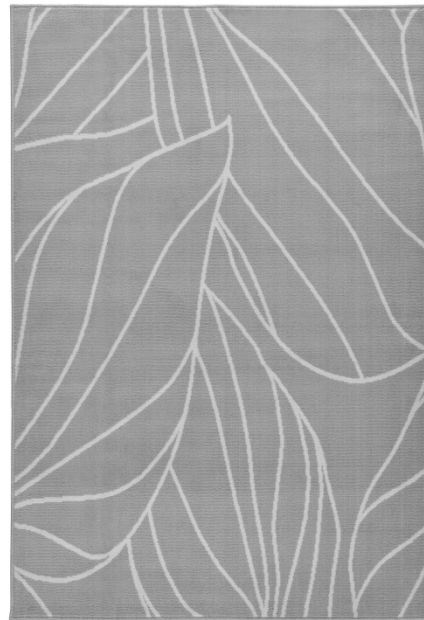


## Problem Set 5 Report

### 1. Greyscale function



2. Correlation function. Note: I have two correlation functions, one that takes in a filter value and a dimension, and one that takes in a 1D array. Both are basically the same.

```
/* Correlates a filter value on an image. This function takes in a greyscale BMPImage,
and a separable filter with n x n dimensions and a uniform filter value. The filter
value parameter should be the value before separation. For instance, if the box filter
has all values of 1/49, then 1/49 should be used as input, as this function will
separate the box filter into two 1D filters with the value of 1/7. The function then
applies the two 1D filters to the image.*/
```

```
void correlationFunction(BMPImage *image, float filter, int n) {

    float readVal, writeVal, filterVal;

    filterVal = sqrt(filter);

    //for each pixel in the image

    for (int y = 0; y < image->getYSize(); y++) {

        for (int x = 0; x < image->getXSize(); x++) {

            writeVal = 0;

            readVal = 0;
```

```
//filter across x

for (int i = -1 * (n / 2); i <= (n / 2); i++) {

    int offsetXCoord = x + i;

    //padding left

    if (offsetXCoord <= 0) {

        //use left most value in row

        image->readPixel(0, y, readVal, readVal, readVal);

        writeVal += readVal * filterVal;

    }

    //padding right

    else if (offsetXCoord >= image->getXSize() - 1) {

        //use right most value in row

        image->readPixel(image->getXSize() - 1, y, readVal,
readVal, readVal);

        writeVal += readVal * filterVal;

    }

    else {

        //use value at offset in row

        image->readPixel(offsetXCoord, y, readVal, readVal,
readVal);

        writeVal += readVal * filterVal;

    }

}

clampValues(&writeVal);

image->writePixel(x, y, writeVal, writeVal, writeVal);

}

}

//for each pixel in the image

for (int y = 0; y < image->getYSize(); y++) {

    for (int x = 0; x < image->getXSize(); x++) {
```

```
writeVal = 0;

readVal = 0;

//filter across y
for (int i = -1 * (n / 2); i <= (n / 2); i++) {
    int offsetYCoord = y + i;

    //padding top
    if (offsetYCoord <= 0) {
        //use top most value in column
        image->readPixel(x, 0, readVal, readVal, readVal);

        writeVal += readVal * filterVal;
    }

    //padding bottom
    else if (offsetYCoord >= image->getYSize() - 1) {
        //use top most value in column
        image->readPixel(x, image->getYSize() - 1, readVal,
readVal, readVal);

        writeVal += readVal * filterVal;
    }
    else {
        //use value at offset in column
        image->readPixel(x, offsetYCoord, readVal, readVal,
readVal);

        writeVal += readVal * filterVal;
    }
    }clampValues(&writeVal);
    image->writePixel(x, y, writeVal, writeVal, writeVal);
}
}
}
```



## 2. Gaussian function

```
/* Creates a gaussian filter. This function takes in a value for sigma and a pointer
to an integer. The function will create a new 1D filter and populate it with values
for the gaussian filter. The function will return a pointer to the 1D filter, and will
modify the integer pointer to reflect the dimension of the filter. */

float* filterGaussianFunction(float sigma, int *dimen) {

    const float PI = 3.1415927;

    int filterDimen = 2 * (ceilf(3 * sigma)) + 1;

    float *filter = new float[filterDimen];

    int j = 0; //index in the filter

    //populate the filter

    for (int i = -1 * (filterDimen / 2); i <= (filterDimen / 2); i++) {

        //calculate filter value and place in filter

        filter[j] = sqrt(1 / (2 * sigma * sqrt(2 * PI))) * exp(-1 * (i * i) / (2 *
sigma * sigma));

        j++;

    }

    //normalize the filter values

    float sum = 0.0f;

    for (int i = 0; i < filterDimen; i++) {

        sum += filter[i];

    }

    for (int i = 0; i < filterDimen; i++) {

        filter[i] = (filter[i] / sum);

    }

    *dimen = filterDimen; //"return" the dimension of the filter

    return filter; //return the filter

}
```

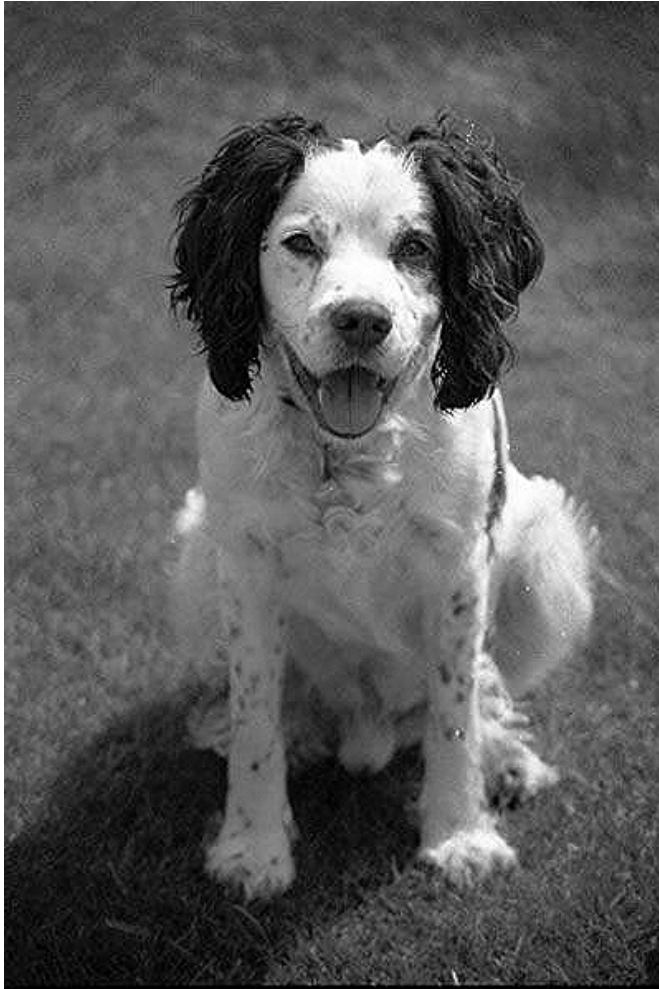




### 3. Sharpening function

/\* Creates a sharpening filter. This function takes in a value for sigma, a pointer to a 1D Gaussian filter and the dimension of the filter. The function will subtract the Gaussian filter from an all-pass filter with a center value of 2, with the rest being zero. The function returns the filter T-G. \*/

```
float* filterSharpeningFunction(float sigma, float *filter, int dimen) {  
    for (int i = 0; i < dimen; i++) {  
        if (i == (dimen / 2)) {  
            filter[i] = 2 - filter[i]; //center value of filter T is 2,  
subtract the center gaussian filter value  
        }  
        else {  
            filter[i] *= -1.0f; //all other values of T are 0, so subtract  
gaussian filter value at this position  
        }  
    }  
    return filter;  
}
```





#### 4. Resize function

/\* Resizes an image using bilinear interpolation to fill in pixel values. The function will look at surrounding pixels and interpolate the color for a given pixel. \*/

```
void resizeFunction(BMPImage *image, float scale, char *saveName) {  
  
    float temp1 = image->getXSize() * scale;  
  
    float temp2 = image->getYSize() * scale;  
  
    /* compute the image size */  
  
    int remainder = (int)fmodl(temp1, 4L);  
  
    if (remainder != 0) {  
        temp1 += (4 - remainder);  
    }  
  
    BMPImage scaledImage = BMPImage(temp1, temp2);  
  
    int xLeft, xRight, yTop, yBot;  
  
    float topLeftVal, topRightVal, botLeftVal, botRightVal;  
  
    float weightX, weightY;  
  
    float leftBorderVal, rightBorderVal;  
  
    float finalVal;  
  
    //for all pixels in the scaled image  
    for (int scaledX = 0; scaledX < scaledImage.getXSize(); scaledX++) {  
        for (int scaledY = 0; scaledY < scaledImage.getYSize(); scaledY++) {  
            //get coordinates of surrounding pixels in original image  
  
            xLeft = scaledX / scale;  
  
            //make sure we don't exceed bounds of image  
            if (xLeft == image->getXSize() - 1) {  
                xRight = xLeft;  
            }  
  
            else {  
                xRight = xLeft + 1;  
            }  
        }  
    }  
}
```

```
yTop = scaledY / scale;

//make sure we don't exceed bounds of image
if (yTop == image->getYSize() - 1) {
    yBot = yTop;
}
else {
    yBot = yTop + 1;
}

//get color value at surrounding pixels in original image
image->readPixel(xLeft, yTop, topLeftVal, topLeftVal, topLeftVal);
//top left value

image->readPixel(xRight, yTop, topRightVal, topRightVal,
topRightVal);
//top right value

image->readPixel(xLeft, yBot, botLeftVal, botLeftVal, botLeftVal);
//bot left value

image->readPixel(xRight, yBot, botRightVal, botRightVal,
botRightVal);
//bot right value

//get weight in the y direction
weightY = (scaledY / scale) - yTop;

//get color value on left border at the y value
leftBorderVal = (weightY * (botLeftVal - topLeftVal)) +
topLeftVal;

//get color value on right border at the y value
rightBorderVal = (weightY * (botRightVal - topRightVal)) +
topRightVal;

//get weight in the x direction
weightX = (scaledX / scale) - xLeft;

//get color between the two weighted border values
finalVal = (weightX * (rightBorderVal - leftBorderVal)) +
leftBorderVal;
```

```
        scaledImage.writePixel(scaledX, scaledY, finalVal, finalVal,  
finalVal);  
    }  
}  
scaledImage.save(saveName);  
}
```

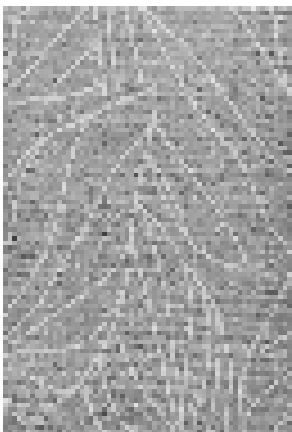
Dog scaled by 3:



Dog scaled by 0.75



Rug scaled by 0.05



Rug sigma 10 Gaussian and then scaled by 0.05

