

# **itklib**

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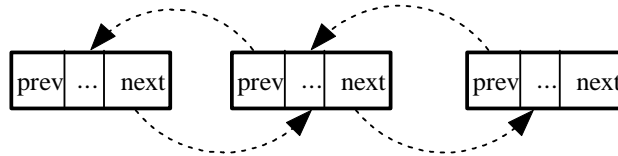
# libgraphics Data Structure Index

## libgraphics Data Structures

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## PRIMITIVE



```

typedef enum{
    PRIMARY_CRV_T = 1,
    COMPLEX_CRV_T = 2,
    RULE_CRV_T    = 3
}PRIMITIVE_E;
typedef struct tagPrimitiveAttr{
    unsigned short u:1;           // exist user data?
    unsigned short f:1;           // is supporting format?
    unsigned short d:2;           // dimension(2 - 2D , 3 - 3D)
    unsigned short h:1;           // hole or solid
    unsigned short reversed:1;
    unsigned short continuous:1;  // for SQ_POINTS.
    unsigned short closed:1;      // for SQ_POLYLINE
    unsigned short del:1;         // is deleted?
    unsigned short r:3;
    unsigned short type:4;        //
} PRIMITIVEATTR_T,* PPRIMITIVEATTR_T;
primitive
typedef struct tagSQHeader
    char          id;             // id of element
    char          layer;          // level or layer element is on
    PRIMITIVEATTR_T attr;         //
    unsigned long handle;
    SQVOLUME      volume;         /// primitive's volume
    struct{
        short ltype;             // line type
        short lweight;           // line weight
        unsigned char lcolor[3]; // line color(r,g,b)
        char r;                  // reserved
        long lscale;             // arrow
    }display;
    char          desc[16];       // description
    unsigned long tsize,esize;
}SQHEADER,* PSQHEADER;
primitive header

typedef struct tagSQPrimitive
    SQHEADER hdr;
    union{
        POINT_T      point;
        SQVERTEX     vertex;
  
```

```

LINE_T      line;
PPOINT_TNODE polyline;
SQSHAPE     shape;
TEXT_T      text;
SQREFERENCE reference;
list<SQVERTEX>* plstVertices;
vector<POINT_T>* pvtPoints;

//--> curve
CIRCLE_T    circle;
ARC_T       arc;
ELLIPSE_T   ellipse;
SQCURVE     curve;
SQINTCURVE  intcurve;
//<--

CONE_T      cone;

//--> surface
PSQSURFACE  pSurface;
PSQPLANESURFACE pPlaneSurface;
PSQCONESURFACE pConeSurface;
PSQSPHERESURFACE pSphereSurface;
PSQTORUSSURFACE pTorusSurface;
//<--

PLAYER_T    player;
struct tagSQPrimitive* pPrimitive;
char*       pData;
}body;
void* pLinkageData;
struct tagSQPrimitive *prev,*next; /// pointer to prev and next
}SQPRIMITIVE,* PSQPRIMITIVE;
primitive body union .

```

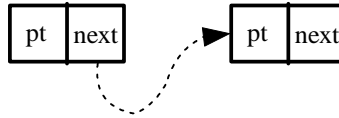
## tagSQVertex Struct Reference

```

typedef struct tagSQVertex{
    struct tagCode{
        unsigned char visit : 1; /// already visited?
        unsigned char moveto: 1; /// moveto or lineto
        unsigned char r : 6; /// reserved
    }code;
    double x,y,z; /// value
}SQVERTEX,* PSQVERTEX;

```

## tagSQPointNode Struct Reference



```
typedef struct tagSQPointNode{
    POINT_T pt;
    struct tagSQPointNode* next; /// next pointnode
}SQPOINTNODE,* PPOINT_TNODE;
```

## tagSQShape Struct Reference

```
typedef struct tagSQShape{
    unsigned short fcolor; /// fill color
    struct _list{
        POINT_T point;
        struct _list* next;
    }* list;
}SQSHAPE,* PSQSHAPE;
```

---

The documentation for this struct was generated from the following file:

- sqstruct.h

## tagCone Struct Reference

```
typedef struct tagCone{
    VECTOR_T vecAxis; /// axis of cone
    POINT_T ptOrigin[2];
    double nRadius[2];
}CONE_T,* PCONE_T;
```

---

The documentation for this struct was generated from the following file:

- cone.h

## tagLayer Struct Reference

```
typedef struct tagLayer{
    char szName[32]; /// layer name buffer
}LAYER_T,* PLAYER_T;
```

---

The documentation for this struct was generated from the following file:

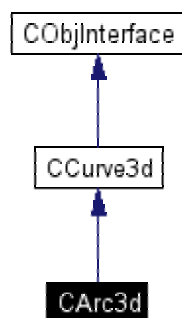
- layer.h

# libgraphics Data Structure Documentation

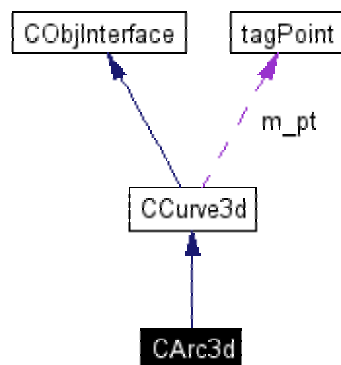
## CArc3d Class Reference

002CArc3d#include <arc3d.h>

Inheritance diagram for CArc3d:



Collaboration diagram for CArc3d:



### Public Member Functions

- [CArc3d](#) ()
- [CArc3d](#) (const [ARC T](#) &arc)
- [CArc3d](#) (const [CArc3d](#) &arc)
- [CArc3d](#) ([POINT T](#) ptOrigin, [POINT T](#) ptStart, const double &nSweepAng)
- virtual [~CArc3d](#) ()
  
- void [CreateSegments](#) ()  
The [CArc3d::CreateSegments](#) function



*user must have a copy of points of segments.*

*because of another curve will overwrite the point value.*

- [PPOINT\\_T Revolve](#) (VECTOR\_T vecAxis, double nAngle, int nParts)  
(vecAxis)                      nAngle                      .

#### Static Public Member Functions

- void [segments](#) ([POINT\\_T](#) ptEDGE[], const [POINT\\_T](#) &ptOrigin, const [POINT\\_T](#) &ptStart, const VECTOR\_T &vecNorm, const double nSweep, const int &nSegments)
- [POINT\\_T on](#) (const [POINT\\_T](#) &ptOrigin, const VECTOR\_T vecNorm, const double nRadius, const double &nAngle)
- [POINT\\_T OnPoint](#) (const [POINT\\_T](#) ptOrigin, const double nRadius, const VECTOR\_T vecAxis, const double &nAngle)  
*ptOrigin, nRadius, vecAxis    ↗    arc                      nAngle                      .*

#### Data Fields

- int [m\\_nSegments](#)

---

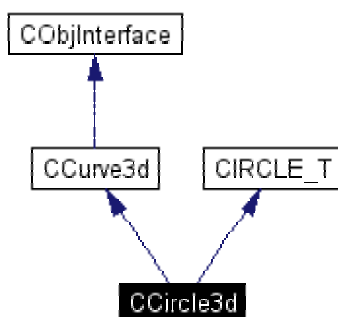
The documentation for this class was generated from the following files:

- [arc3d.h](#)
- [arc3d.cpp](#)

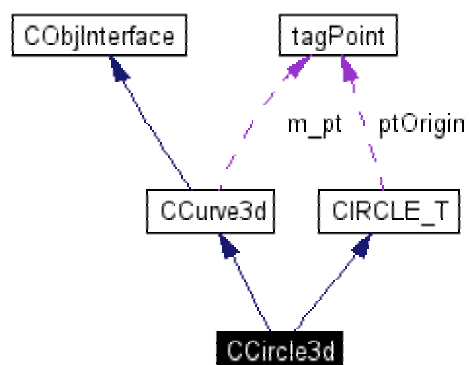
## CCircle3d Class Reference

002CCircle3d#include <circle3d.h>

Inheritance diagram for CCircle3d:



Collaboration diagram for CCircle3d:



### Public Member Functions

- [CCircle3d](#) ()
- [CCircle3d](#) (const [CIRCLE\\_T](#) &circle)
- [CCircle3d](#) (const [CCircle3d](#) &circle)
- [CCircle3d](#) (double x, double y, double z, double radius)  
 $x, y, z$  ,  $radius =$
- virtual [~CCircle3d](#) ()
- [POINT\\_T GetOrigin](#) ()

- double [GetRadius](#) ()
- void [SetOrigin](#) (double x, double y, double z)
- void [SetOrigin](#) ([POINT T](#) ptCenter)
- void [SetRadius](#) (const double &radius)
- void [CreateSegments](#) ()
- [PPOINT T Sweep](#) (*Ccurve3d::m\_pt* VECTOR\_T vecAxis, double nAngle, int nParts)

---

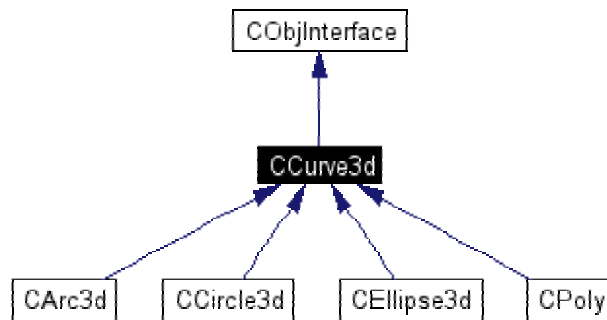
The documentation for this class was generated from the following files:

- [circle3d.h](#)
- [circle3d.cpp](#)

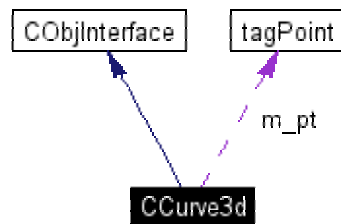
## CCurve3d Class Reference

002CCurve3d#include <curve3d.h>

Inheritance diagram for CCurve3d:



Collaboration diagram for CCurve3d:



### Public Member Functions

- [CCurve3d](#) ()
- virtual [~CCurve3d](#) ()
- void [SetSegments](#) (const int nSegments)  
*curve segment*
- int [GetNumOfPoints](#) ()  
*curve*
- virtual [PPOINT\\_T GetFacets](#) ()  
*∇*
- virtual void [CreateSegments](#) ()=0
- virtual [PPOINT\\_T Sweep](#) (VECTOR\_T vecAxis, double nAngle, int nParts)

### Static Public Member Functions

- [PPOINT\\_T Revolve](#) (const VECTOR\_T &vecAxis, int nSize, [PPOINT\\_T](#) pptOriginal, const double &nAngle, const int &nParts)  
*(vecAxis)* *nAngle*
- const int [GetNumOfSegments](#) ()  
*curve* *curve* *segment*
- [POINT\\_T](#) & [pt](#) (const int &nIndex)  
Return Ccuve3d::m\_pt[nIndex];

### Static Protected Attributes

- int [NUM\\_OF\\_SEGMENTS](#) /// *curve* *segment*
- [POINT\\_T m\\_pt](#) [MAX\_CURVE\_POINTS]

---

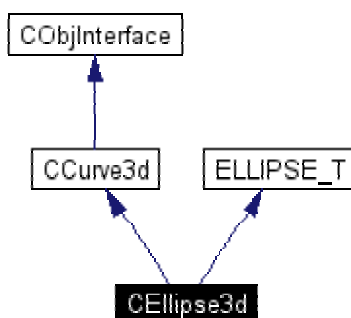
The documentation for this class was generated from the following files:

- [curve3d.h](#)
- [curve3d.cpp](#)

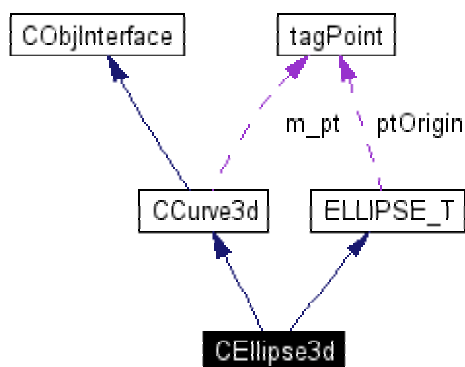
## CEllipse3d Class Reference

002CEllipse3d#include <ellipse3d.h>

Inheritance diagram for CEllipse3d:



Collaboration diagram for CEllipse3d:



### Public Member Functions

- [CEllipse3d](#) ()
- [CEllipse3d](#) (const [ELLIPSE\\_T](#) &ellipse)
- [~CEllipse3d](#) ()

- void [CreateSegments](#) ()

Ccurve3d::m\_pt

---

The documentation for this class was generated from the following files:

- [ellipse3d.h](#)
- [ellipse3d.cpp](#)

## CGeometry Class Reference

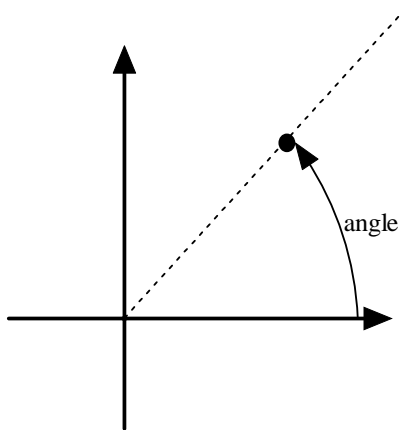
```
002CGeometry#include <geometry.h>
```

### Public Member Functions

- [CGeometry\(\)](#)
- [~CGeometry\(\)](#)

### Static Public Member Functions

- bool [IsSameValue](#) (double val1, double val2, double tol)  
*tol*
- bool [IsSamePoint](#) (const [POINT\\_T](#) &pt1, const [POINT\\_T](#) &pt2, double tol)  
*check whether pt1 and pt2 are same points or not.*
- double [GetRotatedAngleInXYPlane](#) (const [POINT\\_T](#) &pt)



*calculate angle in 2D.*

- double [GetRotatedAngleInXYPlane](#) (const [VECTOR\\_T](#) &vec)  
*calculate rotated angle of pt in 2D.*
- void [GetRotatedAngleOfAxis](#) (const [VECTOR\\_T](#) &vecAxis, double &alpha, double &beta)  
*The [CGeometry::GetRotatedAngleOfAxis](#) function  
get rotated angle of x-axis,y-axis about z-axis( $\langle 0,0,1 \rangle$ ).*
- [VECTOR\\_T](#) [RotateOnXYPlane](#) (const [VECTOR\\_T](#) vec, double nDeg)  
*x-y                  vec                  nDeg*

- [POINT\\_T RotateAboutXYAxis](#) ([POINT\\_T](#) &pt, const double &xangle, const double &yangle)  
*first, rotate about x axis by alpha angle,*  
*then rotate about y axis by beta angle.*  
rotating matrix=  

$$\begin{bmatrix} 1 & 0 & 0 \\ 0 & \cos(\beta) & -\sin(\beta) \\ 0 & \sin(\alpha) \cos(\beta) & \cos(\alpha) \cos(\beta) \end{bmatrix} \begin{bmatrix} \cos(\alpha) & \sin(\alpha) \\ 0 & 1 \end{bmatrix}$$
- [VECTOR\\_T RotateAboutXYAxis](#) (const [VECTOR\\_T](#) &pt, double xangle, double yangle)  
The [CGeometry::RotateAboutXYAxis](#) function  
*first, rotate about x axis by alpha angle,*  
*then rotate about y axis by beta angle.*  
rotating matrix=  

$$\begin{bmatrix} 1 & 0 & 0 \\ 0 & \cos(\beta) & -\sin(\beta) \\ 0 & \sin(\alpha) \cos(\beta) & \cos(\alpha) \cos(\beta) \end{bmatrix} \begin{bmatrix} \cos(\alpha) & \sin(\alpha) \\ 0 & 1 \end{bmatrix}$$
- [POINT\\_T RotateAboutYXAxis](#) ([POINT\\_T](#) &pt, double beta, double alpha)  
The [CGeometry::RotateAboutYXAxis](#) function  
*first rotate about y axis by beta angle,*  
*rotate about x axis by alpha angle.*  

$$\begin{bmatrix} \cos(\beta) & -\sin(\beta) & 0 \\ 0 & 1 & 0 \\ 0 & \sin(\alpha) \cos(\beta) & \cos(\alpha) \cos(\beta) \end{bmatrix} \begin{bmatrix} \cos(\alpha) & \sin(\alpha) \\ 0 & 1 \end{bmatrix}$$
- [VECTOR\\_T RotateAboutYXAxis](#) ([VECTOR\\_T](#) &pt, double beta, double alpha)  
The [CGeometry::RotateAboutYXAxis](#) function  
*first rotate about y axis by beta angle,*  
*rotate about x axis by alpha angle.*  

$$\begin{bmatrix} \cos(\beta) & -\sin(\beta) & 0 \\ 0 & 1 & 0 \\ 0 & \sin(\alpha) \cos(\beta) & \cos(\alpha) \cos(\beta) \end{bmatrix} \begin{bmatrix} \cos(\alpha) & \sin(\alpha) \\ 0 & 1 \end{bmatrix}$$
- [POINT\\_T RotateAboutZAxis](#) (const [POINT\\_T](#) &pt, const double theta)  
The [CGeometry::RotateAboutZAxis](#) function  
rotating matrix=  

$$\begin{bmatrix} \cos(\theta) & -\sin(\theta) & 0 \\ \sin(\theta) & \cos(\theta) & 0 \\ 0 & 0 & 1 \end{bmatrix}$$



- VECTOR\_T [RotateAboutZAxis](#) (const VECTOR\_T &pt, const double theta)  
The [CGeometry::RotateAboutZAxis](#) function  
rotate about z axis by theta.  
rotating matrix=  

$$\begin{pmatrix} \cos(\theta) & -\sin(\theta) & 0 \\ \sin(\theta) & \cos(\theta) & 0 \\ 0 & 0 & 1 \end{pmatrix}$$
- [POINT\\_T Rotate](#) ([POINT\\_T](#) pt, [QUAT\\_T](#) quat)  
pt quat .
- VECTOR\_T [Rotate](#) (VECTOR\_T vec, [QUAT\\_T](#) quat)  
vec quat .
- bool [IsPointOnLine](#) (double x, double y, double px, double py, double qx, double qy)  
x,y  $\nearrow$  px,py,qx,qy  $\nearrow$ ?
- [INTERSECTION\\_E IntersectLine2D](#) (double \*x, double \*y, double x1, double y1, double x2, double y2, double x3, double y3, double x4, double y4, const double tol)  
check line is intersect. if so get intersection point.  
Otherwise ,line is collinear or no intersecton.
- [INTERSECTION\\_E IntersectLine2D](#) ([POINT\\_T](#) &pt, const [LINE\\_T](#) &line1, const [LINE\\_T](#) &line2)
- bool [IntersectLineWithPlane](#) ([POINT\\_T](#) \*pt, [LINE\\_T](#) line, [PLANE\\_T](#) plane)  
line plane .
- bool [IntersectLineToVolume](#) ([PLINE\\_T](#) pLine, [PSQVOLUME](#) pVolume, [PPOINT\\_T](#) pRet)  
line volume .
- bool [IsLeftSidePoint](#) (const [POINT\\_T](#) &pt, const [LINE\\_T](#) &line)  
test which pt is located on left side of line or not.
- bool [IsRightSidePoint](#) (const [POINT\\_T](#) &pt, const [LINE\\_T](#) &line)  
test which the point is located on right side of line or not.
- bool [IsEqualPoint2D](#) ([POINT\\_T](#) &x, [POINT\\_T](#) &y, double tol=0.)  
 $\nearrow$ ?

---

The documentation for this class was generated from the following files:

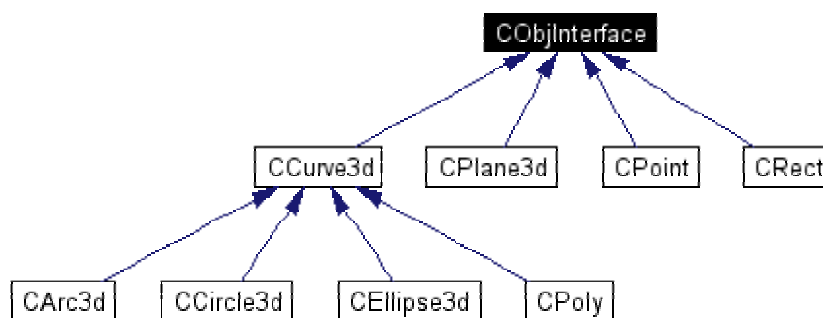
- [geometry.h](#)
- [geometry.cpp](#)

## CObjInterface Class Reference

002CObjInterface#include <ObjInterface.h>

Inheritance diagram for CObjInterface:

Root      ㄱ      . itklib      ㄱ CObjInterface      .



### Public Member Functions

- virtual [~CObjInterface](#) ()
- bool [IsKindOf](#) (const long nId)  
nId ㄱ m\_nId ㄱ?

### Protected Attributes

- unsigned long [m\\_nId](#)

---

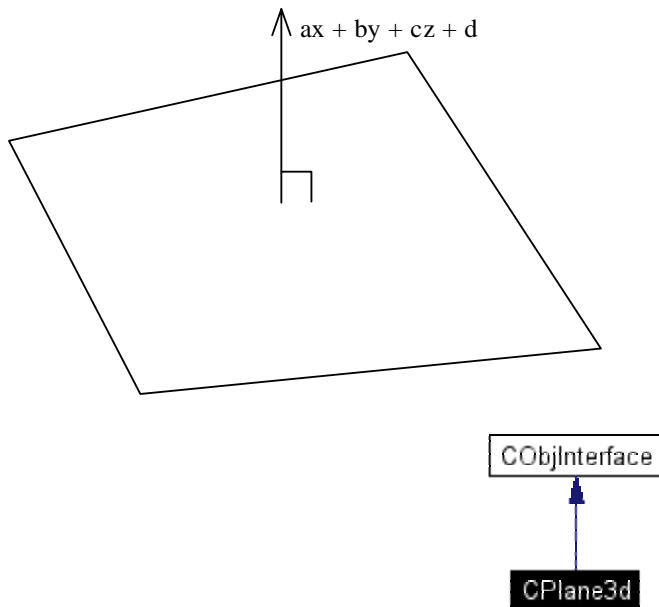
The documentation for this class was generated from the following files:

- [ObjInterface.h](#)
- [ObjInterface.cpp](#)

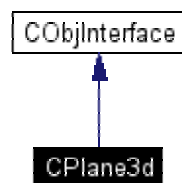
## CPlane3d Class Reference

002CPlane3d#include <plane3d.h>

Inheritance diagram for CPlane3d:



Collaboration diagram for CPlane3d:



### Public Member Functions

- [CPlane3d](#) ()
- [CPlane3d](#) (VECTOR\_T &vec)
- [CPlane3d](#) (POINT\_T &pt1, POINT\_T &pt2, POINT\_T &pt3)
- virtual [~CPlane3d](#) ()
- VECTOR\_T [GetNormVector](#) ()
- void [SetNormVector](#) (double dx, double dy, double dz)

- void [SetNormVector](#) (VECTOR\_T vecNorm)
- void [GetRotatedAngleOfAxis](#) (double &alpha, double &beta)  
 $\nearrow x,y$
- [POINT\\_T RotateAboutXYAxis](#) ([POINT\\_T](#) pt, const double &alpha, const double &beta)  
 $pt \quad x,y \quad \quad \quad \alpha,\beta$
- VECTOR\_T [RotateAboutXYAxis](#) (const VECTOR\_T &vec, double alpha, double beta)  
 $vec \quad x,y \quad \quad \quad \alpha,\beta$
- [POINT\\_T RotateAboutYXAxis](#) ([POINT\\_T](#) pt, double beta, double alpha)  
 $pt \quad y,x \quad \quad \quad \beta,\alpha$
- VECTOR\_T [RotateAboutYXAxis](#) (VECTOR\_T &vec, double beta, double alpha)  
 $vec \quad y,x \quad \quad \quad \beta,\alpha$
- double [GetAngle](#) (VECTOR\_T &vec)  
 $vec \nearrow$
- bool [ComputePlaneEquation](#) ([POINT\\_T](#) &pt1, [POINT\\_T](#) &pt2, [POINT\\_T](#) &pt3)  
*Computes plane equation.*
- [SIGN\\_T WhichSideOfPlane](#) ([POINT\\_T](#) &pt)  
 $pt \nearrow \quad \quad \quad \nearrow?$

#### Data Fields

- VECTOR\_T [m\\_vecNorm](#) ///  $(a,b,c)$
- double [m\\_nD](#)

#### Static Public Attributes

- const VECTOR\_T [XAXIS](#) = {1.,0.,0.}
- const VECTOR\_T [YAXIS](#) = {0.,1.,0.}
- const VECTOR\_T [ZAXIS](#) = {0.,0.,1.}

---

The documentation for this class was generated from the following files:

- [plane3d.h](#)
- [plane3d.cpp](#)

## PLANE\_T Struct Reference

002PLANE\_T#include <plane3d.h>

### Data Fields

- double [a](#)
- double [b](#)
- double [c](#)
- double [d](#)

---

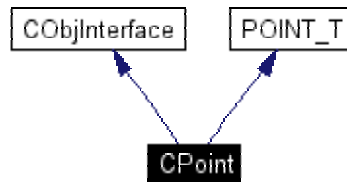
The documentation for this struct was generated from the following file:

- [plane3d.h](#)

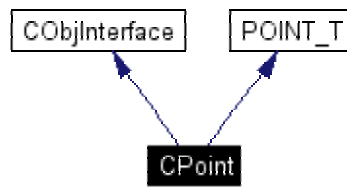
## CPoint Class Reference

002CPoint#include <point.h>

Inheritance diagram for CPoint:



Collaboration diagram for CPoint:



### Public Member Functions

- [CPoint](#) ()
- virtual [~CPoint](#) ()

### Static Public Member Functions

- const double [Distance](#) (const [POINT\\_T](#) &pt1, const [POINT\\_T](#) &pt2)  
*calculate distance between pt1 and pt2.*

---

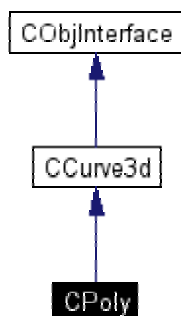
The documentation for this class was generated from the following files:

- [point.h](#)
- [point.cpp](#)

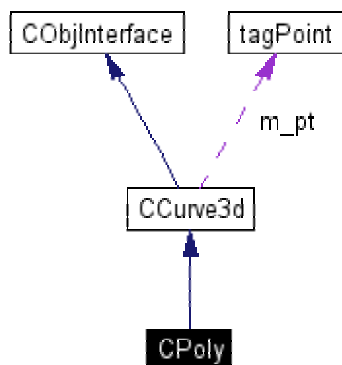
## CPoly Class Reference

002CPoly#include <poly.h>

Inheritance diagram for CPoly:



Collaboration diagram for CPoly:



### Public Member Functions

- [CPoly](#) ()
- virtual [~CPoly](#) ()

### Protected Attributes

- bool [m\\_bClosed](#) /// *7/?*
- list< [CPoint](#) \* > \* [m\\_plst](#)

---

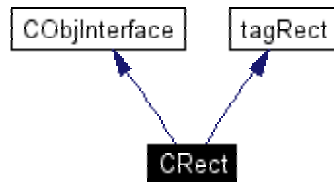
The documentation for this class was generated from the following files:

- [poly.h](#)
- [poly.cpp](#)

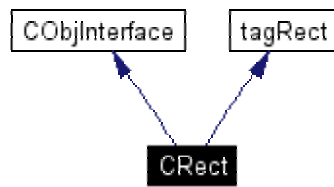
## CRect Class Reference

002CRect#include <rect.h>

Inheritance diagram for CRect:



Collaboration diagram for CRect:



### Public Member Functions

- [CRect](#) ()
- virtual [~CRect](#) ()
- bool [IsInnerPoint](#) (const [POINT T](#) &pt)  
*pt* ↗? ↗?
- bool [IsOverlapped](#) (const [CRect](#) &rect)  
*rect* ↗? ↗?

---

The documentation for this class was generated from the following files:

- [rect.h](#)
- [rect.cpp](#)



## ITKGeo Class Reference

002ITKGeo#include <ITKGeo.h>

### Static Public Member Functions

- double [GetRotatedAngleInXYPlane](#) ([POINT\\_T](#) pt)  
*pt* .
- bool [IsOverlapRect](#) ([PRECT\\_T](#) pRect1, [PRECT\\_T](#) pRect2)  
*pRect1, pRect2, ㄱ?*
- bool [IsPointInRect](#) (const [POINT\\_T](#) &point, const [RECT\\_T](#) &rect)  
*point ㄱ? rect ㄱ?*
- bool [IntersectLineToVolume](#) ([PLINE\\_T](#) pLine, PSQVOLUME pVolume, [PPOINT\\_T](#) pRet)
- bool [ComputePlaneEquation](#) ([PPLANE\\_T](#) pPlaneEquation, [POINT\\_T](#) pt1, [POINT\\_T](#) pt2, [POINT\\_T](#) pt3)  
*pt1, pt2, pt3* .
- [POINT\\_T](#) [GetMinDistPoint](#) (const [POINT\\_T](#) &pt, int &nLoc, const [LINE\\_T](#) &line)  
*pt ㄱ? ㄱ? line* .

---

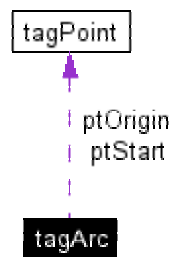
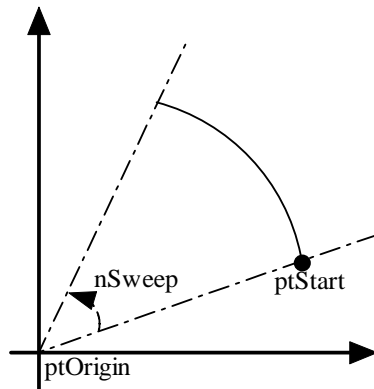
The documentation for this class was generated from the following files:

- [ITKGeo.h](#)
- [ITKGeo.cpp](#)

## tagArc Struct Reference

002tagArc#include <arc3d.h>

Collaboration diagram for tagArc:



### Data Fields

- [POINT\\_T ptOrigin](#) /// arc
- [POINT\\_T ptStart](#) /// arc
- [VECTOR\\_T vecNorm](#) /// arc
- double [nSweep](#)
- double [nRatio](#) /// (1 circular arc)

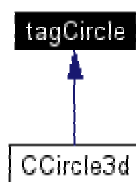
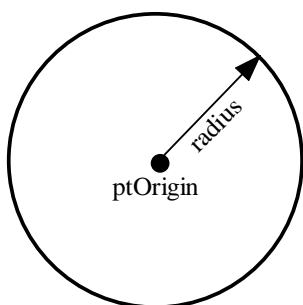
The documentation for this struct was generated from the following file:

- [arc3d.h](#)

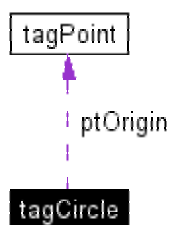
## tagCircle Struct Reference

002tagCircle#include <circle3d.h>

Inheritance diagram for tagCircle:



Collaboration diagram for tagCircle:



### Data Fields

- [POINT\\_T ptOrigin](#)
- double [nRadius](#)
- VECTOR\_T [vecNorm](#)

---

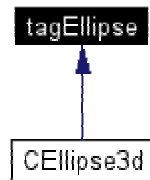
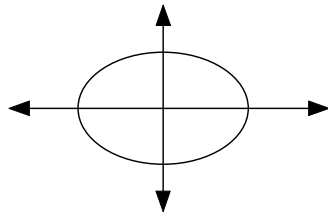
The documentation for this struct was generated from the following file:

- [circle3d.h](#)

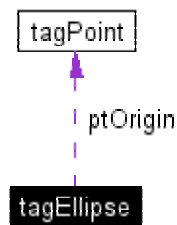
## tagEllipse Struct Reference

002tagEllipse#include <ellipse3d.h>

Inheritance diagram for tagEllipse:



Collaboration diagram for tagEllipse:



### Data Fields

- VECTOR\_T [vecNorm](#) ///
- POINT\_T [ptOrigin](#) ///
- double [nRotate](#) ///
- double [nAxis](#) [2] // ,
- double [nStartAngle](#) ///
- double [nSweepAngle](#) /// *sweep*

---

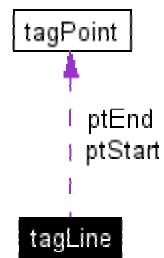
The documentation for this struct was generated from the following file:

- [ellipse3d.h](#)

## tagLine Struct Reference

002tagLine#include <line.h>

Collaboration diagram for tagLine:



### Data Fields

- [POINT\\_T ptStart](#) ///
- [POINT\\_T ptEnd](#) ///

---

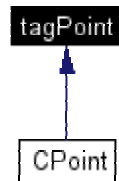
The documentation for this struct was generated from the following file:

- [line.h](#)

## tagPoint Struct Reference

002tagPoint#include <point.h>

Inheritance diagram for tagPoint:



### Data Fields

- double [x](#)
- double [y](#)
- double [z](#)

---

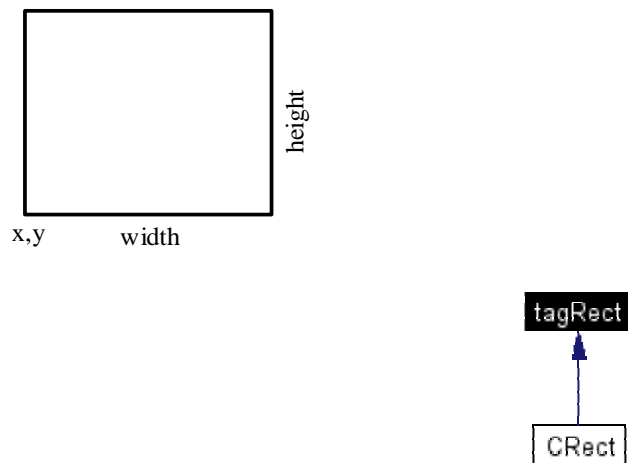
The documentation for this struct was generated from the following file:

- [point.h](#)

## tagRect Struct Reference

```
002tagRect#include <rect.h>
```

Inheritance diagram for tagRect:



### Data Fields

- double [x](#)
- double [y](#)
- double [width](#)
- double [height](#)

---

The documentation for this struct was generated from the following file:

- `rect.h`