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Short introduction for non-programmers

Variable:

- stores numbers, characters, strings, objects..
- variable = address of an object in computer memory

```
#include <stdio.h>
#include <malloc.h>
int main(void){
    int i,n;
    n=3;
    int a[2];
    double *b;
    b= (double*) malloc(n*sizeof(double));
    printf("\n\n%s\n", "===== Example 1 =====");
    printf("%s %u \n", "Size of integer is:", sizeof(int));
    printf("%s %u \n", "Size of double is:", sizeof(double));

    a[0]=1;
    a[1]=2;
    printf("\n\n%s\n", "///// Integer array a[2]:");
    printf("%s %d %s %u \n", "a[0]: Value is ", a[0], " Adress is" , &a[0]);
    printf("%s %d %s %u \n", "a[1]: Value is ", a[1], " Adress is" , &a[1]);

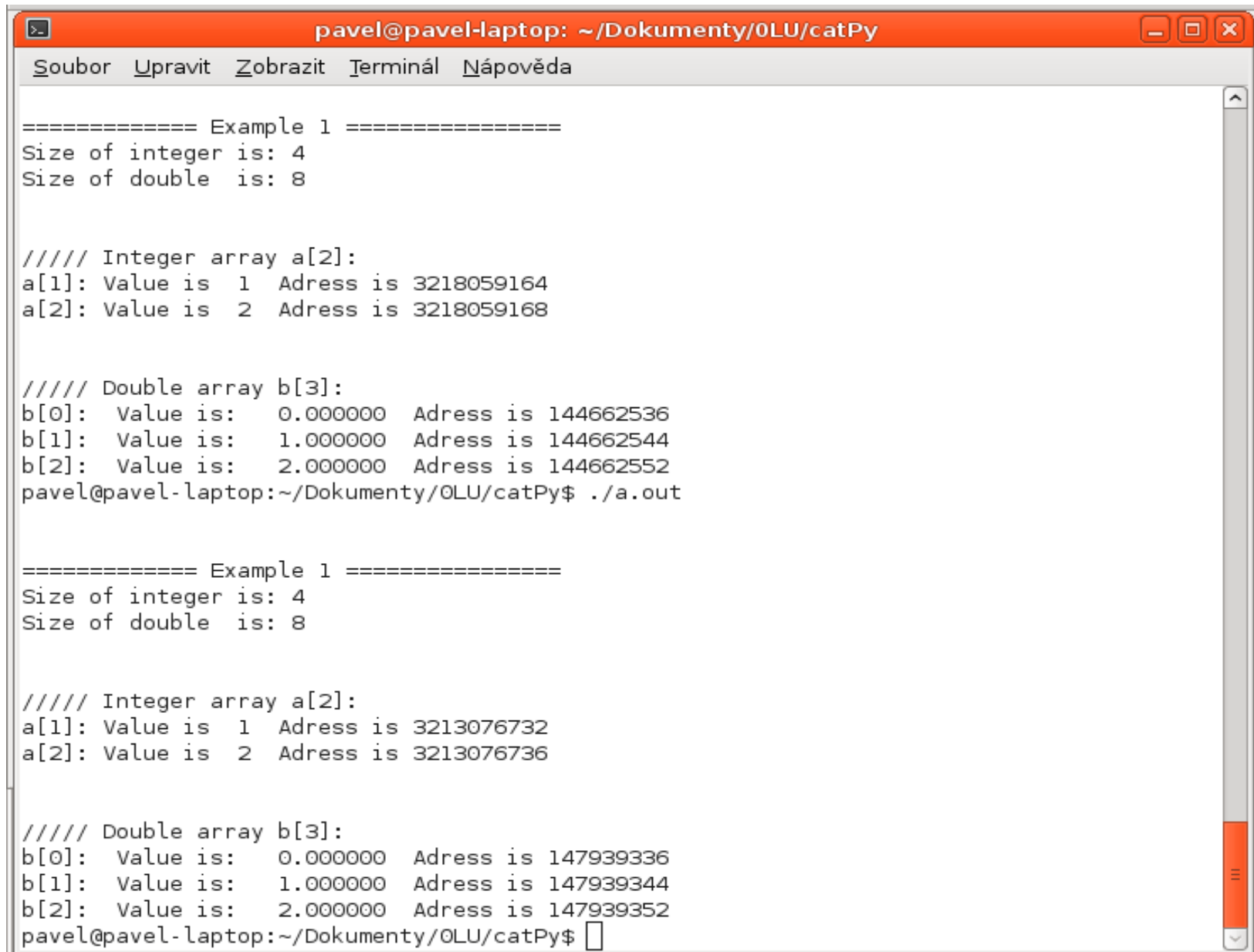
    for (i=0; i<n; i++){
        b[i]=(double)i;
    }
    printf("\n\n%s%d%s\n", "///// Double array b[,n,:");
    for (i=0; i<n; i++){
        printf("%s%d%s  %f %s %u\n", "b[,i,]:  Value is: ", *(b+i), " Adress is" ,b+i);
    }
}
```

Short introduction for non-programmers

Variable:

- address is managed by the operating system / program environment

Reference: C PROGRAMMING LANGUAGE, Kerninghan, Ritchie



The screenshot shows a terminal window titled "pavel@pavel-laptop: ~/Dokumenty/OLU/catPy". The window contains the output of a C program. The output is divided into two identical sections, each starting with "==== Example 1 =====". Each section first prints the size of integer (4) and double (8) types. Then, it prints the values and memory addresses for an integer array 'a' and a double array 'b'. The first run shows addresses in the 3218059164-3218059168 range, while the second run shows addresses in the 3213076732-3213076736 range, indicating a different memory layout or a second execution. The prompt "pavel@pavel-laptop:~/Dokumenty/OLU/catPy\$./a.out" is visible between the two sections.

```
pavel@pavel-laptop: ~/Dokumenty/OLU/catPy
Soubor  Upravit  Zobrazit  Terminál  Nápověda

==== Example 1 =====
Size of integer is: 4
Size of double  is: 8

///// Integer array a[2]:
a[1]: Value is  1  Adress is 3218059164
a[2]: Value is  2  Adress is 3218059168

///// Double array b[3]:
b[0]: Value is:  0.000000  Adress is 144662536
b[1]: Value is:  1.000000  Adress is 144662544
b[2]: Value is:  2.000000  Adress is 144662552
pavel@pavel-laptop:~/Dokumenty/OLU/catPy$ ./a.out

==== Example 1 =====
Size of integer is: 4
Size of double  is: 8

///// Integer array a[2]:
a[1]: Value is  1  Adress is 3213076732
a[2]: Value is  2  Adress is 3213076736

///// Double array b[3]:
b[0]: Value is:  0.000000  Adress is 147939336
b[1]: Value is:  1.000000  Adress is 147939344
b[2]: Value is:  2.000000  Adress is 147939352
pavel@pavel-laptop:~/Dokumenty/OLU/catPy$
```

Short introduction for non-programmers

Structures:

- A lot of variables makes program bad readable for humans
- This usually leads to errors, prolongs program development, ...

Solution is called data structures:

- Data with common denominator are grouped together
- dot convention is used:

```
Parent.child=something
```

Example in GNU/octave, MATLAB:

```
Aircraft=struct( )
```

```
Wing=struct( )
```

```
Wing.parameters=struct( )
```

```
Wing.parameters.span=10.0
```

```
Wing.parameters.rootChord=0.9
```

```
Wing.parameters.tipChord=0.35
```

```
Wing.parameters.airfoil = „NACA 2412“
```

```
Aircraft.wing=Wing
```

Short introduction for non-programmers

Functions:

- A lot of lines makes program bad readable for humans
- This usually leads to errors, prolongs program development, ...

Solution is called functions:

- Repeated calculations are done by functions

```
returnValue=function(input1,..inputN)
```

Example in GNU/octave, MATLAB:

```
function m=getVectorMagnitude(v)
    m=( v(1)^2 + v(2)^2 + v(3)^2 )^0.5;
end
```

```
a=[ 1,0,0 ]
vm=getVectorMagnitude(a)
```

Short introduction for non-programmers

Objects:

- Contains data and functions
- Functions are called “methods”
- Object is an instance of an class
- Class is a template, which defines the methods and how the data are stored
- Dot convention is usulally used:

```
object.data=something
```

```
something=Object.method(input1,..inputN)
```



Python:

- free and open source software
- a general-purpose, high-level programming language
- multi-paradigm programming language, intended to be a highly readable
- large standard library, providing pre-written tools suited to many tasks
NumPy + SciPy can easily replace Matlab, except toolboxes.
- mainly used as a scripting language, but Python code can be packaged into standalone executable programs.
- interpreters are available for many operating systems.
- uses whitespace indentation, rather than braces or keywords, to delimit blocks

Short introduction for non-programmers

Objects:

- An example in python:
source code:

```
##### Create a class #####
class myNumber():
    def __init__(self):                # constructor method
        self.value=0.0                # data

    def setValue(self,value):          # some other methods
        self.value=value

    def getVaule(self):
        return self.value

    def square(self):
        return self.value*self.value

    def multiply(self,n):
        return self.value*n

##### Create and use an object #####

number1=myNumber()                   # number1 is an instance of the myNumber class
number1.setValue(5.0)                 # number1.value = 5.0
b=number1.multiply(10.0)              # b= 5*10
```


Short introduction for non-programmers

Objects:

- An example in python:
program run:

```
pavel@pavel-laptop:~/Dokumenty/OLU/catPy$ ipython myObjects.py
Python 2.6.6 (r266:84292, Dec 27 2010, 00:02:40)
Type "copyright", "credits" or "license" for more information.

IPython 0.10 -- An enhanced Interactive Python.
?                -> Introduction and overview of IPython's features.
%quickref        -> Quick reference.
help             -> Python's own help system.
object?         -> Details about 'object'. ?object also works, ?? prints more.

In [1]: b
Out[1]: 50.0

In [2]: number1
Out[2]: <__main__.myNumber instance at 0xb6fecf0c>

In [3]: number1.getVaule()
Out[3]: 5.0

In [4]: □
```

Requirements:

- MS Windows operating system
- Access to WindowsAPI
- CATIA V5, V6
- Text editor, not Word, Notepad

WindowsAPI:

- API = Application Programming Interface
- Collection of objects, which can be used by programmer
- Examples:

Program can run another program by calling WinAPI

Windows dialog boxes are usually created by calling the WinAPI

Programs can interact each other using the WinAPI + COM

COM:

- Component Object Model
- Microsoft technology for inter-process communication
- Programs can create new objects or modify existing objects in other programs.

Example:

Spell check is used in word processor and in e-mail application.

Instead of creating two **spell checks**, only **spell check** in the word-processor is created.

If there is a need for e-mail spell checking, the **spell check object** from the word processor is called via WinAPI.

The binary interface, which allows this ability is called COM

- Interacting programs can be written in different languages.
- Common thing is the same object in all programs.

Strategy for working with CATIA from script:

- The strategy for working with CATIA from the script is same as the strategy for working with CATIA using the GUI.
- COM objects require same inputs as the user fills in GUI forms.
- However the task is more complex, for example naming objects in CATIA bodies may be necessary for using references.

What to do? Getting help:

- CATIA has build-in VB engine, which can record macros:

`menu -> Tools -> Macro -> Start recording`

- Reading recorded macros is fast method for understanding, what is all that about, but recorded macros can be filled with ballast stuff.

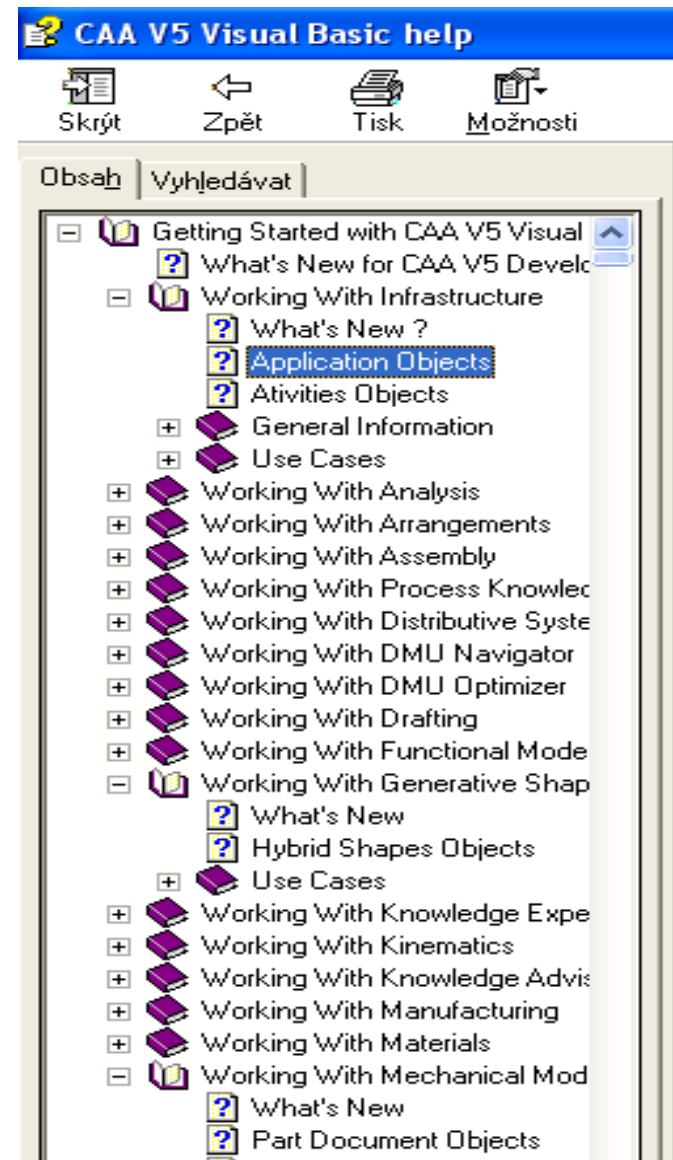
- Help is available:

`Dassault Systemes/B19/intel_a/code/bin/V5Automation.chm`

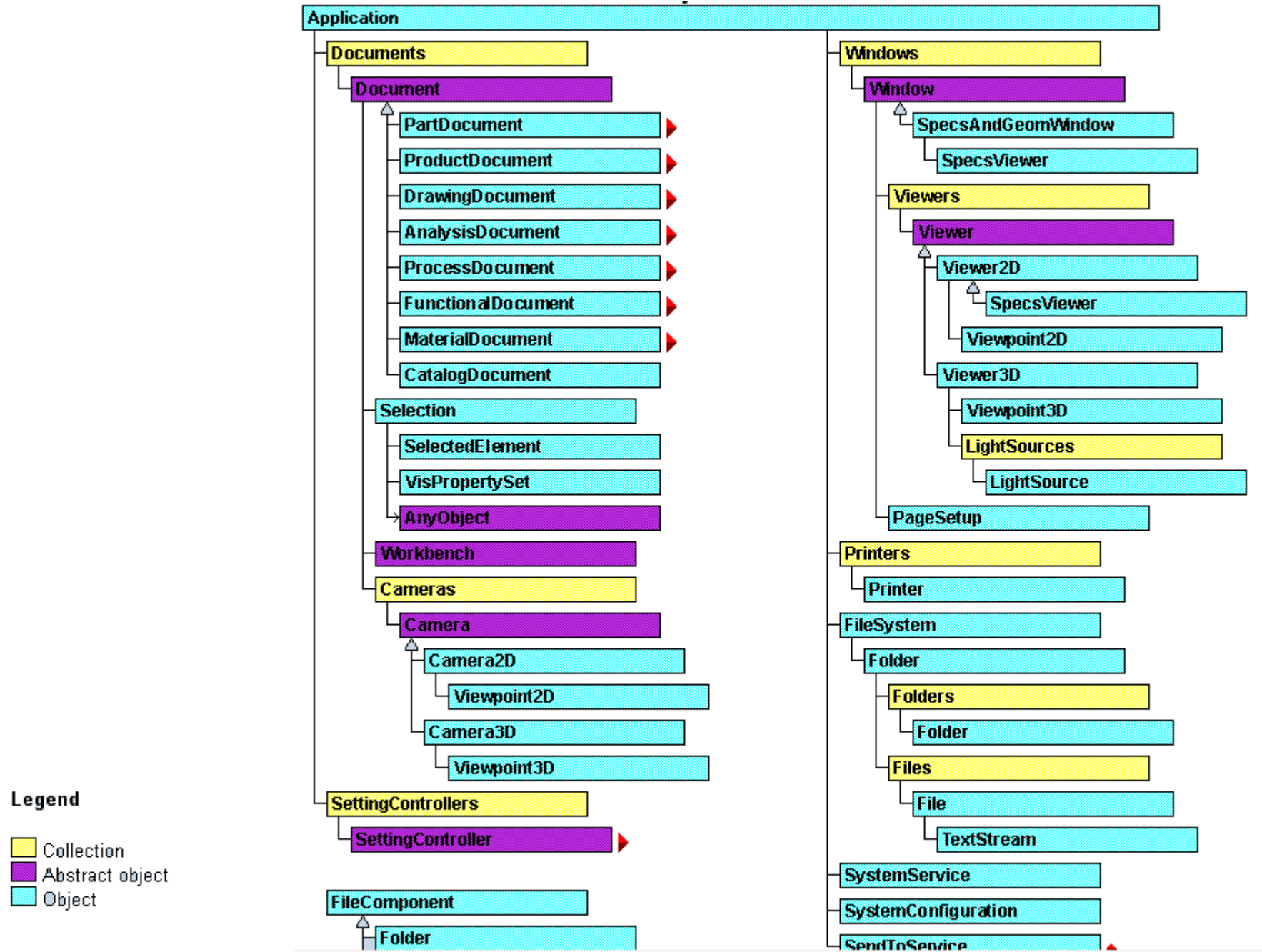
V5Automation.chm

- READ IT BEFORE writing your scripts!

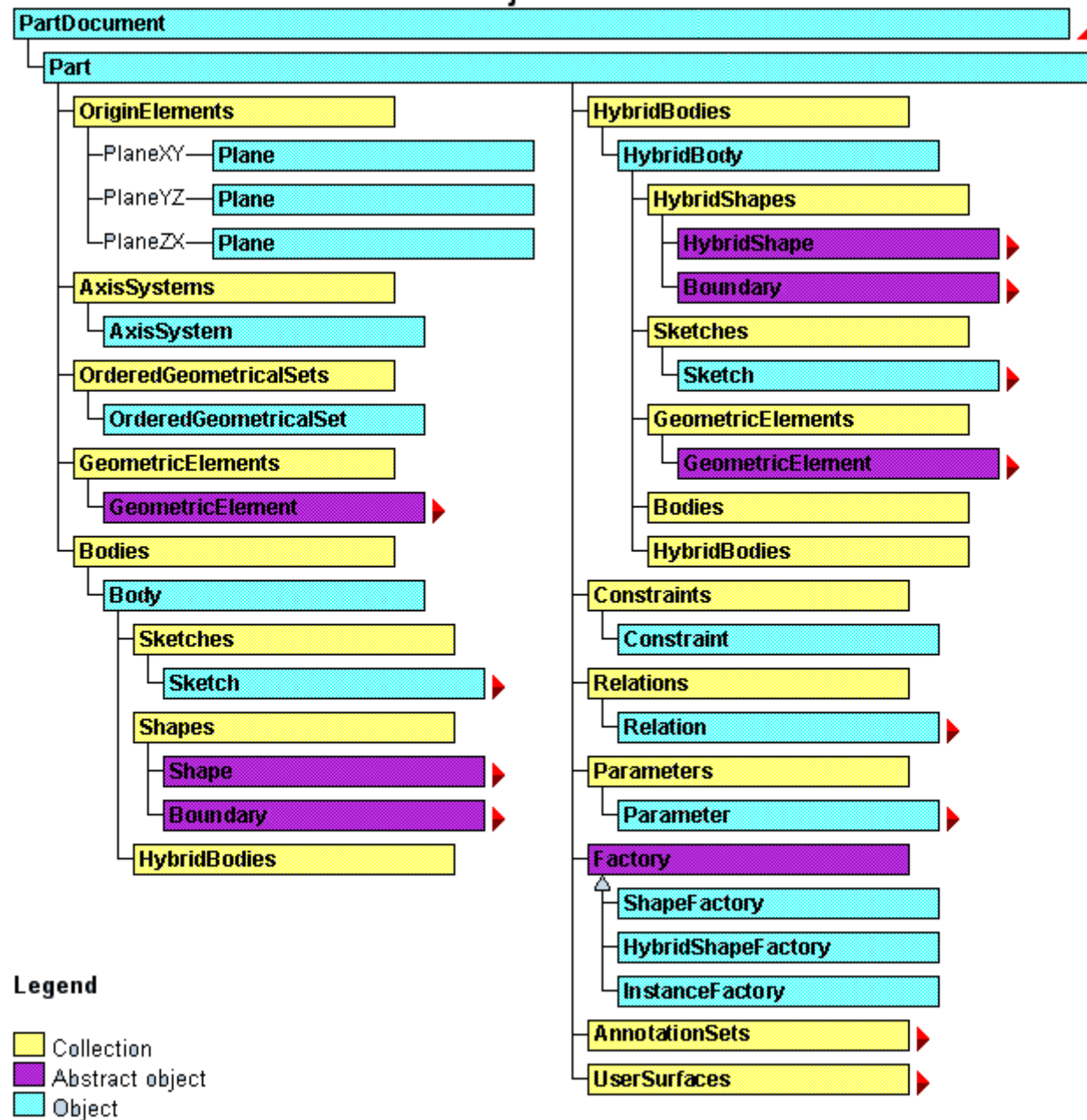
Description of CATIA objects:



Infrastructure Automation Objects:

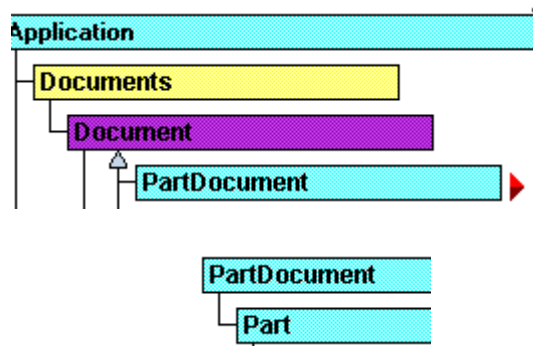


Part Document Objects:



Scripting the CATIA V5

Creating new part

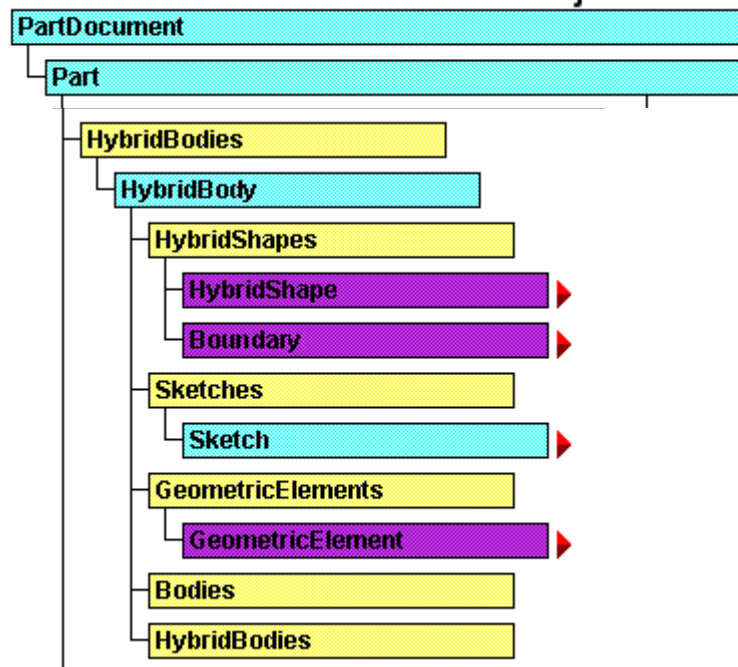


```
# Binding python session into CATIA
import win32com.client.dynamic # Module for COM-Client
CATIA = win32com.client.Dispatch("CATIA.Application")
```

```
# CATIA object for managing documents
documents1 = CATIA.Documents
```

```
# Starting new part
partDocument1 = documents1.Add("Part")
part1 = partDocument1.Part
```

Creating new body



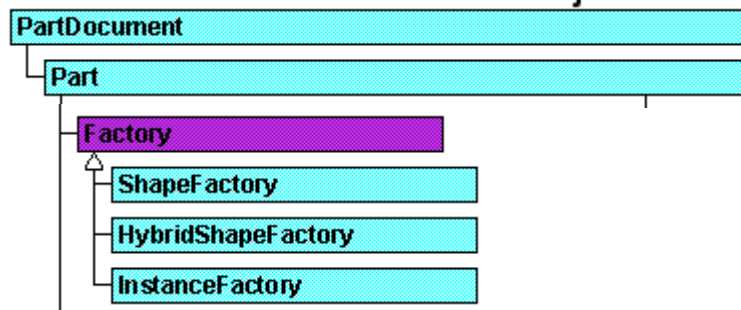
```
# Starting new body (geometrical set) in part1
bodies1 = part1.HybridBodies
```

```
# Adding new body to part1
body1 = bodies1.Add()
```

```
# Naming new body as "wireframe"
body1.Name="Wireframe"
```


Starting new shape factory

Interface to create all kinds of HybridShape objects that may be needed in wireframe and surface design.



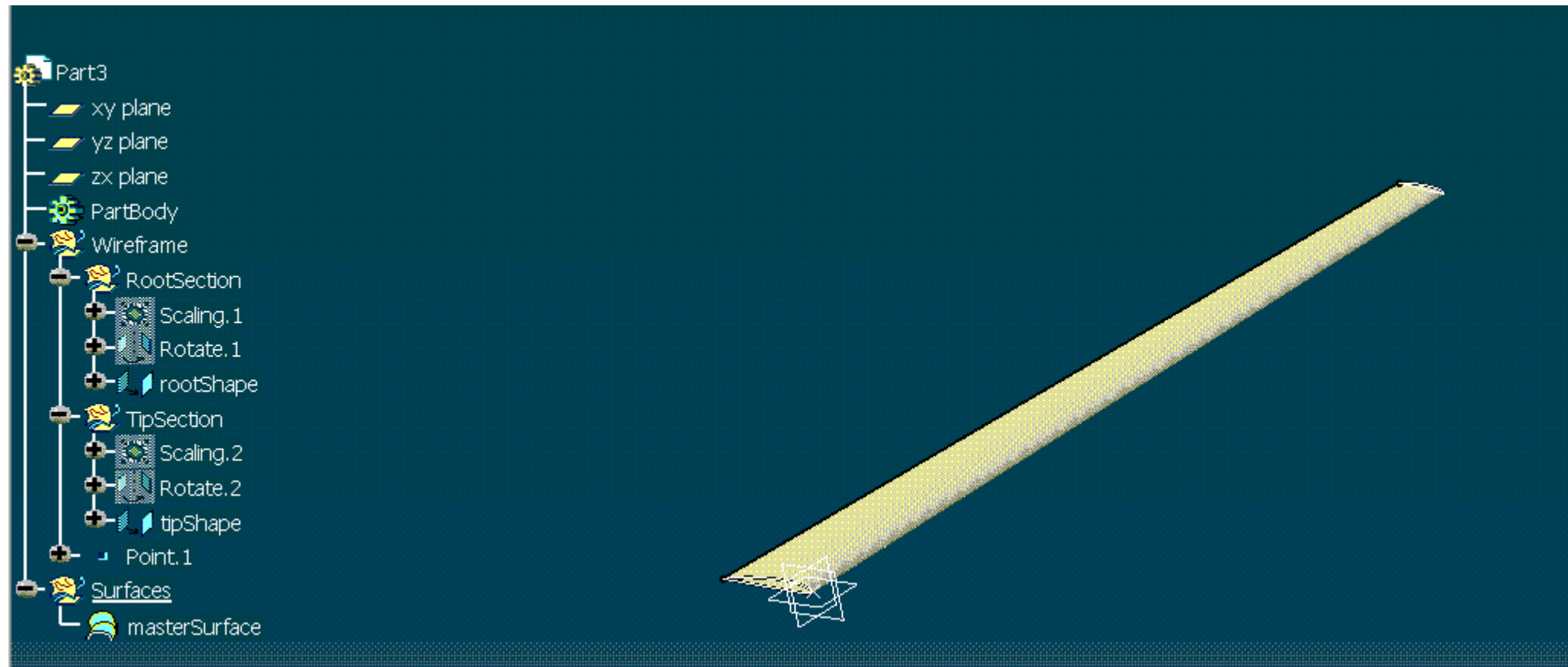
```
# Shape factory provides generating of shapes
ShFactory = part1.HybridShapeFactory
```

Using hybridShapeFactory

```
# Creating new point [0,0,0] in Wireframe
point0 = ShFactory.AddNewPointCoord(0.000000, 0.000000, 0.000000)
body1.AppendHybridShape(point0)

# part1 should be updated after every new object
part1.Update()
```

Example1: System model of tapered wing



Actions are the same as in interactive session !

Scripting the CATIA V5

Example1: System model of tapered wing

```
import win32com.client.dynamic      # Module for COM-Client
import sys, os                      # Module for File-Handling
import win32gui                     # Module for MessageBox
import numpy as np                  # Module for numerical computing

# Some basic geometrical data
halfSpan=1000.0
rootLength=100.0
tipLength=50.0
rootTwist=0.0
tipTwist=5.0

# Binding python session into CATIA
CATIA = win32com.client.Dispatch("CATIA.Application")
documents1 = CATIA.Documents        # CATIA object for managing documents
partDocument1 = documents1.Add("Part") # Starting new part
part1 = partDocument1.Part

#Shape factory provides generating of shapes
ShFactory = part1.HybridShapeFactory
# Starting new body (geometrical set) in part1
bodies1 = part1.HybridBodies
# Adding new body to part1
body1 = bodies1.Add()
# Naming new body as "wireframe"
body1.Name="Wireframe"
```

Scripting the CATIA V5

Example1: System model of tapered wing

```
bodies2 = body1.hybridBodies          # Starting new geometrical set in Wireframe
body2 = bodies2.Add()                # Adding new body to Wireframe
body2.Name="RootSection"             # Naming new body as "RootSection"
body3 = bodies2.Add()
body3.Name="TipSection"

body4 = bodies1.Add()                # Adding new body in part1
body4.Name="Surfaces"               # Naming new body as "Surfaces"

# Loading point coordinated from text file
RootAirfoil=np.loadtxt('data/clarky.dat',skiprows=1)
TipAirfoil=np.loadtxt('data/clarky.dat',skiprows=1)

# Creating new point [0,0,0] in Wireframe
point0 = ShFactory.AddNewPointCoord(0.000000, 0.000000, 0.000000)
body1.AppendHybridShape(point0)
# part1 should be updated after every new object
part1.Update()

#Creatinging Z-direction for translating wing sections
wingAxis1= ShFactory.AddNewDirectionByCoord(0.000000, 0.000000, 1.000000)

#Creating twist point, sections will be twisted around this point
twistPoint1=ShFactory.AddNewPointCoord(25.0,0.0,0.0)
twistRef1= part1.CreateReferenceFromObject(twistPoint1)
```

Scripting the CATIA V5

Example1: System model of tapered wing

```
#Creating Z-direction for translating wing sections
twistDir1 = ShFactory.AddNewDirectionByCoord(0.000000, 0.000000, 1.000000)
#Creating [POINT-DIRECTION] axis for twisting wing sections
twistAxis1 = ShFactory.AddNewLinePtDir(twistRef1, twistDir1, 0.000000, 20.000000,
False)

# Starting new spline for root section
spline1 = ShFactory.AddNewSpline()
spline1.SetSplineType(0)
spline1.SetClosing(0)
# Filling the spline with points
for i in range(0,len(RootAirfoil)):
    PT=RootAirfoil[i]*100      # coordinates are 0..1 which is too small for CATIA
    point=ShFactory.AddNewPointCoord(PT[0],PT[1],0.0)# coordinates are 2D, Z=0.0
    spline1.AddPoint(point)    # new point to spline is added
ShFactory.GSMVisibility(spline1,0)    # hide the spline
```

Example1: System model of tapered wing

```
# Starting new spline for tip section
spline2 = ShFactory.AddNewSpline()
spline2.SetSplineType(0)
spline2.SetClosing(0)
# Filling the spline with points
for i in range(0,len(TipAirfoil)):
    PT=TipAirfoil[i]*100
    point=ShFactory.AddNewPointCoord(PT[0],PT[1],0.0)
    spline2.AddPoint(point)
ShFactory.GSMVisibility(spline2,0)
```

Example1: System model of tapered wing

```
#Scale [REFERENCE POINT - RATIO] the root section
ref1 = part1.CreateReferenceFromObject(spline1)
ref2 = part1.CreateReferenceFromObject(twistPoint1)
scaling1 = ShFactory.AddNewHybridScaling(ref1,ref2, rootLength/100.0)
scaling1.VolumeResult = False
body2.AppendHybridShape(scaling1)
ShFactory.GSMVisibility(scaling1,0)
```

```
#Rotate [AXIS] the root section
rotatel= ShFactory.AddNewEmptyRotate()
ref1= part1.CreateReferenceFromObject(scaling1)
ref2 = part1.CreateReferenceFromObject(twistAxis1)
rotatel.ElemToRotate = ref1
rotatel.VolumeResult = False
rotatel.RotationType = 0
rotatel.Axis = twistAxis1
rotatel.AngleValue = rootTwist
body2.AppendHybridShape(rotatel)
ShFactory.GSMVisibility(rotatel,0)
```

Example1: System model of tapered wing

```
#Translate [DIRECTION - DISTANCE] the root section
# is actually not necessary here
translate1 = ShFactory.AddNewEmptyTranslate()
ref1= part1.CreateReferenceFromObject(rotate1)
translate1.ElemToTranslate = rotate1
translate1.VectorType = 0
translate1.Direction = wingAxis1
translate1.DistanceValue = 0.00
translate1.VolumeResult = False
translate1.Name="rootShape"    # Naming result "rootShape" IMPORTANT!!!
body2.AppendHybridShape(translate1)
```

Create the tip section yourself

Example1: System model of tapered wing

```
#Create new loft - MULTISECTION SURFACE
loft1 = ShFactory.AddNewLoft()
loft1.SectionCoupling = 1
loft1.Relimitation = 1
loft1.CanonicalDetection = 2

#Adding root section to the loft
shapes1 = body2.HybridShapes
# getting item from pool!!
result1 = shapes1.Item("rootShape")
ref1 = part1.CreateReferenceFromObject(result1)
ref2 = None
loft1.AddSectionToLoft(ref1, 1, ref2)

#Adding tip section to the loft
shapes2 = body3.HybridShapes
# getting item from pool!!
result2 = shapes2.Item("tipShape")
ref1 = part1.CreateReferenceFromObject(result2)
ref2 = None
loft1.AddSectionToLoft(ref1, 1, ref2)
loft1.Name="masterSurface"

#Adding loft to Surfaces geometrical set
body4.AppendHybridShape(loft1)
part1.Update()
```