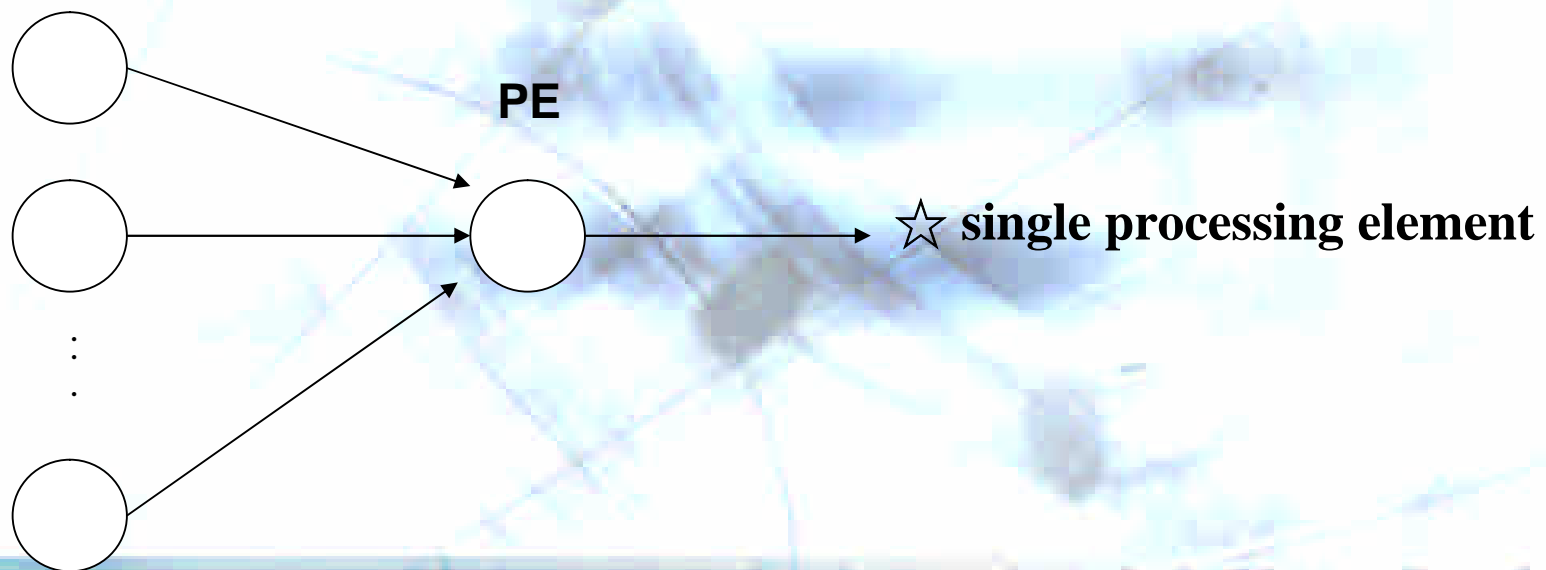


Outline

- **ADALINE**
- **MADALINE**
- **Least-Square Learning Rule**
- **The proof of Least-Square Learning Rule**

ADALINE (1/3)

- ADALINE: (Adaptive Linear Neuron) 1959 by Bernard Widrow



ADALINE (2/3)

- Method :① The value in each unit must +1 or -1
(perceptron 爲1)

- $\text{net} = \sum X_i W_i$

$$X_0 = 1 \therefore \text{net} = W_0 + W_1 X_1 + W_2 X_2 + \cdots + W_n X_n$$

$$Y = \begin{cases} 1 & \text{net} \geq 0 \\ -1 & \text{if net} < 0 \end{cases}$$

different from perceptron's transfer function

ADALINE (3/3)

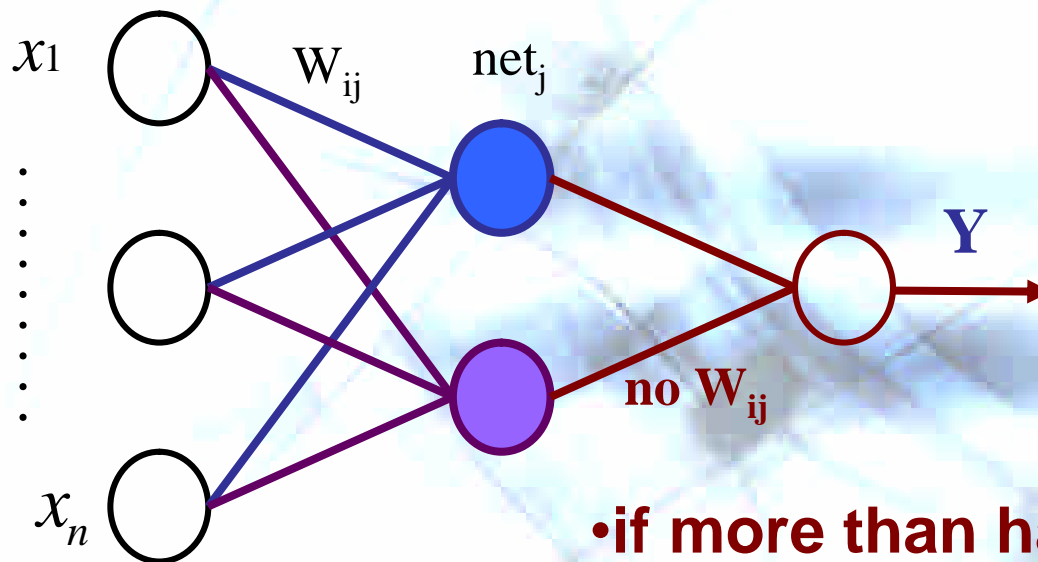
$$\Delta W_i = \eta (T - Y) X_i, \quad T = \text{expected output}$$

$$W_i = W_i + \Delta W_i$$

□ ADALINE can solve only linear problem(the limitation)

MADALINE

- MADALINE : It is composed of many ADALINE (Multilayer Adaline.)



•if more than half of $net_j \geq 0$, then output $+1$, otherwise, output -1

•After the second layer, the majority vote is used.

Least-Square Learning Rule (1/6)

- $X_j = (x_0, x_1, \dots, x_n)^t$, (i.e. $X_j = \begin{pmatrix} x_0 \\ x_1 \\ \vdots \\ x_n \end{pmatrix}$) $1 \leq j \leq L$

字母小寫 j : 代表第 j 組 input pattern

t : 代表向量轉置 (transpose)

L : 代表 input pattern 數量

- $W = (w_0, w_1, \dots, w_n)^t$, (i.e. $W = \begin{pmatrix} w_0 \\ w_1 \\ \vdots \\ w_n \end{pmatrix}$)

$$Net_j = W^t X_j = \sum_{i=0}^n w_i x_i = w_0 x_0 + w_1 x_1 + \dots + w_n x_n$$

Least-Square Learning Rule (2/6)

- By applying the least-square learning rule the weights is :

$$\begin{aligned} RW^* &= P \\ W^* &= R^{-1}P \quad \text{where} \left\{ \begin{array}{l} R: \text{Correlation Matrix} \\ R = \frac{R'}{L}, R' = R'_1 + R'_2 + \dots + R'_L = \sum_{j=1}^L X_j X_j^t \\ P^t = \frac{T X_j^t}{L} \end{array} \right. \end{aligned}$$

Least-Square Learning Rule (3/6)

Example : $X_1 = \begin{pmatrix} 1 \\ 1 \\ 0 \end{pmatrix}$ $X_2 = \begin{pmatrix} 1 \\ 0 \\ 1 \end{pmatrix}$ $X_3 = \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix}$

$T_1=1$ $T_2=1$ $T_3=-1$

	X_1	X_2	X_3	T_j
X_1	1	1	0	1
X_2	1	0	1	1
X_3	1	1	1	-1

Least-Square Learning Rule (4/6)

- Sol. 先算R

$$\left. \begin{aligned} R_1' &= \begin{pmatrix} 1 \\ 1 \\ 0 \end{pmatrix} (110) = \begin{pmatrix} 1 & 1 & 0 \\ 1 & 1 & 0 \\ 0 & 0 & 0 \end{pmatrix} \\ R_2' &= \begin{pmatrix} 1 \\ 0 \\ 1 \end{pmatrix} (101) = \begin{pmatrix} 1 & 0 & 1 \\ 0 & 0 & 0 \\ 1 & 0 & 1 \end{pmatrix} \\ R_3' &= \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix} (111) = \begin{pmatrix} 1 & 1 & 1 \\ 1 & 1 & 1 \\ 1 & 1 & 1 \end{pmatrix} \end{aligned} \right\} R = \frac{1}{3} \begin{pmatrix} 3 & 2 & 2 \\ 2 & 2 & 1 \\ 2 & 1 & 2 \end{pmatrix} \Rightarrow \begin{pmatrix} 1 & 2/3 & 2/3 \\ 2/3 & 2/3 & 1/3 \\ 2/3 & 1/3 & 2/3 \end{pmatrix}$$

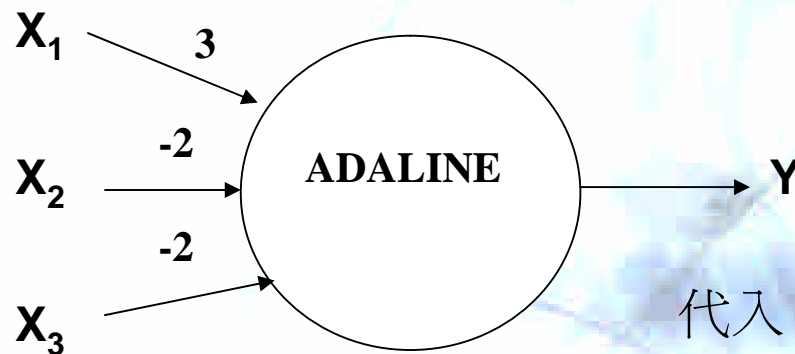
Least-Square Learning Rule (5/6)

$$\left. \begin{aligned} P_1^t &= 1 \cdot (1,1,0) = (1,1,0) \\ P_2^t &= 1 \cdot (1,0,1) = (1,0,1) \\ P_3^t &= -1 \cdot (1,1,1) = (-1,-1,-1) \end{aligned} \right\} P^t = \frac{1}{3}(1,0,0) = \left(\frac{1}{3}, 0, 0\right)$$

$$R \cdot W^* = P \Rightarrow \begin{pmatrix} 1 & 2/3 & 2/3 \\ 2/3 & 2/3 & 1/3 \\ 2/3 & 1/3 & 2/3 \end{pmatrix} \begin{pmatrix} W_1 \\ W_2 \\ W_3 \end{pmatrix} = \begin{pmatrix} 1/3 \\ 0 \\ 0 \end{pmatrix} \Rightarrow \begin{cases} 3W_1 + 2W_2 + 2W_3 = 1 \\ 2W_1 + 2W_2 + W_3 = 0 \\ 2W_1 + W_2 + 2W_3 = 0 \end{cases} \Rightarrow \begin{cases} W_1 = 3 \\ W_2 = -2 \\ W_3 = -2 \end{cases}$$

Least-Square Learning Rule (6/6)

- Verify the net:



代入 (1,1,0) $\text{net}=3X_1-2X_2-2X_3=1$ $Y=1$ ok

代入 (1,0,1) $\text{net}=3X_1-2X_2-2X_3=1$ $Y=1$ ok

代入 (1,1,1) $\text{net}=3X_1-2X_2-2X_3=-1$ $Y=-1$ ok

$\langle \varepsilon_k^2 \rangle = 0$ this is minimum \implies best solution

(*)同學回家應了解反矩陣的計算方法

Proof of Least Square Learning Rule(1/3)

- We use Least Mean Square Error to ensure the minimum total error. As long as the total error approaches zero, the best solution is found. Therefore, we are looking for the minimum of $\langle \varepsilon_k^2 \rangle$.
- Proof:

$$\begin{aligned}\text{mean} \rightarrow \langle \varepsilon^2 \rangle &= \frac{1}{L} \sum_{k=1}^L \varepsilon_k^2 = \frac{1}{L} \sum_{k=1}^L (T_k - Y_k)^2 = \frac{1}{L} \sum_{k=1}^L (T_k^2 - 2T_k Y_k + Y_k^2) \\ &= \frac{1}{L} \sum_{k=1}^L T_k^2 - \frac{2}{L} \sum_{k=1}^L T_k Y_k + \frac{1}{L} \sum_{k=1}^L Y_k^2 \text{ let } \langle T_k^2 \rangle \text{ represents mean} \\ &= \langle T_k^2 \rangle - \frac{2}{L} \sum_{k=1}^L T_k Y_k + \frac{1}{L} \cdot [W^t (\sum_{k=1}^L X_k X_k^t) W]\end{aligned}$$

Proof of Least Square Learning Rule(2/3)

$$\begin{aligned} ps &:= \sum_{k=1}^L Y_k^2 = \sum_{k=1}^L \left(\sum_{i=1}^n w_i x_{ik} \right)^2 = \sum_{k=1}^L (W^t X_k)^2 = \sum_{k=1}^L (W^t X_k)(X_k^t W) \\ &= W^t \left(\sum_{k=1}^L X_k \cdot X_k^t \right) \cdot W \end{aligned}$$

承上頁

$$\begin{aligned} &= \langle T_k^2 \rangle - \frac{2}{L} \sum_{k=1}^L T_k Y_k + W^t \left[\frac{1}{L} \left(\sum_{k=1}^L X_k X_k^t \right) \right] W \\ &= \langle T_k^2 \rangle - \frac{2}{L} \sum_{k=1}^L T_k (W^t X_k) + W^t \langle X_k X_k^t \rangle W \\ &= \langle T_k^2 \rangle - 2 \left[\frac{1}{L} \sum_{k=1}^L (T_k X_k^t) W \right] + W^t \langle X_k X_k^t \rangle W \\ &= \langle T_k^2 \rangle - 2 \langle T_k X_k^t \rangle W + W^t \langle X_k X_k^t \rangle W \end{aligned}$$

令此項為R

Proof of Least Square Learning Rule(3/3)

* Let $R_k = X_k X_k^t$, i.e., R_k is a $n \times n$ matrix, also called Correlation Matrix.

* Let $R' = R_1 + R_2 + \dots + R_K + \dots + R_L = \sum_{k=1}^L T_k X_k^t$

* Let $R = R'/L$ (i.e. mean of R') $\Rightarrow R = \langle X_k X_k^t \rangle$

承上頁

$$= \langle T_k^2 \rangle - 2 \langle T_k X_k^t \rangle W + W^t R W$$

★ Find W^* such that $\langle \varepsilon_k^2 \rangle$ is minimal

$$\frac{\partial \langle \varepsilon_k^2 \rangle}{\partial W} = [\langle T_k^2 \rangle - 2 \langle T_k X_k^t \rangle W + W^t R W]$$

$$= -2 \langle T_k X_k \rangle + 2 R W = 2 R W - 2 P \quad \text{Let } P = \langle T_k X_k^t \rangle$$

$$\text{if } \frac{\partial \langle \varepsilon_k^2 \rangle}{\partial W} = 0 \Rightarrow 2 R W^* - 2 P = 0 \text{ 即 } W^* = R^{-1} P \text{ 或 } R W^* = P$$