

```
graph BT; A["/home/travis/build  
/Autonomous-Racing-PG  
/ros.package/docs/master  
/ros_ws/src/navigation_stack  
/msgs_converter/include/navigation_stack_control_converter.h"] <--> B["/home/travis/build  
/Autonomous-Racing-PG  
/ros.package/docs/master  
/ros_ws/src/navigation_stack  
/msgs_converter/src/main.cpp"]; A <--> C["/home/travis/build  
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/ros_ws/src/navigation_stack  
/msgs_converter/src/navigation_stack_control_converter.cpp"];
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