

A diagram consisting of two rectangular boxes. The bottom box is white with a black border and contains a file path. The top box is gray with a black border and contains a modified file path. A blue arrow points from the bottom box to the top box, indicating a transformation or relationship between the two paths.

```
/home/travis/build  
/Autonomous-Racing-PG  
/ros.package/docs/master  
/ros_ws/src/teleoperation  
/include/remote_keyboard.h
```

```
/home/travis/build  
/Autonomous-Racing-PG  
/ros.package/docs/master  
/ros_ws/src/teleoperation  
/src/remote_keyboard.cpp
```