

/home/travis/build  
/Autonomous-Racing-PG  
/ros.package/docs/master  
/ros\_ws/src/navigation\_stack  
/navigation\_stack\_control\_converter  
/src/main.cpp

```
graph TD; A["/home/travis/build  
/Autonomous-Racing-PG  
/ros.package/docs/master  
/ros_ws/src/navigation_stack  
/navigation_stack_control_converter  
/src/main.cpp"] --> B["navigation_stack_control  
_converter.h"]; B --> C["ros/ros.h"]; B --> D["drive_msgs/drive_param.h"]; B --> E["geometry_msgs/Twist.h"];
```

navigation\_stack\_control  
\_converter.h

ros/ros.h

drive\_msgs/drive\_param.h

geometry\_msgs/Twist.h