

```
graph BT; A["/home/travis/build  
/Autonomous-Racing-PG  
/ros.package/docs/master  
/ros_ws/src/autonomous/emergency  
_stop/include/rviz_geometry_publisher.h"] --> B["/home/travis/build  
/Autonomous-Racing-PG  
/ros.package/docs/master  
/ros_ws/src/autonomous/emergency  
_stop/include/emergency_stop.h"]; B --> C["/home/travis/build  
/Autonomous-Racing-PG  
/ros.package/docs/master  
/ros_ws/src/autonomous/emergency  
_stop/src/emergency_stop.cpp"]
```

/home/travis/build
/Autonomous-Racing-PG
/ros.package/docs/master
/ros_ws/src/autonomous/emergency
_stop/include/rviz_geometry_publisher.h

/home/travis/build
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/ros.package/docs/master
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_stop/include/emergency_stop.h

/home/travis/build
/Autonomous-Racing-PG
/ros.package/docs/master
/ros_ws/src/autonomous/emergency
_stop/src/emergency_stop.cpp