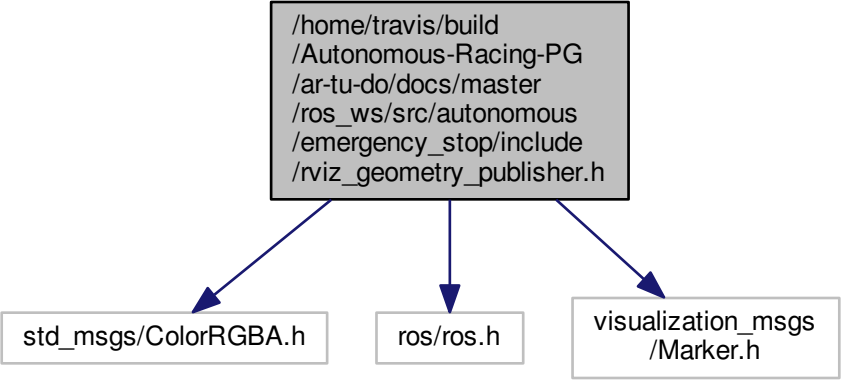


/home/travis/build
/Autonomous-Racing-PG
/ar-tu-do/docs/master
/ros_ws/src/autonomous
/emergency_stop/include
/rviz_geometry_publisher.h



```
graph TD; A["/home/travis/build<br/>/Autonomous-Racing-PG<br/>/ar-tu-do/docs/master<br/>/ros_ws/src/autonomous<br/>/emergency_stop/include<br/>/rviz_geometry_publisher.h"] --> B["std_msgs/ColorRGBA.h"]; A --> C["ros/ros.h"]; A --> D["visualization_msgs<br/>/Marker.h"]
```

std_msgs/ColorRGBA.h

ros/ros.h

visualization_msgs
/Marker.h