

/home/travis/build
/Autonomous-Racing-PG
/ros.package/ros_ws/src
/auto_race_pg/src/remote
_joy.cpp

```
graph TD; A["/home/travis/build  
/Autonomous-Racing-PG  
/ros.package/ros_ws/src  
/auto_race_pg/src/remote_joy.cpp"] --> B["ros/ros.h"]; A --> C["sensor_msgs/Joy.h"]; A --> D["std_msgs/Float64.h"];
```

ros/ros.h

sensor_msgs/Joy.h

std_msgs/Float64.h