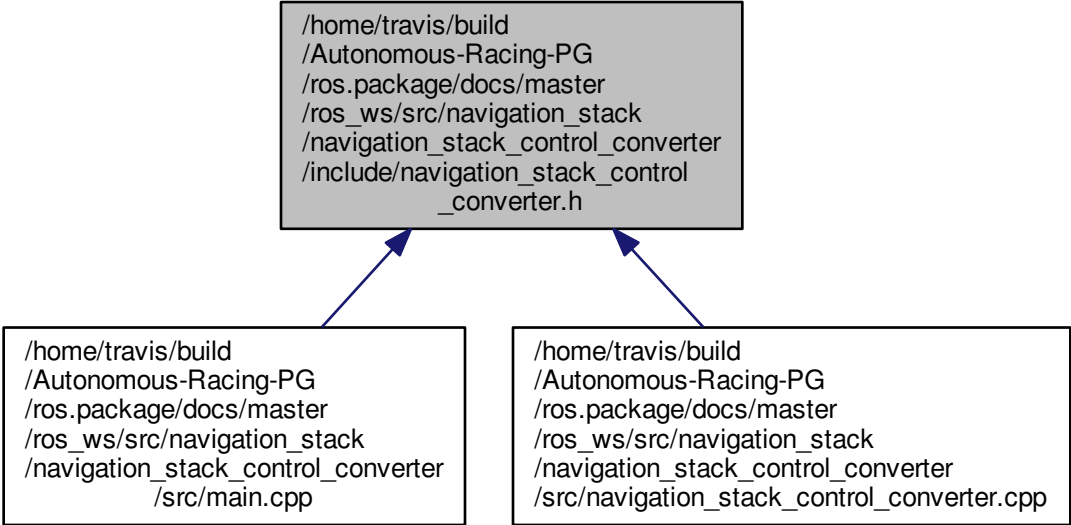


/home/travis/build
/Autonomous-Racing-PG
/ros.package/docs/master
/ros_ws/src/navigation_stack
/navigation_stack_control_converter
/include/navigation_stack_control
_converter.h



/home/travis/build
/Autonomous-Racing-PG
/ros.package/docs/master
/ros_ws/src/navigation_stack
/navigation_stack_control_converter
/src/main.cpp

/home/travis/build
/Autonomous-Racing-PG
/ros.package/docs/master
/ros_ws/src/navigation_stack
/navigation_stack_control_converter
/src/navigation_stack_control_converter.cpp