

A diagram consisting of two rectangular boxes. The bottom box is white with a black border and contains a list of file paths. The top box is gray with a black border and contains a similar list of file paths. A blue arrow points from the bottom box to the top box, indicating a transformation or relationship between the two sets of paths.

```
/home/travis/build  
/Autonomous-Racing-PG  
/ros.package/docs/master  
/ros_ws/src/car_control  
/include/drive_parameters  
_multiplexer.h
```

```
/home/travis/build  
/Autonomous-Racing-PG  
/ros.package/docs/master  
/ros_ws/src/car_control  
/src/drive_parameters_multiplexer.cpp
```