

```
graph BT; A["/home/travis/build  
/Autonomous-Racing-PG  
/ros.package/docs/master  
/ros_ws/src/simulation/vesc  
_sim/src/main.cpp"] --> B["/home/travis/build  
/Autonomous-Racing-PG  
/ros.package/docs/master  
/ros_ws/src/simulation/vesc  
_sim/include/vesc_sim_driver.h"]; C["/home/travis/build  
/Autonomous-Racing-PG  
/ros.package/docs/master  
/ros_ws/src/simulation/vesc  
_sim/src/vesc_sim_driver.cpp"] --> B;
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