

/home/travis/build  
/Autonomous-Racing-PG  
/ros.package/docs/master  
/ros\_ws/src/teleoperation  
/include/joystick\_controller.h

```
graph TD; A["/home/travis/build<br/>/Autonomous-Racing-PG<br/>/ros.package/docs/master<br/>/ros_ws/src/teleoperation<br/>/include/joystick_controller.h"] --> B["ros/ros.h"]; A --> C["chrono"]; A --> D["drive_msgs/drive_param.h"]; A --> E["sensor_msgs/Joy.h"];
```

ros/ros.h

chrono

drive\_msgs/drive\_param.h

sensor\_msgs/Joy.h