

/home/travis/build  
/Autonomous-Racing-PG  
/ar-tu-do/docs/master  
/ros\_ws/src/simulation  
/vesc\_sim/include/vesc\_sim.h

```
graph TD; A["/home/travis/build  
/Autonomous-Racing-PG  
/ar-tu-do/docs/master  
/ros_ws/src/simulation  
/vesc_sim/include/vesc_sim.h"] --> B["ros/ros.h"]; A --> C["string"]; A --> D["tf/transform_broadcaster.h"];
```

The diagram illustrates the file paths and dependencies for a project. A central box lists five paths, with the last one, `/vesc_sim/include/vesc_sim.h`, being the source file. Three arrows point from this source file to three other boxes below it, representing the files it includes: `ros/ros.h`, `string`, and `tf/transform_broadcaster.h`.

ros/ros.h

string

tf/transform\_broadcaster.h