

/home/travis/build  
/Autonomous-Racing-PG  
/ros.package/ros\_ws/src  
/auto\_race\_pg/src/talker.cpp

```
graph TD; A["/home/travis/build<br/>/Autonomous-Racing-PG<br/>/ros.package/ros_ws/src<br/>/auto_race_pg/src/talker.cpp"] --> B["ros/ros.h"]; A --> C["std_msgs/String.h"]; A --> D["sstream"];
```

ros/ros.h

std\_msgs/String.h

sstream