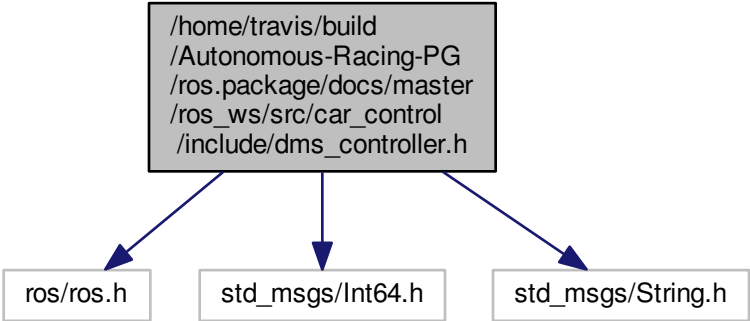


/home/travis/build
/Autonomous-Racing-PG
/ros.package/docs/master
/ros_ws/src/car_control
/include/dms_controller.h



```
graph TD; A["/home/travis/build  
/Autonomous-Racing-PG  
/ros.package/docs/master  
/ros_ws/src/car_control  
/include/dms_controller.h"] --> B["ros/ros.h"]; A --> C["std_msgs/Int64.h"]; A --> D["std_msgs/String.h"];
```

ros/ros.h

std_msgs/Int64.h

std_msgs/String.h