

```
/home/travis/build  
/Autonomous-Racing-PG  
/ar-tu-do/docs/master  
/ros_ws/src/navigation  
_stack/navigation_stack  
_control_converter/src/main.cpp
```

```
graph TD; A["/home/travis/build  
/Autonomous-Racing-PG  
/ar-tu-do/docs/master  
/ros_ws/src/navigation_stack/navigation_stack_control_converter/src/main.cpp"] --> B[navigation_stack_control_converter.h]; B --> C[ros/ros.h]; B --> D[drive_msgs/drive_param.h]; B --> E[geometry_msgs/Twist.h];
```

The diagram illustrates the compilation of a C++ source file into a header file. The source file, located at `/home/travis/build/Autonomous-Racing-PG/ar-tu-do/docs/master/ros_ws/src/navigation_stack/navigation_stack_control_converter/src/main.cpp`, is compiled into `navigation_stack_control_converter.h`. This header file then includes three other headers: `ros/ros.h`, `drive_msgs/drive_param.h`, and `geometry_msgs/Twist.h`.

`navigation_stack_control
_converter.h`

`ros/ros.h`

`drive_msgs/drive_param.h`

`geometry_msgs/Twist.h`