

/home/travis/build  
/Autonomous-Racing-PG  
/ros.package/docs/master  
/ros\_ws/src/auto\_race\_pg  
/src/talker.cpp

```
graph TD; A["/home/travis/build  
/Autonomous-Racing-PG  
/ros.package/docs/master  
/ros_ws/src/auto_race_pg  
/src/talker.cpp"] --> B["ros/ros.h"]; A --> C["std_msgs/String.h"]; A --> D["sstream"];
```

ros/ros.h

std\_msgs/String.h

sstream