

/home/travis/build
/Autonomous-Racing-PG
/ros.package/docs/master
/ros_ws/src/autonomous/emergency
_stop/include/rviz_geometry_publisher.h

```
graph TD; A["/home/travis/build  
/Autonomous-Racing-PG  
/ros.package/docs/master  
/ros_ws/src/autonomous/emergency  
_stop/include/rviz_geometry_publisher.h"] --> B["std_msgs/ColorRGBA.h"]; A --> C["ros/ros.h"]; A --> D["visualization_msgs  
/Marker.h"];
```

std_msgs/ColorRGBA.h

ros/ros.h

visualization_msgs
/Marker.h