

```
graph BT; A["/home/travis/build  
/Autonomous-Racing-PG  
/ros.package/docs/master  
/ros_ws/src/car_control  
/include/car_control.h"]; B["/home/travis/build  
/Autonomous-Racing-PG  
/ros.package/docs/master  
/ros_ws/src/car_control  
/src/car_controller.cpp"]; C["/home/travis/build  
/Autonomous-Racing-PG  
/ros.package/docs/master  
/ros_ws/src/car_control  
/src/dms_controller.cpp"]; B --> A; C --> A;
```

/home/travis/build
/Autonomous-Racing-PG
/ros.package/docs/master
/ros_ws/src/car_control
/include/car_control.h

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/ros.package/docs/master
/ros_ws/src/car_control
/src/car_controller.cpp

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/Autonomous-Racing-PG
/ros.package/docs/master
/ros_ws/src/car_control
/src/dms_controller.cpp