

/home/travis/build  
/Autonomous-Racing-PG  
/ros.package/docs/master  
/ros\_ws/src/autonomous/include  
/rviz\_geometry\_publisher.h

```
graph TD; A["/home/travis/build<br>/Autonomous-Racing-PG<br>/ros.package/docs/master<br>/ros_ws/src/autonomous/include<br>/rviz_geometry_publisher.h"] --> B["std_msgs/ColorRGBA.h"]; A --> C["ros/ros.h"]; A --> D["visualization_msgs<br>/Marker.h"]
```

std\_msgs/ColorRGBA.h

ros/ros.h

visualization\_msgs  
/Marker.h