

```
graph BT; A["/home/travis/build  
/Autonomous-Racing-PG  
/ros.package/docs/master  
/ros_ws/src/teleoperation  
/src/joystick_controller.cpp"] --> B["/home/travis/build  
/Autonomous-Racing-PG  
/ros.package/docs/master  
/ros_ws/src/teleoperation  
/include/joystick_controller.h"]
```

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