

/home/travis/build
/Autonomous-Racing-PG
/ros.package/docs/master
/ros_ws/src/auto_race_pg
/include/remote_joy.h

```
graph TD; A["/home/travis/build<br/>/Autonomous-Racing-PG<br/>/ros.package/docs/master<br/>/ros_ws/src/auto_race_pg<br/>/include/remote_joy.h"] --> B["ros/ros.h"]; A --> C["sensor_msgs/Joy.h"]; A --> D["std_msgs/Float64.h"];
```

ros/ros.h

sensor_msgs/Joy.h

std_msgs/Float64.h