```
Input: B = \{b_1(x_1, y_1, x_2, y_2), ..., b_N\}, S = \{s_1, ..., s_N\}, N_t, N_c
          B is the list of initial detection boxes,
          (x_1, y_1) and (x_2, y_2) are the upper-left corner and the lower-right corner
          coordinates of each b respectively
          S contains corresponding detection scores
          N_t is the NMS threshold
          N_c is the correlation threshold
begin
     D \leftarrow \{\}
     A \leftarrow \{\}
      while B \neq empty do
           m \leftarrow \operatorname{argmax} S
           M \leftarrow b_m
           D \leftarrow D \cup M; B \leftarrow B - M
            for b_i in B do
                 if iou (M, b_i) \ge N_t then
                       for b_i in B do
                             if iou (M, b_i) * s_i \ge N_c then
                               A \leftarrow A \cup b_i
                             end
                             B \leftarrow B - b_i; S \leftarrow S - s_i
                       end
                 end
                 A \leftarrow A \cup b_i
                 for a_i in A do
                       min \ x_l \leftarrow argmin \ x_l; \ max\_y_l \leftarrow argmax \ y_l;
                       max \ x_2 \leftarrow \operatorname{argmax} x_2; min \ y_2 \leftarrow \operatorname{argmin} y_2
                 end
```

 $b_i. x_1 \leftarrow min_x_1; b_i. y_1 \leftarrow max_y_1;$ $b_i. x_2 \leftarrow max x_2; b_i. y_2 \leftarrow min y_2$

end

return D, S

end

end