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# A Complementary Way of Teaching Reinforcement Learning and Decision Making

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## Abstract

Reinforcement Learning and Decision Making is a complex subject. Being the focus of research of a variety of fields including artificial intelligence, psychology, machine learning, operations research, control theory, animal and human neuroscience, economics, and ethology, it is expected that the vast amount of available information could become counterproductive. Beginners often find themselves lost while trying to grasp the key concepts that are truly vital for understanding. Additionally, reinforcement learning and decision making, being a relatively new field, is often taught by world-class researchers that frequently unintentionally omit explaining core concepts that might seem too basic, but are as well fundamental. This creates a gap of knowledge that, if left unfilled, causes trouble for learning the more advanced topics.

Fortunately, as reinforcement learning and decision making is also studied by fields like animal and human neuroscience, ethology, and psychology, often the concepts can be taught on an intuitive level. The notion of learning by interacting with the environment should be easy to understand to all of us as this is one of the ways we learn. The work described on this paper is an attempt to deliver reinforcement learning and decision making concepts using different teaching techniques that potentially promote intuitive learning. The idea is that these work would serve beginners fill the gaps of knowledge, as a 'primer' to prepare them for the more advanced and in-depth material.

**Keywords:** teaching tutorials jupyter intuition hands-on

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# 1 Introduction

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## 3 Using Intuition as a Primer

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## 4 Creating Awareness through Experimentation

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## 5 Building Knowledge through Assigned Readings

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