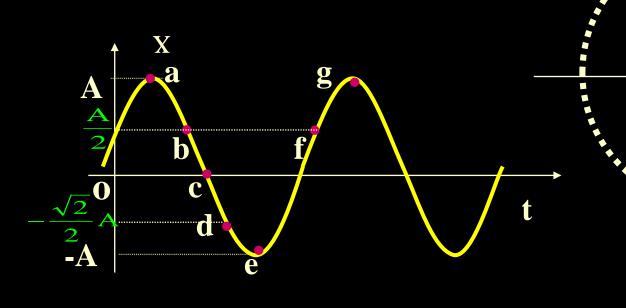


一、熟练掌握旋转矢量图法

(1) 振动的表示(2) 任意时刻的相位、



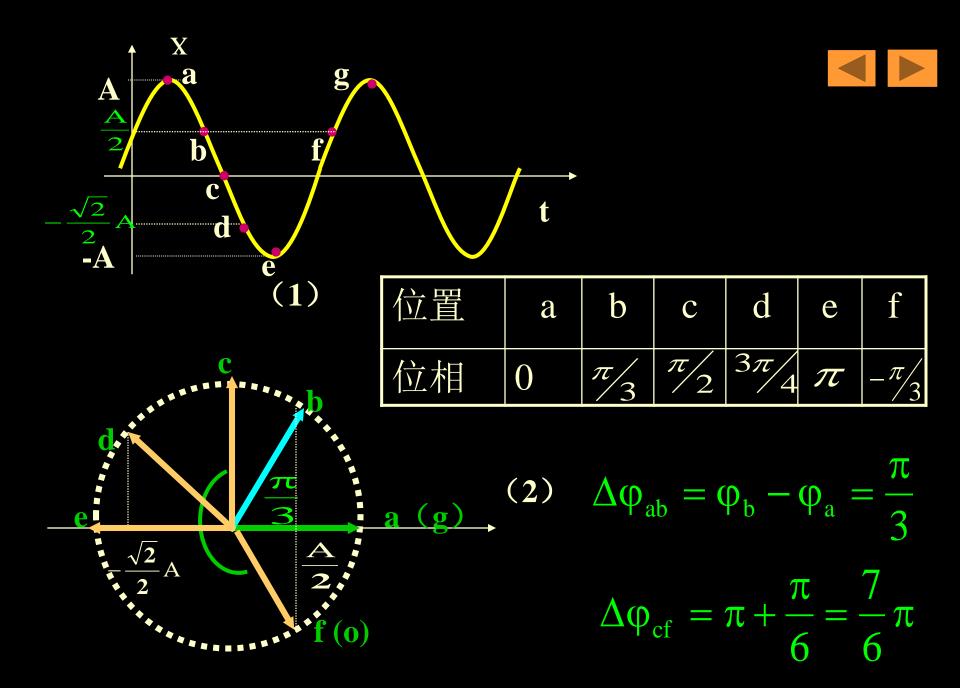


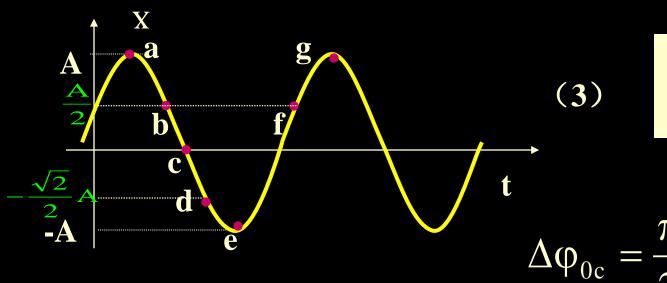
例1(1)根据振动曲线填写下表,

且在旋转矢量图上标出相应的旋转矢量位置

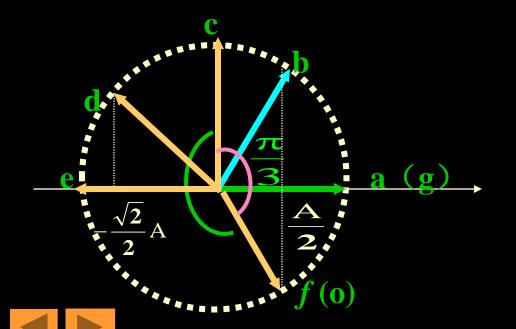
- (2) a与b的振动状态的相位差是多少? c与f?
- (3) 若 Oc = 1s ,则振动方程如何?







$$\Delta \phi_{0c} = \frac{\pi}{2} + \frac{\pi}{3} = \frac{5}{6}\pi$$



$$\omega = \frac{2\pi}{T} = \frac{\frac{5}{6}\pi}{1} = \frac{5}{6}\pi$$

$$x = A\cos(\frac{5}{6}\pi t - \frac{\pi}{3})(SI)$$

已知简谐振动的v~t曲线及T=2s,



辰动方程
$$\omega = \frac{2\pi}{T} = \pi$$

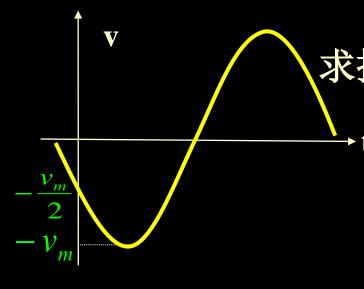
$$v_m = \omega A \Longrightarrow A = \frac{v_m}{\pi}$$

$$-\frac{v_m}{2} = -v_m \sin \alpha$$

$$\Rightarrow \sin \alpha = \frac{1}{2}$$

$$\alpha = \frac{\pi}{6}$$
 or $\alpha = \frac{5}{6}\pi$

$$x = \frac{v_m}{\pi} \cos(\pi t + \frac{\pi}{6})(SI)$$





例2、(自测练习p17 3)质量为0.25kg的物体与k=25N/m的弹簧组成弹簧振子,若初始时的动能和势能分别为0.02J和0.06J.而且物体的 $x_0>0,v_0<0$,试求: (1)物体谐振动的表达式:

- (2)物体从初位置回到平衡位置的最短时间;
- (3)物体到达平衡位置时的速度.

P(1)
$$\omega = \sqrt{\frac{k}{m}} = \sqrt{\frac{25}{0.25}} = 10s^{-1}$$

$$E = E_P + E_k = 0.08 = \frac{1}{2}kA^2 \implies A = 0.08(m)$$

$$E_{P0} = 0.06 = \frac{1}{2}kx_0^2 \implies x_0 = \frac{\sqrt{3}}{2}A \implies \alpha = \frac{\pi}{6}$$

$$x = 0.08\cos(10t + \frac{\pi}{6})(SI)$$

(2)
$$\frac{2\pi}{T} = \frac{\Delta\varphi}{\Delta t}$$
 $\Rightarrow \Delta t = \frac{\Delta\varphi}{\omega} = \frac{\frac{\pi}{3}}{10}$ $\frac{\pi}{3}$ $\frac{\sqrt{3}A}{2}$ $\frac{\sqrt{3}A}{2}$ $\frac{\sqrt{3}A}{2}$ $\frac{\sqrt{3}A}{2}$ $\frac{\pi}{2}$ $\frac{\pi$

$$cos(10t + \frac{\pi}{6}) = 0 \Rightarrow 10t + \frac{\pi}{6} = (2k+1)\frac{\pi}{2}$$

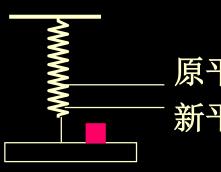
取 $\mathbf{k}=\mathbf{0} \implies t$

(3)
$$v = \frac{dx}{dt} = -0.08 \sin(10t + \frac{\pi}{6}) \times 10$$

= $-0.08 \sin(\frac{\pi}{2}) \times 10 = -0.8 m/s$

练习: 自测练习 p13 1、3

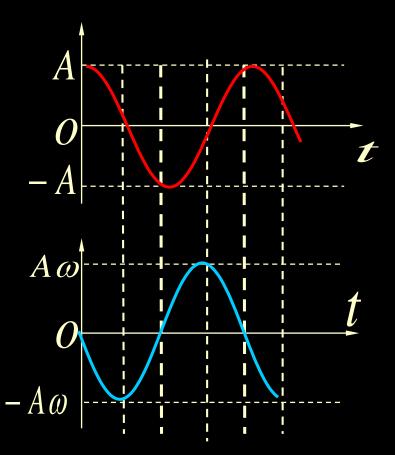




原平衡位置 新平衡位置



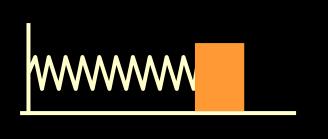
$$\varphi \sim \frac{3}{2}\pi \sim 2\pi$$







弹簧、 熟悉基本的振动系统的规律: 单摆、

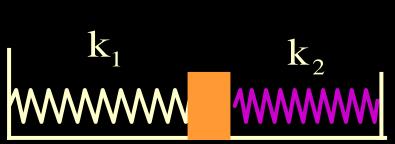


$$\omega = \sqrt{\frac{k}{m}}$$

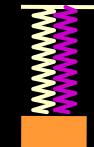
$$\omega = \sqrt{\frac{g}{l}}$$



$$\frac{1}{\mathbf{k}} = \frac{1}{\mathbf{k}_1} + \frac{1}{\mathbf{k}_2}$$



$$\mathbf{k} = \mathbf{k}_1 + \mathbf{k}_2$$



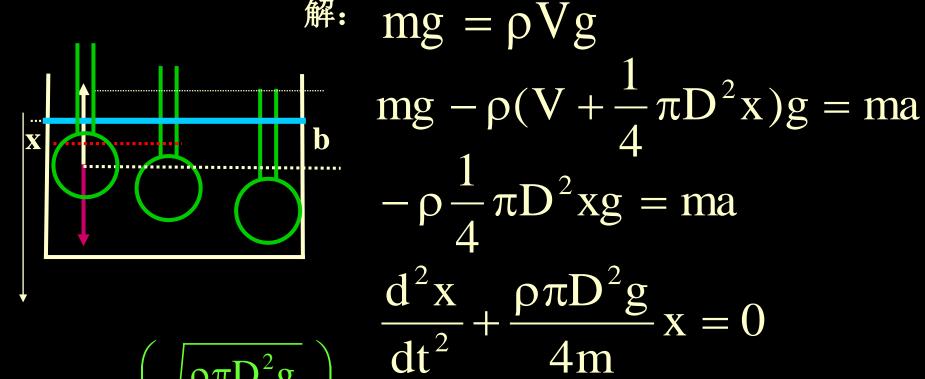




- 三、简谐振动的综合应用
- 1、证明物体作简谐振动
- 2、通过物理过程建立初始条件
- 3、通过物理过程研究力学问题

例3、已知: 比重计m、直径D, 液体密度ρ。若在平衡位置用力按下深度为b后, 放手任其运动。求振动方程。

例5、已知:比重计m、直径D, 液体密度ρ。若在平衡位置用力按下深度为b后,放手任其运动。求振动方程。



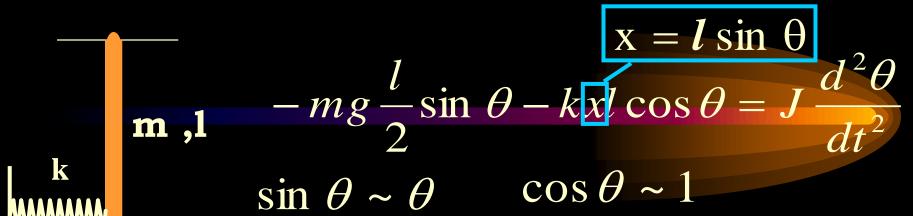
$$x = b \cos \left(\sqrt{\frac{\rho \pi D^2 g}{4m}} t \right)$$

$$A = \sqrt{x_0^2 + \frac{v_0^2}{\omega^2}} = b$$

初始条件: x = b $v_0 = 0$

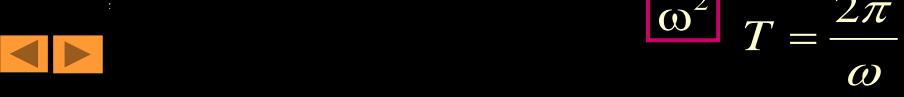


例4、证明下列系统作简谐振动,并求其振动的周期。



$$-\operatorname{mg}\frac{l}{2}\theta - kl^2\theta \approx \frac{1}{3}\operatorname{ml}^2\frac{\mathrm{d}^2\theta}{\mathrm{d}t^2}$$

$$\frac{d^2\theta}{dt^2} + \frac{\frac{1}{2} \operatorname{mg} l + k l^2}{\frac{1}{3} \operatorname{m} l^2} \theta = 0$$



$$E = \frac{1}{2}mv^2 + \frac{1}{2}kx^2 \qquad 0 = mv\frac{dv}{dt} + kx\frac{dx}{dt}$$



$$\frac{dv}{dt} + \frac{k}{m}x = 0 \quad \left(\frac{d^2x}{dt^2} + \frac{k}{m}x = 0\right)$$

$$mgx = \frac{1}{2}mv^{2} + \frac{1}{2}J\omega^{2} + \frac{1}{2}kx^{2}$$

$$mgv = mv\frac{dv}{dt} + J\omega\frac{d\omega}{dt} + kxv$$

$$mgv = mv\frac{dv}{dt} + J\omega\frac{d\omega}{dt} + kxv$$

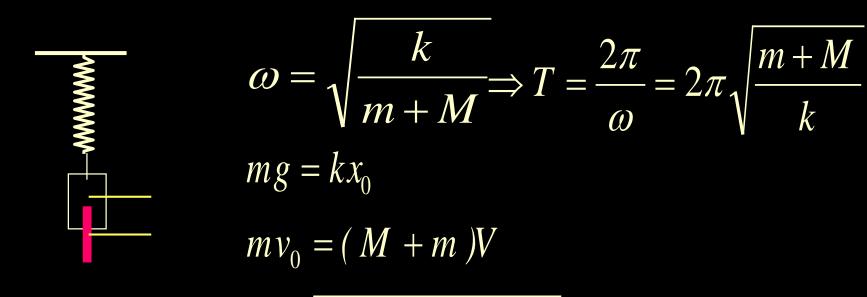
$$mgv = mv\frac{dv}{dt} + J\frac{v}{R}\frac{1}{R}\frac{dv}{dt} + kxv$$

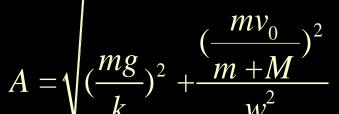
$$mg\sqrt{\frac{dv}{dt}} + J\sqrt{\frac{dt}{R}} \frac{dt}{dt} + kx\sqrt{v}$$

$$\left(m + \frac{J}{R^2}\right)\frac{dv}{dt} + (kx - mg) = 0 \qquad x = x_0 + x'$$

习题册 5 一弹簧振子,由弹性系数为k的弹簧和质量为M的物块组成,将弹簧一端与顶板连接,如图所示。开始时物块静止,一质量为m、速度为v₀的子弹由下而上射入物块,并停留在物块中,试求:

- (1) 振子振动的振幅和周期;
- (2) 物块由初位置运动到最高点所需的时间;







$$tg\varphi = -\frac{v_0}{x_0\omega} = -\frac{v_0}{g}\sqrt{\frac{k}{m+M}}$$

向上为正,最高点 $cos(\omega t + \varphi) = 1$

$$\frac{0-\varphi}{\Delta t} = \frac{2\pi}{T} = \omega$$



例8、一装有弹簧的框架静止地放在光滑的水平面上,框架的质量M,弹簧的弹性系数k。现有质量为m的小球以水平速度v₀射入框架与弹簧连接,并开始压缩弹簧,设小球与框架均光滑.

- (1) 证明小球在框架内作谐振动,并写出振动方程;
- (2) 试求弹簧的最大压缩量;
- (3) 从弹簧与小球接触到弹簧达到最大压缩量的时间。



$$kx = Ma_{M^{\sharp h}}$$



$$f = kx$$

$$f_g = ma$$

$$m\frac{d^2x}{dt^2} = -kx - ma_{M}$$

$$= -kx - m\frac{kx}{M} = -k\frac{m+M}{M}x$$

$$x_0 = 0, \quad v_0 = v_0$$

$$\frac{d^2x}{dt^2} + k\frac{m+M}{Mm}x = 0$$

$$A = \sqrt{x_0^2 + (\frac{v_0}{\omega})^2} = \left| \frac{v_0}{\omega} \right| \qquad \varphi = -\frac{\pi}{2}$$

$$x = \frac{v_0}{\sqrt{k \frac{m+M}{mM}}} \cos(\sqrt{k \frac{m+M}{mM}}t - \frac{\pi}{2})$$



$$f = kx$$

$$\mathbf{M}$$

$$\mathbf{m}$$

$$f_{g} = ma$$

$$x_m = A = \sqrt{x_0^2 + (\frac{v_0}{\omega})^2} = \left| \frac{v_0}{\omega} \right|$$

$$\Delta t = \frac{T(\frac{2\pi}{\omega})}{4} = \frac{\pi}{2} \sqrt{\frac{Mm}{k(m+M)}}$$



四、同方向同频率振动的合成

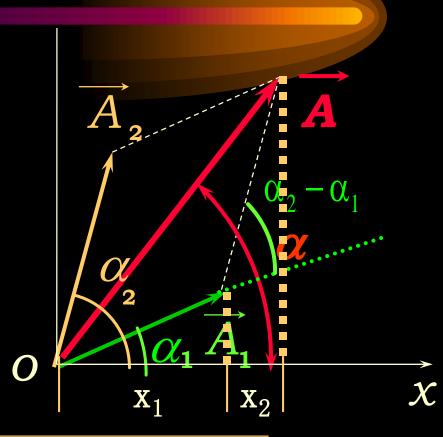


$$x_2 = A_2 \cos(\omega t + \alpha_2)$$

$$X = X_1 + X_2$$

$$= A\cos(\omega t + \alpha)$$

合振动的振幅为:



$$A = \sqrt{A_1^2 + A_2^2 + 2A_1 A_2 \cos(\alpha_2 - \alpha_1)}$$

例7、已知
$$\begin{cases} x_1 = \sqrt{3}\cos\left(3t + \frac{3\pi}{4}\right) \\ x_2 = \cos\left(3t + \frac{\pi}{4}\right) \end{cases}$$

求: 合振动的表达式
$$A = \sqrt{A_1^2 + A_2^2} = 2$$

$$tg\beta = \frac{\sqrt{3}}{1}$$

$$\alpha = \frac{\pi}{4} + \frac{\pi}{3} = \frac{7}{12}\pi$$

$$x = 2\cos\left(3t + \frac{7\pi}{12}\right)$$

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$$\begin{cases} A = A_1 + A_2 & \chi \\ \varphi = \varphi_2 = \varphi_1 & \chi \\ x = (A_1 + A_2)\cos\left(\frac{2\pi}{T}t + \pi\right)O & \chi \\ A_1 = |A_1 - A_2| & \chi \\ \varphi = \varphi_2 & Q & \chi \\ x = (A_2 - A_1)\cos\left(\frac{2\pi}{T}t + \pi\right)O & \chi \\ \chi = (A_2 - A_1)\cos\left(\frac{2\pi}{T}t + \pi\right)O & \chi \\ \chi = (A_2 - A_1)\cos\left(\frac{2\pi}{T}t + \pi\right)O & \chi \\ \chi = (A_2 - A_1)\cos\left(\frac{2\pi}{T}t + \pi\right)O & \chi \\ \chi = (A_2 - A_1)\cos\left(\frac{2\pi}{T}t + \pi\right)O & \chi \\ \chi = (A_2 - A_1)\cos\left(\frac{2\pi}{T}t + \pi\right)O & \chi \\ \chi = (A_2 - A_1)\cos\left(\frac{2\pi}{T}t + \pi\right)O & \chi \\ \chi = (A_2 - A_1)\cos\left(\frac{2\pi}{T}t + \pi\right)O & \chi \\ \chi = (A_2 - A_1)\cos\left(\frac{2\pi}{T}t + \pi\right)O & \chi \\ \chi = (A_2 - A_1)\cos\left(\frac{2\pi}{T}t + \pi\right)O & \chi \\ \chi = (A_2 - A_1)\cos\left(\frac{2\pi}{T}t + \pi\right)O & \chi \\ \chi = (A_2 - A_1)\cos\left(\frac{2\pi}{T}t + \pi\right)O & \chi \\ \chi = (A_2 - A_1)\cos\left(\frac{2\pi}{T}t + \pi\right)O & \chi \\ \chi = (A_2 - A_1)\cos\left(\frac{2\pi}{T}t + \pi\right)O & \chi \\ \chi = (A_2 - A_1)\cos\left(\frac{2\pi}{T}t + \pi\right)O & \chi \\ \chi = (A_2 - A_1)\cos\left(\frac{2\pi}{T}t + \pi\right)O & \chi \\ \chi = (A_2 - A_1)\cos\left(\frac{2\pi}{T}t + \pi\right)O & \chi \\ \chi = (A_2 - A_1)\cos\left(\frac{2\pi}{T}t + \pi\right)O & \chi \\ \chi = (A_2 - A_1)\cos\left(\frac{2\pi}{T}t + \pi\right)O & \chi \\ \chi = (A_2 - A_1)\cos\left(\frac{2\pi}{T}t + \pi\right)O & \chi \\ \chi = (A_2 - A_1)\cos\left(\frac{2\pi}{T}t + \pi\right)O & \chi \\ \chi = (A_2 - A_1)\cos\left(\frac{2\pi}{T}t + \pi\right)O & \chi \\ \chi = (A_2 - A_1)\cos\left(\frac{2\pi}{T}t + \pi\right)O & \chi \\ \chi = (A_2 - A_1)\cos\left(\frac{2\pi}{T}t + \pi\right)O & \chi \\ \chi = (A_2 - A_1)\cos\left(\frac{2\pi}{T}t + \pi\right)O & \chi \\ \chi = (A_2 - A_1)\cos\left(\frac{2\pi}{T}t + \pi\right)O & \chi \\ \chi = (A_2 - A_1)\cos\left(\frac{2\pi}{T}t + \pi\right)O & \chi \\ \chi = (A_2 - A_1)\cos\left(\frac{2\pi}{T}t + \pi\right)O & \chi \\ \chi = (A_2 - A_1)\cos\left(\frac{2\pi}{T}t + \pi\right)O & \chi \\ \chi = (A_2 - A_1)\cos\left(\frac{2\pi}{T}t + \pi\right)O & \chi \\ \chi = (A_2 - A_1)\cos\left(\frac{2\pi}{T}t + \pi\right)O & \chi \\ \chi = (A_2 - A_1)\cos\left(\frac{2\pi}{T}t + \pi\right)O & \chi \\ \chi = (A_2 - A_1)\cos\left(\frac{2\pi}{T}t + \pi\right)O & \chi \\ \chi = (A_2 - A_1)\cos\left(\frac{2\pi}{T}t + \pi\right)O & \chi \\ \chi = (A_2 - A_1)\cos\left(\frac{2\pi}{T}t + \pi\right)O & \chi \\ \chi = (A_2 - A_1)\cos\left(\frac{2\pi}{T}t + \pi\right)O & \chi \\ \chi = (A_2 - A_1)\cos\left(\frac{2\pi}{T}t + \pi\right)O & \chi \\ \chi = (A_2 - A_1)\cos\left(\frac{2\pi}{T}t + \pi\right)O & \chi \\ \chi = (A_2 - A_1)\cos\left(\frac{2\pi}{T}t + \pi\right)O & \chi \\ \chi = (A_2 - A_1)\cos\left(\frac{2\pi}{T}t + \pi\right)O & \chi \\ \chi = (A_2 - A_1)\cos\left(\frac{2\pi}{T}t + \pi\right)O & \chi \\ \chi = (A_2 - A_1)\cos\left(\frac{2\pi}{T}t + \pi\right)O & \chi \\ \chi = (A_2 - A_1)\cos\left(\frac{2\pi}{T}t + \pi\right)O & \chi \\ \chi = (A_2 - A_1)\cos\left(\frac{2\pi}{T}t + \pi\right)O & \chi \\ \chi = (A_2 - A_1)\cos\left(\frac{2\pi}{T}t + \pi\right)O & \chi \\ \chi = (A_2 - A_1)\cos\left(\frac{2\pi}{T}t + \pi\right)O & \chi \\ \chi = (A_1 - A_2)O & \chi \\ \chi = (A_1 -$$