

Polynomial Ergodicity of Langevin Dynamics

Draft Draft

7/05/2024

An overdamped Langevin dynamics on \mathbb{R} is defined as the solution to the following SDE:

$$dX_t = -\nabla V(X_t) dt + \sqrt{2\beta^{-1}} dB_t, \quad X_0 = x_0.$$

If $V(x) = \frac{x^2}{2}$, X becomes an Ornstein-Uhlenbeck process. Transforming via $f(t, x) = xe^t$ and using Itô's formula, we get

$$X_t = x_0 e^{-t} + \sqrt{2\beta^{-1}} \int_0^t e^{-(t-s)} dB_s.$$

Hence, X is a Gaussian process with $X_t \sim N(x_0 e^{-t}, \beta^{-1}(1 - e^{-2t}))$.

In this case, expectation with respect to $G(y) = e^{\kappa V(y)} = e^{\frac{\kappa y^2}{2}}$ ($\kappa \in \mathbb{R}$) is given by

$$\begin{aligned} \mathbb{E}_x[G(X_t)] &= \int_{\mathbb{R}} G(y) \frac{1}{\sqrt{2\pi\beta^{-1}(1 - e^{-2t})}} \exp\left(-\frac{(y - xe^{-t})^2}{2\beta^{-1}(1 - e^{-2t})}\right) dy \\ &= \frac{1}{\sqrt{2\pi\beta^{-1}(1 - e^{-2t})}} \int_{\mathbb{R}} \exp\left(\frac{\kappa\beta^{-1}(1 - e^{-2t})y^2 - (y - xe^{-t})^2}{2\beta^{-1}(1 - e^{-2t})}\right) dy. \end{aligned}$$

Taking a closer look at the numerator inside exp,

$$\begin{aligned} &\kappa\beta^{-1}(1 - e^{-2t})y^2 - (y - xe^{-t})^2 \\ &= y^2 \left(\kappa\beta^{-1}(1 - e^{-2t}) - 1 \right) - 2xe^{-t}y + x^2e^{-2t}. \end{aligned}$$

Therefore, we conclude

$$\mathbb{E}_x[G(X_t)] < \infty \quad \Leftrightarrow \quad \kappa\beta^{-1}(1 - e^{-2t}) < 1.$$

In other words, $P_t G(x)$ is finite as long as

$$t < -\frac{1}{2} \log\left(1 - \frac{\beta}{\kappa}\right).$$