

Numerical Recipes for Astrophysics

Solutions hand-in Assignment-2

Luther Algra - s1633376

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Abstract

The current document contains the solutions for the second hand-in assignment of Numerical Recipes. The main questions, 1, 2, 3 ..., 7, are in this document all given their own section. Each section contains a subsection for its related sub-questions (1.a, 1.b, 1.c, ..., 1.e) and ends with a final subsection that contains two segments of code. The first segment contains the code of the main question. The second segment contains the code of shared modules used by the sub-questions. A sub-question itself always starts with a short summary of the question that needs to be answered. The summary is followed by an explanation of how the problem is solved and the code that provides the solution. If necessary some of the results are discussed here. The output of the code is always presented after the code and plots are discussed in their caption.

1 - Normally distributed pseudo-random numbers

Question 1.a

Problem

Write a random number generator that returns a random floating-point number between 0 and 1. At minimum, use some combination of an MWC and a 64-bit XOR-shift. Plot a sequential of random numbers against each other in a scatter plot (x_{i+1} vs x_i) for the first 1000 numbers generated. Also plot the value of the random numbers for the first 1000 numbers vs the index of the random number, this mean the x-axis has a value from 0 through 999 and the y-axis 0 through 1). Finally, have your code generate 1,000,000 random numbers and plot the result of binning these in 20 bins 0.05 wide.

Solution

The state of the random number generator (RNG) is updated by first performing a 64-bit XOR-shift on the current state. Next, a modified version of the 64-bit XOR-shift output is given to the MWC algorithm. The modified XOR-shifts output that is given to the MWC algorithm is the output of the 64 XOR-shift with the last 32 bits put to zero. This is done by performing the 'AND' operation with the maximum value of an unsigned int32. This modification was performed as the MWC algorithm expects as input a 64-bit unsigned integer with a value between $0 < x < 2^{32}$. The output of the MWC is finally XORd with the unmodified output of the 64-bit XOR-shift. The result is set as the new state of the RNG.

The first 32 bits of the new state are used to provide a random value, as the output of the MWC algorithm only contains 32 significant bits. This random value is obtained by performing the 'AND' operation between the seed and the maximum value of an unsigned int32. The resulting value is then divided by the maximum value of an unsigned int32 to obtain a value between 0 and 1.

The code for the random number generator can be found at the end of this section, as it is treated as a shared module (see page 19). The code for generating the plots and the created plots can be found below. The code does not only print the random seed, but also prints the maximum and minimum number of counts for the binned 1,000,000 values. These values are referred to in the description of the plot that displayed the uniformness (figure 2).

Code - Plots

The code for generating the plots. The used imports and the initialization of the random number generator are not explicit shown in this piece of code, but can be found on page 19. The code for the random number generator can, as mentioned before, be found on page 19.

```
1 def assignment_1a(random):
2     """
3     Execute assignment 1.a
4     Int:
5     param: random — An initialization of the random number generator.
6     """
7
8     # The relevant imports for this piece of code are:
9
10    # (1) matplotlib.pyplot as plt
11    # (2) mathlib.random as random
12    # (3) mathlib.stats as ml_stats
13    # (3) numpy as np
14
15    # Print the seed.
16    print('[1.a] Initial seed: ', random.get_seed())
17
18    # Generate 1000 numbers.
19    numbers_1000 = random.gen_uniforms(1000)
20
21    # Plot them against each other.
22    plt.scatter(numbers_1000[0:999], numbers_1000[1:], s=2)
23    plt.ylabel(r'Probability  $x_{i+1}$ ')
24    plt.xlabel(r'Probability  $x_i$ ')
25    plt.savefig('./Plots/1_plot_against.pdf')
26    plt.figure()
27
28    # Plot them against the index.
29    plt.plot(range(0, 1000), numbers_1000)
30    plt.ylabel('Probability p')
31    plt.xlabel('Index')
32    plt.savefig('./Plots/1_plot_index.pdf')
33    plt.figure()
34
35    # Create a histogram for 1e6 points with 20 bins of 0.05 wide.
36    numbers_mil = random.gen_uniforms(int(1e6))
37    plt.hist(numbers_mil, bins=20, range=(0,1), color='orange', edgecolor='black')
38    plt.ylabel('Counts')
39    plt.xlabel('Generate values')
40    plt.savefig('./Plots/1_hist_uniformnes.pdf')
41    plt.figure()
42
43    # Extra, to print the smallest and lagest bin value.
44    counts, _ = np.histogram(numbers_mil, bins=20)
45    print('[1.a] Max counts: ', max(counts))
46    print('[1.a] Min counts: ', min(counts))
```

./Code/assignment_1.py

Code - Output text

The text output produced by the code. The first value is the initial seed of the RNG. The second and third value are the maximum and minimum amount of counts for the histogram displaying the uniformness.

```
1 [1.a] Initial seed: 78379522
2 [1.a] Max counts: 50343
3 [1.a] Min counts: 49557
```

./Output/assignment1_out.txt

Code - Output plots

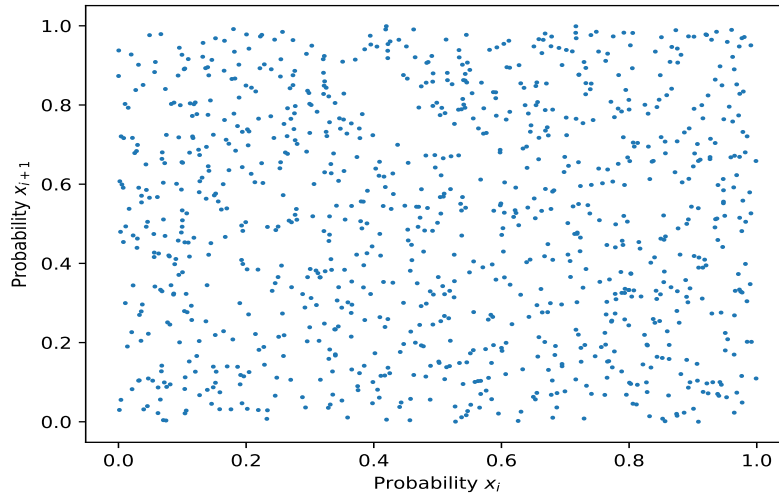


Figure 1: A plot of random number x_{i+1} against random number x_i for the first 1000 random uniforms produced by the random number generator. A good random number generator should produce a homogeneous plot without many (large) empty spots. The largest empty spot in the above plot is at $x_i = 0.4$ and $x_{i+1} = 0.8$. The spot is not significant large, but might point towards an impurity in the RNG.

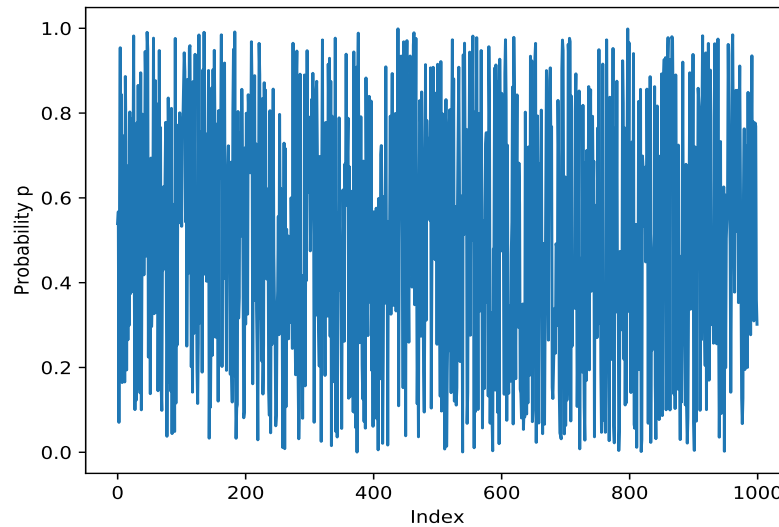


Figure 2: The first 1000 random uniform numbers produced by the random number generator (RNG) against their index. A good random number generator should not have large wide gaps (e.g when moving from index 400 to 450 it should not only produce values larger than 0.8, which would leave a wide gap). In the plot small gaps appear, see for example index ~ 420 at a probability of $p = 0.6$. The number of gaps and the width of the gaps do not appear to be significant. This might therefore either be the result of being unlucky, or could point towards an impurity in the RNG. The average value produced by the RNG should furthermore be 0.5. This corresponds to rapidly moving up and down around the horizontal line corresponding with a probability of $p = 0.5$. In the plot this should, result in a 'dense' region (less white) around the line $p = 0.5$. It can indeed be seen that the plot is denser around the line $p = 0.5$ than at $p = 0.8$ or $p = 0.2$.

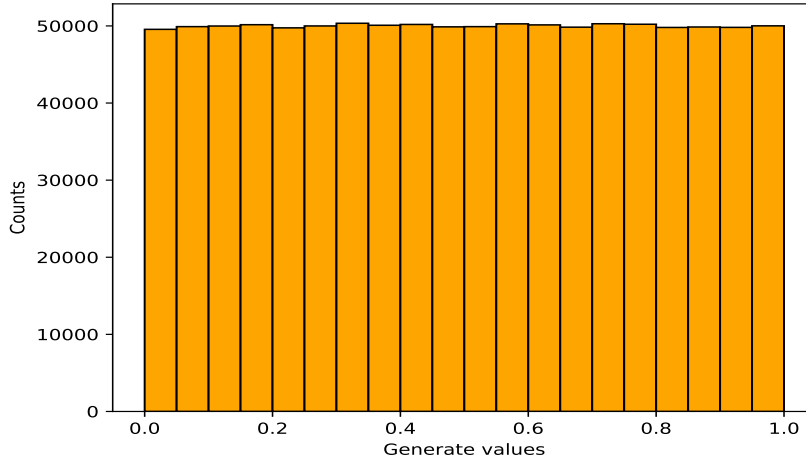


Figure 3: The uniforms of the random number generator for 1 million random values. The values are binned in 20 bins. A good random number generator should fluctuate around $50000 \pm 2\sqrt{50000} = 50000 \pm 447$ counts per bin (2 sigma). The maximum and minimum amount of counts corresponds to 50343 and 49557 counts. These values just lay withing the 2 sigma uncertainty. The uniformness of the random number generator therefore appears to be acceptable.

Question 1.b)

Problem

Now use the Box-Muller method to generate 1000 normally-distributed random numbers. To check if they are following the expected Gaussian distribution, make a histogram (scaled appropriate) with the corresponding true probability distribution (normalized to integrate to 1) as line. This plot should contain the interval of -5σ until 5σ from the theoretical probability distribution. Indicate the theoretical 1σ , 2σ , 3σ and 4σ interval with a line. For this plot, use $\mu = 3$ and $\sigma = 2.4$ and choose bins that are appropriate.

Solution

The solution consists of deriving the transformation of two i.i.d uniform variables to two i.i.d normal distributed variables with the Box-Muller method. A brief version of the derivation can be found below. The final transformation, equation ??, is implemented in the random number generator and used to generate the plot. The final histogram is created with 20 bins and can be found on page 6.

Let $X, Y \sim G(\mu, \sigma^2)$ be two i.i.d Gaussian distributed random variables. Their joined CDF is then given by,

$$P(X \leq x_1, Y \leq y_1) = \int_{-\infty}^{x_1} \int_{-\infty}^{y_1} G(x|\mu, \sigma^2)G(y|\mu, \sigma^2)dxdy \quad (1)$$

Transforming to polar coordinates by substituting $(x - \mu) = r \cos(\theta)$ and $(y - \mu) = r \sin(\theta)$ yields,

$$\begin{aligned} P(R \leq r_1, \Theta \leq \theta_1) &= \int_0^{r_1} \int_0^{\theta_1} G(r \cos(\theta)\sigma + \mu|\mu, \sigma^2)G(r \sin(\theta)\sigma + \mu|\mu, \sigma^2)rdrd\theta \\ &= \frac{1}{2\pi\sigma^2} \int_0^{r_1} \int_0^{\theta_1} r e^{-\frac{1}{2}\left[\left(\frac{r \cos(\theta)}{\sigma}\right)^2 + \left(\frac{r \sin(\theta)}{\sigma}\right)^2\right]} drd\theta \\ &= \frac{1}{2\pi\sigma^2} \int_0^{r_1} \int_0^{\theta_1} r e^{-\frac{r^2}{2\sigma^2}} drd\theta \end{aligned}$$

The CDF's for the polar coordinates are now given by,

$$P(R \leq r_1) = \frac{1}{\sigma^2} \int_0^{r_1} r e^{-\frac{r^2}{2\sigma^2}} dr = \int_0^{r_1} \frac{d}{dr} \left(-e^{-\frac{r^2}{2\sigma^2}} \right) dr = 1 - e^{-\frac{r_1^2}{2\sigma^2}} \quad (2)$$

$$P(\Theta \leq \theta_1) = \frac{1}{2\pi} \left[-e^{-\frac{r^2}{2\sigma^2}} \right]_0^\infty \int_0^{\theta_1} d\theta = \frac{\theta_1}{2\pi} \quad (3)$$

The CDFs can be used to convert two uniform distributed variables to the polar coordinates of the Gaussian distributed variables. Let $U_1, U_2 \sim U(0, 1)$ be two i.i.d uniform variables. From the transformation law of probability we then must have that,

$$P(R \leq r_1) = P(U_1 \leq u_1) \rightarrow 1 - e^{-\frac{r_1^2}{2\sigma^2}} = \int_0^{u_1} du_1 = u_1 \quad (4)$$

$$P(\Theta \leq \theta) = P(U_2 \leq u_2) \rightarrow \frac{\theta_1}{2\pi} = \int_0^{u_2} du_2 = u_2 \quad (5)$$

The transformation from the two uniform distributed variables to the polar coordinates of the Gaussian distributed variables then becomes,

$$r_1 = \sqrt{-2\sigma^2 \ln(1 - u_1)} \quad (6)$$

$$\theta_1 = 2\pi u_2 \quad (7)$$

Converting back to Cartesian coordinates yields the transformation from two i.i.d uniform distributed variables to two i.i.d Gaussian distributed variables;

$$x_1 = r \cos(\theta) + \mu = \sqrt{-2\sigma^2 \ln(1 - u_1)} \cos(2\pi u_2) + \mu \quad (8)$$

$$y_1 = r \sin(\theta) + \mu = \sqrt{-2\sigma^2 \ln(1 - u_1)} \sin(2\pi u_2) + \mu \quad (9)$$

These above transformation are implemented in the random number generator (see page ??). The code for the generation of the plot and the created plot can be found below. The code that generates the plot makes besides the RNG use of a function for the normal distribution in the file `./Code/mathlib/statistics.py`. This file is treated as a shared module and can be found on page 22. The called function, `normal`, can be found on line 227 in this file.

Code - Plots

The code for generating the plots. The imports are again not explicit shown, but can be found on page 19. The shared modules can be found on pages 19 and 22.

```

1 def assignement_1b(random):
2     """
3         Execute assignement 1.b
4     Int:
5         param: random — An instance of the random number generator.
6     """
7
8     # The relevant imports for this piece of code are:
9
10    # (1) matplotlib.pyplot as plt
11    # (2) mathlib.random as random
12    # (3) mathlib.stats as ml_stats
13    # (4) numpy as np
14
15    # Sigma and mean for the distribution.
16    mean = 3.0
17    sigma = 2.4
18
19    # Generate 1000 random normal variables for the given mean and sigma.
```

```

20 samples = random.gen_normals(mean, sigma, 1000)
21
22 # The true normal distribution for the given mean and sigma.
23 gaussian_x = np.linspace(-sigma*4 +mean, sigma*4 +mean, 1000)
24 gaussian_y = ml.stats.normal(gaussian_x, mean, sigma)
25
26 # Create a histogram.
27 plt.hist(samples, bins=20, density=True, edgecolor='black',
28          facecolor='orange', zorder=0.1, label='Sampled')
29 plt.plot(gaussian_x, gaussian_y, c='red', label='Normal')
30 plt.xlim(-sigma*6.5 + mean, sigma*6.5 + mean)
31 plt.ylim(0, max(gaussian_y)*1.2)
32
33 # Add the sigma lines.
34
35 # The hight of the sigma lines that need to be added.
36 lines_height = max(gaussian_y)*1.2
37
38 for i in range(1, 6):
39     # Absolute shift from the mean for the given sigma
40     shift = i*sigma
41
42     # Sigma right of the mean.
43     plt.vlines(mean + shift, 0, lines_height,
44               linestyle='-', color='black', zorder=0.0)
45     plt.text(mean + shift -0.4, lines_height/1.2, str(i) + r'$\sigma$',
46             color='black', backgroundcolor='white', fontsize=9)
47
48     # Sigma line left of the mean.
49     plt.vlines(mean - shift, 0, lines_height, linestyle='-', zorder=0.0)
50     plt.text(mean - shift -0.4, lines_height/1.2, str(i) + r'$\sigma$',
51             color='black', backgroundcolor='white', fontsize=9)
52
53 plt.legend(framealpha=1.0)
54 plt.savefig('./Plots/1_hist_gaussian.pdf')
55 plt.figure()

```

./Code/assigment.1.py

Code - Output plot(s)

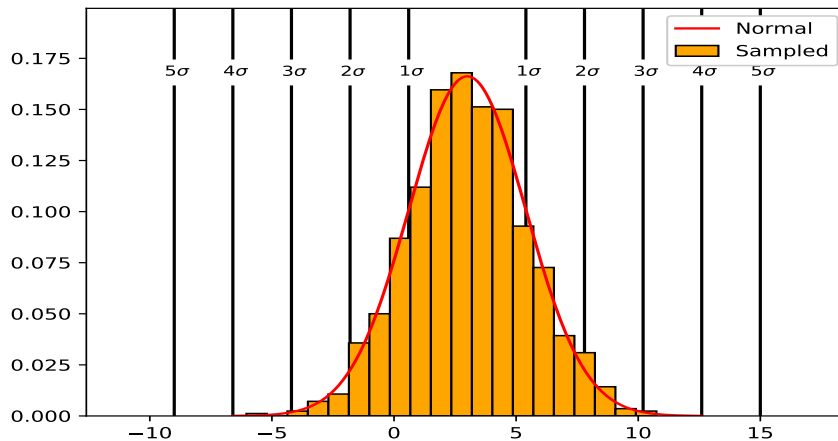


Figure 4: A histogram of the 1000 random normal distributed variables generated with the box muller method for $\mu = 3$ and $\sigma = 2.4$ (orange). The red line is the true normal distribution. The histogram appears to approximate the distribution quite well, but displays small deviations. The bin left of the peak (the highest bin) is larger than it should be. The first bins right of the peak is smaller than it should be and the second bin right of the peak is to high. The histogram does however still appear to be acceptable by eye. A statistical test is of course better to determine whether the histogram would truly be acceptable or not.

Question 1.c)

Problem

Write a code that can do the KS-test on the your function to determine if it is consistent with a normal distribution. For this, use $\mu = 0$ and $\sigma = 1$. Make a plot of the probability that your Gaussian random number generator is consistent with Gaussian distributed random numbers, start with 10 random numbers and use in your plot a spacing of 0.1 dex until you have calculated it for 10^5 random numbers on the x-axis. Compare your algorithm with the KS-test function from `scipy`, `scipy.stats.kstest` by making an other plot with the result from your KS-test and the KS-test from `scipy`.

Solution

The implementation of the KS-test is in general straight forwards. There are however two points of interest that needs to be discussed. The first point is the implementation of the CDF for the KS-statistic and the second point is the implementation of the CDF for the normal distribution.

(1) CDF KS-statistic

The p-value produced by the KS-tests requires the evaluation of the CDF for the KS-test statistic,

$$P_{KS}(z) = \frac{2\sqrt{\pi}}{z} \sum_{j=1}^{\infty} \exp\left(-\frac{(2j-1)^2 + \pi^2}{8z^2}\right) \quad (10)$$

This infinite sum needs to be numerically approximated in order to perform the KS-test. The chosen approximation for the above equation is taken from the book *Numerical Recipes - The art of Scientific Computation, 3d edition*,

$$P_{KS}(z) \approx \begin{cases} \frac{\sqrt{2\pi}}{z} \left[\left(e^{-\pi^2/(8z^2)} \right) + 9 + \left(e^{-\pi^2/(8z^2)} \right) \left(e^{-\pi^2/(8z^2)} \right)^{25} \right] & \text{for } z < 1.18 \\ 1 - 2 \left[\left(e^{-2z^2} \right) - \left(e^{-2z^2} \right)^4 + \left(e^{-2z^2} \right)^9 \right] & \text{for } z \geq 1.18 \end{cases} \quad (11)$$

(2) CDF normal distribution

The CDF of the normal distribution is needed in order to perform the KS-test under the null hypothesis that the data follows a normal distribution. The CDF of the normal distribution can in general be written as,

$$\Phi\left(\frac{x-\mu}{\sigma}\right) = \frac{1}{2} \left[1 + \operatorname{erf}\left(\frac{x-\mu}{\sigma\sqrt{2}}\right) \right] \quad (12)$$

where the erf is given by,

$$\operatorname{erf}(x) = \frac{2}{\sqrt{\pi}} \int_0^x e^{-t^2} dt \quad (13)$$

The integral of the erf function lacks a closed form and therefore needs to be numerically approximated. The chosen approximation is taken from *Abramowitz and Stegun*,

$$\operatorname{erf}(x) \approx 1 - (a_1 t + a_2 t^2 + \dots + a_5 t^5) e^{-x^2} \quad t = \frac{1}{1 + px} \quad (14)$$

where, $p = 0.3275911$, $a_1 = 0.254829592$, $a_2 = -0.284496736$, $a_3 = 1.421413741$, $a_4 = -1.453152027$, $a_5 = 1.061405429$.

The KS-test and the CDF are implemented with these approximations. The code for the KS-test and the CDF is located in the file `./Code/mathlib/statistics.py` at page 22, as this file is threaded as a shared module. The KS-test does require an sorting algorithm, this algorithm is implemented in the file `./Code/matlib/sorting` and can be found on page 26. The code for the generation of the plots and plots are displayed below.

Code - Plots

The code for generating the two plots. The imports for this file are not explicit shown, but can be found on page 19.

```
1 def assignment_1c(random):
2     """
3     Execute assignment 1.c
4     Int:
5     param: random — An initialization of the random number generator.
6     """
7
8     # The relevant imports for this piece of code are:
9     # (1) matplotlib.pyplot as plt
10    # (2) numpy as np
11    # (3) astropy.stats
12    # (4) mathlib.statistics as ml_stats
13
14    # The values to plot point for.
15    plot_values = np.array(10*np.arange(1, 5.1, 0.1), dtype=int)
16
17    # An array in which the p-values are stored for the self created.
18    # ks-test and the scipy version.
19    p_values_self = np.zeros(len(plot_values))
20    p_values_scipy = np.zeros(len(plot_values))
21
22    # Generate the maximum amount of needed random numbers.
23    random_numbers = random.gen_normals(0, 1, int(1e5))
24
25    # Calculate the p-values with the ks-test.
26    for idx, values in enumerate(plot_values):
27
28        # Calculate the value with scipy.
29        p_values_scipy[idx] = sp.stats.kstest(random_numbers[0:values],
30                                             'norm')[1]
31
32        # Calculate the p-values with the own implementation.
33        p_values_self[idx] = ml_stats.kstest(random_numbers[0:values],
34                                             ml_stats.normal_cdf)
35
36    # Plot the probabilities for only my own implementation.
37    plt.plot(plot_values, p_values_self, label='self', color='orange')
38    plt.hlines(0.05, 0, 10**5, colors='red', linestyle='—')
39    plt.xscale('log')
40    plt.xlabel(r'Log($N_{samples}$)')
41    plt.ylabel('Probabillity (p-value)')
42    plt.legend()
43    plt.savefig('./Plots/1_plot_ks-test_self.pdf')
44    plt.figure()
45
46    # Plot the probabilities for both the scipy and my own implemntation.
47    plt.plot(plot_values, p_values_scipy, label='scipy', linestyle=':',
48             zorder=1.1)
49    plt.plot(plot_values, p_values_self, label='self', zorder=1.0,
50             color='orange')
51    plt.hlines(0.05, 0, 10**5, colors='red', linestyle='—')
52    plt.xscale('log')
53    plt.xlabel(r'Log($N_{samples}$)')
54    plt.ylabel('Probabillity (p-value)')
55    plt.legend()
56    plt.savefig('./Plots/1_plot_ks-test_self_scipy.pdf')
57    plt.figure()
```

./Code/assignment_1.py

Code - Output plot(s)

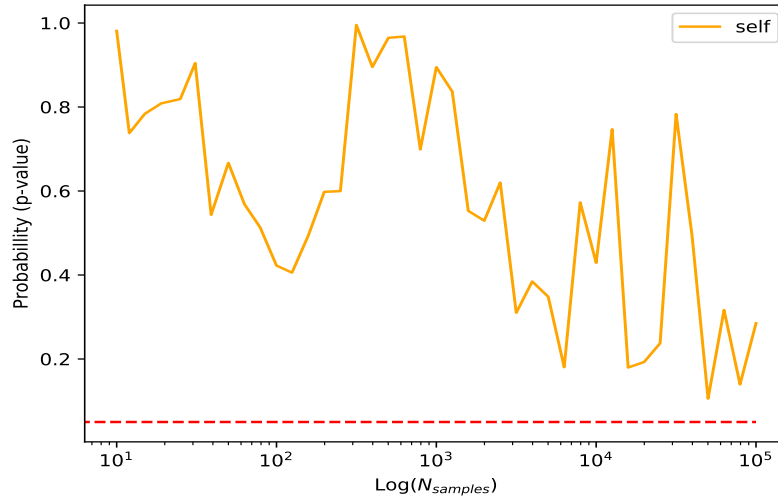


Figure 5: The P-value produced by the KS-test against the number of samples on which the KS-test is performed for the self written RNG. The red line indicates the line of $p = 0.05$. A point **below** the line would suggest that there is enough statistical evidence to reject the (null) hypothesis that the data is normal distributed. The plot shows that the RNG always passes KS-test up to atleast 10^5 samples. The p-value does however appear to drop for a large number of samples and might even drop further when more samples are used. The drop suggests again that the RNG is likely not perfect.

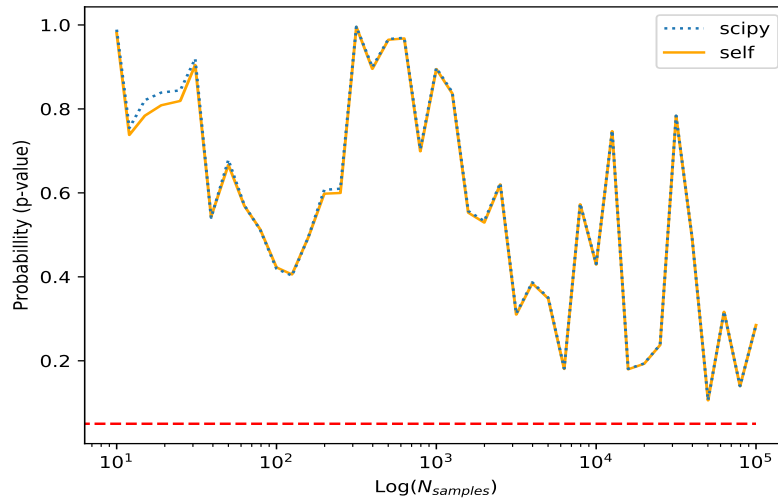


Figure 6: The P-value produced by the KS-test against the number of samples on which the KS-test is performed for the self written RNG. The red line indicates the line of $p = 0.05$. The orange line is the self written implementation of the KS-test and the blue line is the scipy version. A point **below** the red line would suggest that there is enough statistical evidence to reject the (null) hypothesis that the data is normal distributed. The self written KS-test is close to the scipy version, but shows (small) deviations at small sample sizes (see $N_{samples} = 10$ or $N_{samples} = 200$). The self written implementation always has the same shape as the scipy version, even at the deviations. The exact cause for the deviations are unknown, but are likely the result of an approximation that scipy makes that the self written implementation doesn't make.

Question 1.d)

Problem

Write a code that does the Kuiper's test on your random numbers (see tutorial 8) and make the same plot as for the KS-test.

Solution

The implementation of the Kuiper test does require a numerical approximation of the CDF for the kuiper statistics. The CDF of the kuiper staistic is given by,

$$P_{kuiper}(\lambda) = 1 - 2 \sum_{j=1}^{\infty} (4j^2\lambda^2 - 1)e^{-2j^2\lambda^2} \quad (15)$$

The sum in the above expression negligible compared to the machine error if $\lambda < 0.4$. In this case the numerically approximation thus consist of returning 1. If $\lambda > 0.4$ then the sum is approximated by calculating the first 100 terms of the sum. This should be more than enough for the sum to converge.¹

The Kuiper-test and the CDF are implemented in the shared module `./Code/mathlib/statistics.py` that can be found on page 22. The code that creates the plots and the plots can be found below. The code does make use of **astropy** to compare the self written implementation of the Kuiper-test with the implementation of astropy.

Code - Plots

The code for generating the two plots. The imports are not explicit shown but can be shown on page 19.

```
1 def assignment_1d(random):
2     """
3     Execute assignment 1.d
4     Int:
5     param: random — An initialization of the random number generator.
6     """
7
8     # The relevant imports for this piece of code are:
9     # (1) matplotlib.pyplot as plt
10    # (2) numpy as np
11    # (3) scipy.stats as sp_stats
12    # (4) mathlib.statistics as ml_stats
13
14    # The values to plot point for.
15    plot_values = np.array(10*np.arange(1, 5.1, 0.1), dtype=int)
16
17    # Generate the maximum amount of needed random numbers.
18    random_numbers = random.gen_normals(0, 1, int(1e5))
19
20    # An array in which the p-values are stored for the self created
21    # kuiper-test and the astropy version.
22    p_values_self = np.zeros(len(plot_values))
23    p_values_astropy = np.zeros(len(plot_values))
24
25    # Calculate the p-values with the ks-test
26    for idx, values in enumerate(plot_values):
27
28        # Calculate the value with the own implemnetation
29        p_values_self[idx] = ml_stats.kuiper_test(random_numbers[0:values],
30        ml_stats.normal_cdf)
31        # Calculare the value with astropy.
32        p_values_astropy[idx] = astropy.stats.kuiper(random_numbers[0:values],
33        ml_stats.normal_cdf)[1]
```

¹Actually, less terms are enough. The evaluation of the sum could therefore stop early by checking for a required precision.

```

33
34 # Plot the probabilities for only my own implementation
35 plt.plot(plot_values, p_values_self, label = 'self')
36 plt.hlines(0.05,0,10**5,colors='red',linestyles='—')
37 plt.xscale('log')
38 plt.xlabel(r'Log($N_{samples}$)')
39 plt.ylabel('Probabillity (p-value)')
40 plt.legend()
41 plt.savefig('./Plots/1-plot-kuiper-test-self.pdf')
42 plt.figure()
43
44 # Plot the probabilliteis with both the own implementation and astropy
45 plt.plot(plot_values, p_values_astropy, label='astropy', linestyle=':',
46         zorder=1.1)
47 plt.plot(plot_values, p_values_self, label='self',zorder=1.0)
48 plt.hlines(0.05,0,10**5,colors='red',linestyles='—')
49 plt.xscale('log')
50
51 plt.xlabel(r'Log($N_{samples}$)')
52 plt.ylabel('Probabillity (p-value)')
53 plt.legend()
54 plt.savefig('./Plots/1-plot-kuiper-test-self-astropy.pdf')
55 plt.figure()

```

./Code/assigment_1.py

Code - Output plot(s)

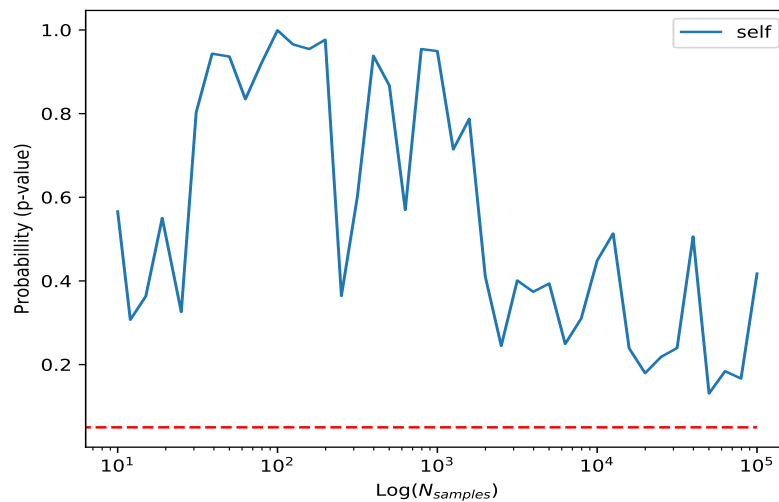


Figure 7: The P-value produced by the Kuiper-test against the number of samples on which the kuiper-test is performed for the self written RNG. The red line indicates the line of $p = 0.05$. A point **below** there line would suggests that there is enough statistical evidence to reject the (null) hypothesis that the data is normal distributed. The plot shows that the RNG always passes Kuiper test. It can however be seen that the p-value drops for larger sample size, similar as what happens by the KS-test. This might, as mentioned before, indicate that there is an flaw in the random number generator.

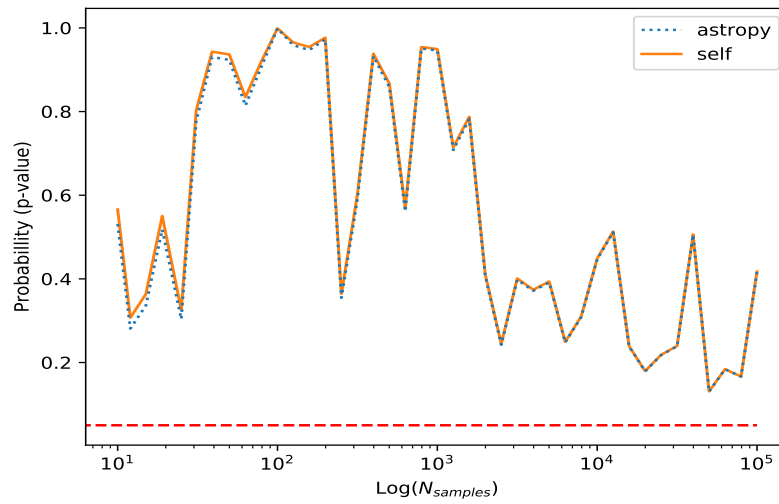


Figure 8: The P-value produced by the kuiper test against the number of samples on which the kuiper-test is performed for the self written RNG. The red line indicates the line of $p = 0.05$. A point **below** there line would suggests that there is enough statistical evidence to reject the (null) hypothesis that the data is normal distributed. The plot shows that the self written implementation has (small) deviations from the astropy implementation at small sample sizes. This is similar to the situation with the KS-test and might be caused by an approximation made in astropy.

Question 1.e)

Problem

Download the dataset. The dataset contains 10 sets of random numbers. Compare these 10 sets with your Gaussian pseudo random numbers and make the plot of the probabilities as in either of the previous two exercises (your choice). Which random number arrays is/are consistent with a Gaussian random numbers with $\sigma = 1$ and $\mu = 0$

Solution

The distributions are compared by performing the KS-test 2 (2 sample distributions). The KS-test 2 has to be applied to 10 columns. The random numbers that are compared with the column data are as result only generated once (i.e each column is compared with the same random numbers). This was done to save computation time. The code that contains the implementation of the ks-test 2 can be found on page 22. The code that generates the plots and the generated plots can be found below.

The plots show that there is only one column which might be² a normal distribution with $\sigma = 1$ and $\mu = 0$. This is column 4 (index 3, see figure 12 on page 15). In all other plots the p-value drops and stays below $p = 0.05$ when including all samples, which indicates that their is enough statistical evidence to reject the hypothesis that they follow a normal distribution with $\sigma = 1$ and $\mu = 0$.

²A p-value only shows statistical evidence against the null hypothesis, it isn't a measure of how good the null hypothesis is.

Code - Plots

The code for generating the 10 plots.

```
1 def assignment_1e(random):
2     """
3     Execute assignment 1.e
4     Int:
5     param: random — An initialization of the random number generator.
6     """
7
8     # The relevant imports for this piece of code are:
9     # (1) matplotlib.pyplot as plt
10    # (2) numpy as np
11    # (3) scipy.stats as sp_stats
12    # (4) mathlib.statistics as ml_stats
13
14    # Load the data.
15    data = np.loadtxt('randomnumbers.txt')
16
17    # Generate the maximum amount of needed random numbers.
18    random_numbers = random.gen_normals(0, 1, int(1e5))
19
20    # The values to plot point for.
21    plot_values = np.array(10*np.arange(1, 5.1, 0.1), dtype=int)
22
23    # Pre-sort the random numbers
24    random_nums_sorted = list()
25
26    for idx, values in enumerate(plot_values):
27        random_nums_sorted.append(sorting.merge_sort(random_numbers[0:values]))
28
29
30    # Go over the columns and perform the KS-test2
31    for i in range(data.shape[1]):
32
33        # An array in which the p-values are stored for the self created
34        # ks-test2 and the scipy version.
35        p_values_self = np.zeros(len(plot_values))
36
37        # Calculate the p-values with the ks-test2
38        for idx, values in enumerate(plot_values):
39
40            # Perform the ks-test2 with the own implementation.
41            p_values_self[idx] = ml_stats.kstest2(data[:, i][0:values],
42                                                random_numbers[0:values],
43                                                random_nums_sorted[idx])
44
45        # Plot the p-values.
46        plt.plot(plot_values, p_values_self, label = 'self', color = 'orange')
47        plt.hlines(0.05, 0, 10*5, colors='red', linestyle='—')
48
49        plt.xlabel(r'Log($N_{samples}$)')
50        plt.ylabel('Probabillity (p-value)')
51        plt.xscale('log')
52        plt.legend()
53        plt.savefig("./Plots/1e_plot_column_{0}.pdf".format(i))
54        plt.figure()
```

./Code/assignment_1.py

Code - Output plot(s)

Note: Expect very similar captions for the upcoming 10 plots.

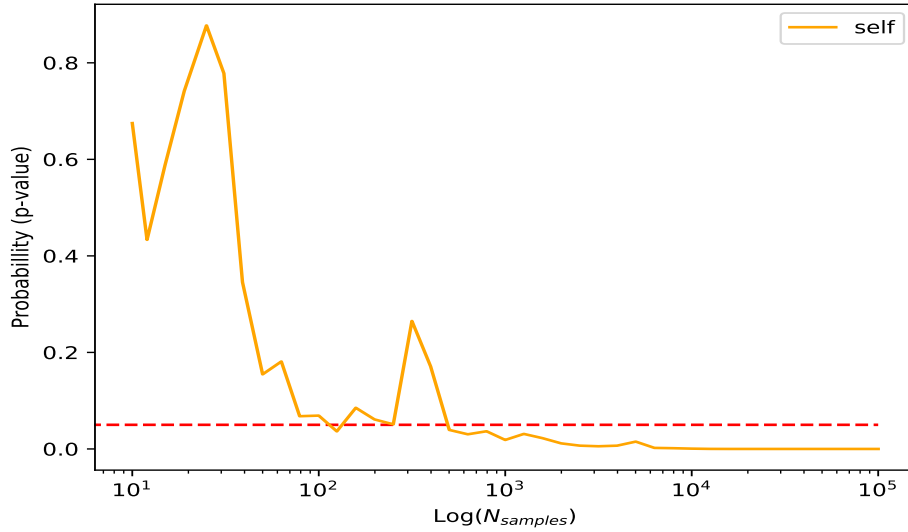


Figure 9: The P-value produced by performing the KS-test2 for a normal distribution with $\mu = 0$ and $\sigma = 1$ on the **first** column. The red line indicates the line of $p = 0.05$. A point **below** there line would suggests that there is enough statistical evidence to reject the (null) hypothesis that the data is normal distributed. The plot shows that the p-value drops below 0.05 when including all samples. There is thus enough statistical evidence to reject the hypothesis that this column is normal distributed with $\mu = 0$ and $\sigma = 1$.

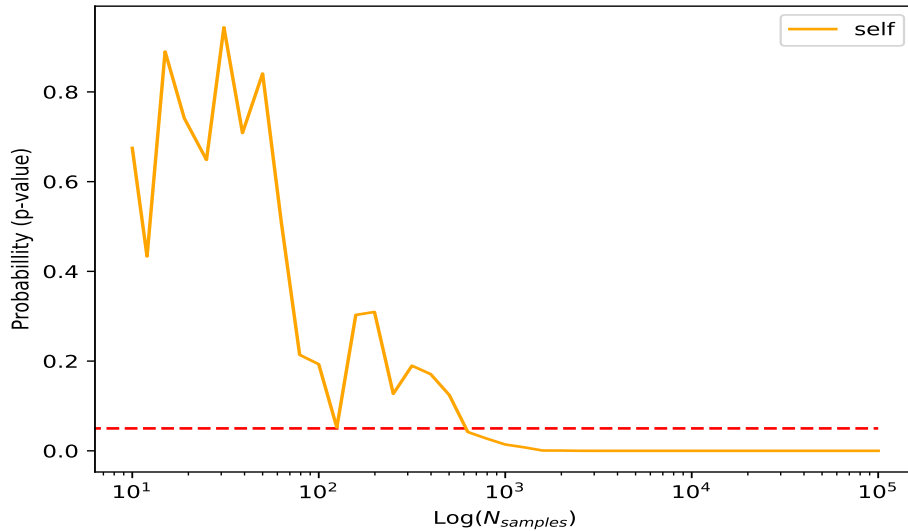


Figure 10: The P-value produced by performing the KS-test2 for a normal distribution with $\mu = 0$ and $\sigma = 1$ on the **second** column. The red line indicates the line of $p = 0.05$. A point **below** there line would suggests that there is enough statistical evidence to reject the (null) hypothesis that the data is normal distributed. The plot shows that the p-value drops below 0.05 when including all samples. There is thus enough statistical evidence to **reject** the hypothesis that this column is normal distributed with $\mu = 0$ and $\sigma = 1$.

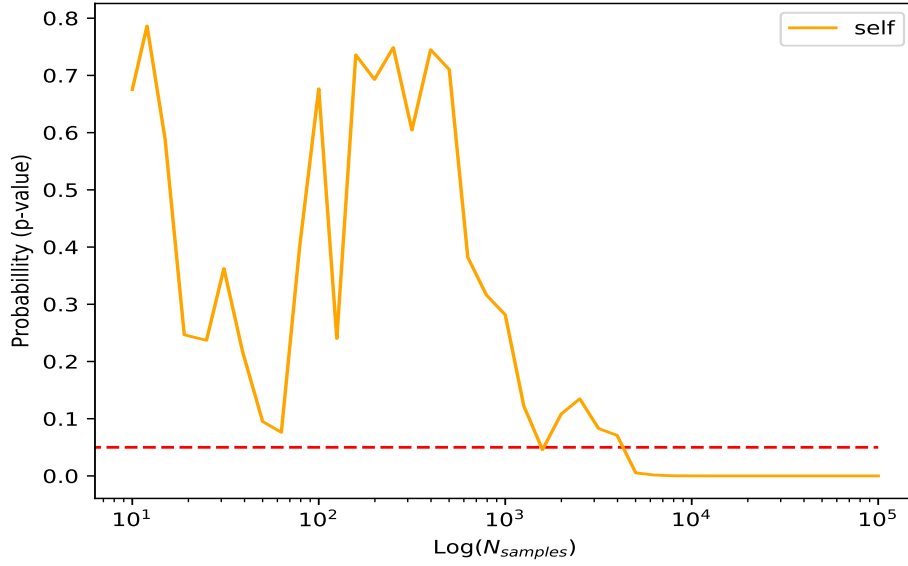


Figure 11: The P-value produced by performing the KS-test2 for a normal distribution with $\mu = 0$ and $\sigma = 1$ on the **third** column. The red line indicates the line of $p = 0.05$. A point **below** there line would suggests that there is enough statistical evidence to reject the (null) hypothesis that the data is normal distributed. The plot shows that the p-value drops below 0.05 when including all samples. There is thus enough statistical evidence to **reject** the hypothesis that this column is normal distributed with $\mu = 0$ and $\sigma = 1$.

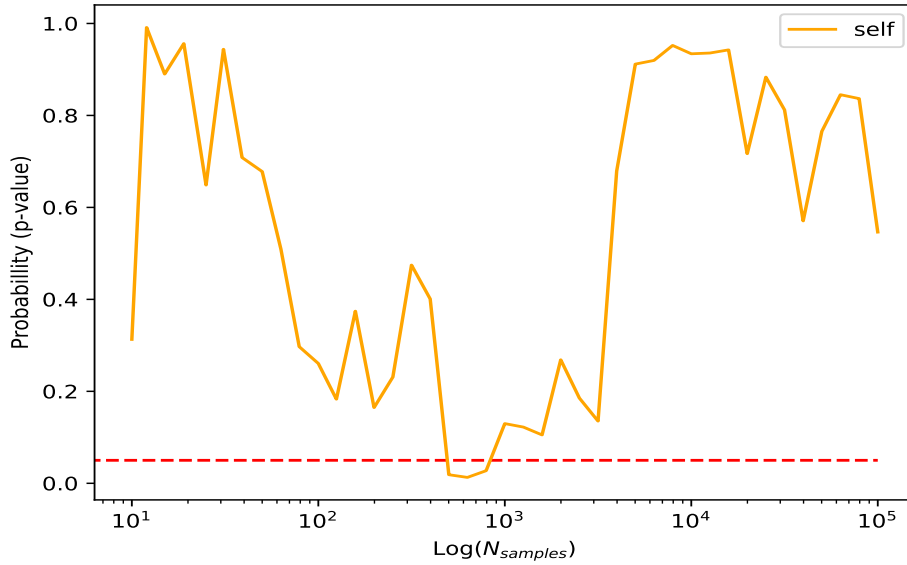


Figure 12: The P-value produced by performing the KS-test2 for a normal distribution with $\mu = 0$ and $\sigma = 1$ on the **fourth** column. The red line indicates the line of $p = 0.05$. A point **below** there line would suggests that there is enough statistical evidence to **reject** the (null) hypothesis that the data is normal distributed. The plot shows that the p-value drops below 0.05 only between 500 – 1000 samples. In all other cases it passes the KS-test. The most important point in this plot is the p-value when all samples are included. It can be clearly seen that this point isn't below the red line. The plot therefore suggests that the given c olumn might(see footnote 2 on page 12) be a Gaussian with $\mu = 0$ and $\sigma = 1$.

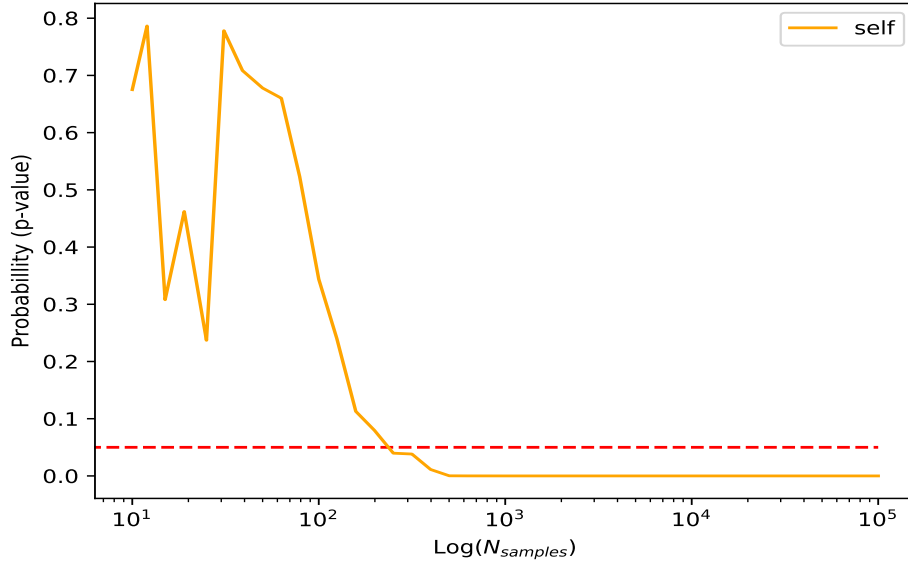


Figure 13: The P-value produced by performing the KS-test2 for a normal distribution with $\mu = 0$ and $\sigma = 1$ on the **fifth** column. The red line indicates the line of $p = 0.05$. A point **below** there line would suggests that there is enough statistical evidence to reject the (null) hypothesis that the data is normal distributed. The plot shows that the p-value drops below 0.05 when including all samples. There is thus enough statistical evidence to reject the hypothesis that this column is normal distributed with $\mu = 0$ and $\sigma = 1$.

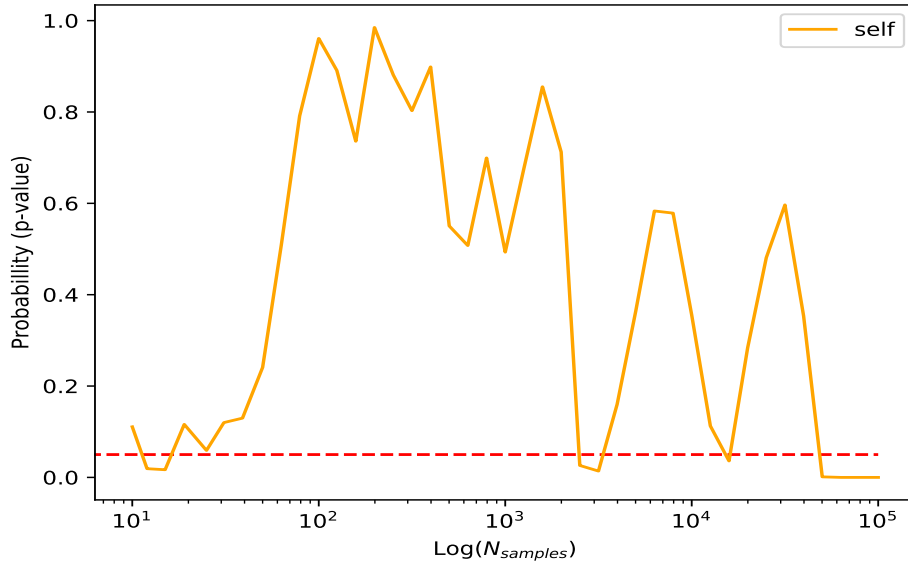


Figure 14: The P-value produced by performing the KS-test2 for a normal distribution with $\mu = 0$ and $\sigma = 1$ on the **sixth** column. The red line indicates the line of $p = 0.05$. A point **below** there line would suggests that there is enough statistical evidence to reject the (null) hypothesis that the data is normal distributed. The plot shows that the p-value drops below 0.05 and stays there when including more than half of the samples. The most important part of the figure is the part that includes most samples. There is thus enough statistical evidence to reject the hypothesis that this column is normal distributed with $\mu = 0$ and $\sigma = 1$.

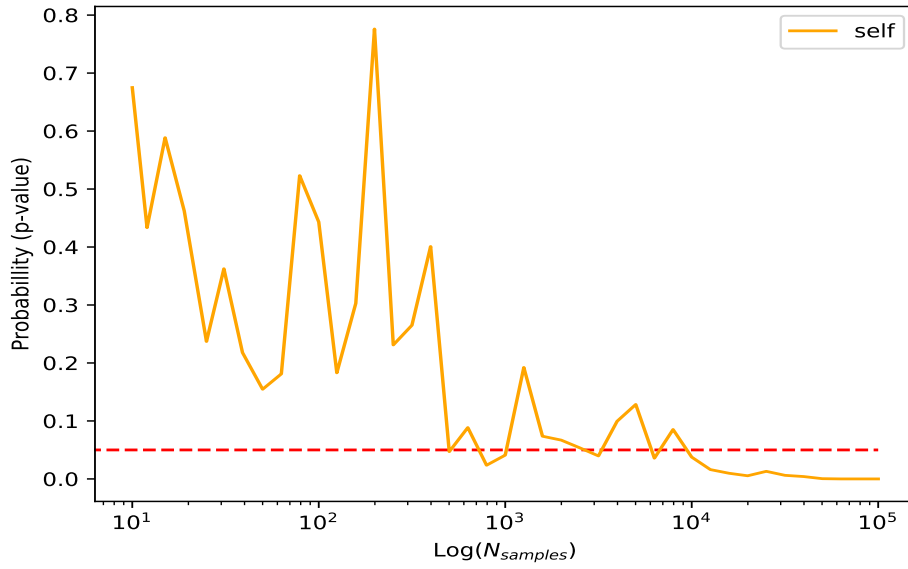


Figure 15: The P-value produced by performing the KS-test2 for a normal distribution with $\mu = 0$ and $\sigma = 1$ on the **seventh** column. The red line indicates the line of $p = 0.05$. A point **below** there line would suggests that there is enough statistical evidence to reject the (null) hypothesis that the data is normal distributed. The plot shows that the p-value drops below 0.05 when including all samples. There is thus enough statistical evidence to reject the hypothesis that this column is normal distributed with $\mu = 0$ and $\sigma = 1$.

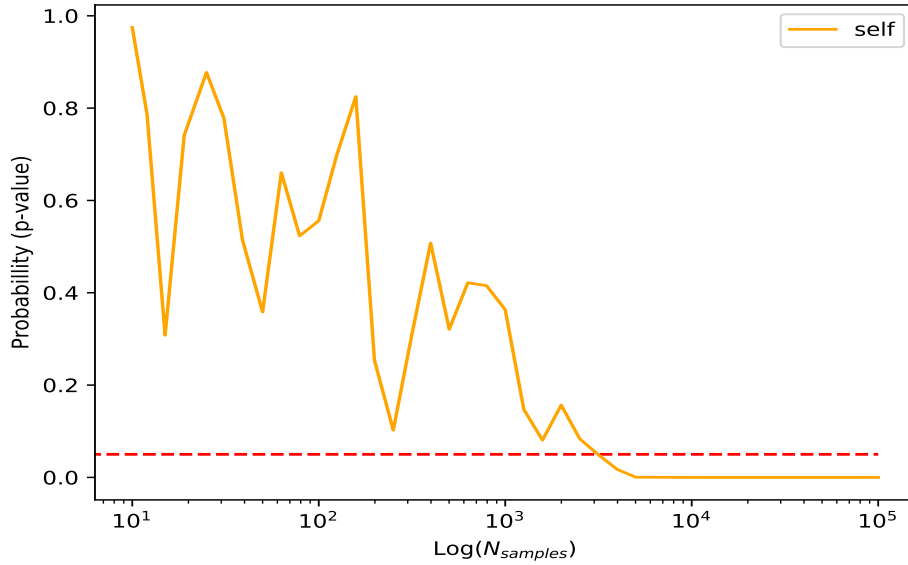


Figure 16: The P-value produced by performing the KS-test2 for a normal distribution with $\mu = 0$ and $\sigma = 1$ on the **eight** column. The red line indicates the line of $p = 0.05$. A point **below** there line would suggests that there is enough statistical evidence to reject the (null) hypothesis that the data is normal distributed. The plot shows that the p-value drops below 0.05 when including all samples. There is thus enough statistical evidence to reject the hypothesis that this column is normal distributed with $\mu = 0$ and $\sigma = 1$.

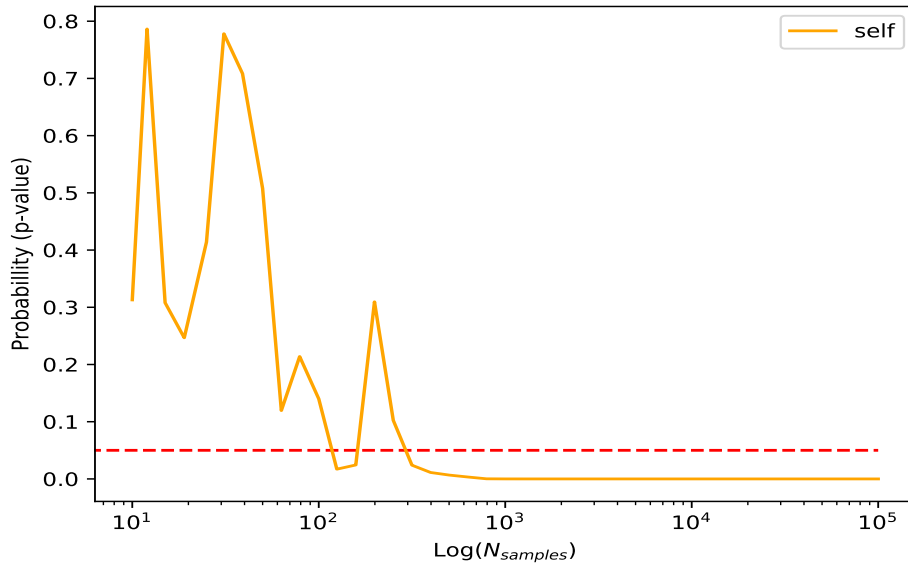


Figure 17: The P-value produced by performing the KS-test2 for a normal distribution with $\mu = 0$ and $\sigma = 1$ on the **ninth** column. The red line indicates the line of $p = 0.05$. A point **below** there line would suggests that there is enough statistical evidence to reject the (null) hypothesis that the data is normal distributed. The plot shows that the p-value drops below 0.05 when including all samples. There is thus enough statistical evidence to reject the hypothesis that this column is normal distributed with $\mu = 0$ and $\sigma = 1$.

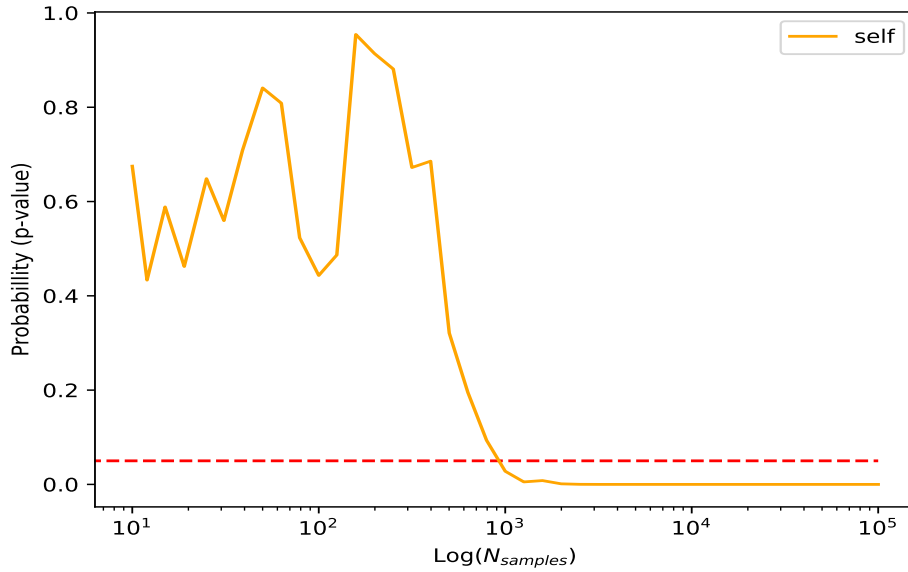


Figure 18: The P-value produced by performing the KS-test2 for a normal distribution with $\mu = 0$ and $\sigma = 1$ on the **tenth** column. The red line indicates the line of $p = 0.05$. A point **below** there line would suggests that there is enough statistical evidence to reject the (null) hypothesis that the data is normal distributed. The plot shows that the p-value drops below 0.05 when including all samples. There is thus enough statistical evidence to reject the hypothesis that this column is normal distributed with $\mu = 0$ and $\sigma = 1$.

Question 1- Summary

Summary

The current sub-section contains the summary of the code used for assignment 1. This includes the file containing all sub-questions and all used shared modules.

Code - Assignment

The code of the file that executes the sub-questions. The code presented below only consists of the part that has not yet been shown in the subquestions. This part consists of the initialization of the random number generator (1.a) and the used imports.

```
1 import astropy.stats
2 import matplotlib.pyplot as plt
3 import mathlib.random as random
4 import mathlib.sorting as sorting
5 import mathlib.statistics as ml_stats
6 import numpy as np
7 import scipy.stats as sp_stats
8
9 def main():
10     # Initialize the random number generator.
11     rng = random.Random(78379522)
12
13     # Run assignments
14     assignment_1a(rng)
15     assignment_1b(rng)
16     assignment_1c(rng)
17     assignment_1d(rng)
18     assignment_1e(rng)
```

./Code/assignment_1.py

Code - Random Number Generator

The code for the random number generator.

```
1 import numpy as np
2
3 class Random(object):
4     """
5     A class representing a random number generator (RNG)
6     """
7
8     def __init__(self, seed):
9         """
10         Create a new instance of the random number generator.
11
12         In:
13         param: seed — The seed of the random number generator.
14                    This must be a positive integer.
15         """
16
17         # The seed and state of the generator
18         self._seed = np.uint64(seed)
19         self._state = self._seed
20
21         # maximum uint32 value
22         self._uint32_max = np.uint64(0xFFFFFFFF)
23
24         # The values for the Xor shift.
25         self._xor_a1 = np.uint64(20)
26         self._xor_a2 = np.uint64(41)
27         self._xor_a3 = np.uint64(5)
28
29         # The values for the multiply with carry.
30         self._mwc_a = np.uint64(4294957665)
```

```

32         self._mwc_base = np.uint64(2**32)
33
34     def get_seed(self):
35         """
36         Get the seed that is used to initialize this generator.
37
38         Out:
39         return: The seed used to initialize the generator.
40         """
41         return self._seed
42
43     def get_state(self):
44         """
45         Get the state of the generator.
46
47         Out:
48         return: The state of the generator.
49         """
50         return self._state
51
52
53     def gen_next_int(self):
54         """
55         Generate a new random 32-bit unsigned integer.
56         Out:
57         return: A random 32-bit unsigned integer.
58         """
59
60         # The state is at the end updated with mwc.
61         # We therefore shouldn't use more than 32 bits to generate
62         # the number.
63
64         return self._update_state() & self._uint32_max
65
66     def gen_uniform(self):
67         """
68         Generate a random float between 0 and 1.
69         Out:
70         return: A random float between 0 and 1.
71         """
72
73         return self.gen_next_int()*1.0 / self._uint32_max
74
75     def gen_uniforms(self, amount):
76         """
77         Generate multiple random floats
78         between 0 and 1.
79         In:
80         param: amount — The amount of floats to generate.
81         Out:
82         return: An array with 'amount' random floats
83                 between 0 and 1.
84         """
85
86         samples = np.zeros(amount)
87
88         for i in range(amount):
89             samples[i] = self.gen_uniform()
90
91         return samples
92
93     def gen_normal(self, mean, sigma):
94         """
95         Generate a random normal distributed float.
96
97         In:
98         param: mean — The mean of the gaussian distribution.
99         param: sigma — The squareroot of the variance of the distribution.
100        Out:
101        return: A random float that is drawn from the parameterized normal
102                distribution.

```

```

103     """
104
105     # Generate two uniform variables.
106     u1 = self.gen_uniform()
107     u2 = self.gen_uniform()
108
109     # Use the box muller transformation.
110     return sigma*np.sqrt(-2* np.log(1-u1))*np.cos(2*np.pi*u2) + mean
111
112 def gen_normal_uniform(self, mean, sigma, u1, u2):
113     """
114         Generate a random normal distributed float from two provided
115         uniform variables.
116
117     """
118     pre_factor= sigma*np.sqrt(-2* np.log(1-u1))
119
120     return pre_factor*np.cos(2*np.pi*u2) + mean, pre_factor*np.sin(2*np.pi*u2
121 ) + mean
122
123 def gen_normals(self, mean, sigma, amount):
124     """
125         Generate multible random normal distributed float.
126
127     In:
128         param: mean — The mean of the gaussian distribution.
129         param: sigma — The squareroot of the variance of the distribution.
130         param: amount — The amount of floats to generate.
131     Out:
132         return: An array with random floats drawn from the parameterized
133 normal
134         distribution.
135     """
136
137     # Pre-factors in the box muller transformation.
138     square_pre_factor = -2*sigma**2
139     angle_pre_factor = 2*np.pi
140
141     # With the Box-muller two random normals can be generated for two
142     # uniforms. If the amount of requested variables is odd then add
143     # one to it and later remove it when returning the result.
144     elements = amount if amount % 2 == 0 else amount + 1
145
146     # Array in which the drawn normal distributed variables are stored.
147     normal_dist = np.zeros(elements)
148
149     # Apply the box muller transformation to generate the samples.
150     for i in range(0, elements, 2):
151
152         # Generate the uniforms.
153         u1 = self.gen_uniform()
154         u2 = self.gen_uniform()
155
156         # Calculate common terms.
157         pre_fact = np.sqrt(square_pre_factor*np.log(1-u1))
158
159         # Calculate the samples.
160         normal_dist[i] = pre_fact*np.cos(angle_pre_factor*u2) + mean
161         normal_dist[i+1] = pre_fact*np.sin(angle_pre_factor*u2) + mean
162
163     # If amount is odd, don't return the last element.
164     return normal_dist[0:amount]
165
166 def _update_state(self):
167     """
168         Update the state of the random number generator.
169
170     Out:
171         return: The new state of the random number generator.
172     """

```

```

172         self._state = self._xor_shift(self._state)
173         self._state = self._mwc(self._state & self._uint32_max) ^ self._state
174
175     return self._state
176
177
178 def _xor_shift(self, number):
179     """
180     Execute the XOR-shift algorithm on the
181     input number.
182     In:
183         param: number — The number to XOR-shift.
184     Out:
185         return: The number produced by XOR-shift.
186     """
187
188     # Shift to the right and then bitwise xor.
189     number ^= (number >> self._xor_a1)
190     # Shift to the left and then bitwise xor.
191     number ^= (number << self._xor_a2)
192     # Shift to the right and then bitwise xor.
193     number ^= (number >> self._xor_a3)
194
195     return number
196
197 def _mwc(self, number):
198     """
199     Perform multiply with carry (MWC) on
200     the given input.
201     In:
202         param: number — The number to perform MWC on, must be an uint64.
203     Out:
204         return: The new number.
205     """
206
207     return self._mwc_a * (number & (self._uint32_max - np.uint64(1))) + (
        number >> np.uint64(32))

```

./Code/mathlib/random.py

Code - Statistical functions

The code that containing all statistical functions that where needed for the sub-questions. The imported sorting module used by this piece of code can be found on page ??.

```

1 import numpy as np
2 import mathlib.sorting as sorting
3
4 def kstest(x, cdf):
5     """
6     Perform the Kolmogorov-Smirnov test for goodness of fit
7     and return the p-value.
8     In:
9         param: x — An array with value's who's CDF is expected to be
10                  the same as the provided CDF. Must be atleast size 4
11
12         param: cdf — A function that is the expected cdf under the null
13                    hypothesis.
14     Out:
15         return: The p-value obtained by performing the KS-test.
16     """
17
18     # Amount of values in the input array.
19     x_size = len(x)
20
21     # Sort the values and evaluate the cdf.
22     x_sorted = sorting.merge_sort(x)
23     x_sorted_cdf = cdf(x_sorted)

```

```

24
25 # Maximum distance.
26 max_dist = 0
27
28 # Value of the emperical cdf at step i-1.
29 x_cdf_emperical_previous = 0
30
31 # Find the maximum distance.
32 for idx in range(0, x_size):
33
34     # Calculate the emperical cdf.
35     x_cdf_emperical = (idx+1)/x_size
36     # The true cdf evaluation at the given point.
37     x_cdf_true = x_sorted_cdf[idx]
38
39     # Find the distance. The emperical
40     # CDF is a step function so there are two distances
41     # that need to be checked at each step.
42
43     # Calculate the two distances
44     distance_one = abs(x_cdf_emperical - x_cdf_true)
45     distance_two = abs(x_cdf_emperical_previous - x_cdf_true)
46
47
48     # Find the maximum of those two distances and
49     # check if it is larger than the current know maximum distance.
50     max_dist = max(max_dist, max(distance_one, distance_two))
51
52     # Save the current value of the emperical cdf.
53     x_cdf_emperical_previous = x_cdf_emperical
54
55 # Calculate the p-value with the help of the CDF.
56 sqrt_elems = np.sqrt(x_size)
57 cdf = _ks_statistic_cdf((sqrt_elems + 0.12+0.11/sqrt_elems)*max_dist)
58 return 1 - cdf
59
60
61 def kstest2(x1, x2, x2_sorted = None):
62     """
63     Perform the Kolmogorov-Smirnov test for goodness of fit
64     and return the p-value.
65     In:
66         param: x1 — An array with value's who's CDF is expected to be
67                   the same as the CDF of the provided values.
68                   Must be atleast size 4.
69
70         param: x2 — A discretized pdf of the expected distribution under the
71                   null hypothesis.
72     Out:
73         return: The p-value obtained by performing the KS-test
74     """
75
76     # Amount of values in the input distributions.
77     x1_size = len(x1)
78     x2_size = len(x2)
79
80     # Sort both arrays.
81     x1 = sorting.merge_sort(x1)
82     x2 = sorting.merge_sort(x2) if type(x2_sorted) is not None else x2_sorted
83
84     # The maximum distance
85     max_dist = 0
86
87     # The iteration values used to determine
88     # the emperical pdf's and the max distance.
89     x1_i, x2_j = 0,0
90
91     # Find the maximum distance by updating the emperical CDFs.
92     while x1_i < x1_size and x2_j < x2_size:
93
94         # Update the indices used for the emperical CDF's.

```

```

94         if x1[x1_i] < x2[x2_j]:
95             x1_i += 1
96         else:
97             x2_j += 1
98
99     # Find the max distance
100     max_dist = max(abs(x1_i/x1_size-x2_j/x2_size), max_dist)
101
102     sqrt_factor = np.sqrt((x1_size*x2_size)/(x1_size+x2_size))
103     cdf = _ks_statistic_cdf((sqrt_factor + 0.12+0.11/sqrt_factor)*max_dist)
104
105     return 1 - cdf
106
107 def kuiper_test(x, cdf):
108     """
109     Perform the Kuiper test for goodness of fit
110     and return the p-value.
111     In:
112     param: x — An array with value's who's CDF is expected to be
113              the same as the provided CDF. Must be atleast size 4
114
115     param: cdf — A function that is the expected cdf under the null
116     hypothesis.
117     Out:
118     return: The p-value obtained by performing the kuiper-test
119     """
120
121     # Sort the data in ascending order, calculate the
122     # cdf and the emperical cdf for the sorted values and
123     # save the total amount of elements we have.
124     x_sorted = sorting.merge_sort(x)
125     x_sorted_cdf = cdf(x_sorted)
126     x_elements = len(x)
127
128     # Find the maximum distance above and below
129     # the true cdf.
130     max_dist_above = 0
131     max_dist_below = 0
132
133     # Value of the cdf at step i-1.
134     x_cdf_emperical_previous = 0
135
136
137     for idx, x in enumerate(x_sorted):
138
139         # Calculate the emperical cdf.
140         x_cdf_emperical = (idx+1)/x_elements
141         # Calculate the true cdf.
142         x_cdf_true = x_sorted_cdf[idx]
143
144         # Find the maximum distance above and below
145         max_dist_above = max(x_cdf_emperical - x_cdf_true, max_dist_above)
146         max_dist_below = max(x_cdf_true - x_cdf_emperical_previous,
147                               max_dist_below)
148
149         # Update previous cdf
150         x_cdf_emperical_previous = x_cdf_emperical
151
152     sqrt_elem = np.sqrt(x_elements)
153     v = max_dist_above + max_dist_below
154     cdf = _kuiper_statistic_cdf((sqrt_elem + 0.155+0.24/sqrt_elem)*v)
155
156     return 1 - cdf
157
158 def _ks_statistic_cdf(z):
159     """
160     An approximation for the cdf of the
161     Kolmogorov-Smirnov (KS) test staistic.
162     In:

```



```

163     param: z — The value to calculate the cdf at.
164 Out:
165     return: An approximation of the cdf for the given value.    print(
max_dist_above + max_dist_below)
166 """
167
168 # Numerical approximation taken from:
169 # Numerical methods – The art of scientific computation.
170 # Third edition.
171
172 if z < 1.18:
173     exponent = np.exp(-np.pi**2/(8*z**2))
174     pre_factor = np.sqrt(2*np.pi)/z
175
176     return pre_factor*exponent*(1+ exponent**8)*(1+exponent**16)
177 else:
178     exponent = np.exp(-2*z**2)
179     return 1-2*exponent*(1-exponent**3)*(1-exponent**6)
180
181 def _kuiper_statistic_cdf(z):
182     """
183     An approximation for the cdf of the
184     Kuiper test statistic
185 In:
186     param: z — The value to calculate the cdf at.
187 Out:
188     return: An approximation of the cdf for the given value.
189 """
190
191 # Value of z is too small, sum will be 1 up to 7 digits
192 if z < 0.4:
193     return 1
194
195 # Approximate value of the sum by performing 100 iterations
196
197 # The value to return
198 ret = 0
199 # A term often needed in the sum.
200 z_squared = z**2
201
202 # Evaluate the first 100 terms in the sum.
203 for j in range(1, 100):
204     power = j**2 * z_squared
205     ret += (4 * power - 1)*np.exp(-2*power)
206
207 return 1- 2*ret
208
209
210
211 def normal_cdf(x, mean = 0, sigma = 1):
212     """
213     Evaluate the cumulative normal distribution for
214     the given parameters
215 In:
216     param: x — The point to evaluate the cdf at or an array of points to
evaluate it for.
217     param: mean — The mean of the normal distribution.
218     param: sigma — The square root of the variance for the normal
distribution.
219 Out:
220     return: The cumulative normal distribution evaluated at.
221 """
222
223 # Calculate the CDF using the erf function (defined below).
224 return 0.5 + 0.5*erf((x-mean)/(np.sqrt(2)*sigma))
225
226
227 def normal(x, mean = 0, sigma = 1):
228     """
229     Evaluate the normal distribution for the given
230     parameters.

```

```

231 In:
232     param: x — The point to evaluate the distribution at.
233     param: mean — The mean of the distribution.
234     param: sigma — The square root of the variance for the distribution.
235 Out:
236     return: The value of the parameterized distribution evaluated at the
237     given point.
238     """
239     return 1/((np.sqrt(2*np.pi)*sigma))*np.exp(-0.5*((x - mean)/sigma)**2)
240
241 def erf(x):
242     """
243     Evaluate the erf function for a value of x.
244 In:
245     param: x — The value to evaluate the erf function for.
246 Out:
247     return: The erf function evaluated for the given value of x.
248     """
249
250     # Numerical approximation taken from Abramowitz and Stegun.
251
252     # Constants for the numerical approximation
253     p = 0.3275911
254     a1 = 0.254829592
255     a2 = -0.284496736
256     a3 = 1.421413741
257     a4 = -1.453152027
258     a5 = 1.061405429
259
260     # Array in which the result is stored
261     ret = np.zeros(len(x))
262
263     # The approximation functions
264     erf_func_t_val = lambda x: 1/(1+ p*x)
265     erf_func_approx = lambda t, x : 1 - t*(a1 + t*(a2 + t*(a3 + t*(a4 + t*a5))))
266     *np.exp(-x**2)
267
268     # Evaluate for both positive and negative
269     neg_mask = x < 0
270     neg_x = x[neg_mask]
271     pos_mask = x >= 0
272     pos_x = x[pos_mask]
273
274     ret[neg_mask] = -erf_func_approx(erf_func_t_val(-neg_x), -neg_x)
275     ret[pos_mask] = erf_func_approx(erf_func_t_val(pos_x), pos_x)
276
277     return ret

```

./Code/mathlib/statistics.py

Code - Sorting

The sorting algorithm used to sort the input of the KS-test and Kuiper-test.

```

1 import numpy as np
2
3 def merge_sort(array):
4     """
5     Sort an array using merge sort
6
7 In:
8     param: array — The array to sort.
9 Out:
10    return: The sorted array.
11    """
12
13    # Get the length of the array.
14    size = len(array)

```

```

15
16 # If the length is 1 then return the input array.
17 # This is an important check as this function is called
18 # recursively.
19 if size == 1:
20     return array
21
22 # Split the array in an sorted left and right segment.
23 left_sorted = merge_sort(array[:size >> 1])
24 right_sorted = merge_sort(array[size >> 1:])
25 left_sorted_len = len(left_sorted)
26 right_sorted_len = len(right_sorted)
27
28 #
29 # Merge the left and right array.
30 #
31
32 # The final sorted array.
33 result = np.zeros(size)
34
35 # Current index in the left sorted array.
36 left_idx = 0
37 # Current index in the right sorted array.
38 right_idx = 0
39 # Current index in the final sorted array.
40 result_idx = 0
41
42 # While we didn't fill the result array.
43 while result_idx < size:
44
45     # Element from left array is smaller, insert it and increase position.
46     if left_sorted[left_idx] < right_sorted[right_idx]:
47         result[result_idx] = left_sorted[left_idx]
48         left_idx += 1
49         result_idx += 1
50     # Element from right array is smaller, insert it and increase position.
51     else:
52         result[result_idx] = right_sorted[right_idx]
53         right_idx += 1
54         result_idx += 1
55
56     # Only right array has elements left, insert the remaining elements.
57     if left_idx == left_sorted_len:
58         result[result_idx:] = right_sorted[right_idx:]
59         break
60
61     # Only left has elements left, insert the remaining elements
62     if right_idx == right_sorted_len:
63         result[result_idx:] = left_sorted[left_idx:]
64         break
65
66 return result

```

./Code/mathlib/sorting.py

2 - Normally distributed pseudo-random numbers

Question 2

Problem

Make plots of three Gaussian random fields, using $n = -1$, $n = -2$ and $n = -3$. Give the plots a size of 1024. The axis should be in physical size. Choose a minimum physical size and explain how this impacts the maximum physical size, the minimum k and maximum k .

Solution

The Gaussian fields are initially created in k -space by using Fourier shifted coordinates (i.e. the zeroth wavenumber corresponds with the left top and not the center) and are then inverse Fourier transformed. The method in which a field is created in k -space consists of two steps. One, the shifted wavenumbers are used to create a matrix with complex numbers based on the power spectrum. Two, the matrix is given the correct hermitian symmetry. The first step is briefly explained in the code. The second step, how the matrix is given the correct symmetry, is described below.

The matrix has the correct symmetry if the complex number created with wavenumbers k_{x_i}, k_{y_j} is equal to the conjugate of the complex number created with wavenumbers $-k_{x_i}, -k_{y_j}$. Let N be the size of the $N \times N$ matrix created in step one and let $c_{i,j}$ be the value in cell i, j . The matrix then has the correct hermitian symmetry if the following three points hold,

- A **First row**: The value of matrix cell $c_{0,j}$ should be equal to the complex conjugate of the value in cell $c_{0,N-j}$, for $0 < j < N$. If N is even then the value in cell $c_{0,N/2}$ should be equal to its own conjugate (i.e. this value should only have a real component, because it is created with k_0 and $k_{nyquist}$).
- B **First column**: This point is similar to the first point. The value of matrix cell $c_{i,0}$ should be equal to the complex conjugate of the value in the cell $c_{N-i,0}$, for $0 < i < N$. If N is even then the value in cell $c_{N/2,0}$ should be equal to its own conjugate (i.e. this value should only have a real component, because it is created with $k_{nyquist}$ and k_0).
- C **Inner matrix**: The value in cell $c_{i,j}$ should be equal to the complex conjugate in cell $c_{N-i,N-j}$ with $1 \leq i, j < N$. If the matrix is even then cell $c_{N/2,N/2}$ must be real, as it is created with $k_{nyquist}, k_{nyquist}$.

The code that uses these properties to give the matrix the correct symmetry can be found on the next page.

The minimum physical size, the size of 1 cell, is chosen to be 1 Mpc. This immediately fixes the maximum physical size as the grid must be 1024×1024 . The maximum physical size is thus $1 \text{ Mpc} \times 1024 = 1024 \text{ Mpc}$. The minimum k and maximum k are fixed by the minimum and maximum size,

$$k_{min} = \frac{2\pi}{(N \times \text{min distance})} = \frac{2\pi}{\text{max distance}} \quad (16)$$

$$k_{max} = k_{nyquist} = \frac{2\pi N}{2 \times (N \times \text{min distance})} = \frac{\pi}{\text{min distance}} \quad (17)$$

An increase in minimum distance would thus result in a smaller value for k_{min} and a smaller value of k_{max} .

The code that creates the fields and gives them the correct symmetry, can as mentioned before, be found below. **Important** to point out is that the same random uniform variables have been Box-Muller transformed to create the fields for the different powers, $n = -1$, $n = -2$, $n = -3$. This was done to save computational time and has as consequence that the three created plots show the evolution of the fluctuations as function of the power n (i.e. the second plot and third plot show the same kind of structure, only with a different intensity).

Code

The code is split over two files. The first file contains the code for the plots and the second file contains the code for the helper functions.

Code - Plots

The code for the creation of the plots.

```
1 import numpy as np
2 import matplotlib.pyplot as plt
3 import mathlib.random as rnd
4 import mathlib.misc as misc
5
6 # Constants.
7 grid_size = 1024
8 min_distance = 1 # size of a single cell in Mpc.
9
10 # Create the random number generator.
11 random = rnd.Random(78379522)
12
13 # The orders of the power spectrum.
14 powers = [-1, -2, -3]
15
16 def main():
17
18     # Generate the random uniform numbers that
19     # are later transformed to normal distributed variables.
20     # The numbers are generated once to reduce computational time.
21     random_numbers = random.gen_uniforms(grid_size*grid_size*2)
22
23     # Create the plots for n = -1, n = -2, n = -3
24     for power in powers:
25
26         # Generate the field matrix.
27         matrix = misc.generate_matrix_2D(grid_size, min_distance,
28                                         gen_complex, random_numbers, power)
29
30         # Give it the correct symmetry.
31         field = misc.make_hermitian_2D(matrix)
32
33         # Plot it
34
35         # The field is real, but it is still treated as a complex
36         # value this, we have to take the real part. It is also multiplied
37         # by grid_size^2 to correct for the normalization constant
38         # in np.fft.ifft2.
39
40         plt.imshow(np.fft.ifft2(field).real * grid_size*grid_size)
41         plt.xlabel('Distance [Mpc]')
42         plt.ylabel('Distance [Mpc]')
43         plt.title('n = {0}'.format(power))
44         plt.colorbar()
45         plt.savefig('./Plots/2_field_{0}.pdf'.format(power))
46         plt.figure()
47
48 def gen_complex(k, n, rand1, rand2):
49     """
50     Generate a complex number using the power
51     spectrum.
52
53     In:
54     param:k — The magnitude of the wavenumber.
55     param:n — The order of the power law.
56     param: rand1 — A random uniform variable between 0 and 1.
57     param: rand2 — A random uniform variables between 0 and 1.
58
59     """
60     sigma = 0
61
62     if n == -2:
```

```

63     sigma = 1/k
64 else:
65     sigma = np.sqrt(k**n)
66
67 # Determine the complex value
68 a,b = random.gen_normal_uniform(0,sigma ,rand1 ,rand2)
69 return complex(a,b)
70
71
72
73 if __name__ == "__main__":
74     main()

```

./Code/assigment_2.py

Code - Symmetry

The code containing the functions to create the matrix and give it the correct symmetry. Only part of this file is shown, the full file is shown in assignment 4.

```

1 import numpy as np
2
3 def gen_wavenumbers(size , min_distance):
4     """
5         Generate the shifted wavenumbers
6         for the discrete fourier transform.
7     In:
8         param: size — The size of the matrix.
9         param: min_distance — The distance of a cell/ the sample spacing.
10    Out:
11        return: An array with shifted wave numbers.
12    """
13    # Array to return.
14    ret = np.zeros(size)
15
16    # Positive values
17    ret[0:int(size/2)+1] = np.arange(0,int(size/2)+1)
18
19    if size % 2 == 0: # even
20        ret[int(size/2):] = -np.arange(int(size/2),0,-1)
21    else: # odd
22        ret[int(size/2)+1:] = -np.arange(int(size/2),0,-1)
23
24
25    return (ret/(size*min_distance))*2*np.pi
26
27
28 def generate_matrix_2D(size , min_distance , func , random_numbers , power):
29     """
30         Generate a 2D matrix with complex numbers in
31         shifted fourier coordinates using the power spectrum
32     In:
33         param: size — The size of the matrix (size x size).
34         param: min_distance — The physical size of 1 cell.
35         param: func — A functiion that takes the power and to random uniform
36                        variables to calculate the correct complex number.
37         param: random_numbers — An array with random uniform numbers.
38                        Must be of atleast size: size x size x 2.
39         param: power — The power of the power spectrum to create the matrix for.
40    Out:
41        return: A 2D matrix with complex numbers assigned by the power spectrum
42                in fourier shifted coordinates.
43    """
44
45    # Generate the shifted wavenumbers
46    wavenumber = gen_wavenumbers(size , min_distance)
47    # The matrix to return
48    ret = np.zeros((size , size),dtype=complex)
49
50    # A counter for the random uniform variables.
51    steps = 0

```

```

52
53 # Fill the matrix
54 for i in range(size):
55     for j in range(size):
56
57         # Element of k_0,k_0 is left zero.
58         if i == 0 and j == 0:
59             continue
60
61         # Calculate the magnitude of the wavenumbers.
62         k = np.sqrt(wavenumber[i]**2 + wavenumber[j]**2)
63         # Fill the matrix.
64         ret[i][j] = func(k, power,
65                           random_numbers[steps], random_numbers[steps+1])
66         steps += 2
67
68 # Return the matrix
69 return ret
70
71
72 def make_hermitian2D(matrix):
73     """
74         Give a matrix in shifted fourier coordinates
75         the correct hermitian symmetry so that the ifft is real.
76     In:
77         param: matrix — The matrix to give the correct symmetry.
78     Out:
79         return: A matrix with the correct hermitan symmetry so that the
80                ifft is real.
81     """
82
83     # The size of the matrix
84     size = matrix.shape[0]
85
86     # Loop over the rows
87     for row in range(1, int(size/2) + 1):
88
89         # Give the first column (index 0) has the correct symmetry (see report
90         # point A)
91         matrix[row,0] = complex(matrix[size-row,0].real,
92                                 - matrix[size-row,0].imag)
93         # Give the first row (index 0) the correct symmetry (see report point B)
94         matrix[0, row] = complex(matrix[0, size-row].real,
95                                 - matrix[0,size-row].imag)
96
97         # Give the inner matrix the correct symmetry (see report point C)
98         for column in range(1, size):
99             matrix[row, column] = complex(matrix[size-row, size-column].real,
100                                             -matrix[size-row, size-column].imag)
101
102     # Corrections for even matrix
103     if size % 2 == 0:
104         matrix[int(size/2), 0] = matrix[int(size/2), 0].real + 0J
105         matrix[0, int(size/2)] = matrix[0, int(size/2)].real + 0J
106         matrix[int(size/2), int(size/2)] = matrix[int(size/2), int(size/2)].real
107         + 0J
108
109     # Return the matrix.
110     return matrix

```

./Code/mathlib/misc.py

Plots - Fields

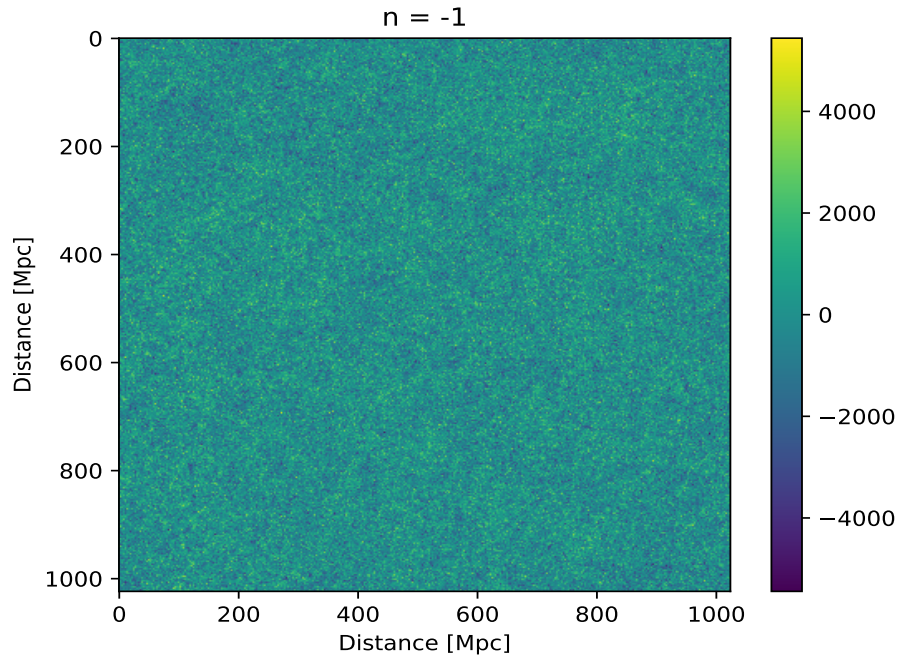


Figure 19: The Gaussian field for $n = -1$ and a minimal physical size of 1 Mpc. The power drops for $n = -1$ slowly, as result, mainly noise is expected. The plot seems to show that this is the case.

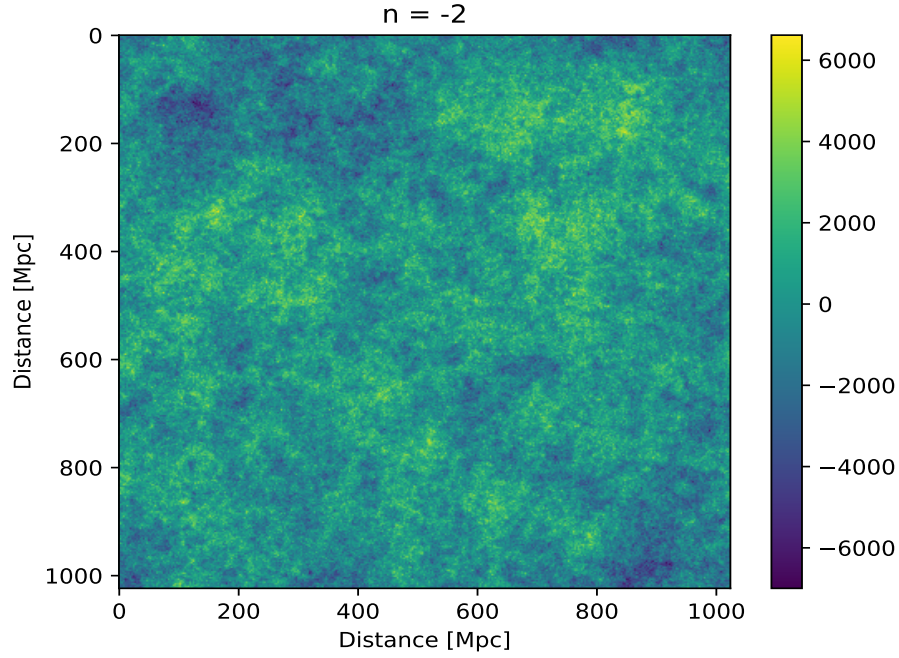


Figure 20: The Gaussian field for $n = -2$ and a minimal physical size of 1 Mpc. The plot seems to be less noisy than the previous plot, which is expected as n is now smaller.

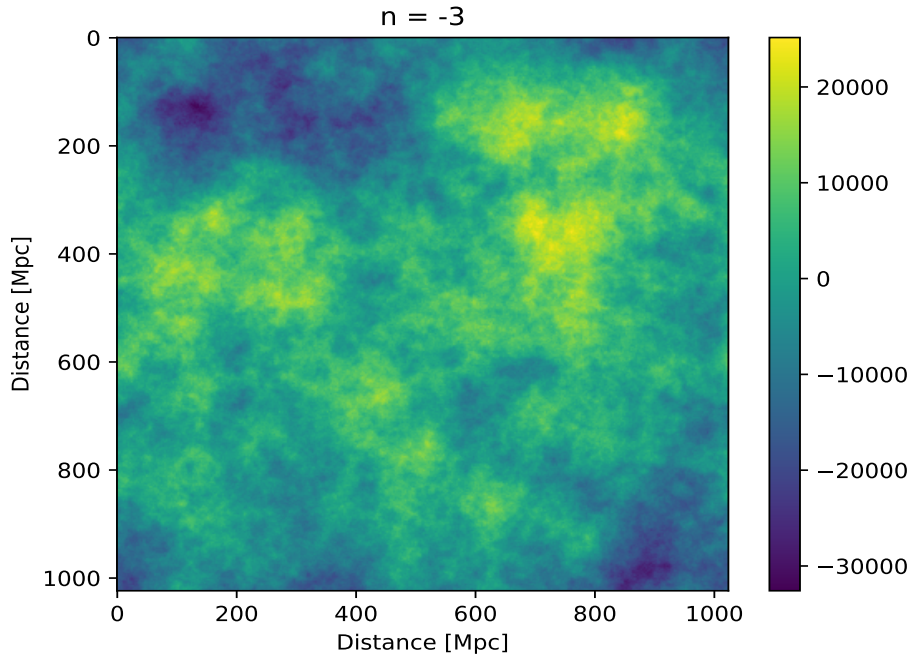


Figure 21: The Gaussian field for $n = -3$ and a minimal physical size of 1 Mpc. High and low density fluctuations are now clearly visible. Notice that the plot looks similar to the plot for $n = -2$. This is a consequence of using the same random uniform variables in the Box-Muller method.

3 - Linear structure growth

Question 3

Problem

Solve the ODE of equation ?? for the 3 given initial conditions in an matter-dominated Einstein de Sitter Universe. Use an appropriate numerical method. Compare the results with the analytical solution of the ODE. Plot the solution for $t = 1$ until $t = 1000$ yr, use a log log plot.

$$\frac{d^2 D}{dt^2} + 2 \frac{\dot{a}}{a} \frac{dD}{dt} = \frac{3}{2} \omega_0 H_0^2 \frac{1}{a^3} D \quad (18)$$

Initial conditions:

$$(A) D(1) = 3, D'(1) = 2 \quad (B) D(1) = 10, D'(1) = -10 \quad (C) D(1) = 5, D'(1) = 0$$

Solution

The solution of this problem consist of three parts. One, a rewritten version of equation ?? with the scale factor plugged in. Two, a derivation of the analytical solution. Three, a (brief) explanation on how this rewritten version is used numerically.

(1) Rewriting the ODE.

The numerical and analytical solution both require a version of equation ?? with the scale factor plugged in. For an Einstein-de Sitter Universe the scale factor and its derivative are given by,

$$a(t) = \left(\frac{3}{2} H_0 t \right)^{2/3} \quad \text{and} \quad \dot{a}(t) = H_0 \left(\frac{3}{2} H_0 t \right)^{-1/3} \quad (19)$$

Plugin this in by equation 18 and using that $\Omega_0 = 1$ results in the rewritten version,

$$\frac{d^2 D}{dt^2} + \frac{H_0 \left(\frac{3}{2} H_0 t\right)^{-1/3}}{\left(\frac{3}{2} H_0 t\right)^{2/3}} \frac{dD}{dt} - \frac{3}{2} \Omega_0 \frac{H_0^2}{\left(\frac{3}{2} H_0 t\right)^{2/3}} D = 0 \quad (20)$$

$$\frac{d^2 D}{dt^2} + \frac{4}{3t} \frac{dD}{dt} - \frac{2}{3t^2} D = 0 \quad (21)$$

(2) Analytical solution

The analytical solution that is required for the plots can be found by solving equation 21. The equation is solved by finding two particular solutions. These can be found by finding the values of lambda for which the the ansatz $D(t) = t^\lambda$ holds. Plugin in the ansatz yields,

$$\lambda(\lambda - 1)t^{\lambda-2} + \frac{4}{3t}\lambda t^{\lambda-1} - \frac{2}{3t^2}t^\lambda = 0 \quad (22)$$

This simplifies to

$$\begin{aligned} 0 &= \lambda(\lambda - 1)t^\lambda + \frac{4}{3}\lambda t^\lambda - \frac{2}{3}t^\lambda \\ &= \lambda(\lambda - 1) + \frac{4}{3}\lambda - \frac{2}{3} \\ &= \lambda^2 + \frac{1}{3}\lambda - \frac{2}{3} \\ &= (\lambda + 1)\left(\lambda - \frac{2}{3}\right) \end{aligned}$$

From the above expression it can be seen that peculiar solutions of the ODE are given by,

$$D(t) = t^{-1} \quad D(t) = t^{2/3} \quad (23)$$

The general solution is the superposition of the peculiar solutions with constants and can therefore be written as,

$$D(t) = c_1 t^{2/3} + c_2 t^{-1} \quad (24)$$

The constants for the three initial cases can be found by calculating the derivative of the above equation and solving the system for the derivative and the non derivative. This yields for the three cases that,

$$(A) \ c_1 = 3, c_2 = 0 \quad (B) \ c_1 = 0, c_2 = 10 \quad (C) \ c_1 = 3, c_2 = 2 \quad (25)$$

(3) Numerical solution

The numerical solution is obtained by first writing equation 21 as a system of first order ODE's and then by applying the Dormand Prince version of the Runge-kutta method. The second order ODE can be written as a system of first order ODE's by substituting $dD/dt = u$. The system then becomes,

$$\begin{cases} \frac{dD}{dt} &= u \\ \frac{d^2 D}{dt^2} &= -\frac{4}{3t}u + \frac{2}{3t^2}D \end{cases} \quad (26)$$

The above system is as mentioned before solved with the Dormand Prince version of the Runge-Kutta method. The algorithm uses an adaptive step size that is initial set to $t_{step} = 0.01$ year for all cases. The code that is used to solve the ODE numerically and generates the plots is split over two files. The first file generates the plots and the second file contains the implementation of the Dormand Prince version of the Runge-Kutta method. The code and its output can be found below.

Code - Plots

The code that created the plots for the three given initial conditions of the ODE.

```
1 import numpy as np
2 import mathlib.ode as ml_ode
3 import matplotlib.pyplot as plt
4
5 def main():
6
7     # The constants of the analytical solution for the 3 cases.
8     c1_cases = [3, 0, 3]
9     c2_cases = [0, 10, 2]
10
11     # The initial conditions for the ODE solver of the 3 cases.
12     initial = [[3,2],[10, -10], [5,0]]
13
14     # The start and stop time to solve the ODE for.
15     t_start = 1 # year
16     t_stop = 1000 # years
17
18     # Initial step size for the numerical solution
19     t_step = 0.01 # year
20
21     # The time values to plot the analytical solution for.
22     t_plot = np.arange(t_start, t_stop+t_step, t_step)
23
24     # Create the plots
25     for case in range(len(c1_cases)):
26
27         # Constants for the analytical solution.
28         c1 = c1_cases[case]
29         c2 = c2_cases[case]
30
31         # Initial conditions for the numerical solution
32         initial_cond = np.array(initial[case])
33
34         # The analytical solution.
35         analytical = lambda t: c1*t**(2/3)+ c2*t**(-1)
36
37         # The numerical solutions.
38         sol_num, time = ml_ode.runge_kutta_54(_linear_density_growth,
39                                             initial_cond,
40                                             t_start, t_stop, t_step,
41                                             1e-6, 1e-3)
42
43         # Plot the analytical and numeric solution.
44         plt.plot(t_plot, analytical(t_plot), label='Analytical',
45                 linestyle=':', zorder=0.1)
46         plt.plot(time, sol_num[:,0], label='Numeric', zorder=0)
47         plt.xlabel('Time [year]')
48         plt.ylabel('D(t)')
49         plt.loglog()
50         plt.legend()
51         plt.savefig('./Plots/3_ode-{:0}.pdf'.format(case))
52         plt.figure()
53
54
55 def _linear_density_growth(values, t):
56     """
57     A function representing the system of ODE's that needs
58     to be solved for the linear density growth equation.
59
60     In:
61         param: values — The current values of the linear growth function and its
62             derivatie.
63         param: t — The current time step for which the ODE is integrated.
64
65     Out:
66         return: An array representing the system of first order ODE's for the
67             given parameters.
68     """
69
70     # Current value of the linear growth function.
```

```

67     d = values[0]
68     # Current value of the derivative of the linear growth function.
69     u = values[1]
70
71     # The two systems of first order ODE's.
72     first = u
73     second = -(4/(3*t))*u + (2/(3*t**2))*d
74
75     return np.array([first, second])
76
77
78 if __name__ == '__main__':
79     main()

```

./Code/assignment.3.py

Code - Runge-Kutta

The code for the Dormand Prince version of the Runge kutta method.

```

1  import numpy as np
2
3
4  def runge_kutta_54(func, y0, t_start, t_stop, t_step, atol=1e-6, rtol=1e-3):
5      """
6          Perform the 4th order runge-kutta method for first order ODE integration
7          .
8          In:
9              param: func — The function describing the differential equation or the
10                  system
11                  of first order ODEs to integrate. Must return a numpy
12                  array.
13              param: y0 — The initial conditions.
14              param: t_start — The time to start integration at.
15              param: t_stop — The time to stop integration at.
16              param: t_step — The initial step size to use.
17              param: steps — The step size to use for integration.
18              param: order — The order of the algorithm to use.
19      """
20
21      # If true, solving a single ODE, else solving a system.
22      if type(y0) is not np.ndarray:
23          y0 = np.array([y0]) # convert to array
24
25      # Array with values to return, for both the integrated
26      # values and the time stems. The size is increased by a
27      # factor of 2 when needed.
28
29      ret = np.zeros((int((t_stop-t_start)/t_step)+1, len(y0)))
30      time = np.zeros(int((t_stop-t_start)/t_step)+1)
31
32      # Set initial state.
33      ret[0] = y0
34      time[0] = t_start
35
36      # Solve the ODE or the system of ODEs
37      min_update_scale = 0.2
38      max_update_scale = 10
39
40      # Current time at the integration
41      t_now = t_start
42      # Total amount of executed steps
43      steps = 1 # skip zero
44
45      # Current error
46      error = 1.1
47      y_next = 0
48
49      while t_now <= t_stop:

```

```

49
50 # Check if we need to expand the return arrays
51 if steps >= ret.shape[0]:
52     ret_old = ret.copy()
53     ret = np.zeros((ret_old.shape[0]*2, ret_old.shape[1]))
54     ret[0:steps] = ret_old
55
56     time_old = time.copy()
57     time = np.zeros(time_old.shape[0]*2)
58     time[0:steps] = time_old
59
60
61 # Get the value found at the previous step
62 previous = ret[steps-1]
63
64 # Calculate the constants for the Dormand Prince Runge kutta method.
65
66 # Appologies if this looks ugly in the report.
67 k1 = t_step*func(previous, t_now)
68 k2 = t_step*func(previous + (1/5)*k1, t_now + (1/5)*t_step)
69 k3 = t_step*func(previous + (3/40)*k1 + (9/40)*k2, t_now + (3/10)*t_step)
70 k4 = t_step*func(previous + (44/45)*k1 - (56/15)*k2 + (32/9)*k3, t_now +
71 (4/5)*t_step)
72 k5 = t_step*func(previous + (19372/6561)*k1 - (25360/2187)*k2 +
73 (64448/6561)*k3 - (212/729)*k4, t_now + (8/9)*t_step)
74 k6 = t_step*func(previous + (9017/3168)*k1 - (355/33)*k2 + (46732/5247)*
75 k3 + (49/176)*k4 - (5103/18656)*k5, t_now + t_step)
76
77 # Calculate the new value.
78 y_next = previous + ( (35/384)*k1 + (500/1113)*k3 + (125/192)*k4 -
79 (2187/6784)*k5 + (11/84)*k6)
80 y_embedded = previous + ( (5179/57600)*k1 + (7571/16695)*k3 + (393/640)*
81 k4 - (92097/339200)*k5 + (187/2100)*k6 )
82
83 # Calculate error
84 delta = abs(y_embedded - y_next)
85 scale = atol+np.maximum(abs(previous),abs(y_next))*rtol
86 error = np.sqrt(np.sum((delta/scale)**2)/len(k1))
87
88 # The factor used to calculate the new step size.
89 update_scale = 0.9*(error)**(-0.2)
90
91 # Make sure the factor is not too large or too small.
92 if error == 0:
93     update_scale = max_update_scale
94 elif update_scale < min_update_scale:
95     update_scale = min_update_scale
96 elif update_scale > max_update_scale:
97     update_scale = max_update_scale
98
99 # Check if the current step should be accepted.
100 if error > 1: # reject
101     t_step *= min(update_scale, 1.0)
102 else: # accept
103     t_now += t_step
104     t_step *= update_scale
105
106     ret[steps] = y_next
107     time[steps] = t_now
108     steps += 1
109
110 return ret[0:steps], time[0:steps]

```

./Code/mathlib/ode.py

Code - Output plot(s)

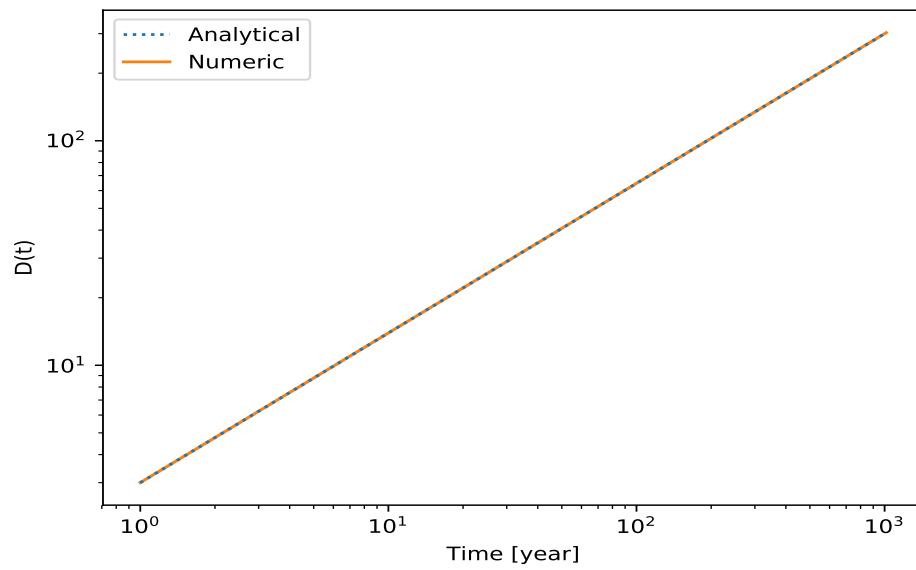


Figure 22: The analytical (blue) and numerical (orange) solution of the ODE with initial conditions $D(1) = 3, D'(1) = -10$. The plots show that the numerical solution does not appear to have a visible deviation from the analytical solution for the given time interval.

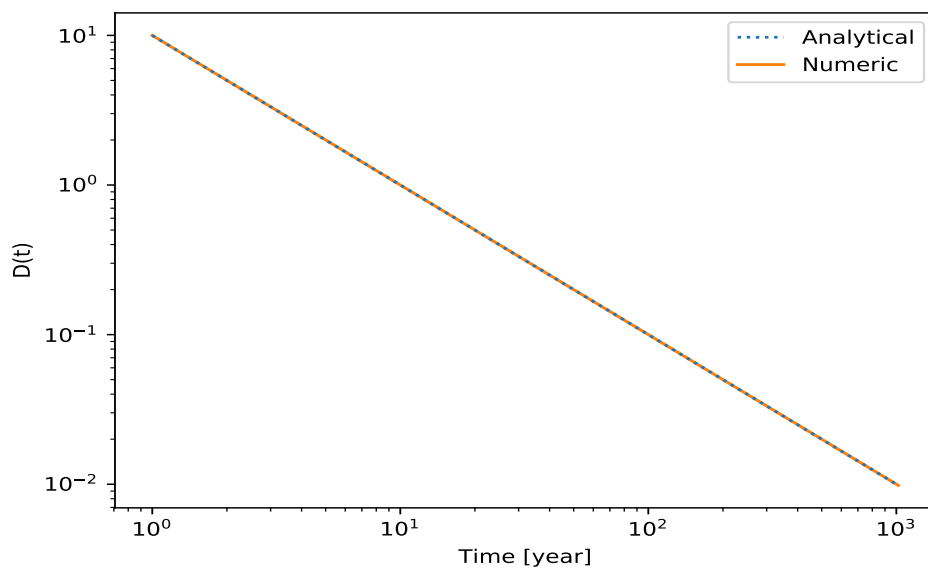


Figure 23: The analytical (blue) and numerical solution (orange) of the ODE with initial conditions $D(1) = 10, D'(1) = -10$. The plots show that the numerical solution does not appear to have a visible deviation from the analytical solution for the given time interval.

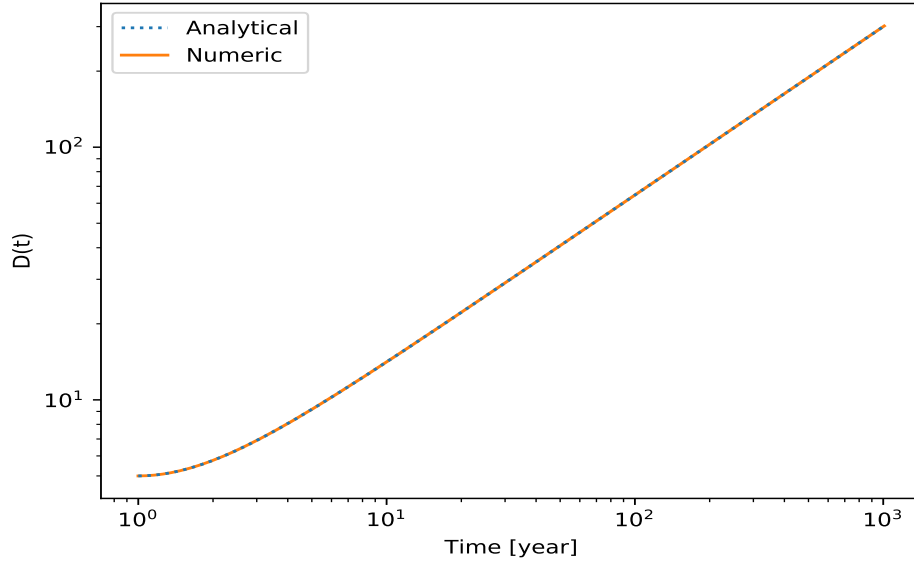


Figure 24: The analytical (blue) and numerical (orange) solution of the ODE with initial conditions $D(1) = 5$, $D'(1) = 0$. The plots show that the numerical solution does not appear to have a visible deviation from the analytical solution for the given time interval.

4 - Zeldovich approximation

Question 4.a)

Problem

The linear growth factor is expressed in terms of an integral expression given by,

$$D(z) = \frac{5\Omega_m H_0^2}{2} H(z) \int_z^\infty \frac{1+z'}{H^3(z')} dz' \quad (27)$$

Here z is the redshift, Ω_m is the matter fraction of the Universe at $z = 0$ ($\Omega_m = 0.3$), H_0 is the Hubble constant at $z = 0$ and $H(z)$ is the redshift dependent Hubble parameter given by,

$$H(z)^2 = H_0^2 (\Omega_m (1+z)^3 + \Omega_\Lambda) \quad (28)$$

Here Ω_Λ is the dark energy fraction of the Universe given by $\Omega_\Lambda = 0.7$. Use numerical integration to calculate the growth factor at $z = 50$ with a relative accuracy of 10^{-5} . Note that $D(a(z = 50)) = D(z = 50)$, so use either variable.

Solution

The equation is before integrating first written in terms of the scale factor a . Substituting $a = 1/(1+z)$ yields,

$$dz = -(1+z)^2 da = -a^{-2} da \quad (29)$$

Plug in this in by equation 27 results in,

$$D(a) = \frac{5\Omega_m H_0^2}{2} H(a) \int_a^0 \frac{-a'^{-3}}{H^3(a')} da' = \frac{5\Omega_m H_0^2}{2} H(a) \int_0^a \frac{a'^{-3}}{H^3(a')} da' \quad (30)$$

The Hubble parameter in terms of the scale factor a given by,

$$H(a)^2 = H_0^2 (\Omega_m a^{-3} + \Omega_\Lambda) \quad (31)$$

Substituting this in equation 30 and simplifying yields,

$$D(a) = \frac{5\Omega_m H_0^3}{2} (\Omega_m a^{-3} + \Omega_\Lambda)^{0.5} \int_0^a \frac{a'^{-3}}{(H_0^2(\Omega_m a'^{-3} + \Omega_\Lambda))^{3/2}} da' \quad (32)$$

$$= \frac{5\Omega_m}{2} (\Omega_m a^{-3} + \Omega_\Lambda)^{0.5} \int_0^{a'} \frac{a'^{-3}}{(\Omega_m a'^{-3} + \Omega_\Lambda)^{3/2}} da' \quad (33)$$

The above integral is with the help of Romberg integration solved for $\Omega_m = 0.3$ and $\Omega_\Lambda = 0.7$. The code for Romberg integration can be found at page 57. The code that prints the output and the printed output can be found below. The shared modules used by the code start at page 53.

Code - Output

The code that prints the value of the linear growth factor. The code for the called helper function, `helpers4.calculate_linear_growth` can be found on page 53.

```

1 def assign4_a():
2     """
3     Execute assign4 a
4     """
5
6     # Relevant imports are.
7     # (1) import mathlib.helpers4 as helpers4
8
9
10    # The value of the scale to integrate to
11    a_max = 1/51
12
13    # The values of the density parameters
14    omega_m = 0.3
15    omega_lambda = 0.7
16
17    # Print the result
18    print('[4a] D(a = 1/51) = ', helpers4.calculate_linear_growth(a_max,
19                                                                    omega_m, omega_lambda))

```

./Code/assign4.py

Text - Output

The output produced by the above code.

```

1 [4a] D(a = 1/51) = 0.019607780428272343

```

./Output/assign4.out.txt

Question 4.b)

Problem

Use your result from the previous question to analytically calculate for $a = 1/51$,

$$\dot{D}(t) = \frac{dD(a)}{da} \dot{a} \quad (34)$$

Bonus points if you calculate it numerically and match the analytical result within 10^{-8} .

Solution

In this question the derivative is not only calculated analytically, but also numerically. The numerical calculation is performed with ridders method. The analytical solution is derived below and evaluated. The code for the numerical solution and the code that prints the analytical solution³ can be found after this derivation. This includes the code for ridders method.

To simplify the derivation we define,

$$C = \int_0^{a'} \frac{a'^{-3}}{(\Omega_m a'^{-3} + \Omega_\Lambda)^{3/2}} da' \quad (35)$$

The derivative can then by substituting ?? in equation ?? be written as,

$$\dot{D}(t) = \frac{5\Omega_m}{2} \left(\frac{-3\Omega_m a^{-4}}{2} (\Omega_m a^{-3} + \Omega_\Lambda)^{-0.5} C + (\Omega_m a^{-3} + \Omega_\Lambda)^{0.5} \frac{a^{-3}}{(\Omega_m a^{-3} + \Omega_\Lambda)^{3/2}} \right) \dot{a} \quad (36)$$

$$= \frac{5\Omega_m}{2} \left(\frac{-3\Omega_m a^{-4}}{2(\Omega_m a^{-3} + \Omega_\Lambda)^{0.5}} C + \frac{a^{-3}}{(\Omega_m a^{-3} + \Omega_\Lambda)} \right) \dot{a} \quad (37)$$

Substituting $\dot{a} = H(a)a(t) = H_0 (\Omega_m a^{-3} + \Omega_\Lambda)^{0.5} a(t)$ results in,

$$\dot{D} = \frac{5\Omega_m H_0}{2} \left(\frac{-3\Omega_m a^{-3}}{2} C + \frac{a^{-2}}{(\Omega_m a^{-3} + \Omega_\Lambda)^{0.5}} \right) \quad (38)$$

$$= \frac{5\Omega_m H_0}{2a^2} \left(\frac{1}{(\Omega_m a^{-3} + \Omega_\Lambda)^{0.5}} - \frac{3\Omega_m}{2a} C \right) \quad (39)$$

The above expression is evaluated in the code. The value of C is numerically calculated for the analytical expression. This value is just the result of the previous question without scale factor and was allowed to be used for this question. The analytical output (with the numerical calculation for C) and the numerical output (with ridders method) can be found after the code section.

³The analytical solution is printed to make it easier to compare.

Code - Print

The code that prints the analytical and numerical result. The code for ridders method follows after this.

```
1 def assignment4_b():
2     """
3     Execute assignment 4b
4     """
5
6     # Relevant imports include:
7     # (1) import mathlib.derivative as ml_dir
8     # (2) import mathlib.helpers4 as helpers4
9     # (3) import mathlib.integrate as integrate
10
11     # Start with numerical
12
13     # The linear growth factor as function of a
14     D = lambda a: helpers4.calculate_linear_growth(a, 0.3, 0.7)
15
16     # Calculate the derivative with ridder for a = 1/51
17     derivative = ml_dir.ridder(D, 1/51, 1e-15)
18
19     # Calculate  $\dot{a} = H(a)a$ 
20     H_0 = 7.16e-11
21     H = H_0 * (0.3*(1/51)**(-3) + 0.7)**0.5
22
23     # Final result
24     final_numerical = derivative*H*(1/51)
25
26     # Analytical
27
28     # The function to integrate.
29     func = lambda a: a**(-3) / (0.3 * (1/(a**3)) + 0.7)**(3/2)
30     C = integrate.romberg(func, 1e-7, (1/51), 15)
31
32     # The right term in brackets
33     right = -(3*0.3*C)/(2*(1/51))
34     # The left term in brackets
35     left = 1/(0.3*(1/51)**(-3)+0.7)**0.5
36
37     # Prefactor
38     pre = (5*0.3*H_0)/(2*(1/51)**2)
39
40     # Print the results
41     print("[4b] Analytical: ", pre*(left+right))
42     print("[4b] Numerically: ", final_numerical)
```

./Code/assignment_4.py

Code - Ridder

The code for ridders method.

```
1 import numpy as np
2
3 def central_diff(function, x, h):
4     """
5     Use the central difference method to approximate the derivative
6     at a point x.
7
8     In:
9         param: function — The function to calculate the derivative of.
10        param: x — The point to approximate the derivative of the function at.
11        param: h — A small value h that in the limit would go to zero.
12
13     Out:
14        return: An approximation of the derivative of the provided
15               function at x.
16     """
```

```

15
16 #f'(x) approx (f(x+h)-f(x-h))/2h
17 return (function(x+h) - function(x-h))/(2*h)
18
19
20 def ridder(function, x, precision):
21     """
22     Perform ridders differential method to estimate
23     the derivative at a point x
24
25     In:
26     param: function — The function to estimate the derivative for.
27     param: x — The point to estimate the derivative at.
28     param: precision — The precision that must be obtained
29                      in the estimation.
30
31     Out:
32     return: An approximation of the derivative.
33     """
34     # The number of initial approximations to use.
35     approximations = 0
36     # The return value.
37     ret = 0
38     # The current precision.
39     current_precision = 0xFFFFFFFF
40
41     # While we didn't reach the request precision with
42     # the current amount of initial approximations, try again
43     # but with more approximations.
44     while current_precision > precision:
45         # Increase the amount of initial approximations.
46         approximations += 5
47         # Reset the error.
48         current_precision = 0xFFFFFFFF
49
50
51     # The array to store the combined results in.
52     results = np.zeros(approximations)
53
54     # The current combination:
55     # 0 = combine initial central-difference evaluations,
56     # 1 = combine the combined central difference evaluations
57     # 2 = combine the combined combined central difference evaluations etc.
58     for combination in range(0, approximations-1):
59
60         # Combine for the current 'combination'.
61         for j in range(1, approximations-combination):
62
63             # Create the initial central difference to combine.
64             if combination == 0:
65                 # We need two central difference's to
66                 # combine the very first time.
67                 if j == 1:
68                     results[j-1] = central_diff(function, x, 1)
69
70                 # Decrease h by a factor of 2 for each next approximation.
71                 results[j] = central_diff(function, x, (1/2)**j)
72
73             # Keep the evaluation of the previous combination that
74             # is getting overwritten temporary in memory to update
75             # the current precision.
76             previous = results[j-1]
77
78             # Combine
79             power = 4**(combination+1)
80             results[j-1] = (power*results[j] - results[j-1])/(power-1)
81
82             # Determine the new precision
83             precision_tmp = max(abs(results[j-1] - previous), \
84                               abs(results[j-1] - results[j]))
85

```

```

86         # New precision is smaller-> update
87         if precision_tmp < current_precision:
88             current_precision = precision_tmp
89             ret = results[j-1]
90
91         # Terminate if requested precision is reached
92         if current_precision < precision:
93             return ret
94
95         # Abort early if the error of the last combined result is worse
96         # than the previous order by a large amount.
97         if j == (approximations-combination-1) \
98             and abs(ret - previous) > 100*current_precision:
99
100             return ret
101     return ret

```

./Code/mathlib/derivative.py

Text - Output

The analytical and numerical result. As can be seen is the numerical approximation within 10^{-8} .

```

1 [4b] Analytical:  2.800638157126267e-10
2 [4b] Numerically: 2.8006381571292944e-10

```

./Output/assignment4_out.txt

Question 4.c)

Problem

Use the Zeldovich approximation to generate a movie of the evolution of a volume in two dimensions from a scale factor of 0.0025 until a scale factor of 1.0. To do this, start with 64x64 particles arranged in a square grid with a grid spacing of 1 Mpc. Use $P(k) = k^{-2}$ and the given equation to generate c_k , then use the FFT on your grid of particles to calculate $\mathbf{S}(\mathbf{q})$. As a increases, update the positions and momenta of the particles and save each step as a frame for your movie.

Solution

The difficulty of this exercise lays by the calculation the components of the displacement vector. A brief description of how this is done can be found below.

The displacement vector is calculated by first creating a matrix in k -space with complex values based on the given power law (similar to exercise 2). The matrix is next given the correct hermitian symmetry (see again exercise 2). The components of the displacement vector, s_x and s_y , are then calculated independent with the help of this matrix. This calculation is done as follows. The hermitian matrix is copied and the components in the matrices are multiplied with the wavenumbers and the complex number i . The wavenumbers by which the components are multiplied depends on whether we want s_x or s_y . The result is two matrices where the cells have respectively values of $ic_k k_x$ and $ic_k k_y$. After this multiplication the matrices cannot be directly fourier transformed to obtain s_x and s_y , as the multiplication with the wavenumbers breaks the symmetry in the columns with nyquist wavenumbers. The symmetry is only broken by a minus sign and this is corrected before doing the IFFT.

The code that creates the movie and the plots for the first 10 particles can be found below. The final plot of the movie is also included and shows that the particles clearly move to the denser region (see figure ?? on page ??).

Code - Plots:

The code that creates the movie and the plots of the first 10 particles. The code does make use of an object called 'random' and a function called `gen_complex`. This object and the function can be found on page 53. The code for the imported shared modules can also be found at page 53. The movie can be found in the movie folder.

```
1 def assignement4_c():
2     """
3     Execute assignement 4c
4     """
5
6     # The relevant imports include:
7     # (1) import numpy as np
8     # (2) import scipy.fftpack
9     # (3) import mathlib.misc as misc
10    # (4) random, defined outside the main function.
11
12
13
14    # Constants and random number generator
15    grid_size = 64
16    min_distance = 1
17    power = -2
18
19    # Create the hermitian matrix and the ifft.
20    # The ifft is used to plot the background
21    matrix = misc.generate_matrix_2D(grid_size, min_distance,
22                                    gen_complex,
23                                    random.gen_uniforms(grid_size**2*2), power)
24    matrix = misc.make_hermitian2D(matrix)
25
26    # Calculate the ifft, used for the background of the movie.
27    matrix_ifft = scipy.fftpack.ifft2(matrix).real * grid_size
28
29    # wavenumbers
30    wavenumbers = misc.gen_wavenumbers(grid_size, min_distance)
31
32    matrix_y = matrix * wavenumbers*1J
33    matrix_x = matrix * wavenumbers[:, np.newaxis]*1J
34
35    # Fix the symmetry that is broken
36
37    size = matrix_x.shape[0]
38
39    matrix_x[int(size/2),0] = matrix_x[int(size/2),0].real
40    matrix_x[int(size/2),int(size/2)] = matrix_x[int(size/2),int(size/2)].real
41
42    matrix_y[0,int(size/2)] = matrix_y[0,int(size/2)].real
43    matrix_y[int(size/2),int(size/2)] = matrix_y[int(size/2),int(size/2)].real
44
45
46    for i in range(int(size/2)+1, size):
47        matrix_x[int(size/2),i] *= -1
48        matrix_y[i,int(size/2)] *= -1
49
50    # Generate the components of the displacement vectors
51    # We have to transpose/ switch to get the x and y.
52    # Multiplication with grid_size is to correct for the
53    # normalization factor of the scipy implementation of the ifft.
54    s_x = scipy.fftpack.ifft2(matrix_y).real * grid_size
55    s_y = scipy.fftpack.ifft2(matrix_x).real * grid_size
56
57    # Positions of particles
58    pos_x, pos_y = np.meshgrid(range(0, grid_size), range(0, grid_size))
59
60    # Begin simulation
61
62    # Constants for integration
63    a_min = 0.0025
64    scale_factors = np.linspace(a_min, 1, 90)
```

```

65
66 # List in which the momentum and position
67 # of the first 10 particles is saved.
68 pos_top_10 = list()
69 momentum_top_10 = list()
70
71 # Create the plot
72 for idx,a in enumerate(scale_factors):
73     print(idx)
74     # Calculate da
75     da = 0
76
77     if idx != 0:
78         da = scale_factors[idx] - scale_factors[idx-1]
79     else:
80         da = scale_factors[idx] - a_min
81
82     # Calculate D(a) and \dot(D)
83     d = helpers4.calculate_linear_growth(a)
84     ddot = helpers4.calculate_linear_growth_dir(a -da/2)
85
86     # Update position.
87     pos_x_new = (pos_x+ s_x*d) % grid_size
88     pos_y_new = (pos_y+ s_y*d) % grid_size
89
90     pos_top_10.append(pos_y_new[0:10,0])
91
92     # Update momentum.
93     p_x = -(a-da/2)**2 * ddot * s_x
94     p_y = -(a-da/2)**2 * ddot*s_y
95
96     momentum_top_10.append(p_y[0:10,0])
97
98     # Create the plot.
99     plt.scatter(pos_x_new, pos_y_new, s=1, c='black')
100     plt.imshow(matrix_ifft, alpha=0.7)
101     plt.colorbar()
102     plt.title('a=' + str(a))
103     plt.xlabel('x [Mpc]')
104     plt.ylabel('y [Mpc]')
105     plt.savefig('./Plots/4c/4c={0}.png'.format(idx))
106     plt.close()
107
108 # Plot the momentum and position
109 pos_top_10 = np.array(pos_top_10)
110 momentum_top_10 = np.array(momentum_top_10)
111
112 # Momentum
113 for i in range(0,10):
114     plt.plot(scale_factors, momentum_top_10[:,i], label='particle ' + str(i+1))
115
116     plt.xlabel('a')
117     plt.ylabel(r'$P_y$')
118 plt.legend()
119 plt.savefig('./Plots/4c.momentum.pdf')
120 plt.close()
121
122 # Position
123 for i in range(0,10):
124     plt.plot(scale_factors, pos_top_10[:,i], label='particle ' + str(i+1))
125     plt.xlabel('a')
126     plt.ylabel(r'$y$')
127
128 plt.legend()
129 plt.savefig('./Plots/4c-pos.pdf')
130 plt.close()

```

./Code/assignment_4.py

Plots - Field

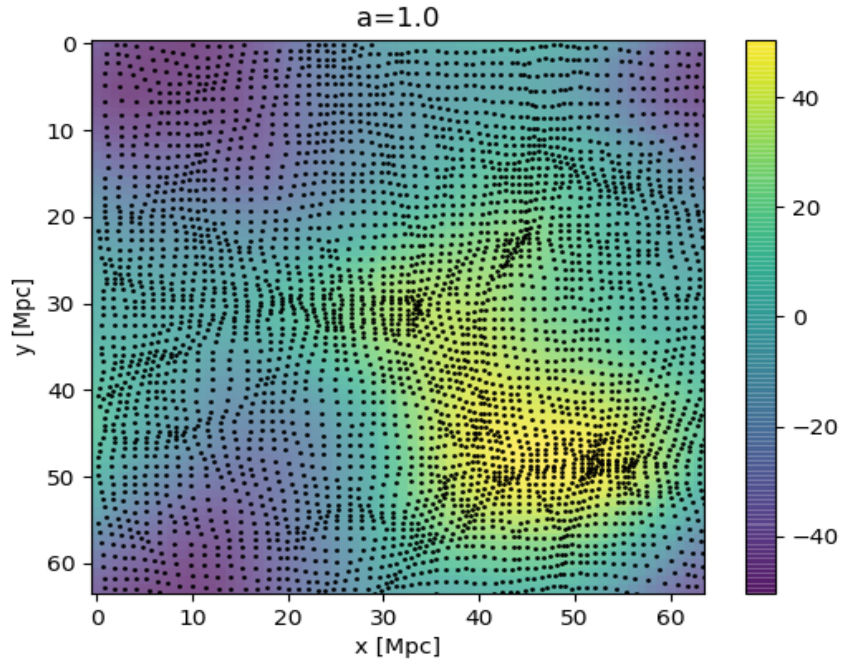


Figure 25: The final plot of the movie. It can clearly be seen that the particles (black dots) moved to the denser region.

Plots - particles

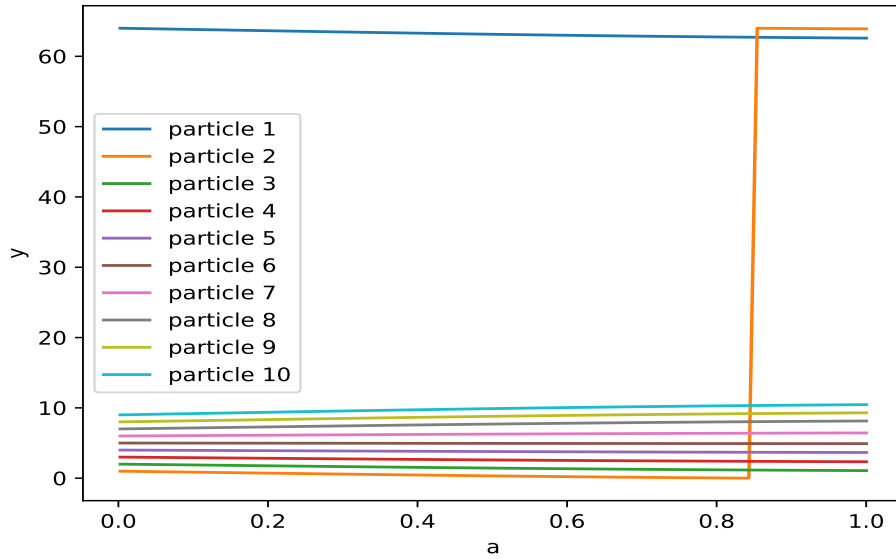


Figure 26: The y-positions of the first 10 particles as function of the scale factor. The plot shows that the particles are slowly moving to a denser region (see figure 25, where the first 10 particles are at the left top). The large jump for particle 2 (orange) at a scale factor of around $a \approx 0.8$ is the result of the circular boundary conditions.

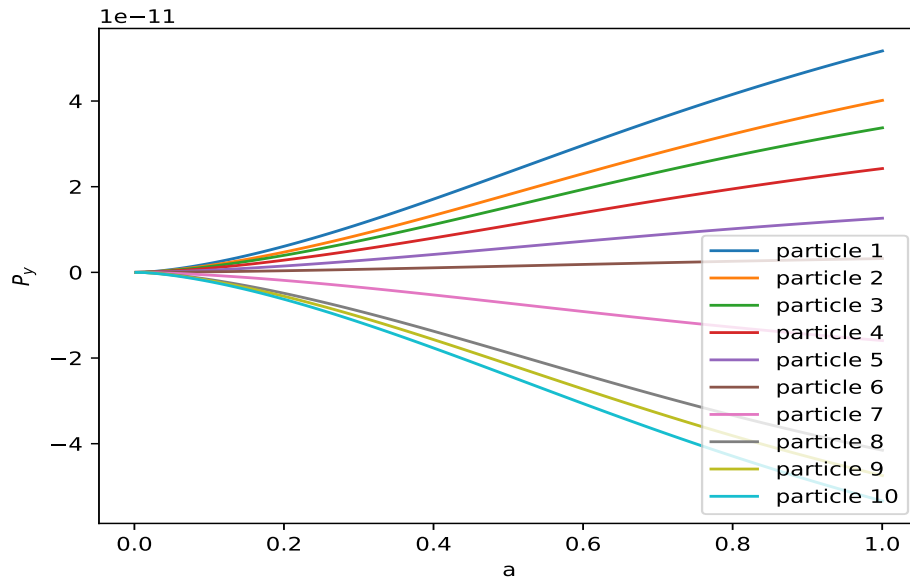


Figure 27: The momentum of the first 10 particles as function of the scale factor. The fact that about half of the particles have a positive momentum and that the other half have a negative momentum is the result of the circular boundary conditions and the created field.

Question 4.d)

Problem

Generate initial conditions for a three dimensional box to do a N-body simulation, make initial conditions for 64^3 particles starting at redshift $z = 50$. Besides this make 3 separate movies of a slice of thickness $1/64$ th of your box at its center, make a slice for $x - y$, $x - z$, $y - z$. Again make a movie of at least 3 seconds with at least 30 frames per second. Finally plot the position and momentum of the first 10 particles along the z -direction vs a .

Solution

The method in which the displacement vector is similar to the method in 4c. This thus means that first a 3D matrix (tensor) is created in k-space with complex values based on the given power law. The matrix is next given the correct hermitian symmetry, which is done by an extended version of the algorithm explained in question 2. The symmetric matrix (tensor) is now used to calculate the components s_x , s_y and s_z . This is identical to 4c: The matrix is first copied and the copies multiplied with the correct wavenumbers and the complex value i . In the end this results in three matrices that need to be inverse Fourier transformed to obtain the components of \mathbf{S} . The three matrices can again not be directly inverse Fourier transformed as the multiplication with the wavenumbers breaks the symmetry in the nyquist planes. The symmetry is again only broken by a minus sign and is first corrected before doing the IFFT. The corrected matrices are then used to calculate s_x , s_y and s_z .

The code that uses the displacement vector to creates the 3 simulations and the plots for the first 10 particles can found below. The code make use of an object called 'random' and a function called `gen_complex`. This object and the function can be found on page 53. The code for the imported modules can also be found at page 53. The movie can be found in the movie folder.

Code - Plots:

The code that creates the movie and the plots of the first 10 particles in 3D.

```
1 def assigment4_d():
2     """
3     Execute assigment 4d
4     """
5
6     # The relevant imports include:
7     # (1) import numpy as np
8     # (2) import scipy.fftpack
9     # (3) import mathlib.misc as misc
10    # (4) random, defined outside the main function.
11
12    # Create the matrix
13    grid_size = 64
14    min_size = 1
15    power = -2
16
17    # Create the matrix and give it the correct symmetry
18    matrix = misc.generate_matrix_3D(grid_size, min_size,
19                                     gen_complex,
20                                     random.gen_uniforms(grid_size**3 * 2),
21                                     power)
22    matrix = misc.make_hermitian3D(matrix)
23
24    # Wavenumbers and matrices for positions
25    wavenumbers = misc.gen_wavenumbers(grid_size, 1)
26
27    kx, ky, kz = np.meshgrid(wavenumbers, wavenumbers, wavenumbers)
28    matrix_x = matrix * kx * 1J
29    matrix_y = matrix * ky * 1J
30    matrix_z = matrix * kz * 1J
31
32    # Fix the broken symmetry
33
34    # Fix matrix_x
35    for i in range(matrix.shape[0]):
36        for j in range(int(grid_size/2)+1, grid_size):
37            matrix_x[i, int(grid_size/2), j] *= -1
38
39            if i > int(grid_size/2):
40                matrix_x[i, int(grid_size/2), int(grid_size/2)] *= -1
41                matrix_x[i, int(grid_size/2), 0] *= -1
42
43    # Special points
44    matrix_x[int(grid_size/2), 0, 0] = matrix_x[int(grid_size/2), 0, 0].imag
45    matrix_x[0, int(grid_size/2), 0] = matrix_x[0, int(grid_size/2), 0].imag
46    matrix_x[0, 0, int(grid_size/2)] = matrix_x[0, 0, int(grid_size/2)].imag
47
48    matrix_x[int(grid_size/2), int(grid_size/2), 0] = matrix_x[int(grid_size/2),
49    int(grid_size/2), 0].imag
50    matrix_x[int(grid_size/2), 0, int(grid_size/2)] = matrix_x[int(grid_size/2),
51    0, int(grid_size/2)].imag
52    matrix_x[0, int(grid_size/2), int(grid_size/2)] = matrix_x[0, int(grid_size
53    /2), int(grid_size/2)].imag
54    matrix_x[int(grid_size/2), int(grid_size/2), int(grid_size/2)] = matrix_x[int
55    (grid_size/2), int(grid_size/2), int(grid_size/2)].imag
56
57    # Fix matrix_z
58    for i in range(matrix.shape[0]):
59        for j in range(int(grid_size/2)+1, grid_size):
60            matrix_z[i, j, int(grid_size/2)] *= -1
61
62            if i > int(grid_size/2):
63                matrix_z[i, int(grid_size/2), int(grid_size/2)] *= -1
64                matrix_z[i, 0, int(grid_size/2)] *= -1
65
66    # special points
67    matrix_z[int(grid_size/2), 0, 0] = matrix_z[int(grid_size/2), 0, 0].imag
68    matrix_z[0, int(grid_size/2), 0] = matrix_z[0, int(grid_size/2), 0].imag
```

```

65 matrix_z[0,0,int(grid_size/2)] = matrix_z[0,0,int(grid_size/2)].imag
66
67 matrix_z[int(grid_size/2), int(grid_size/2),0] = matrix_z[int(grid_size/2),
68 int(grid_size/2),0].imag
69 matrix_z[int(grid_size/2), 0, int(grid_size/2)] = matrix_z[int(grid_size/2)
70 ,0, int(grid_size/2)].imag
71 matrix_z[0, int(grid_size/2), int(grid_size/2)] = matrix_z[0, int(grid_size
72 /2), int(grid_size/2)].imag
73 matrix_z[int(grid_size/2), int(grid_size/2), int(grid_size/2)] = matrix_z[int
74 (grid_size/2), int(grid_size/2), int(grid_size/2)].imag
75
76 # Fix matrix y
77 for j in range(grid_size):
78     for k in range(grid_size):
79         if (j == 0 or j == int(grid_size/2)) and k > int(grid_size/2):
80             matrix_y[int(grid_size/2),j,k] *= -1
81         elif j > int(grid_size/2):
82             matrix_y[int(grid_size/2),j,k] *= -1
83
84 # special points
85 matrix_y[int(grid_size/2),int(grid_size/2),int(grid_size/2)] = matrix_y[int(
86 grid_size/2),int(grid_size/2),int(grid_size/2)].imag + 0J
87 matrix_y[int(grid_size/2),int(grid_size/2),0] = matrix_y[int(grid_size/2),int
88 (grid_size/2),0].imag + 0J
89 matrix_y[int(grid_size/2),0,int(grid_size/2)] = matrix_y[int(grid_size/2),0,
90 int(grid_size/2)].imag + 0J
91 matrix_y[int(grid_size/2),0,0] = matrix_y[int(grid_size/2),0,0].imag + 0J
92
93 # Generate the components of the displacemnet vectors
94 s_y = scipy.fftpack.ifftn(matrix_y).real * grid_size**(3/2)
95 s_x = scipy.fftpack.ifftn(matrix_x).real * grid_size**(3/2)
96 s_z = scipy.fftpack.ifftn(matrix_z).real * grid_size**(3/2)
97
98 # Positions
99 pos_x, pos_y, pos_z = np.meshgrid(range(0,grid_size),range(0,grid_size),
100 range(0, grid_size))
101
102 #
103 # Begin simulation
104
105 # Constants for integration
106 a_min = 1/51
107 scale_factors = np.linspace(a_min,1,90,endpoint=False)
108
109 # List in which the momentum and position
110 # of the first 10 particles is saved.
111 pos_top_10 = list()#.zeros((10,10))
112 momentum_top_10 = list() #np.zeros((90,10))
113
114 # Create the plot
115 for idx,a in enumerate(scale_factors):
116
117     # calculate da
118     da = 0
119
120     if idx != 0:
121         da = scale_factors[idx] - scale_factors[idx-1]
122     else:
123         da = scale_factors[idx] - a_min
124
125     # Calculate D(a)
126     # Calculate \dot{D}
127     d = helpers4.calculate_linear_growth(a)
128     ddot = helpers4.calculate_linear_growth_dir(a -da/2)
129
130     # Update position
131     pos_x_new = (pos_x + s_x*d) % grid_size
132     pos_y_new = (pos_y + s_y*d) % grid_size

```

```

128     pos_z_new = (pos_z + s_z*d) % grid_size
129
130     pos_top_10.append(pos_z_new[0:10,0,0])
131
132     # Update momentum
133     p_x = -(a-da/2)**2 * ddot * s_x
134     p_y = -(a-da/2)**2 * ddot * s_y
135     p_z = -(a-da/2)**2 * ddot * s_y
136
137     momentum_top_10.append(p_z[0:10,0,0])
138
139     # slices
140     z_mask = np.where(abs(pos_z_new - 32) < 0.5)
141     y_mask = np.where(abs(pos_y_new - 32) < 0.5)
142     x_mask = np.where(abs(pos_x_new - 32) < 0.5)
143
144     # Create the plots.
145
146     # z
147     plt.scatter(pos_x_new[z_mask], pos_y_new[z_mask], s=1, c='black')
148     plt.title('a=' + str(a))
149     plt.xlabel('x [Mpc]')
150     plt.ylabel('y [Mpc]')
151     plt.savefig('./Plots/4d/xy/4d_xy={0}.png'.format(idx))
152     plt.close()
153
154     # y
155     plt.scatter(pos_x_new[y_mask], pos_z_new[y_mask], s=1, c='black')
156     plt.title('a=' + str(a))
157     plt.xlabel('x [Mpc]')
158     plt.ylabel('z [Mpc]')
159     plt.savefig('./Plots/4d/xz/4d_xz={0}.png'.format(idx))
160     plt.close()
161
162     # x
163     plt.scatter(pos_y_new[x_mask], pos_z_new[x_mask], s=1, c='black')
164     plt.title('a=' + str(a))
165     plt.xlabel('y [Mpc]')
166     plt.ylabel('z [Mpc]')
167     plt.savefig('./Plots/4d/yz/4d_yz={0}.png'.format(idx))
168     plt.close()
169
170     # Plot the momentum and position
171     pos_top_10 = np.array(pos_top_10)
172     momentum_top_10 = np.array(momentum_top_10)
173
174     # Momentum
175     for i in range(0,10):
176         plt.plot(scale_factors, momentum_top_10[:,i], label = 'particle ' + str(i
177         +1))
178         plt.xlabel('a')
179         plt.ylabel(r'$P_z$')
180
181     plt.legend()
182     plt.savefig('./Plots/4d.momentum.pdf')
183     plt.close()
184
185     # Position
186     for i in range(0,10):
187         plt.plot(scale_factors, pos_top_10[:,i], label = 'particle ' + str(i+1))
188         plt.xlabel('a')
189         plt.ylabel('z')
190
191     plt.legend()
192     plt.savefig('./Plots/4d-pos.pdf')
193     plt.close()

```

./Code/assignment_4.py

Plots - particles

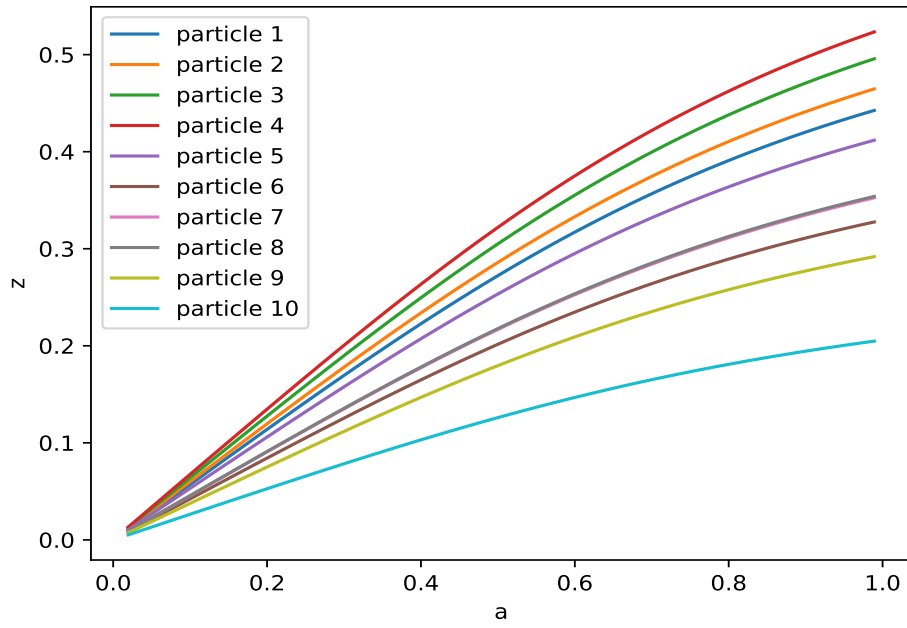


Figure 28: The z-positions of the first 10 particles against the scale factor.

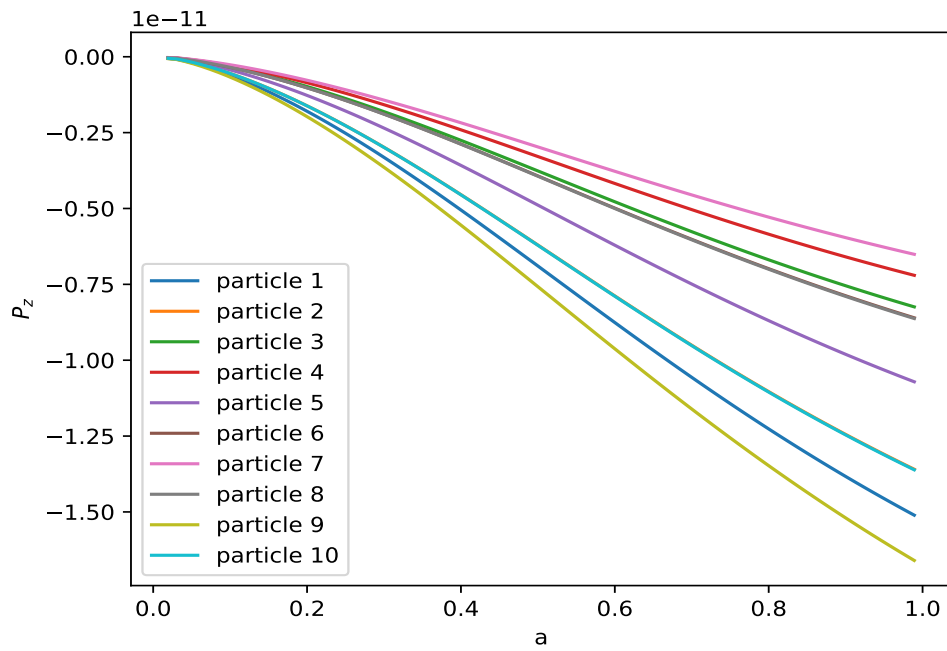


Figure 29: The z-component of the momentum of the first 10 particles against the scale factor.

Question 4 - Summary

Summary

The current sub-section contains the summary of the code used for assignment 4. This includes the part of the main file that executes the subquestions, the relevant imports, the functions to calculate the linear growth factor and the functions used to generate and sort the matrices (tensor).

Code - Assignment

The code with the main function and the function `gen_complex`, which is called in 4c and 4d.

```
1 import mathlib.integrate as integrate
2 import mathlib.misc as misc
3 import mathlib.random as rnd
4 import mathlib.helpers4 as helpers4
5 import matplotlib.pyplot as plt
6 import mathlib.derivative as ml_dir
7 import numpy as np
8 import scipy.fftpack
9
10 random = rnd.Random(783341)
11
12 def main():
13     assignment4_a()
14     assignment4_b()
15     assignment4_c()
16     assignment4_d()
17
18 def gen_complex(k, power, rand1, rand2):
19     """
20     Generate a complex number using the power
21     spectrum.
22     In:
23     param: k — The magnitude of the wavenumber.
24     param: n — The order of the power law.
25     param: rand 1 — A random uniform variable.
26     param: rand 2 — A random uniform variable.
27     Out:
28     return: A complex number in the fourier plane for the
29            given power law.
30     """
31
32     sigma = np.sqrt(k**power)
33     a,b = random.gen_normal_uniform(0,1,rand1,rand2)
34     return complex(a,-b)*(1/k**2) *0.5*sigma
```

./Code/assignment_4.py

Code - Linear growth

The code which calculates the linear growth factor and the derivative of the liner growth factor.

```
1 import numpy as np
2 import mathlib.integrate as integrate
3
4 def calculate_linear_growth(a_max, omega_m = 0.3, omega_lambda = 0.7):
5     """
6     Calculate the linear growth factor.
7     In:
8     param: a_max — The value of a to evaluate the linear growth function at.
9     param: omega_m — The mass fraction in the universe.
10    param: omega_lambda — The dark energy fraction in the universe.
11    Out:
12    return: The value of the linear growth factor for the given parameters.
13    """
14    if a_max <= 0 :
15        return 0
```

```

16
17 # The prefactor of the integral
18 pre_factor = 0.5*(5*omega_m)*(omega_m*a_max**(-3) + omega_lambda)**(0.5)
19
20 # The function to integrate.
21 func = lambda a: a**(-3) /(omega_m * (1/(a**3))+omega_lambda)**(3/2)
22
23 return pre_factor*integrate.romberg(func, 1e-7, a_max, 15)
24
25 def calculate_linear_growth_dir(a, omega_m = 0.3, omega_lambda = 0.7):
26     """
27     Calculate the derivative of the linear growth factor
28     In:
29         param: a — The scale factor for which to calculate it.
30         param: omega_m — The fraction of matter in the universe.
31         param: omega_lambda — The fraction of dark energy in the universe
32     Out:
33         return: The derivative of the scale factor for the given parameters
34     """
35     # Hubble constant
36     H0 = 7.16e-11
37
38     # The function to integrate, which appears in the second term.
39     func = lambda a: a**(-3) /(omega_m * (1/(a**3))+omega_lambda)**(3/2)
40
41
42     # The terms in the expression.
43     pre_factor = (5*omega_m*H0)/(2*a**2)
44     first_bracked_term = 1/(omega_m*a**(-3)+omega_lambda)**0.5
45     second_bracked_term = (-3*omega_m*integrate.romberg(func, 1e-7, a, 15))/(2*a)
46
47     return pre_factor*(first_bracked_term + second_bracked_term)

```

./Code/mathlib/helpers4.py

Code - Tensor/matrix

The code containing all the function used to create the matrices (tensors) and make then symmetric.

```

1 import numpy as np
2
3 def gen_wavenumbers(size, min_distance):
4     """
5     Generate the shifted wavenumbers
6     for the discrete fourier transform.
7     In:
8         param: size — The size of the matrix.
9         param: min_distance — The distance of a cell/ the sample spacing.
10    Out:
11        return: An array with shifted wave numbers.
12    """
13    # Array to return.
14    ret = np.zeros(size)
15
16    # Positive values
17    ret[0:int(size/2)+1] = np.arange(0,int(size/2)+1)
18
19    if size % 2 == 0: # even
20        ret[int(size/2):] = -np.arange(int(size/2),0,-1)
21    else: # odd
22        ret[int(size/2)+1:] = -np.arange(int(size/2),0,-1)
23
24
25    return (ret/(size*min_distance))*2*np.pi
26
27
28 def generate_matrix_2D(size, min_distance, func, random_numbers, power):
29     """
30     Generate a 2D matrix with complex numbers in
31     shifted fourier coordinates using the power spectrum

```

```

32 In:
33     param: size — The size of the matrix (size x size).
34     param: min_distance — The physical size of 1 cell.
35     param: func — A function that takes the power and to random uniform
36                   variables to calculate the correct complex number.
37     param: random_numbers — An array with random uniform numbers.
38                               Must be of atleast size: size x size x 2.
39     param: power — The power of the power spectrum to create the matrix for.
40 Out:
41     return: A 2D matrix with complex numbers assigned by the power spectrum
42            in fourier shifted coordinates.
43 """
44
45 # Generate the shifted wavenumbers
46 wavenumber = gen_wavenumbers(size, min_distance)
47 # The matrix to return
48 ret = np.zeros((size, size), dtype=complex)
49
50 # A counter for the random uniform variables.
51 steps = 0
52
53 # Fill the matrix
54 for i in range(size):
55     for j in range(size):
56
57         # Element of k_0, k_0 is left zero.
58         if i == 0 and j == 0:
59             continue
60
61         # Calculate the magnitude of the wavenumbers.
62         k = np.sqrt(wavenumber[i]**2 + wavenumber[j]**2)
63         # Fill the matrix.
64         ret[i][j] = func(k, power,
65                           random_numbers[steps], random_numbers[steps+1])
66         steps += 2
67
68 # Return the matrix
69 return ret
70
71 def make_hermitian2D(matrix):
72     """
73     Give a matrix in shifted fourier coordinates
74     the correct hermitian symmetry so that the ifft is real.
75 In:
76     param: matrix — The matrix to give the correct symmetry.
77 Out:
78     return: A matrix with the correct hermitian symmetry so that the
79            ifft is real.
80 """
81
82 # The size of the matrix
83 size = matrix.shape[0]
84
85 # Loop over the rows
86 for row in range(1, int(size/2) + 1):
87
88     # Give the first column (index 0) has the correct symmetry (see report
89     point A)
90     matrix[row, 0] = complex(matrix[size-row, 0].real,
91                               - matrix[size-row, 0].imag)
92     # Give the first row (index 0) the correct symmetry (see report point B)
93     matrix[0, row] = complex(matrix[0, size-row].real,
94                               - matrix[0, size-row].imag)
95
96     # Give the inner matrix the correct symmetry (see report point C)
97     for column in range(1, size):
98         matrix[row, column] = complex(matrix[size-row, size-column].real,
99                                       -matrix[size-row, size-column].imag)
100
101 # Corrections for even matrix

```

```

102     if size % 2 == 0:
103         matrix[int(size/2), 0] = matrix[int(size/2), 0].real + 0J
104         matrix[0, int(size/2)] = matrix[0, int(size/2)].real + 0J
105         matrix[int(size/2), int(size/2)] = matrix[int(size/2), int(size/2)].real
+ 0J
106
107     # Return the matrix.
108     return matrix
109
110
111
112
113 def generate_matrix_3D(size, min_distance, func, random_numbers, power):
114     """
115     Generate a 3D matrix with complex numbers in
116     shifted fourier coordinates using the power spectrum
117     In:
118     param: size — The size of the matrix (size x size).
119     param: min_distance — The physical size of 1 cell.
120     param: func — A function that takes the power and to random uniform
121             variables to calculate the correct complex number.
122     param: random_numbers — An array with random uniform numbers.
123             Must be of atleast size: size x size x 2.
124     param: power — The power of the power spectrum to create the matrix for.
125     Out:
126     return: A 3D matrix with complex numbers assigned by the power spectrum
127            in fourier shifted coordinates.
128     """
129
130     # Generate the shifted wavenumbers
131     wavenumber = gen_wavenumbers(size, min_distance)
132     # The matrix to return
133     ret = np.zeros((size, size, size), dtype=complex)
134
135     # A counter for the random uniform variables.
136     steps = 0
137
138     # Fill the matrix
139     for u in range(size):
140         for i in range(size):
141             for j in range(size):
142
143                 # Element of k_0,k_0,k_0 is left zero.
144                 if i == 0 and j == 0 and u == 0:
145                     continue
146
147                 # Calculate the magnitude of the wavenumbers.
148                 k = np.sqrt(wavenumber[i]**2 + wavenumber[j]**2 + wavenumber[u
]**2)
149
150                 # Fill the matrix.
151                 ret[u][i][j] = func(k, power,
152                                     random_numbers[steps], random_numbers[steps+1])
153
154                 steps += 2
155
156     # Return the matrix
157     return ret
158
159 def make_hermitian3D(tensor):
160     """
161     Give a 3D matrix (tensor) in shifted fourier coordinates
162     the correct hermitian symmetry so that the ifft is real.
163     In:
164     param: tensor — The tensor to give the correct symmetry.
165     Out:
166     return: A tensor with the correct hermitian symmetry so that the
167            ifft is real.
168     """
169
170     # Note: I am fully aware that the loops below can be combined.

```



```

171 #         The way it is now is however the first way in which I managed
172 #         to get it correct and is also the way in which it is easier to follow
173 .
174
175 size = tensor.shape[0]
176
177 # Inner matrix
178 for row in range(1, size):
179     for column in range(1, size):
180         for depth in range(1, size):
181             tensor[row, column, depth] = complex(tensor[size-row, size-column,
182 size-depth].real, -tensor[size-row, size-column, size-depth].imag)
183
184 # Outside top
185 for depth in range(1, int(size/2)+1):
186
187     tensor[0,0,depth] = complex(tensor[0,0,size-depth].real, -tensor[0,0,size
188 -depth].imag)
189     tensor[0,depth,0] = complex(tensor[0,size-depth,0].real, -tensor[0,size-
190 depth,0].imag)
191     tensor[depth,0,0] = complex(tensor[size-depth,0,0].real, -tensor[size-
192 depth,0,0].imag)
193
194     # outside inner
195     for column in range(1, size):
196         tensor[depth, column,0] = complex(tensor[size-depth, size-column,0].
197 real, -tensor[size-depth, size-column,0].imag)
198         tensor[depth,0,column] = complex(tensor[size-depth,0, size-column].
199 real, -tensor[size-depth,0, size-column].imag)
200         tensor[0, depth, column] = complex(tensor[0, size-depth, size-column].
201 real, - tensor[0, size-depth, size-column].imag)
202
203 if size % 2 == 0:
204     # Finally fix niquist
205     for i in range(0,size):
206         for j in range(0,size):
207             tensor[int(size/2),i,j] = tensor[int(size/2),i,j].real + 0J
208             tensor[i,j,int(size/2)] = tensor[i,j,int(size/2)].real + 0J
209             tensor[i,int(size/2),j] = tensor[i,int(size/2),j].real + 0J
210
211 return tensor

```

./Code/mathlib/misc.py

Code - Romberg

The code for romberg integration

```

1 import numpy as np
2
3 def trapezoid(function, a, b, num_trap):
4     """
5         Perform trapezoid integration
6
7     In:
8         param: function — The function to integrate.
9         param: a — The value to start the integration at.
10        param: b — The value to integrate the function to.
11        param: num_trap — The number of trapezoids to use.
12
13    Out:
14        return: An approximation of the integral from a to b of
15               the function 'function'
16    """
17
18    # The step size for the integration range.
19    dx = (b-a)/num_trap
20
21    # Find trapezoid points.

```

```

22     x_i = np.arange(a, b+dx, dx)
23
24     # Determine the area of all trapezoids.
25     area = dx*(function(a) + function(b))/2
26     area += np.sum(function(x_i[1:num_trap])) * dx
27
28     return area
29
30
31
32 def romberg(function, a, b, num_trap):
33     """
34         Perform romberg integration
35
36     In:
37         param: function — The function to integrate.
38         param: a — The value to start the integration at.
39         param: b — The value to stop the integrate at.
40         param: num_trap — The maximum number of initial trapezoid
41                          to use to approximate the area.
42
43     Out:
44         return: An approximation of the integral from a to b of
45                the function 'function'
46     """
47
48     # The array to store the combined results in.
49     results = np.zeros(num_trap)
50
51     # The current combination:
52     # 0 = combine trapezoids, 1 = combine combined trapezoids,
53     # 2 = combine the combined combined trapezoids etc.
54     for combination in range(0, num_trap-1):
55
56         # Iterate and combine.
57         for j in range(1, num_trap-combination):
58             # Create the initial trapezoids to combine.
59             if combination == 0:
60                 # We need two trapezoids to combine the very first time.
61                 if j == 1:
62                     results[j-1] = trapezoid(function, a, b, 1)
63
64                     results[j] = trapezoid(function, a, b, 2**j)
65
66             # Combine.
67             power = 4**(combination+1)
68             results[j-1] = (power*results[j] - results[j-1])/(power-1)
69
70     return results[0]

```

./Code/mathlib/integrate.py

5 - Mass assignment schemes

Question 5.a

Problem

The most simple choice for the particle shape is a point like shape given by:

$$S(x) = \frac{1}{\Delta x} \delta\left(\frac{x}{\Delta x}\right) \quad (40)$$

Explain how we need to assign mass to the grid in this scheme and explain why this method is called the Nearest Grid Point (NGP) method. Code up your own implementation of the mass assignment scheme NGP, using a grid of 16^3 . Display x-y slices of the grid with z values of 4,9,11 and 14.

Solution

The easiest way of assigning the mass of the particles to a grid is by assigning it to the grid points. For the given particle shape this would correspond to assigning the full mass of a particle to its nearest grid point, from which the name follows. For other particle shapes, such as the cloud in a cell shape, the mass might be fully assigned to the nearest grid point, but it might also be partially assigned to multiple grid points.

The mass is for the given particle shape assigned to the grid points by abusing the fact that a cast to an integer always result in down a cast (i.e 15.7 casted to an integer gives 15). The indices of a grid point to which a particle has to assign its mass can, by abusing the down cast, be found by adding 0.5 to the position and then down casting the result to an integer. To include circular boundary conditions the modulo with 16 (grid size) is taken.

The code that creates the plots with the slices and the plots can be found below. The code that assigns the mass can be found in the shared module `./Code/mathlib/mass.py` on page 73

Code - slices

The code that creates the plots with the slices of the mass grid.

```
1 def assignment_5a():
2     """
3     Execute assignment 5.a
4     """
5
6     # Relevant imports are:
7     # (1) import numpy as np
8     # (2) import mathlib.mass as mass
9     # (3) import matplotlib.pyplot as plt
10
11     # Create the positions of the particles.
12     np.random.seed(121)
13     positions = np.random.uniform(low =0, high=16, size=(3,1024))
14
15     # Create the mass grid.
16     mass_grid = mass._assign_mass_NGP(positions)
17
18     # Plot the slices
19     for z in [4,9,11,14]:
20         slice = mass_grid[:, :, z]
21         #slice[slice == 0] = np.nan
22
23         plt.imshow(slice)
24         plt.colorbar()
25         plt.savefig('Plots/5a_slice_{0}.pdf'.format(z))
26         plt.close()
```

`./Code/assignment_5.py`

Plots - Slices

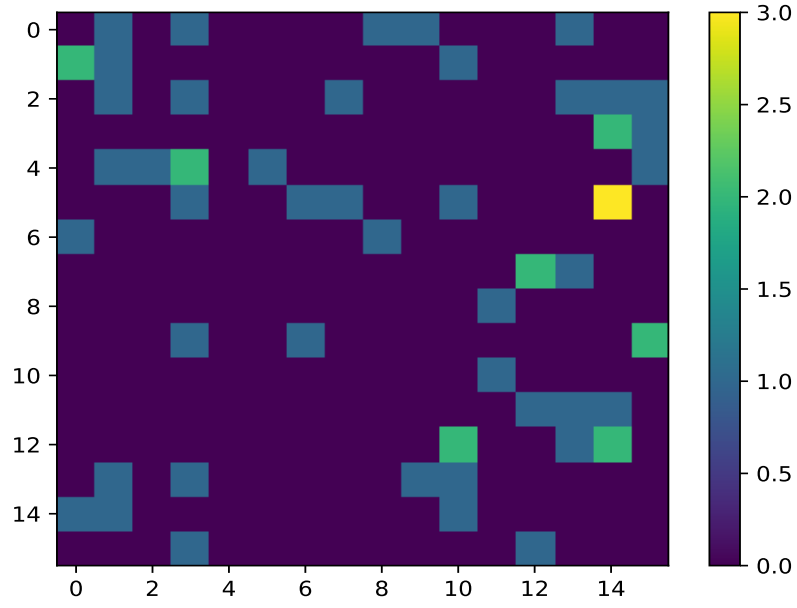


Figure 30: The x-y slice of the created mass grid for $z = 4$. The color indicates the assigned mass in terms of particle mass.

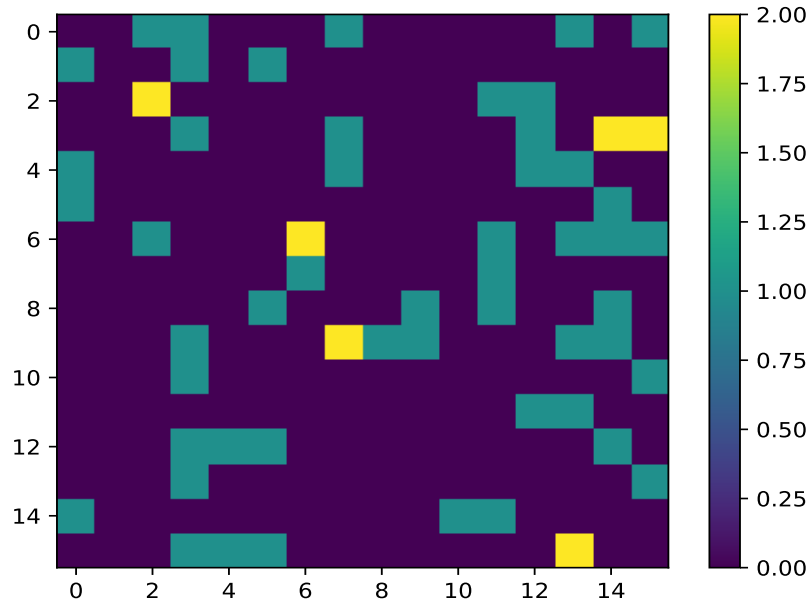


Figure 31: The x-y slice of the created mass grid for $z = 9$. The color indicates the assigned mass in terms of particle mass. Notice that the range of the colorbar is different from the first and last plot.

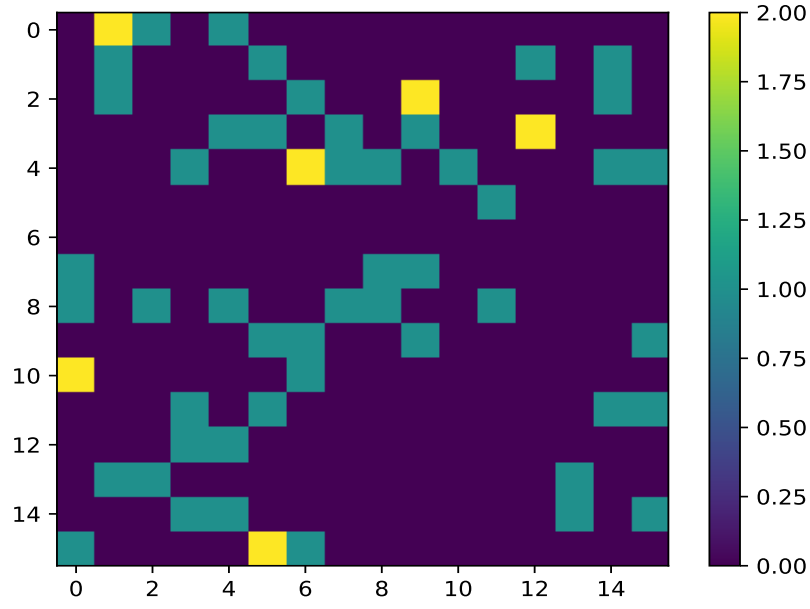


Figure 32: The x-y slice of the created mass grid for $z = 11$. The color indicates the assigned mass in terms of particle mass. Notice that the range of the colorbar is different than the first and last plot.

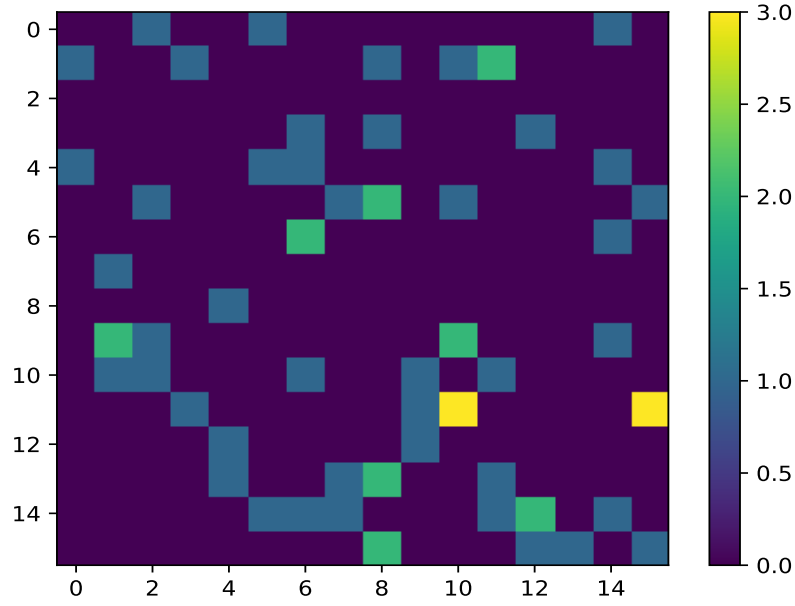


Figure 33: The x-y slice of the created mass grid for $z = 14$. The color indicates the assigned mass in terms of particle mass.

Question 5.b)

Problem

To check the robustness of your implementation make a plot of the x position of an individual particle and the value in cell 4 in 1 dimension and let x vary from the lowest value to the highest possible value in x . Repeat for cell 0.

Solution

There is not much to explain here, besides that the results for cell 4 and cell 0 are shown in the same plot. The code that creates the plot and the plot can be found below.

Code - Plots

The code that creates the plots for cell 0 and cell 4.

```
1 def assignment_5b():
2     """
3     Execute assignment 5.b
4     """
5
6     # Relevant imports are:
7     # (1) import numpy as np
8     # (2) import mathlib.mass as mass
9     # (3) import matplotlib.pyplot as plt
10
11     # The x positions of the moving particle
12     x_values = np.linspace(0, 16, 1000)
13
14     # The y positions of the moving particle for
15     # cell 0 and 4
16     y_values_4 = list()
17     y_values_0 = list()
18
19     # For each position create the mass grid and get the value in cell 4 and 0
20     for x in x_values:
21         grid = mass._assign_mass_NGP(np.array([[x], [0], [0]]))
22         y_values_0.append(grid[0,0,0])
23         y_values_4.append(grid[4,0,0])
24
25     # plot the positions
26     plt.plot(x_values, y_values_4, label='Cell 4')
27     plt.plot(x_values, y_values_0, label='Cell 0')
28     plt.xlabel('Positon x')
29     plt.ylabel('Mass in terms of particle mass')
30     plt.legend()
31     plt.savefig('./Plots/5b-cell.pdf')
32     plt.close()
```

./Code/assigment_5.py

Plots - Cell

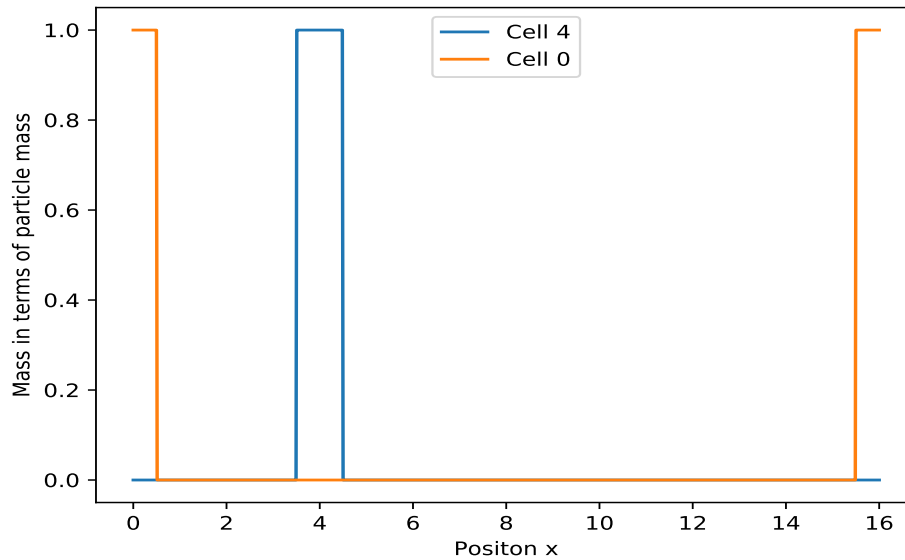


Figure 34: The mass assigned for a particle moving from $x = 0$ to $x = 16$. The orange and red line respectively indicate the mass assigned to cells 0 and 4 as function of the position of the particle. The plot is created for a mass grid of size 16 with circular boundary conditions.

Question 5.c)

Problem

Right now we want to improve this method, because NGP has several disadvantages. For this we are going to use a method which assumes that particles are cubes in 3D of uniform density and have the size of a grid cell. Calculatue how mass needs to be assigned in the case of this other method called the Cloud In Cell (CIC) method and implement it in code. To check the robustness of your implementation again make the same plots as before.

Solution

The mass needs to be assigned over the nearest 8 grid points. Each grid point gets thereby a fraction of the cube around the particle. The fraction assigned to a grid point here depends on the position of the particle and might be zero for some of the nearest 8 grid points. The way in which the mass is assigned to the nearest gird points is explained in the comment of the code that assigns the mass (page 73). The code that creates the plots and the plots them self can be found below.

Code - Plots

The code that creates the same plots as in 5.a and 5.b for a 3D grid with the CIC method.

```
1 def assignment_5c():
2     """
3     Execute assignment 5.c
4     """
5
6     # Relevant imports are:
7     # (1) import numpy as np
8     # (2) import mathlib.mass as mass
9     # (3) import matplotlib.pyplot as plt
10
11
12     np.random.seed(121)
13     positions = np.random.uniform(low =0, high=16, size=(3,1024))
14
15     # Create the mass grid.
16     mass_grid = mass._assign_mass_CIC(positions)
17
18     # Plot the slices.
19     for z in [4,9,11,14]:
20         slice = mass_grid[:, :, z]
21         #slice[slice == 0] = np.nan
22
23         plt.imshow(slice)
24         plt.colorbar()
25         plt.savefig('./Plots/5c_slice_{0}.pdf'.format(z))
26         plt.close()
27
28     # The x positions of the moving particle
29     x_values = np.linspace(0, 16, 1000)
30
31     # The y positions of the moving particle for
32     # cell 0 and 4
33     y_values_4 = list()
34     y_values_0 = list()
35
36     # For each position create the mass grid and get the value in cell 4 and 0
37     for x in x_values:
38         grid = mass._assign_mass_CIC(np.array([[x],[0],[0]]))
39         y_values_0.append(grid[0,0,0])
40         y_values_4.append(grid[4,0,0])
41
42     # plot the positions
43     plt.plot(x_values, y_values_4, label='Cell 4')
44     plt.plot(x_values, y_values_0, label='Cell 0')
45     plt.xlabel('Positon x')
46     plt.ylabel('Mass in terms of particle mass')
47     plt.legend()
48     plt.savefig('./Plots/5c_cell.pdf')
49     plt.close()
```

./Code/assignment_5.py

Plots - Slices

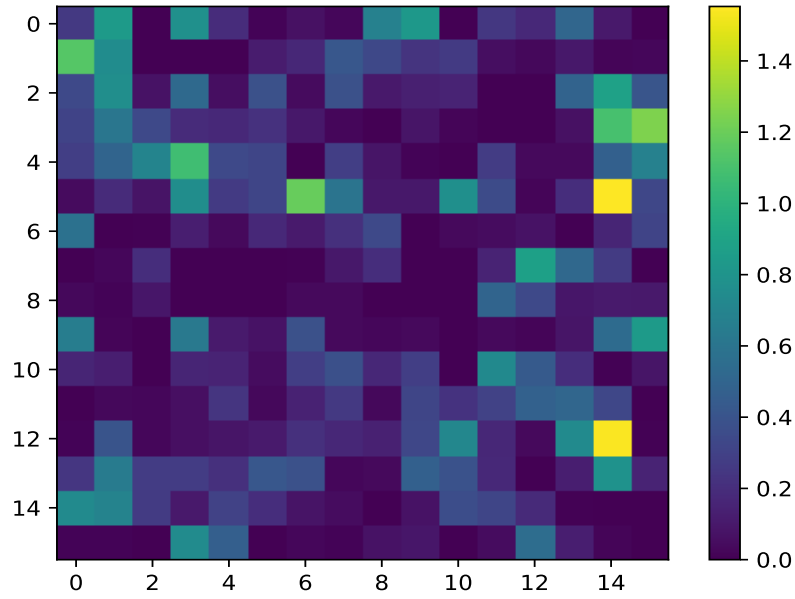


Figure 35: The x-y slice of the created mass grid with the CIC method for $z = 4$. The color indicates the assignment mass in terms of particle mass. Notice that the range of the colorbar deviates from the other three figures below.

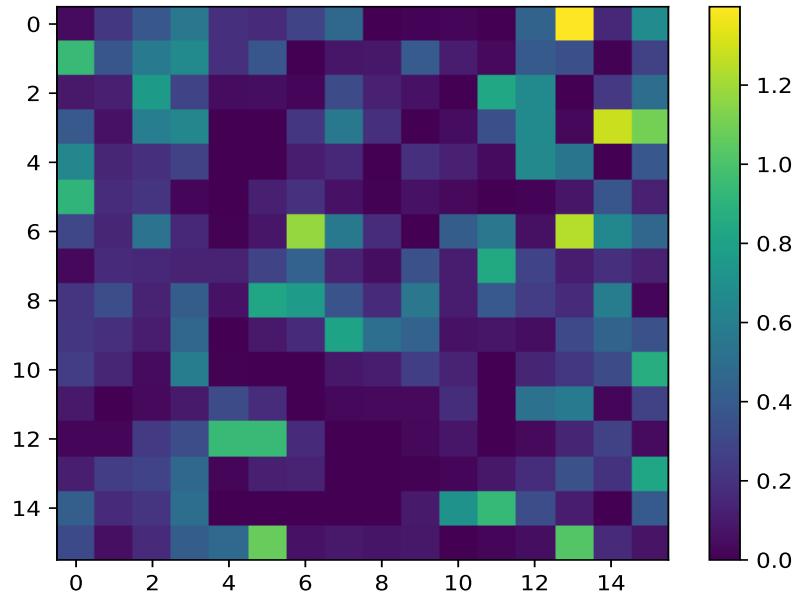


Figure 36: The x-y slice of the created mass grid with the CIC method for $z = 9$. The color indicates the assignment mass in terms of particle mass. Notice that the scale of the colorbar deviates from the other three figures.

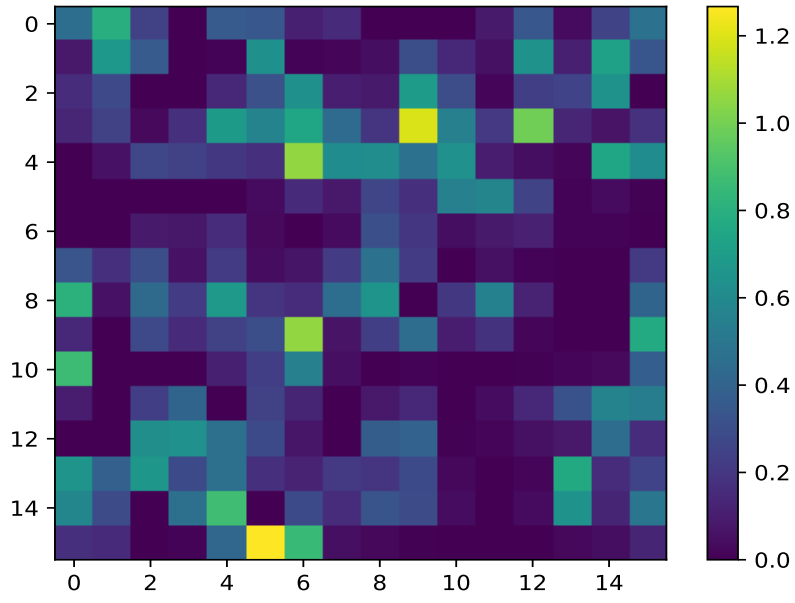


Figure 37: The x-y slice of the created mass grid with the CIC method for $z = 11$. The color indicates the assignment mass in terms of particle mass. Notice that the colorbar deviates from the other three figures.

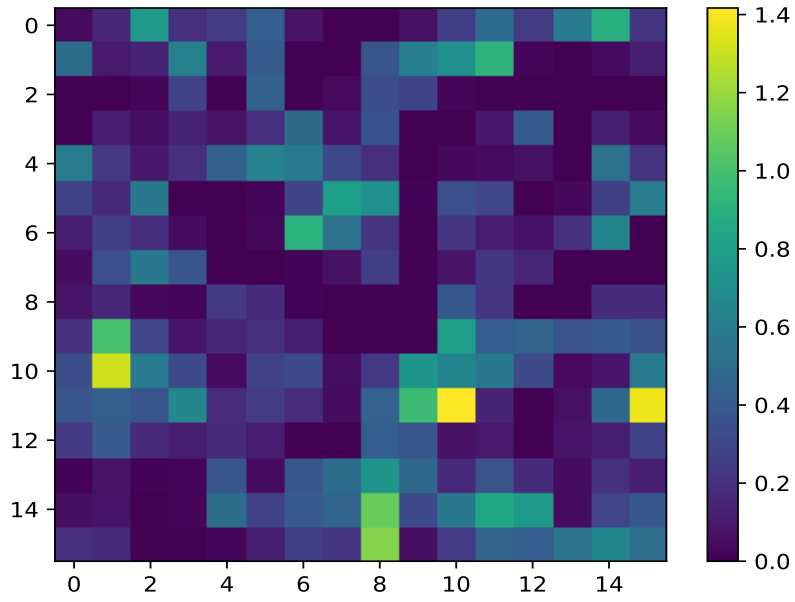


Figure 38: The x-y slice of the created mass grid with the CIC for $z = 14$. The color indicates the assignment mass in terms of particle mass. Notice that the scale of the colorbar deviates from the other three figures.

Plots - Cells

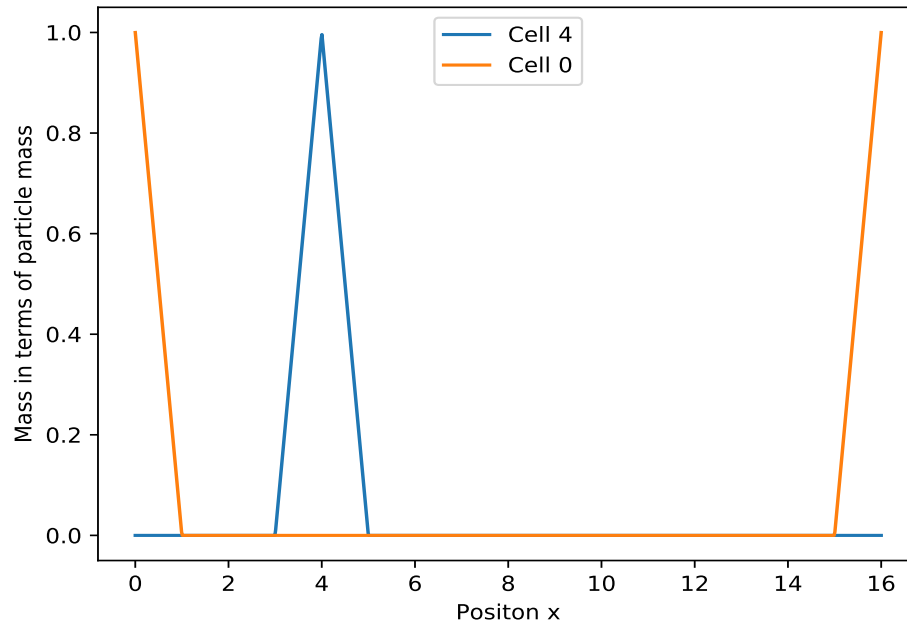


Figure 39: The mass assigned for a particle moving from $x = 0$ to $x = 16$ for the cloud in the cell method. The orange and red line respectively indicate the mass assigned to cells 0 and 4 as function of the position of the particle. The plot is created for a 3D mass grid of size 16 with circular boundary conditions.

Question 5.d)

Problem

Write your own FFT algorithm; check that your code works with a 1D function (no Gaussian) by making a plot of the FFT and compare your result with a python package and the analytical FFT of your function. In the rest of this exercise you need to use your own FFT.

Solution

The created implementation of the FFT consist of an recursive implementation with the Cooley-Tukey algorithm. The implementation doesn't store the data inplace, but in a new array. This choice was made to prevent the input array from being modified. One consequence of this choice is that the input array does not have to be reverse bit shifted.

The implementation is compared with the numpy implementation. The function that is chosen to fourier transform is the cosine⁴,

$$\mathcal{F}(\cos(x)) \propto 0.5(\delta(f - x) + \delta(f + x)) \quad (41)$$

The code for the FFT can be found on page 75. The code that compares the self written implementation with the numpy implementation and the analytical solution can be found below.

⁴The given expression contains a proportional sign as the pre-factor depends on the definition of the Fourier transformation.

Code - Plot

The code that creates the plot for the comparison of the self written FFT with the numpy implementation and the analytical solution. The plot can be found below this segment of code.

```
1 def assignment_5d():
2     """
3     Execute assignment 5.d
4     """
5
6     # Relevant imports are:
7     # (1) import numpy as np
8     # (2) import matplotlib.pyplot as plt
9     # (3) import mathlib.misc as misc
10    # (3) import mathlib.fourier as fourier
11
12    # Create the data to fourier transform.
13    size = 64
14
15    t = np.linspace(0, size, size)
16    f = 5
17    y = np.cos(2*np.pi*f*t)
18
19
20    # Execute the FFT
21    fft_np = np.fft.fft(y)
22    fft_self = fourier.fft(y)
23
24    # Frequencies to plot for.
25    freq = misc.gen_wavenumbers(size,1)*size
26
27    plt.plot(freq, abs(fft_np), label='numpy', linestyle=':', zorder=1.1)
28    plt.plot(freq, abs(fft_self), label='self', zorder=1.0)
29    plt.vlines(-2*np.pi*f, 0, max(abs(fft_self))+10, label='Analytical')
30    plt.vlines(2*np.pi*f, 0, max(abs(fft_self))+10)
31
32    plt.xlabel('Frequency')
33    plt.ylabel('Power')
34    plt.legend()
35    plt.savefig('./Plots/5d_fourier.pdf')
36    plt.close()
```

./Code/assignment_5.py

Plot - Comparison

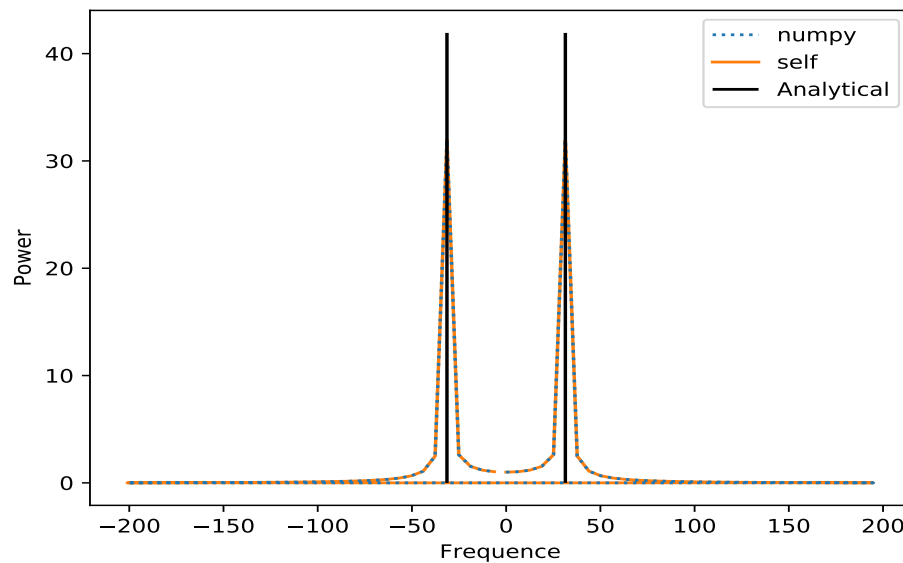


Figure 40: The own implementation of the FFT (orange), the numpy implementation (blue) and the analytical fft (black). The plot shows that there is now visible deviation from the numpy version. It can also be seen that both the numpy and the self written implementation do not correctly represent the peak of the delta function. This is expected as it would require an infinite amount of samples to obtain the exact same result.

Question 5.e)

Problem

Generalize your own FFT algorithm to 2 and 3 dimensions and make a plot of the FFT of a 2D function (no bivariate Gaussian) and compare it with the analytical FFT of your FFT. Also make a plot of the FFT of a 3D multivariate Gaussian function, plot 3 slices centered at the center for the 3 different slice options x-y, x-z, y-z.

Solution

The code for the 2D and 3D implementation makes use of the code for the 1D implementation. In 2D the FFT is first taken over the first axis of the input matrix and then over the second axis. In 3D the FFT2 is first taken over the first axis and then the FFT is taken over the third axis. The code is not generalized to N-dimensions, as the question did not ask to write your own swapaxis algorithm.

The chosen function to 2D fourier transform is $\cos(x + y)$. The analytical result consists of two 2D delta functions. The code that makes the plots for the 2D FFT and the 3D FFT can be found below, the implementation its self can be found on page 75. The plots can be found below the code.

Code - Plot

The code that creates the plots.

```
1 def assignment_5e():
2     """
3     Execute assignment 5e
4     """
5
6     # Relevant imports are:
7     # (1) import numpy as np
8     # (2) import matplotlib.pyplot as plt
9     # (3) import mathlib.misc as misc
10    # (3) import mathlib.fourier as fourier
11
12    # The function to 2D fourier transform
13    func_2d = lambda x,y: np.cos(x+y)
14    x,y = np.meshgrid(range(0, 64), range(0,64))
15    x = np.array(x, dtype=complex)
16    y = np.array(y, dtype=complex)
17
18    _, ax = plt.subplots(nrows=1,ncols=2)
19
20    # Self written FFT2
21    ax[0].imshow(abs(fourier.fft2(func_2d(x,y))))
22    ax[0].set_title("Self written FFT2")
23    ax[0].set_xlabel('index')
24    ax[0].set_ylabel('index')
25
26    # Numpy FFT
27    ax[1].imshow(abs(np.fft.fft2(func_2d(x,y))))
28    ax[1].set_title("Numpy version FFT2")
29    ax[1].set_xlabel('index')
30    ax[1].set_ylabel('index')
31
32    plt.savefig('./Plots/5e_2d_fft.pdf',bbox_inches='tight')
33    plt.close()
34
35    # 3D
36    # The multivariate gaussian.
37    # I am fully aware that this line looks ugly in the report.
38    multivariate_sigma = lambda x,y,z, sigma: (1.0/(sigma**2*np.pi)**(3/2)) *
39    np.exp(-(((x**2)/2) + ((y**2)/2) + ((z**2)/2))/sigma**2)
40
41    # The multivariate to plot, sigma = 0.5
42    multivariate = lambda x,y,z: multivariate_sigma(x,y,z, 0.5)
43
44    # Plot the multivariate gaussian
45    N = 64
46    values = np.arange(0,N)
47    values = np.array(values,dtype=complex)
48    x,y,z = np.meshgrid(values,values,values)
49
50    matrix = multivariate(x,y,z)
51    matrix_fft = fourier.fft3(matrix)
52
53    # y-z slice
54    plt.imshow(abs(matrix_fft[int(N/2)]))
55    plt.xlabel('y')
56    plt.ylabel('z')
57    plt.savefig('./Plots/5e-gaussian_yz.pdf')
58    plt.close()
59
60    # x-z slice
61    plt.imshow(abs(matrix_fft[:,int(N/2),:]))
62    plt.xlabel('x')
63    plt.ylabel('z')
64    plt.savefig('./Plots/5e-gaussian_xz.pdf')
65    plt.close()
66
67    # y-x slice
68    plt.imshow(abs(matrix_fft[:, :,int(N/2)]))
```

```

68 plt.xlabel('x')
69 plt.ylabel('y')
70 plt.savefig('./Plots/5e-gaussian-xy.pdf')

```

./Code/assignment_5.py

Plot - 2D

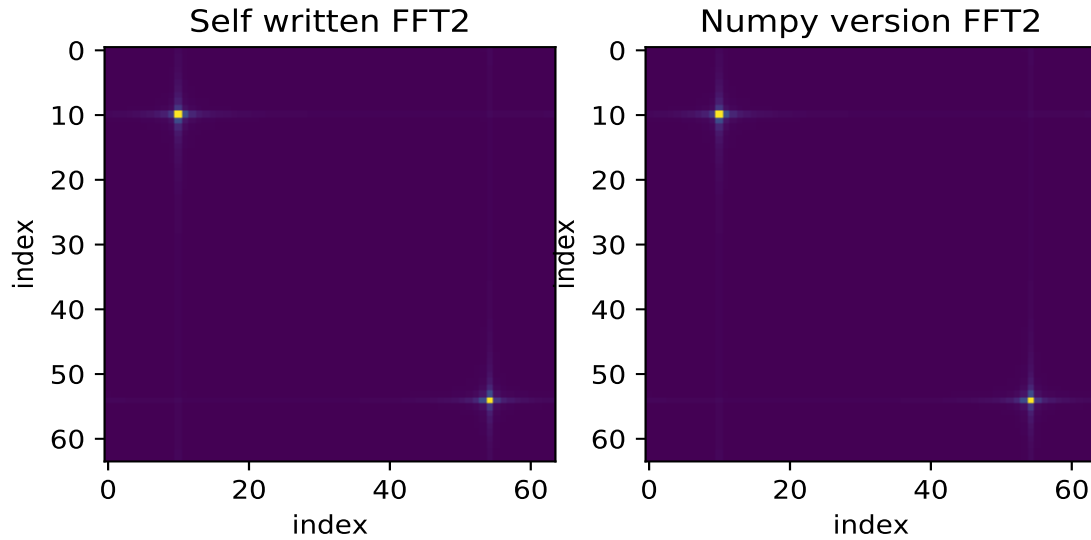


Figure 41: The 2D fourier transformation for the function $\cos(x + y)$. Left, the own implementation of the FFT2 (left) and right the numpy implementation. The results show that the self written version appears to be equal to the numpy version. For the cosine two delta peaks are expected to arise which can also be seen. The peaks are not infinite sharp as that would require an infinite amount of samples.

Plot - 3D

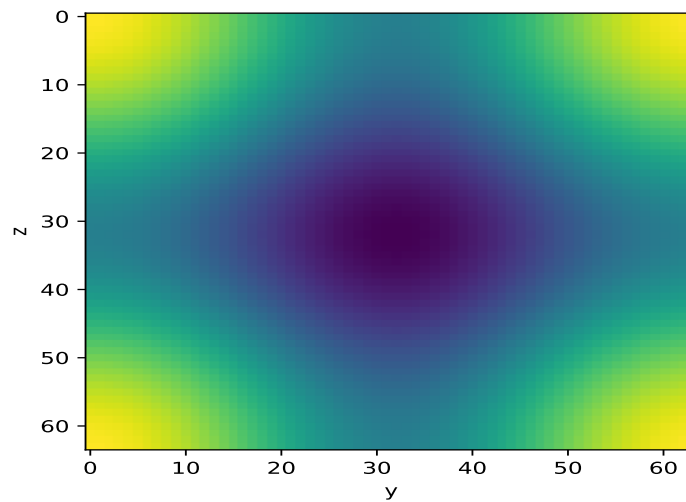


Figure 42: The yz slice around the center of the 3D Fourier transform of a multivariate gaussian with $\mu = 0$ and $\sigma = 0.5$. The slice should be perfectly symmetric and the result shows that this is indeed the case.

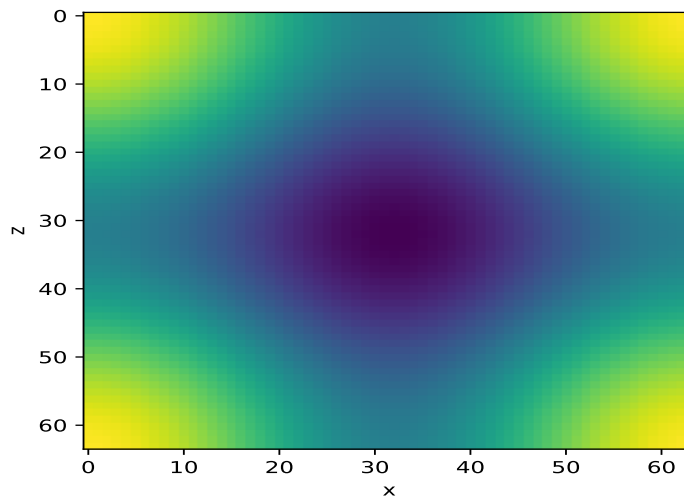


Figure 43: The xz slice around the center of the 3D Fourier transform of a multivariate gaussian with $\mu = 0$ and $\sigma = 0.5$. The slice should be perfectly symmetric and the result shows that this is indeed the case.

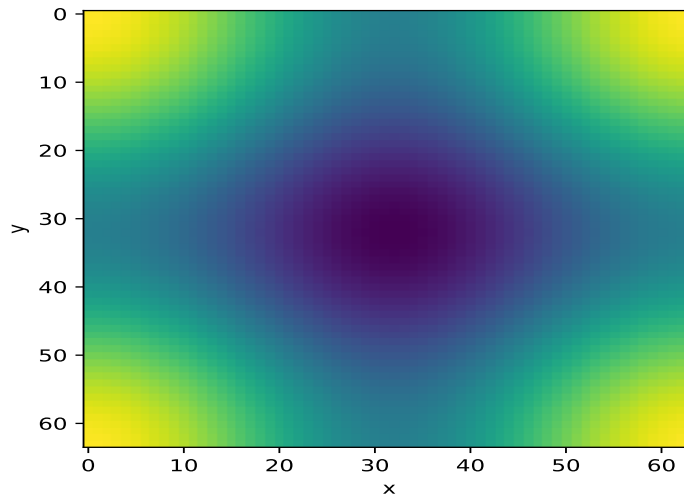


Figure 44: The xy slice around the center of the 3D Fourier transform of a multivariate gaussian with $\mu = 0$ and $\sigma = 0.5$. The slice should be perfectly symmetric and the result shows that this is indeed the case.

Question 5 - Summary

Summary

The current sub-section contains the summary of the code used for assignment 5. This includes the part of the main file that executes the subquestions, the relevant imports, the functions to assign the mass for the NGP and CIC method and, the code for the Fourier transformations.

Code - Assignment

The code with the main function that executes the sub questions and the relevant imports.

```

1 import numpy as np
2 import matplotlib.pyplot as plt
3 import mathlib.mass as mass
4 import mathlib.fourier as fourier
5 import mathlib.misc as misc
6

```



```

7 def main():
8     assignment_5a()
9     assignment_5b()
10    assignment_5c()
11    assignment_5d()
12    assignment_5e()

```

./Code/assignment_5.py

Code - Mass

The code that assigns the masses for the NGP and CIC method

```

1 import numpy as np
2
3
4 def _assign_mass_NGP(positions):
5     """
6         Create a mass grid of size 16x16 with
7         the Nearest Grid Point shape.
8     In:
9         param: positions — The positions of the N particles as
10                        an matrix of size 2xN.
11     Out:
12         return: A matrix representing the mass grid.
13     """
14
15     # Create the empty grid
16     mass_grid = np.zeros((16,16,16))
17
18     # Add 0.5 and cast to an integer. The positions are now
19     # the indices in the grid.
20     positions = np.array(positions + 0.5, dtype=np.int32)
21
22     # Assign the masses by looping over the positions
23     for i in range(0, len(positions[0])):
24         # Mod 16 for cirulair boundaries.
25         mass_grid[positions[0][i] % 16, positions[1][i] % 16, positions[2][i] %
26         16] += 1
27
28     # Return the mass.
29     return mass_grid
30
31 def _assign_mass_CIC(positions):
32     """
33         Create a mass grid of size 16x16x16 with
34         the Nearest Grid Point shape.
35     In:
36         param: positions — The positions of the N particles as
37                        an matrix of size 3xN.
38     Out:
39         return: A matrix representing the mass grid.
40     """
41
42     mass_grid = np.zeros((16,16,16))
43
44     for i in range(0, len(positions[0])):
45
46         # The cube below represents the cube made by the 8 grid points that
47         # enclose a particle. Next we assume that the sides of are side
48         #   LTU————RTY
49         #   //          //
50         #  //          //
51         # LTD————RTD
52         #  |  |  LBU-----RBU
53         #  |  |  //          //
54         #  //          //
55         # LBD —————RBD

```

```

57
58 # Let $x_{cell},y_{cell},z_{cell}$ be the position of
59 # the left top bottom (LTB) edge of the Grid Cube that
60 # encloses the particle. Let x,y,z be the position of the particle.
61 # The difference between the particle position and the LTB edge
62 # is then given by,
63 # dx = x - x_{cell}
64 # dy = y - y_{cell}
65 # dz = z - z_{cell}
66 # The above quantities can be used to calculate the volume fractions
67 # that needs to be assigned to the 8 nearest grid points of the cube
68 # that the particle represents.
69 # Working this out (by for example a drawing) gives.
70 #
71 # LTD = (1 - dx)*(1 - dy)*(1-dz)
72 # RTD = (1 - dx)*dy*(1 - dz)
73 # LTU = (1 - dx)*(1 - dy)*dz
74 # RTU = (1 - dx)*dy*dz
75 # LBD = dx*(1-dy)*dz
76 # RBD = dx*dy*(1-dz)
77 # LBU = dx*(1-dy)*dz
78 # RBU = dx*dy*dz
79
80 # Get the indices of the grid point at the left bottom of
81 # the cell in which the particle is
82 center_x = np.int32(positions[0][i]) % 16
83 center_y = np.int32(positions[1][i]) % 16
84 center_z = np.int32(positions[2][i]) % 16
85
86 # Helper variables to calculate the
87 # volume fractions. Mode 16 for circular boundary conditions
88 dx = positions[0][i] % 16 - center_x
89 dy = positions[1][i] % 16 - center_y
90 dz = positions[2][i] % 16 - center_z
91
92 frac_dx = 1 - dx
93 frac_dy = 1 - dy
94 frac_dz = 1 - dz
95
96 # Calculate the volume fractions, assume unit particle mass
97
98 # Left top down
99 mass_grid[center_x][center_y][center_z] += frac_dx*frac_dy*frac_dz
100 # Right top down
101 mass_grid[center_x][(center_y+1) % 16][center_z] += frac_dx*dy*frac_dz
102 # Left top up
103 mass_grid[center_x][center_y][(center_z+1) % 16] += frac_dx*frac_dy*dz
104 # Right top up
105 mass_grid[center_x][(center_y+1) % 16][(center_z+1) % 16] += frac_dx*dy*dz
106
107 #Left bottom down
108 mass_grid[(center_x+1) % 16][center_y][center_z] += dx*frac_dy*frac_dz
109 # Right bottom down
110 mass_grid[(center_x+1) % 16][(center_y+1) % 16][center_z] += dx*dy*
111 frac_dz
112 # Left bottom up
113 mass_grid[(center_x+1) % 16][center_y][(center_z+1) % 16] += dx*frac_dy*
114 dz
115 # Right bottom up
116 mass_grid[(center_x+1) % 16][(center_y+1) % 16][(center_z+1) % 16] += dx*
117 dy*dz
118
119 return mass_grid

```

./Code/mathlib/mass.py

Code - Fourier

The code containing the fourier transformations.

```
1 import numpy as np
2
3 def fft(data):
4     """
5     Perform the DFT with the cooley-tukey algorithm.
6     In:
7         param: data — The array to fourier transform, must be of length 2**N
8     Out:
9         return: The fft of the data with the zeroth frequency as the first element
10    """
11
12    # Get the length of the data
13    n = len(data)
14
15    # The array to return. By using this
16    # array the input array won't require
17    # a reverse bitshift. This was mainly done
18    # to prevent modifying the input array.
19    ret = np.zeros(n, dtype=complex)
20
21    # The FFT of 1 element is the element self.
22    if n == 1:
23        ret[0] = data[0]
24        return ret
25
26    # Perform the FFT on the even indices and
27    # odd indices.
28    even = fft(data[::2])
29    odd = fft(data[1::2])
30
31    # Calculate the recurrent split for the
32    # values of k. Notice here that
33    # there is a minus sign, which the result
34    # of symmetry that is exploited.
35    for k in range(int(n/2)):
36
37        # Multiply with the complex exponent
38        odd[k] *= np.exp(-1j*2*np.pi*k/n)
39
40        # Calculate the FFT for the discretized k (or f) values
41        ret[k] = even[k] + odd[k]
42        # symmetry exploit
43        ret[k+int(n/2)] = even[k] - odd[k]
44
45    # return the fourier transform, don't use a normalization
46    return ret
47
48
49 def fft2(data):
50     """
51     Calculate the 2D fourier transformation.
52     In:
53         param: data — The data to fourier transform
54     Out:
55    """
56
57    for i in range(data.shape[0]):
58        #kx_0, ky_0, kx_0, ky_1, kx_0, ky_2, kx_0, ky_3
59        data[i] = fft(data[i])
60
61    # now perform it over the rows (x direction)
62    for i in range(data.shape[0]):
63        #kx_0, ky_0, kx_1, ky_0, kx_2, ky_0, (store in column)
64        data[:, i] = fft(data[:, i])
65
66    return data
67
```

```

68
69 def fft3(data):
70     """
71     Perform the 3 dimensionale fourier transform
72     In:
73     param: — The data to fourier transform
74     Out:
75     return: The 3D fourier transform of the data.
76     """
77
78     # First fourier transform the planes
79     for i in range(data.shape[0]):
80         data[i, :, :] = fft2(data[i, :, :])
81
82     # Finally fourier transform the last axis.
83     for i in range(data.shape[2]):
84         for j in range(data.shape[1]):
85             data[:, i, j] = fft(data[:, i, j])
86
87     return data

```

./Code/mathlib/fourier.py

6 - Classifying x-ray bursts

Question 6

Problem

Use logistic regression to make a model of the data, using a binary classification for short or long GRBs. Explain which properties your model uses to predict whether a GRB is short or long, and how you handle missing data. Plot a histogram of the class (0 or 1) of GRB and overplot the actual class based on the value of T_{90} .

Solution

The data is before training the model pre-processed as follows. The first step consists of removing all rows with missing T_{90} (this only consists of two rows). Next, the columns with logarithmic values are taken to the power of an exponent. Finally the values of -1 in the non logarithmic columns and the values of e^{-1} in the logarithmic columns are replaced with 0. The reason that the columns with logarithmic values were first taken to the exponent is because directly replacing -1.0 in such a column with 0 is equivalent to creating your own data. (i.e if $\ln(M_*/M_\odot) = 0$, then we would have created data that implies that $M_* = M_\odot$).

The columns that were chosen for training consist of the redshift, the star formation rate and the log of the mass ratio. These columns were selected based on a scatter plot made with seaborn in which all columns were plotted against each other. The code for this is not included⁵.

With these columns an accuracy of 78 % was obtained (see page 80). This value is unfortunately the base line that needs to be broken, as in the final dataset 78% of all entries are long GRBs. The model is thus returning '1' for each entry. Attempts to use different combinations of columns always resulted in the same accuracy. The code that creates the histogram and the code for the logistic regression can be found below.

Code - Plot

The code that creates the plots.

```
1 import numpy as np
2 import matplotlib.pyplot as plt
3 import matplotlib.pyplot as plt
4
5 # Load the data
6 # Column 2 = redshift, 3 = T90
7 data = np.genfromtxt("GRBs.txt")
8
9 # Remove the first 2 columns. These contain 'GRB/XRF' and the number.
10 data = data[:,2:]
11 data = np.array(data)
12 # The columns are now:
13 # 0 = redshift, 1 = T90, 2 = log(M*/M_{sun})
14 # 3 = SFR, 4 = log(Z/Z_{sun}), 5 = SSFR, 6 = AV
15
16 # Remove all rows without T90
17 data = data[data[:,1] != -1]
18
19 # Replace all missing data with zero's, but be careful about
20 # the logarithms. To correct the logarithms we take the
21 # column of a logarithm to the power of e and then put e^{-1} to zero.
22
23 data[:,2] = np.exp(data[:,2])
24 data[:,4] = np.exp(data[:,4])
25
26 # Correct for missing data
27 for i in range(0,7):
28     if i == 2 or i == 4:
29         mask = (data[:,i] == np.exp(-1))
30         data[:,i][mask] = 0
31     else:
32         mask = (data[:,i] == -1)
```

⁵I did not have enough time to recreate the plot without seaborn before the deadline.

```

33     data[:, i][mask] = 0
34
35
36 # The chosen columns are:
37 # - redshift
38 # - log(M*/M_{sun})
39 # - SFR
40 #
41 # These are used to create the final data for training the model.
42 # The final train data consists of the chosen columns plus
43 # one additional column that is all 1 (used for bias)
44
45 # The columns in the dataset to select.
46 columns = [0, 2, 3]
47
48 train_data = np.ones((data.shape[0], len(columns)+1))
49 train_data[:, [0, 1, 2]] = data[:, columns]
50 train_labels = data[:, 1] > 10
51
52 # Train the model.
53 logistic_reg = lg.LogisticRegression(len(columns), 1e-3, 1e-5)
54 logistic_reg.train(train_data, train_labels)
55
56 # Predictions
57 predictions = logistic_reg.predict(train_data)
58 predictions = np.array(predictions, dtype=int)
59
60 # Create the histogram
61 bins = np.arange(0, 1.1, 0.05)
62
63 plt.hist(predictions, alpha=0.9, bins=bins, label='Model')
64 plt.hist(np.array(train_labels, dtype=int), bins=bins, label='True')
65 plt.legend()
66 plt.ylabel('Counts')
67 plt.savefig('./Plots/6a_hist.pdf')
68
69 # Print the accuracy
70 print('[6] Accuracy: ', 1 - np.sum(predictions - train_labels)/len(train_labels))

```

./Code/assignment_6.py

Code - Logistic regression

The code for logistic regression.

```

1 import numpy as np
2
3 class LogisticRegression(object):
4
5     def __init__(self, variables, learn_rate = 0.01, error = 1e-2):
6         """
7         Create a new instance of a LogisticRegressor
8         """
9         # weights, also add bias
10        self._weights = np.zeros(variables + 1)
11        self._learn_rate = learn_rate
12        self._error = error
13
14
15    def train(self, data, labels):
16        """
17        Train the current logistic regression model
18        """
19
20        # Current error
21        error = 1e4
22
23        # Max iterations
24        max_iter = 1e4
25        # Current iteration
26        curr_iter = 0

```

```

27
28 # Cost of the previous train iteration
29 old_cost = 1e4
30
31 # While we haven't accuired the required error
32 # or haven't reahced hte maximum number of iterations
33 # keep training.
34
35 while error > self._error and curr_iter < max_iter:
36
37     # Cost and gradient
38     cost = 0
39     gradient = np.zeros(self._weights.shape[0])
40
41     # Calculate the cost and the gradient
42     for idx in range(0, data.shape[0]):
43         y_est = self._sigmoid(np.dot(self._weights, data[idx]))
44         y = labels[idx]
45         term = -(y*np.log(y_est) + (1-y)*np.log(1-y_est))
46
47         cost += term
48         gradient += term*data[idx]
49
50     cost = cost/data.shape[0]
51     gradient = gradient/data.shape[0]
52
53     # Update the weights
54     self._weights += self._learn_rate*gradient
55
56     # Update the error
57     error = abs(cost - old_cost)
58     old_cost = cost
59     curr_iter += 1
60
61
62 def predict(self, data):
63     """
64     Predict the labels for the given data.
65     In:
66         param: — A matrix where each row represent a row in the data
67                set for which a label needs to be predicted. The last
68                value of each row must be a 1.
69     Out:
70         return: An array with predicted labels.
71     """
72     labels = list()
73     for row in data:
74         labels.append(self._sigmoid(np.dot(self._weights, row))> 0.5)
75
76     return np.array(labels)
77
78
79 def _sigmoid(self, x):
80     """
81     Evaluate the sigmoid activation function.
82     In:
83         param: x — The point(s) to evaluate it for.
84     Out:
85         return: The sigmoid activation function evaluated at the
86                given point(s).
87     """
88     # 1e-7 is to correct for exponents that are zero.
89     # This was needed as some values of columns where taken to the exponent.
90
91     return 1/(1+np.exp(-x) + 1e-7)

```

./Code/mathlib/LogisticRegression.py

Text - Output

The accuracy obtained by the model.

```
1 [6] Accuracy: 0.7811158798283262
```

./Output/assignment6_out.txt

Plots- Histogram

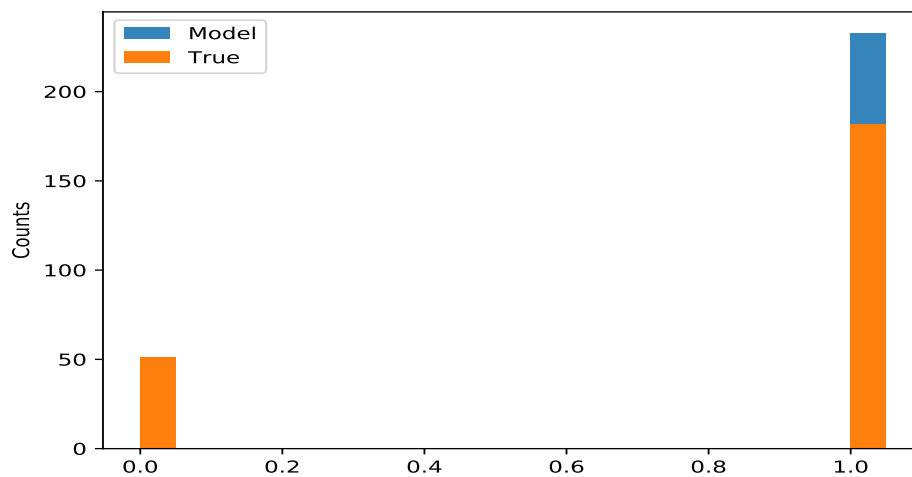


Figure 45: The created histogram for the prediction made by the model and the true labels. It can be seen here that the model always returns '1'.

7 - Building a quadtree

Question 7

Problem

Download the file containing 1200 particle masses and positions. Considering only the x and y coordinates of these particles (between 0 and 150), construct a Barnes-Hut quadtree with at most 12 particles per leaf node. You can treat the masses and positions as dimensionless and use $G = 1$. Plot the particles and indicate which particles are in which node. Calculate the $n = 0$ multipole moment of each leaf and then recursively for each node in the tree. Print the $n = 0$ multipole moment for the leaf node containing the particle with index $i = 100$ and that of all its parent nodes up to and including the root node.

Solution

The zeroth order multipole moment for a leaf node corresponds to the sum of the masses of the particles in that leaf node. The multipole moment of a parent node (this can be a parent of a leaf, or a parent of a non leaf) is the sum of the multipole moment of its children. With this knowledge a quadtree has been constructed that calculates the multipole moment for each of its nodes. The origin of the tree is chosen to be $x = 0, y = 0$ and corresponds with the left bottom coordinate of the root quad. The size of the root node is chosen to be 150. The root node is thus a quad with edge points: (0,0) (origin), (150,0) right bottom, (0,150) left top, (150,150) right

top.

The code for the tree, a plot of the particles in the tree and the multipole moments can be found below. The code is split over two files, the first file contains the code that constructs the quadtree and adds the particles to the tree. The second file contains the code that contains the quadtree its self.

Code - Output

The code that constructs the quad tree and adds the particles to it.

```
1 import h5py
2 import matplotlib.pyplot as plt
3 import numpy as np
4 import mathlib.quadtree as qt
5
6 # Load the data
7 particles_data = h5py.File('colliding.hdf5')['PartType4']
8 particles_pos = np.array(particles_data['Coordinates'])
9 particles_masses = np.array(particles_data['Masses'])
10
11 # Create a combined array with mass and positions
12 # (I assumend that np.concatenate was not allowed)
13 particle_info = np.zeros((len(particles_masses),4))
14 particle_info[:,3] = particles_masses
15 particle_info[:,2] = particles_pos[:,2]
16 particle_info[:,1] = particles_pos[:,1]
17 particle_info[:,0] = particles_pos[:,0]
18
19 # Create an instance of the quad tree with origin (0,0)
20 # size 150 and max 12 particles per node.
21 tree = qt.QuadTree((0,0), 150, 12)
22
23 # Add the particles to the tree.
24 for particle in particle_info:
25     tree.add_boddy(particle)
26
27 # Before creating the plot, plot the particle with
28 # index 100.
29 plt.scatter(particle_info[100,0], particle_info[100,1], c='red', s=100)
30 # Create the plot with final particles.
31 tree.plot()
32
33 # Print the moments of the leaf containing the particle with
34 # index 100 and the moment of its parent nodes.
35 tree.print_moments(particle_info[100,0], particle_info[100,1])
```

./Code/assignment_7.py

Code - Tree

The code of the quadtree.

```
1 import numpy as np
2 import matplotlib.pyplot as plt
3 import matplotlib.patches as patches
4 import matplotlib.collections as collections
5
6 class QuadTree(object):
7     """
8     An object representing a quad tree
9     """
10
11     def __init__(self, left_bottom, size, max_boddies):
12         """
13         Create an instance of the quadtree.
14         In:
15         param: left_bottom — The coordinates of the leftbottom point of
16                             the root quad.
17         param: size — The size of the root quad.
18         param: max_boddies — The maximum amount of boddies to add before
```

```

19                                     splitting a node.
20     """
21
22     # Create the root quad.
23     self._root = Quad(left_bottom, size, max_boddies, None)
24
25 def add_boddy(self, boddy):
26     """
27         Add a boddy to the tree.
28     In:
29         param: boddy — The boddy to add.
30     """
31
32     # Add the boddy to the root node
33     self._root.add_boddy(boddy)
34
35 def find_leaf(self, pos_x, pos_y):
36     """
37         Find the leaf node that contains the specific positon.
38     In:
39         param: pos_x — The x coordinate of the position.
40         param: pos_y — The y coordinate of the position.
41     Out:
42         return: The leaf node that contains the specific positon.
43     """
44
45     # Start by assuming that the root node is the node.
46     leaf = self._root
47
48     # If it has children find the child containing the position.
49     while not leaf._leaf:
50         leaf = leaf._find_quad(pos_x, pos_y)
51
52     # return the quad that contains the current position.
53     return leaf
54
55 def print_moments(self, pos_x, pos_y):
56     """
57         Print the multipole moment for the leaf node
58         and al its parents that contain the given positon.
59     In:
60         param: pos_x — The x coordinate of the position.
61         param: pos_y — The y coordinate of the position.
62     """
63
64     # Find the leaf that contains the given position.
65     leaf = self.find_leaf(pos_x, pos_y)
66
67     # Print the mulitpole moment of the leaf
68     print(leaf._moment)
69
70     # Iterate through its parents and print the
71     # multipole moment of the parents
72     parent = leaf._parent
73
74     # Only root doesn't have a parent, thus abort
75     # when parent is root.
76     while parent._parent != None:
77         print(parent._moment)
78         parent = parent._parent
79
80     # Don't forget printing the moment of the root node.
81     print(parent._moment)
82
83 def plot(self):
84     """
85         Create a visual representation of the quad tree
86         and the boddies added to the tree.
87     """
88
89     # The axis used for plotting

```

```

90     axis = plt.gca()
91     # An list that contains rectangle objects (matplotlib.patches.Rectangle)
92     # for each of the quads in the tree.
93     rectangles = list()
94
95     # Fill the list with rectangles by recursively calling the
96     # children of the root. If a quad is a leaf it will furthermore
97     # axis.scatter. This is to add the boddies of that leaf
98     # to the plot. The reason that a quad not directly adds its own
99     # rectangle to the axis (axis.add_patches) is to save time.
100    self._root._plot(axis, rectangles)
101
102    # Add all the rectangles at once to save time.
103    axis.add_collection(collections.PatchCollection(rectangles,
104                                                    match_original=True))
105
106    # Create and save the plot
107    plt.xlim(self._root._left_bottom[0],
108            self._root._left_bottom[1] + self._root._size)
109    plt.ylim(self._root._left_bottom[1],
110            self._root._left_bottom[1] + self._root._size)
111    plt.xlabel('x')
112    plt.ylabel('y')
113    plt.savefig('./Plots/7_quadtree.pdf')
114    plt.figure()
115
116    class Quad(object):
117
118    def __init__(self, left_bottom, size, max_boddies, parent = None):
119        """
120        Create an instance of a quad in a quadtree.
121        In:
122        param: left_bottom — The coordinates of the leftbottom point of
123                          the quad.
124        param: size — The size of the quad.
125        param: max_boddies — The maximum amount of boddies to add before
126                          splitting this quad.
127        param: parent — The parent quad if any.
128        """
129
130        # Geometric properties of the current quad
131        self._left_bottom = left_bottom
132        self._size = size
133        self._halve_size = size/2
134
135        # 'Facts' about the quad at the moment of initalization
136        self._max_boddies = max_boddies
137        self._leaf = True
138        self._parent = parent
139
140        # An array containing child quads (if any) and
141        # the boddies in this quad (if it is a leaf).
142
143        # The child quads are named:
144        # Left Top (index 0), Left Bottom (index 1)
145        # Right top (index 2), Right bottom (index 3)
146        self._child_quads = None
147        self._boddies = list()
148
149        # The multipole moment of the current quad.
150        self._moment = 0
151
152
153    def add_boddy(self, boddy):
154        """
155        Add a boddy to the current quad or to one of its
156        child quads.
157        In:
158        param: boddy — The boddy to add. Should be an array
159                      in which the first for elemnts respectively
160                      correspond with the x-position, y-position,

```

```

161                                     z-positon and mass.
162     """
163
164
165     # If current quad is not a leaf find
166     # the child quad that should hold the boddy.
167     if not self._leaf:
168         self._find_quad(boddy[0], boddy[1]).add_boddy(boddy)
169         return
170
171     # Current quad is a leaf and can still add a boddy.
172     if len(self._boddies) < self._max_boddies:
173         # Add the boddy.
174         self._boddies.append(boddy)
175         # Update the multipole moment for this quad.
176         self._update_moment(boddy[3]) #index 3 = mass.
177
178     # Current quad is a leaf, but must split when adding a new boddy.
179     else:
180         # The boddy is before splitting first added
181         # to the current quad. When it splits the boddies
182         # of this quad will be assigned to the child quads created
183         # in the split.
184         self._boddies.append(boddy)
185         # Split the current quad and make it a leaf.
186         self._split()
187
188
189
190 def _find_quad(self, pos_x, pos_y):
191     """
192         Find a child quad that contains the specific
193         position.
194     In:
195         param: pos_x — The x coordinate of the position.
196         param: pos_y — The y coordinates of the position.
197     Out:
198         return: The child quad containing the position. If this
199                quad is a leaf, then the quad its self is returned.
200     """
201
202     # Current quad is a leaf, return its self.
203     if self._leaf:
204         return self
205
206     # Positon is in the right top or right bottom quad.
207     if pos_x > self._halve_size+self._left_bottom[0]:
208         # Position is in the right top quad.
209         if pos_y >= self._halve_size + self._left_bottom[1]:
210             return self._child_quads[2]
211         # Position is in the right bottom quad.
212         else:
213             return self._child_quads[3]
214     # Position is in the left top quad.
215     elif pos_y >= self._halve_size + self._left_bottom[1]:
216         return self._child_quads[0]
217     # Position is in the left bottom quad.
218     else:
219         return self._child_quads[1]
220
221 def _split(self):
222     """
223         Split the current quad in 4 child quads.
224     """
225
226     # Initialize the array that holds the child wuads.
227     self._child_quads = list()
228
229     # Left bottom coordinates of child quads
230     # lt = left top, lb = left bottom, rt = right top, rb = right bottom.
231     lt = [self._left_bottom[0],

```

```

232         self._left_bottom[1] + self._halve_size]
233 lb = self._left_bottom
234 rt = [self._left_bottom[0] + self._halve_size ,
235       self._left_bottom[1] + self._halve_size]
236 rb = [self._left_bottom[0] + self._halve_size ,
237       self._left_bottom[1]]
238
239 # Add the quads
240 self._child_quads.append(Quad(lt , self._halve_size ,
241                               self._max_boddies , self))
242 self._child_quads.append(Quad(lb , self._halve_size ,
243                               self._max_boddies , self))
244 self._child_quads.append(Quad(rt , self._halve_size ,
245                               self._max_boddies , self))
246 self._child_quads.append(Quad(rb , self._halve_size ,
247                               self._max_boddies , self))
248
249 # Current quad is not a leaf anymore
250 self._leaf = False
251
252 # Add the boddies of the current quad to the new child quads.
253 for boddy in self._boddies:
254     self.add_boddy(boddy)
255
256 # Empty the boddies that where hold by t his quad.
257 self._boddies = None
258
259 def _update_moment(self , mass = 0):
260     """
261     Update the multipole moment of the current quad
262     In:
263     param: mass — The mass to update the multipole moment with if the
264                current quad is a leaf.
265     """
266
267     # Current quad is a leaf , thus
268     # add the mass (zeroth order multipole moment)
269     if self._leaf:
270         self._moment += mass
271     # Current quad is not a leaf.
272     else:
273         # Reset the multipole moment and recalculate
274         # it by looping of the child quads.
275         self._moment = 0
276
277         for quad in self._child_quads:
278             self._moment += quad._moment
279
280     # Make sure the parents of the current quad update the multipole moment.
281     if self._parent != None:
282         self._parent._update_moment()
283
284
285 def _plot(self , axis , quads):
286     """
287     Plot the current quad.
288     In:
289     param: axis — The axis object to plot this quad at.
290     param: quads — A list of quads at which the current
291                   quad should add a rectangle which represents
292                   the current quad.
293     """
294
295     # Create the rectangle to plot of the current quad and add it to the list
296     rect = patches.Rectangle(self._left_bottom , self._size ,
297                              self._size , fill=False)
298     quads.append(rect)
299
300     # If the current quad is a leaf plot the boddies.
301     if self._leaf:
302         if len(self._boddies) == 0:

```

```

303         return
304         a = np.array(self._boddies)
305         axis.scatter(a[:,0],a[:,1],c='blue',s=1)
306         # If the current quad is not a leaf recursively call this
307         # method for all its 4 child quads.
308         else:
309             for quad in self._child_quads:
310                 quad._plot(axis, quads)

```

./Code/mathlib/quadtree.py

Output - Text

The text output produced by the code. This consists of the multipole moments of the leaf containing the particle with index 100 and its parents. The first line is thus the multipole moment of the leaf containing the particle with index 100 and the last line is the multipole moment of the root.

```

1 0.12500000186264515
2 0.21250000316649675
3 0.28750000428408384
4 7.162500106729567
5 7.162500106729567
6 15.000000223517418

```

./Output/assignment7.out.txt

Output - Plot

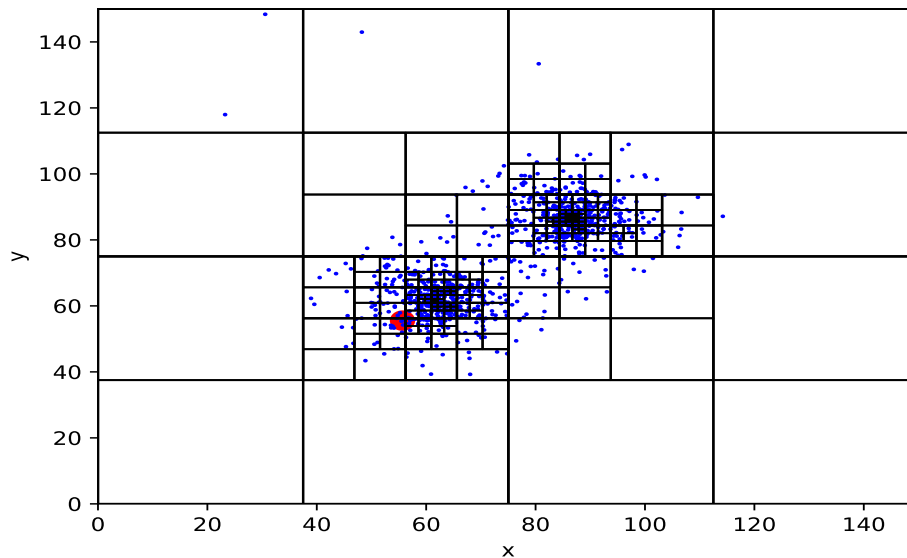


Figure 46: A visual representation of the constructed quadtree. The blue points indicate the positions of the bodies added to the tree. The red point indicates the position of the body with index 100.