Numerical Recipes for Astrophysics Solutions hand-in Assignment-2

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Abstract

The current document contains the solutions for the second hand-in assignment of Numerical Recipes. The main questions, 1, 2, 3 ..., 7, are in this document all given their own section. Each section contains a subsection for its related sub-questions (1.a, 1.b, 1.c, ..., 1.e) and ends with a final subsection that contains two segments of code. The first segment contains the code of the main question. The second segment contains the code of shared modules used by the sub-questions. A sub-question itself always starts with a short summary of the question that needs to be answered. The summary is followed by an explanation of how the problem is solved and the code that provides the solution. If necessary some of the results are discussed here. The output of the code is always presented after the code and plots are discussed in their caption.

1 - Normally distributed pseudo-random numbers

Question 1.a

Problem

Write a random number generator that returns a random floating-point number between 0 and 1. At minimum, use some combination of an MWC and a 64-bit XOR-shift. Plot a sequential of random numbers against each other in a scatter plot $(x_{i+1} \text{ vs } x_i)$ for the first 1000 numbers generated. Also plot the value of the random numbers for the first 1000 numbers vs the index of the random number, this mean the x-axis has a value from 0 through 999 and the y-axis 0 through 1). Finally, have your code generate 1,000,000 random numbers and plot the result of binning these in 20 bins 0.05 wide.

Solution

The state of the random number generator (RNG) is updated by first performing a 64-bit XOR-shift on the current state. Next, a modified version of the 64-bit XOR-shift output is given to the MWC algorithm. The modified XOR-shifts output that is given to the MWC algorithm is the output of the 64 XOR-shift with the last 32 bits put to zero. This is done by performing the 'AND' operation with the maximum value of an unsigned int32. This modification was performed as the MWC algorithm expects as input a 64-bit unsigned integer with a value between $0 < x < 2^{32}$. The output of the MWC is finally XORd with the unmodified output of the 64-bit XOR-shift. The result is set as the new state of the RNG.

The first 32 bits of the new state are used to provide a random value, as the output of the MWC algorithm only contains 32 significant bits. This random value is obtained by performing the 'AND' operation between the seed and the maximum value of an unsigned int32. The resulting value is then divided by the maximum value of an unsigned int32 to obtain a value between 0 and 1.

The code for the random number generator can be found at the end of this section, as it is treated as a shared module (see page 19). The code for generating the plots and the created plots can be found below. The code does not only print the random seed, but also prints the maximum and minimum number of counts for the binned 1,000,000 values. These values are referred to in the description of the plot that displayed the uniformness (figure 2).

Code - Plots

The code for generating the plots. The used imports and the initialization of the random number generator are not explicit shown in this piece of code, but can be found on page 19. The code for the random number generator can, as mentioned before, be found on page 19.

```
,, ,, ,,
             Execute assigment 1.a
        Int:
            param: random -- An initialization of the random number generator.
       # The relevant imports for this piece of code are:
       # (1) matplotlib.pyplot as plt
       # (2) mathlib.random as random
       # (3) mathlib.stats as ml_stats
11
       \# (3) numpy as np
12
13
       # Print the seed.
        print('[1.a] Initial seed: ', random.get_seed())
16
       # Generate 1000 numbers.
       numbers_1000 = random.gen_uniforms(1000)
18
19
       # Plot them agianst each other.
20
21
        {\tt plt.scatter\,(\,numbers\_1000\,[\,0:9\,9\,9\,]\,\,,\,\,\,numbers\_1000\,[\,1:]\,\,,\,\,\,s\!=\!2)}
       plt.ylabel(r'Probability $x_{i+1}$')
plt.xlabel(r'Probability $x_{i}$')
22
23
        plt.savefig('./Plots/1_plot_against.pdf')
24
        plt.figure()
25
26
       # Plot them against the index.
27
        plt.plot(range(0, 1000), numbers_1000)
28
       plt.ylabel('Probability p')
plt.xlabel('Index')
29
30
        plt.savefig('./Plots/1-plot_index.pdf')
31
32
        plt.figure()
33
       # Create a histogram for 1e6 points with 20 bins of 0.05 wide.
34
        numbers_mil = random.gen_uniforms(int(1e6))
35
        plt.hist(numbers_mil, bins=20, range=(0,1), color='orange',edgecolor='black')
36
        plt.ylabel('Counts')
plt.xlabel('Generate values')
37
38
        plt.savefig('./Plots/1_hist_uniformnes.pdf')
39
        plt.figure()
40
41
       # Extra, to print the smallest and lagest bin value.
42
       counts , _ = np.histogram(numbers_mil , bins=20)
print('[1.a] Max counts: ', max(counts))
print('[1.a] Min counts: ', min(counts))
43
44
```

./Code/assigment_1.py

Code - Output text

The text output produced by the code. The first value is the initial seed of the RNG. The second and third value are the maximum and minimum amount of counts for the histogram displaying the uniformness.

```
[1.a] Initial seed: 78379522
[1.a] Max counts: 50343
[1.a] Min counts: 49557
```

./Output/assigment1_out.txt

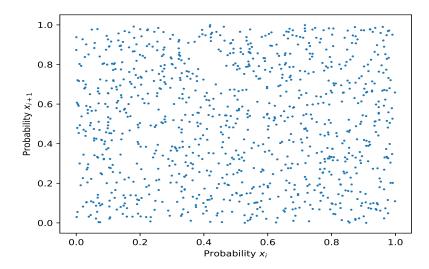


Figure 1: A plot of random number x_{i+1} against random number x_i for the first 1000 random uniforms produced by the random number generator. A good random number generator should produce a homogeneous plot without many (large) empty spots. The largest empty spot in the above plot is at $x_i = 0.4$ and $x_{i+1} = 0.8$. The spot is not significant large, but might point towards an impurity in the RNG.

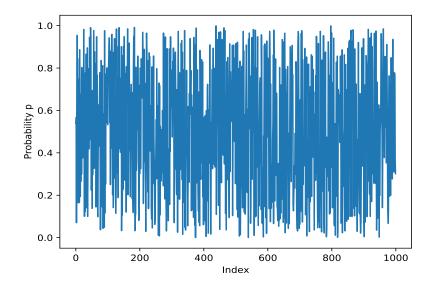


Figure 2: The first 1000 random uniform numbers produced by the random number generator (RNG) against their index. A good random number generator should not have large wide gaps (e.g when moving from index 400 to 450 it should not only produce values larger than 0.8, which would leave a wide gap). In the plot small gaps appear, see for example index ~ 420 at a probability of p=0.6. The number of gaps and the width of the gaps do not appear to be significant. This might therefore either be the result of being unlucky, or could point towards an impurity in the RNG. The average value produced by the RNG should furthermore be 0.5. This corresponds to rapidly moving up and down around the horizontal line corresponding with a probability of p=0.5. In the plot this should, result in a 'dense' region (less white) around the line p=0.5. It can indeed be seen that the plot is denser around the line p=0.5 than at p=0.8 or p=0.2.

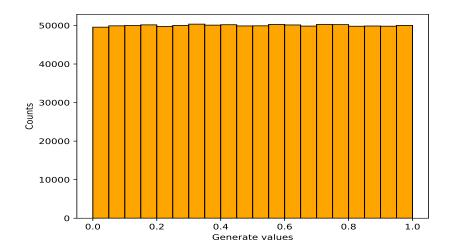


Figure 3: The uniforms of the random number generator for 1 million random values. The values are binned in 20 bins. A good random number generator should fluctuate around $50000 \pm 2\sqrt{50000} = 50000 \pm 447$ counts per bin (2 sigma). The maximum and minimum amount of counts corresponds to 50343 and 49557 counts. These values just lay withing the 2 sigma uncertainty. The uniformness of the random number generator therefore appears to be acceptable.

Question 1.b)

Problem

Now use the Box-Muller method to generate 1000 normally-distributed random numbers. To check if they are following the expected Gaussian distribution, make a histogram (scaled appropriate) with the corresponding true probability distribution (normalized to integrate to 1) as line. This plot should contain the interval of -5σ until 5σ from the theoretical probability distribution. Indicate the theoretical 1σ , 2σ , 3σ and 4σ interval with a line. For this plot, use $\mu = 3$ and $\sigma = 2.4$ and choose bins that are appropriate.

Solution

The solution consists of deriving the transformation of two i.i.d uniform variables to two i.i.d normal distributed variables with the Box-Muller method. A brief version of the derivation can be found below. The final transformation, equation 9, is implemented in the random number generator and used to generate the plot. The final histogram is created with 20 bins and can be found on page 6.

Let $X, Y \sim G(\mu, \sigma^2)$ be two i.i.d Gaussian distributed random variables. Their joined CDF is then given by,

$$P(X \le x_1, Y \le y_1) = \int_{-\infty}^{x_1} \int_{-\infty}^{y_1} G(x|\mu, \sigma^2) G(y|\mu, \sigma^2) dx dy$$
 (1)

Transforming to polar coordinates by substituting $(x-\mu) = r\cos(\theta)$ and $(y-\mu) = r\sin(\theta)$ yields,

$$P(R \le r_1, \Theta \le \theta_1) = \int_0^{r_1} \int_0^{\theta_1} G(r\cos(\theta)\sigma + \mu|\mu, \sigma^2) G(r\sin(\theta)\sigma + \mu|\mu, \sigma^2) r dr d\theta$$

$$= \frac{1}{2\pi\sigma^2} \int_0^{r_1} \int_0^{\theta_1} r e^{-\frac{1}{2} \left[\left(\frac{r\cos(\theta)}{\sigma} \right)^2 + \left(\frac{r\sin(\theta)}{\sigma} \right)^2 \right]} dr d\theta$$

$$= \frac{1}{2\pi\sigma^2} \int_0^{r_1} \int_0^{\theta_1} r e^{-\frac{r^2}{2\sigma^2}} dr d\theta$$

The CDF's for the polar coordinates are now given by,

$$P(R \le r_1) = \frac{1}{\sigma^2} \int_0^{r_1} r e^{-\frac{r^2}{2\sigma^2}} dr = \int_0^{r_1} \frac{d}{dr} \left(-e^{-\frac{r^2}{2\sigma^2}} \right) dr = 1 - e^{-\frac{r_1^2}{2\sigma^2}}$$
(2)

$$P(\Theta \le \theta_1) = \frac{1}{2\pi} \left[-e^{-\frac{r^2}{2\sigma^2}} \right]_0^\infty \int_0^{\theta_1} d\theta = \frac{\theta_1}{2\pi}$$
 (3)

The CDFs can be used to convert two uniform distributed variables to the polar coordinates of the Gaussian distributed variables. Let $U_1, U_2 \sim U(0, 1)$ be two i.i.d uniform variables. From the transformation law of probability we then must have that,

$$P(R \le r_1) = P(U_1 \le u_1) \to 1 - e^{-\frac{r_1^2}{2\sigma^2}} = \int_0^{u_1} du_1 = u_1 \tag{4}$$

$$P(\Theta \le \theta) = P(U_2 \le u_2) \to \frac{\theta_1}{2\pi} = \int_0^{u_2} du_2 = u_2$$
 (5)

The transformation from the two uniform distributed variables to the polar coordinates of the Gaussian distributed variables then becomes,

$$r_1 = \sqrt{-2\sigma^2 \ln(1 - u_1)} \tag{6}$$

$$\theta_1 = 2\pi u_2 \tag{7}$$

Converting back to Cartesian coordinates yields the transformation from two i.i.d uniform distributed variables to two i.i.d Gaussian distributed variables;

$$x_1 = r\cos(\theta) + \mu = \sqrt{-2\sigma^2 \ln(1 - u_1)}\cos(2\pi u_2) + \mu$$
 (8)

$$y_1 = r\sin(\theta) + \mu = \sqrt{-2\sigma^2 \ln(1 - u_1)} \sin(2\pi u_2) + \mu \tag{9}$$

These above transformation are implemented in the random number generator (see page 19). The code for the generation of the plot and the created plot can be found below. The code that generates the plot makes besides the RNG use of a function for the normal distribution in the file ./Code/mathlib/statistics.py. This file is treated as a shared module and can be found on page 22. The called function, normal, can be found on line 227 in this file.

Code - Plots

The code for generating the plots. The imports are again not explicit shown, but can be found on page 19. The shared modules can be found on pages 19 and 22.

```
def assigment_1b(random):
    """

Execute assigment 1.b

Int:
    param: random — An instance of the random number generator.
    """

# The relevant imports for this piece of code are:

# (1) matplotlib.pyplot as plt
# (2) mathlib.random as random
# (3) mathlib.stats as ml_stats
# (4) numpy as np

# Sigma and mean for the distribution.
mean = 3.0
sigma = 2.4

# Generate 1000 random normal variables for the given mean and sigma.
```

```
samples = random.gen_normals(mean, sigma, 1000)
21
22
       # The true normal distribution for the given mean and sigma.
        gaussian_x = np.linspace(-sigma*4 + mean, sigma*4 + mean, 1000)
23
        gaussian_y = ml_stats.normal(gaussian_x, mean, sigma)
25
26
       # Create a histogram.
        plt.hist(samples, bins=20, density=True, edgecolor='black',
27
        facecolor='orange', zorder=0.1, label='Sampled')
plt.plot(gaussian_x, gaussian_y, c='red', label='Normal')
28
29
        plt.xlim(-sigma*6.5 + mean, sigma*6.5 + mean)
30
        plt.ylim(0, max(gaussian_y)*1.2)
31
32
       # Add the sigma lines.
33
34
       # The hight of the sigma lines that need to be added.
35
        lines_height = max(gaussian_y)*1.2
36
37
38
        for i in range (1, 6):
            # Absolute shift from the mean for the given sigma
39
             shift = i*sigma
40
41
            # Sigma right of the mean.
42
             plt.vlines(mean + shift, 0, lines_height,
linestyles='-', color='black', zorder=0.0)
plt.text(mean + shift -0.4, lines_height/1.2, str(i) + r'$\sigma$',
43
44
45
                       color='black', backgroundcolor='white', fontsize=9)
46
47
            # Sigma line left of the mean.
48
             plt.vlines(mean - shift, 0, lines_height, linestyles='-', zorder=0.0) plt.text(mean - shift -0.4, lines_height/1.2, str(i) + r'\\sigma\$',
49
50
                                      color='black', backgroundcolor='white', fontsize=9)
        plt.legend(framealpha=1.0)
53
        plt.savefig('./Plots/1_hist_gaussian.pdf')
        plt.figure()
```

./Code/assigment_1.py

Code - Output plot(s)

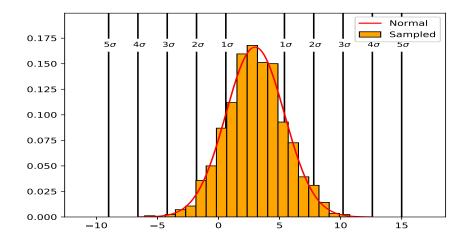


Figure 4: A histogram of the 1000 random normal distributed variables generated with the box muller method for $\mu=3$ and $\sigma=2.4$ (orange). The red line is the true normal distribution. The histogram appears to approximate the distribution quite well, but displays small deviations. The bin left of the peak (the highest bin) is larger than it should be. The first bins right of the peak is smaller than it should be and the second bin right of the peak is to high. The histogram does however still appear to be acceptable by eye. A statistical test is of course better to determine whether the histogram would truly be acceptable or not.

Question 1.c)

Problem

Write a code that can do the KS-test on the your function to determine if it is consistent with a normal distribution. For this, use $\mu=0$ and $\sigma=1$. Make a plot of the probability that your Gaussian random number generator is consistent with Gaussian distributed random numbers, start with 10 random numbers and use in your plot a spacing of 0.1 dex until you have calculated it for 10^5 random numbers on the x-axis. Compare your algorithm with the KS-test function from scipy, scipy.stats.kstest by making an other plot with the result from your KS-test and the KS-test from scipy.

Solution

The implementation of the KS-test is in general straight forwards. There are however two points of interest that needs to be discussed. The first point is the implementation of the CDF for the KS-statistic and the second point is the implementation of the CDF for the normal distribution.

(1) CDF KS-statistic

The p-value produced by the KS-tests requires the evaluation of the CDF for the KS-test statistic,

$$P_{KS}(z) = \frac{2\sqrt{\pi}}{z} \sum_{j=1}^{\infty} \exp\left(-\frac{(2j-1)^2 + \pi^2}{8z^2}\right)$$
 (10)

This infinite sum needs to be numerically approximated in order to perform the KS-test. The chosen approximation for the above equation is taken from the book *Numerical Recipes - The art of Scientific Computation*, 3d edition,

$$P_{KS}(z) \approx \begin{cases} \frac{\sqrt{2\pi}}{z} \left[\left(e^{-\pi^2/(8z^2)} \right) + 9 + \left(e^{-\pi^2/(8z^2)} \right) \left(e^{-\pi^2/(8z^2)} \right)^{25} \right] & \text{for } z < 1.18 \\ 1 - 2 \left[\left(e^{-2z^2} \right) - \left(e^{-2z^2} \right)^4 + \left(e^{-2z^2} \right)^9 \right] & \text{for } z >= 1.18 \end{cases}$$

$$(11)$$

(2) CDF normal distribution

The CDF of the normal distribution is needed in order to perform the KS-test under the null hypothesis that the data follows a normal distribution. The CDF of the normal distribution can in general be written as,

$$\Phi\left(\frac{x-\mu}{\sigma}\right) = \frac{1}{2} \left[1 + \operatorname{erf}\left(\frac{x-\mu}{\sigma\sqrt{2}}\right) \right] \tag{12}$$

where the erf is given by,

$$\operatorname{erf}(x)\frac{2}{\sqrt{\pi}}\int_0^x e^{-t^2}dt\tag{13}$$

The integral of the erf function lacks a closed form and therefore needs to be numerically approximated. The chosen approximation is taken from *Abramowitz and Stegun*,

$$\operatorname{erf}(x) \approx 1 - (a_1 t + a_2 t^2 + \dots + a_5 t^5) e^{-x^2} \mathbf{x} \quad t = \frac{1}{1 + px}$$
 (14)

where, p = 0.3275911, $a_1 = 0.254829592$, $a_2 = -0.284496736$, $a_3 = 1.421413741$, $a_4 = -1.453152027$, $a_5 = 1.061405429$.

The KS-test and the CDF are implemented with these approximations. The code for the KS-test and the CDF is located in the file ./Code/mathlib/statistics.py at page 22, as this file is threaded as a shared module. The KS-test does require an sorting algorithm, this algorithm is implemented in the file ./Code/matlib/sorting and can be found on page 26. The code for the generation of the plots and plots are displayed below.

Code - Plots

The code for generating the two plots. The imports for this file are not explicit shown, but can be found on page 19.

```
assigment_1c(random):
            Execute assignment 1.c
           \operatorname{param}: \operatorname{random} — An initialization of the random number generator.
       # The relevant imports for this piece of code are:
       # (1) matplotlib.pyplot as plt
       # (2) numpy as np
11
       # (3) astropy.stats
       # (4) mathlib.statistics as ml_stats
12
       # The values to plot point for.
14
       plot_values = np.array(10**np.arange(1, 5.1, 0.1), dtype=int)
16
       # An array in which the p-values are stored for the self created.
       # ks-test and the scipy version.
18
       p_values_self = np.zeros(len(plot_values))
       p_values_scipy = np.zeros(len(plot_values))
20
21
       # Generate the maximum amount of needed random numbers.
22
       random_numbers = random.gen_normals(0, 1, int(1e5))
23
24
25
       # Calculate the p-values with the ks-test.
       for idx, values in enumerate(plot_values):
26
27
           # Calculate the value with scipy.
28
            p\_values\_scipy[idx] = sp\_stats.kstest(random\_numbers[0:values],
29
                                                        'norm')[1]
30
           # Calculate the p-values with the own implementation.
31
            p_values_self[idx] = ml_stats.kstest(random_numbers[0:values],
32
                                                      ml_stats.normal_cdf)
33
34
35
       # Plot the probabilities for only my own implementation.
36
       plt.plot(plot_values, p_values_self, label = 'self', color='orange')
plt.hlines(0.05,0,10**5,colors='red',linestyles='--')
37
38
       plt.xscale('log')
39
       plt.xlabel(r'Log($N_{samples}$)')
plt.ylabel('Probabillity (p-value)')
40
41
       plt.legend()
42
       plt.savefig('./Plots/1_plot_ks_test_self.pdf')
43
44
       plt.figure()
45
       \# Plot the probabilities for both the scipy and my own implemntation.
46
47
       plt.plot(plot_values, p_values_scipy, label='scipy', linestyle=':',
                                                                   zorder = 1.1)
48
       plt.plot(plot_values, p_values_self, label='self', zorder=1.0,
49
                                                                   color='orange')
50
       plt.hlines(0.05,0,10**5,colors='red',linestyles='--
51
       plt.xscale('log')
52
       plt.xlabel(r'Log($N_{samples}$)')
plt.ylabel('Probabillity (p-value)')
54
       plt.legend()
       plt.savefig('./Plots/1_plot_ks_test_self_scipy.pdf')
       plt.figure()
```

./Code/assigment_1.py

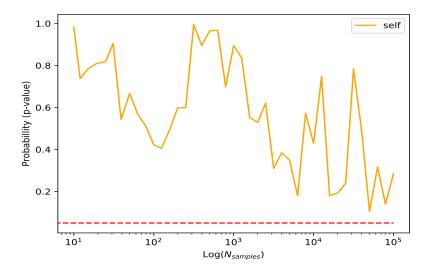


Figure 5: The P-value produced by the KS-test against the number of samples on which the KS-test is performed for the self written RNG. The red line indicates the line of p = 0.05. A point **below** the line would suggests that there is enough statistical evidence to reject the (null) hypothesis that the data is normal distributed. The plot shows that the RNG always passes KS-test up to atleast 10^5 samples. The p-value does however appear to drop for a large number of samples and might even drop further when more samples are used. The drop suggests again that the RNG is likely not perfect.

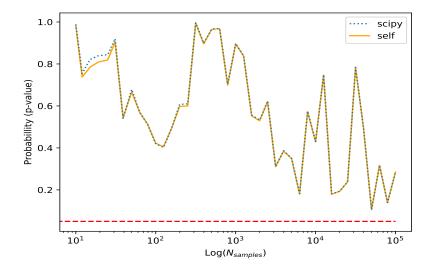


Figure 6: The P-value produced by the KS-test against the number of samples on which the KS-test is performed for the self written RNG. The red line indicates the line of p=0.05. The orange line is the self written implementation of the KS-test and the blue line is the scipy version. A point **below** the red line would suggests that there is enough statistical evidence to reject the (null) hypothesis that the data is normal distributed. The self written KS-test is close to the scipy version, but shows (small) deviations at small sample sizes (see $N_{samples} = 10$ or $N_{samples} = 200$). The self written implementation always has the same shape as the scipy version, even at the deviations. The exact cause for the deviations are unknown, but are likely the result of an approximation that scipy makes that the self written implementation doesn't make.

Question 1.d)

Problem

Write a code that does the Kuiper's test on your random numbers (see tutorial 8) and make the same plot as for the KS-test.

Solution

The implementation of the Kuiper test does require a numerical approximation of the CDF for the kuiper statistics. The CDF of the kuiper staistic is given by,

$$P_{kuiper}(\lambda) = 1 - 2\sum_{j=1}^{\infty} (4j^2\lambda^2 - 1)e^{-2j^2\lambda^2}$$
(15)

The sum is in the above expression negligible compared to the machine error if $\lambda < 0.4$. In this case the numerically approximation thus consist of returning 1. If $\lambda > 0.4$ then the sum is approximated by calculating the first 100 terms of the sum. This should be more than enough for the sum to converge. ¹

The Kuiper-test and the CDF are implemented in the shared module ./Code/mathlib/statistics.py that can be found on page 22. The code that creates the plots and the plots can be found below. The code does make use of **astropy** to compare the self written implementation of the Kuiper-test with the implementation of astropy.

Code - Plots

The code for generating the two plots. The imports are not explicit shown but can be shown on page 19.

```
def assigment_ld(random):
          Execute assigment 1.d
      Int:
          param: random -- An initialization of the random number generator.
      # The relevant imports for this piece of code are:
      # (1) matplotlib.pyplot as plt
      # (2) numpy as np
      # (3) scipy.stats as sp_stats
12
      # (4) mathlib.statistics as ml_stats
13
      # The values to plot point for.
14
      plot_values = np.array(10**np.arange(1, 5.1, 0.1), dtype=int)
15
16
      # Generate the maximum amount of needed random numbers.
      random_numbers = random.gen_normals(0, 1, int(1e5))
18
19
      # An array in which the p-values are stored for the self created
20
      # kuiper-test and the astropy version.
      p_values_self = np.zeros(len(plot_values))
22
23
      p_values_astropy = np.zeros(len(plot_values))
24
      # Calculate the p-values with the ks-test
25
      for idx, values in enumerate(plot_values):
26
27
          # Calculate the value with the own implemnetation
28
          p_values_self[idx] = ml_stats.kuiper_test(random_numbers[0:values],
29
      ml_stats.normal_cdf)
30
          # Calculare the value with astropy.
          p_values_astropy[idx] = astropy.stats.kuiper(random_numbers[0:values],
31
                                                          ml_stats.normal_cdf)[1]
```

Actually, less terms are enough. The evaluation of the sum could therefore stop early by checking for a required precision.

```
# Plot the probabilities for only my own implementation
34
        plt.plot(plot_values, p_values_self, label = 'self')
plt.hlines(0.05,0,10**5,colors='red',linestyles='--')
35
36
         plt.xscale('log')
37
        plt.xlabel(r'Log($N_{samples}$)')
plt.ylabel('Probabillity (p-value)')
38
39
         plt.legend()
40
         plt.savefig('./Plots/1-plot_kuiper_test_self.pdf')
41
42
         plt.figure()
43
        # Plot the probabiliteis with both the own implementation and astropy
44
        plt.plot(plot_values, p_values_astropy, label='astropy', linestyle=':',
45
        zorder = 1.1)
        plt.plot(plot_values, p_values_self, label='self',zorder=1.0) plt.hlines(0.05,0,10**5,colors='red',linestyles='--')
46
47
         plt.xscale('log')
48
49
        plt.xlabel(r'Log($N_{samples}$)')
plt.ylabel('Probabillity (p-value)')
50
51
         plt.legend()
52
         plt.savefig(
                         './Plots/1_plot_kuiper_test_self_astropy.pdf')
         plt.figure()
```

./Code/assigment_1.py

Code - Output plot(s)

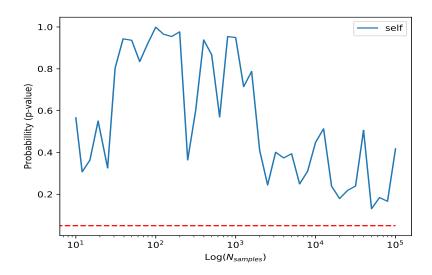


Figure 7: The P-value produced by the Kuiper-test against the number of samples on which the kuiper-test is performed for the self written RNG. The red line indicates the line of p=0.05. A point **below** there line would suggests that there is enough statistical evidence to reject the (null) hypothesis that the data is normal distributed. The plot shows that the RNG always passes Kuiper test. It can however be seen that the p-value drops for larger sample size, similar as what happens by the KS-test. This might, as mentioned before, indicate that there is an flaw in the random number generator.

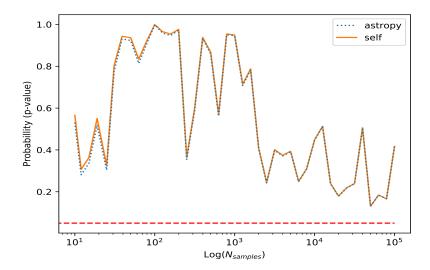


Figure 8: The P-value produced by the kuiper test against the number of samples on which the kuiper-test is performed for the self written RNG. The red line indicates the line of p = 0.05. A point **below** there line would suggests that there is enough statistical evidence to reject the (null) hypothesis that the data is normal distributed. The plot shows that the self written implementation has (small) deviations from the astropy implementation at small sample sizes. This is similar to the situation with the KS-test and might be caused by an approximation made in astropy.

Question 1.e)

Problem

Download the dataset. The dataset contains 10 sets of random numbers. Compare these 10 sets with your Gaussian pseudo random numbers and make the plot of the probabilities as in either of the previous two exercises (your choice). Which random number arrays is/are consistent with a Gaussian random numbers with $\sigma=1$ and $\mu=0$

Solution

The distributions are compared by performing the KS-test 2 (2 sample distributions). The KS-test 2 has to be applied to 10 columns. The random numbers that are compared with the column data are as result only generated once (i.e each column is compared with the same random numbers). This was done to save computation time. The code that contains the implementation of the ks-test 2 can be found on page 22. The code that generates the plots and the generated plots can be found below.

The plots show that there is only one column which might be² a normal distribution with $\sigma=1$ and $\mu=0$. This is column 4 (index 3, see figure 12 on page 15). In all other plots the p-value drops and stays below p=0.05 when including all samples, which indicates that their is enough statistical evidence to reject the hypothesis that they follow a normal distribution with $\sigma=1$ and $\mu=0$.

²A p-value only shows statistical evidence against the null hypothesis, it isn't a measure of how good the null hypothesis is.

Code - Plots

The code for generating the 10 plots.

```
assigment_le(random):
           Execute assigment 1.e
          # The relevant imports for this piece of code are:
      # (1) matplotlib.pyplot as plt
      # (2) numpy as np
      # (3) scipy.stats as sp_stats
12
      # (4) mathlib.statistics as ml_stats
13
14
      # Load the data.
      data = np.loadtxt('randomnumbers.txt')
15
16
      # Generate the maximum amount of needed random numbers.
17
      random_numbers = random.gen_normals(0, 1, int(1e5))
18
      # The values to plot point for.
20
      plot_values = np.array(10**np.arange(1, 5.1, 0.1), dtype=int)
21
22
      # Pre-sort the random numbers
23
      random_nums_sorted = list()
24
25
      for idx, values in enumerate(plot_values):
26
           random\_nums\_sorted.append (sorting.merge\_sort (random\_numbers [0:values]))
27
28
29
      # Go over the columns and perform the KS-test2
30
31
       for i in range (data.shape [1]):
33
          # An array in which the p-values are stored for the self created
           # ks-test2 and the scipy version.
34
           p_values_self = np.zeros(len(plot_values))
35
36
           # Calculate the p-values with the ks-test2
37
           for idx, values in enumerate(plot_values):
38
39
               # Perform the ks-test2 with the own implementation.
40
               p_values_self[idx] = ml_stats.kstest2(data[:,i][0:values],
41
                                                        random_numbers [0: values],
42
                                                        random_nums_sorted[idx])
43
44
           # Plot the p-values.
45
           plt.plot(plot_values, p_values_self, label = 'self',color = 'orange') plt.hlines(0.05,0,10**5,colors='red',linestyles='---')
46
47
48
           plt.xlabel(r'Log(\$N_{-}\{samples\}\$)')
49
           plt.ylabel('Probabillity (p-value)')
plt.xscale('log')
50
51
52
           plt.legend()
           plt.savefig("./Plots/1e_plot_column_{0}.pdf".format(i))
53
           plt.figure()
```

./Code/assigment_1.py

Code - Output plot(s)

Note: Expect very similar captions for the upcoming 10 plots.

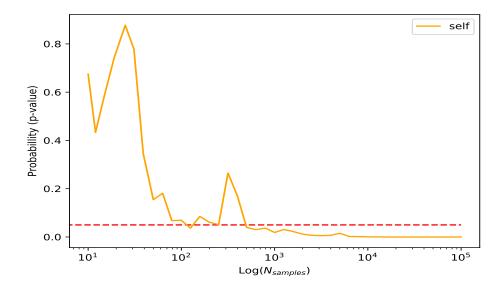


Figure 9: The P-value produced by performing the KS-test2 for a normal distribution with $\mu=0$ and $\sigma=1$ on the first column. The red line indicates the line of p=0.05. A point **below** there line would suggests that there is enough statistical evidence to reject the (null) hypothesis that the data is normal distributed. The plot shows that the p-value drops below 0.05 when including all samples. There is thus enough statistical evidence to reject the hypothesis that this column is normal distributed with $\mu=0$ and $\sigma=1$.

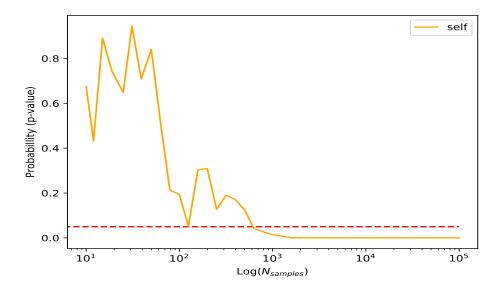


Figure 10: The P-value produced by performing the KS-test2 for a normal distribution with $\mu=0$ and $\sigma=1$ on the **second** column. The red line indicates the line of p=0.05. A point **below** there line would suggests that there is enough statistical evidence to reject the (null) hypothesis that the data is normal distributed. The plot shows that the p-value drops below 0.05 when including all samples. There is thus enough statistical evidence to **reject** the hypothesis that this column is normal distributed with $\mu=0$ and $\sigma=1$.

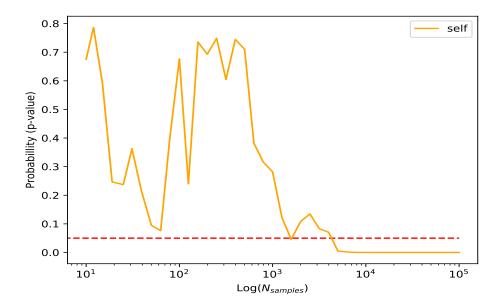


Figure 11: The P-value produced by performing the KS-test2 for a normal distribution with $\mu=0$ and $\sigma=1$ on the **third** column. The red line indicates the line of p=0.05. A point **below** there line would suggests that there is enough statistical evidence to reject the (null) hypothesis that the data is normal distributed. The plot shows that the p-value drops below 0.05 when including all samples. There is thus enough statistical evidence to **reject** the hypothesis that this column is normal distributed with $\mu=0$ and $\sigma=1$.

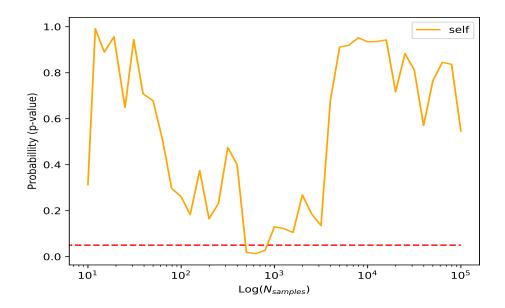


Figure 12: The P-value produced by performing the KS-test2 for a normal distribution with $\mu=0$ and $\sigma=1$ on the **fourth** column. The red line indicates the line of p=0.05. A point **below** there line would suggests that there is enough statistical evidence to **reject** the (null) hypothesis that the data is normal distributed. The plot shows that the p-value drops below 0.05 only between 500-1000 samples. In all other cases it passes the KS-test. The most important point in this plot is the p-value when all samples are included. It can be clearly seen that this point isn't below the red line. The plot therefore suggests that the given c olumn might (see footnote 2 on page 12) be a Gaussian with $\mu=0$ and $\sigma=1$.

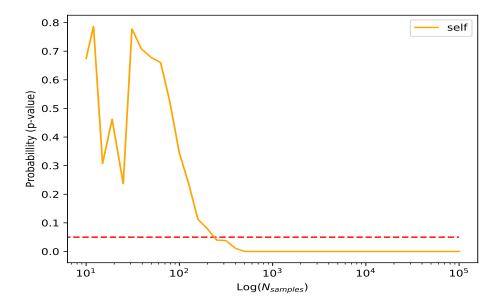


Figure 13: The P-value produced by performing the KS-test2 for a normal distribution with $\mu=0$ and $\sigma=1$ on the **fifth** column. The red line indicates the line of p=0.05. A point **below** there line would suggests that there is enough statistical evidence to reject the (null) hypothesis that the data is normal distributed. The plot shows that the p-value drops below 0.05 when including all samples. There is thus enough statistical evidence to reject the hypothesis that this column is normal distributed with $\mu=0$ and $\sigma=1$.

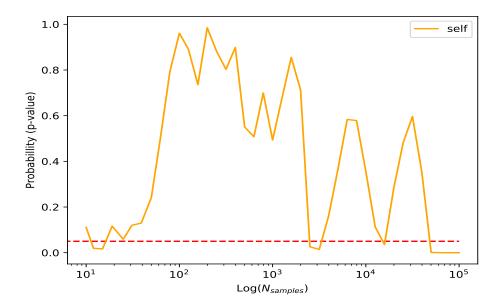


Figure 14: The P-value produced by performing the KS-test2 for a normal distribution with $\mu=0$ and $\sigma=1$ on the **sixth** column. The red line indicates the line of p=0.05. A point **below** there line would suggests that there is enough statistical evidence to reject the (null) hypothesis that the data is normal distributed. The plot shows that the p-value drops below 0.05 and stays there when including more than halve of the samples. The most important part of the figure is the part that includes most samples. There is thus enough statistical evidence to reject the hypothesis that this column is normal distributed with $\mu=0$ and $\sigma=1$.

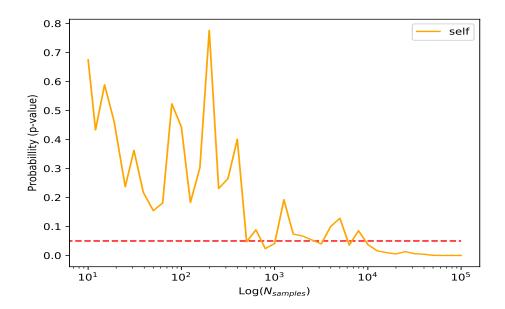


Figure 15: The P-value produced by performing the KS-test2 for a normal distribution with $\mu=0$ and $\sigma=1$ on the **seventh** column. The red line indicates the line of p=0.05. A point **below** there line would suggests that there is enough statistical evidence to reject the (null) hypothesis that the data is normal distributed. The plot shows that the p-value drops below 0.05 when including all samples. There is thus enough statistical evidence to reject the hypothesis that this column is normal distributed with $\mu=0$ and $\sigma=1$.

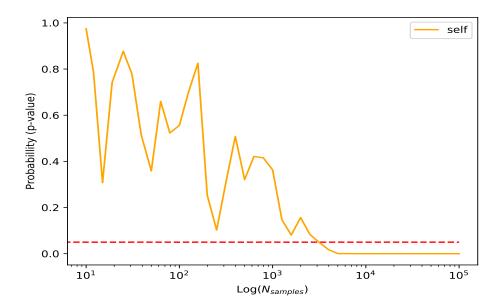


Figure 16: The P-value produced by performing the KS-test2 for a normal distribution with $\mu=0$ and $\sigma=1$ on the **eight** column. The red line indicates the line of p=0.05. A point **below** there line would suggests that there is enough statistical evidence to reject the (null) hypothesis that the data is normal distributed. The plot shows that the p-value drops below 0.05 when including all samples. There is thus enough statistical evidence to reject the hypothesis that this column is normal distributed with $\mu=0$ and $\sigma=1$.

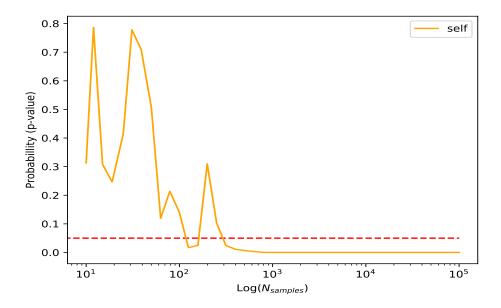


Figure 17: The P-value produced by performing the KS-test2 for a normal distribution with $\mu=0$ and $\sigma=1$ on the **ninth** column. The red line indicates the line of p=0.05. A point **below** there line would suggests that there is enough statistical evidence to reject the (null) hypothesis that the data is normal distributed. The plot shows that the p-value drops below 0.05 when including all samples. There is thus enough statistical evidence to reject the hypothesis that this column is normal distributed with $\mu=0$ and $\sigma=1$.

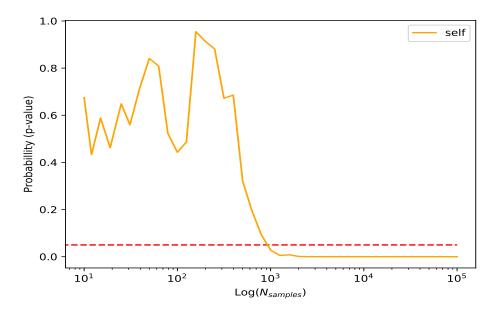


Figure 18: The P-value produced by performing the KS-test2 for a normal distribution with $\mu=0$ and $\sigma=1$ on the **tenth** column. The red line indicates the line of p=0.05. A point **below** there line would suggests that there is enough statistical evidence to reject the (null) hypothesis that the data is normal distributed. The plot shows that the p-value drops below 0.05 when including all samples. There is thus enough statistical evidence to reject the hypothesis that this column is normal distributed with $\mu=0$ and $\sigma=1$.

Question 1- Summary

Summary

The current sub-section contains the summary of the code used for assignment 1. This includes the file containing all sub-questions and all used shared modules.

Code - Assignment

The code of the file that executes the sub-questions. The code presented below only consists of the part that has not jet been shown in the subquestions. This part consists of the initialization of the random number generator (1.a) and the used imports.

```
import astropy.stats
  import matplotlib.pyplot as plt
  import mathlib.random as random
  import mathlib.sorting as sorting
  import mathlib.statistics as ml_stats
  import numpy as np
  import scipy.stats as sp_stats
  def main():
      # Initialize the random number generator.
      rng = random.Random(78379522)
      # Run assigments
13
      assigment_1a(rng)
      assigment_1b(rng)
15
      assigment_1c(rng)
      assigment_1d(rng)
      assigment_le(rng)
```

./Code/assigment_1.py

Code - Random Number Generator

The code for the random number generator.

```
import numpy as np
  class Random(object):
          A class representing a random number generator (RNG)
       def = init_{--}(self, seed):
               Create a new instance of the random number generator.
           In:
12
               param: seed -- The seed of the random number generator.
13
                              This must be a positive integer.
14
           ,, ,, ,,
16
17
           # The seed and state of the generator
18
           self.\_seed = np.uint64(seed)
           self._state = self._seed
20
21
           # maximum uint32 value
22
           self._uint32_max = np.uint64(0xFFFFFFFF)
23
           # The values for the Xor shift.
25
           self.\_xor\_a1 = np.uint64(20)
26
           self.\_xor\_a2 = np.uint64(41)
           self.\_xor\_a3 = np.uint64(5)
28
29
           # The values for the multiply with carry.
30
           self._mwc_a = np.uint64(4294957665)
```

```
self._mwc_base = np.uint64(2**32)
32
33
34
       def get_seed(self):
35
                Get the seed that is used to initialize this generator.
36
37
38
           return: The seed used to initalize the generatorr.
39
40
            return self._seed
41
42
43
       def get_state(self):
44
               Get the state of the generator.
45
46
           Out:
47
           return: The state of the generator. ""
48
49
           return self.state
50
51
53
       def gen_next_int(self):
54
                Generate a new random 32-bit unsigned integer.
56
57
              return: A random 32-bit unsigned integer.
58
59
           # The state is at the end updated with mwc.
60
61
           # We therefore shouldn't use more than 32 bits to generate
62
           # the number.
63
           return self._update_state() & self._uint32_max
64
65
       def gen_uniform(self):
66
67
                Generate a random float between 0 and 1.
68
69
           Out:
           return: A random float between 0 and 1. """
70
71
72
            return self.gen_next_int()*1.0 / self._uint32_max
73
74
       def gen_uniforms(self, amount):
75
76
77
                Generate multiple random floats
78
                between 0 and 1.
           In:
79
80
                param: amount -- The amount of floats to generate.
           Out:
81
                return: An array with 'amount' random floats
82
                        between 0 and 1.
83
           22 22 22
84
85
            samples = np.zeros(amount)
86
87
            for i in range (amount):
88
                samples[i] = self.gen_uniform()
89
90
91
            return samples
92
       def gen_normal(self, mean, sigma):
93
94
                Generate a random normal distributed float.
95
96
97
           In:
                param: mean — The mean of the gaussian distribution.
98
99
                param: sigma -- The squareroot of the variance of the distribution.
           Out:
100
                return: A random float that is drawn from the parameterized normal
101
                         distribution.
102
```

```
104
105
            # Generate two uniform variables.
            u1 = self.gen_uniform()
106
            u2 = self.gen_uniform()
108
            # Use the box muller transformation.
             \begin{array}{lll} \textbf{return} & \textbf{sigma*np.sqrt} \left( -2* & \textbf{np.log} \left( 1-\textbf{u1} \right) \right)*\textbf{np.cos} \left( 2*\textbf{np.pi*u2} \right) \ + \ \textbf{mean} \end{array} 
111
        def gen_normal_uniform(self, mean, sigma, u1, u2):
113
                 Generate a random normal distributed float from two provided
114
                 uniform variables.
116
118
            pre_factor = sigma*np.sqrt(-2*np.log(1-u1))
119
120
            return pre_factor*np.cos(2*np.pi*u2) + mean, pre_factor*np.sin(2*np.pi*u2
121
        def gen_normals(self, mean, sigma, amount):
123
124
                 Generate multible random normal distributed float.
126
            In:
                 param: mean -- The mean of the gaussian distribution.
128
129
                 param: sigma -- The squareroot of the variance of the distribution.
                 param: amount — The amount of floats to generate.
130
131
                 return: An array with random floats drawn from the parameterized
        normal
                           distribution.
133
134
135
            # Pre-factors in the box muller transformation.
136
            square\_pre\_factor = -2*sigma**2
             angle_pre_factor = 2*np.pi
138
139
            # With the Box-muller two random normals can be generated for two
140
141
            # uniforms. If the amount of requested variables is odd then add
            # one to it and later remove it when returning the result.
142
            elements = amount if amount % 2 == 0 else amount + 1
143
144
            # Array in which the drawn normal distributed variables are stored.
145
            normal_dist = np.zeros(elements)
146
147
            # Apply the box muller transformation to generate the samples.
148
             for i in range (0, elements, 2):
149
150
                 # Generate the uniforms.
                 u1 = self.gen\_uniform()
                 u2 = self.gen_uniform()
154
                 # Calculate common terms.
                 pre_fact = np.sqrt(square_pre_factor*np.log(1-u1))
156
                 # Calculate the samples.
158
                 normal\_dist\left[\:i\:\right] \: = \: pre\_fact*np.\cos\left(\:angle\_pre\_factor*u2\right) \: + \: mean
                 normal\_dist[i+1] = pre\_fact*np.sin(angle\_pre\_factor*u2) + mean
160
161
            \# If amount is odd, don't return the last element.
162
            return normal_dist[0:amount]
163
164
        def _update_state(self):
166
                 Update the state of the random number generator.
167
168
            Out:
169
                 return: The new state of the random number generator.
170
171
```

```
172
            self._state = self._xor_shift(self._state)
173
            self._state = self._mwc(self._state & self._uint32_max) ^ self._state
174
175
            return self._state
176
178
       \frac{def}{def} _xor_shift(self, number):
179
180
                Execute the XOR-shift algorithm on the
181
182
                input number.
183
                param: number — The number to XOR—shift.
184
             return: The number produced by XOR-shift.
186
187
188
            # Shift to the right and then bitwise xor.
189
            number ^= (number >> self._xor_a1)
190
            # Shift to the left and then bitwise xor.
191
            number \hat{\ } = (number << self.\_xor\_a2)
192
            # Shift to the right and then bitwise xor.
193
            number ^= (number >> self._xor_a3)
194
195
            return number
196
198
       def _mwc(self, number):
199
               Perform multiply with carry (MWC) on
200
               the given input.
201
202
                param: number -- The number to perform MWC on, must be an uint64.
203
204
               return: The new number.
205
206
            return self._mwc_a * (number & (self._uint32_max -np.uint64(1))) + (
       number \gg np.uint64(32))
```

./Code/mathlib/random.py

Code - Statistical functions

The code that containing all statistical functions that where needed for the sub-questions. The imported sorting module used by this piece of code can be found on page 27.

```
import numpy as np
  import mathlib.sorting as sorting
  def kstest(x, cdf):
          Perform the Kolmogorov-Smirnov test for goodness of fit
          and return the p-value.
      In:
10
                     -- An array with value's who's CDF is expected to be
                         the same as the provided CDF. Must be atleast size 4
          param: cdf -- A function that is the expected cdf under the null
      hypothesis.
          return: The p-value obtained by performing the KS-test.
15
17
      # Amount of values in the input array.
18
      x_size = len(x)
19
20
21
      # Sort the values and evaluate the cdf.
      x\_sorted = sorting.merge\_sort(x)
22
      x_sorted_cdf = cdf(x_sorted)
```

```
# Maximum distance.
25
26
       \max_{dist} = 0
27
      # Value of the emperical cdf at step i-1.
28
29
       x_cdf_emperical_previous = 0
30
      # Find the maximum distance.
31
       for idx in range(0, x-size):
32
33
           # Calculate the emperical cdf.
34
           x_cdf_emperical = (idx+1)/x_size
35
           # The true cdf evaluation at the given point.
36
37
           x_cdf_true = x_sorted_cdf[idx]
38
           # Find the distance. The emperical
39
           # CDF is a step function so there are two distances
40
           # that need to be checked at each step.
41
42
           # Calculate the two distances
43
           distance\_one = abs(x\_cdf\_emperical - x\_cdf\_true)
44
45
           distance_two = abs(x_cdf_emperical_previous - x_cdf_true)
46
47
           # Find the maximum of those two distances and
48
           # check if it is larger than the current know maximum distance.
49
           max_dist = max(max_dist, max(distance_one, distance_two))
51
           # Save the current value of the emperical cdf.
53
           x_cdf_emperical_previous = x_cdf_emperical
54
      # Calculate the p-value with the help of the CDF.
       sqrt_elemens = np.sqrt(x_size)
       \vec{cdf} = \_ks\_statistic\_cdf((sqrt\_elemens + 0.12 + 0.11/sqrt\_elemens)*max\_dist) \\ return \ 1 - cdf 
57
58
59
60
  def kstest2(x1, x2, x2\_sorted = None):
61
62
           Perform the Kolmogorov-Smirnov test for goodness of fit
63
64
           and return the p-value.
65
                      -- An array with value's who's CDF is expected to be
66
           param: x1
                           the same as the CDF of the proviced values.
67
                           Must be atleast size 4.
68
69
70
           param: x2 - A discretized pdf of the expected distribution under the
       null hypothesis.
      return: The p-value obtained by performing the KS-test
72
73
74
      # Amount of values in the input distributions.
75
76
       x1-size = len(x1)
       x2\_size = len(x2)
77
78
      # Sort both arrays.
79
      x1 = sorting.merge_sort(x1)
80
      x2 = sorting.merge\_sort(x2) if type(x2\_sorted) is not None else x2\_sorted
81
82
      # The maximum distance
83
84
      \max_{\text{dist}} = 0
85
      # The iteration values used to determine
86
      # the emperical pdf's and the max distance.
87
88
      x1_i, x2_j = 0,0
89
90
      # Find the maximum distance by updating the emperical CDFs.
      while x1_i < x1_size and x2_j < x2_size:
91
92
           # Update the indices used for the emperical CDF's.
93
```

```
if x1[x1_i] < x2[x2_j]:
95
96
                x1_i += 1
97
                x2_{-j} += 1
98
99
           # Find the max distance
100
            max\_dist \ = \ max(abs(x1\_i/x1\_size-x2\_j/x2\_size), \ max\_dist)
       sqrt_factor = np. sqrt((x1_size*x2_size)/(x1_size+x2_size))
103
       cdf = _ks_statistic_cdf((sqrt_factor + 0.12+0.11/sqrt_factor)*max_dist)
105
       return 1 - cdf
106
107
   def kuiper_test(x, cdf):
108
            Perform the Kuiper test for goodness of fit
110
           and return the p-value.
112
       In ·
           param: x -- An array with value's who's CDF is expected to be
113
                          the same as the provided CDF. Must be atleast size 4
114
115
           param: cdf -- A function that is the expected cdf under the null
       hypothesis.
       Out:
       return: The p-value obtained by performing the kuiper-test ".""
118
120
       # Sort the data in ascending order, calculate the
       # cdf and the emperical cdf for the sorted values and
       # save the total amount of elements we have.
123
       x_sorted = sorting.merge_sort(x)
       x_sorted_cdf = cdf(x_sorted)
       x_{elements} = len(x)
126
       # Find the maximum distance above and below
128
       # the true cdf.
130
       max_dist_above = 0
       max_dist_below = 0
132
133
       # Value of the cdf at step i-1.
       x_cdf_emperical_previous = 0
134
135
136
       for idx, x in enumerate(x_sorted):
138
           # Calculate the emperical cdf.
139
           x_cdf_emperical = (idx+1)/x_elements
140
           # Calculate the true cdf.
141
            x_cdf_true = x_sorted_cdf[idx]
142
143
            # Find the maximum distance above and below
            \max_{dist\_above} = \max_{dist\_above} (x\_cdf\_emperical - x\_cdf\_true, \max_{dist\_above})
145
146
            max_dist_below = max(x_cdf_true - x_cdf_emperical_previous,
       max_dist_below)
147
           # Update previous cdf
148
            x_cdf_emperical_previous = x_cdf_emperical
149
       sqrt_elem = np.sqrt(x_elements)
       v = max_dist_above + max_dist_below
153
       cdf = _kuiper_statistic_cdf((sqrt_elem + 0.155+0.24/sqrt_elem)*v)
154
       return 1 - cdf
   def_{-ks\_statistic\_cdf(z)}:
158
            An approximation for the cdf of the
160
            Kolmogorov-Smirnov (KS) test staistic.
161
       In:
162
```

```
param: z — The value to calculate the cdf at.
       Out:
164
           return: An approximation of the cdf for the given value.
165
                                                                            print (
       max_dist_above + max_dist_below)
166
167
       # Numerical approximation taken from:
168
       # Numerical methods - The art of scientific computation.
169
       # Third edition.
170
172
       if z < 1.18:
            exponent = np.exp(-np.pi**2/(8*z**2))
173
            pre_factor = np.sqrt(2*np.pi)/z
174
175
           return pre_factor*exponent*(1+ exponent**8)*(1+exponent**16)
176
        else:
177
            exponent = np.exp(-2*z**2)
178
            return 1-2*exponent*(1-exponent**3)*(1-exponent**6)
179
180
       _kuiper_statistic_cdf(z):
181
182
            An approximation for the cdf of the
183
            Kuiper test statistic
184
185
       In:
           param: z -- The value to calculate the cdf at.
186
187
           return: An approximation of the cdf for the given value.
188
189
190
191
       # Value of z is to small, sum will be 1 up to 7 digits
       if z < 0.4:
            return 1
193
194
       # Approximateed value of the sum by performing 100 iterations
195
196
       # The value to return
197
       ret = 0
198
199
       # A term often needed in the sum.
       z_squared = z**2
200
201
202
       # Evaluate the first 100 terms in the sum.
       for j in range (1, 100):
203
204
            power = j**2 * z\_squared
            ret += (4 * power -1)*np.exp(-2*power)
205
206
207
       return 1- 2*ret
208
209
210
   def normal_cdf(x, mean = 0, sigma = 1):
211
212
            Evaluate the cumulative normal distribution for
213
            the given parameters
214
215
       In:
            param: x -- The point to evaluate the cdf at or an array of points to
216
       evaluate it for.
            param: mean -- The mean of the normal distribution.
217
            param: sigma -- The square root of the variance for the normal
218
       {\it distribution}\;.
       Out:\\
       return: The cummulative normal distribution evaluated at. ""
220
221
222
       # Calculate the CDF using the erf function (defined below).
       return 0.5 + 0.5 * erf((x-mean)/(np.sqrt(2)*sigma))
224
225
226
   def normal(x, mean = 0, sigma = 1):
228
            Evaluate the normal distribution for the given
229
230
```

```
In:
231
            param: x -- The point to evaulte the distribution at.
232
233
            param: mean -- The mean of the distribution.
            param: sigma -- The square root of the variance for the distribution.
234
            return: The value of the parameterized distribution evaluated at the
       given point.
238
       return 1/((\text{np.sqrt}(2*\text{np.pi})*\text{sigma}))*\text{np.exp}(-0.5*((x - \text{mean})/\text{sigma})**2)
239
240
   def erf(x):
241
242
            Evaluate the erf function for a value of x.
243
244
            param: x — The value to evaluate the erf function for.
245
246
           return: The erf function evaluated for the given value of x.
247
248
249
       # Numerical approximation taken from Abramowits and Stegun.
250
251
       # Constants for the numerical approximation
252
       p = 0.3275911
253
       a1 = 0.254829592
254
       a2 = -0.284496736
255
256
       a3 = 1.421413741
257
       a4 = -1.453152027
       a5 = 1.061405429
258
259
       # Array in which the result is stored
260
       ret = np. zeros(len(x))
261
262
       # The approximation functions
263
       erf_func_t_val = lambda x: 1/(1+ p*x)
264
        erf_func_approx = lambda t, x : 1 - t*(a1 + t*(a2 + t*(a3 + t*(a4 + t*a5))))
265
       *np.exp(-x**2)
       # Evaluate for both positive and negative
267
       neg_mask = x < 0
268
269
       neg_x = x[neg_mask]
       pos_mask = x >= 0
270
271
       pos_x = x[pos_mask]
272
       ret[neg\_mask] = -erf\_func\_approx(erf\_func\_t\_val(-neg\_x), -neg\_x)
273
274
       ret[pos\_mask] = erf\_func\_approx(erf\_func\_t\_val(pos\_x), pos\_x)
275
        return ret
```

./Code/mathlib/statistics.py

Code - Sorting

The sorting algorithm used to sort the input of the KS-test and Kuiper-test.

```
# If the length is 1 then return the input array.
16
17
       # This is an important check as this function is called
       # recursively.
18
       if size == 1:
19
20
           return array
21
       # Split the array in an sorted left and right segment.
22
       left_sorted = merge_sort(array[:size >> 1])
23
       right_sorted = merge_sort(array[size >> 1:])
24
       left_sorted_len = len(left_sorted)
25
       right_sorted_len = len(right_sorted)
26
27
28
29
       # Merge the left and right array.
       #
30
31
       # The final sorted array.
32
       result = np.zeros(size)
33
       # Current index in the left sorted array.
35
36
       left_idx = 0
37
       # Current index in the right sorted array.
38
       right_idx = 0
       # Current index in the final sorted array.
39
       result_idx = 0
40
41
       # While we didn't fill the result array.
42
       while result_idx < size:
43
44
           # Element from left array is smaller, insert it and increase position.
45
            if left_sorted[left_idx] < right_sorted[right_idx]:
46
47
                result [result_idx] = left_sorted [left_idx]
                left_idx += 1
48
                result_idx += 1
49
           # Element from right array is smaller, insert it and increase position.
50
            else:
51
                result \left[ \, result \_idx \, \right] \, = \, right \_sorted \left[ \, right \_idx \, \right]
52
                right_idx += 1
53
                result_idx += 1
55
           # Only right arrat has elements left, insert the remaining elements.
56
            if \ \ left\_idx == \ left\_sorted\_len:
57
                result[result_idx:] = right_sorted[right_idx:]
58
                break
59
60
           # Only left has elements left, insert the remaining elements
61
            if right_idx == right_sorted_len:
62
                result \left[ \, result \, \_id \, x : \right] \,\, = \,\, left \, \_sorted \left[ \, left \, \_id \, x : \right]
63
                break
64
65
       return result
```

./Code/mathlib/sorting.py

2 - Normally distributed pseudo-random numbers

Question 2

Problem

Make plots of three Gaussian random fields, using n = -1, n = -2 and n = -3. Give the plots a size of 1024. The axis should be in physical size. Choose a minimum physical size and explain how this impacts the maximum physical size, the minimum k and maximum k.

Solution

The Gaussian fields are initial created in k-space by using Fourier shifted coordinates (i.e the zeroth wavenumber corresponds with the left top and not the center) and are then inverse Fourier transformed. The method in which a field is created in k-space consists of two steps. One, the shifted wavenumbers are used to create a matrix with complex numbers based on the power spectrum. Two, the matrix is given the correct hermitian symmetry. The first step is briefly explained in the code. The second step, how the matrix is given the correct symmetry, is described below.

The matrix has the correct symmetry if the complex number created with wavenumbers k_{x_i}, k_{y_i} is equal to the conjugate of the complex number created with wavenumbers $-k_{x_i}$, $-k_{y_j}$. Let N be the size of the $N \times N$ matrix created in step one and let $c_{i,j}$ be the value in cell i,j. The matrix then has the correct hermitian symmetry if the following three points hold,

- A First row: The value of matrix cell $c_{0,j}$ should be equal to the complex conjugate of the value in cell $c_{0,N-j}$, for 0 < j < N. If N is even then the value in cell $c_{0,N/2}$ should be equal to its own conjugate (i.e this value should only have a real component, because it is created with k_0 and $k_{nyquist}$).
- B First column: This point is similar to the first point. The value of matrix cell $c_{i,0}$ should be equal to the complex conjugate of the value in the cell $c_{N-i,0}$, for 0 < i < N. If N is even then the value in cell $c_{N/2,0}$ should be equal to its own conjugate (i.e this value should only have a real component, because it is created with $k_{nyquist}$ and k_0).
- C Inner matrix: The value in cell $c_{i,j}$ should be equal to the complex conjugate in cell $c_{N-i,N-j}$ with $1 \leq i,j < N$. If the matrix is even then cell $c_{N/2,N/2}$ must be real, as it is created with $k_{nyquist}, k_{nyquist}$.

The code that uses these properties to give the matrix the correct symmetry can be found on the next page.

The minimum physical size, the size of 1 cell, is chosen to be 1 Mpc. This immediately fixes the maximum physical size as the grid must be 1024×1024 . The maximum physical size is thus 1 Mpc \times 1024 = 1024 Mpc. The minimum k and maximum k are fixed by the minimum and maximum size,

$$k_{min} = \frac{2\pi}{(N \times \text{min distance})} = \frac{2\pi}{\text{max distance}}$$
 (16)

$$k_{min} = \frac{2\pi}{(N \times \text{min distance})} = \frac{2\pi}{\text{max distance}}$$

$$k_{max} = k_{nyquist} = \frac{2\pi N}{2 \times (N \times \text{min distance})} = \frac{\pi}{\text{min distance}}$$
(16)

An increase in minimum distance would thus result in a smaller value for k_{min} and a smaller value of k_{max} .

The code that creates the fields and gives them the correct symmetry, can as mentioned before, be found below. Important to point out is that the same random uniform variables have been Box-Muller transformed to create the fields for the different powers, n = -1, n = -2, n = -3. This was done to save computational time and has as consequence that the three created plots show the evolution of the fluctuations as function of the power n (i.e the second plot and third plot show the same kind of structure, only with a different intensity).

Code

The code is split over two files. The first file contains the code for the plots and the second file contains the code for the helper functions.

Code - Plots

The code for the creation of the plots.

```
import numpy as np
  import matplotlib.pyplot as plt
  import mathlib.random as rnd
  import mathlib.misc as misc
  # Constants.
  grid\_size = 1024
  min_distance = 1 # size of a single cell in Mpc.
10 # Create the random number generator.
  random = rnd.Random(78379522)
11
  # The orders of the power spectrum.
13
  powers = [-1, -2, -3]
14
  def main():
16
17
       # Generate the random uniform numbers that
18
       # are later transformed to normal distributed variablaes.
       # The numbers are generated once to reduce computational time.
20
21
       random_numbers = random.gen_uniforms(grid_size*grid_size*2)
22
       \# Create the plots for n=-1,\ n=-2,\ n=-3
23
24
       for power in powers:
           # Generate the field matrix.
26
           matrix = misc.generate_matrix_2D(grid_size, min_distance,
27
28
                                               gen_complex , random_numbers , power)
29
           #Give it the correct symmetry.
30
           field = misc.make_hermitian2D(matrix)
31
32
           # Plot it
33
34
           # The field is real, but it is still treated as a complex
35
36
           \# value this, we have to take the r eal part. It is also multiplied
           # by grid_size^2 to correct for the normalization constant
37
           # in np.fft.ifft2.
38
39
40
           plt.imshow(np.fft.ifft2(field).real * grid_size*grid_size)
           plt.xlabel('Distance [Mpc]')
plt.ylabel('Distance [Mpc]')
41
42
           plt.title('n = {0}'.format(power))
43
           plt.colorbar()
44
           plt.savefig(,./Plots/2\_field\_\{0\}.pdf'.format(power))
45
           plt.figure()
46
47
  def gen_complex(k, n, rand1, rand2):
48
49
50
           Generate a complex number using the power
51
           spectrum.
       In:
52
           param:k — The magnitude of the wavenumber.
53
           param:n -- The order of the power law.
           param: rand1 — A random uniform variable between 0 and 1. param: rand2 — A random uniform variables between 0 and 1.
55
56
58
59
       sigma = 0
60
61
       if n == -2:
62
```

```
sigma = 1/k
       else:
64
65
            sigma = np. sqrt(k**n)
66
       # Determine the complex value
67
       a, b = random.gen_normal_uniform(0, sigma, rand1, rand2)
68
69
       return complex(a,b)
70
71
72
      _{-name_{--}} == "_{-main_{--}}":
73
       main()
```

./Code/assigment_2.py

Code - Symmetry

The code containing the functions to create the matrix and give it the correct symmetry. Only part of this file is shown, the full file is shown in assignment 4.

```
import numpy as np
  def gen_wavenumbers(size, min_distance):
           Generate the shifted wavenumbers
           for the discrete fourier transform.
      In:
           param: size -- The size of the matrix.
           param: min_distance -- The distance of a cell/ the sample spacing.
10
          return: An array with shifted wave numbers.
      # Array to return.
      ret = np.zeros(size)
15
      # Positive values
      ret [0:int(size/2)+1] = np.arange(0,int(size/2)+1)
18
       if size \% 2 == 0: \# even
19
          ret[int(size/2):] = -np.arange(int(size/2),0,-1)
20
       else: # odd
21
           ret[int(size/2)+1:] = -np.arange(int(size/2),0,-1)
23
24
      return (ret/(size*min_distance))*2*np.pi
25
26
28
  def generate_matrix_2D(size, min_distance, func, random_numbers, power):
29
           Generate a 2D matrix with complex numbers in
30
           shifted fourier coordinates using the power spectrum
31
      In:
32
           param: size — The size of the matrix (size x size).
33
           param: min_distance -- The physical size of 1 cell.
34
                         - A functiion that takes the power and to random uniform
35
           param: func -
36
                          variables to calculate the correct complex number.
           param: random_numbers -- An array with random uniform numbers.
37
                                     Must be of atleast size: size x size x 2.
38
           param: power -- The power of the power spectrum to create the matrix for.
39
      Out:
40
41
           return: A 2D matrix with complex numbers assigned by the power spectrum
                   in fourier shifted coordinates.
42
      ""
43
44
      # Generate the shifted wavenumbers
45
      wavenumber = \verb"gen-wavenumbers" ( \verb"size", \verb"min-distance")
46
47
      # The matrix to return
      ret = np.zeros((size, size), dtype=complex)
48
49
      # A counter for the random uniform variables.
50
      steps = 0
51
```

```
# Fill the matrix
53
54
          for i in range(size):
               for j in range(size):
55
56
57
                     # Element of k_0, k_0 is left zero.
                     if i = 0 and j = 0:
58
                          continue
59
60
                     # Calculate the magnitude of the wavenumbers.
61
                     k \, = \, np \, . \, s \, q \, r \, t \, \left( \, wavenumber \, [ \, i \, ] \, **2 \, + \, wavenumber \, [ \, j \, ] \, **2 \, \right)
62
                    # Fill the matrix.
63
                     ret[i][j] = func(k, power,
64
                                           random_numbers[steps], random_numbers[steps+1])
 65
                     steps += 2
66
67
         # Return the matrix
68
         return ret
69
70
71
    def make_hermitian2D(matrix):
72
 73
               Give a matrix in shifted fourier coordinates
74
               the correct hermitian symmetry so that the ifft is real.
75
 76
77
               param: matrix -- The matrix to give the correct symmetry.
         Out .
 78
 79
               return: A matrix with the correct hermitan symmetry so that the
                          ifft is real.
80
 81
82
         # The size of the matrix
83
          size = matrix.shape[0]
 84
85
         # Loop over the rows
 86
          for row in range (1, int(size/2) +1):
88
               \# Give the first column (index 0) has the correct symmetry (see report
 89
               \begin{array}{ll} \operatorname{matrix} \left[ \operatorname{row} \,, 0 \, \right] \; = \; \operatorname{complex} \left( \, \operatorname{matrix} \left[ \, \operatorname{size} - \operatorname{row} \,, 0 \, \right] . \, \operatorname{real} \,, \end{array}
90
91
                                              - matrix [size-row, 0].imag)
               # Give the first row (index 0) the correct symmetry (see report point B)
92
93
               matrix[0, row] = complex(matrix[0, size-row].real,
                                            - matrix [0, size - row].imag)
94
95
96
               # Give the inner matrix the correct symmetry (see report point C)
97
               for column in range(1, size):
                    \mathtt{matrix} \, [\, \mathtt{row} \, , \,\, \mathtt{column} \, ] \,\, = \,\, \mathtt{complex} \, (\, \mathtt{matrix} \, [\, \mathtt{size} \, - \mathtt{row} \, , \,\, \, \mathtt{size} \, - \mathtt{column} \, ] \, . \, \, \mathtt{real} \, \, ,
98
                                                             -matrix [size-row, size-column].imag)
99
100
         # Corrections for even matrix
101
          if size \% 2 == 0:
               matrix\left[\,int\,(\,size\,/2\,)\;,\;\;0\,\right]\;=\;matrix\left[\,int\,(\,size\,/2\,)\;,\;\;0\,\right].\,real\;+\;0J
103
               matrix[0, int(size/2)] = matrix[0, int(size/2)].real + 0J
104
               matrix[int(size/2), int(size/2)] = matrix[int(size/2), int(size/2)].real
106
         # Return the matrix.
          return matrix
108
```

./Code/mathlib/misc.py

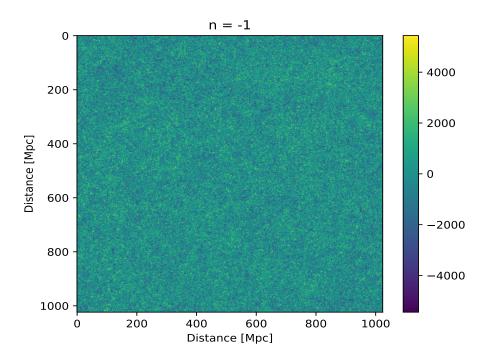


Figure 19: The Gaussian field for n = -1 and a minimal physical size of 1 Mpc. The power drops for n = -1 slowly, as result, mainly noise is expected. The plot seems to show that this is the case.

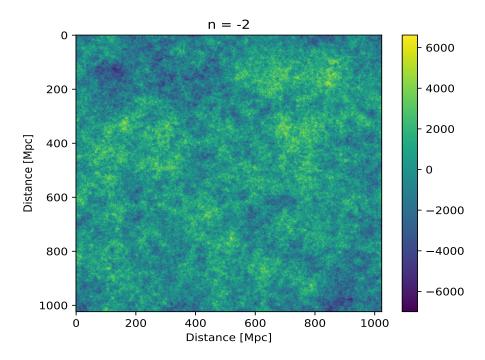


Figure 20: The Gaussian field for n = -2 and a minimal physical size of 1 Mpc. The plot seems to be less noisy than the previous plot, which is expected as n is now smaller.

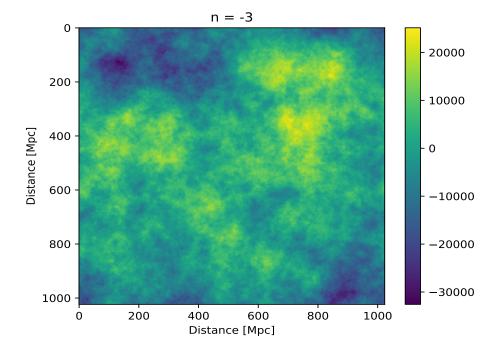


Figure 21: The Gaussian field for n = -3 and a minimal physical size of 1 Mpc. High and low density fluctuations are now clearly visible. Notice that the plot looks similar to the plot for n = -2. This is a consequence of using the same random uniform variables in the Box-Muller method.

3 - Linear structure growth

Question 3

Problem

Solve the ODE of equation 18 for the 3 given initial conditions in an matter-dominated Einstein de Sitter Universe. Use an appropriate numerical method. Compare the results with the analytical solution of the ODE. Plot the solution for t = 1 until t = 1000 yr, use a log log plot.

$$\frac{d^2D}{dt^2} + 2\frac{\dot{a}}{a}\frac{dD}{dt} = \frac{3}{2}\omega_0 H_0^2 \frac{1}{a^3}D\tag{18}$$

Initial conditions:

(A)
$$D(1) = 3, D'(1) = 2$$
 (B) $D(1) = 10, D'(1) = -10$ (C) $D(1) = 5, D'(1) = 0$

Solution

The solution of this problem consist of three parts. One, a rewritten version of equation 18 with the scale factor plugged in. Two, a derivation of the analytical solution. Three, a (brief) explanation on how this rewritten version is used numerically.

(1) Rewriting the ODE.

The numerical and analytical solution both require a version of equation 18 with the scale factor plugged in. For an Einstein-de Sitter Universe the scale factor and its derivative are given by,

$$a(t) = \left(\frac{3}{2}H_0t\right)^{2/3}$$
 and $\dot{a}(t) = H_0\left(\frac{3}{2}H_0t\right)^{-1/3}$ (19)

Plugin this in by equation 18 and using that $\Omega_0 = 1$ results in the rewritten version of equation 18,

$$\frac{d^2D}{dt^2} + \frac{H_0 \left(\frac{3}{2}H_0t\right)^{-1/3}}{\left(\frac{3}{2}H_0t\right)^{2/3}} \frac{dD}{dt} - \frac{3}{2}\Omega_0 \frac{H_0^2}{\left(\frac{3}{2}H_0t\right)^{2/3}} D = 0$$
 (20)

$$\frac{d^2D}{dt^2} + \frac{4}{3t}\frac{dD}{dt} - \frac{2}{3t^2}D = 0 {21}$$

(2) Analytical solution

The analytical solution that is required for the plots can be found by solving equation 21. The equation is solved by finding two particular solutions. These can be found by finding the values of lambda for which the ansatz $D(t) = t^{\lambda}$ holds. Plugin in the ansatz yields,

$$\lambda (\lambda - 1) t^{\lambda - 2} + \frac{4}{3t} \lambda t^{\lambda - 1} - \frac{2}{3t^2} t^{\lambda} = 0$$
 (22)

This simplifies to

$$0 = \lambda (\lambda - 1) t^{\lambda} + \frac{4}{3} \lambda t^{\lambda} - \frac{2}{3} t^{\lambda}$$
$$= \lambda (\lambda - 1) + \frac{4}{3} \lambda - \frac{2}{3}$$
$$= \lambda^2 + \frac{1}{3} \lambda - \frac{2}{3}$$
$$= (\lambda + 1)(\lambda - \frac{2}{3})$$

From the above expression it can be seem that peculiar solutions of the ODE are given by,

$$D(t) = t^{-1} D(t) = t^{2/3} (23)$$

The general solution is the superposition of the peculiar solutions with constants and can therefore be written as,

$$D(t) = c_1 t^{2/3} + c_2 t^{-1} (24)$$

The constants for the three initial cases can be found by calculating the derivative of the above equation and solving the system for the derivative and the non derivative. This yields for the three cases that,

(A)
$$c_1 = 3, c_2 = 0$$
 (B) $c_1 = 0, c_2 = 10$ (C) $c_1 = 3, c_2 = 2$ (25)

(3) Numerical solution

The numerical solution is obtained by first writing equation 21 as a system of first order ODE's and then by applying the Dormand Prince version of the Runge-kutta method. The second order ODE can be written as a system of first order ODE's by substituting dD/dt = u. The system then becomes,

$$\begin{cases} \frac{dD}{dt} = u \\ \frac{d^2D}{d^2} = -\frac{4}{3t}u + \frac{2}{3t^2}D \end{cases}$$
 (26)

The above system is as mentioned before solved with the Dormand Prince version of the Runge-Kutta method. The algorithm uses an adaptive step size that is initial set to $t_{step}=0.01$ year for all cases. The code that is used to solve the ODE numerically and generates the plots is split over two files. The first file generates the plots and the second file contains the implementation of the Dormand Prince version of the Runge-Kutta method. The code and its output can be found below.

The code that created the plots for the three given initial conditions of the ODE.

```
import numpy as no
  import mathlib.ode as ml_ode
  import matplotlib.pyplot as plt
  def main():
       # The constants of the anlytical solution for the 3 cases.
       c1\_cases = [3, 0, 3]
       c2\_cases = [0, 10, 2]
10
       # The initial conditions for the ODE solver of the 3 cases.
       initial = [[3,2],[10,-10], [5,0]]
       # The start and stop time to solve the ODE for.
14
       t\_start \, = \, 1 \, \, \# \, \, year
       t\_stop = 1000 \# years
16
       # Initial step size for the numerical solution
18
       t\_step = 0.01 \# year
19
20
       # The time values to plot the anlytical solution for.
21
22
       t_plot = np.arange(t_start, t_stop+t_step, t_step)
23
24
       # Create the plots
       for case in range(len(c1_cases)):
25
26
           # Constants for the anlytical solution.
27
           c1 = c1\_cases[case]
28
           c2 = c2\_cases[case]
29
30
           # Initial conditions for the numerical solution
31
           initial_cond = np.array(initial[case])
32
33
           # The analytical solution.
34
           analytical = lambda t: c1*t**(2/3)+ c2*t**(-1)
35
36
           # The numerical solutions.
37
           sol_num, time = ml_ode.runge_kutta_54(_linear_density_growth,
38
39
                                                        initial_cond ,
                                                        t\_start , t\_stop , t\_step ,
40
                                                        1e-6, 1e-3
41
42
43
           # Plot the analytical and numeric solution.
           plt.plot(t_plot, analytical(t_plot), label='Analytical', linestyle=':', zorder=0.1)
44
45
           plt.plot(time, sol_num[:,0], label='Numeric',zorder=0)
46
           plt.xlabel('Time [year]')
47
           plt.ylabel(''D(t)'')
48
49
            plt.loglog()
            plt.legend()
           plt.savefig('./Plots/3_ode_{0}.pdf'.format(case))
51
           plt.figure()
52
53
54
  \begin{array}{ll} \textbf{def} & \texttt{-linear\_density\_growth} \ ( \ values \ , t \ ) : \end{array}
56
           A function representing the sytem of ODE's that needs
57
58
           to be solved for the lineer density growth equation.
59
           param: values -- The current values of the linear growth function and its
60
        derivatie.
           param: t -- The current time step for which the ODE is integrated.
61
62
63
           return: An array representing the system of first order ODE's for the
       given parameters.
64
65
       # Current value of the linear growth function.
66
```

```
d = values[0]
      # Current value of the derivative of the linear growth function.
68
69
      u = values[1]
70
      # The two systems of first order ODE's.
71
72
      second = -(4/(3*t))*u + (2/(3*t**2))*d
73
74
       return np.array([first, second])
75
76
77
  if __name__ == '__main__':
78
      main()
```

./Code/assigment_3.py

Code - Runge-Kutta

The code for the Dormand Prince version of the Runda kutta method.

```
import numpy as np
   \frac{\text{def runge\_kutta\_54}(\text{func, y0, t\_start, t\_stop, t\_step, atol=1e-6, rtol=1e-3)}{:} 
           Perform the 4the order runga_kutta method for first order ODE integration
       In:
           param: func -- The function describing the differential equation or the
       system
                              of first order ODEs to integrate. Must return a numpy
       array.
           param: y0 -- The initial conditions.
           param: t_start — The time to start integration at.
11
           param: t_stop -- The time to stop integration at.
           param: t_step -- The initial step size to use.
13
           param: steps — The step size to use for integration.
           param: order -- The order of the algorithm to use.
15
17
18
       \# If true, solving a single ODE, else solving a system. if type(y0) is not np.ndarray:
19
20
           y0 = np.array([y0]) \# convert to array
21
22
23
       # Array with values to return, for both the integrated # values and the time stemps. The size is increased by a
25
       # factor of 2 when needed.
26
27
       ret = np.zeros((int((t_stop-t_start)/t_step)+1, len(y0)))
29
       time = np.zeros(int((t_stop-t_start)/t_step)+1)
30
       # Set initial state.
31
       ret[0] = y0
32
       time [0] = t_start
33
34
       # Solve the ODE or the system of ODEs
35
       min\_update\_scale = 0.2
36
       max\_update\_scale = 10
37
38
       # Current time at the integration
39
       t_now = t_start
40
       # Total amount of executed steps
41
       steps = 1 \# skip zero
42
43
44
       # Current error
       error = 1.1
45
       y_next = 0
46
47
       while t_{now} \le t_{stop}:
48
```

```
# Check if we need to expand the return arrays
 50
 51
                                    if steps >= ret.shape [0]:
                                                 ret_old = ret.copy()
 52
                                                 ret = np.zeros((ret_old.shape[0]*2, ret_old.shape[1]))
 53
                                                  ret[0:steps] = ret_old
 55
                                                 \mathtt{time\_old} \; = \; \mathtt{time.copy} \, ( \, )
                                                  time = np.zeros(time_old.shape[0]*2)
 57
                                                 time[0:steps] = time_old
  59
 60
                                    # Get the value found at the previous step
 61
                                    previous = ret[steps - 1]
 63
                                    # Calculate the constants for the Dormand Prince Runge kutta method.
 64
  65
                                    # Appoligies if this looks ugly in the report.
 66
  67
                                    k1 = t_step*func(previous, t_now)
                                    k2 = t_step*func(previous + (1/5)*k1, t_now + (1/5)*t_step)
  68
                                   \begin{array}{l} k3 = t\_step*func(previous + (3/40)*k1 + (9/40)*k2, t\_now + (3/10)*t\_step) \\ k4 = t\_step*func(previous + (44/45)*k1 - (56/15)*k2 + (32/9)*k3, t\_now + (3/10)*t\_step) \\ \end{array}
 69
  70
                      (4/5)*t_step)
                                   {\tt k5} \, = \, {\tt t\_step*func(previous} \, + \, (19372/6561)*{\tt k1} \, - \, (25360/2187)*{\tt k2} \, + \,
  71
                       (64448/6561)*k3 - (212/729)*k4, t_now + (8/9)*t_step)
                                   k6 = t_step*func(previous + (9017/3168)*k1 - (355/33)*k2 + (46732/5247)*
  72
                      k3 + (49/176)*k4 - (5103/18656)*k5, t_now + t_step
  73
                                    # Calculate the new value.
  74
  75
                                    y_next = previous + ((35/384)*k1 + (500/1113)*k3 + (125/192)*k4 - (125/192)*k4 + (125/192)*k4 
                       (2187/6784)*k5 + (11/84)*k6
                                     y\_embedded = previous + ( (5179/57600)*k1 + (7571/16695)*k3 + (393/640)*k1 + (393/64
                      k4 - (92097/339200) * k5 + (187/2100) * k6
                                    # Calculate error
  78
                                    delta = abs(y_embedded - y_next)
  79
                                    scale = atol+np.maximum(abs(previous),abs(y_next))*rtol
  80
                                    error = np.sqrt(np.sum((delta/scale)**2)/len(k1))
  81
 82
                                    # The factor used to calculate the new step size.
 83
 84
                                    update_scale = 0.9*(error)**(-0.2)
 85
                                    # Make sure the factor is not to large or to small.
  86
                                    if error = 0:
  87
                                                 update_scale = max_update_scale
  88
                                    elif update_scale < min_update_scale:</pre>
  89
                                                 update_scale = min_update_scale
 90
                                    elif update_scale > max_update_scale:
 91
                                                 update\_scale = max\_update\_scale
  92
 93
                                    # Check if the current step should be accepted.
 94
                                     if error > 1: # reject
                                               t_step*= min(update_scale, 1.0)
 96
 97
                                     else: # accept
                                                t_now += t_step
 98
                                                 t_step *= update_scale
 99
100
                                                 ret[steps] = y_next
                                                 time[steps] = t_now
                                                  steps += 1
104
105
                       return ret[0:steps], time[0:steps]
```

./Code/mathlib/ode.py

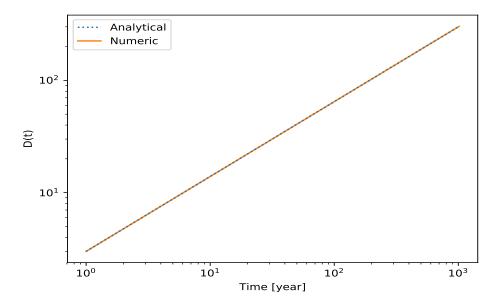


Figure 22: The analytical (blue) and numerical (orange) solution of the ODE with initial conditions D(1) = 3, D'(1) = -10. The plots show that he numerical solution does not appear to have a visible deviation from the analytical solution for the given time interval.

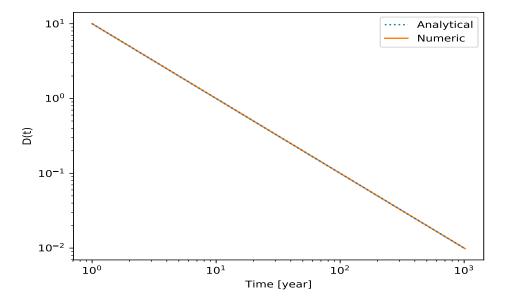


Figure 23: The analytical (blue) and numerical solution (orange) of the ODE with initial conditions D(1) = 10, D'(1) = -10. The plots show that he numerical solution does not appear to have a visible deviation from the analytical solution for the given time interval.

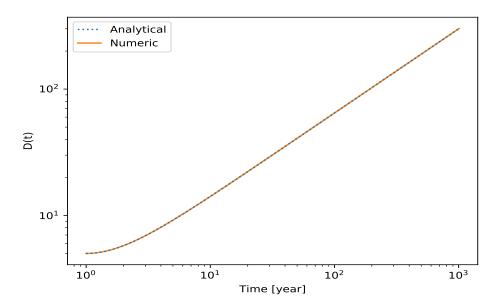


Figure 24: The analytical (blue) and numerical (orange) solution of the ODE with initial conditions D(1) = 5, D'(1) = 0. The plots show that he numerical solution does not appear to have a visible deviation from the analytical solution for the given time interval.

4 - Zeldovich approximation

Question 4.a)

Problem

The linear growth factor is expressed in terms of a integral expression given by,

$$D(z) = \frac{5\Omega_m H_0^2}{2} H(z) \int_z^\infty \frac{1+z'}{H^3(z')} dz'$$
 (27)

Here z is the redshift, Ω_m is the matter fraction of the Universe at z = 0 ($\Omega_m = 0.3$), H_0 is the Hubble constant at z = 0 and H(z) is the redshift dependent Hubble parameter given by,

$$H(z)^{2} = H_{0}^{2} \left(\Omega_{m} (1+z)^{3} + \Omega_{\Lambda} \right)$$
 (28)

Here Ω_{Λ} is the dark energy fraction of the Universe given by $\Omega_{\Lambda} = 0.7$. Use numerical integration to calculate the growth factor at z = 50 with a relative accuracy of 10^{-5} . Note that D(a(z = 50)) = D(z = 50), so use either variable.

Solution

The equation is before integrating first written in terms of the scale factor a. Substituting a = 1/(1+z) yields,

$$dz = -(1+z)^2 da = -a^{-2} da (29)$$

Plugin this in by equation 27 results in,

$$D(a) = \frac{5\Omega_m H_0^2}{2} H(a) \int_a^0 \frac{-a'^{-3}}{H^3(a')} da' = \frac{5\Omega_m H_0^2}{2} H(a) \int_0^a \frac{a'^{-3}}{H^3(a')} da'$$
 (30)

The Hubble parameter in terms of the scale factor a given by,

$$H(a)^{2} = H_{0}^{2}(\Omega_{m}a^{-3} + \Omega_{\Lambda})$$
(31)

Substituting this in equation 30 and simplifying yields,

$$D(a) = \frac{5\Omega_m H_0^3}{2} (\Omega_m a^{-3} + \Omega_\Lambda)^{0.5} \int_0^a \frac{a'^{-3}}{(H_0^2 (\Omega_m a^{-3} + \Omega_\Lambda))^{3/2}} da'$$
 (32)

$$= \frac{5\Omega_m}{2} (\Omega_m a^{-3} + \Omega_\Lambda)^{0.5} \int_0^{a'} \frac{a'^{-3}}{(\Omega_m a^{-3} + \Omega_\Lambda)^{3/2}} da'$$
 (33)

The above integral is with the help of Romberg integration solved for $\Omega_m = 0.3$ and $\Omega_{\lambda} = 0.7$. The code for Romberg integration can be found at page 57. The code that prints the output and the printed output can be found below. The shared modules used by the code start at page 53.

Code - Output

The code that prints the value of the linear growth factor. The code for the called helper function, helpers4.calculate_linear_growth can be found on page 53.

```
def assigment4_a():

"""

Execute assigment 4a

"""

# Relevant imports are.
# (1) import mathlib.helpers4 as helpers4

# The value of the scale to integrate to
a_max = 1/51

# The values of the density parameters
omega_m = 0.3
omega_lambda = 0.7

# Print the result
print('[4a] D(a = 1/51) = ', helpers4.calculate_linear_growth(a_max, omega_m, omega_lambda))
```

./Code/assigment_4.py

Text - Output

The output produced by the above code.

```
1 [4a] D(a = 1/51) = 0.019607780428272343

./Output/assigment4_out.txt
```

Question 4.b)

Problem

Use your result from the previous question to analytically calculate for a = 1/51,

$$\dot{D(t)} = \frac{dD(a)}{da}\dot{da} \tag{34}$$

Bonus points if you calculate it numerically and match the analytical result within 10^{-8} .

Solution

In this question the derivative is not only calculated analytically, but also numerically. The numerical calculation is performed with ridders method. The analytical solution is derived below and evaluated. The code for the numerical solution and the code that prints the analytical solution³ can be found after this derivation. This includes the code for ridders method.

To simplify the derivation we define,

$$C = \int_0^{a'} \frac{a'^{-3}}{(\Omega_m a'^{-3} + \Omega_\Lambda)^{3/2}} da'$$
 (35)

The derivative can then by substituting 33 in equation 34 be written as,

$$\dot{D}(t) = \frac{5\Omega_m}{2} \left(\frac{-3\Omega_m a^{-4}}{2} \left(\Omega_m a^{-3} + \Omega_\Lambda \right)^{-0.5} C + \left(\Omega_m a^{-3} + \Omega_\Lambda \right)^{0.5} \frac{a^{-3}}{\left(\Omega_m a^{-3} + \Omega_\Lambda \right)^{3/2}} \right) \dot{a} \quad (36)$$

$$= \frac{5\Omega_m}{2} \left(\frac{-3\Omega_m a^{-4}}{2 \left(\Omega_m a^{-3} + \Omega_\Lambda \right)^{0.5}} C + \frac{a^{-3}}{\left(\Omega_m a^{-3} + \Omega_\Lambda \right)} \right) \dot{a} \quad (37)$$

Substituting $\dot{a} = H(a)a(t) = H_0 \left(\Omega_m a^{-3} + \Omega_\Lambda\right)^{0.5} a(t)$ results in,

$$\dot{D} = \frac{5\Omega_m H_0}{2} \left(\frac{-3\Omega_m a^{-3}}{2} C + \frac{a^{-2}}{(\Omega_m a^{-3} + \Omega_\Lambda)^{0.5}} \right)$$
(38)

$$= \frac{5\Omega_m H_0}{2a^2} \left(\frac{1}{(\Omega_m a^{-3} + \Omega_{\Lambda})^{0.5}} - \frac{3\Omega_m}{2a} C \right)$$
 (39)

The above expression is evaluated in the code. The value of C is numerically calculated for the analytical expression. This value is just the result of the previous question without scale factor and was allowed to be used for this question. The analytical output (with the numerical calculation for C) and the numerical output (with ridders method) can be found after the code section.

³The analytical solution is printed to make it easier to compare.

Code - Print

The code that prints the analytical and numerical result. The code for ridders method follows after this.

```
def assigment4_b():
            Execute assigment 4b
       # Relevant imports include:
       # (1) import mathlib.derivative as ml_dir
       # (2) import mathlib.helpers4 as helpers4
       # (3) import mathlib.integrate as integrate
11
       # Start with numerical
       # The linear growth factor as function of a
13
14
       D = lambda a: helpers4.calculate\_linear\_growth(a, 0.3, 0.7)
       # Calculate the derivative with ridder for a=1/51
16
       dirivative = ml_dir.ridder(D, 1/51, 1e-15)
18
       \# \operatorname{Calculate} \operatorname{dot}\{a\} = \operatorname{H}(a)a
19
       H_{-}0 = 7.16e - 11
20
21
       H = H_0 * (0.3*(1/51)**(-3) + 0.7)**0.5
22
       # Final result
23
       final\_numerical = dirivative*H*(1/51)
24
25
       # Analytical
26
27
       # The function to integrate.
28
       func = lambda a: a**(-3) / (0.3 * (1/(a**3)) + 0.7) **(3/2)
29
       C = integrate.romberg(func, 1e-7, (1/51), 15)
30
31
       # The right term in brackets
32
       right = -(3*0.3*C)/(2*(1/51))
33
       # The left term in brackets
34
35
       left = 1/(0.3*(1/51)**(-3)+0.7)**0.5
36
       # Prefactor
37
38
       pre = (5*0.3*H_{-}0)/(2*(1/51)**2)
39
40
       # Print the results
       print("[4b] Analytical: ", pre*(left+right))
print("[4b] Numerically: ", final_numerical)
41
```

./Code/assigment_4.py

Code - Ridder

The code for ridders method.

```
import numpy as np

def central_diff(function, x, h):
    """

    Use the central difference method to approximate the derivative at a point x.

In:
    param: function — The function to calculate the derivative of.
    param: x — The point to approximate the derivative of the function at.
    param: h — A small value h that in the limit would go to zero.

Out:
    return: An approximation of the derivative of the provided
    function at x.

"""
```

```
\#f'(x) \text{ approx } (f(x+h)-f(x-h))/2h
16
17
      return (function(x+h) - function(x-h))/(2*h)
18
19
  def ridder(function, x , precision):
20
21
           Perform ridders differential method to estimate
22
           the derivative at a point x
23
24
25
           param: function -- The function to estimate the derivative for.
26
           param: x -- The point to estimate the derivative at.
27
           param: precision -- The precision that must be obtained
28
29
                                 in the estimation.
30
          return: An approximation of the derivative.
31
32
33
      # The number of initial approximations to use.
34
      approximations = 0
35
36
      # The return value.
37
      ret = 0
      # The current precision.
38
      39
40
      # While we didn't reach the request precision with
41
42
      # the current amount of initial approximations, try again
      # but with more approximations.
43
44
      while current_precision > precision:
          # Increase the amount of initial approximations.
45
          approximations += 5
46
           # Reset the error.
47
           current_precision = 0xFFFFFFFFF
48
49
           # The array to store the combined results in.
51
52
           results = np.zeros(approximations)
53
           # The current combination:
54
           # 0 = combine initial central_difference evaluations,
           # 1 = combine the combined central difference evaluations
           \# 2 = combine the combined combined central difference evaluations etc.
           for combination in range (0, approximations -1):
58
59
60
               # Combine for the current 'combination'.
                for j in range(1, approximations-combination):
61
62
                   # Create the initial central difference to combine.
63
                   if combination == 0:
64
                       # We need two central difference's to
65
                       # combine the very first time.
66
                        if j == 1:
67
                            results[j-1] = central_diff(function, x,1)
68
69
                       # Decrease h by a factor of 2 for each next approximation.
70
                        results [j] = central_diff(function, x, (1/2)**j)
71
72
                   # Keep the evaluation of the previous combination that
73
                   # is getting overwritten temporary in memory to update
74
                   # the current precision.
75
76
                   previous = results[j-1]
77
                   # Combine
78
                   power = 4**(combination+1)
                   results[j-1] = (power*results[j] - results[j-1])/(power-1)
80
81
                   # Determine the new precision
                   precision_tmp = \max(abs(results[j-1] - previous), \\ abs(results[j-1] - results[j]))
83
```

```
# New precision is smaller-> update
                    if precision_tmp < current_precision:
87
                         current_precision = precision_tmp
89
                         ret = results[j-1]
90
                        # Terminate if requested precision is reached
                         if current_precision < precision:
92
93
                             return ret
94
                    # Abort early if the error of the last combined result is worse
95
96
                    # than the previous order by a large amount.
                    if j = (approximations - combination - 1) \setminus
97
                        and abs(ret - previous) > 100*current_precision:
98
99
                         return ret
100
       return ret
```

./Code/mathlib/derivative.py

Text - Output

The analytical and numerical result. As can be seen is the numerical approximation within 10^{-8} .

```
[4b] Analytical: 2.800638157126267e-10
[4b] Numerically: 2.8006381571292944e-10
```

./Output/assigment4_out.txt

Question 4.c)

Problem

Use the Zeldovich approximation to generate a movie of the evolution of a volume in two dimensions from a scale factor of 0.0025 until a scale factor of 1.0. To do this, start with 64x64 particles arranged in a square grid with a grid spacing of 1 Mpc. Use $P(k) = k^{-2}$ and the given equation to generate c_k , then use the FFT on your grid of particles to calculate $\mathbf{S}(\mathbf{q})$. As a increases, update the positions and momenta of the particles and save each step as a frame for your movie.

Solution

The difficulty of this exercise lays by the calculation the components of the displacement vector. A brief description of how this is done can be found below.

The displacement vector is calculated by first creating a matrix in k-space with complex values based on the given power law (similar to exercise 2). The matrix is next given the correct hermitian symmetry (see again exercise 2). The components of the displacement vector, s_x and s_y , are then calculated independent with the help of this matrix. This calculation is done as follows. The hemitian matrix is copied and the components in the matrices are multiplied with the wavenumbers and the complex number i. The wavenumbers by which the components are multiplied depends on whether we want s_x or s_y . The result is two matrices where the cells have respectively values of ic_kk_x and ic_kk_y . After this multiplication the matrices cannot be directly fourier transformed to obtain s_x and s_y , as the multiplication with the wavenumbers breaks the symmetry in the columns with nyquest wavenumbers. The symmetry is only broken by a minus sign and this is corrected before doing the IFFT.

The code that creates the movie and the plots for the first 10 particles can be found below. The final plot of the movie is also included and shows that the particles clearly move to the denser region (see figure 25 on page 47).

Code - Plots:

The code that creates the movie and the plots of the first 10 particles. The code does make use of an object called 'random' and a function called gen_ complex. This object and the function can be found on page 53. The code for the imported shared modules can also be found at page 53. The movie can be found in the movie folder.

```
assigment4_c():
            Execute assignment 4c
       # The relevant imports include:
       # (1) import numpy as np
       # (2) import scipy.fftpack
       # (3) import mathlib.misc as misc
       # (4) random, defined outside the main function.
12
13
14
       # Constants and random number generator
15
        grid_size = 64
       min_distance = 1
       power = -2
18
       # Create the hermitan matrix and the ifft.
       # The ifft is used to plot the backgound
20
       matrix = misc.generate_matrix_2D(grid_size, min_distance,
21
22
                                                gen_complex,
                                               random.gen_uniforms(grid_size **2*2),power)
23
       matrix = misc.make_hermitian2D(matrix)
25
       # Calculate the ifft, used for the background of the movie.
26
       {\tt matrix\_ifft} \, = \, scipy.\, fftpack.\, ifft\, 2\, (\, matrix\,) \, .\, real \, * \, grid\_size
27
28
       # wavenumbers
29
30
       wavenumbers = misc.gen_wavenumbers(grid_size, min_distance)
31
       matrix_y = matrix * wavenumbers*1J
32
       matrix_x = matrix * wavenumbers[:, np.newaxis]*1J
33
34
       # Fix the symmetry that is broken
35
36
       size = matrix_x.shape[0]
37
38
       matrix_x[int(size/2),0] = matrix_x[int(size/2),0].real
39
       matrix_x[int(size/2),int(size/2)] = matrix_x[int(size/2),int(size/2)].real
40
41
       matrix_y[0, int(size/2)] = matrix_y[0, int(size/2)].real
42
       matrix\_y \left[ \, \underline{int} \left( \, size \, / 2 \right) \, , \underline{int} \left( \, size \, / 2 \right) \, \right] \, = \, matrix\_y \left[ \, \underline{int} \left( \, size \, / 2 \right) \, , \underline{int} \left( \, size \, / 2 \right) \, \right] . \, real
43
44
45
46
        for i in range(int(size/2)+1, size):
            matrix_x[int(size/2),i] *= -1

matrix_y[i,int(size/2)] *= -1
47
48
49
       # Generate the components of the displacemnet vectors
50
       # We have to transpose/ switch to get the x and y.
51
       # Multiplication with grid_size is to correct for the
       \# normalization factor of the scipy implementation of the ifft.
53
       s_x = scipy.fftpack.ifft2(matrix_y).real *grid_size
       s_y = scipy.fftpack.ifft2(matrix_x).real *grid_size
       # Positons of particles
57
       pos_x, pos_y = np.meshgrid(range(0,grid_size),range(0,grid_size))
58
59
       # Begin simulation
60
61
       # Constants for integration
62
       a_{-}min = 0.0025
63
       scale_factors = np.linspace(a_min, 1, 90)
64
```

```
# List in which the momentum and position
66
67
       # of the first 10 particles is saved.
       pos_top_10 = list()
68
       momentum_top_10 = list()
69
70
       # Create the plot
71
        for idx,a in enumerate(scale_factors):
72
            print(idx)
73
            # Calculate da
74
            \mathrm{d} a \,=\, 0
75
76
            if idx != 0:
77
                da = scale_factors[idx] - scale_factors[idx-1]
78
79
            else:
                da \,=\, scale\_factors\left[\,idx\,\right] \,-\, a\_min
80
81
            # Calculate D(a) and \dot(D)
82
            d = helpers4.calculate_linear_growth(a)
83
            ddot = helpers4.calculate_linear_growth_dir(a -da/2)
84
85
86
            # Update position.
            pos_x_new = (pos_x + s_x*d) \% grid_size
87
            pos_y_new = (pos_y + s_y*d) \% grid_size
88
89
            pos_top_10.append(pos_y_new[0:10,0])
90
91
92
            # Update momentum.
            p_x = -(a-da/2)**2 * ddot *s_x
93
94
            p_y = -(a-da/2)**2 * ddot*s_y
95
            momentum\_top\_10.append(p\_y[0:10,0])
96
97
            # Create the plot.
98
            plt.scatter(pos_x_new, pos_y_new, s=1,c='black')
90
            plt.imshow(matrix_ifft,alpha=0.7)
100
            plt.colorbar()
101
102
            plt.title('a='
            plt.xlabel('x [Mpc]')
            plt.ylabel('y [Mpc]')
plt.savefig('./Plots/4c/4c={0}.png'.format(idx))
            plt.close()
106
       # Plot the momentum and position
108
       pos\_top\_10 = np.array(pos\_top\_10)
109
110
       momentum_top_10 = np.array(momentum_top_10)
       # Momentum
        for i in range (0,10):
113
            plt.plot(scale_factors, momentum_top_10[:,i],label='particle' + str(i+1)
114
            plt.xlabel('a')
            plt.ylabel(r'$P_y$')
117
        plt.legend()
        plt.savefig('./Plots/4c_momentum.pdf')
118
        plt.close()
119
120
       # Position
121
        for i in range (0,10):
            plt.plot(scale\_factors, pos\_top\_10[:,i],label='particle' + str(i+1))
123
            plt.xlabel('a')
124
            plt.ylabel(r'y')
125
126
        plt.legend()
        plt.savefig('./Plots/4c_pos.pdf')
        plt.close()
129
```

./Code/assigment_4.py

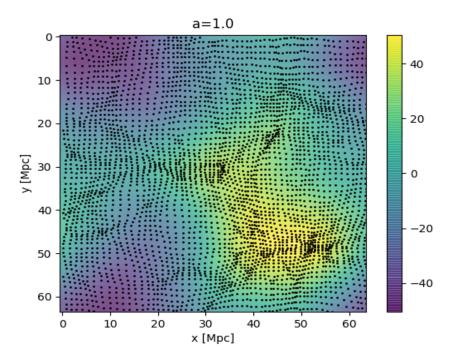


Figure 25: The final plot of the movie. It can clearly be seen that the particles (black dots) moved to the denser region.

Plots - particles

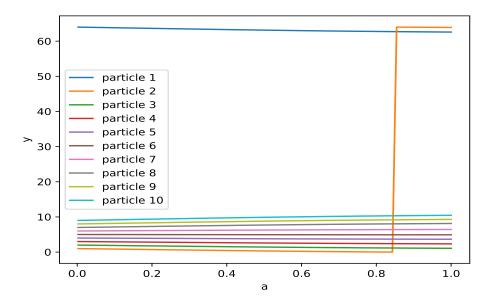


Figure 26: The y-positions of the first 10 particles as function of the scale factor. The plot shows that the particles are slowly moving to a denser region (see figure 25, where the first 10 particles are at the left top). The large jump for particle 2 (orange) at a scale factor of around $a \approx 0.8$ is the result of the circular boundary conditions.

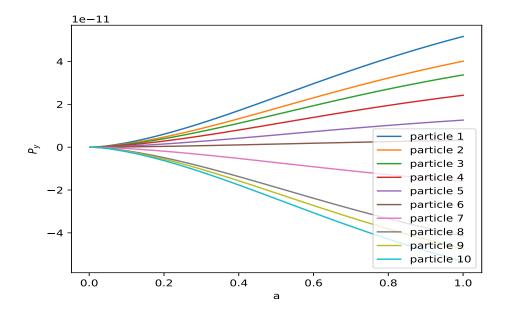


Figure 27: The momentum of the first 10 particles as function of the scale factor. The fact that about halve of the particles have a positive momentum and that the other halve have a negative momentum is the result of the circular boundary conditions and the created field.

Question 4.d)

Problem

Generate initial conditions for a three dimensional box to do a N-body simulation, make initial conditions for 64^3 particles starting at redshift z=50. Besides this make 3 separate movies of a slice of thickness 1/64th of your box at its center, make a slice for x-y, x-z, y-z. Again make a movie of at least 3 seconds with at least 30 frames per second. Finally plot the position and momentum of the first 10 particles along the z-direction vs a.

Solution

The method in which the displacement vector is similar to the method in 4c. This thus means that first a 3D matrix (tensor) is created in k-space with complex values based on the given power law. The matrix is next given the correct hermitian symmetry, which is done by an extended version of the algorithm explained in question 2. The symmetric matrix (tensor) is now used to calculate the components s_x , s_y and s_z . This is identical to 4c: The matrix is first copied and the copies multiplied with the correct wavenumbers and the complex value i. In the end this results in three matrices that need to be inverse Fourier transformed to obtain the components of S. The three matrices can again not be directly inverse Fourier transformed as the multiplication with the wavenumbers breaks the symmetry in the nyquest planes. The symmetry is again only broken by a minus sign and is first corrected before doing the IFFT. The corrected matrices are then used to calculate s_x , s_y and s_z .

The code that uses the displacement vector to creates the 3 simulations and the plots for the first 10 particles can found below. The code make use of an object called 'random' and a function called gen_ complex. This object and the function can be found on page 53. The code for the imported modules can also be found at page 53. The movie can be found in the movie folder.

Code - Plots:

The code that creates the movie and the plots of the first 10 particles in 3D.

```
Execute assigment 4d
       # The relevant imports include:
       # (1) import numpy as np
       # (2) import scipy.fftpack
# (3) import mathlib.misc as misc
       # (4) random, defined outside the main function.
11
       # Create the matrix
       grid_size = 64
12
       min_size = 1
13
       power = -2
14
16
       # Create the matrix and give it the correct symmetry
17
       matrix = misc.generate_matrix_3D(grid_size, min_size,
                                              gen_complex,
18
19
                                             random.gen_uniforms(grid_size**3 *2),
                                             power)
20
       matrix = misc.make_hermitian3D(matrix)
21
22
       # Wavenumbers and matrices for positions
24
       wavenumbers = misc.gen_wavenumbers(grid_size,1)
25
       kx, ky, kz = np. meshgrid (wavenumbers, wavenumbers, wavenumbers)
26
27
       matrix_x = matrix*kx*1J
       matrix_y = matrix*ky*1J
28
       matrix_z = matrix*kz*1J
29
30
       # Fix the broken symmetry
31
32
       # Fix matrix_x
33
       for i in range(matrix.shape[0]):
34
            for j in range(int(grid_size/2)+1, grid_size):
35
                 matrix_x[i, int(grid_size/2), j] *= -1
36
37
            if i > int(grid_size/2):
38
                 \texttt{matrix\_x} \left[ \, \text{i} \, , \, \text{int} \, ( \, \text{grid\_size} \, / 2 ) \, , \, \text{int} \, ( \, \text{grid\_size} \, / 2 ) \, \right] \ *=-1
39
                 matrix_x[i, int(grid_size/2), 0] *= -1
40
41
       # Special points
42
       matrix_x[int(grid_size/2), 0, 0] = matrix_x[int(grid_size/2), 0, 0].imag
43
       matrix_x[0,int(grid_size/2),0] = matrix_x[0,int(grid_size/2),0].imag
44
       matrix_x[0,0,int(grid_size/2)] = matrix_x[0,0,int(grid_size/2)].imag
45
46
       matrix_x[int(grid_size/2), int(grid_size/2),0] = matrix_x[int(grid_size/2),
47
       int(grid_size/2),0].imag
       matrix_x[int(grid_size/2), 0, int(grid_size/2)] = matrix_x[int(grid_size/2)]
48
       0, int(grid_size/2)].imag
       matrix_x[0, int(grid_size/2), int(grid_size/2)] = matrix_x[0, int(grid_size/2)]
49
       /2), int(grid_size/2)].imag
matrix_x[int(grid_size/2), int(grid_size/2), int(grid_size/2)] = matrix_x[int
       (grid_size/2), int(grid_size/2), int(grid_size/2)].imag
       # Fix matrix_z
       for i in range(matrix.shape[0]):
            for j in range(int(grid_size/2)+1, grid_size):
54
55
                 matrix_z[i, j, int(grid_size/2)] *= -1
            if i > int(grid_size/2):
                 matrix_z[i, int(grid_size/2), int(grid_size/2)] *=-1
58
                 matrix_z[i,0,int(grid_size/2)] *= -1
59
60
       # special points
61
       matrix_z[int(grid_size/2), 0, 0] = matrix_z[int(grid_size/2), 0, 0].imag
62
       matrix_z[0, int(grid_size/2), 0] = matrix_z[0, int(grid_size/2), 0].imag
63
       \operatorname{matrix}_{z}[0,0,\inf(\operatorname{grid}_{size}/2)] = \operatorname{matrix}_{z}[0,0,\inf(\operatorname{grid}_{size}/2)]. imag
```

```
matrix_z[int(grid_size/2), int(grid_size/2),0] = matrix_z[int(grid_size/2),
                                     int(grid_size/2),0].imag
                                     matrix_z[int(grid_size/2), 0, int(grid_size/2)] = matrix_z[int(grid_size/2)]
   67
                                      0, int (grid_size/2)].imag
                                     matrix_z[0, int(grid_size/2), int(grid_size/2)] = matrix_z[0, int(grid_size
                                     /2), int(grid_size/2)].imag
                                     matrix\_z \left[ \, \underbrace{int} \left( \, grid\_size \, / 2 \right) \,, \right. \\ \left. int \left( \, grid\_size \, / 2 \right) \,, \right. \\ \left. int \left( \, grid\_size \, / 2 \right) \,\right] \\ = \, matrix\_z \left[ \, \underbrace{int} \left( \, grid\_size \, / 2 \right) \,, \right. \\ \left. int \left( \, grid\_size \, / 2 \right) \,, \right. \\ \left. int \left( \, grid\_size \, / 2 \right) \,, \right. \\ \left. int \left( \, grid\_size \, / 2 \right) \,, \right. \\ \left. int \left( \, grid\_size \, / 2 \right) \,, \right. \\ \left. int \left( \, grid\_size \, / 2 \right) \,, \right. \\ \left. int \left( \, grid\_size \, / 2 \right) \,, \right. \\ \left. int \left( \, grid\_size \, / 2 \right) \,, \right. \\ \left. int \left( \, grid\_size \, / 2 \right) \,, \right. \\ \left. int \left( \, grid\_size \, / 2 \right) \,, \right. \\ \left. int \left( \, grid\_size \, / 2 \right) \,, \right. \\ \left. int \left( \, grid\_size \, / 2 \right) \,, \right. \\ \left. int \left( \, grid\_size \, / 2 \right) \,, \right. \\ \left. int \left( \, grid\_size \, / 2 \right) \,, \right. \\ \left. int \left( \, grid\_size \, / 2 \right) \,, \right. \\ \left. int \left( \, grid\_size \, / 2 \right) \,, \right. \\ \left. int \left( \, grid\_size \, / 2 \right) \,, \right. \\ \left. int \left( \, grid\_size \, / 2 \right) \,, \right. \\ \left. int \left( \, grid\_size \, / 2 \right) \,, \right. \\ \left. int \left( \, grid\_size \, / 2 \right) \,, \right. \\ \left. int \left( \, grid\_size \, / 2 \right) \,, \right. \\ \left. int \left( \, grid\_size \, / 2 \right) \,, \right. \\ \left. int \left( \, grid\_size \, / 2 \right) \,, \right. \\ \left. int \left( \, grid\_size \, / 2 \right) \,, \right. \\ \left. int \left( \, grid\_size \, / 2 \right) \,, \right. \\ \left. int \left( \, grid\_size \, / 2 \right) \,, \right. \\ \left. int \left( \, grid\_size \, / 2 \right) \,, \right. \\ \left. int \left( \, grid\_size \, / 2 \right) \,, \right. \\ \left. int \left( \, grid\_size \, / 2 \right) \,, \right. \\ \left. int \left( \, grid\_size \, / 2 \right) \,, \right. \\ \left. int \left( \, grid\_size \, / 2 \right) \,, \right. \\ \left. int \left( \, grid\_size \, / 2 \right) \,, \right. \\ \left. int \left( \, grid\_size \, / 2 \right) \,, \right. \\ \left. int \left( \, grid\_size \, / 2 \right) \,, \right. \\ \left. int \left( \, grid\_size \, / 2 \right) \,, \right. \\ \left. int \left( \, grid\_size \, / 2 \right) \,, \right. \\ \left. int \left( \, grid\_size \, / 2 \right) \,, \right. \\ \left. int \left( \, grid\_size \, / 2 \right) \,, \right. \\ \left. int \left( \, grid\_size \, / 2 \right) \,, \right. \\ \left. int \left( \, grid\_size \, / 2 \right) \,, \right. \\ \left. int \left( \, grid\_size \, / 2 \right) \,, \right. \\ \left. int \left( \, grid\_size \, / 2 \right) \,, \right. \\ \left. int \left( \, grid\_size \, / 2 \right) \,, \right. \\ \left. int \left( \, grid\_size \, / 2 \right) \,, \right. \\ \left. int \left( \, grid\_size \, / 2 \right) \,, \right. \\ \left. int \left( \, grid\_size \, / 2 \right) \,, \right. \\ \left. int \left( \, grid\_size \, / 2 \right) \,, \right. \\ \left. int \left( \, grid\_size \, / 2 \right) \,, \right. \\ \left. int \left( \, grid\_size \, /
   69
                                     (grid_size/2), int(grid_size/2), int(grid_size/2)].imag
   71
                                    # Fix matrix y
   72
                                    for j in range(grid_size):
   73
                                                         for k in range(grid_size):
   74
   75
                                                                               if (j = 0 \text{ or } j = int(grid\_size/2)) and k > int(grid\_size/2):
   76
                                                                                                  matrix_y[int(grid_size/2),j,k] *= -1
   77
                                                                                elif j > int(grid_size/2):
   78
                                                                                                    matrix_y[int(grid_size/2), j, k] *= -1
   79
   80
                                    # special points
   81
                                     {\rm matrix\_y}\left[\,{\rm int}\left(\,{\rm grid\_size}\,/2\right), {\rm int}\left(\,{\rm grid\_size}\,/2\right), {\rm int}\left(\,{\rm grid\_size}\,/2\right)\,\right] \,=\, {\rm matrix\_y}\left[\,{\rm int}\left(\,{\rm grid\_size}\,/2\right), {\rm int}\left(\,{\rm grid\_size}\,/2\right)
                                     \verb|grid_size|/2|, \verb|int|(|grid_size|/2|), \verb|int|(|grid_size|/2|)|. imag + 0 J
                                     matrix\_y \left[ int \left( \, grid\_size \, / 2 \right), int \left( \, grid\_size \, / 2 \right), 0 \right] = matrix\_y \left[ \, int \left( \, grid\_size \, / 2 \right), int \left( \, g
   83
                                     (grid_size/2), 0.imag + 0J
                                     matrix_y[int(grid_size/2),0,int(grid_size/2)] = matrix_y[int(grid_size/2),0,
                                     int(grid_size/2)].imag + 0J
                                     matrix_y[int(grid_size/2),0,0] = matrix_y[int(grid_size/2),0,0].imag + 0J
   85
   86
                                    # Generate the components of the displacemnet vectors
   87
                                     s_y = scipy.fftpack.ifftn(matrix_y).real * grid_size **(3/2)
   88
                                     s_x = scipy.fftpack.ifftn(matrix_x).real * grid_size**(3/2)
   89
                                     s_z = scipy.fftpack.ifftn(matrix_z).real * grid_size**(3/2)
   90
   91
   92
                                    # Positions
   93
                                     pos\_x\;,\;\;pos\_y\;,\;\;pos\_z\;=\;np.\,meshgrid\left(\,range\left(\,0\;,\,grid\_size\,\right)\;,range\left(\,0\;,\,grid\_size\,\right)\;,
   94
                                     range(0, grid_size))
   95
   96
   97
                                    # Begin simulation
   98
   99
                                    # Constants for integration
                                     a_{min} = 1/51
100
                                     scale_factors = np.linspace(a_min,1,90,endpoint=False)
101
                                    # List in which the momentum and position
103
                                    # of the first 10 particles is saved.
                                    pos\_top\_10 = list()\#.zeros((10,10))
                                    momentum\_top\_10 = list() \#np.zeros((90,10))
106
                                    # Create the plot
108
                                     for idx, a in enumerate(scale_factors):
                                                         # calculate da
                                                         da = 0
                                                           if idx != 0:
114
                                                                             da = scale_factors[idx] - scale_factors[idx-1]
116
                                                                             \mathrm{d} a \, = \, \mathrm{scale\_factors} \, [\, \mathrm{id} \, x \, ] \, - \, a \text{-min}
118
                                                         # Calculate D(a)
                                                         # Calculate \dot(D)
120
                                                          d = helpers4.calculate_linear_growth(a)
                                                          ddot = helpers4.calculate_linear_growth_dir(a -da/2)
123
124
                                                         # Update position
                                                          pos\_x\_new = (pos\_x + s\_x*d) \% grid\_size
125
                                                          pos_y_new = (pos_y + s_y*d) \% grid_size
126
                                                          pos_z_new = (pos_z + s_z*d) \% grid_size
127
```

```
128
             pos_top_10.append(pos_z_new[0:10,0,0])
129
130
             # Update momentum
131
             p_{-}x \; = \; -(a - da \, / \, 2) \, **2 \; * \; ddot \; *s_{-}x
             p_{y} = -(a-da/2)**2 * ddot*s_{y}
133
             p_z = -(a-da/2)**2 * ddot*s_y
134
135
             momentum\_top\_10.append(p_z[0:10,0,0])
136
138
             # slices
             z_{mask} = np.where(abs(pos_{z_new} - 32) < 0.5)

y_{mask} = np.where(abs(pos_{y_new} - 32) < 0.5)
139
140
             x_mask = np.where(abs(pos_x_new - 32) < 0.5)
141
142
             # Create the plots.
143
144
             # z
145
             plt.scatter(pos_x_new[z_mask], pos_y_new[z_mask], s=1,c='black')
146
             plt.title('a='+str(a))
147
             plt.xlabel('x [Mpc]')
plt.ylabel('y [Mpc]')
148
149
             plt.savefig('./Plots/4d/xy/4d_xy=\{0\}.png'.format(idx))
150
             plt.close()
152
             # у
             plt.scatter(pos_x_new[y_mask], pos_z_new[y_mask],s=1,c='black')
155
             plt.title('a='+str(a))
             plt.xlabel('x [Mpc]')
             plt.ylabel ('z [Mpc]')
             plt.savefig('./Plots/4d/xz/4d_xz={0}.png'.format(idx))
158
             plt.close()
160
             # x
161
             plt.scatter(pos_y_new[x_mask], pos_z_new[x_mask],s=1,c='black')
162
             plt.title('a='+str(a))
163
             plt.xlabel('y [Mpc]')
plt.ylabel('z [Mpc]')
plt.savefig('./Plots/4d/yz/4d_yz={0}.png'.format(idx))
164
165
166
             plt.close()
167
168
        # Plot the momentum and position
169
170
        pos\_top\_10 = np.array(pos\_top\_10)
        momentum\_top\_10 = np.array(momentum\_top\_10)
171
        # Momentum
173
        for i in range (0,10):
174
             plt.plot(scale\_factors\;,\;momentum\_top\_10\,[:\,,i\,]\;,\;label=\;'particle\;'\;+\;str(i)
             plt.xlabel('a')
             plt.ylabel(r'$P_z$')
178
        plt.legend()
        plt.savefig('./Plots/4d_momentum.pdf')
180
        plt.close()
181
182
        # Position
183
        for i in range (0,10):
184
             plt.plot(scale_factors, pos_top_10[:,i], label = 'particle' + str(i+1))
185
             plt.xlabel('a')
186
             plt.ylabel('z')
187
188
        plt.legend()
189
        plt.savefig('./Plots/4d_pos.pdf')
190
        plt.close()
```

./Code/assigment_4.py

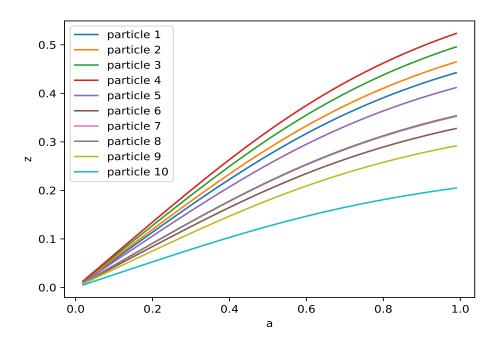


Figure 28: The z-positions of the first 10 particles against the scale factor.

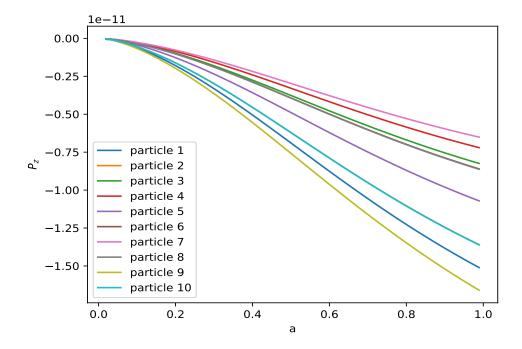


Figure 29: The z-component of the momentum of the first 10 particles against the scale factor.

Question 4 - Summary

Summary

The current sub-section contains the summary of the code used for assignment 4. This includes the part of the main file that executes the subquestions, the relevant imports, the functions to calculate the linear growth factor and the functions used to generate and sort the matrices (tensor).

Code - Assignment

The code with the main function and the function gen_complex, which is called in 4c and 4d.

```
import mathlib.integrate as integrate
  import mathlib.misc as misc
  import mathlib.random as rnd
  import mathlib.helpers4 as helpers4
  import matplotlib.pyplot as plt
  import mathlib.derivative as ml_dir
  import numpy as np
  import scipy.fftpack
  random = rnd.Random(783341)
  def main():
      assigment4_a()
13
      assigment4_b()
      assigment4_c()
15
      assigment4_d()
  def gen_complex(k, power, rand1, rand2):
18
19
20
           Generate a complex number using the power
           spectrum.
21
22
      In:
           param: k -- The magnitude of the wavenumber.
23
           param: n — The order of the power law.
24
25
           param: rand 1 -- A random uniform variable.
26
           param: rand 2 -- A random uniform variable.
      Out:
27
28
           return: A complex number in the fourier plane for the
                   given power law.
29
30
31
      sigma = np.sqrt(k**power)
32
```

./Code/assigment_4.py

Code - Linear growth

The code which calculates the linear growth factor and the derivative of the liner growth factor.

```
 pre\_factor = 0.5*(5*omega\_m)*(omega\_m*a\_max**(-3) + omega\_lambda)**(0.5) 
18
19
20
       # The function to integrate.
       func = lambda \ a: \ a**(-3) \ /(omega_m * (1/(a**3)) + omega_lambda) **(3/2)
21
23
       return pre_factor*integrate.romberg(func, 1e-7, a_max, 15)
24
  def calculate_linear_growth_dir(a, omega_m = 0.3, omega_lambda = 0.7):
25
26
            Calculate the derivative of the linear growth factor
27
28
       In:
            param: a -- The scale factor for which to calculate it.
29
           param: omega_m -- The fraction of matter in the universe.
30
           param: omega_lambda -- The fraction of dark energy in the universe
31
32
           return: The derivative of the scale factor for the given parameters
33
34
       # Hubble constant
35
       H0 = 7.16e - 11
36
37
       # The function to integrate, which appears in the second term.
38
39
       func = lambda \ a: \ a**(-3) \ /(omega\_m \ * \ (1/(a**3)) + omega\_lambda) **(3/2)
40
41
       # The terms in the expression.
42
       pre_factor = (5*omega_m*H0)/(2*a**2)
43
       \label{eq:first_bracked_term} \texttt{first\_bracked\_term} \ = \ 1/(\texttt{omega\_m*a**}(-3) + \texttt{omega\_lambda}) **0.5
44
45
       second_bracked_term = (-3*omega_m*integrate.romberg(func, 1e-7, a, 15))/(2*a)
46
       return pre_factor*(first_bracked_term + second_bracked_term)
```

./Code/mathlib/helpers4.py

Code - Tensor/matrix

The code containing all the function sued to create the matrices (tensors) and make then symmetric.

```
import numpy as np
  def gen_wavenumbers(size, min_distance):
           Generate the shifted wavenumbers
           for the discrete fourier transform.
      In:
           param: size -- The size of the matrix.
          param: min_distance -- The distance of a cell/ the sample spacing.
      Out:
          return: An array with shifted wave numbers.
      # Array to return.
13
      ret = np.zeros(size)
14
      # Positive values
16
      ret [0:int(size/2)+1] = np.arange(0,int(size/2)+1)
17
18
       if size % 2 == 0: # even
19
          ret[int(size/2):] = -np.arange(int(size/2),0,-1)
20
       else: # odd
21
          ret [int(size/2)+1:] = -np.arange(int(size/2),0,-1)
22
23
24
      return (ret/(size*min_distance))*2*np.pi
26
27
  def generate_matrix_2D(size, min_distance, func, random_numbers, power):
28
29
           Generate a 2D matrix with complex numbers in
30
           shifted fourier coordinates using the power spectrum
31
32
           param: size -- The size of the matrix (size x size).
33
```

```
param: min_distance -- The physical size of 1 cell.
           param: func -- A functiion that takes the power and to random uniform
35
36
                          variables to calculate the correct complex number.
           param: random_numbers -- An array with random uniform numbers.
37
                                      Must be of atleast size: size x size x 2.
38
           param: power — The power of the power spectrum to create the matrix for.
39
40
           return: A 2D matrix with complex numbers assigned by the power spectrum
41
                    in fourier shifted coordinates.
42
43
44
       # Generate the shifted wavenumbers
45
       wavenumber = gen_wavenumbers(size, min_distance)
46
47
       # The matrix to return
       ret = np.zeros((size, size), dtype=complex)
48
49
       # A counter for the random uniform variables.
51
       steps = 0
52
       # Fill the matrix
53
       for i in range(size):
54
55
           for j in range(size):
56
57
                # Element of k_0, k_0 is left zero.
                if i = 0 and j = 0:
58
                    continue
59
60
61
                # Calculate the magnitude of the wavenumbers.
                k = np. sqrt (wavenumber [i] **2 + wavenumber [j] **2)
62
                # Fill the matrix.
63
64
                ret[i][j] = func(k, power,
                                 random_numbers[steps], random_numbers[steps+1])
6.5
                steps += 2
66
67
       # Return the matrix
68
       return ret
69
70
   def make_hermitian2D(matrix):
72
73
74
            Give a matrix in shifted fourier coordinates
           the correct hermitian symmetry so that the ifft is real.
75
76
       In:
           param: matrix -- The matrix to give the correct symmetry.
77
       Out:
78
79
           return: A matrix with the correct hermitan symmetry so that the
80
                    ifft is real.
81
82
       # The size of the matrix
83
       size = matrix.shape[0]
84
       # Loop over the rows
86
       for row in range (1, int(size/2) +1):
87
88
           \# Give the first column (index 0) has the correct symmetry (see report
89
       point A)
           matrix [row, 0] = complex (matrix [size-row, 0]. real,
90
                                   - matrix [size-row, 0].imag)
91
           # Give the first row (index 0) the correct symmetry (see report point B)
92
           matrix[0, row] = complex(matrix[0, size-row].real,
93
94
                                  - matrix [0, size - row].imag)
95
           # Give the inner matrix the correct symmetry (see report point C)
96
            for column in range(1, size):
97
98
                matrix [row, column] = complex (matrix [size-row, size-column].real,
                                              -matrix [size-row, size-column].imag)
99
100
       # Corrections for even matrix
101
       if size \% 2 == 0:
           matrix[int(size/2), 0] = matrix[int(size/2), 0].real + 0J
103
```

```
matrix[0, int(size/2)] = matrix[0, int(size/2)].real + 0J
                        matrix[int(size/2), int(size/2)] = matrix[int(size/2), int(size/2)].real
105
               + 0.1
106
               # Return the matrix.
               return matrix
108
111
      def generate_matrix_3D(size, min_distance, func, random_numbers, power):
114
                        Generate a 3D matrix with complex numbers in
                        shifted fourier coordinates using the power spectrum
116
                        param: size -- The size of the matrix (size x size).
118
                        param: min_distance -- The physical size of 1 cell.
119
                        param: func -- A functiion that takes the power and to random uniform
120
                                                      variables to calculate the correct complex number.
                        param: random_numbers — An array with random uniform numbers.
                                                                            Must be of atleast size: size x size x 2.
123
124
                        param: power — The power of the power spectrum to create the matrix for.
125
126
                        return: A 3D matrix with complex numbers assigned by the power spectrum
                                          in fourier shifted coordinates.
129
130
               # Generate the shifted wavenumbers
               wavenumber = gen_wavenumbers(size, min_distance)
               # The matrix to return
132
               ret = np.zeros((size, size, size), dtype=complex)
133
               # A counter for the random uniform variables.
135
               steps = 0
136
               # Fill the matrix
138
               for u in range(size):
140
                        for i in range(size):
141
                                 for j in range(size):
142
143
                                         \# Element of k_{-}0, k_{-}0, k_{-}0 is left zero.
                                          if i = 0 and j = 0 and u ==0:
144
                                                  continue
145
146
                                         # Calculate the magnitude of the wavenumbers.
147
                                          k \, = \, np \, . \, sqrt \, (\, wavenumber \, [\, i \,] **2 \, + \, wavenumber \, [\, j \,] **2 \, + \, wavenumber \, [\, u \,] **2 \, + \, wavenumber \, [\, u \,] **2 \, + \, wavenumber \, [\, u \,] **2 \, + \, wavenumber \, [\, u \,] **3 \, + \, wavenumber \, [\, u \,] **4 \, + \, wavenumber \, [\, u \,] **4 \, + \, wavenumber \, [\, u \,] **4 \, + \, wavenumber \, [\, u \,] **4 \, + \, wavenumber \, [\, u \,] **4 \, + \, wavenumber \, [\, u \,] **4 \, + \, wavenumber \, [\, u \,] **4 \, + \, wavenumber \, [\, u \,] **4 \, + \, wavenumber \, [\, u \,] **4 \, + \, wavenumber \, [\, u \,] **4 \, + \, wavenumber \, [\, u \,] **4 \, + \, wavenumber \, [\, u \,] **4 \, + \, wavenumber \, [\, u \,] **4 \, + \, wavenumber \, [\, u \,] **4 \, + \, wavenumber \, [\, u \,] **4 \, + \, wavenumber \, [\, u \,] **4 \, + \, wavenumber \, [\, u \,] **4 \, + \, wavenumber \, [\, u \,] **4 \, + \, wavenumber \, [\, u \,] **4 \, + \, wavenumber \, [\, u \,] **4 \, + \, wavenumber \, [\, u \,] **4 \, + \, wavenumber \, [\, u \,] **4 \, + \, wavenumber \, [\, u \,] **4 \, + \, wavenumber \, [\, u \,] **4 \, + \, wavenumber \, [\, u \,] **4 \, + \, wavenumber \, [\, u \,] **4 \, + \, wavenumber \, [\, u \,] **4 \, + \, wavenumber \, [\, u \,] **4 \, + \, wavenumber \, [\, u \,] **4 \, + \, wavenumber \, [\, u \,] **4 \, + \, wavenumber \, [\, u \,] **4 \, + \, wavenumber \, [\, u \,] **4 \, + \, wavenumber \, [\, u \,] **4 \, + \, wavenumber \, [\, u \,] **4 \, + \, wavenumber \, [\, u \,] **4 \, + \, wavenumber \, [\, u \,] **4 \, + \, wavenumber \, [\, u \,] **4 \, + \, wavenumber \, [\, u \,] **4 \, + \, wavenumber \, [\, u \,] **4 \, + \, wavenumber \, [\, u \,] **4 \, + \, wavenumber \, [\, u \,] **4 \, + \, wavenumber \, [\, u \,] **4 \, + \, wavenumber \, [\, u \,] **4 \, + \, wavenumber \, [\, u \,] **4 \, + \, wavenumber \, [\, u \,] **4 \, + \, wavenumber \, [\, u \,] **4 \, + \, wavenumber \, [\, u \,] **4 \, + \, wavenumber \, [\, u \,] **4 \, + \, wavenumber \, [\, u \,] **4 \, + \, wavenumber \, [\, u \,] **4 \, + \, wavenumber \, [\, u \,] **4 \, + \, wavenumber \, [\, u \,] **4 \, + \, wavenumber \, [\, u \,] **4 \, + \, wavenumber \, [\, u \,] **4 \, + \, wavenumber \, [\, u \,] **4 \, + \, wavenumber \, [\, u \,] **4 \, + \, wavenumber \, [\, u \,] **4 \, + \, wavenumber \, [\, u \,] **4 \, + \, wavenumber \, [\, u \,] **4 \, + \, wa
148
               ] * * 2)
                                         # Fill the matrix.
149
                                          ret[u][i][j] = func(k, power,
                                                                    random_numbers[steps], random_numbers[steps+1])
                                          steps += 2
               # Return the matrix
154
155
                return ret
156
      def make_hermitian3D(tensor):
160
                        Give a 3D matrix (tensor) in shifted fourier coordinates
161
                        the correct hermitian symmetry so that the ifft is real.
162
               In:
163
                        param: tensor -- The tensor to give the correct symmetry.
164
               Out:
165
                        return: A tensor with the correct hermitan symmetry so that the
                                          ifft is real.
167
               22 22 22
168
169
               # Note: I am fully aware that the loops below can be combined.
                                 The way it is now is however the first way in which I managed
                                 to get it correct and is also the way in which it is easyer to follow
172
```

```
173
174
        size = tensor.shape[0]
175
        # Inner matrix
177
        for row in range(1, size):
178
             for column in range (1, size):
                   for depth in range(1, size):
                        tensor [row, column, depth] = complex(tensor [size-row, size-column,
180
        size-depth].real, -tensor[size-row, size-column, size-depth].imag)
181
        # Outside top
182
        for depth in range (1, int(size/2)+1):
183
              tensor [0,0,depth] = complex (tensor [0,0,size-depth].real, -tensor [0,0,size
185
        -depth].imag)
             tensor [0, depth, 0] = complex (tensor [0, size-depth, 0]. real, -tensor [0, size-
186
        depth, 0].imag)
             tensor [depth, 0, 0] = complex (tensor [size-depth, 0, 0].real, -tensor [size-
        depth , 0 , 0 ] . imag)
188
              # outside inner
190
191
             for column in range(1, size):
                   tensor [depth, column,0] = complex(tensor [size-depth, size-column,0].
192
        real, -tensor[size-depth, size-column,0].imag)
                   tensor [depth, 0, column] = complex (tensor [size-depth, 0, size-column].
193
        real, -tensor[size-depth,0, size-column].imag)
                  tensor[0, depth, column] = complex(tensor[0, size-depth, size-column].
        real, - tensor [0, size-depth, size-column].imag)
195
196
         if size \% 2 == 0:
197
             # Finally fix niquist
198
             for i in range (0, size):
199
                   for j in range(0, size):
200
                        \begin{array}{l} tensor\left[int\left(size/2\right),i,j\right] = tensor\left[int\left(size/2\right),i,j\right].\,real\,+\,0J\\ tensor\left[i,j,int\left(size/2\right)\right] = tensor\left[i,j,int\left(size/2\right)\right].\,real\,+\,0J \end{array}
201
202
                        tensor [i, int(size/2), j] = tensor [i, int(size/2), j]. real + 0J
203
204
         return tensor
```

./Code/mathlib/misc.py

Code - Romberg

The code for romberg integration

```
import numpy as np
  def trapezoid(function, a, b, num_trap):
           Perform trapezoid integration
      In:
          param: function -- The function to integrate.
           param: a — The value to start the integration at.
           param: b -- The value to integrate the function to.
10
          param: num_trap -- The number of trapezoids to use.
12
      Out:
13
          return: An approximation of the integral from a to b of
14
                   the function 'function'
16
18
      # The step size for the integration range.
      dx = (b-a)/num_trap
19
20
      # Find trapezoid points.
21
      x_i = np. arange(a, b+dx, dx)
```

```
# Determine the area of all trapezoids.
        area = dx*(function(a) + function(b))/2
25
        area \hspace{0.1cm} + = \hspace{0.1cm} np.sum(\hspace{0.1cm} function \hspace{0.1cm} (\hspace{0.1cm} x\_i \hspace{0.1cm} [\hspace{0.1cm} 1: num\_trap \hspace{0.1cm}] \hspace{0.1cm}) \hspace{0.1cm} ) \hspace{0.1cm} *dx
26
27
28
        return area
29
30
31
   def romberg(function, a, b, num_trap):
32
33
             Perform romberg integration
34
35
        In:
36
             param: function — The function to integrate.
37
38
             param: a -- The value to start the integration at.
             param: b -- The value to stop the integrate at.
39
             param: num_trap -- The maximum number of initial trapezoid
40
                                      to use to approximate the area.
41
42
        Out:
43
             return: An approximation of the integral from a to b of
44
                       the function 'function'
45
46
47
48
        # The array to store the combined results in.
49
        results = np.zeros(num_trap)
50
51
        # The current combination:
        \# 0 = \text{combine trapezoids}, 1 = \text{combine combined trapezoids},
52
53
        \# 2 = combine the combined combined trapezoids etc.
        for combination in range (0, num\_trap-1):
54
             # Iterate and combine.
56
                \begin{tabular}{ll} for & j & in & range (1, & num\_trap-combination): \\ \end{tabular}
57
                  # Create the initial trapezoids to combine.
58
                   if combination == 0:
59
                         # We need two trapezoids to combine the very first time.
60
                        if j == 1:
61
                             results[j-1] = trapezoid(function, a, b, 1)
62
63
                        results[j] = trapezoid(function,a,b,2**j)
64
65
66
                  # Combine.
                  power = 4**(combination+1)
67
                   results \, [\, j\, -1] \, = \, (\, power * \, results \, [\, j\, ] \, - \, results \, [\, j\, -1]) \, / (\, power \, -1)
68
69
70
        return results [0]
```

./Code/mathlib/integrate.py

5 - Mass assignment schemes

Question 5.a

Problem

The most simple choice for the particle shape is a point like shape given by:

$$S(x) = \frac{1}{\Delta x} \delta\left(\frac{x}{\Delta x}\right) \tag{40}$$

Explain how we need to assign mass to the grid in this scheme and explain why this method is called the Nearest Grid Point (NGP) method. Code up your own implementation of the mass assignment scheme NGP, using a grid of 16^3 . Display x-y slices of the grid with z values of 4,9,11 and 14.

Solution

The easiest way of assigning the mass of the particles to a grid is by assigning it to the grid points. For the given particle shape this would correspond to assigning the full mass of a particle to its nearest gird point, from which the name follows. For other particle shapes, such as the cloud in a cell shape, the mass might be fully assignment to the nearest gird point, but it might also be partially assigned to multiple grid points.

The mass is for the given particle shape assigned to the gird points by abusing the fact that a cast to an integer always result in down a cast (i.e 15.7 casted to an integer gives 15). The indices of a grid point to which a particle has to assign its mass can, by abusing the down cast, be found by adding 0.5 to the position and then down casting the result to an integer. To include circular boundary conditions the modulo with 16 (grid size) is taken.

The code that creates the plots with the slices and the plots can be found below. The code that assigns the mass can be found in the shared module ./Code/mathlib/mass.py on page 73

Code - slices

The code that creates the plots with the slices of the mass grid.

```
assigment_5a():
           Execute assignment 5.a
      # Relevant imports are:
        (1) import numpy as np
        (2) import mathlib.mass as mass
        (3) import matplotlib.pyplot as plt
10
      # Create the positions of the particles.
      np.random.seed(121)
      positions = np.random.uniform(low =0, high=16, size=(3,1024))
13
15
      # Create the mass grid.
      mass_grid = mass._assign_mass_NGP(positions)
17
      # Plot the slices
18
      for z in [4,9,11,14]:
19
           slice = mass\_grid[:,:,z]
20
          \#slice [slice == 0] = np.nan
21
22
           plt.imshow(slice)
23
           plt.colorbar()
           plt.savefig('./Plots/5a_slice_{0}.pdf'.format(z))
25
26
           plt.close()
```

./Code/assigment_5.py

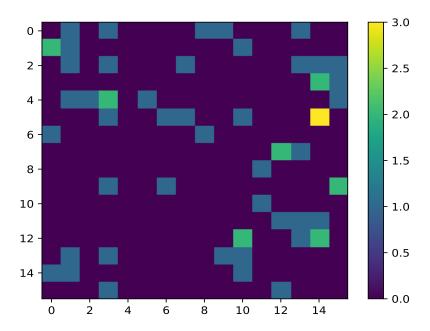


Figure 30: The x-y slice of the created mass grid for z = 4. The color indicates the assigned mass in terms of particle mass.

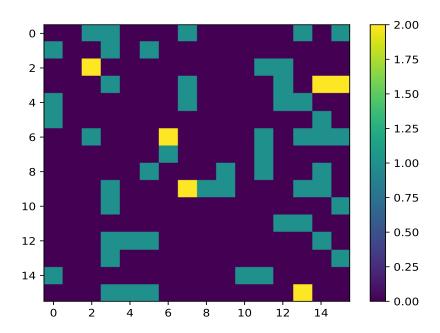


Figure 31: The x-y slice of the created mass grid for z = 9. The color indicates the assigned mass in terms of particle mass. Notice that the range of the colorbar is different from the first and last plot.

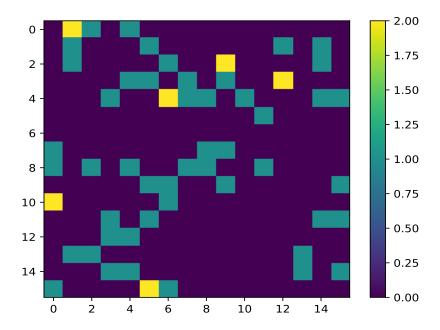


Figure 32: The x-y slice of the created mass grid for z = 11. The color indicates the assigned mass in terms of particle mass. Notice that the range of the colorbar is different than the first and last plot.

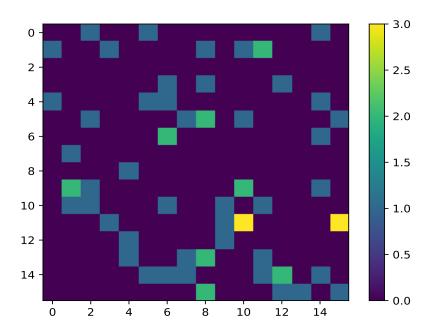


Figure 33: The x-y slice of the created mass grid for z = 14. The color indicates the assigned mass in terms of particle mass.

Question 5.b)

Problem

To check the robustness of your implementation make a plot of the x position of an individual particle and the value in cell 4 in 1 dimension and let x vary from the lowest value to the highest possible value in x. Repeat for cell 0.

Solution

There is not much to explain here, besides that the results for cell 4 and cell 0 are shown in the same plot. The code that creates the plot and the plot can be found below.

Code - Plots

The code that creates the plots for cell 0 and cell 4.

```
def assigment_5b():
          Execute assignment 5.b
      # Relevant imports are:
      # (1) import numpy as np
      # (2) import mathlib.mass as mass
      # (3) import matplotlib.pyplot as plt
      # The x positions of the moving particle
11
      x_values = np.linspace(0, 16, 1000)
13
      # The y positions of the moving particle for
      \# cell 0 and 4
15
      y_values_4 = list()
16
17
      y_values_0 = list()
18
      \# For each position create the mass grid and get the value in cell 4 and 0
19
20
      for x in x_values:
           grid = mass.assign_mass_NGP(np.array([[x],[0],[0]]))
21
22
           y_values_0.append(grid[0,0,0])
23
           y_values_4. append (grid [4,0,0])
25
      # plot the positions
      plt.plot(x_values, y_values_4, label='Cell 4')
26
      plt.plot(x_values, y_values_0, label='Cell 0')
27
      plt xlabel('Positon x')
      plt.ylabel ('Mass in terms of particle mass')
29
30
      plt.legend()
      plt.savefig('./Plots/5b_cell.pdf')
31
      plt.close()
```

./Code/assigment_5.py

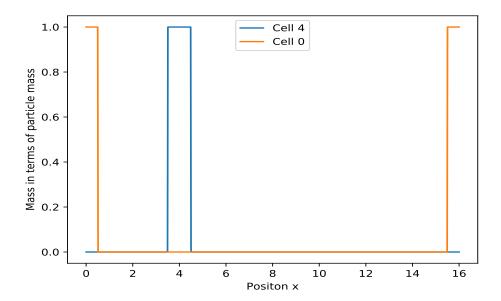


Figure 34: The mass assigned for a particle moving from x = 0 to x = 16. The orange and red line respectively indicate the mass assigned to cells 0 and 4 as function of the position of the particle. The plot is created for a mass grid of size 16 with circular boundary conditions.

Question 5.c)

Problem

Right now we want to improve this method, because NGP has several disadvantages. For this we are going to use a method which assumes that particles are cubes in 3D of uniform density and have the size of a grid cell. Calculatue how mass needs to be assigned in the case of this other method called the Cloud In Cell (CIC) method and implement it in code. To check the robustness of your implementation again make the same plots as before.

Solution

The mass needs to be assigned over the nearest 8 grid points. Each grid point gets thereby a fraction of the cube around the particle. The fraction assigned to a grid point here depends on the position of the particle and might be zero for some of the nearest 8 grid points. The way in which the mass is assigned to the nearest gird points is explained in the comment of the code that assigns the mass (page 73). The code that creates the plots and the plots them self can be found below.

Code - Plots

The code that creates the same plots as in 5.a and 5.b for a 3D grid with the CIC method.

```
assigment_5c():
           Execute assignment 5.c
       # Relevant imports are:
      # (1) import numpy as np
# (2) import mathlib.mass as mass
       # (3) import matplotlib.pyplot as plt
11
       np.random.seed(121)
12
       positions = np.random.uniform(low =0, high=16, size=(3,1024))
13
14
       # Create the mass grid.
       mass_grid = mass._assign_mass_CIC(positions)
16
17
       # Plot the slices.
18
19
       for z in [4,9,11,14]:
           slice = mass\_grid[:,:,z]
20
           #slice[slice == 0] = np.nan
21
22
           plt.imshow(slice)
24
           plt.colorbar()
           plt.savefig('./Plots/5c_slice_{0}.pdf'.format(z))
25
           plt.close()
26
27
      # The x positions of the moving particle
28
       x_values = np.linspace(0, 16, 1000)
29
30
       # The y positions of the moving particle for
31
       # cell 0 and 4
32
       y_values_4 = list()
33
       y_values_0 = list()
34
35
       \# For each position create the mass grid and get the value in cell 4 and 0
36
       for x in x_values:
37
38
           grid = mass.assign_mass_CIC(np.array([[x],[0],[0]]))
           y_values_0.append(grid[0,0,0])
39
40
           y_values_4.append(grid[4,0,0])
41
       # plot the positions
42
       plt.plot(x_values, y_values_4, label='Cell 4')
43
       plt.plot(x_values, y_values_0, label='Cell 0')
44
       plt.xlabel('Positon x')
plt.ylabel('Mass in terms of particle mass')
45
46
       plt.legend()
47
       plt.savefig('./Plots/5c_cell.pdf')
48
49
       plt.close()
```

./Code/assigment_5.py

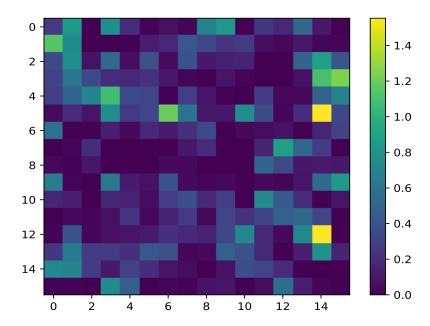


Figure 35: The x-y slice of the created mass grid with the CIC method for z = 4. The color indicates the assignment mass in terms of particle mass. Notice that the range of the colorbar deviates from the other three figures below.

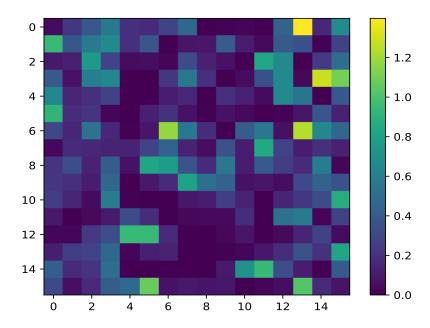


Figure 36: The x-y slice of the created mass grid with the CIC method for z = 9. The color indicates the assignment mass in terms of particle mass. Notice that the scalre of the colorbar deviates from the other three figures.

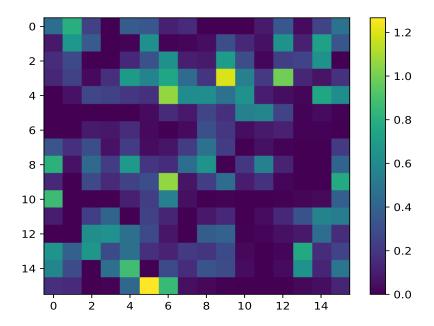


Figure 37: The x-y slice of the created mass grid with the CIC method for z = 11. The color indicates the assignment mass in terms of particle mass. Notice that the color bar deviates from the other three figures.

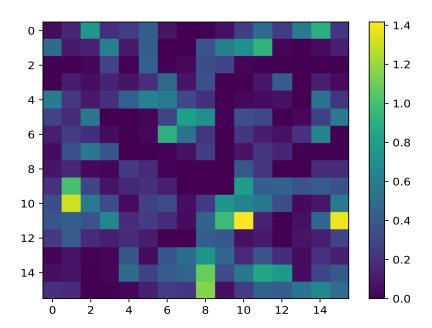


Figure 38: The x-y slice of the created mass grid with the CIC for z = 14. The color indicates the assignment mass in terms of particle mass. Notice that the scale of the colorbar deviates from the other three figures.

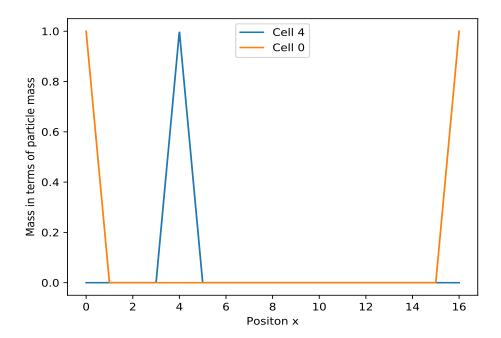


Figure 39: The mass assigned for a particle moving from x = 0 to x = 16 for the cloud in the cell method. The orange and red line respectively indicate the mass assigned to cells 0 and 4 as function of the position of the particle. The plot is created for a 3D mass grid of size 16 with circular boundary conditions.

Question 5.d)

Problem

Write your own FFT algorithm; check that your code works with a 1D function (no Gaussian) by making a plot of the FFt and compare your result with a python package and the analytical FFT of your function. In the rest of this exercise you need to use your own FFT.

Solution

The created implementation of the FFT consist of an recursive implementation with the Cooley-Tukey algorithm. The implementation doesn't store the data inplace, but in a new array. This choice was made to prevent he input array from being modified. One consequence of this choice is that the input array does not have to be reverse bit shifted.

The implementation is compared with the numpy implementation. The function that is chosen to fourier transform is the cosine⁴,

$$\mathcal{F}(\cos(x)] \propto 0.5(\delta(f-x) + \delta(f+x)) \tag{41}$$

The code for the FFT can be found on page 75. The code that compares the self written implementation with the numpy implementation and the analytical solution can be found below.

⁴The given expression contains a proportional sign as the pre-factor depends on the definition of the Fourier transformation.

Code - Plot

The code that creates the plot for the comparison of the self written FFT with the numpy implementation and the analytical solution. The plot can be found below this segment of code.

```
def assigment_5d():
               Execute assignment 5.d
         # Relevant imports are:
         # (1) import numpy as np
         # (2) import matplotlib.pyplot as plt
         # (3) import mathlib.misc as misc
         # (3) import mathlib.fourier as fourier
11
         # Create the data to fourier transform.
12
         size = 64
         t = np.linspace(0, size, size)
15
         f = 5
         y = np.cos(2*np.pi*f*t)
17
18
19
         # Execute the FFT
20
         fft_np = np.fft.fft(y)
21
         fft_self = fourier.fft(y)
23
         \# Frequencies to plot for.
         freq = misc.gen_wavenumbers(size,1)*size
25
26
         \begin{array}{l} plt.\ plot\left(freq\ ,\ abs\left(fft\_np\right),\ label='numpy', linestyle=':',\ zorder=1.1\right)\\ plt.\ plot\left(freq\ ,abs\left(fft\_self\right),\ label='self', zorder=1.0\right)\\ plt.\ vlines\left(-2*np.\ pi*f\ ,0\ ,max\left(abs\left(fft\_self\right)\right)+10, label='Analytical'\right)\\ \end{array}
27
28
29
         plt.vlines(2*np.pi*f,0,max(abs(fft_self))+10)
31
         plt.xlabel('Frequence')
plt.ylabel('Power')
33
         plt.legend()
34
         plt.savefig('./Plots/5d_fourier.pdf')
         plt.close()
```

./Code/assigment_5.py

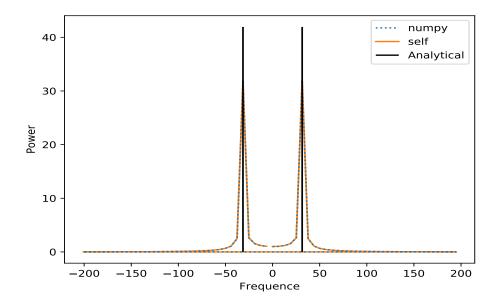


Figure 40: The own implementation of the FFT (orange), the numpy implementation (blue) and the analytical fft (black). The plot shows that there is now visible deviation from the numpy version. It can also be seen that both the numpy and the self written implementation do not correctly represent the peak of the delta function. This is expected as it would require an infinite amount of samples to obtain the exact same result.

Question 5.e)

Problem

Generalize your own FFT algorithm to 2 and 3 dimensions and make a plot of the FFT of a 2D function (no bivariate Gaussian) and compare it with the analytical FFT of your FFT. Also make a plot of the FFT of a 3D multivariate Gaussian function, plot 3 slices centered at the center for the 3 different slice options x-y, x-z,y-z.

Solution

The code for the 2D and 3D implementation makes use of the code for the 1D implementation. In 2D the FFT is first taken over the first axis of the input matrix and then over the second axis. In 3D the FFT2 is first taken over the first axis and then the FFT is taken over the third axis. The code is not generalized to N-dimensions, as the question did not ask to write your own swapaxis algorithm.

The chosen function to 2D fourier transform is $\cos(x+y)$. The analytical result consists of two 2D delta functions. The code that makes the plots for the 2D FFT and the 3D FFT can be found below, the implementation its self can be found on page 75. The plots can be found below the code.

Code - Plot

The code that creates the plots.

```
assigment_5e():
           Execute assigment 5e
      # Relevant imports are:
       \# (1) import numpy as np
       # (2) import matplotlib.pyplot as plt
      # (3) import mathlib.misc as misc
       # (3) import mathlib.fourier as fourier
11
      # The function to 2D fourier transform
12
       func_2d = lambda x, y: np.cos(x+y)
13
       x, y = np. meshgrid(range(0, 64), range(0, 64))
14
       x = np.array(x, dtype=complex)
16
       y = np.array(y, dtype=complex)
17
       =, ax = plt.subplots(nrows=1,ncols=2)
18
19
       # Self written FFT2
20
       ax[0].imshow(abs(fourier.fft2(func_2d(x,y))))
21
       ax[0].set_title("Self written FFT2")
       ax [0]. set_xlabel('index')
ax [0]. set_ylabel('index')
23
24
25
       # Numpy FFT
26
       ax[1].imshow(abs(np.fft.fft2(func-2d(x,y))))
27
       ax[1].set_title("Numpy version FFT2")
28
       ax[1].set_xlabel('index')
29
       ax[1]. set_ylabel('index')
30
31
       plt.savefig('./Plots/5e_2d_fft.pdf',bbox_inches='tight')
32
       plt.close()
33
34
35
       # 3D
       # The multivariate gaussian.
36
       \# I am fully aware that this line looks ugly in the report.
37
       multivariate\_sigma = \frac{lambda}{s} \times y, z, sigma: (1.0/(sigma**2*2*np.pi)**(3/2)) *
38
       np.exp(-(((x**2)/2) + ((y**2)/2) + ((z**2)/2))/sigma**2)
39
40
       \# The multivariate to plot, sigma = 0.5
       multivariate = lambda x, y, z: multivariate\_sigma(x, y, z, 0.5)
41
42
       # Plot the multivariate gaussian
43
       N = 64
44
45
       values = np.arange(0,N)
       values = np.array(values, dtype=complex)
46
       x, y, z = np. meshgrid (values, values, values)
47
48
       matrix = multivariate(x, y, z)
49
50
       matrix_fft = fourier.fft3 (matrix)
51
       # y-z slice
52
       \verb|plt.imshow(abs(matrix_fft[int(N/2)])|)|
53
       plt.xlabel('y')
plt.ylabel('z')
54
5.5
       plt.savefig('./Plots/5e_gaussian_yz.pdf')
56
       plt.close()
57
58
       # x-z slice
59
       plt.imshow(abs(matrix_fft[:,int(N/2),:]))
60
       plt.xlabel('x')
61
       plt.ylabel ('z')
62
       plt.savefig('./Plots/5e_gaussian_xz.pdf')
63
       plt.close()
64
65
       # y-x slice
66
       plt.imshow(abs(matrix_fft[:,:,int(N/2)]))
```

```
plt.xlabel('x')
plt.ylabel('y')
plt.savefig('./Plots/5e_gaussian_xy.pdf')
```

./Code/assigment_5.py

Plot - 2D

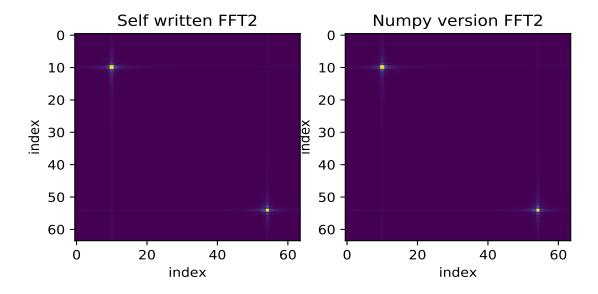


Figure 41: The 2D fourier transformation for the function $\cos(x+y)$. Left, the own implementation of the FFT2 (left) and right the numpy implementation. The results show that the self written version appears to be equal to the numpy version. For the cosine two delta peaks are expected to arise which can also be seen. The peaks are not infinite sharp as that would require an infinite amount of samples.

Plot - 3D

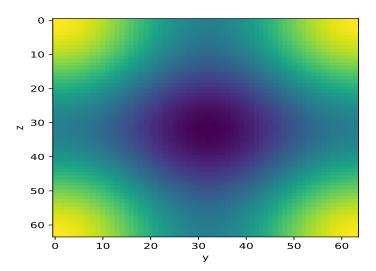


Figure 42: The yz slice around the center of the 3D Fourier transform of a multivariate gaussian with $\mu=0$ and $\sigma=0.5$. The slice should be perfectly symmetric and the result shows that this is indeed the case.

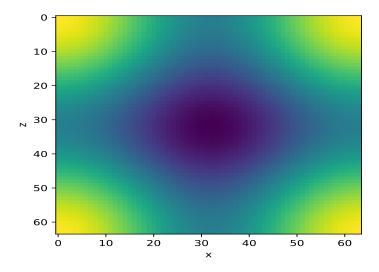


Figure 43: The xz slice around the center of the 3D Fourier transform of a multivariate gaussian with $\mu = 0$ and $\sigma = 0.5$. The slice should be perfectly symmetric and the result shows that this is indeed the case.

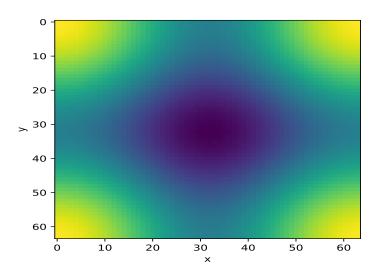


Figure 44: The xy slice around the center of the 3D Fourier transform of a multivariate gaussian with $\mu=0$ and $\sigma=0.5$. The slice should be perfectly symmetric and the result shows that this is indeed the case.

Question 5 - Summary

Summary

The current sub-section contains the summary of the code used for assignment 5. This includes the part of the main file that executes the subquestions, the relevant imports, the functions to assign the mass for the NGP and CIC method and, the code for the Fourier transformations.

Code - Assignment

The code with the main function that executes the sub questions and the relevant imports.

```
import numpy as np
import matplotlib.pyplot as plt
import mathlib.mass as mass
import mathlib.fourier as fourier
import mathlib.misc as misc
```

./Code/assigment_5.py

Code - Mass

The code that assigns the masses for the NGP and CIC method

```
import numpy as np
  def _assign_mass_NGP(positions):
           Create a mass grid of size 16x16 with
           the Nearest Grid Point shape.
           param: positions -- The positions of the N particles as
                                  an matrix of size 2xN.
           return: A matrix representing the mass grid.
13
15
       # Create the empty grid
       mass\_grid = np.zeros((16,16,16))
16
18
       # Add 0.5 and cast to an integer. The positions are now
       # the indices in the grid.
19
       positions = np.array(positions + 0.5, dtype=np.int32)
20
21
       # Assign the masses by looping over the positions
22
       for i in range (0, len (positions [0])):
23
           # Mod 16 for cirulair boundaries.
24
           mass\_grid [\,positions\,[0\,][\,i\,]\,\,\%\,\,16\,,\,\,positions\,[\,1\,][\,i\,]\,\,\%\,\,16\,,positions\,[\,2\,][\,i\,]\,\,\%
25
       16] += 1
26
27
       # Return the mass.
28
       return mass_grid
29
30
  def _assign_mass_CIC(positions):
31
32
33
            Create a mass grid of size 16x16x16 with
           the Nearest Grid Point shape.
34
       In:
35
           param: positions -- The positions of the N particles as
36
37
                                 an matrix of size 3xN.
       Out:
38
           return: A matrix representing the mass grid.
39
40
41
       mass\_grid = np.zeros((16,16,16))
42
43
       for i in range(0, len(positions[0])):
44
45
           # The cube below represents the cube made by the 8 grid points that
46
             enclose a particle. Next we assume that the sides of are side
47
                LTU-
                             –RTY
           #
48
           #
49
           #
50
           # LTD-
                            RTD
51
52
                  LBU-
                             -RBU
           #
           #
54
55
           # LBD -
                          -RBD
```

```
\# Let x_{cell}, y_{cell}, z_{cell} be the position of
58
59
            # the left top bottom (LTB) edge of the Grid Cube that
            # encloses the particle. Let x,y,z be the position of the particle.
60
            # The difference between the particle positon and the LTB edge
61
            # is then given by,
62
            \# dx = x - x_{-} \{ cell \}
63
            \# dy = y - y_{-} \{cell\}
64
            \# dz = z - z_{-} \{ cell \}
65
            # The above quenties can be used to calculate the volumne fractions
66
67
            # that needs to be assigned to the 8 nearest grid points of the cube
            # that the particle represents.
68
            # Working this out (by for example a drawing) gives.
69
70
           # LTD = (1 - dx)*(1 - dy)*(1-dz)
# RTD = (1 - dx)*dy*(1 - dz)
71
72
            \# LTU = (1 - dx)*(1 - dy)*dz
73
            \# RTU = (1 - dx)*dy*dz
74
            \# LBD = dx*(1-dy)*dz
75
            \# RBD = dx*dy*(1-dz)
76
            \# LBU = dx*(1-dy)*dz
77
78
            \# RBU = dx*dy*dz
79
80
           \# Get the indices of the grid point at the left bottom of
            # the cel in which the particle is
81
            center_x = np.int32(positions[0][i]) % 16
82
            center_y = np.int32(positions[1][i]) % 16
83
84
            center_z = np.int32(positions [2][i]) % 16
85
86
            # Helper variables to calculate the
            # volume fractions. Mode 16 for circulair boundary conditions
87
            dx = positions[0][i] \% 16 - center_x
88
            dy = positions[1][i] \% 16 - center_y
89
            dz = positions [2][i] % 16 - center_z
90
91
            frac_dx = 1 - dx
92
            frac_dy = 1 - dy
93
            frac_dz = 1 - dz
94
95
            # Calculate the volume fractions, assume unit particle mass
96
97
           # Left top down
98
            mass\_grid [center\_x] [center\_y] [center\_z] += frac\_dx*frac\_dy*frac\_dz
99
100
            # Right top down
            mass\_grid [center\_x][(center\_y+1) \% 16][center\_z] += frac\_dx*dy*frac\_dz
101
            # Left top up
            mass_grid[center_x][center_y][(center_z+1) % 16] += frac_dx*frac_dy*dz
            # Right top up
            mass\_grid[center\_x][(center\_y+1) \% 16][(center\_z+1) \% 16] += frac\_dx*dy*
106
            #Left bottom down
            mass\_grid [(center\_x + 1) \% 16] [center\_y] [center\_z] += dx*frac\_dy*frac\_dz
108
109
            # Right bottom down
           mass_grid [(center_x+1) % 16][(center_y+1) % 16][center_z] += dx*dy*
       frac_dz
            # Left bottom up
            mass_grid [(center_x+1) % 16] [center_y] [(center_z+1) % 16] += dx*frac_dy*
       dz
            # Right bottom up
           mass_grid [(center_x+1) % 16][(center_y+1) % 16][(center_z+1) % 16] += dx*
114
       dy*dz
       return mass_grid
```

./Code/mathlib/mass.py

Code - Fourier

The code containing the fourier transformations.

```
import numpy as np
  def fft(data):
          Perform the DFT with the cooley-tukey algorithm.
           param: data — The array to fourier transform, must be of length 2**N
      Out:
           return: The fft of the data with the zeroth frequence as the first elment
      # Get the length of the data
      n = len(data)
13
      # The array to return. By using this
16
      # array the input array wont't require
      # a reverse bitshift. This was mainly done
17
18
      # to prevent modifying the input array.
      ret = np.zeros(n, dtype=complex)
19
20
      # The FFT of 1 element is the element self.
21
      if n == 1:
22
           ret[0] = data[0]
23
           return ret
24
25
26
      # Perform the FFT on the even indices and
27
      # odd indices.
      even = fft (data[::2])
28
29
      odd = fft(data[1::2])
30
      # Calculate the recurrent split for the
31
      # values of k. Notice here that
32
      # there is a minus sign, which the result
33
34
      # of symmetry that is exploited.
      for k in range (int(n/2)):
35
36
37
           # Multiply with the complex exponent
           odd[k] = np.exp(-1J*2*np.pi*k/n)
38
39
40
          # Calculate the FFT for the discritized k (or f) values
           ret[k] = even[k] + odd[k]
41
42
           # symmetry exploid
           ret[k+int(n/2)] = even[k] - odd[k]
43
44
45
      # return the fourier transform, don't use a normalization
46
      return ret
47
48
  def fft2(data):
49
50
           Calculate the 2D fourier transformation.
51
52
53
          param: data -- The data to fourier transform
      Out:
54
55
56
57
      for i in range (data.shape [0]):
58
           #kx_0, ky_0, kx_0, ky_1, kx_0, ky_2, kx_0, ky_3
59
           data[i] = fft(data[i])
60
61
      # now perform it over the rows (x direction)
62
63
      for i in range (data.shape [0]):
           \#kx_0, ky_0, kx_1, ky_0, kx_2, ky_0, (store in column)
64
           data[:,i] = fft (data[:,i])
65
66
      return data
67
```

```
69
   def fft3(data):
70
            Perform the 3 dimensionale fourier transform
71
        In:
72
            param: -- The data to fourier transform
73
74
        return: The 3D fourier transform of the data.
75
76
77
       # First fourier transform the planes
for i in range(data.shape[0]):
78
79
            data[i,:,:] = fft2(data[i,:,:])
80
       # Finally fourier transform the last axis.
82
        for i in range (data.shape[2]):
83
            for j in range(data.shape[1]):
    data[:,i,j] = fft(data[:,i,j])
84
85
86
        return data
```

./Code/mathlib/fourier.py

6 - Classifying x-ray bursts

Question 6

Problem

Use logistic regression to make a model of the data, suing a binary classification for short or long GRBs. Explain which properties your model uses to prediced whether a GRB is short or long, and how you handle missing data. Plot a histogram of the class (0 or 1) of GRB and overplot the actual class based on the value of T_{90} .

Solution

The data is before training the model pre-processed as follows. The first stap consists of removing all rows with missing T_{90} (this only consists of two rows). Next, the columns with logarithmic values are taken to the power of an exponent. Finally the values of -1 in the non logarithmic columns and the values of e^{-1} in the logarithmic columns are replaced with 0. The reason that the columns with logarithmic values where first taken to the exponent is because directly replacing -1.0 in such a column with 0 is equivalent to creating your own data. (i.e if $\ln(M_*/M_{\odot}) = 0$, then we would have created data that implies that $M_* = M_{\odot}$).

The columns that where chosen for training consist of the redshift, the star formation rate and the log of the mass ratio. These columns where selected based on a scatter plot made with seaborn in which all columns where plotted against each other. The code for this is not included⁵.

With these columns an accuracy of 78 % was obtained (see page 80). This value is unfortunately the base line that needs to be broken, as in the final dataset 78% of all entries are long GRBS. The model is thus returning '1' for each entry. Attempts to use different combinations of columns always resulted in the same accuracy. The code that creates the histogram and the code for the logistic regression can be found below.

Code - Plot

The code that creates the plots.

```
import numpy as np
  import mathlib. Logistic Regression as lg
  import matplotlib.pyplot as plt
  # Load the data
  \# Column 2 = red_shift, 3 = T90
  data = np.genfromtxt("GRBs.txt")
  # Remove the first 2 columns. These contain 'GRB/XRF' and the number.
  data = data[:,2:]
  data = np.array(data)
  # The columns are now:
  \# 0 = \text{red\_shift}, 1 = \text{T90}, 2 = \log(M^*/M_{sun})
  \# 3 = SFR, 4 = \log(Z/Z_{-}\{sun\}), 5 = SSFR, 6 = AV
  # Remove all rows without T90
  data = data[data[:,1] != -1]
  # Replace all missing data with zero's, but be carefull about
  # the logarithms. To correct the logarithms we take the
20
  # column of a logirhtm to the power of e and then put e^{-1} to zero.
  data[:,2] = np.exp(data[:,2])
23
  data[:,4] = np.exp(data[:,4])
25
  # Correct for missing data
26
  for i in range (0,7):
28
       if i == 2 or i == 4:
          mask = (data[:,i] = np.exp(-1))
29
30
           data[:,i][mask] = 0
       else:
31
          mask = (data[:,i] = -1)
```

⁵I did not had enough time to recreate the plot without seaborn before the deadline.

```
data[:,i][mask] = 0
34
35
36 # The chosen columns are:
37 # - redshift
  \# - \log (M^*/M_{sun})
39
  # - SFR
40 #
  # These are used to create the final data for training the model.
41
  # The final train data consits of the chosen columns plus
43 # one additional column that is all 1 (used for bias)
  # The columns in the dataset to select.
45
  columns = [0, 2, 3]
47
48 | train_data = np.ones((data.shape[0], len(columns)+1))
49 | train_data[:,[0,1,2]] = data[:,columns]
|train\_labels = data[:,1] > 10
52 # Train the model.
  logistic_reg = lg.LogisticRegression(len(columns),1e-3,1e-5)
53
  logistic_reg.train(train_data,train_labels)
55
56
  # Predictions
  predictions = logistic_reg.predict(train_data)
  predictions = np.array(predictions, dtype=int)
60
  #Create the histogram
|bins| = np.arange(0, 1.1, 0.05)
  plt.hist(predictions, alpha=0.9, bins=bins, label='Model', density=True)
63
  plt.hist(np.array(train_labels, dtype=int),bins=bins, label='True', density=True
  plt.legend()
plt.ylabel('Normalized counts')
65
66
  plt.savefig('./Plots/6a_hist.pdf')
68
  # Print the accuracy
  print('[6] Accuracy: ', 1 - np.sum(predictions - train_labels)/len(train_labels))
```

./Code/assigment_6.py

Code - Logistic regression

The code for logistic regression.

```
import numpy as np
  class LogisticRegression(object):
       \begin{array}{lll} \textbf{def} & \texttt{\_init\_\_(self, variables, learn\_rate} = 0.01, \ error = 1e-2): \end{array}
                Create a new instance of a LigisticRegressor
            #weights, also add bias
            self._weights = np.zeros(variables + 1)
            self.\_learn\_rate = learn\_rate
            self._error = error
12
13
14
       def train(self, data, labels):
16
                Train the current logistic regresion model
18
19
20
            # Current error
            error = 1e4
21
22
            # Max iterations
23
            max iter = 1e4
24
            # Current iteration
```

```
curr_iter = 0
27
28
           # Cost of the previous train iteration
           old\_cost = 1e4
29
30
           # While we haven't accuired the required error
31
           # or haven't realced hte maximum number of iterations
32
           # keep training.
33
34
           while error > self._error and curr_iter < max_iter:
35
36
               # Cost and gradient
37
               cost = 0
38
               gradient = np.zeros(self._weights.shape[0])
39
40
               # Calculate the cost and the gradient
41
               for idx in range(0, data.shape[0]):
42
                    y_est = self._sigmoid(np.dot(self._weights, data[idx]))
43
44
                    y = labels[idx]
                    term = -(y*np.log(y_est) + (1-y)*np.log(1-y_est))
45
46
47
                    cost += term
                    gradient += term*data[idx]
48
49
               cost = cost/data.shape[0]
50
               gradient = gradient/data.shape[0]
51
52
53
               # Update the weights
               self._weights += self._learn_rate*gradient
54
55
56
               # Update the error
               error = abs(cost - old_cost)
57
               old\_cost = cost
58
               curr\_iter += 1
59
60
61
       def predict(self, data):
62
63
               Predict the labels for the given data.
64
           In:
65
66
               param: -- A matrix where each row represent a row in the data
                          set for which a label needs to be predicted. The last
67
68
                          value of each row must be a 1.
69
               return: An array with predicted labels.
70
71
           labels = list()
72
           for row in data:
73
               labels.append(self._sigmoid(np.dot(self._weights, row))> 0.5)
75
           return np.array(labels)
76
77
78
79
       def _sigmoid(self, x):
80
               Evaluate the sigmoid activation function.
81
           In:
82
               param: x -- The point(s) to evaluate it for.
83
           Out:
84
               return: The sigmoid activation function evaluated at the
85
                        given point(s).
86
           ,, ,, ,,
87
           \# 1e-7 is to correct for exponents that are zero.
88
           # This was needed as some values of columns where taken to the exponent.
89
           return 1/(1+np.exp(-x) + 1e-7)
91
```

./Code/mathlib/LogisticRegression.py

Text - Output

The accuracy obtained by the model.

[6] Accuracy: 0.7811158798283262

./Output/assigment6_out.txt

Plots- Histogram

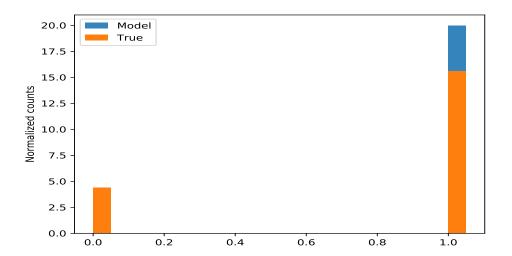


Figure 45: The created histogram for the prediction made by the model and the true labels. It can be seen here that the model always returns '1'.

7 - Building a quadtree

Question 7

Problem

Download the file containing 1200 particle masses and positions. Considering only the x and y coordinates of these particles (between 0 and 150), construct a Barnes-Hut quadtree with at most 12 particles per leaf node. You can treat the masses and positions as dimensionless and use G=1. Plot the particles and indicate which particles are in which node. Calculate the n=0 multipole moment of each leaf and then recursively for each node in the tree. Print the n=0 multipole moment for the leaf node containing the particle with index i=100 and that of all its parent nodes up to and including the root node.

Solution

The zeroth order multipole moment for a leaf node corresponds to the sum of the masses of the particles in that leaf node. The multipole moment of a parent node (can be a parent of a leaf, or of a other non leaf) is the sum of the multipole moment of its children. With this knowledge a quadtree has been constructed that calculates the multipole moment for each of its nodes. The origin of the tree is chosen to be x = 0, y = 0 and corresponds with the left bottom coordinate of the root quad. The size of the root node is chosen to be 150. The root node is thus a quad with edge points: (0,0) (origin), (150,0) right bottom, (0,150) left top, (150,150) right top.

The code for the tree, a plot of the particles in the tree and the multipole moments can be found below. The code is split over two files, the first file contains the code that constructs the quad tree and adds the particles to the tree. The second file contains the code that contains the quad tree its self.

Code - Output

The code that constructs the quad tree and adds the particles to it.

```
import matplotlib.pyplot as plt
  import numpy as np
  import mathlib.quadtree as qt
  # Load the data
  particles_data = h5py. File('colliding.hdf5')['PartType4']
  particles_pos = np.array(particles_data['Coordinates',])
  particles_masses = np.array(particles_data['Masses'])
  # Create a combined array with mass and positions
12 # (I assumend that np.concatenate was not allowed)
particle_info = np.zeros((len(particles_masses),4))
particle_info[:,3] = particles_masses
particle_info[:,2] = particles_pos[:,2]
16 particle_info[:,1] = particles_pos[:,1]
  particle_info[:,0] = particles_pos[:,0]
19
  \# Create an instance of the quad tree with origin (0,0)
  # size 150 and max 12 particles per node.
20
  tree = qt.QuadTree((0,0), 150, 12)
  # Add the particles to the tree.
23
  for particle in particle_info:
24
      tree.add_boddy(particle)
26
  # Before creating the plot, plot the particle with
27
29 plt. scatter (particle_info [100,0], particle_info [100,1], c='red', s=100)
  # Create the plot with final particles.
31 tree.plot()
  # Print the moments of the leaf containing the particle with
34 # index 100 and the moment of its parent nodes.
_{35}| tree.print_moments (particle_info [100,0], particle_info [100,1])
```

./Code/assigment_7.py

Code - Tree

The code of the quadtree.

```
import numpy as np
  import matplotlib.pyplot as plt
  import matplotlib.patches as patches
  import matplotlib.collections as collections
  class QuadTree(object):
         An object representing a quad tree
      def __init__(self, left_bottom, size, max_boddies):
11
12
              Create an instance of the quadtree.
          In:
14
              param: left_bottom -- The coordinates of the leftbottom point of
15
                                    the root quad.
              param: size — The size of the root quad.
17
              param: max_boddies -- The maximum amount of boddies to add before
                                     splitting a node.
```

```
21
22
           # Create the root quad.
           self._root = Quad(left_bottom, size, max_boddies, None)
23
24
25
      def add_boddy(self, boddy):
26
              Add a boddy to the tree.
27
           In:
28
              param: boddy -- The boddy to add.
29
30
31
           # Add the boddy to the root node
32
33
           self._root.add_boddy(boddy)
34
      def find_leaf(self, pos_x, pos_y):
35
36
               Find the leaf node that contains the specific positon.
37
38
           In:
               param: pos_x -- The x coordinate of the position.
39
               param: pos_y -- The y coordinate of the position.
40
41
           Out:
           return: The leaf node that contains the specific positon.
42
43
44
           # Start by assuming that the root node is the node.
45
           leaf = self._root
46
47
           # If it has children find the child containing the position.
48
49
           while not leaf._leaf:
               leaf = leaf._find_quad(pos_x, pos_y)
50
51
           # return the quad that contains the current position.
52
           return leaf
53
54
      def print_moments(self, pos_x, pos_y):
55
56
57
               Print the multipole moment for the leaf node
               and al its parents that contain the given positon.
58
           In:
59
60
               param: pos_x -- The x coordinate of the position.
               param: pos_y -- The y coordinate of the position.
61
62
63
           # Find the leaf that contains the given position.
64
65
           leaf = self.find_leaf(pos_x, pos_y)
66
           # Print the mulitpole moment of the leaf
67
           print(leaf._moment)
68
69
           # Iterate through its parents and print the
70
           # multipole moment of the parents
71
           parent = leaf._parent
72
73
           # Only root doesn't have a parent, thus abort
74
           # when parent is root.
75
           while parent .-parent != None:
76
77
               print ( parent . _moment )
78
               parent = parent._parent
79
           # Don't forget printing the moment of the root node.
80
81
           print ( parent . _moment )
82
      def plot(self):
83
               Create a visual representation of the quad tree
85
               and the boddies added to the tree.
86
87
88
          # The axis used for plotting
           axis = plt.gca()
```

```
# An list that contains rectangle objects (matplotlib.patches.Rectangle)
           # for each of the quads in the tree.
92
93
           rectangles = list()
94
           # Fill the list with rectangles by recursively calling the
95
           # children of the root. If a quad is a leaf it will furtheremore
96
           # axis.scatter. This is to add the boddies of that leaf
97
           # to the plot. The reason that a quad not directly adds its own
98
           # rectangle to the axis (axis.add_patches) is to save time.
99
           self._root._plot(axis, rectangles)
           # Add all the rectangles at once to save time.
102
           axis. add\_collection (\ collections. Patch Collection (\ rectangles\ ,
103
                                 match_original=True))
           # Create and save the plot
106
           plt.xlim(self._root._left_bottom[0],
           self._root._left_bottom [1] + self._root._size)
plt.ylim(self._root._left_bottom [1],
108
                     self._root._left_bottom[1] + self._root._size)
            plt.xlabel('x')
            plt.ylabel('y')
           plt.savefig(''./Plots/7_quadtree.pdf')
113
114
            plt.figure()
115
   class Quad(object):
118
       def __init__(self , left_bottom , size , max_boddies , parent = None):
                Create an instance of a quad in a quadtree.
120
121
           In:
                param: left_bottom -- The coordinates of the leftbottom point of
                                       the quad.
123
                param: size -- The size of the quad.
                param: max_boddies -- The maximum amount of boddies to add before
                                       splitting this quad.
126
               param: parent -- The parent quad if any.
128
129
           # Geometric properties of the current quad
130
            self._left_bottom = left_bottom
            self.\_size = size
            self._halve_size = size/2
134
           # 'Facts' about the quad at the moment of initalization
135
            self._max_boddies = max_boddies
136
            self._leaf = True
            self._parent = parent
138
139
           # An array containing child quads (if any) and
140
           # the boddies in this quad (if it is a leaf).
141
142
           # The child quads are named:
143
           # Left Top (index 0), Left Bottom (index 1)
144
           # Right top (index 2), Right bottom (index 3)
145
            self.\_child\_quads = None
146
            self._boddies = list()
147
148
           # The multipole moment of the current quad.
149
            self.\_moment = 0
150
152
       def add_boddy(self, boddy):
153
                Add a boddy to the current quad or to one of its
                child quads.
           In:
158
                param: boddy -- The boddy to add. Should be an array
                                 in which the first for elemnts respectivelty
                                 correspond with the x-position, y-position,
160
                                 z-positon and mass.
161
```

```
162
163
164
           # If current quad is not a leaf find
165
           # the child quad that should hold the boddy.
166
            if not self._leaf:
167
                self._find_quad(boddy[0], boddy[1]).add_boddy(boddy)
168
169
                return
170
           # Current quad is a leaf and can still add a boddy.
            if len(self._boddies) < self._max_boddies:</pre>
172
                # Add the boddy.
173
                self._boddies.append(boddy)
174
                # Update the multipole moment for this quad.
175
                self.\_update\_moment(boddy[3]) \#index 3 = mass.
176
177
           # Current quad is a leaf, but must split when adding a new boddy.
178
179
                \# The boddy is before splitting first added
180
                # to the current quad. When it splits the boddies
181
                # of this quad will be assigned to the child quads created
182
183
                # in the split.
                self._boddies.append(boddy)
184
                \# Split the current quad and make it a leaf.
185
186
                self._split()
187
188
189
       def _find_quad(self, pos_x, pos_y):
190
191
                Find a child quad that contains the specific
                position.
193
           {\rm In}:
194
                param: pos_x -- The x coordinate of the position.
195
                param: pos_y -- The y coordinates of the position.
196
197
                return: The child quad containing the position. If this
198
                          quad is a leaf, then the quad its self is returned.
199
200
201
202
           # Current quad is a leaf, return its self.
            if self._leaf:
203
204
                return self
205
           # Positon is in the right top or right bottom quad.
206
            if pos_x > self._halve_size+self._left_bottom[0]:
207
                # Position is in the right top quad.
208
                if pos_y >= self._halve_size + self._left_bottom[1]:
209
                    return self._child_quads[2]
210
                # Position is in the right bottom quad.
211
212
                else:
                    return self._child_quads[3]
213
           # Position is in the left top quad.
214
215
            elif pos_y >= self._halve_size + self._left_bottom[1]:
                return self._child_quads[0]
216
           # Position is in the left bottom quad.
218
                return self._child_quads[1]
219
220
       def _split(self):
221
222
                Split the current quad in 4 child quads.
223
224
           # Initialize the array that holds the child wuads.
226
            self._child_quads = list()
227
228
           # Left bottom coordinates of child quads
           \# lt = left top, lb = left bottom, rt = right top, rb = right bottom.
230
            lt \ = \ [\ self.\_left\_bottom\ [0]\ ,
231
                  self._left_bottom[1] + self._halve_size]
232
```

```
lb = self.\_left\_bottom
233
            rt = [self._left_bottom[0] + self._halve_size
234
                  self._left_bottom[1] + self._halve_size]
235
            rb = [self._left_bottom[0] + self._halve_size,
236
                  self.\_left\_bottom[1]
238
            # Add the quads
239
            self._child_quads.append(Quad(lt, self._halve_size,
240
                                       self._max_boddies, self))
241
            self._child_quads.append(Quad(lb, self._halve_size
242
243
                                       self._max_boddies, self))
            self._child_quads.append(Quad(rt, self._halve_size,
244
                                       self._max_boddies, self))
245
            self._child_quads.append(Quad(rb, self._halve_size,
246
                                       self._max_boddies, self))
247
248
            # Current quad is not a leaf anymore
249
            self._leaf = False
250
251
            # Add the boddies of the current quad to the new child quads.
252
            for boddy in self._boddies:
253
254
                self.add_boddy(boddy)
255
            # Empty the boddies that where hold by t his quad.
256
            self.\_boddies = None
257
258
259
       def \_update\_moment(self, mass = 0):
260
                Update the multipole moment of the current quad
261
            In:
262
                praram: mass -- The mass to update the multipole moment with if the
263
                                  current quad is a leaf.
264
265
266
            # Current quad is a leaf, thus
267
            # add the mass (zeroth order multipole moment)
268
269
            if self._leaf:
                self.\_moment += mass
270
            # Current quad is not a leaf.
271
            else:
272
273
                # Reset the multipole moment and recalculate
                # it by looping of the child quads.
274
275
                self._moment = 0
276
                for quad in self._child_quads:
277
                    self.\_moment += quad.\_moment
278
279
            # Make sure the parents of the current quad update the multipole moment.
280
            if self._parent != None:
281
                self._parent._update_moment()
282
283
284
       def -plot(self, axis, quads):
285
286
                Plot the current quad.
287
            In:
288
                param: axis -- The axis object to plot this quad at.
                param: gaudss -- A list of guads at which the current
290
                                   quad should add a rectangle which represents
291
                                   the current quad.
292
            " " "
293
294
            # Create the rectangle to plot of the current quad and add it to the list
295
            rect = patches.Rectangle(self._left_bottom, self._size,
296
                                       self._size, fill=False)
297
            quads.append(rect)
298
299
300
            # If the current quad is a leaf plot the boddies.
            if self._leaf:
301
                if len(self._boddies) == 0:
302
                    return
303
```

```
a = np.array(self._boddies)
axis.scatter(a[:,0],a[:,1],c='blue',s=1)

# If the current quad is not a leaf recursively call this
# method for all its 4 child quads.

else:
for quad in self._child_quads:
quad._plot(axis, quads)
```

./Code/mathlib/quadtree.py

Output - Text

The text output produced by the code. This consists of the multipole moments of the leaf containing the particle with index 100 and its parents. The first line is thus the multipole moment of the leaf containing the particle with index 100 and the last line is the multipole moment of the root.

./Output/assigment7_out.txt

Output - Plot

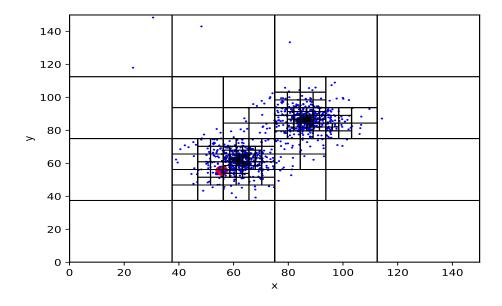


Figure 46: A visual representation of the constructed quadtree. The blue points indicate the positions of the bodies added to the tree. The red point indicates the position of the body with index 100.