

MATH 9878 ASSIGNMENT 5

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1. Problem 1

Show that, under the spot measure, the LMM dynamics has the form given by formula (6) of Lecture Notes 7. Note: you should follow the logic of the calculation that we discussed in class (that was done for the forward measure), with the appropriate numeraire replacing the zero coupon bonds.

Answer:

From the lecture note, we know that the dynamics of $L_j(t)$ is

$$dL_j(t) = \Delta_j(t) + C_j(t)dW_j(t)$$

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, and the drift and instantaneous volatility in this way should be:

$$\Delta_j(t) = \Delta_j(t, L(t))$$

$$C_j(t) = C_j(t, L(t))$$

Assume that the numeraire for measure Q_j is the price $P(t, T_{j+1})$ of the zero coupon bond expiring at T_{j+1} .

Then, let F_i denotes the OIS forward spanning the accrual period $[T_i, T_{i+1})$, and $\gamma : [0, T_N] \rightarrow \mathbb{Z}$, define

$$\gamma(t) = m + 1, \text{ if } t \in [T_m, T_{m+1})$$

,we then have

$$P(t, T_{j+1}) = P(t, T_{\gamma(t)}) \prod_{\gamma(t) \leq i \leq j} \frac{1}{1 + \delta_j F_j(t)}$$

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Note that the numeraire for the spot measure Q_0 is

$$B(t) = \frac{P(t, T_{\gamma(t)})}{\prod_{1 \leq i \leq \gamma(t)} P(T_{i-1}, T_i)}$$

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Since the drift of $L_j(t)$ under Q_j is zero,

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¹Formula 1, Lecture 7.

²Formula 2, Lecture 7.

³Formula 5, Lecture 7.

$$E^P[\exp(\frac{1}{2} \int_0^t \theta(s)^T \theta(s) ds)] < \infty$$

$$dD(t) = \theta(t)^T D(t) dW(t)$$

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, when we switch from Q_j measure to spot measure, $\Delta_j(t)$ becomes

$$\begin{aligned} \Delta_j(t) &= \frac{d}{dt} [L_j, \log \frac{B(t)}{P(t, T_{j+1})}] (t) \\ &= \frac{d}{dt} [L_j, \log (\frac{\frac{P(t, T_{\gamma(t)})}{\prod_{1 \leq i \leq \gamma(t)} P(T_{i-1}, T_i)}}{P(t, T_{\gamma(t)}) \prod_{\gamma(t) \leq i \leq j} \frac{1}{1 + \delta_i F_i(t)}})] (t) \\ &= \frac{d}{dt} [L_j, \log (\frac{1}{\prod_{1 \leq i \leq \gamma(t)} P(T_{i-1}, T_i)} \prod_{\gamma(t) \leq i \leq j} (1 + \delta_i F_i(t)))] (t) \\ &= \frac{d}{dt} [L_j, \log (\frac{1}{\prod_{1 \leq i \leq \gamma(t)} \frac{1}{1 + \delta_i F_i(t)}} \prod_{\gamma(t) \leq i \leq j} (1 + \delta_i F_i(t)))] (t) \\ &= \frac{d}{dt} [L_j, \log \prod_{0 \leq i \leq \gamma(t)-1} (1 + \delta_i F_i(t)) \prod_{\gamma(t) \leq i \leq j} (1 + \delta_i F_i(t))] (t) \\ &= \frac{d}{dt} [L_j, \log \prod_{0 \leq i \leq j} (1 + \delta_i F_i(t))] (t) \end{aligned}$$

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Since $T_i < t$, for $0 \leq i \leq \gamma(t) - 1$, $\prod_{0 \leq i \leq \gamma(t)-1} (1 + \delta_i F_i(T_i))$ is constant .

Then,

$$\begin{aligned} \Delta_j(t) &= \sum_{\gamma(t) \leq i \leq j} dL_j(t) d\log(1 + \delta_i F_i(t)) \\ &= \sum_{\gamma(t) \leq i \leq j} dL_j(t) \frac{\delta_i dF_i(t)}{1 + \delta_i F_i(t)} \\ &= C_j(t) \sum_{\gamma(t) \leq i \leq j} \frac{\rho_{ij} \delta_i C_i(t)}{1 + \delta_i F_i(t)} \end{aligned}$$

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Since the change of measure does not affect the diffusion part,

$$dL_j(t) = C_j(t) [\sum_{\gamma(t) \leq i \leq j} \frac{\rho_{ij} \delta_i C_i(t)}{1 + \delta_i F_i(t)} dt + dW_j(t)]$$

under the spot measure.

⁴Formula 26 & 27, Lecture 2.

⁵Page 9, Lecture 7.

⁶Page 9, Lecture 7

2. Problem 2

Prove the identity stated in formula (32) of Lecture Notes 8.

Answer:

$$\begin{aligned}
I_{(a,b)} + I_{(b,a)} &= \int_t^{t+\Delta} \int_t^s (dZ_a(u)dZ_b(s) + dZ_b(u)dZ_a(s)) \\
&= \int_t^{t+\Delta} \left(\int_t^s dZ_a(u) \right) dZ_b(s) + \int_t^{t+\Delta} \left(\int_t^s dZ_b(u) \right) dZ_a(s) \\
&= \int_t^{t+\Delta} (Z_a(s) - Z_a(t))dZ_b(s) + \int_t^{t+\Delta} (Z_b(s) - Z_b(t))dZ_a(s) \\
&= \int_t^{t+\Delta} Z_a(s)dZ_b(s) - \int_t^{t+\Delta} Z_a(t)dZ_b(s) + \int_t^{t+\Delta} Z_b(s)dZ_a(s) - \int_t^{t+\Delta} Z_b(t)dZ_a(s) \\
&= \int_t^{t+\Delta} Z_a(s)dZ_b(s) + \int_t^{t+\Delta} Z_b(s)dZ_a(s) - Z_a(t) \int_t^{t+\Delta} dZ_b(s) - Z_b(t) \int_t^{t+\Delta} dZ_a(s) \\
&= \int_t^{t+\Delta} [Z_a(s)dZ_b(s) + Z_b(s)dZ_a(s)] - Z_a(t)\Delta Z_b(t) - Z_b(t)\Delta Z_a(t) \\
&= \int_t^{t+\Delta} [Z_a(s)dZ_b(s) + Z_b(s)dZ_a(s)] - 2\Delta Z_a(t)Z_b(t)
\end{aligned}$$

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Apply Ito's Lemma to $Z_a(u)Z_b(s)$, we should have

$$\begin{aligned}
d(Z_a(s)Z_b(s)) &= Z_a(s)dZ_b(s) + Z_b(s)dZ_a(s) \\
\Rightarrow Z_a(s)Z_b(s)|_t^{t+\Delta} &= \int_t^{t+\Delta} (Z_a(s)dZ_b(s) + Z_b(s)dZ_a(s))
\end{aligned}$$

Thus, we have

$$\begin{aligned}
I_{(a,b)} + I_{(b,a)} &= \int_t^{t+\Delta} [Z_a(s)dZ_b(s) + Z_b(s)dZ_a(s)] - 2\Delta Z_a(t)Z_b(t) \\
&= Z_a(s)Z_b(s)|_t^{t+\Delta} - 2\Delta Z_a(t)Z_b(t) \\
&= (Z_a(t) + Z_a(t)\Delta)(Z_b(t) + \Delta Z_b(t)) - Z_a(t)Z_b(t) - 2\Delta Z_a(t)Z_b(t) \\
&= \Delta Z_a \Delta Z_b
\end{aligned}$$

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3. Problem 3

Show that the dynamics of LMM satisfies the integrability condition (30) (or (31)) of Lecture Notes 8, and it thus can be numerically implemented by means of Milstein's scheme.

Answer:

Rewrite the dynamics of the model in terms of the independent Brownian motions:

$$dL_j(t) = \Delta_j(t)dt + \sum_{1 \leq a \leq d} B_{ja}(t)dZ_a(t)$$

⁷Formula 29, Lecture 8

⁸Formula 32, Lecture 8

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where $B_{ia}(t) = U_{ia}C_i(t)$ ¹⁰ and $Z_a(t)$ are independent Brownian Motions.

$$\mathcal{L}^a B_{ib} = \sum_{1 \leq k \leq n} B_{ka} \frac{\partial B_{ib}}{\partial X_k} = \sum_{1 \leq k \leq n} U_{ka} C_k(t) \frac{\partial U_{ib} C_i(t)}{\partial \mathcal{L}_k}$$

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Since $C_i(t, \mathcal{L}_i(t))$ is a function of t and $L_i(t)$, $\frac{\partial C_i(t)}{\partial L_k} = \begin{cases} 0, & k \neq i \\ \frac{\partial C_i(t)}{\partial \mathcal{L}_i}, & k = i \end{cases}$, U_{ka} is just a coefficient.

Thus, we then should be able to get

$$\begin{aligned} \mathcal{L}^a B_{ib} &= \sum_{1 \leq k \leq n} U_{ka} C_k(t) \frac{\partial U_{ib} C_i(t)}{\partial L_k} \\ &= U_{ia} C_i(t) \cdot U_{ib} \frac{\partial C_i(t)}{\partial \mathcal{L}_i} \\ &= U_{ia} U_{ib} C_i(t) \frac{\partial C_i(t)}{\partial \mathcal{L}_i} \\ \mathcal{L}^b B_{ia} &= \sum_{1 \leq k \leq n} U_{kb} C_k(t) \frac{\partial U_{ia} C_i(t)}{\partial L_k} \\ &= U_{ib} C_i(t) \cdot U_{ia} \frac{\partial C_i(t)}{\partial \mathcal{L}_i} \\ &= U_{ib} U_{ia} C_i(t) \frac{\partial C_i(t)}{\partial \mathcal{L}_i} \\ \Rightarrow \mathcal{L}^a B_{ib} &= \mathcal{L}^b B_{ia} \end{aligned}$$

In this way we proved that the integrability condition is satisfied.

⁹Formula 12, Lecture 7

¹⁰Formula 13, Lecture 7

¹¹Formula 25, Lecture 7