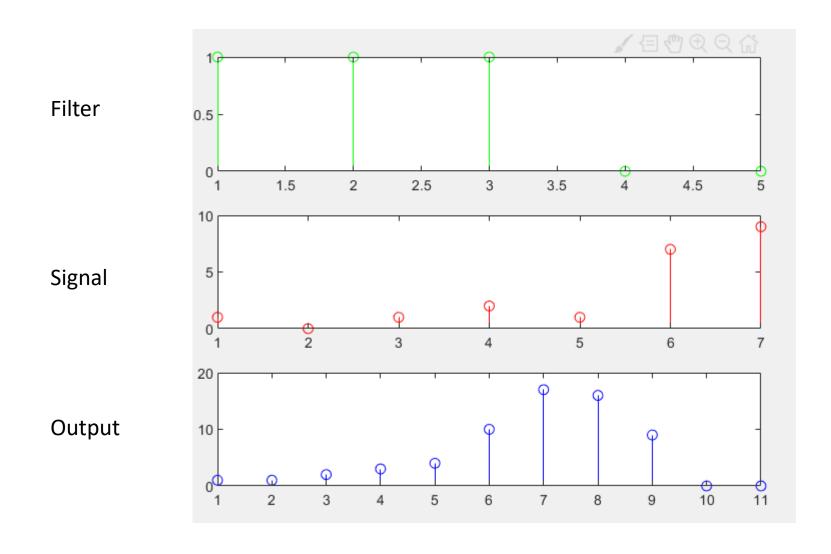
Programmable, Finite Impulse Response (FIR) Filter

Engineered by Bruno E. Gracia Villalobos

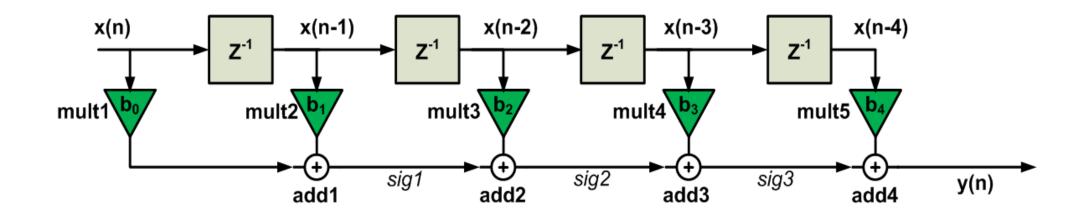
EE 4513

December 2019

WHAT IS A FILTER?



DIRECT FORM I – 4th ORDER FIR FILTER

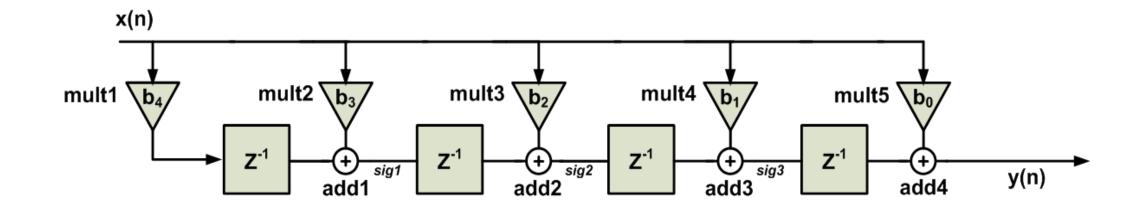


$$y[n] = \sum_{k=0}^{M} h[k]x[n-k]$$

$$y[n] = b4 * x[n-4] + b3 * x[n-3] + b2 * x[n-2] + b1 * x[n-1] + b0 * x[n]$$

After four clock cycles, y[n] sees T = Tmult + 4Tadd

TRANSPOSED, DIRECT FORM I – 4th ORDER



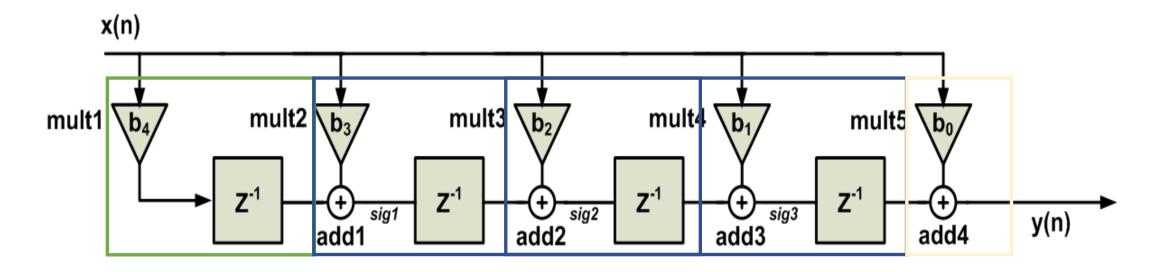
Why?

Increase sampling rate... output y[n] "sees" T = Tmult + Tadd

How?

Reverse all branches without changing functionality. Switch x[n] & y[n] placement.

PROGRAMMABLE....?



GREEN =

- 1 Multiplier
- 1 Register

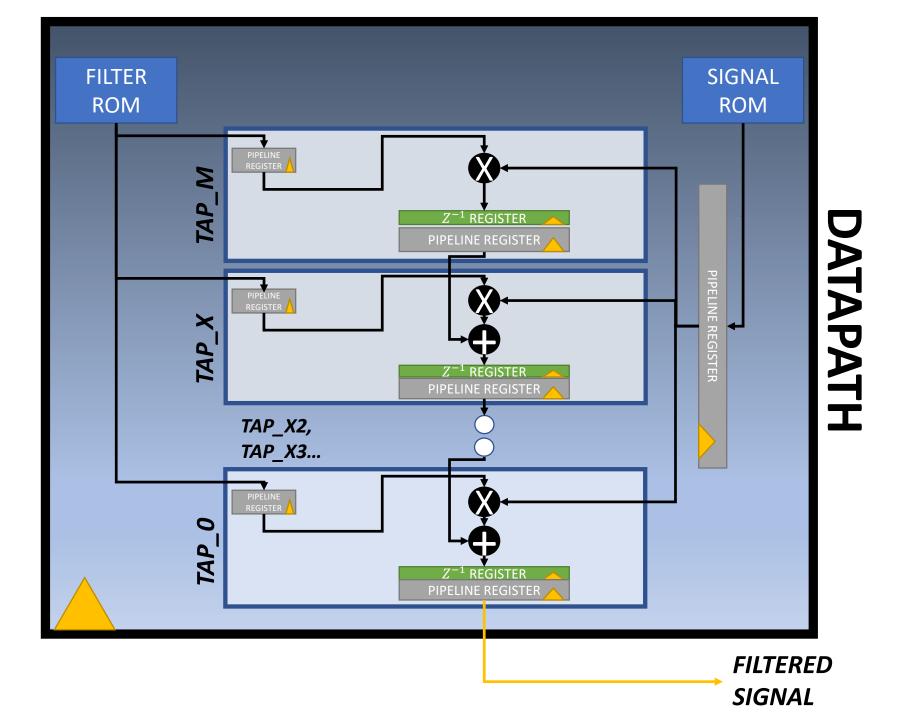
BLUE =

- 1 Multiplier
- 1 Adder
- 1 Register

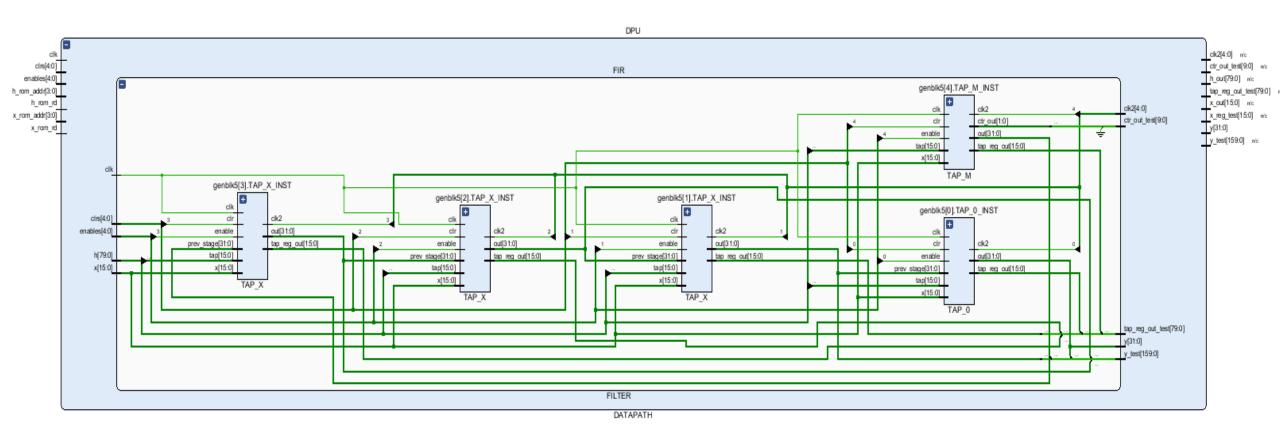
green = 1 # yellow = 1 # blue = M-1

YELLOW =

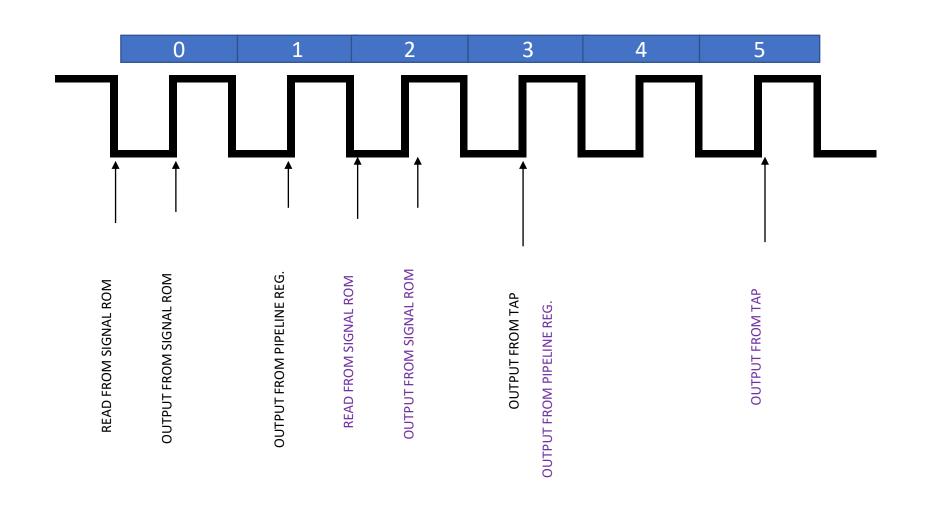
- 1 Multiplier
- 1 Adder

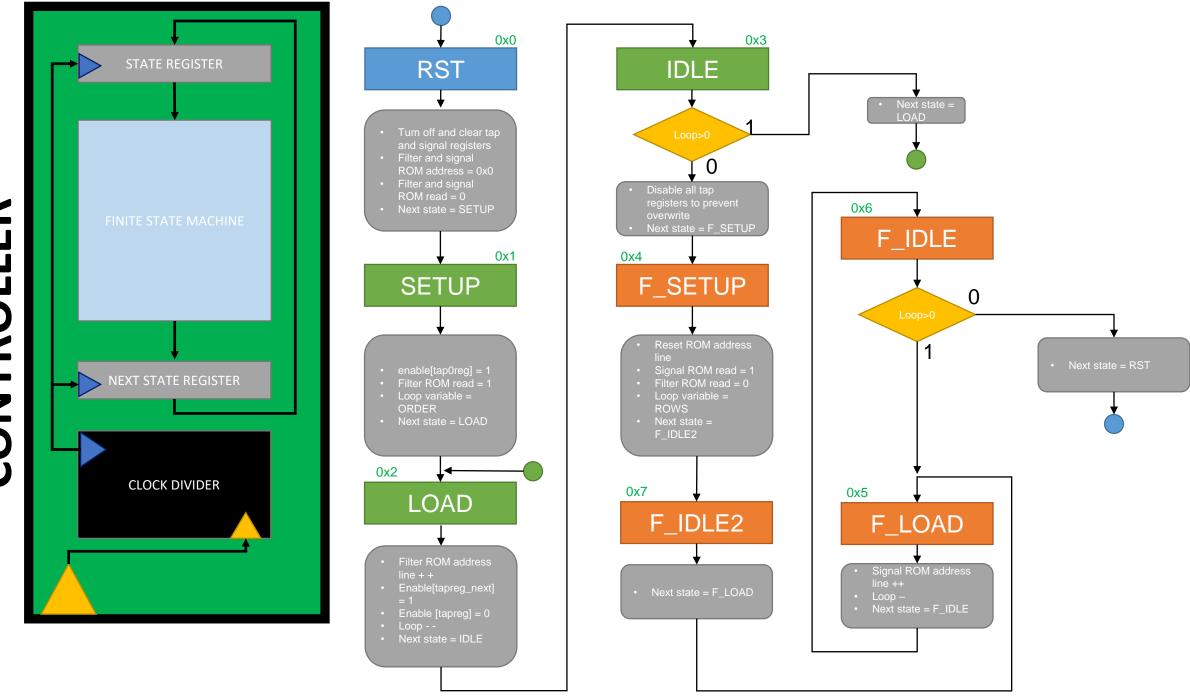


FILTER IN HDL. WHAT IS THE ORDER?



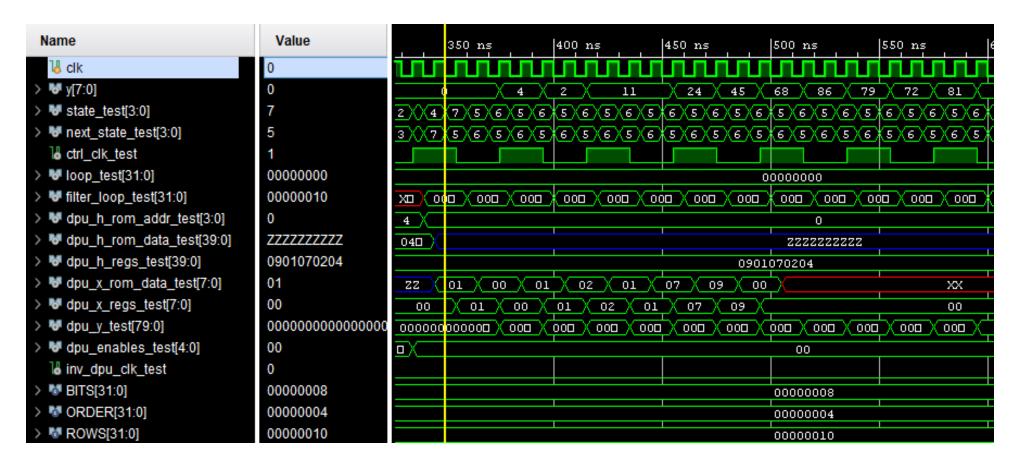
PIPELINE





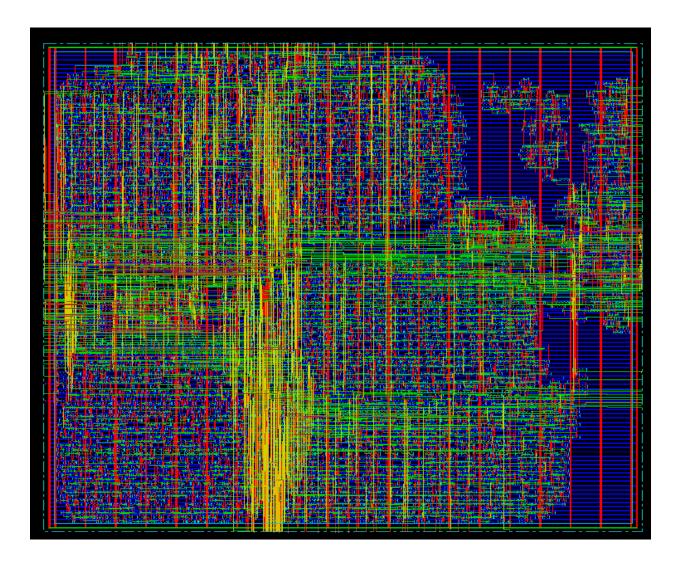
COOL... DOES IT WORK?

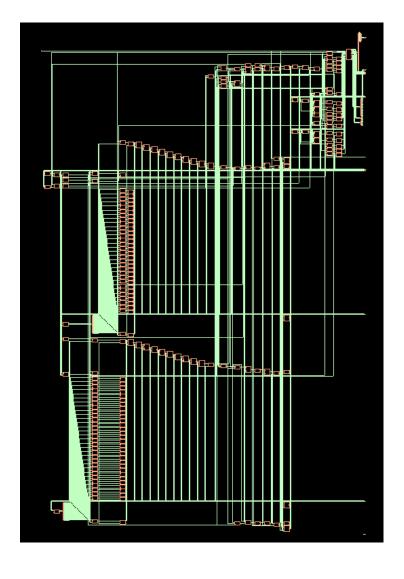
h = [4 2 7 1 9] x = [1 0 1 2 1 7 9] y = [4 2 11 11 24 45 68 86 79 72 81]



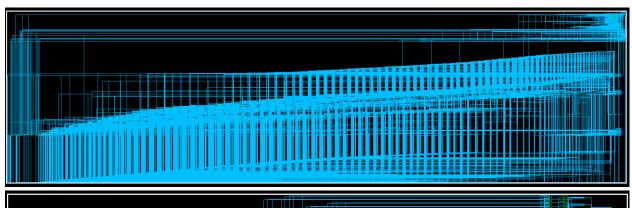
WHERE IS THE MEMORY COMING FROM?

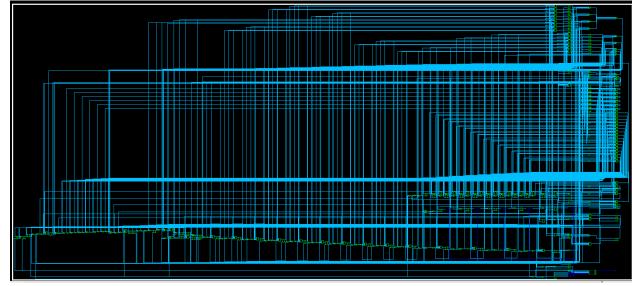
180NM





45 VS 90 NM





	45NM	90NM
TIMING	0.46f	0.61 f
TOTAL AREA	10948.894428	64264.217708
TOTAL POWER	3.8015e-02 mW	181.5616 uW

THANK YOU ALL