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# 1、休眠问题定位

## 1.1、wake\_lock 导致无法休眠

可以通过 `cat /sys/power/wake_lock`（只能看到 Android 的锁无法看到 kernel 中设置的锁）

和 `cat /sys/kernel/debug/wake_source`（有锁都可以看到，即使你通过命令行 `echo xxxxx> /sys/power/wake_lock` 输入的）

```
rk3399:/ # echo xxxxx> /sys/power/wake_lock
rk3399:/ # cat /sys/kernel/debug/wake_sources
```

name	active_count	event_count	wakeup_count	expire_count	active_since	total_time	max_time	last_change
xxxxx	1	1	0	0	1616	1616	1616	70272
NETLINK	24	24	0	0	0	5	1	31743
[timerfd]	2	2	0	0	0	1	1	64068
eventpoll	26	26	0	0	0	0	0	64068
wlan_wd_wake	2	2	0	0	0	0	0	2308
wlan_wake	0	0	0	0	0	0	0	2284
wlan_evt_wake	0	0	0	0	0	0	0	2284
wlan_ctrl_wake	0	0	0	0	0	0	0	2284
wlan_rx_wake	0	0	0	0	0	0	0	2284
rockchip-key	0	0	0	0	0	0	0	2084
rk29-keypad	0	0	0	0	0	0	0	2084
rtw_wifi_scan	0	0	0	0	0	0	0	2039
rtw_wifi_resume	0	0	0	0	0	0	0	2039
rtw_wifi_traffic	0	0	0	0	0	0	0	2039
rtw_wifi_rx	0	0	0	0	0	0	0	2039
rtw_wifi_ext	0	0	0	0	0	0	0	2039
rtw_wifi	0	0	0	0	0	0	0	2039
fe900000.dwc3	0	0	0	0	0	0	0	1720
fe800000.dwc3	0	0	0	0	0	0	0	1710
gpu	3	3	0	0	67861	68364	67861	4027
rockchip_otg	0	0	0	0	0	0	0	1595
rga	0	0	0	0	0	0	0	1592
rfkill_rk_irq_wl	0	0	0	0	0	0	0	1588
rfkill_wlan_wake	0	0	0	0	0	0	0	1586
fe330000.sdhci	0	0	0	0	0	0	0	1553
test_usb	1	1	0	0	0	0	0	1466
test_battery	1	1	0	0	0	0	0	1466
test_ac	1	1	0	0	0	0	0	1466
rk808-rtc	0	0	0	0	0	0	0	760
0-001b	0	0	0	0	0	0	0	728
vpu	1	1	0	0	0	0	0	562
vpu	1	1	0	0	0	1	1	560
iop	1	1	0	0	0	0	0	558
alarmtimer	0	0	0	0	0	0	0	526
serial-debug	1	1	0	0	0	496	496	683
autosleep	0	0	0	0	0	0	0	113
deleted	0	0	0	0	0	0	0	0

```
rk3399:/ #
```

## 1.2、休眠的过程中断产生，或者驱动的休眠函数里面有 wake\_lock

### 1.3、判断出 2S 内会有闹钟中断产生

```
static int alarmtimer_suspend(struct device *dev)
{
    struct rtc_time tm;
    ktime_t min, now;
    unsigned long flags;
    struct rtc_device *rtc;
    int i;
    int ret;

    spin_lock_irqsave(&freezer_delta_lock, flags);
    min = freezer_delta;
    freezer_delta = ktime_set(0, 0);
    spin_unlock_irqrestore(&freezer_delta_lock, flags);

    rtc = alarmtimer_get_rtcdev();
    /* If we have no rtcdev, just return */
    if (!rtc)
        return 0;

    /* Find the soonest timer to expire */
    for (i = 0; i < ALARM_NUMTYPE; i++) {
        struct alarm_base *base = &alarm_bases[i];
        struct timerqueue_node *next;
        ktime_t delta;

        spin_lock_irqsave(&base->lock, flags);
        next = timerqueue_getnext(&base->timerqueue);
        spin_unlock_irqrestore(&base->lock, flags);
        if (!next)
            continue;
        delta = ktime_sub(next->expires, base->gettime());
        if (!min.tv64 || (delta.tv64 < min.tv64))
            min = delta;
    }
    if (min.tv64 == 0)
        return 0;

    if (ktime_to_ns(min) < 2 * NSEC_PER_SEC)
        pm_wakeup_event(ws, 2 * MSEC_PER_SEC);
    return -EBUSY;
}

/* Setup an rtc timer to fire that far in the future */
rtc_timer_cancel(rtc, &rtotimer);
rtc_read_time(rtc, &tm);
now = rtc_tm_to_ktime(tm);
```

2S内就唤醒就不让睡。

### 1.4、实验

在驱动代码的休眠函数中加 wake\_lock 阻止系统休眠（从对应的 log 可以看到，虽然休眠失败，带他会去执行对应驱动 resume 函数）

```

                                IRQF_ONESHOT, -1,
@@ -847,6 +851,20 @@ static int rk808_suspend(struct device *dev)
{
    int i, ret;
    struct rk808 *rk808 = i2c_get_clientdata(rk808_i2c_client);
+   printk("rk808_suspend\n");
+   printk("rk808_suspend\n");
+   printk("rk808_suspend\n");
+   printk("rk808_suspend\n");
+   printk("rk808_suspend\n");
+   printk("rk808_suspend\n");
+   printk("rk808_suspend\n");
+   printk("rk808_suspend\n");
+   printk("rk808_suspend\n");
+   printk("rk808_suspend\n");
+   wake_lock(&rk808_wake_lock);

    for (i = 0; i < suspend_reg_num; i++) {
        ret = regmap_update_bits(rk808->regmap,
@@ -859,6 +877,7 @@ static int rk808_suspend(struct device *dev)
        return ret;
    }
+   printk("rk808_suspend %d-----\n", __LINE__);
    return 0;
}

```

```

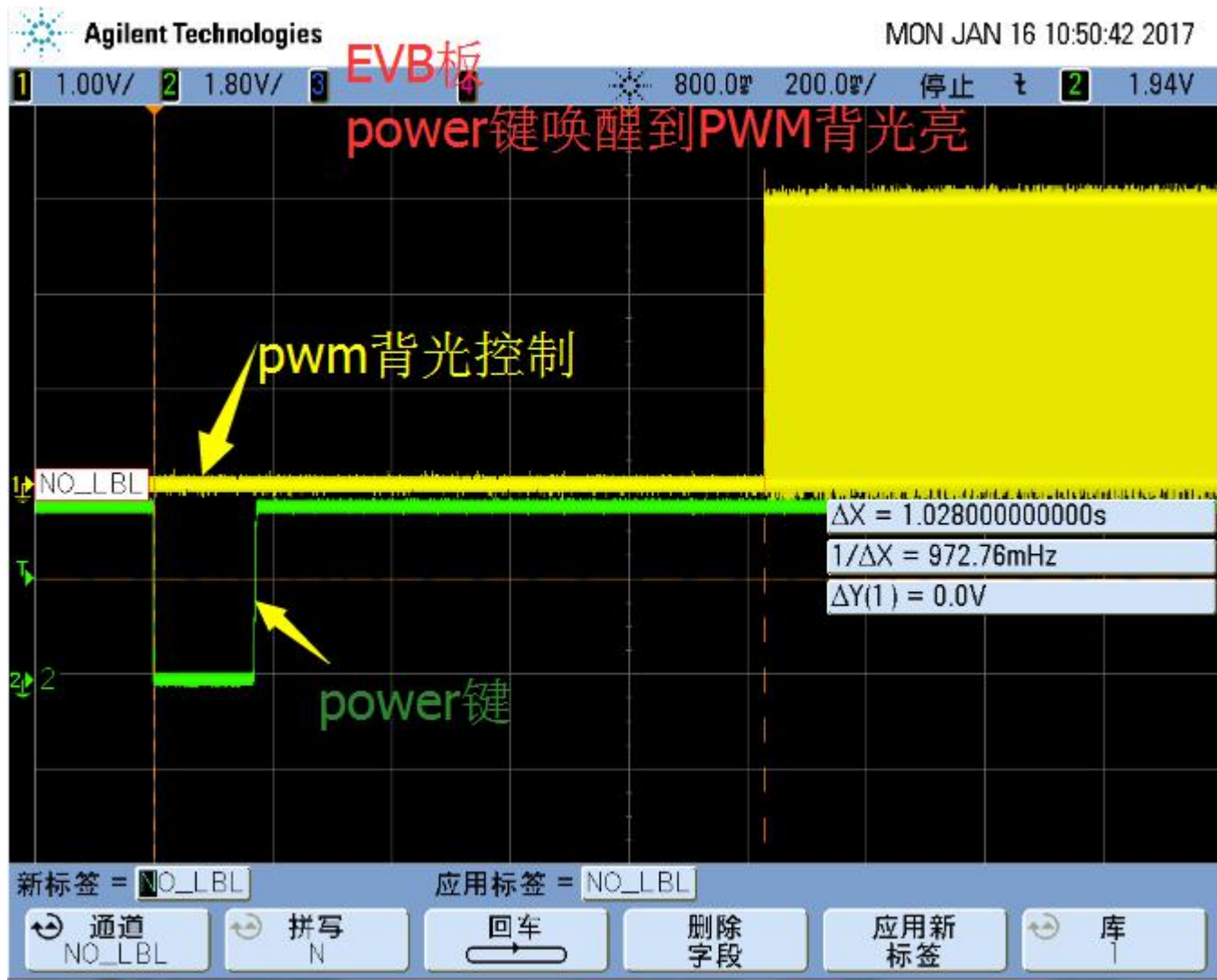
27.140224] suspending console(s) (use no_console_suspend to debug)
27.168483] bcmsdh_sdmmc_suspend Enter func->num=2
27.168508] bcmsdh_sdmmc_suspend Exit
27.168549] bcmsdh_sdmmc_suspend Enter func->num=1
27.180006] rk808_suspend
27.180017] rk808_suspend
27.180026] rk808_suspend
27.180033] rk808_suspend
27.180041] rk808_suspend
27.180048] rk808_suspend
27.180056] rk808_suspend
27.180063] rk808_suspend
27.180070] rk808_suspend
27.180077] rk808_suspend
27.180085] rk808_suspend
27.180092] rk808_suspend
27.180099] rk808_suspend
27.180129] rk808_suspend 880-----
27.180160] PM: wakeup pending, aborting suspend
27.180210] active wakeup source: rk808_wake_lock_test
27.180273] PM: Some devices failed to suspend, or early wake event detected
27.180571] rk808_resume
27.180581] rk808_resume
27.180589] rk808_resume
27.180596] rk808_resume
27.180603] rk808_resume
27.180610] rk808_resume
27.180618] rk808_resume
27.180625] rk808_resume
27.180632] rk808_resume
27.180640] rk808_resume
27.180647] rk808_resume
27.180655] rk808_resume
27.180662] rk808_resume
27.295895] mmc_host mmc2: Bus speed (slot 0) = 50000000Hz (slot req 50000000

```

对应的休眠唤醒函数会执行

## 二、休眠唤醒流程时间

以 rk3399 为例，从按下 power 键到背光 pwm 有波形输出的时间在 972ms。



若发现休眠唤醒时间太长可以通过以下方法定位：

## 2.1、命令行形式定位

```
echo N > /sys/module/printk/parameters/console_suspend
```

```
echo 1 > /sys/power/pm_print_times
```

打印出每个设备休眠的耗时



```

70.672395] calling rfkill2+ @ 277, parent: mmc2:0001:2, cb: rfkill_suspend
70.673053] call rfkill2+ returned 0 after 1 usecs
70.673511] calling rfkill1+ @ 277, parent: phy0, cb: rfkill_suspend
70.674100] call rfkill1+ returned 0 after 0 usecs
70.674576] calling phy0+ @ 180, parent: mmc2:0001:2, cb: wiphy_suspend
70.674604] call phy0+ returned 0 after 6 usecs
70.675607] calling mmc2:0001:3+ @ 277, parent: mmc2:0001, cb: pm_generic_suspend
70.675628] call mmc2:0001:3+ returned 0 after 0 usecs
70.675646] calling mmc2:0001:2+ @ 277, parent: mmc2:0001, cb: pm_generic_suspend
70.675658] bcmsdh_sdmmc_suspend Enter func->num=2
70.675669] bcmsdh_sdmmc_suspend Exit
70.675679] call mmc2:0001:2+ returned 0 after 20 usecs
70.675695] calling mmc2:0001:1+ @ 277, parent: mmc2:0001, cb: pm_generic_suspend
70.675716] bcmsdh_sdmmc_suspend Enter func->num=1
70.675736] call mmc2:0001:1+ returned 0 after 8 usecs
70.675752] calling mmc2:0001+ @ 277, parent: mmc2, cb: mmc_bus_suspend
70.675775] call mmc2:0001+ returned 0 after 4 usecs
70.675790] calling input1+ @ 277, parent: rockchip-key, cb: input_dev_suspend
70.675821] call input1+ returned 0 after 2 usecs
70.680107] calling es8316-sound+ @ 277, parent: platform, cb: platform_pm_suspend
70.680130] call es8316-sound+ returned 0 after 4171 usecs
70.680154] calling dmc+ @ 277, parent: platform, cb: platform_pm_suspend
70.680173] call dmc+ returned 0 after 11 usecs
70.680187] calling fe310000.dwmcc+ @ 277, parent: platform, cb: pm_generic_suspend
70.680297] call fe310000.dwmcc+ returned 0 after 1 usecs
70.736885] calling usb4+ @ 180, parent: fe3e0000.usb, cb: usb_dev_suspend
70.736970] call usb4+ returned 0 after 55234 usecs
70.736999] calling fe3e0000.usb+ @ 277, parent: platform, cb: pm_generic_suspend
70.737102] call fe3e0000.usb+ returned 0 after 14 usecs
70.793279] calling usb3+ @ 180, parent: fe3a0000.usb, cb: usb_dev_suspend
70.793409] call usb3+ returned 0 after 54834 usecs
70.793438] calling fe3a0000.usb+ @ 277, parent: platform, cb: pm_generic_suspend
70.793606] call fe3a0000.usb+ returned 0 after 14 usecs
70.806331] calling usb2+ @ 180, parent: fe3c0000.usb, cb: usb_dev_suspend
70.806331] call usb2+ returned 0 after 13208 usecs

```

## 2.2、打开 DPM\_WATCHDOG\_TIMEROUT

```

Symbol: DPM_WATCHDOG_TIMEOUT [=5]
Type : integer
Range : [1 120]
Prompt: watchdog timeout in seconds
Location:
-> Power management options
-> Device power management core functionality (PM [=y])
-> Power Management Debug Support (PM_DEBUG [=y])
(2) -> Device suspend/resume watchdog (DPM_WATCHDOG [=y])
Defined at kernel/power/Kconfig:211
Depends on: DPM_WATCHDOG [=y]

```

超时时间可配置，但只能精确到秒

```

[ ] Extra PM attributes in sysfs for low-level debugging/testing
[ ] Test suspend/resume and wakealarm during bootup
[*] Device suspend/resume watchdog
(60) watchdog timeout in seconds (NEW)
[ ] Enable workqueue power-efficient mode by default

```

```

--- a/drivers/mfd/rk808.c
+++ b/drivers/mfd/rk808.c
@@ -842,12 +842,12 @@ err_irq:
    regmap_del_irq_chip(client->irq, rk808->irq_data);
    return ret;
}
-
+
+#include <linux/delay.h>
static int rk808_suspend(struct device *dev)
{
    int i, ret;
    struct rk808 *rk808 = i2c_get_clientdata(rk808_i2c_client);
-
+
    mdelay(8000);
    for (i = 0; i < suspend_reg_num; i++) {
        ret = regmap_update_bits(rk808->regmap,
                                suspend_reg[i].addr,

```

```

31.897864] rk808 0-001c: *** DPM device timeout ***
31.898102] [c010f608>] (unwind_backtrace) from [c010b800>] (show_stack+0x10/0x14)
31.898248] [c010b800>] (show_stack) from [c0504c9c>] (dpm_watchdog_handler+0x20/0x4c)
31.898388] [c0504c9c>] (dpm_watchdog_handler) from [c018cb90>] (call_timer_fn+0xa0/0x20c)
31.898514] [c018cb90>] (call_timer_fn) from [c018cf3c>] (run_timer_softirq+0x240/0x2cc)
31.898636] [c018cf3c>] (run_timer_softirq) from [c012a45c>] (__do_softirq+0x138/0x354)
31.898750] [c012a45c>] (__do_softirq) from [c012a900>] (irq_exit+0x88/0xf8)
31.898870] [c012a900>] (irq_exit) from [c017b884>] (__handle_domain_irq+0x8c/0xb0)
31.898986] [c017b884>] (__handle_domain_irq) from [c010142c>] (gic_handle_irq+0x44/0x74)
31.899086] [c010142c>] (gic_handle_irq) from [c010c314>] (__irq_svc+0x54/0x90)
31.899153] Exception stack(0xdc90bbf0 to 0xdc90bc38)
31.899235] bbe0: dc90bc50 3835d96f 00005dbf c05239d4 ddb158d0 ddb34e20 c0ee31e3 c1258f7c
31.899341] bc00: dc90bc50 3835d96f 00005dbf c05239d4 ddb158d0 ddb34e20 c0ee31e3 c1258f7c
31.899434] bc20: c05239d4 dc90bc40 c03c86c0 c010edf4 a00f0113 ffffffff
31.899543] [c010c314>] (__irq_svc) from [c010edf4>] (arch_timer_read_counter_long+0x8/0x18)
31.899674] [c010edf4>] (arch_timer_read_counter_long) from [c03c86c0>] (read_current_timer+0x20/0x38)
31.899794] [c03c86c0>] (read_current_timer) from [c03c8708>] (__timer_delay+0x30/0x6c)
31.899918] [c03c8708>] (__timer_delay) from [c0523a04>] (rk808_suspend+0x30/0xac)
31.900043] [c0523a04>] (rk808_suspend) from [c0504d80>] (dpm_run_callback+0xb8/0x23c)
31.900154] [c0504d80>] (dpm_run_callback) from [c0505b5c>] (__device_suspend+0x254/0x340)
31.900263] [c0505b5c>] (__device_suspend) from [c0507694>] (dpm_suspend+0x12c/0x38c)
31.900373] [c0507694>] (dpm_suspend) from [c0176df0>] (suspend_devices_and_enter+0x78/0x350)
31.900484] [c0176df0>] (suspend_devices_and_enter) from [c0177734>] (pm_suspend+0x66c/0x78c)
31.900585] [c0177734>] (pm_suspend) from [c017591c>] (state_store+0x40/0x68)
31.900691] [c017591c>] (state_store) from [c0297b18>] (kernfs_fop_write+0x148/0x1ac)
31.900804] [c0297b18>] (kernfs_fop_write) from [c0234558>] (__vfs_write+0x2c/0xf4)
31.900907] [c0234558>] (__vfs_write) from [c0234d50>] (vfs_write+0xac/0x17c)
31.901002] [c0234d50>] (vfs_write) from [c0235588>] (sys_write+0x4c/0xa4)
31.901104] [c0235588>] (sys_write) from [c0107180>] (ret_fast_syscall+0x0/0x3c)
31.901322] Kernel panic - not syncing: rk808 0-001c: unrecoverable failure
31.901322]
32.134735] CPU: 0 PID: 547 Comm: system_server Not tainted 4.4.77 #623
32.141381] Hardware name: Rockchip (Device Tree)
32.146180] [c010f608>] (unwind_backtrace) from [c010b800>] (show_stack+0x10/0x14)
32.153998] [c010b800>] (show_stack) from [c03ca7d4>] (dump_stack+0x7c/0x9c)
32.161311] [c03ca7d4>] (dump_stack) from [c01ec0d4>] (panic+0x94/0x208)
32.168265] [c01ec0d4>] (panic) from [c0504cc0>] (dpm_watchdog_handler+0x44/0x4c)
32.175999] [c0504cc0>] (dpm_watchdog_handler) from [c018cb90>] (call_timer_fn+0xa0/0x20c)
32.184515] [c018cb90>] (call_timer_fn) from [c018cf3c>] (run_timer_softirq+0x240/0x2cc)

```

### 三、Pm-test 使用说明：

#### 3.1、/sys/power/pm\_test

可以设置 pm-test 唤醒的间隔时间，默认是 5s

```
rk3399:/ # cat /sys/power/pm_test
```

```
[none] core processors platform devices freezer
```

```
# echo 30 > /sys/module/suspend/parameters/pm_test_delay
```

```
# echo core > /sys/power/pm_test
```

```
# echo mem > /sys/power/state
```







**Suspend.c**

- platform\_suspend
- platform\_suspend
- platform\_suspend
- platform\_resume
- platform\_resume
- platform\_resume
- platform\_suspend
- platform\_resume
- platform\_recover
- platform\_suspend
- pm\_test\_delay
- module\_param
- MODULE\_PARM\_DE
- endif
- suspend\_test
- suspend\_prepare
- arch\_suspend\_dis
- arch\_suspend\_enal
- suspend\_enter
- suspend\_devices
- suspend\_finish
- enter\_state
- pm\_suspend
- EXPORT\_SYMBOL

```
00358:
00359:     printk("%s line = %d\n", __FUNCTION__, __LINE__);
00360:     trace_suspend_resume(TPS("machine_suspend"), state, true);
00361:     freeze_enter();
00362:     trace_suspend_resume(TPS("machine_suspend"), state, false);
00363:     goto Platform_wake;
00364: }
00365:
00366: error = disable_nonboot_cpus();
00367: if (error || suspend_test(TEST_CPUS))
00368:     goto Enable_cpus;
00369:
00370: arch_suspend_disable_irqs();
00371: BUG_ON(!irqs_disabled());
00372: printk("%s line = %d\n", __FUNCTION__, __LINE__);
00373:
00374: error = sync_core_suspend();
00375: if (!error) {
00376:     *wakeup = pm_wakeup_pending();
00377:     if (!suspend_test(TEST_CORE) || *wakeup) {
00378:         trace_suspend_resume(TPS("machine_suspend"),
00379:             state, true);
00380:         error = suspend_ops->enter(state);
00381:         trace_suspend_resume(TPS("machine_suspend"),
00382:             state, false);
00383:         events_check_enabled = false;
00384:     } else if (*wakeup) {
00385:         error = -EBUSY;
00386:     }
00387: }
```

**TEST\_CPUS** Enum Constant in Power.h (i:\rt-kernel\A...\power) at line 211

```
* Suspend test levels
*/
enum {
    /* keep first */
    TEST_NONE,
    TEST_CORE,
    TEST_CPUS,
    TEST_PLATFORM,
    TEST_DEVICES,
    TEST_FREEZER,
    /* keep last */
    __TEST_AFTER_LAST
};

#define TEST_FIRST TEST_NONE
#define TEST_MAX    (__TEST_AFTER_LAST - 1)

extern int pm_test_level;
```

## 3.2、Suspend\_test 说明

kernel/power/suspend\_test.c

注意确保 RTC 的驱动已经加载了。

在 4.4 的 kernel 里面有自带一个 suspend\_test.c 是利用 rtc 定时唤醒系统（自测稳定性），

1、需要再 menuconfig 里面配置这个

-> Power management

options

|  
| -> Device power management core functionality (PM [=y])

| (1) -> Power Management Debug Support (PM\_DEBUG [=y])

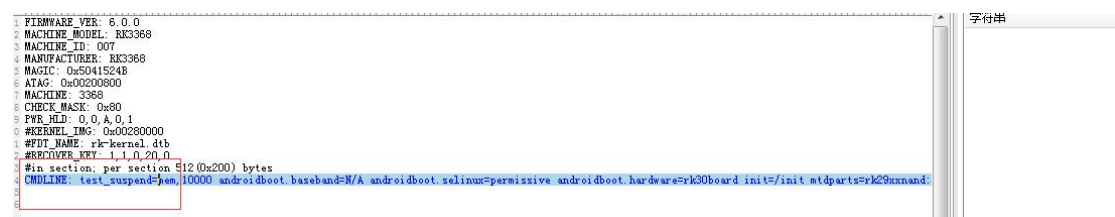
[\*] Test suspend/resume and wakealarm during bootup

2、在 parameter 增加这个属性 test\_suspend=mem,10

test\_suspend=mem,10

这个 10 是拷机的次数，你可以换成 100,1000，

这个功能在平台开发前期会用到（系统没有跑进 Android）



```
FIRMWARE_VER: 6.0.0
MACHINE_MODEL: RK3368
MACHINE_ID: 007
MANUFACTURER: RK3368
MAGIC: 0x5041924b
ATAG: 0x00200800
MACHINE: 3368
CHECK_MASK: 0x80
FWL_REL: 0.0.A.0.1
#KERNEL_IMG: 0x00280000
#FDT_NAME: rk-kernel.dtb
#REDIRECT_KEY: 1_1_0_20_0
Win section: per section 512 (0x200) bytes
CMDLINE: test_suspend=mem,10000 androidboot.baseband=N/A androidboot.selinux=permissive androidboot.hardware=rk30board init=/init mtdparts=rk29xxnand:
```

```

.40:
.41: /*
.42:  * Kernel options like "test_suspend=mem" force suspend/resume sanity tests
.43:  * at startup time. They're normally disabled, for faster boot and because
.44:  * we can't know which states really work in this particular system.
.45:  */
.46: static const char *test_state_label __initdata;
.47:
.48: static char warn_bad_state[] __initdata =
.49:     KERN_WARNING "PM: can't test '%s' suspend state\n";
.50:
.51: static int __init setup_test_suspend(char *value)
.52: {
.53:     int i;
.54:     char *repeat;
.55:     char *suspend_type;
.56:
.57:     /* example: "=mem[,N]" ==> "mem[,N]" */
.58:     value++;
.59:     suspend_type = strsep(&value, ",");
.60:     if (!suspend_type)
.61:         return 0;
.62:
.63:     repeat = strsep(&value, ",");
.64:     if (repeat) {
.65:         if (kstrtou32(repeat, 0, &test_repeat_count_max))
.66:             return 0;
.67:     }
.68:
.69:     for (i = 0; pm_labels[i]; i++)
.70:         if (!strcmp(pm_labels[i], suspend_type)) {
.71:             test_state_label = pm_labels[i];
.72:             return 0;
.73:         }
.74:
.75:     printk(warn_bad_state, suspend_type);
.76:     return 0;
.77: } ? end setup_test_suspend ?
.78: setup("test_suspend" return test_suspend);

```

commandline 里面加一个  
test\_suspend=mem[,1000] 会做1000次休眠唤醒的操作。

## 四、重要的节点

### 4.1、节点/sys/kernel/debug/suspend\_stats

(dev\_pm\_ops 相关的步骤)

查看之前休眠的状态，会总结休眠唤醒成功多少次，失败多少次及在哪一步失败；

```

rk3288:/ # cat /sys/kernel/debug/suspend_stats
success: 1
fail: 0
failed_freeze: 0
failed_prepare: 0
failed_suspend: 0
failed_suspend_late: 0
failed_suspend_noirq: 0
failed_resume: 0
failed_resume_early: 0
failed_resume_noirq: 0
failures:
  last_failed_dev:
    last_failed_errno: 0
    last_failed_step:

```

### 4.2、节点/sys/power/state

```
rk3399:/ # cat /sys/power/state
```

```
freeze mem
```

我们支持 freeze 和 mem 两种休眠方式

可以通过 echo mem > /sys/power/state 可以强制进入休眠；

#### 4.3、节点/sys/power/pm\_wakeup\_irq

获取最近一次唤醒系统的中断号。

#### 4.4、节点/sys/power/pm\_print\_times

Echo 1 > /sys/power/pm\_print\_times 打印每个设备休眠唤醒所用的时间，一般与/sys/module/printk/parameters/console\_suspend 一起操作。

用于调试：

确认对应的休眠函数有没有被调用；

确认休眠和唤醒所用的时间；

#### 4.5、节点/sys/kernel/debug/wake\_source

打印出系统的锁，并可以看到其当前所处的状态，包含驱动和 Android 中的锁；

#### 4.6、节点/sys/module/printk/parameters/console\_suspend

echo N > /sys/module/printk/parameters/console\_suspend 休眠的时候 console 不进休眠状态，可以打印更多 log。