edX

Problem: Drake Installation
Drake Installation

0.0/10.0 points (graded)

Throughout the course, we will use the software toolbox Drake along with MATLAB. Drake contains our best implementations of many of the algorithms taught in the course, as well as code to generate the equations of motion from very simple descriptions of robots. For this Problem Set, we ask that you visit the website at http://drake.mit.edu and follow the installation procedure.

To verify that you were able to install Drake, within MATLAB, cd to the directory "examples/PlanarMonopodHopper" and enter the line "StateMachineControl.run". A simulation should run of a simple hopper. How many times did it hop?

Please describe any problems you encountered during the installation process. To get the points for this problem, you have to write something!

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1
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Press ESC then TAB or click outside of the code editor to exit

Unanswered

Submit