

<http://www.oshwa.org/>

<http://creativecommons.org/licenses/by-sa/3.0/>

Title: PX4FLOW2.1 CAM X0.SchDoc

Date: 29/08/2015

Time: 5:57:20 PM

Sheet:* of: *

Drawn By: Philip Rowse

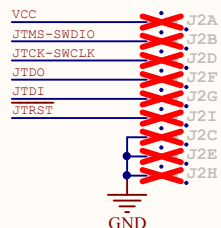
Approved: *

Checked By: *

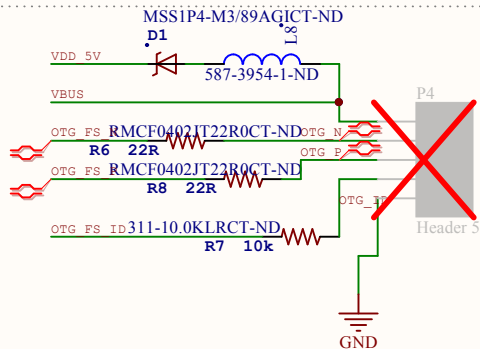


3DRobotics

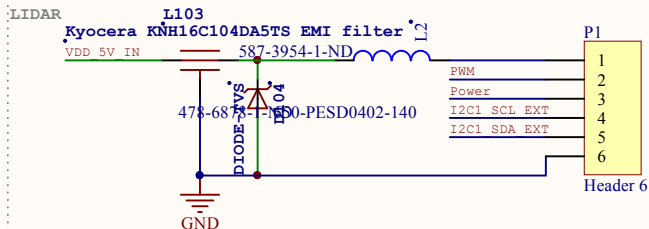
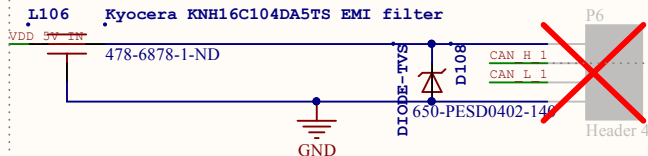
JTAG



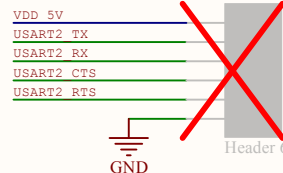
USB



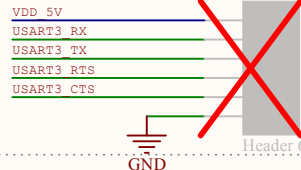
Ports and Connectors




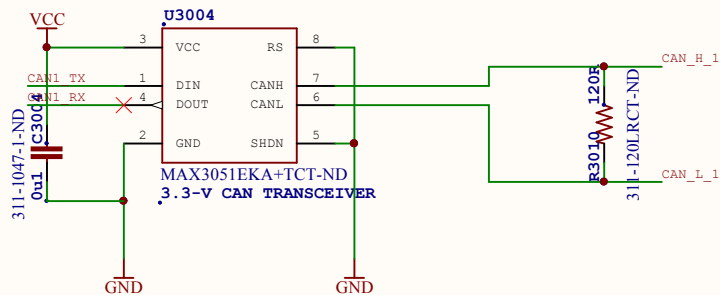
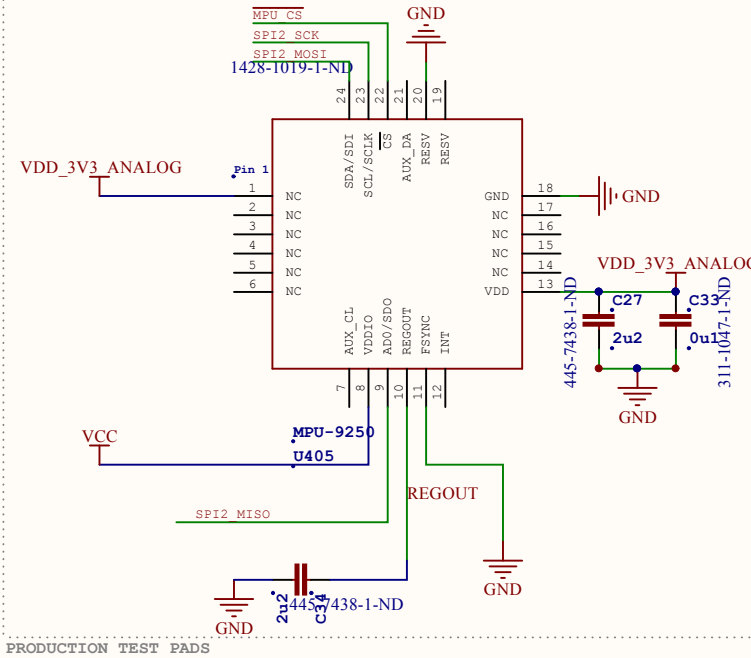
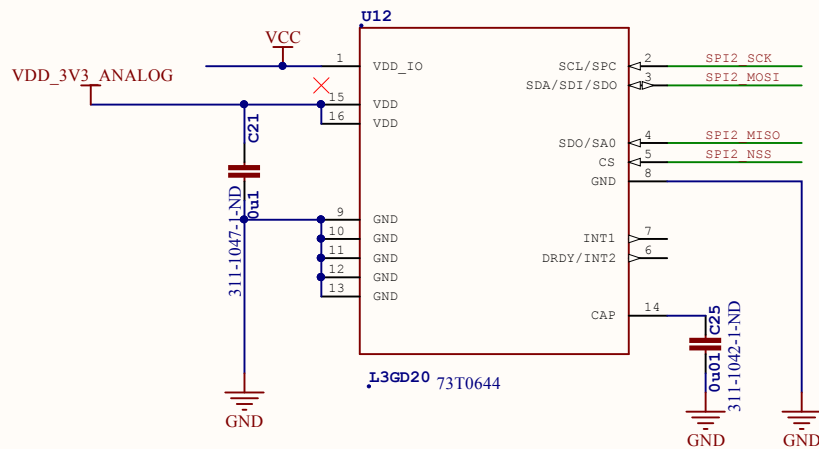
UART2 - MASTER, for radio modems



UART3 - SLAVE, for autopilot connection



Title *			
Size: A4	Number:*	Revision:*	
Date: 29/08/2015	Time: 5:57:20 PM	Sheet* of *	
File: F:\Current Work\00_0 git\Pixhawk OS Hardware\PX4-FLOW-2.1\X0\PX4FLOW2.1 Connectors_X0.SchDoc			



<http://www.oshwa.org/>

<http://creativecommons.org/licenses/by-sa/3.0/>

Title: PX4FLOW2.1 Sensors CAN X0.SchDoc

Date: 29/08/2015

Time: 5:57:21 PM

Sheet: * of: *

Drawn By: Philip Rowse

Approved: *

Checked By: *

