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Title: PX4FLOW2.0 CAM X0.SchDoc

Date: 22/07/2015

Time: 6:38:20 PM

Sheet:* of: *

Drawn By: Philip Rowse

Approved: *

Checked By: *

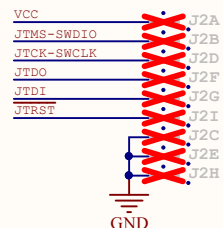


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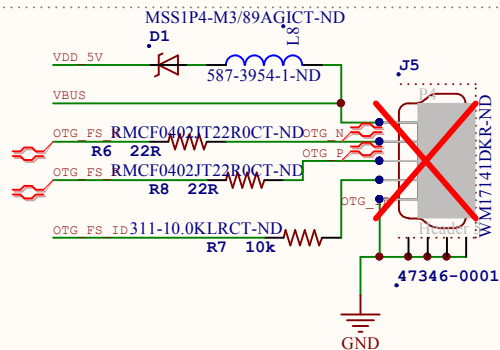
SONAR



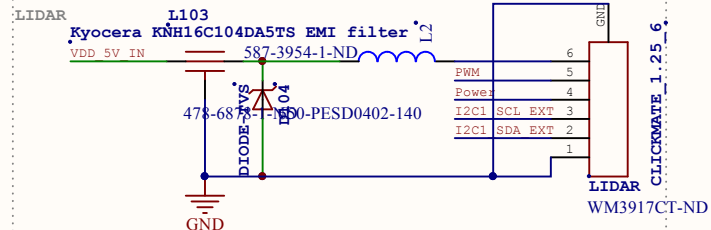
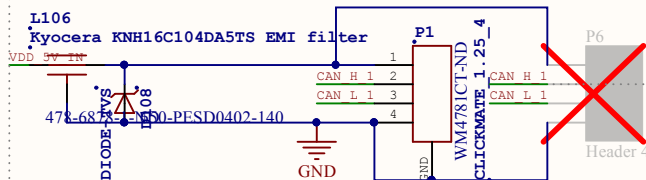
JTAG



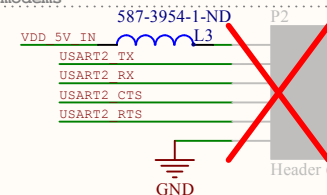
USB



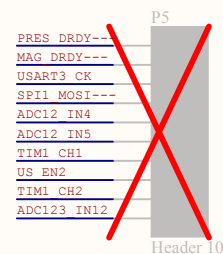
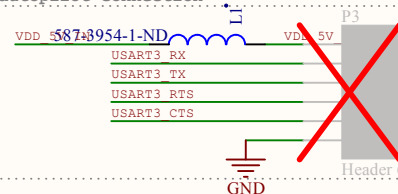
Ports and Connectors



UART2 - MASTER, for radio modems



UART3 - SLAVE, for autopilot connection



Title *

Size: A4

Number:*

Revision:*

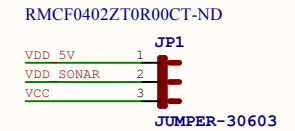
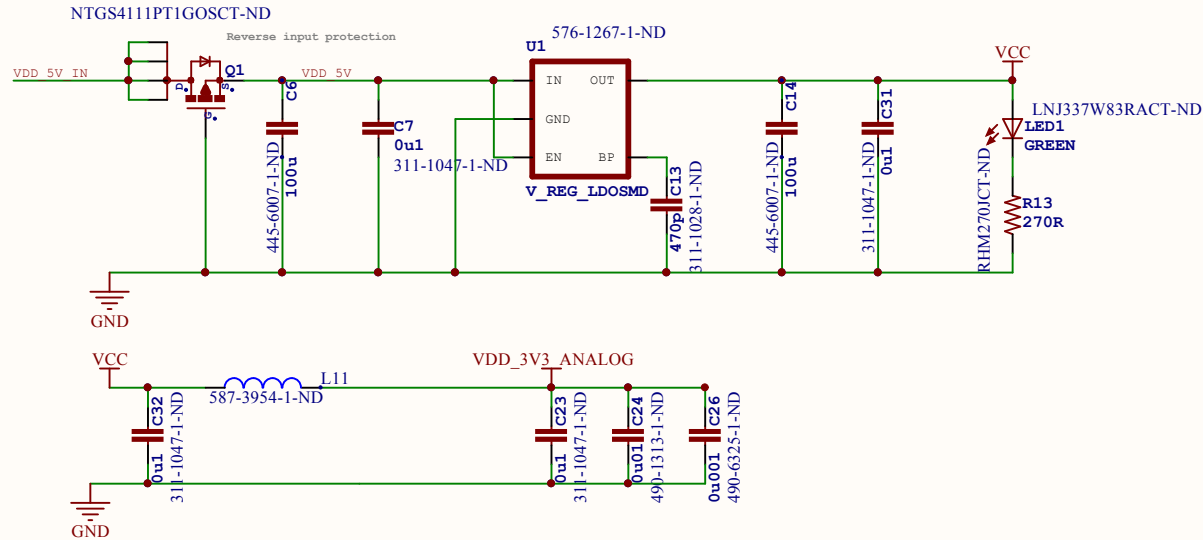
Date: 22/07/2015

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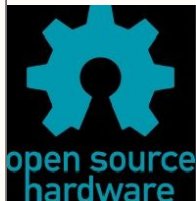
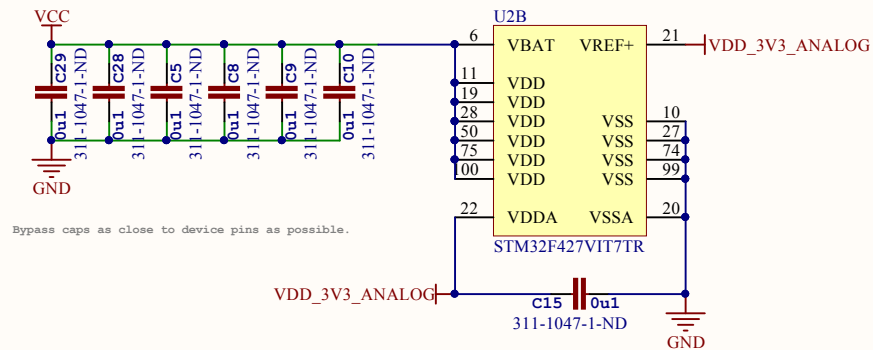
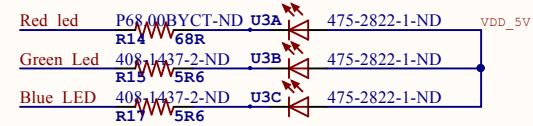
Sheet* of *

File: F:\Current Work\00_0_git\Pixhawk_OS Hardware\PX4_FLOW2.0_X0\PX4FLOW2.0_Connectors_X0.SchDoc






Red	625 nm	20 mA	2.05Vf	1077,5 mcd
Green	523 nm	20 mA	3.2 Vf	1507 mcd
Blue	465nm	20 mA	3.2 Vf	377.5 mcd



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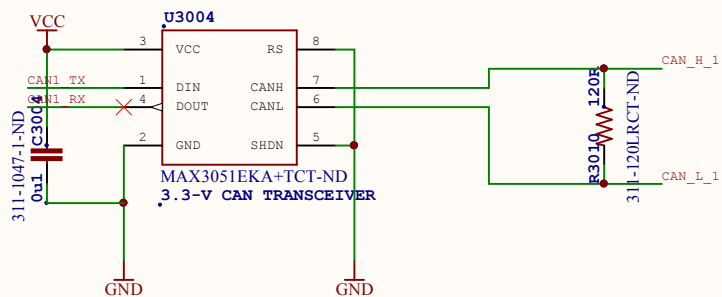
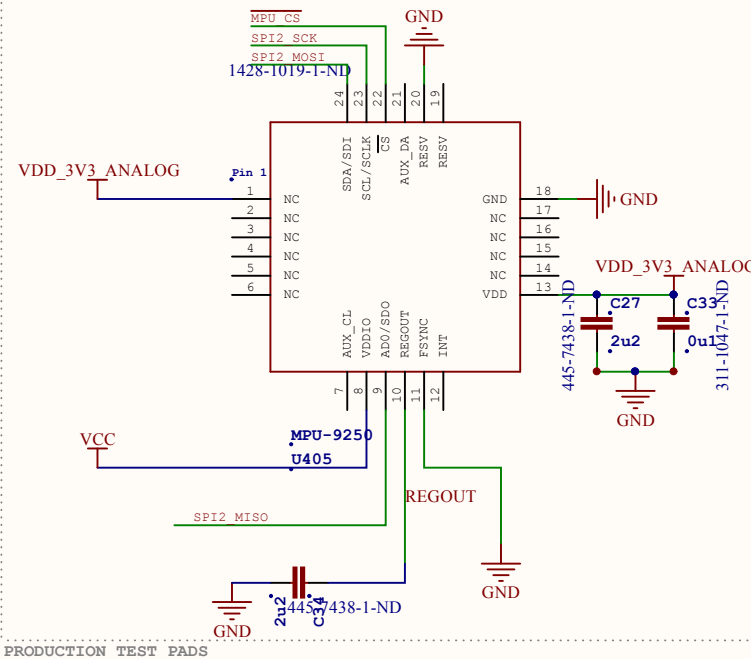
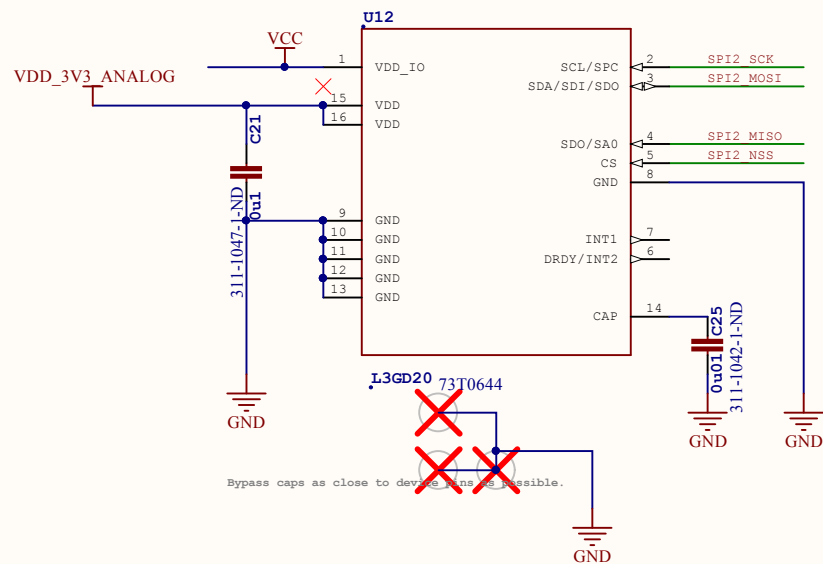
Title: PX4FLOW2.0 Power X0.SchDoc		
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