

Klipper 固件使用说明-Nano V3

—,	准备	1
	1) 硬件板卡准备	1
	2) 镜像文件下载	1
	3) 镜像文件安装	1
	4) 无线网络配置	2
	5) 连接树莓派	2
	6)Octoprint 安装	4
	7)Notepad++安装 NttFTP 插件	5
=,	Klipper 固件下载-设置-编译-更新	6
	1) 下载	6
	2)设置	7
	3)编译	7
	4) 更新	8
三、	Octoprint 初始化-串口设置	9
	1) Octoprint 初始化设置	9
	2) 串口设置	13
四、	Klipper 配置文件	14
	1)printer.cfg 配置文件	14
	2) 基本参数	15
	步进设置	15
	挤出机设置	15
	热床设置	15
	风扇设置	16
	机器设置	16
	EXP1/EXP2 接口	16
	屏幕设置	17
	串口设置	17
五、	Octoprint 连接控制打印机	19
	1) 连接主板控制	19
	2) FIRMWARE_RESTART 指令	20
六、	测试	21
七、	常见问题处理(FAQ)	22
	问题一: make: arm-none-eabi-gcc: Command not found	22
	问题二: Octoprint 终端发送 FIRMWARE_RESTART 无法返回温度	22
	问题三: Octoprint 添加"/tmp/printer"但"Serial Port"选项无法显示	23
八、	附录-相关资料	24



一、准备

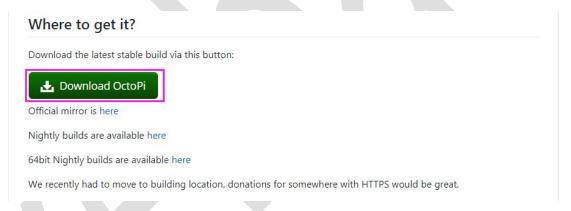
1) 硬件板卡准备

树莓派主板(含无线网卡)、Micro USB 线、方口 USB 线,3D 打印主板(MKS 系列均支持,本文以 MKS Robin Nano V3 为例)、2 张 TF 卡(一张用在树莓派,一张用在主板)、读卡器

2) 镜像文件下载

https://github.com/guysoft/OctoPi

(文件夹: "2019-09-26-octopi-buster-lite-0.17.0.img")

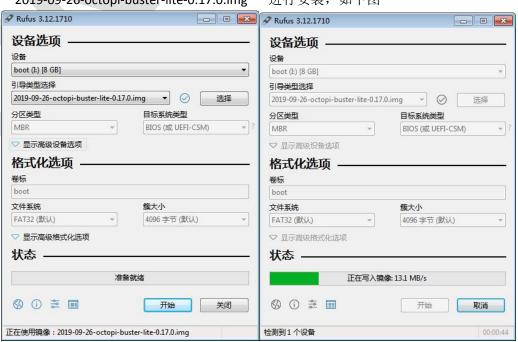


3) 镜像文件安装

(文件夹: 使用工具 "rufus-3.12.exe")

使用 TF 卡,读卡器接在电脑,运行 "rufus-3.12.exe",并选择

"2019-09-26-octopi-buster-lite-0.17.0.img" 进行安装,如下图





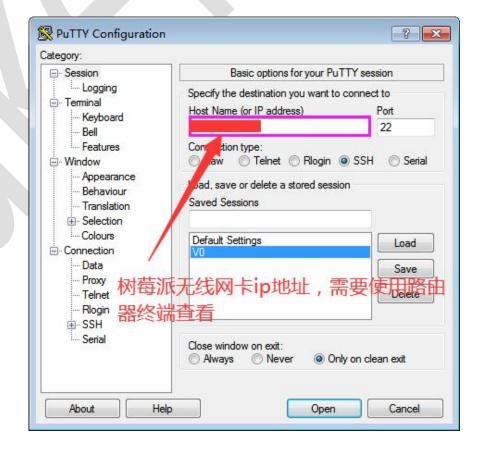
4) 无线网络配置

电脑选择 TF 卡目录,打开"octopi-wpa-supplicant.txt"文件,输入无线网络名称和密码,并取消注释 # 号,设置好后,卡取出,装到树莓派上电,路由器终端查看 Ip 地址。

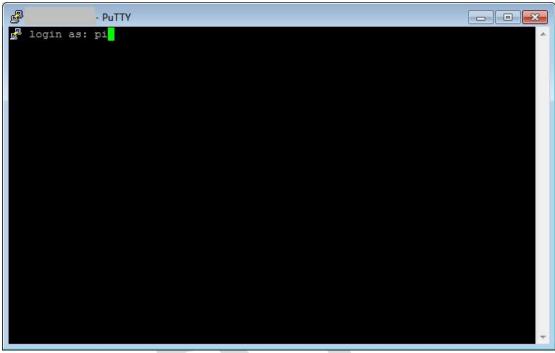
```
🔚 octopi-wpa-supplicant. txt🛚
 16 # configuration won't work. Use a proper text editor instead.
 17
     # Recommended: Notepad++, VSCode, Atom, SublimeText.
     # !!!!! HEADS-UP MACOSX USERS !!!!!
 19
    # If you use Textedit to edit this file make sure to use "plain text format"
    # and "disable smart quotes" in "Textedit > Preferences", otherwise Textedit
     # will use none-compatible characters and your network configuration won't
 24
    # work!
     ## WPA/WPA2 secured
 26
 27
     network={
 28
      ssid="put SSID here"
 29
      psk="put password here"
```

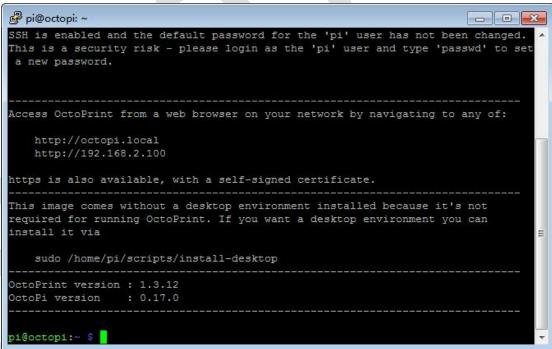
5) 连接树莓派

运行: "putty.exe" 并设置好 ip 地址等参数,并分别输入"pi" "raspberry"进行树莓派登录





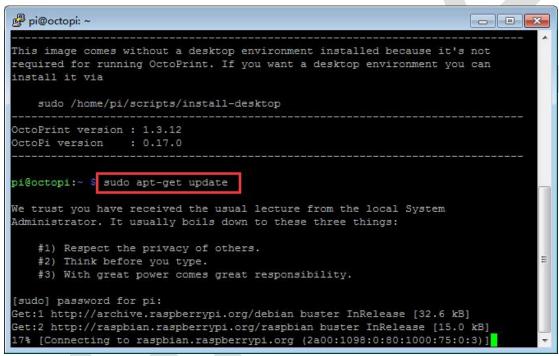






6) Octoprint 安装

更新指令: "sudo apt-get update",安装过程中有可能输入密码"raspberry"。等待完成安装。



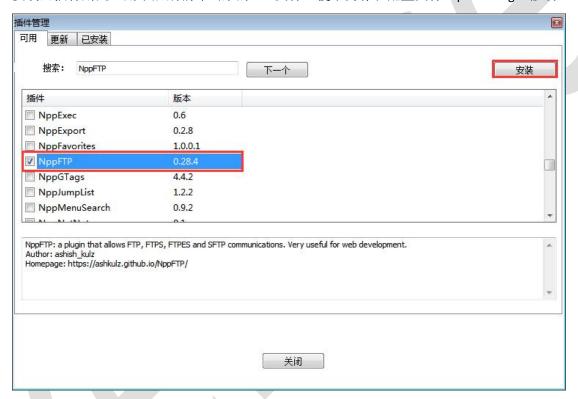
升级指令: "sudo apt-get upgrade", 安装过程中有可能输入密码"raspberry"。安装过程中提示输入"Y"回车确认安装。安装过程中提示按下"Q"键确认,等待完成安装。

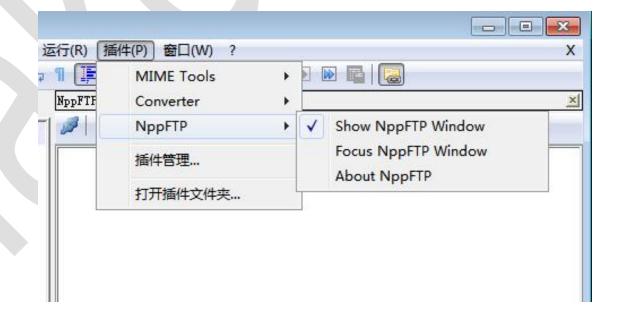
```
- - X
pi@octopi: ~
Ign:4 http://raspbian.raspberrypi.org/raspbian buster/main armhf Packages
Get:5 http://raspbian.raspberrypi.org/raspbian buster/contrib armhf Packages [58
.7 kB1
Get:6 http://raspbian.raspberrypi.org/raspbian buster/non-free armhf Packages [
04 kB]
Get:4 http://raspbian.raspberrypi.org/raspbian buster/main armhf Packages [18.3
Fetched 18.9 MB in 29min 28s (10.7 kB/s)
Reading package lists... Done
pi@octopi:~ $ sudo apt-get upgrade
[sudo] password for pi:
Sorry, try again.
[sudo] password for pi:
Reading package lists... Done
Building dependency tree
Reading state information... Done
Calculating upgrade... Done
The following package was automatically installed and is no longer required:
 rpi-eeprom-images
Use 'sudo apt autoremove' to remove it.
The following packages have been kept back:
 binutils binutils-arm-linux-gnueabihf binutils-common libbinutils
 libgl1-mesa-dri python-rpi.gpio raspi-config
The following packages will be upgraded:
```



7) Notepad++安装 NttFTP 插件

安装此插件过程中,会关闭 Notepad++,完成后会重新启动 Notepad++ 安装此插件用处:用于后期编译出来的 bin 文件,便于另存和配置文件"printer.cfg"修改







二、Klipper 固件下载-设置-编译-更新

1) 下载

执行 "git clone https://github.com/KevinOConnor/klipper"

```
- - X
🔗 pi@octopi: ~
Access OctoPrint from a web browser on your network by navigating to any of:
    http://octopi.local
    http://192.168.2.100
https is also available, with a self-signed certificate.
This image comes without a desktop environment installed because it's not
required for running OctoPrint. If you want a desktop environment you can
install it via
    sudo /home/pi/scripts/install-desktop
OctoPrint version: 1.3.12
OctoPi version
                 : 0.17.0
pi@octopi:~ $ git clone https://github.com/KevinOConnor/klipper
Cloning into 'klipper'...
remote: Enumerating objects: 19, done.
remote: Counting objects: 100% (19/19), done.
remote: Compressing objects: 100% (14/14), done.
 eceiving objects: 3% (686/22847), 176.01 KiB | 139.00 KiB/s
```

完成后执行: "./klipper/scripts/install-octopi.sh"并输入密码"raspberry"

```
pi@octopi: ~
                                                                           - - X
remote: Enumerating objects: 19, done.
remote: Counting objects: 100% (19/19), done.
remote: Compressing objects: 100% (14/14), done.
remote: Total 22847 (delta 5), reused 14 (delta 5), pack-reused 22828 Receiving objects: 100% (22847/22847), 14.95 MiB | 28.00 KiB/s, done.
Resolving deltas: 100% (17248/17248), done.
Checking out files: 100% (1274/1274), done
pi@octopi:~
             $ ./klipper/scripts/install-octopi.sh
###### Running apt-get update...
We trust you have received the usual lecture from the local System
Administrator. It usually boils down to these three things:
    #1) Respect the privacy of others.
    #2) Think before you type.
    #3) With great power comes great responsibility.
[sudo] password for pi:
Get:1 http://archive.raspberrypi.org/debian buster InRelease [32.6 kB]
Get:2 http://raspbian.raspberrypi.org/raspbian buster InRelease [15.0 kB]
Get:3 http://archive.raspberrypi.org/debian buster/main armhf Packages [351 kB]
0% [3 Packages 5,325 B/351 kB 2%]
```

执行安装 GCC: "sudo apt-get install gcc-arm-none-eabi"



2) 设置

执行"cd ~/klipper/",并执行"make menuconfig"。Nano V3 主板设置

```
- - X
Ppi@octopi: ~/klipper
[*] Enable extra low-level configuration options
   Micro-controller Architecture (STMicroelectronics STM32)
   Processor model (STM32F407) -
   Bootloader offset (48KiB bootloader (MKS Robin Nano V3)) --->
   Clock Reference (8 MHz crystal) --->
   Communication interface (USB (on PA11/PA12)) --->
   USB ids --->
[ ] Specify a custom step pulse duration
   GPIO pins to set at micro-controller startup
                                [?] Help
                                                    [/] Search
[Space/Enter] Toggle/enter
[Q] Quit (prompts for save)
                                [ESC] Leave menu
```

3)编译

MKS Robin Nano V3 主板: 执行"make"编译,并等待完成

```
Ppi@octopi: ~/klipper
                                                                      - - X
  Compiling out/src/tmcuart.o
 Compiling out/src/neopixel.o
 Compiling out/src/pulse_counter.o
 Compiling out/src/stm32/watchdog.o
 Compiling out/src/stm32/gpio.o
 Compiling out/src/generic/crc16 ccitt.o
 Compiling out/src/generic/armcm_boot.o
 Compiling out/src/generic/armcm_irq.o
 Compiling out/src/generic/armcm reset.o
 Compiling out/src/../lib/stm32f4/system stm32f4xx.o
 Compiling out/src/stm32/stm32f4.o
 Compiling out/src/generic/armcm timer.o
 Compiling out/src/stm32/adc.o
 Compiling out/src/stm32/i2c.o
 Compiling out/src/stm32/spi.o
 Compiling out/src/stm32/usbotg.o
 Compiling out/src/stm32/chipid.o
 Compiling out/src/generic/usb cdc.o
 Building out/compile time request.o
ersion: v0.9.1-617-gf2421005
 Preprocessing out/src/generic/armcm link.ld
 Linking out/klipper.elf
 Creating hex file out/klipper.bin
pi@octopi:~/klipper $
```

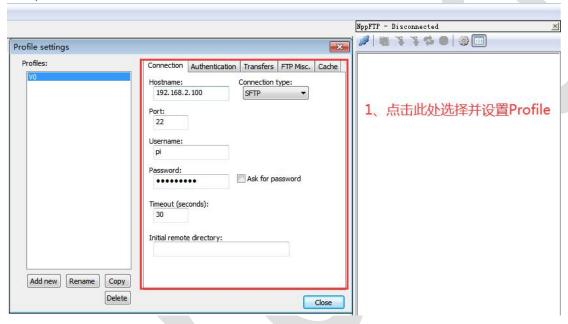
若提示"make: arm-none-eabi-gcc: Command not found"

请参考: FAQ 问题一



4)更新

Notepad++设置并连接到树莓派(提示: IP 地址根据自己实际设置)



Klipper.bin 文件位于: "pi->klipper->out->klipper.bin" 右键另存为操作 MKS Robin Nano V3 主板,另存 Robin_nano_v3.bin 文件到 TF 卡,并插到主板进行固件升级。升级完成后,蜂鸣器将滴滴两声



三、Octoprint 初始化-串口设置

1) Octoprint 初始化设置

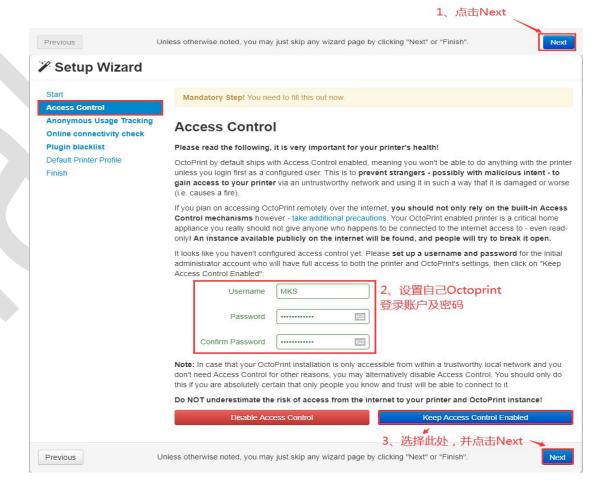
Setup Wizard



Hello!

Thank you for installing OctoPrint!

This wizard will guide you through the final steps to get your OctoPrint instance all set up and ready to go. We'll get you printing in no time!





Setup Wizard Mandatory Step! You need to fill this out now Access Control Configure Anonymous Usage Tracking Online connectivity check Plugin blacklist Anonymous usage tracking provides valuable insights into how many instances running what versions of OctoPrint are out there, whether they are successfully completing print jobs and various other metrics. Default Printer Profile By enabling it you help to identify problems with new releases and release candidates early on, and to better tailor OctoPrint's future development to actual use For details on what gets tracked, please refer to tracking octoprint org and also the Privacy Policy at tracking.octoprint.org Note: You can always change your decision and also access more granular controls via Settings > Anonymous Usage Tracking. Disable Anonymous Usage Tracking Enable Anonymous Usage Tracking 4、选择Enable,并点击Next

Setup Wizard

Start

Previous

Access Control

Anonymous Usage Tracking

Inline connectivity check

Plugin blacklist

Default Printer Profile Finish Mandatory Step! You need to fill this out now

Configure the connectivity check

Unless otherwise noted, you may just skip any wizard page by clicking "Next" or "Finish".

If the connectivity check is enabled, OctoPrint will regularly check if it's connected to the internet. This is **useful to prevent resource intensive operations** (such as checking for updates) if it's already clear that they won't succeed anyhow.

If it is disabled OctoPrint will always assume to have a working connection to the internet. If that should not actually be the case, server startups, update checks and the like might take longer.

OctoPrint comes preconfigured to perform the connectivity check every 15 minutes. You may change the value here.

Check interval 15 min

OctoPrint comes preconfigured to utilize Google's DNS server [8.8.8.8], port 53 for the connectivity check (if it's enabled). If you have concerns about using that, define the IP and port of a different online server that you trust and that has a high availability.

Port 53

Test host & port

Finally, please decide on whether to enable or disable the connectivity check. You may change the configuration at any time through Settings > Server right from within OctoPrint.

Disable Connectivity Check Enable Connectivity Check

5、选择Enable,并点击Next

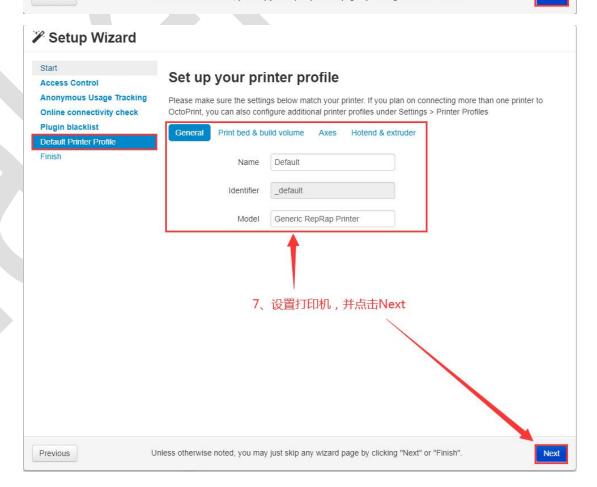
Previous

Unless otherwise noted, you may just skip any wizard page by clicking "Next" or "Finish".

Next

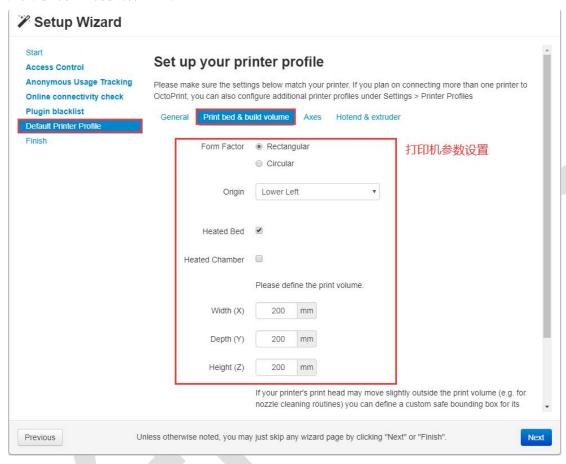


Setup Wizard Mandatory Step! You need to fill this out now. Access Control Anonymous Usage Tracking Configure plugin blacklist processing Online connectivity check To protect against known severe issues with certain versions of third party plugins, OctoPrint supports the use of a centralized plugin version blacklist to automatically disable such plugin versions before they can interfere with Default Printer Profile normal operation, allowing you to uninstall or update them to a newer version. Finish By default, OctoPrint will use the blacklist hosted at plugins.octoprint.org/blacklist.json which you can also take a look at in a more human readable format here. Please decide whether to allow fetch and use of this centralized blacklist starting with the next server start. You may also change your decision at any time through Settings > Server right from within OctoPrint. Enable Plugin Blacklist Processing Disable Plugin Blacklist Processing 6、选择Enable,并点击Next Previous Unless otherwise noted, you may just skip any wizard page by clicking "Next" or "Finish".



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Setup Wizard



All Done!

Your OctoPrint installation is now all set up and ready to go.

For your printer's safety



Even with OctoPrint attached you should **never leave your printer running completely unattended**. The electronics in our consumer printers can and sometimes sadly do catch fire, so stay or have someone else stay close enough to physically intervene in case of such catastrophic failure.

You also should **never make your OctoPrint instance available for everyone on the public internet**, even with Access Control enabled. Your instance *will* be found, and bad people *will* try to abuse it. Don't put yourself at risk, use a safe way to access your instance remotely.

If you enjoy OctoPrint...



Please consider **supporting OctoPrint's ongoing development**, which can only continue with funding by users like you! You can also find this link in the "About" dialog. **Thank you!**

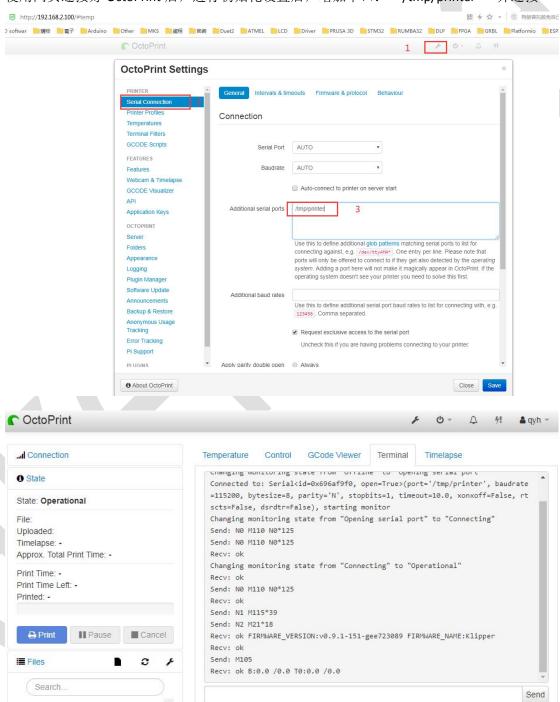
With all that being said, Happy and Safe Printing!





2) 串口设置

使用网页连接好 OctoPrint 后,进行初始化设置后,增加串口: "/tmp/printer" 并连接



若无法添加"/tmp/printer", 执行: ./klipper/scripts/install-octopi.sh

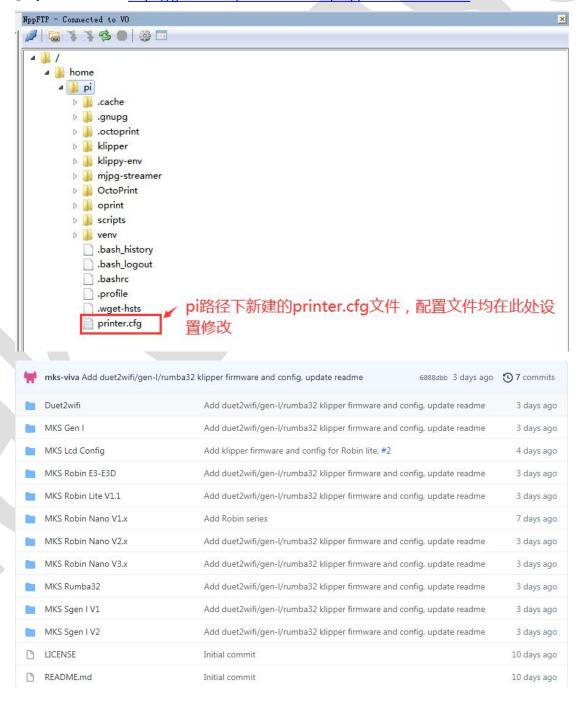
详细请参考: FAQ 问题三



四、Klipper 配置文件

1) printer.cfg 配置文件

Kilpper 固件,读取配置文件均从此文件。可在 pi 文件夹下新建 printer.cfg 文件。相关主板配置文件示例,可参考: Klipper->config 文件夹,可对应打开并复制到 printer.cfg 文件。也可以参考 MSK Github: https://github.com/makerbase-mks/Klipper-for-MKS-Boards





2) 基本参数

以 MKS Robin Nano V3 主板为例,包括步进、加热、热敏、限位、细分、行程、回零、回零速度、屏幕类型等设置

步进设置

[stepper_x] # 适用于 XYZE(E没有限位、回零、最大行程等设置)

step_pin: PE3 # 步进脉冲管脚

dir_pin: !PE2 # 方向管脚,增加或者删除"!"可换向

enable_pin: !PE4 # 步进使能管脚,有"!": 低电平使能; 无则是高电平使能

microsteps: 16 # 细分设置 rotation_distance: 40 # 脉冲设置

endstop_pin: !PA15 # 限位设置, "!"表示 S G 断开,即是常开,常闭去掉"!" position endstop: 0 # 回零到最小设置,若设置为最大行程,则为回零到最大处

position_max: 300 # 最大行程设置 homing_speed: 50 # 回零速度设置

rotation_distance = <full_steps_per_rotation> * <microsteps> / <steps_per_mm> # rotation_distance = ((360° /1.8°) * microsteps) / 80 # 旋转距离 = (圆周 360° /步距角) *细分/每 MM 脉冲值

挤出机设置

[extruder]

nozzle_diameter: 0.400 # 喷嘴直径 filament_diameter: 1.750 # 耗材直径 heater_pin: PE5 # 加热头管脚

sensor type: ATC Semitec 104GT-2 # 测温类型

sensor_pin: PC1 # 测温管脚
control: pid # 加热控制类型
pid_Kp: 14.669 # PID 参数 kp
pid_Ki: 0.572 # PID 参数 ki
pid_Kd: 94.068 # PID 参数 kd
min_temp: 0 # 最小温度
max_temp: 250 # 最大温度

热床设置

[heater_bed]



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heater pin: PAO # 热床加热管脚

sensor_type: EPCOS 100K B57560G104F # 测温类型

sensor_pin: PCO # 测温管脚

control: pid # 加热控制类型



[fan]

pin: PC14 # FAN 控制管脚; FAN2 is use PB1 control

机器设置

[printer]

kinematics: cartesian #机型设置, cartesian、corexy、delta······

max velocity: 250 # XY 最大速度速度设置

max_accel: 4500 # XY 加速度设置

max_z_velocity: 25 # Z 最大速度速度设置

max_z_accel: 100 # Z 加速度设置

EXP1/EXP2 接口

EXP1 / EXP2 (display) pins

[board pins]

aliases:

EXP1 header

EXP1_1=PC5, EXP1_3=PD13, EXP1_5=PE14, EXP1_7=PD11, EXP1_9=<GND>,

EXP1_2=PE13, EXP1_4=PC6, EXP1_6=PE15, EXP1_8=PD10, EXP1_10=<5V>,

EXP2 header

EXP2_1=PA6, EXP2_3=PE8, EXP2_5=PE11, EXP2_7=PE12, EXP2_9=<GND>,

EXP2 2=PA5, EXP2 4=PE0, EXP2 6=PE10, EXP2 8=<RST>, EXP2 10=<3.3v>

Pins EXP2_1, EXP2_6, EXP2_2 are also MISO, MOSI, SCK of bus "ssp1"

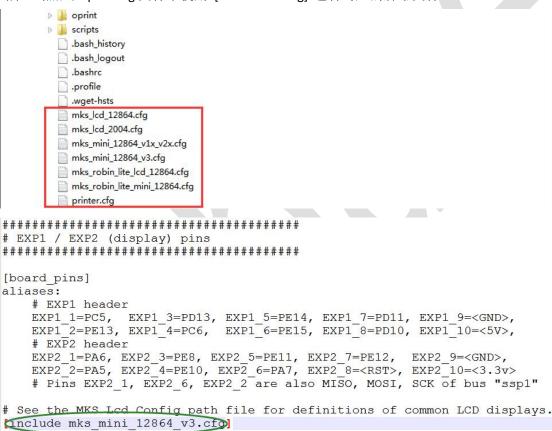
See the sample-lcd.cfg file for definitions of common LCD displays.

Refer to: https://github.com/makerbase-mks/Klipper-for-MKS-Boards MKS Lcd Config 路径



屏幕设置

可以直接拷贝对应的屏幕设置到 print.cfg 文件中;也可以将 LCD 的配置文件,放到同 print.cfg 路径,然后在 print.cfg 文件中使用"[include ***.cfg]"包含对应的屏幕文件



串口设置

获取串口需要执行: ls /dev/serial/by-id MKS Robin Nano V3 主板串口显示如下



```
- - X
🔑 pi@octopi: ~
  Compiling out/src/stm32/gpio.o
 Compiling out/src/generic/crc16 ccitt.o
 Compiling out/src/generic/armcm boot.o
 Compiling out/src/generic/armcm_irq.o
 Compiling out/src/generic/armcm reset.o
 Compiling out/src/../lib/stm32f4/system_stm32f4xx.o
 Compiling out/src/stm32/stm32f4.o
 Compiling out/src/generic/armcm_timer.o
 Compiling out/src/stm32/adc.o
 Compiling out/src/stm32/i2c.o
 Compiling out/src/stm32/spi.o
 Compiling out/src/stm32/usbotg.o
 Compiling out/src/stm32/chipid.o
 Compiling out/src/generic/usb_cdc.o
 Building out/compile time request.o
Version: v0.9.1-617-gf2421005
 Preprocessing out/src/generic/armcm link.ld
 Linking out/klipper.elf
 Creating hex file out/klipper.bin
pi@octopi:~/klipper $ cd
pi@octopi:~ $ ls /dev/serial/by-id
usb-Klipper_stm32f407xx_300044000851363439343739-if00
pi@octopi:~ $ ^C
pi@octopi:~ $
```

[mcu]

serial: /dev/serial/by-id/usb-Klipper_stm32f407xx_300044000851363439343739-if00 # Octoprint 识别端口,根据实际设置

```
[fan]
pin: PC14  # fan1
#pin: PB1 # fan2

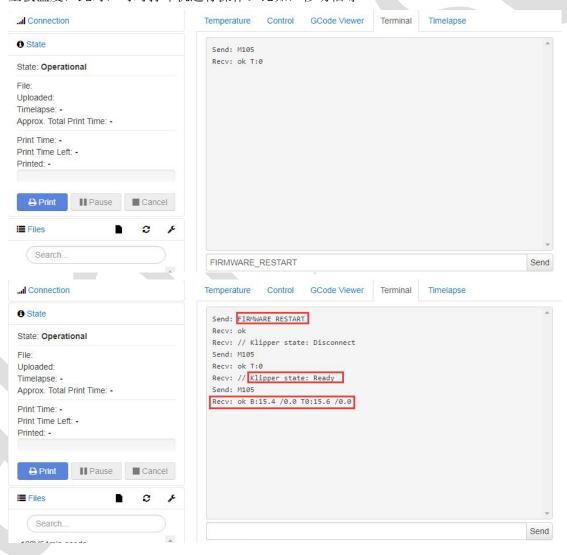
[mcu]
serial: /dev/serial/by-id/usb-Klipper_stm32f407xx_300044000851363439343739-if00
```



五、Octoprint 连接控制打印机

1) 连接主板控制

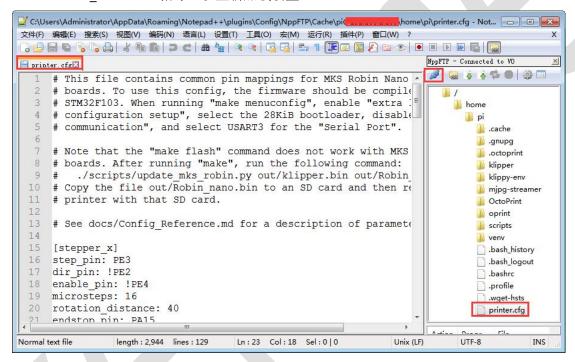
配置好 printer.cfg 文件后,在网页 Octoprint 终端发送: FIRMWARE_RESTART 命令,可查看到 主板温度,此时,可对打印机进行操作。比如,移动轴等





2) FIRMWARE_RESTART 指令

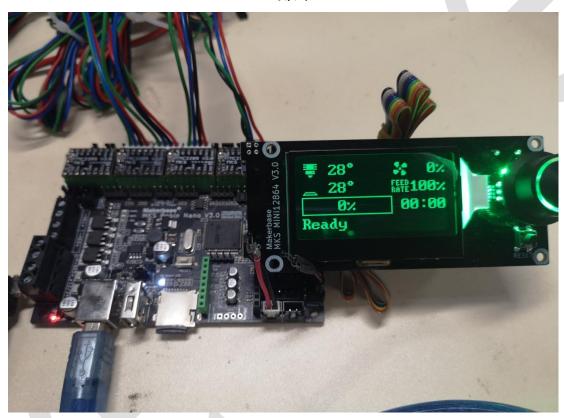
说明: 若在此网页操作过程中,发现参数需要调整修改,均需要在 Notepad++中连接树莓派,并 打 开 printer.cfg 文 件 进 行 编 辑 并 保 存 。 之 前 都 要 在 Octoprint 终 端 发 送 "FIRMWARE_RESTART"指令,以重新加载设置

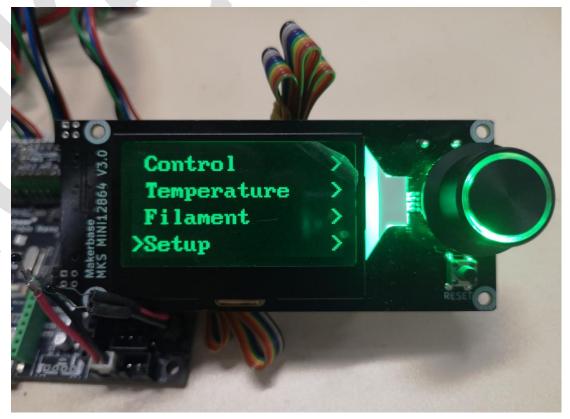




六、测试

MKS Robin Nano V3+MKS MINI12864 V3 测试







七、常见问题处理(FAQ)

问题一: make: arm-none-eabi-gcc: Command not found

解决 执行: "sudo apt-get install gcc-arm-none-eabi",并输入"Y"确认并等待安装

```
- - X
pi@octopi: ~/klipper
 Compiling out/src/sched.o
make: arm-none-eabi-gcc: Command not found make: *** [Makefile:64: out/src/sched.o] Error 127
pi@octopi:~/klipper $ sudo apt-get install gcc-arm-none-eabi
Reading package lists... Done
Building dependency tree
Reading state information... Done
The following package was automatically installed and is no longer required:
 rpi-eeprom-images
Use 'sudo apt autoremove' to remove it.
The following additional packages will be installed:
 binutils-arm-none-eabi libnewlib-arm-none-eabi libnewlib-dev
 libstdc++-arm-none-eabi-newlib
Suggested packages:
 libnewlib-doc
The following NEW packages will be installed:
 binutils-arm-none-eabi gcc-arm-none-eabi libnewlib-arm-none-eabi
  libnewlib-dev libstdc++-arm-none-eabi-newlib
0 upgraded, 5 newly installed, 0 to remove and 7 not upgraded.
Need to get 0 B/170 MB of archives.
After this operation, 1,731 MB of additional disk space will be used.
Do you want to continue? [Y/n] Y
Selecting previously unselected package binutils-arm-none-eabi.
(Reading database ... 47515 files and directories currently installed.)
```

问题二: Octoprint 终端发送 FIRMWARE_RESTART 无法返回温度

解决 执行:对主板手动复位,重新发送"FIRMWARE RESTART"指令



问题三: Octoprint 添加 "/tmp/printer" 但 "Serial Port" 选项无法显示

执行: ./klipper/scripts/install-octopi.sh , 并输入密码 "raspberry" 等待安装。

```
pi@octopi: ~
pi@octopi:~ $ ./klipper/scripts/install-octopi.sh
##### Running apt-get update...
[sudo] password for pi:
Hit:1 http://archive.raspberrypi.org/debian buster InRelease
Get:2 http://raspbian.raspberrypi.org/raspbian buster InRelease [15.0 kB]
Fetched 15.0 kB in 3s (5,950 B/s)
Reading package lists... Done
###### Installing packages...
Reading package lists... Done
Building dependency tree
Reading state information... Done
Note, selecting 'libusb-1.0-0' for regex 'libusb-1.0'
Note, selecting 'libusb-1.0-0-dev' for regex 'libusb-1.0'
Note, selecting 'libusb-1.0-doc' for regex 'libusb-1.0'
binutils-arm-none-eabi is already the newest version (2.31.1-11+rpi1+11).
binutils-arm-none-eabi set to manually installed.
build-essential is already the newest version (12.6).
gcc-arm-none-eabi is already the newest version (15:7-2018-q2-6).
libffi-dev is already the newest version (3.2.1-9).
libnewlib-arm-none-eabi is already the newest version (3.1.0.20181231-1).
```



八、附录-相关资料

固件获取: https://github.com/KevinOConnor/klipper

固件编译: https://www.klipper3d.org/Installation.html

固件配置: https://www.klipper3d.org/Overview.html

功能介绍: https://www.klipper3d.org/Features.html

步进旋转值计算: https://www.klipper3d.org/Rotation Distance.html

MKS 主板,已编译 Klipper 固件:

https://github.com/makerbase-mks/Klipper-for-MKS-Boards