

Safe Walk – Gait Monitoring System

(17S WSN Project)

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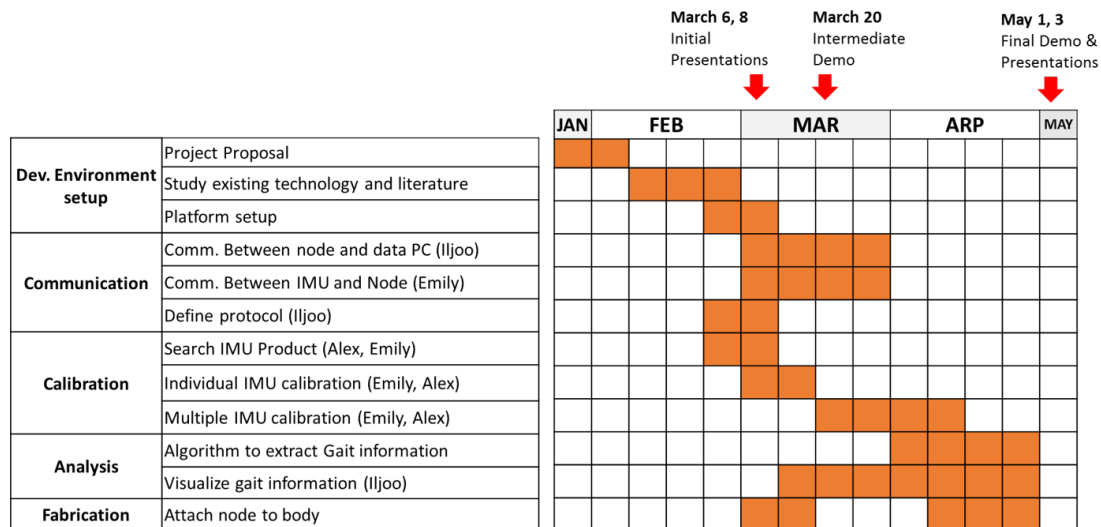
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2 Resources

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3 Schedule



4 Events

4.1 2017-03-03 Meeting

- Done
 - Finished the proposal documentation
 - Built a website on GitHub
 - IMU Sensor:
 - * Got 4 Razor IMU sensors
 - * Tested it with ROS, and checked its output
 - * Decided to transmit binary data stream via RF and serial port
- TODO
 - Develop an interface between serial port and ROS
 - Modify the IMU firmware to output raw + calculated data
 - Build the communication from IMU to Firefly
 - Build the communication from Firefly to PC
 - Solve the time synchronization problem

4.2 2017-03-04 Camera+IMU Development Based on ROS+RobotSDK

Activities | Robot-X | Sat Mar 4, 02:33:52 | +7.3 °C | en

roscore http://ThinkStation-PS10:11311/

File Edit View Search Terminal Tabs Help

alexanderhbw@ThinkStation-PS10:~\$ roscore
... logging to /home/alexanderhbw/.ros/log/d63be642-60a9-11e7-88b0-6c0b846530b0
10-5855.log
Checking log directory for disk usage. This may take awhile.
Press Ctrl-C to interrupt
Done checking log file disk usage. Usage is <1GB.

started roslaunch server http://ThinkStation-PS10:42689/
ros_comm version 1.12.6

SUMMARY

PARAMETERS
* /roslaunch: kinetic
* /rosversion: 1.12.6

NODES

auto-starting new master
process[master]: started with pid [5866]
ROS_MASTER_URI=http://ThinkStation-PS10:11311/
setting /run_id to d63be642-60a9-11e7-88b0-6c0b846530b0
process[roscout-1]: started with pid [5879]
started core service [/roscout]

ImageView: Viewer
07:33:52:109 640 x 400

IMU Message Viewer
IMU Messages

593757	2824	8936	13968	-6	5	11	-217	-22	22	309.39	22.98	207.57
593767	2840	9048	13880	0	5	11	-222	-22	13	309.39	22.98	207.56
593778	2864	9008	14104	0	5	11	-217	-20	18	309.39	22.99	207.55
593788	2952	8976	14016	-4	5	9	-226	-23	21	309.39	22.99	207.54
593797	2760	9072	14128	-3	4	11	-226	-28	21	309.40	22.99	207.54
593807	2784	8960	14264	0	3	11	-223	-14	21	309.41	22.99	207.53
593818	2864	8832	14016	1	6	11	-211	-18	14	309.41	23.00	207.52
593828	2832	8984	14000	-3	4	11	-217	-24	22	309.42	23.00	207.51
593837	2952	9008	14232	-2	4	9	-217	-22	20	309.43	23.00	207.51

Robot-X: Calibration