Machine Learning notes

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0.1 EM algorithm

Consider the following experiment with coin A has probability of θ_A being head, and coin B has probability θ_B flipping head, we pick one coin at a time, and flip it m times, in total, we have chosed n coins, in other words, we have n and have fliped $n \times m$ times of coin.

Complete information: Suppose we write down which coin we have picked every time, we would have the complete likelihood function $p(x, z|\theta)$. where x is a vector of m flips in one sample, z is the label of coins. For mathemetical conveninet, we would like to compute $\log p(x, z|\theta)$, where

$$\log p(x, z | \theta) = \log \prod_{i=1}^{n} p(x_i, z_i | \theta) = \sum_{i=1}^{n} \log p(x_i, z_i | \theta)$$
 (0.1.1)

the way we solve the parameters is the unsurprising Maximumizing Likelihood function (MLE).

$$\theta := \operatorname*{argmax}_{\theta} \log p(x, z | \theta) \tag{0.1.2}$$

Incomplete information(missing information), we didn't record which coin we have picked, onlying knowing the flipping results. Models with hidden variables are known as latent variable models(LVM), in general, there are K laten variables(z_k , k=1,2,...,K), and m visible variables(x_i , i=1,2,...,m). The incomplete likelihood function is $p(x|\theta)$

$$\log p(x|\theta) = \log \prod_{i=1}^{n} p(x_i|\theta)$$

$$= \sum_{i=1}^{n} \log p(x_i|\theta)$$

$$= \sum_{i=1}^{n} \log \sum_{k=1}^{K} p(x_i, z_i = k|\theta)$$

This likelihood function is not easy to solve since we now have unkown variable z_i and unknown parameter θ , hence, **EM algorithm ** comes to play. First of all , we introduce the distribution of hidden variable $Q_i(z_i)$.

$$\sum_{i=1}^{n} \log \sum_{k=1}^{K} p(x_i, z_i = k | \theta) = \sum_{i=1}^{n} \log \sum_{k=1}^{K} Q_i(z_i) \frac{p(x_i, z_i = k | \theta)}{Q_i(z_i)}$$

$$= \sum_{i=1}^{n} \log E \left[\frac{p(x_i, z_i = k | \theta)}{Q_i(z_i)} \right]$$
(0.1.3)

Again , it is not so elegant, however, we have Jasen inequality to handle this complexity. Recall $f(E[x]) \geq E[f(x)]$ holds for convex functions,and the equale sign exists when f(x) is a constant, now we plug this into the above equation $x \to \frac{p(x_i, z_i = k | \theta)}{Q_i(z_i)}$,

$$\sum_{i=1}^{n} \log \sum_{k=1}^{K} p(x_{i}, z_{i} = k | \theta) = \sum_{i=1}^{n} \log E \left[\frac{p(x_{i}, z_{i} = k | \theta)}{Q_{i}(z_{i})} \right]$$

$$\geq \sum_{i=1}^{n} E \left[\log \frac{p(x_{i}, z_{i} = k | \theta)}{Q_{i}(z_{i})} \right]$$

$$\geq \sum_{i=1}^{n} \sum_{k=1}^{K} Q_{i}(z_{i}) \log \frac{p(x_{i}, z_{i} = k | \theta)}{Q_{i}(z_{i})}$$
(0.1.4)

now the goal is to find a solution that the equation has "=" holds.

$$\log p(x|\theta) \ge \sum_{i=1}^{n} \sum_{k=1}^{K} Q_i(z_i) \log \frac{p(x_i, z_i = k|\theta)}{Q_i(z_i)}$$

Remember that we say the equal sign "=" holds if f(x) = C.

Define $\frac{p(x_i, z_i = k | \theta)}{Q_i(z_i)} = C$, we know the fact that the summation of the distribution of z_i must be

1,
$$\sum_{k=1}^{K} Q_i(z_i = k) = 1$$
, it is not difficult to get $\sum_{k=1}^{K} p(x_i, z_i = k | \theta) = C$. now, let's see the compact solution of $Q_i(z_i)$

$$Q_{i}(z_{i}) = \frac{p(x_{i}, z_{i} = k | \theta)}{C}$$

$$= \frac{p(x_{i}, z_{i} = k | \theta)}{\sum_{k=1}^{K} p(x_{i}, z_{i} = k | \theta)}$$

$$= \frac{p(x_{i} | z_{i} = k, \theta) p(z_{i} | k, \theta)}{\sum_{k=1}^{K} p(x_{i}, z_{i} = k | \theta)}$$

$$= \frac{p(x_{i} | z_{i} = k, \theta) p(z_{i} | k, \theta)}{p(x_{i} | \theta)}$$

$$= p(z_{i} | x_{i}, \theta)$$
(0.1.5)

With this in mind, we now explain EM algorithm

- 1.Initial parameter θ
- 2. E step, compute $Q_i(z_i) := p(z_i|x_i,\theta)$
- 3. M step, $\theta := \underset{\theta}{\operatorname{argmax}} \sum_{i=1}^{n} \sum_{k=1}^{K} Q_i(z_i) \log \frac{p(x_i, z_i = k | \theta)}{Q_i(z_i)}$
- $\bullet\,$ 4. Repeat step 2 and 3 until converged.

In practice, Gaussian mixture model is widely used, and parameters $\theta = \mu, \Sigma$, the prior distribution of k is denoted as $\pi_k = p(z_i = k | \mu_k, \Sigma_k)$

$$p(\vec{x}|\mu, \Sigma) = \prod_{i=1}^{m} \sum_{k=1}^{K} \pi_k \mathcal{N}(x_i|z_i = k, \mu_k, \Sigma_k)$$
 (0.1.6)

For mathemetical convenience, we would like to compute $\operatorname{argmax}_{\theta} \log[p(\vec{x}|\theta)]$

$$\log[p(\vec{x}|\mu, \Sigma)] = \sum_{i=1}^{m} \log\left[\sum_{k=1}^{K} p(z_i = k|\mu_k, \Sigma_k) \mathcal{N}(x_i|z_i = k, \mu_k, \Sigma_k)\right]$$
(0.1.7)

also, we define $\gamma_{ik} = p(z_i = k|x_i, \mu_k, \Sigma_k)$, the posterior distribution that point *i* belongs cluster *k*, it is knowns as the reponsibility of cluster *k* for point *i*. According to Bayes' rule

$$\gamma_{ik} = p(z_i = k | x_i, \mu_k, \Sigma_k) = \frac{p(z_i = k | \mu_k, \Sigma_k) p(x_i | z_i = k, \mu_k, \Sigma_k)}{p(x_i | \mu_k, \Sigma_k)}$$

$$= \frac{p(z_i = k | \mu_k, \Sigma_k) p(x_i | z_i = k, \mu_k, \Sigma_k)}{\sum_{k'=1}^{K} p(z_i = k' | \mu'_k, \Sigma'_k) p(x_i | z_i = k', \mu'_k, \Sigma'_k)}$$
(0.1.8)

The EM algorithm for Gaussian Mixture Models work as follows:

- 1. Initialize the different parameters π , μ and Σ .
- 2. E step, Compute the responsibilities $\gamma_{ik} = \frac{\pi_k \mathcal{N}(x_i|z_i=k,\mu_k,\Sigma_k)}{\sum\limits_{k'=1}^K \pi'_k \mathcal{N}(x_i|z_i=k',\mu'_k,\Sigma'_k)}$
- 3. M step, set partial derivative eq(0.1.7) wrt μ_k and Σ_k .

$$\frac{\partial \log[p(\vec{x}|\mu, \Sigma)]}{\partial \mu_k} = \sum_{i=1}^m \frac{\pi_k \mathcal{N}(x_i|z_i = k, \mu_k, \Sigma_k)}{\sum_{k'=1}^K \pi'_k \mathcal{N}(x_i|z_i = k', \mu'_k, \Sigma'_k)} \Sigma_k^{-1}(x_i - \mu_k)$$
$$= \sum_{i=1}^m \gamma_{ik} \Sigma_k^{-1}(x_i - \mu_k)$$
$$= 0$$

there, we obtain

$$\mu_k = \frac{\sum_{i=1}^m \gamma_{ik} x_i}{\sum_{i=1}^m \gamma_{ik}} = \frac{1}{m_k} \sum_{i=1}^m \gamma_{ik} x_i$$

Similarly,

$$\frac{\partial \log[p(\vec{x}|\mu, \Sigma)]}{\partial \Sigma_k} = \sum_{i=1}^m \gamma_{ik} \left[\exp[(x_i - \mu_k) \Sigma^{-1} (x_i - \mu_k)^T] + \Sigma_k \exp[(x_i - \mu_k) \Sigma^{-1} (x_i - \mu_k)^T] (-\Sigma_k^{-2}) \right]
= \sum_{i=1}^m \gamma_{ik} \left[1 - (x_i - \mu_k) (x_i - \mu_k)^T \Sigma^{-1} \right] \exp[(x_i - \mu_k) \Sigma^{-1} (x_i - \mu_k)^T]
= 0$$

Since $\exp[(x_i - \mu_k)\Sigma^{-1}(x_i - \mu_k)^T] \neq 0$, the solution of μ_k is

$$\Sigma_k = \frac{1}{m_k} \sum_{i=1}^m \gamma_{ik} (x_i - \mu_k) (x_i - \mu_k)^T$$
 (0.1.9)

Next, we introduce Largange multiplier to solve π_k the constrains on π_k is $\sum_{k=1}^K \pi_k = 1$

$$\log p(x|\mu, \Sigma) + \lambda (\sum_{k=1}^{K} \pi_k - 1)$$

maximizing the above wrt π_k

$$\frac{\partial \log[p(\vec{x}|\mu, \Sigma)]}{\partial \pi_k} = \sum_{i=1}^m \frac{\mathcal{N}(x_i|z_i = k, \mu_k, \Sigma_k)}{\sum\limits_{k=1}^K \pi_k \mathcal{N}(x_i|z_i = k, \mu_k, \Sigma_k)} + \lambda = 0$$

Multipling both part with π_k and summing over k, we have $\lambda=-N,$ again multipling both sides with π_k yields

$$0 = \sum_{i=1}^{m} \gamma_{ik} - \pi_k m$$

$$\pi_k = \frac{m_k}{m}$$

$$(0.1.10)$$

we have

4. Repeat step 2 and 3 until convergence.