

EEZ Programmable PSU SCPI reference guide



Firmware version: M1

Platform: EEZ PSU with Arduino Shield +BP r1B9 or latter (Mega or Due)

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Table of Contents

1.Introduction	7
1.1.About SCPI	7
2.Syntax and style	9
2.1.Root Specifier	9
2.2.Command termination	9
2.3.Command separators	9
2.4.Querying parameter settings	9
2.5.Using the MIN, MAX, and DEF Parameters	9
2.6.Command and message types	10
2.7.Required Commands	10
2.7.1.Base functionality for the Power supply instrument class	10
2.8.Multiple Commands in a Message	
2.9.Moving Among Subsystems	11
2.10.SCPI parameter types	
3.Registers and queues	13
3.1.Standard Event Status Register	14
3.2.Status Byte Register	15
3.3.OPERation Status Register	
3.3.1.Operation INSTrument Status register	17
3.3.2.Operation Instrument SUMmary status register	
3.4.QUEStionable Status Register	
3.4.1.Questionable INSTrument Status register	
3.4.2.Questionable Instrument SUMmary status register	
3.5.Error queue	
4.Common command reference	
4.1.*CLS	
4.2.*ESE	
4.3.*ESR?	
4.4.*IDN?	
4.5.*OPC	
4.6.*RCL	
4.7.*RST	
4.8.*SAV	
4.9.*STB?	
5.Subsystem command reference	
5.1.CALibrate	
5.1.2.CALibration;[.WODE]	
5.1.3.CALibration:CLEar	
5.1.4.CALibration:CURRent:LEVel	
5.1.5.CALibration:PASSword:NEW	
5.1.6.CALibration: ASSWORD: NEW	
5.1.7.CALibration:SAVE	
5.1.8.CALibration:STATe	
5.1.9.CALibration:VOLTage[:DATA]	
5.1.10.CALibration:VOLTage:LEVel	
5.2.DIAGnostic	
5.2.1.DIAGnostic[:INFOrmation]:ADC?	
5.2.2 DIAGnosticI:INFOrmation1:CAL ibration?	

5.2.3.DIAGnostic[:INFOrmation]:PROTection?	34
5.2.4.DIAGnostic[:INFOrmation]:TEST?	34
5.3.INSTrument	
5.3.1.INSTrument[:SELect]	37
5.3.2.INSTrument:NSELect	37
5.4.MEASure	39
5.4.1.MEASure[:SCALar]:CURRent[:DC]	39
5.4.2.MEASure[:SCALar]:POWer[:DC]	39
5.4.3.MEASure[:SCALar]:TEMPerature[:THERmistor][:DC]	39
5.4.4.MEASure[:SCALar][:VOLTage][:DC]	40
5.5.MEMory	41
5.5.1.MEMory:NSTates	41
5.5.2.MEMory:STATe:CATalog	41
5.5.3.MEMory:STATe:DELete	41
5.5.4.MEMory:STATe:NAME	42
5.5.5.MEMory:STATe:RECall:AUTO	42
5.5.6.MEMory:STATe:RECall:SELect	43
5.5.7.MEMory:STATe:VALid	43
5.6.OUTPut	45
5.6.1.OUTPut[:STATe]	45
5.6.2.OUTPut:MODE?	45
5.6.3.OUTPut:PROTection:CLEar	46
5.6.4.OUTPut:SENSe	46
5.7.SOURce	49
5.7.1.[SOURce[<n>]]:CURRent</n>	49
5.7.2.[SOURce[<n>]]:CURRent:STEP</n>	50
5.7.3.[SOURce[<n>]]:CURRent:PROTection:DELay[:TIME]</n>	51
5.7.4.[SOURce[<n>]]:CURRent:PROTection:STATe</n>	51
5.7.5.[SOURce[<n>]]:CURRent:PROTection:TRIPped?</n>	52
5.7.6.[SOURce[<n>]]:POWer:PROTection[:LEVel]</n>	52
5.7.7.[SOURce[<n>]]:POWer:PROTection:DELay[:TIME]</n>	53
5.7.8.[SOURce[<n>]]:POWer:PROTection:STATe</n>	53
5.7.9.[SOURce[<n>]]:POWer:PROTection:TRIPped?</n>	53
5.7.10.[SOURce[<n>]]:VOLTage</n>	54
5.7.11.[SOURce[<n>]]:VOLTage:STEP</n>	
5.7.12.[SOURce[<n>]]:VOLTage:PROTection:DELay[:TIME]</n>	55
5.7.13.[SOURce[<n>]]:VOLTage:PROTection:STATe</n>	
5.7.14.[SOURce[<n>]]:VOLTage:PROTection:TRIPped?</n>	
5.8.STATus	
5.8.1.STATus:OPERation[:EVENt]?	
5.8.2.STATus:OPERation:CONDition?	
5.8.3.STATus:OPERation:ENABle	
5.8.4.STATus:OPERation:INSTrument[:EVENt]?	
5.8.5.STATus:OPERation:INSTrument:CONDition?	
5.8.6.STATus:OPERation:INSTrument:ENABle	
5.8.7.STATus:OPERation:INSTrument:ISUMmary[<n>][:EVENt]?</n>	
5.8.8.STATus:OPERation:INSTrument:ISUMmary[<n>]:CONDition?</n>	
5.8.9.STATus:OPERation:INSTrument:ISUMmary <n>:ENABle</n>	
5.8.10.STATus:PREset	
5.8.11.STATus:QUEStionable[:EVENt]?	
5.8.12.STATus:QUEStionable:CONDition?	
5.8.13.STATus:QUEStionable:ENABle	62

5.8.14.STATus:QUEStionable:INSTrument[:EVENt]?	62
5.8.15.STATus:QUEStionable:INSTrument:CONDition?	63
5.8.16.STATus:QUEStionable:INSTrument:ENABle	
5.8.17.STATus:QUEStionable:INSTrument:ISUMmary[<n>][:EVENt]?</n>	
5.8.18.STATus:QUEStionable:INSTrument:ISUMmary[<n>]:CONDition?</n>	
5.8.19.STATus:QUEStionable:INSTrument:ISUMmary[<n>]:ENABle</n>	
5.9.SYSTem	
5.9.1.SYSTem:BEEPer	
5.9.2.SYSTem:BEEPer:STATe	
5.9.3.SYSTem:CAPability?	
5.9.4.SYSTem:DATE	
5.9.5.SYSTem:ERRor	
5.9.6.SYSTem:ERRor:COUNt?	
5.9.7.SYSTem:POWer	
5.9.8.SYSTem:TEMPerature:PROTection[:HIGH][:LEVel]	
5.9.9.SYSTem:TEMPerature:PROTection[:HIGH]:CLEar	
5.9.10.SYSTem:TEMPerature:PROTection[:HIGH]:DELay[:TIME]	
5.9.11.SYSTem:TEMPerature:PROTection[:HIGH]:STATe	
5.9.12.SYSTem:TEMPerature:PROTection[:HIGH]:TRIPped?	
5.9.14.SYSTem:VERSion?	
6.Device-specific (unclassified) commands	
6.1.APPLy	
7.Error messages	
7.1.Command Error [-199, -100]	
7.2.Execution Error [-299, -200]	
7.3.Device-Specific Error [-399, -300], [1, 32767]	
7.3.1.Self-Test Error Messages	
8.Parameters and settings	
8.1.Programming parameters	
8.1.1.Voltage	
8.1.2.Current	
8.1.3.Power	
8.2.Reset Settings (*RST)	
9.Software simulator	
9.1.SIMUlator	
9.1.1.SIMUlator:EXIT	
9.1.2.SIMUlator:GUI	
9.1.3.SIMUlator:LOAD	
9.1.4.SIMUlator:LOAD:STATe	
9.1.5.SIMUlator:PWRGood	
9.1.6.SIMUlator:TEMPerature	
10.Programming examples	
10.1.Set channel output values and working with the OCP	
10.2.Voltage and current calibration	
10.3.Working with profiles.	
10.4.Get identification info and self-test results.	
11.SCPI commands scheduled for the Milestone Three (M3)	
12.SCPI commands summary	101

1. Introduction

This manual contains reference information for programming open hardware/open source EEZ programmable PSU (Power Supply Unit) over the remote interface using the SCPI programming language. The SCPI (*Standard Commands for Programmable Instruments*, often pronounced "skippy") is an open standard freely available on the IVI Foundation web pages. Current version is SCPI 1999.0.

SCPI is pure software standard and SCPI syntax is ASCII text, and therefore can be attached to any computer language, such as C, C++, etc.

The physical communications link is not defined by SCPI. While originally created for IEEE 488 (GPIB), it can also be used with RS-232 (serial), Ethernet, USB, VXIbus, HiSLIP, etc. The EEZ PSU supports Serial (via USB) and Ethernet communication.

Application software that use SCPI commands is called *Controller* and SCPI enabled device such as PSU is called *Instrument*.

Please note that IEEE 488 standard documents are still not freely available, and if it is mentioned in this manual that is solely for reference purposes for one who wants to conduct a further research for better understanding or possible modification/improvement of the PSU remote control.

1.1. About SCPI

SCPI 1999.0 standard document says (Section 1.3) that the goal of SCPI is to reduce Automatic Test Equipment (ATE) program development time. SCPI accomplishes this goal by providing a consistent programming environment for instrument control and data usage. This consistent programming environment is achieved by the use of defined program messages, instrument responses, and data formats across all SCPI instruments, regardless of manufacturer.

A consistent program environment uses the same commands and parameters to control instruments that have the same functionality.

SCPI programming consistency is both vertical and horizontal. Vertical programming consistency defines program messages within an instrument class. An example of vertical consistency is using the same command for reading DC voltage from several different multimeters. Horizontal consistency is using the same command to control similar functions across instrument classes. For example, the trigger command would be the same for an identical trigger function found among counters, oscilloscopes, function generators, etc.

A key to consistent programming is the reduction of multiple ways to control similar instrument functions. The philosophy of SCPI is for the same instrument functions to be controlled by the same SCPI commands. To simplify learning, SCPI uses industry-standard names and terms that are manufacturer and customer supported.

SCPI is designed to be expanded with new defined commands in the future without causing programming problems. As new instruments are introduced, the intent is to maintain program compatibility with existing SCPI instruments.

Additional links:

- Wikipedia <u>SCPI</u>
- Technopedia <u>Standard Commands For Programmable Instruments (SCPI)</u>
- Wikipedia IEEE-488
- Keysight (Agilent) Developing a SCPI command set
- NI GPIB Hardware and Software Specifications

Implementation links:

- Open source SCPI device library
- Keysight (Agilent) <u>Application Note 1465-29</u>
- Keysight (Agilent) Command Expert

2. Syntax and style

Throughout this document, the following conventions are used for the SCPI command syntax:

- Square brackets ([]) indicate optional keywords or parameters. The braces are not sent with the command string.
- Braces ({}) enclose parameters within a command string.
- Triangle brackets (<>) indicate that you must substitute a value or a code for the enclosed parameter.
- A vertical bar (|) separates one of two or more alternative parameters.

2.1. Root Specifier

When it precedes the first header of a message unit, the colon becomes the root specifier. It tells the command parser that this is the root or the top node of the command tree.

2.2. Command termination

A command string sent to the PSU must terminate with a <new line>character. A <carriage return> followed by a <new line>is also accepted. Command string termination will always reset the current SCPI command path to the root level.

2.3. Command separators

A colon (:) is used to separate a command keyword from a lower-level keyword as shown below:

```
SOURce1:CURRent:PROTection:STATe
```

A semicolon (;) is used to separate two commands within the same subsystem, and can also minimize typing. For example, sending the following command string,

```
SOURce1: VOLTage 20; CURRent 300mA
```

is the same as sending the following two commands:

```
SOURce1:VOLTage 20
SOURce1:CURRent 1.5
```

Use a colon and a semicolon to link commands from different subsystems. For example, in the following command string, an error is generated if you do not use the colon and semicolon:

```
SYSTem:BEEP;:SOURce1:CURRent 2.5
```

2.4. Querying parameter settings

You can query the value of most parameters by adding a question mark (?) to the command. For example, the following command sets the output voltage to 45.5V:

```
VOLTage 45.5
```

You can query the value by executing:

VOLTage?

If error is occurred use SYSTem:ERRor[:NEXT]? to get more information about error.

2.5. Using the MIN, MAX, and DEF Parameters

For many commands, you can substitute "MIN" or "MAX" in place of a parameter. In some cases you may also substitute "DEF". For example, consider the following command:

[SOURce[<n>]]:VOLTage[:LEVel][:IMMediate][:AMPLitude] {<voltage>|MIN|DEF|MAX|UP|DOWN}

Instead of selecting a specific value for the <voltage> parameter, you can substitute MIN to set the voltage to its minimum value, MAX to set the voltage to its maximum value, or DEF to set the voltage to its default value. For list of parameter values see Section 8.1

2.6. Command and message types

SCPI commands can be divided to **common** and **subsystem** commands.

- Common commands are defined by the IEEE 488.2 standard to perform common interface functions. They begin with an * and consist of three letters (command) or three letters and a ? (query). Description of supported common commands can be found in <u>Section 4</u>
- Subsystem commands are specific to instrument (PSU in this case) functions. They can be a single command or a group of commands. The groups are comprised of commands that extend one or more levels below the root. See Section 5 for commands that is created in accordance to the SCPI 1999.0 standard. Commands that is not defined by SCPI 1999.0 is labeled "unclassified" and are presented in Section 6

There are two types of SCPI messages, **program** and **response**.

- A program message consists of one or more properly formatted SCPI commands sent from the controller to the instrument. The message, which may be sent at any time, requests the instrument to perform some action.
- A response message consists of data in a specific SCPI format sent from the instrument to the controller. The instrument sends the message only in response to a **query** header.

2.7. Required Commands

The following commands are required in all SCPI instruments (see SCPI 1999.0 Section 4.2.1):

Mnemonic	SCPI 1999.0 Command Reference Section	SCPI 1999.0 Syntax and Style Section
:SYSTem		<u> </u>
:ERRor	21.8	
[:NEXT]?	21.8.3e	1996
:VERSion?	19.16	1991
:STATus	18	5
:OPERation		
[:EVENt]?		
:CONDition?		
:ENABle		
:ENABle?		
:QUEStionable		
[:EVENt]?		
:CONDition?		
:ENABle		
:ENABle?		
:PRESet		

2.7.1. Base functionality for the Power supply instrument class

SCPI Command	Description	
OUTPut		
[:STATe] <bool></bool>	Enables the specified output channel(s)	
[SOURce[<n>]]</n>		
CURRent		

```
[:LEVel]
[:IMMediate][:AMPLitude] < current> Sets the output current

VOLTage
[:LEVel]
[:IMMediate][:AMPLitude] < voltage> Sets the output voltage
```

All SCPI power supplies shall implement the status reporting structure. STATus Subsystem defines the commands which shall be used to control the status reporting structure.

For a power supply, the bits of interest in the QUEStionable status structure are VOLTage and CUR-Rent. When a power supply is operating as a voltage source, bit 1 (CURRent) shall be set. When a power supply is operating as a current source, bit 0 (VOLTage) shall be set. When the output is unregulated, both bits shall be set (for example, while the output is changing to a new programmed value).

2.8. Multiple Commands in a Message

Multiple SCPI commands can be combined and sent as a single message with one message terminator. There are two important considerations when sending several commands within a single message:

- Use a semicolon to separate commands within a message.
- There is an implied header path that affects how commands are interpreted by the PSU.

The header path can be thought of as a string that gets inserted before each command within a message. For the first command in a message, the header path is a null string. For each subsequent command the header path is defined as the characters that make up the headers of the previous command in the message up to and including the last colon separator. An example of a message with two commands is:

```
OUTPut:STATe ON, CH1; PROTection:CLEar CH1
```

which shows the use of the semicolon separating the two commands, and also illustrates the header path concept. Note that with the second command, the leading header OUTPut was omitted because after the OUTPut:STATe ON command, the header path became defined as OUTPut and thus the instrument interpreted the second command as:

```
OUTPut:PROTection:CLEar CH1
```

In fact, it would have been syntactically incorrect to include the OUTPut explicitly in the second command, since the result after combining it with the header path would be:

```
OUTPut:OUTPut:PROTection:CLEar CH1
```

which is incorrect.

You can combine common commands (IEEE488) with subsystem commands in the same message. Treat the common command as a message unit by separating it with a semicolon (the message unit separator). Common commands do not affect the header path; you may insert them anywhere in the message.

```
*TST?;SYSTem:ERRor?
```

2.9. Moving Among Subsystems

In order to combine commands from different subsystems, you need to be able to reset the header path to a null string within a message. You do this by beginning the command with a colon (:), which discards any previous header path. For example, you could clear the output protection and check the status of the Operation Condition register in one message by using a root specifier as follows:

```
OUTPut:PROTection:CLEar CH1;:STATus:OPERation:CONDition? CH1
```

The following message shows how to combine commands from different subsystems as well as within the same subsystem:

```
VOLTage: LEVel 7.5, CH1; PROTection 10, CH1; : CURRent: LEVel 0.5, CH1
```

Note the use of the optional header LEVel to maintain the correct path within the subsystems, and the

use of the root specifier to move between subsystems.

2.10. SCPI parameter types

The SCPI language defines several different data formats to be used in program messages and response messages:

Numeric Commands that require numeric parameters will accept all commonly used representations of numbers like integer (also known as NR1 format specified in ANSI X3.42-1990) or decimal representations of numbers including optional signs, decimal points (NR2 format), and scientific notation (i.e. 10E3 or NR3 format). Special values for numeric parameters like MINimum, MAXimum, and DEFault are also accepted. You can also send engineering unit suffixes (V, A, or SEC) with numeric parameters. If only specific numeric values are accepted, the PSU will automatically round the input numeric parameters. The following command uses a numeric parameter:

```
VOLT:STEP {<step>}
```

Discrete Used to program settings that have a limited number of values such as BUS and IMM or CH1 and CH2. Query responses will always return the short form in all uppercase letters. The following command uses discrete parameters:

```
CAL:CURR:LEV {MIN|MID|MAX}
```

Boolean Represent a single binary condition that is either true or false. For a false condition, the PSU will accept OFF or 0. For a true condition, the PSU will accept ON or any nonzero value (i.e. 1 but also 2.34 or -3). When you query a Boolean setting, the PSU will always return 0 or 1. The following command uses a Boolean parameter:

```
OUTP {OFF | ON }
```

String Can contain virtually any set of ASCII characters. A string must begin and end with matching quotes, either with a single quote or with a double quote. You can include the quote delimiter as part of the string by typing it twice without any characters in between. The following command uses a string parameter:

```
CAL: REM <quoted string>
```

3. Registers and queues

SCPI requires the status mechanism described in Section 11 of IEEE 488.2, including full implementation of the status register structure. Summary of implemented registers structure for the PSU is shown on Fig. 1. (commands used to access registers are written in parentheses).

All SCPI instruments have to implement status registers in the same way. The status system records various instrument conditions in the following register groups:

- · the Status Byte register,
- · the Standard Event register,
- the QUEStionable Status register group, and
- the OPERation Status register group.

The Status Byte register records high-level summary information reported in the other register groups. Message interchanging between Controller and Instrument is accomplished by using input buffer and Output queue and Error queue. The length of the Input buffer is 48 characters. Both Output and Error queue can handle up to 20 messages.

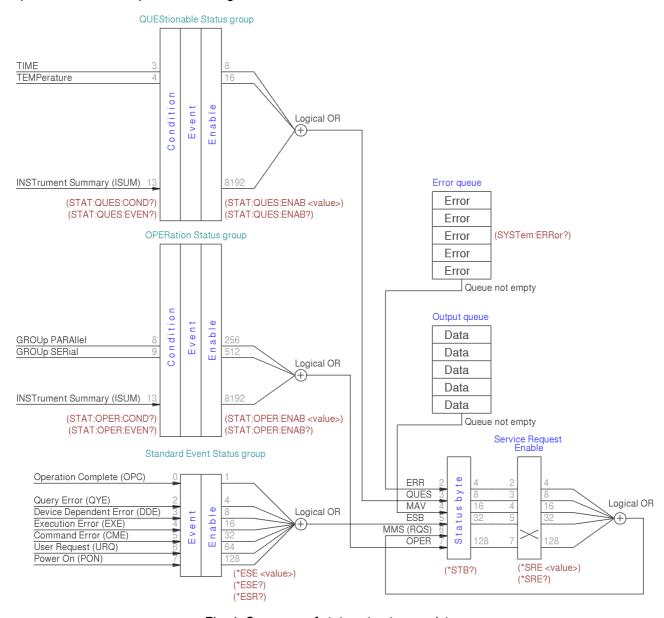


Fig. 1: Summary of status structure registers

3.1. Standard Event Status Register

An status register group is consist of Condition, Event and Enable registers (see Fig. 1):

- The Condition register is a read-only register, which holds the live (unlatched) operational status of the instrument. Reading the Condition register does not clear it.
- The Event register is a read-only that reports defined conditions within the PSU. Bits in an event register are latched. Once an event bit is set, subsequent state changes are ignored. Bits in the Event register are automatically cleared by a query of that register (such as *ESR? or STATus:QUEStionable:EVENt?) or by sending the *CLS (clear status) command. A reset (*RST) or device clear will not clear bits in event registers (See Section 8.2). Querying an event register returns a decimal value which corresponds to the binary-weighted sum of all bits set in the register.
- The ENABle register is used to define which bits of the Event Status register will latch ESB (bit 5) of the Status byte register.

An error status (bit 2, 3, 4 or 5) records one or more errors in the PSU error queue. The SYSTem:ER-Ror? command can be used to read the error queue.

Implementation of the Standard Event Status register follows IEEE 488.2 Section 11.5.1.1:

Bit	Decimal value	Description	
0	1	Operation Complete (OPC) – This event bit is generated in response to the *OPC command. It indicates that the PSU has completed all selected pending operations (including *OPC).	
1	2	Not used	
2	4	Query ERROR (QYE) – Query Errors are detected by the Output Queue Control. This event bit indicates that either	
		 An attempt is being made to read data from the Output Queue when no output is either present or pending, or Data in the Output Queue has been lost. 	
		Events that generate Query Errors do not generate Execution Errors, Command Errors, or Device-Specific Errors.	
3	8	Device-Specific ERROR (DDE) – This event bit indicates that an error has occurred that is neither a Command Error, a Query Error, nor an Execution Error. A Device-Specific Error is any executed device operation that did not properly complete due to some condition, such as over-range, a self-test or calibration error. Following a Device-Specific Error, the PSU will continue to process the input stream. Events that generate Device-Specific Errors do not generate Command Errors,	
		Query Errors, or Execution Errors.	
4	16	Execution ERROR (ERR) – This event bit indicates that:	
		 A <program data=""> element following a header was evaluated by the PSU as outside of its legal input range or is otherwise inconsistent with the PSU's capabilities.</program> A valid program message could not be properly executed due to some PSU condition. 	
		Following an Execution Error, the PSU will continue parsing the input stream. Execution Errors will be reported by the PSU after rounding and expression evaluation operations have taken place. Rounding a numeric data element, for example, will not be reported as an Execution Error. Events that generate Execution Errors do not generate Command Errors, Query Errors, or Device-Specific Errors.	
5	32	Command ERROR (CME) - Command Errors are detected by the parser. This	

event bit indicates that one of the following events has occurred:

- An IEEE 488.2 syntax error has been detected by the parser. That is, a
 controller-to-device message was received that is in violation of this
 standard. Possible violations include a data element that violates the device
 listening formats or whose type is unacceptable to the device (see also IEEE
 488.2 Section 7.1.2.2).
- A semantic error has occurred indicating that an unrecognized header was received. Unrecognized headers include incorrect device-specific headers and incorrect or unimplemented common commands described in <u>Section 4</u>
- A Group Execute Trigger (GET) was entered into the Input Buffer inside of a <PROGRAM MESSAGE> (see also IEEE 488.2 Section 6.1.6.1.1 and 6.4.3.).

When the PSU detects a Command Error, parser synchronization may be lost. When a Command Error is detected, any prior parsable elements of the same <PROGRAM MESSAGE> will be executed. That is also true for all parsable elements that follows after detected Command Error.

The Command Error bit not be set to report any other device-specific condition. Events that are reported as Command Errors cannot be reported as Execution Errors, Query Errors, or Device-Specific Errors.

- 6 User Request (URQ) This event bit indicates that the PSU input device (TFT Touch screen) has been for any reason activated. The setting of this event-bit occur regardless of the IEEE 488.1 Remote/Local state of the device (not supported in M1)
- Power On (PON) This event bit indicates that an off-to-on transition has occurred in the device's power supply. See also SYSTem:POWer.
- 8-15 Not used, always zero

3.2. Status Byte Register

The Status Byte summary register reports conditions from the other status registers (see Fig. 1). Query data that is waiting in the PSU's output buffer is immediately reported through the "Message Available" (MAV) bit (bit 4) of the Status Byte register. Bits in the summary register are NOT latched. Clearing an event register will clear the corresponding bits in the Status Byte summary register. Reading all messages in the output buffer, including any pending queries, will clear the message available bit (MAV). The Status Byte summary register is cleared when the *CLS (clear status) command has been executed

The Status Byte enable register (request service) is cleared when the *SRE 0 command has been executed.

Querying the Standard Event register (*ESR? command) will clear only bit 5 (ESR) in the Status Byte summary register. For example, 24 (8 + 16) is returned when you have queried the status of the Status Byte register, QUES and MAV conditions have occurred.

Bit	Decimal value	Description
0-1	_	Not used, always zero
2	4	ERR – Error queue bit indicates that one or more errors have been stored in the Error queue.
3	8	QUES – One or more bits are set in the QUEStionable Status register (bits must be enabled in the enable register).
4	16	MAV – The Message Available bit indicates whether or not the Output Queue is empty. Whenever the device is ready to accept a request by the controller to output data bytes, the MAV is TRUE. The MAV is FALSE when the Output Queue is empty. This bit is used to synchronize information exchange with the controller. The con-

troller can, for example, send a query command to the device and then wait for MAV to become TRUE.

- 5 32 ESB One or more bits are set in the Standard Event register (bits must be enabled in the enable register, see *ESE command).
- 6 MMS Master Status summary bit indicates that one or more bits are set in the Status Byte Register (bits must be enabled, see *SRE command). Also used to indicate a request for service (RQS).
- 7 128 OPER One or more bits are set in the OPERation Status register.

3.3. OPERation Status Register

The OPERation status register contains conditions which are part of the instrument's normal operation. Each channel of the PSU is considered as separate "instrument". The two logical outputs (channels) of the PSU include an INSTrument summary status register and an individual instrument ISUMmary register for each logical output.

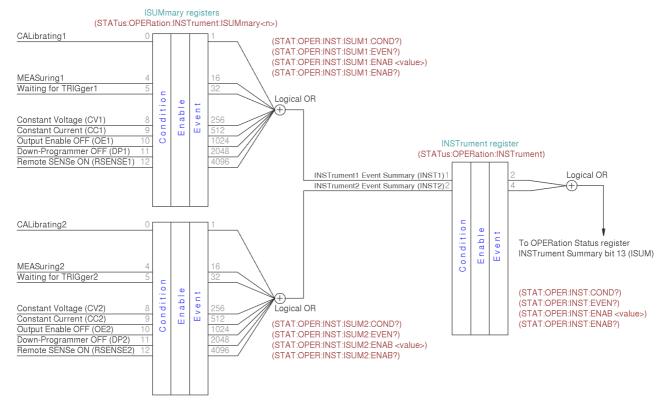


Fig. 2: OPERation Status registers summary

The bit definition of OPERation Status register shown on Fig.1.:

Bit	Decimal value	Description
0-7	_	Not used, always zero
8	256	GROUp PARAllel indicate that PSU's channels are connected in parallel.
9	512	GROUp SERial indicate that PSU's channels are connected in serial.
10-12	-	Not used, always zero
13	8192	INSTrument Summary Bit – One of n multiple logical instruments is reporting OP-ERational status.
14-15	_	Not used, always zero

The Event Status Enable register is cleared when the STAT:EVEN:ENAB 0 command is executed. The

*CLS command can be also used to clear the register.

3.3.1. Operation INSTrument Status register

The bit definition of OPERation INSTrument Status register shown on Fig. 2.:

Bit	Decimal value	Description
0	_	Not used, always zero
1	2	INST1 – Instrument1 summary bit indicate that one or more bits are changed in the Channel 1 OPERation INSTrument Summary register
2	4	INST2 – Instrument2 summary bit indicate that one or more bits are changed in the Channel 2 OPERation INSTrument Summary register
3-15	_	Not used, always zero

3.3.2. Operation Instrument SUMmary status register

The ISUMmary registers report to the INSTrument register, which in turn reports to bit 13 of the Operation Status register. This is illustrated on Fig. 2. Using such a status register configuration allows a status event to be cross- referenced by output channel and type of event. The INSTrument register indicates which channel(s) have generated an event. The ISUMmary register represent a pseudo-operation Status register for a particular logical output.

The bit definition of OPERation INSTrument ISUMmary Status register shown on Fig.2.:

Bit	Decimal value	Description
0	1	CALibrating – Channel is performing calibration
1-3	_	Not used, always zero
4	16	MEASuring – Channel is performing measurement (not supported in M1)
5	32	Waiting for TRIGger – Channel is waiting for the trigger event (not supported in M1)
6-7	_	Not used, always zero
8	256	CV – Channel is entered CV operation mode
9	512	CC – Channel is entered CC operation mode
10	1024	OE – Output is switched off
11	2048	DP – Down-programmer is switched off
12	4096	RSENSE – Remote sense is switched on
13-15	_	Not used, always zero

3.4. QUEStionable Status Register

The Questionable Status register provides information about unexpected operations of the PSU. Each channel of the PSU is considered as separate "instrument". The two logical outputs (channels) of the PSU include an INSTrument summary status register and an individual instrument ISUMmary register for each logical output.

The ISUMmary registers report to the INSTrument register, which in turn reports to bit 13 of the Questionable Status register. This is illustrated on Fig. 3. Using such a status register configuration allows a status event to be cross-referenced by output channel and type of event. The INSTrument register indicates which channel(s) have generated an event. The ISUMmary register represent a pseudo-Questionable Status register for a particular logical output.

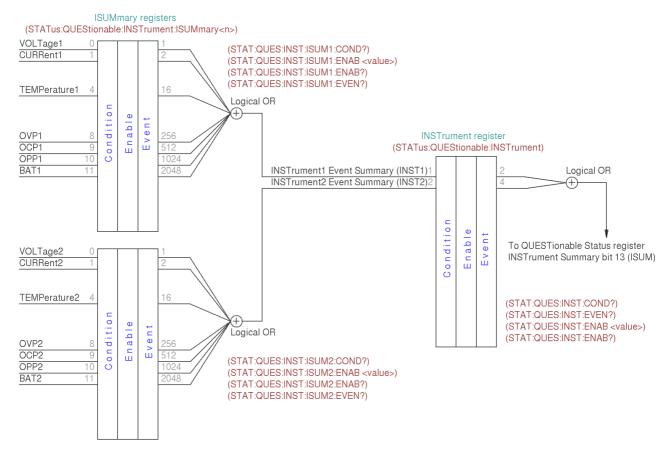


Fig. 3: QUEStionable INSTrument registers summary

For example, if one of the two channels is in constant voltage (CV) mode and due to an overload looses regulation, bit 13 is set (latched). To read the register, the command STATus:QUEStionable? is required. To make use of bit 13 (ISUM), enable register must be correctly set. The command STAT:QUES:INST:ENAB 6 (2 + 4) has to be send to enable the Questionable instrument register, followed by the command STAT:QUES:INST:ISUM<n>:ENAB 19 for each channel to enable the QUEStionable INSTrument SUMmary register, where n is 1 or 2.

Bit definition for QUEStionable Status register shown on Fig.1.:

Bit	Decimal value	Description
0-2	_	Not used, always zero
3	8	TIME – indicate abnormal time/date situation due to RTC failure or conflict between current and time/date retrieved from the stored configuration.
4	16	TEMPerature – temperature measurement that use the temperature sensor on the Arduino Shield board require attention (i.e. over-temperature condition is detected, sensor is not functional, etc.). Do not confuse this sensor with that are connected to a PSU channels.
5-12	_	Not used, always zero
13	8192	INSTrument summary, is described later in this chapter in association with multiple logical instruments.
14-15	_	Not used, always zero

The Questionable Status Enable register is cleared when the STAT:QUES:ENAB 0 command is executed. The *CLS command can be also used to clear the register.

3.4.1. Questionable INSTrument Status register

Bit definition for QUEStionable INSTrument register:

Bit	Decimal value	Description
0	_	Not used, always zero
1	2	INST1 – Instrument1 summary bit indicate that one or more bits are changed in the Channel 1 OPERation INSTrument Summary register.
2	4	INST2 – Instrument2 summary bit indicate that one or more bits are changed in the Channel 2 OPERation INSTrument Summary register.
3-15	-	Not used, always zero

3.4.2. Questionable Instrument SUMmary status register

There are two questionable instrument summary registers, one for each PSU output. These registers provide information about voltage and current regulation.

Bit definition for QUEStionable INSTrument SUMmary register:

Bit	Decimal value	Description
0	1	VOLTage – This bit is set when the voltage becomes unregulated, therefore a channel enters CC operation mode. If the over-voltage protection (OVP) is activated (see VOLTage:PROTection:STATe) channel output will be switched off.
1	2	CURRent – This bit is set when the current becomes unregulated, therefore a channel enters CV operation mode. If the over-current protection (OCP) is activated (see CURRent:PROTection:STATe) channel output will be switched off.
2-3	_	Not used, always zero
4	16	TEMPerature – one of the temperature sensor (heatsink or battery) on the channel power board require attention (i.e. over-temperature condition is detected, sensor is not functional, etc.). Do not confuse this sensor with one that is connected to the Arduino shield board.
5-7	_	Not used, always zero
8	256	OVP – Over-voltage protection is activated. The query VOLT:PROT:TRIP? returns value of this bit. See also STAT:QUES.
9	512	OCP – Over-current protection is activated. The query CURR:PROT:TRIP? returns value of this bit. See also STAT:QUES.
10	1024	OPP – Over-power protection is activated. The query POW:PROT:TRIP? returns value of this bit. See also STAT:QUES.
11	2048	BAT – Over-temperature protection triggered by battery temperature sensor is activated. The query TEMP:PROT:TRIP? BAT <n> returns value of this bit. See also STAT:QUES.</n>
12-15	_	Not used, always zero

Please note here that CURRent bit is use for questionable Voltage operating mode and vice versa. If 0 and 1 bits is true that indicate neither the voltage nor the current is regulated (so-called unregulated or UR mode), and both bits false indicate the PSU channel are off.

To read the register for each PSU channel, the command STAT:QUES:INST:ISUM[<n>]? has to be send, where [<n>] is 1 or 2. If [<n>] is not specified the currently selected channel is used. Use STAT:QUES:INST:ISUM<n>:COND? to determine operating mode (CV or CC) for the PSU channel (where n is 1 or 2 depending on the output).

The Questionable Status event register is cleared with:

- the *CLS (clear status) command or
- the event register is queried using the STAT:QUES? (status questionable event register) command.

3.5. Error queue

The error queue contains items that include a numerical and textual description of the error or event. The <Error/event_number> is a unique integer in the range [-32768, 32767]. All positive numbers are instrument-dependent. All negative numbers are reserved by the SCPI standard with certain standard error/event codes. The value, zero, is also reserved to indicate that no error or event has occurred. The second parameter of the full response is a quoted string containing an <Error/event_description>. Each <Error/event_number> has a unique and fixed <Error/event_description> associated with it. An example:

```
-113, "Undefined header"
```

The maximum string length of <Error/event_description> plus <Device-dependent_info> is 255 characters. List of all error/event messages can be found in <u>Section 7</u> of this document.

As errors and events are detected, they are placed in a queue. This queue is first in, first out. If the queue overflows, the last error/event in the queue is replaced with error:

```
-350, "Queue overflow"
```

Any time the queue overflows, the least recent errors/events remain in the queue, and the most recent error/event is discarded. Reading an error/event from the head of the queue removes that error/event from the queue, and opens a position at the tail of the queue for a new error/event, if one is subsequently detected.

If the error queue is not empty, bit 2 of the Instrument Summary Status Register is set. A query returns only the oldest error code and associated error description information from the error queue. To return all error codes and associated description information, use repetitive queries until an error value of zero is returned, or until bit 2 of the status register is 0.

The error queue is cleared when any of the following occur (IEEE 488.2, section 11.4.3.4):

- Upon power up
- Upon receipt of a *CLS command
- Upon reading the last error message from the queue

4. Common command reference

This section summarizes the mandatory subset of IEEE 488.2 commands that is a requirement for any SCPI compliant instrument.

Common command	Description
*CLS	Clears all status data structures
*ESE { <value>}</value>	Programs the Standard Event Status Enable register bits
*ESR?	Reads the Standard Event Status Register
<u>*IDN?</u>	Returns the UNIQUE identification of the PSU
<u>*OPC</u>	Operation Complete Command used for program synchronization
*RCL { <profile>}</profile>	Recalls the PSU state stored in the specified storage location
<u>*RST</u>	Reset PSU to the initial state
*SAV { <profile>}</profile>	Stores the current PSU state in the specified storage location
<u>*STB?</u>	Reads the Status Byte register
<u>*TST?</u>	Returns Self-Test results

4.1. *CLS

Syntax *CLS

Description Clear Status Command. This command clears all status data structures in the PSU:

Standard Event Status RegisterOPERation Event Status Register

QUEStionable Event Status Register

· Error/Event Queue

The corresponding condition and enable registers are unaffected. If *CLS immediately follows a program message terminator (<NL>), then the output queue and the MAV bit are also cleared.

Return None Related *ESR?

Commands STATus:OPERation[:EVENt]

STATus:OPERation:INSTrument[:EVENt]

STATus:OPERation:INSTrument:ISUMmary[<n>][:EVENt]

STATus:QUEStionable[:EVENt]

STATus:QUEStionable:INSTrument[:EVENt]

STATus:QUEStionable:INSTrument:ISUMmary[<n>][:EVENt]

SYSTem:ERRor

4.2. *ESE

Syntax *ESE {<value>}

*ESE?

Description Standard Event Status Enable Command. This command programs the Standard

Event Status Enable register bits. The programming determines which events of the Standard Event Status Event register (see *ESR?) are allowed to set the ESB (Event Summary Bit) of the Status Byte register. A 1 in the bit position enables the corresponding event. All of the enabled events of the Standard Event Status Event Register are logically ORed to cause the Event Summary Bit (ESB) of the Status Byte Register

to be set.

A STATus:PRESet command does not clear the bits in the Status Byte register.

See also <u>Section 3.1</u> in this document.

Parameters Name Type Range Default

<value> Numeric 0 - 255 (A decimal value which None

> corresponds to the binary-weighted sum of the bits in the register. See

also table in Section 3.1).

The query reads the enable register and returns a decimal value which corresponds to Return

the binary-weighted sum of all bits set in the register.

Usage To enable bit 2 (decimal value = 4), bit 3 (decimal value = 8), and bit 7 (decimal value example

= 128), the corresponding decimal value would be 140 (4 + 8 + 128):

*ESE 140

Read value of the Standard Event Status Enable register:

*ESE? 140

-200, "Execution error" **Errors**

Related *CLS *RST Commands

STATus:PRESet

4.3. *ESR?

*ESR? Syntax

Description Standard Event Status Register (see Section 3.2) Query. Reading the Standard Event

Status Event register clears it.

Return The PSU returns a decimal value which corresponds to the binary-weighted sum of all

bits in the register.

Usage If ERRor (bit 2) is set:

example

ESR?

4.4. *IDN?

*IDN? Syntax

Description Identification query for the UNIQUE identification of the PSU. (see also IEEE 488.2

10.14).

Return The following system parameters will be displayed: <vendor>, <model>, <serial num-

> ber>, <firmware>. The <model> include information about used MCU in brackets and could be Mega, Due or Simulator. More information about simulator could be found in

Section 9.

*IDN? Usage

example EEZ, PSU 2/50/03 (Due), 00001, M1.0.96

4.5. *OPC

Syntax *OPC

*OPC?

Description Operation Complete Command. The command is mainly used for program synchro-

nization. It causes the PSU to set the OPC bit (bit 0) of the Standard Event Status register when the PSU has completed all pending operations sent before *OPC. Pending

operations are complete when:

All commands sent before *OPC, including paralleled commands, have been completed. Most commands are sequential and are completed before the next command is executed. Commands that affect output voltage, current, or state,

relays, and trigger actions are executed in parallel with subsequent commands. *OPC provides notification that all parallel commands have completed.

· All triggered actions are completed.

Query whether the current operation is completed and the query returns 1.

See also IEEE 488.2 Section 12.5 – 12.8.

Return Query causes the PSU to place a 1 in the output buffer when all pending operations

are completed. *OPC? does not suspend processing of commands.

Usage *OPC? example 1

if current operation is not completed:

*OPC?

4.6. *RCL

Syntax *RCL {<profile>}

Description This command recalls the PSU state stored in the specified storage location. The PSU

has ten storage locations in non-volatile memory to store PSU states.

It is not possible to recall the PSU state from a storage location that is empty or was deleted. When the firmware is started for the first time, storage locations 1 through 9

are empty (location 0 has the power-on state).

The PSU uses location 0 to automatically hold the state of the PSU at power down.

Parameters	Name	Type	Range	Default
	<pre><pre><pre><pre><pre><pre><pre><pre></pre></pre></pre></pre></pre></pre></pre></pre>	Numeric	0 – 9	None
Return	None			
Usage example	*RCL 2			
Errors				
Related Commands	*SAV MEMory:STATe:DELe MEMory:STATe:REC MEMory:STATe:REC	all:AUTO		

4.7. *RST

Syntax *RST

Description Reset Command. Restore the PSU to initial state (as predefined in the PSU firmware,

see Section 8.2) and clear the error queue. The reset command explicitly will NOT af-

fect calibration data nor any of saved configuration profiles (0 to 9).

When *RST is issued all output are set to OFF, and voltage and current are programmed to 0. Power up sequence is started. All SPI peripherals are reinitialize ex-

cept Ethernet controller if an active Ethernet connection exists.

Return None Usage *RST

SYSTem: POWer

SYSTem:POWer

Related *RST Commands *SAV MEMory:STATe:CATalog?

4.8. *SAV

Syntax

*SAV {<profile>}

Description

This command stores the current instrument state in the specified storage location. Any state previously stored in the same location is overwritten without generating any errors. The PSU has nine storage locations in non-volatile memory available to user to store current PSU states. The following channel and system parameters will be stored in the non-volatile memory:

- Calibration status (<u>CALibration:STATe</u>)
- Output enable state (<u>OUTPut[:STATe]</u>)
- Remote sense state (<u>OUTPut:SENSe</u>)
- Output voltage ([SOURce[<n>]]:VOLTage)
- Output voltage step ([SOURce[<n>]]:VOLTage:STEP)
- OVP status ([SOURce[<n>]]:VOLTage:PROTection:STATe)
- OVP delay (<u>[SOURce[<n>]]:VOLTage:PROTection:DELay</u>)
- Output current ([SOURce[<n>]]:CURRent)
- Output current step ([SOURce[<n>]]:CURRent:STEP)
- OCP status (<u>[SOURce[<n>]]:CURRent:PROTection:STATe</u>)
- OCP delay (<u>[SOURce[<n>]]:CURRent:PROTection:DELay</u>)
- OPP level ([SOURce[<n>]]:POWer:PROTection[:LEVel])
- OPP status ([SOURce[<n>]]:POWer:PROTection:STATe)
- OPP delay (<u>[SOURce[<n>]]:POWer:PROTection:DELay</u>)
- OTP level (<u>SYSTem:TEMPerature:PROTection[:HIGH][:LEVel]</u>)
- OTP status (<u>SYSTem:TEMPerature:PROTection[:HIGH]:STATe</u>)
- OTP delay (<u>SYSTem:TEMPerature:PROTection[:HIGH]:DELay</u>)
- Power on state (SYSTem:POWer)
- Simulator load value (SIMUlator:LOAD)
- Simulator load connection (<u>SIMUlator:LOAD:STATe</u>)

You can assign a user-defined name to each of locations 1 through 9 using the <u>MEMory:STATe:NAME</u> command.

A reset (*RST command) does not affect the configurations stored in memory. Once a state is stored, it remains until it is overwritten using this command or specifically deleted using the MEMory:STATe:DELete command.

The PSU uses location 0 to automatically hold the state of the PSU at power down.

Parameters	Name	Type	Range	Default
	<pre><pre><pre><pre><pre><pre><pre><pre></pre></pre></pre></pre></pre></pre></pre></pre>	Numeric	1 – 9	None
Return	None			
Usage example	*SAV 2			
Related Commands	*RCL *RST MEMory:STATe:CATalog? MEMory:STATe:NAME MEMory:STATe:DELete			

4.9. *STB?

Syntax

*STB?

Description

Read Status Byte Query. This query reads the Status Byte register (see <u>Section 3.2</u>), which contains the status summary bits and the Output Queue MAV bit. The Status

Byte is a read-only register and the bits are not cleared when it is read.

A serial poll also returns the value of the Status Byte register, except that bit 6 returns Reguest for Service (RQS) instead of Master Status Summary (MSS). A serial poll clears RQS, but not MSS. When MSS is set, it indicates that the PSU has one or more

reasons for requesting service.

Return The PSU returns a decimal value which corresponds to the binary-weighted sum of all

bits in the register.

If OPER (bit 7) is set: Usage

example *STB? 128

Related *SRE

Commands

4.10. *TST?

Syntax *TST?

Description Self-Test Query. The self-test query causes an internal self-test and places a response

into the Output Queue indicating whether or not the PSU completed the self-test with-

out any detected errors.

Ensure that all terminal connections are removed while the internal self-test is being

performed.

If an active Ethernet connection exists, testing of Ethernet controller will be skipped. You can use DIAGnostic[:INFOrmation]:TEST? for guery detailed report of the latest

self-test.

Return 0 or 1 depends of the self-test results. See also DIAGnostic[:INFOrmation]:TEST?.

Usage If all tests passed:

example

*TST? 0

If one or more tests failed:

*TST? 1

Related

DIAGnostic[:INFOrmation]:TEST?

Commands SYSTem:BEEP:STATe

5. Subsystem command reference

This section summarizes the Standard Commands for Programmable Instruments (SCPI) available to program the PSU over the remote interface.

- CALibrate
- DIAGnostic
- INSTrument
- MEASure
- MEMory
- OUTPut
- SOURce
- STATus
- SYSTem

5.1. CALibrate

This subsystem provides commands for the PSU calibration. Only one channel can be calibrated at a time. If calibration mode has not been enabled with CALibrate:STATe, the calibration commands will generate an error. Use CALibrate:SAVE to save any changes, otherwise all changes will be lost on exit from calibration mode. Within the same calibration session both output voltage and current can be calibrated for the currently selected channel.

SCPI Command	Description
<pre>CALibrate[:MODE] {<bool>, <password>}</password></bool></pre>	Enables/disables calibration mode
:CLEar { <password>}</password>	Clears all calibration parameters
:CURRent	
[:DATA] { <new value="">}</new>	Enters the calibration value
:LEVel { <level>}</level>	Calibrates the output current programming
:PASSword	
:NEW { <old>, <new>}</new></old>	Changes calibration password
:REMark { <string>}</string>	Saves calibration information
:SAVE	Saves the new cal constants in non-volatile memory
:STATe { <bool>, <password>}</password></bool>	Enables calibration parameters
:VOLTage	
[:DATA] { <new value="">}</new>	Enters the calibration value
:LEVel { <level>}</level>	Calibrates the output voltage programming

5.1.1. CALibration[:MODE]

Syntax CALibration[:MODE] {<bool> <password>} CALibration[:MODE]?

CALIDIATION[.IVIODE]

Description This command enables or disables calibration mode. Calibration mode must be enabled for the channel to accept any calibration commands. The first parameter specifies the ON (1) or OFF (0) state. The second parameter is the password. Successful execution of this command set both output VOLTage and CURRent of the selected channel to the MINimum value (see Section 8.1).

Execution of this command also affects bit 0 (CALibrating) of the Operation Instrument Isummary register (see <u>Section 3.3.2</u>).

If both voltage and current calibration parameters exists on calibration mode exit (CALibration[:MODE] OFF) the CALibration:STATe ON command will automatically follows.

Parameters Name Type Range Default

Return The returned parameter is 0 (OFF) or 1 (ON).

Usage See <u>Section 10.2</u>

example

Errors 102, "Invalid cal password"

104, "Bad sequence of calibration commands"

Related CALibration:STATe

Commands DIAGnostic[:INFOrmation]:OTIMe?

5.1.2. CALibration:CLEar

Syntax CALibration:CLEar {<password>}

Description Clear all calibration parameters stored in the non-volatile memory for the currently select-

ed channel. After successful execution of this command CALibration:STATe will be set to OFF (0) and further usage of the calibration data will be disabled. This command will be also filled calibration remark with the date and note that calibration data has been

cleared.

Usage CAL:STAT example 1

CAL:CLE

CAL:STAT?

0

DIAG: CAL?

"remark=2015-11-02 Not calibrated", "u cal params exists=0",

"i cal params exists=0"

Errors 102, "Invalid cal password"

Related CALibration:STATe

Commands DIAGnostic[:INFOrmation]:CALibration?

5.1.3. CALibration:CURRent[:DATA]

Syntax CALibration:CURRent[:DATA] {<new value>}

Description This command can only be used when calibration is enabled and the output state of the

currently selected channel is ON. It enters a current value that is obtained by reading an external meter. The minimum calibration level (CAL:CURR:LEV MIN) has to be selected first for the value being entered, then the middle and maximum calibration levels (CAL:CURR:LEV MID and CAL:CURR:LEV MAX) for the value being entered. Three successive values must be selected and entered. Data values are expressed in base

units – either volts or amperes, depending on which function is being calibrated.

Parameters Name Type Range Default

<new value> numeric (NR2) -0.2A to MAX + 0.2A -

The maximum value is dependent on the PSU current rating.

See Section 8.1

Return None

Usage See Section 10.2

example

Errors 104, "Bad sequence of calibration commands"

107, "Cal value out of range"

5.1.4. CALibration:CURRent:LEVel

Syntax CALibration:CURRent:LEVel {<level>}

Description This command can only be used when calibration is enabled and the output state of the

currently selected channel is ON. It sets the PSU to a calibration point that is entered with the CAL:CURR command. During calibration, three points must be entered and the

low-end point (MIN) must be selected and entered first.

This command will set output voltage to MAXimum / 2 (for example 25V for the PSU

also Section 8.1)

model with 0-50V).

Parameters Name Type Range Default

<level> Discrete MINIMIDIMAX (see –

Return None

Usage See Section 10.2

example

Errors 101, "Calibration mode is off"

104, "Bad sequence of calibration commands"

Related CALibration:STATe Commands INSTrument:NSELect

INSTrument[:SELect]

5.1.5. CALibration:PASSword:NEW

Syntax CALibration:PASSword:NEW {<old code>, <new code>}

Description Enter a new calibration password. To change the password, first unsecure the PSU using

the old password. Then, the new code has to be entered. The calibration code may contain up to 16 characters over the remote interface. Minimum length is 4 characters.

The new password is automatically stored in nonvolatile memory and does not have to

be stored with CALibrate:SAVE.

Parameters Name Type Range Default

 <old code>
 <new code>
 Quoted string 4 to 16 characters –
 4 to 16 characters –

Return None

Usage See <u>Section 10.2</u>

example

Errors 102, "Invalid cal password"

105, "Cal password too long"

106, "Cal password too short"

5.1.6. CALibration:REMark

Syntax CALibration:REMark {<user remark>}

CALibration:REMark?

Description Record calibration information about the PSU. The calibration message is consist of two

parts:

datetime stamp in format yyyymmdd and

up to 32 characters.

The PSU should be in calibration mode before sending a calibration message.

Parameters Name Default Type Range <user remark> Quoted string 0 to 32 characters "Calibration passed" Return Query the calibration message. Usage When CAL:REM with text "Calibrated by EEZ" is executed at 2015-09-14: example CAL: REM "Calibrated by EEZ" CAL: REM? "20150904 Calibrated by EEZ" See also Section 10.2 **Errors** The following errors could be generated by command but not query: 101, "Calibration mode is off" 104, "Bad sequence of calibration commands"

Related CALibration:STATe Commands

5.1.7. CALibration:SAVE

Syntax CALibration:SAVE

Description This command saves calibration constants in non-volatile memory after the calibration procedure has been completed. If calibration mode is exited by programming CALibra-

tion:STATe OFF without first saving the new constants, the previous constants are restored. Execution of this command also affects bit 0 (CALibrating) of the Operation In-

strument Isummary register (see <u>Section 3.3.2</u>).

Return None

Usage See <u>Section 10.2</u>

example

Errors -340, "Calibration failed"

104, "Bad sequence of calibration commands"

111, "No new cal data exists"

5.1.8. CALibration:STATe

Syntax CALibration:STATe {<bool>}

CALibration:STATe?

Description This command enables or disables usage of calibration parameters if they exists.

Parameters Name Type Range Default

<bool> Discrete OFFIONI0I1 ON

Return The returned parameter is 0 (OFF) or 1 (ON).

Usage

CAL:STAT OFF, "eezpsu"

example

Errors 110, "Cal params missing or corrupted"

Related DIAGnostic[:INFOrmation]:OTIMe?

Commands

5.1.9. CALibration:VOLTage[:DATA]

Syntax CALibration: VOLTage[:DATA] {<new value>}

Description This command can only be used when calibration is enabled and the output state of the

currently selected channel is ON. It enters a voltage value that you obtained by reading an external meter. You must first select the minimum calibration level (CAL:VOLT:LEV MIN) for the value being entered. You must then select the middle and maximum calibration levels (CAL:VOLT:LEV MID and CAL:VOLT:LEV MAX) for the value being entered. Three successive values must be selected and entered. The PSU then computes new voltage calibration constants. These constants has to be stored in non-volatile memory with CALibration:SAVE command.

Parameters	Name	Type	Range	Default
	<new value=""></new>	numeric (NR2)	-0.5V to MAX + 0.5V The maximum value is dependent on the PSU voltage rating. See Section 8.1	-
Return	None			
Usage example	See Section <u>Section 10.2</u>			
Errors	104, "Bad sequence of calibration commands" 107, "Cal value out of range"			
Related Commands	CALibration:SAVE s CALibration:STATe INSTrument:NSELect INSTrument[:SELect]			

5.1.10. CALibration: VOLTage: LEVel

Syntax CALibration: VOLTage: LEVel {<level>}

Description This command can only be used when calibration is enabled and the output state of the

currently selected channel is ON. It sets the PSU to a calibration point that is entered with the CAL:VOLT[:DATA] command. During calibration, three points must be entered

and the low-end point (MIN) must be selected and entered first.

This command will set output current to 50mA.

Parameters	Name	Type	Range	Default
	<level></level>	Discrete	MIN MID MAX (see also <u>Section 8.1</u>)	_
Return	None			
Usage example	See Section <u>Section 10.2</u>			
Errors	101, "Calibration mode is 104, "Bad sequence of cal		commands"	

5.2. DIAGnostic

The purpose of the DIAGnostic subsystem is to provide a tree node for all of the PSU service and diagnostic routines used in routine maintenance and repair.

SCPI command	Description		
DIAGnostic			
[:INFOrmation]			
:ADC?	Returns the latest values acquired by ADC		
:CALibration?	Returns a list of the calibration parameters		
:PROTection?			
:TEST?	Returns results of the most recent self-test		

5.2.1. DIAGnostic[:INFOrmation]:ADC?

Syntax DIAGnostic[:INFOrmation]:ADC? [<channel>]

Description This guery returns the latest values acquired by ADC (Analog-to-Digital Converter) of the

currently selected channel.

Return a list of quoted strings. The U SET and I SET are values measure on DAC out-Return

puts, and U MON and I SET on the channel output binding posts.

Parameters Name Type Range Default <channel> Discrete CH1|CH2 n/a Usage DIAG:ADC? CH2

example "U SET=10.1202", "U MON=10.12", "I SET=3.00", "I MON=1.23"

Errors Related

Commands

5.2.2. DIAGnostic[:INFOrmation]:CALibration?

DIAGnostic[:INFOrmation]:CALibration? [<channel>] Syntax

This guery returns a list of calibration parameters for the currently selected channel. If the Description

> selected channel is in the calibration mode (CALibration[:MODE] ON) then all calibration information collected to the current calibration step will be returned. Otherwise the cali-

bration data stored in non-volatile memory will be returned.

Return The information will be returned as a list of quoted strings.

Parameters Name Type Range Default

<channel> Discrete CH1|CH2 n/a

Usage example Calibration parameters for an 0-40V/0-5A PSU model when the channel 1 is not in the calibration mode:

DIAG: INFO: CAL? CH1

```
"remark=20151013 New calibration test", "u cal params exists=1",
"u_min_level=0.1V", "u_min_data=0.032V", "u_min_adc=0.06V",
```

"u_mid_level=19.05V", "u_mid_data=18.99V", "u_mid_adc=19.007V", "u_max_level=38.0V", "u_max_data=37.9V", "u_max_adc=37.955V",

"i cal params exists=1", "i min level=0.01A",

"i_min_data=0.005A", "i_min_adc=0.019A", "i_mid_level=2.455A", "i_mid_data=2.45A"; "i_mid_adc=2.464A", "i_max_level=4.9A",

"i max data=4.82A", "i max adc=4.842A"

The query results when a channel is just entered the calibration mode:

```
DIAG:INFO:CAL?
"u level=none", "i level=none"
```

The query results when a channel is at the step MIDdle of the voltage calibration:

```
DIAG:INFO:CAL?
"u_min=0.11V", "u_level=mid", "u_level_value=24.05V",
"u_adc=24.14V", "i_level=none"
```

Related CALibration:REMark Commands CALibration:SAVE

5.2.3. DIAGnostic[:INFOrmation]:PROTection?

Syntax DIAGnostic[:INFOrmation]:PROTection?

Description This query returns information about all currently supported protections.

Return The information will be returned as a list of quoted strings.

Usage example

DIAG: PROT?

"CH1 u_tripped=0","CH1 u_state=0","CH1 u_delay=0.10 s","CH1 i tripped=0","CH1 i state=0","CH1 i delay=0.10 s","CH1

p_tripped=0","CH1 i_state=0","CH1 i_delay=0.10 s","CH1
p_tripped=0","CH1 p_state=1","CH1 p_delay=5.00 s","CH1
p_level=50.00 W","CH2 u_tripped=0","CH2 u_state=0","CH2
u_delay=0.10 s","CH2 i_tripped=0","CH2 i_state=0","CH2
i_delay=0.10 s","CH2 p_tripped=0","CH2 p_state=0","CH2

p_delay=5.00 s","CH2 p_level=50.00

W", "tmain_tripped=0", "tmain_state=1", "tmain_delay=10.00

s", "tmain level=60.00 oC"

Related [SOURce[<n>]]:CURRent:PROTection:DELay[:TIME]

Commands [SOURce[<n>]]:CURRent:PROTection:STATe

[SOURce[<n>]]:CURRent:PROTection:TRIPped?

[SOURce[<n>]]:POWer:PROTection

[SOURce[<n>]]:POWer:PROTection:DELay[:TIME]

[SOURce[<n>]]:POWer:PROTection:STATe
[SOURce[<n>]]:POWer:PROTection:TRIPped?

[SOURce[<n>]]:VOLTage:PROTection:DELay[:TIME]

[SOURce[<n>]]:VOLTage:PROTection:STATe [SOURce[<n>]]:VOLTage:PROTection:TRIPped? SYSTem:TEMPerature:PROTection[:HIGH][:LEVel]

SYSTem:TEMPerature:PROTection[:HIGH]:DELay[:TIME]

SYSTem:TEMPerature:PROTection[:HIGH]:STATe

SYSTem:TEMPerature:PROTection[:HIGH]:TRIPped?

5.2.4. DIAGnostic[:INFOrmation]:TEST?

Syntax DIAGnostic[:INFOrmation]:TEST?

Description This guery returns results of the most recent self-test (see *TST? command).

Return The information will be returned in the following format: "<return code, device name, installed, return message>" where the return code could be one of the following values:

- 0 failed
- 1 passed
- 2 skipped

This information format will repeat with as many iterations as the number of devices found in configuration parameters of the PSU. While in the Stand-by mode this command will returns only test results for the Arduino shield devices.

Return code for the BP option will always be 2 (skipped).

Usage example

Return self-test results where DAC on the channel 2 failed to pass the test and due to that ADC testing has been skipped:

DIAG:TEST?

"1, EEPROM, installed, passed", "1, Ethernet, installed, passed"
"2, RTC, not installed, skipped", "2, BP option, installed,
skipped", "1, CH1 IOEXP, installed, passed", "1, CH1 DAC,
installed, passed", "1, CH1 ADC, installed, passed", "1, CH2
IOEXP, installed, passed", "0, CH2 DAC, installed, failed", "1,
CH2 ADC, installed, skipped"

Return self-test results while PSU is in the Stand-by mode:

DIAG: TEST?

"1, EEPROM, installed, passed", "1, Ethernet, installed, passed" "1, RTC, installed, passed", "2, BP option, installed, skipped"

Related *TST?

Commands SYSTem:POWer

5.3. INSTrument

Each channel of the PSU is considered as separate (logical) instrument, which is required by the SCPI standard. The INSTrument subsystem provides a mechanism to identify and select instruments and establish coupling to simplify programming of more channels at once.

SCPI command	Description
INSTrument	
[:SELect] { <channel>}</channel>	Selects the output to be programmed
:NSELect { <channel_number>}</channel_number>	Selects the output to be programmed

5.3.1. INSTrument[:SELect]

Svntax INSTrument[:SELect] {<channel>}

INSTrument[:SELect]?

Description This command selects the output to be programmed by the output identifier. The outputs

of the PSU are considered as two logical instruments. The INSTrument command pro-

vides a mechanism to identify and select an output.

When one output is selected, the other output is unavailable for programming until selected. The following commands are affected by the INSTrument command: SOURce,

MEASure, and CALibration.

Name **Parameters** Type Range Default <channel> Discrete CH1|CH2 Return Query returns the currently selected output by the INSTrument[:SELect] or INSTrument: NSELect command. The returned value is CH1 or CH2. INST? Usage CH1 example INST:SEL?

CH1

Related INSTrument:NSELect

Commands

Parameters

5.3.2. INSTrument: NSELect

INSTrument:NSELect {<channel number>} Syntax

INSTrument:NSELect?

Name

Description This command is used in conjunction with the SELect command. It serves the same pur-

Type

pose, except that it uses a numeric value instead of the identifier used in the SELect

Range

Default

command.

<channel_number> Numeric 1|2 Return When queried it returns the logical instrument number of the currently selected PSU channel. Note that the numbering used for logical instruments directly corresponds to the numbers used in status reporting for multiple instruments; specifically the STATus:QUEStionable:INSTrument and STATus:OPERation:INSTrument commands.

INST:NSEL 2 Usage INST: NSEL? example

2

Related STATus:QUEStionable:INSTrument Commands STATus: OPERation: INSTrument

5.4. MEASure

Measure commands measure the output voltage, current, power or temperature. They trigger the acquisition of new data before returning the reading. Measurements are performed by digitizing the instantaneous output voltage, current or temperature. Output power is calculated as product of measured voltage and current. Keyword [:DC] is optional since all measurement are by default of the DC level of the signal.

SCPI command	Description
MEASure	
[:SCALar]	
:CURRent	
[:DC]? [<channel>]</channel>	Takes a measurement; returns the average current
:POWer	
[:DC]? [<channel>]</channel>	Takes a measurement; returns the average power
:TEMPerature	
[:DC]? { <sensor>}</sensor>	Takes a measurement; returns the average temperature
[:VOLTage]	
[:DC]? [<channel>]</channel>	Takes a measurement; returns the average voltage

5.4.1. MEASure[:SCALar]:CURRent[:DC]

Syntax	MEASure[:SCALar]:CURRent[:DC]? [<channel>]</channel>					
Description	Query the current meas	sured across the curre	ent sense resistor inside	the PSU.		
Parameters	Name Type Range Default					
	<channel></channel>	Discrete	CH1 CH2	_		
Return	Returns the average or	itput current in amper	es as decimal number (f	NR2).		
Usage	Measure current on the currently selected channel (CH1) and CH2:					
example	MEAS:CURR?;:MEAS:CURR? CH2					
	1.23;0.12					
Related Commands						

5.4.2. MEASure[:SCALar]:POWer[:DC]

Syntax	MEASure[:SCALar]:POWer[:DC]? [<channel>]</channel>					
Description	Query the output power calculated as product of measured voltage and current value.					
Parameters	s Name Type Range Default					
	<channel></channel>	Discrete	CH1 CH2	n/a		
Return	Returns the average output power in watts as decimal number (NR2).					
Usage	MEAS: POW? CH2					
example	80.44					
Related Commands						

5.4.3. MEASure[:SCALar]:TEMPerature[:THERmistor][:DC]

Syntax MEASure[:SCALar]:TEMPerature[:THERmistor][:DC]? {<sensor>}

EEZ PSU SCPI reference M1

Description Query the temperature measured using the specified temperature sensors as follows:

MAIN – Analog temperature sensor connected to Arduino Shield board (can be used to monitor i.e. the main heatsink temperature or power transformer temperature).

Return Returns the average temperature value in degrees Celsius (°C) as decimal number

(NR2).

Parameters Name Type Range Default

<sensor> Discrete [MAIN] MAIN

Usage M

MEAS:TEMP? MAIN

example 30

39.50

Errors

Related Commands

5.4.4. MEASure[:SCALar][:VOLTage][:DC]

Syntax MEASure[:SCALar][:VOLTage][:DC]? [<channel>]

Description Query the voltage measured at the sense terminals of the selected channel.

Parameters Name Type Range Default

<channel> Discrete CH1|CH2 n/a

Poture the average output voltage in volte as desimal number (NP2)

Return Returns the average output voltage in volts as decimal number (NR2).

Usage MEAS: VOLT? CH1 example 43.25

Query voltage of the channel 2 that is currently selected:

INST CH2 MEAS?

12.40

Related Commands

5.5. MEMory

The MEMory subsystem works with PSU state files that are saved to (*SAV) and recalled from (*RCL) non-volatile storage locations numbered 0 through 9. The storage location 0 named "Power down state" is used to store the current PSU parameters.

SCPI command	Description
MEMory	
:NSTates?	Returns total number of state storage memory locations
:STATe	
:CATalog?	Lists the names associated with all ten state storage locations
:DELete { <profile>}</profile>	Deletes the contents of a state storage location
:ALL	Deletes the contents of all state storage locations
:NAME { <profile>, <name>}</name></profile>	Assigns a custom name to a state storage locations
:RECall	
:AUTO { <bool>}</bool>	Specifies whether the power-down state is recalled from location 0 on power-on
:SELect { <profile>}</profile>	Specifies which PSU state will be used at power on
:VALid? { <profile>}</profile>	Determines whether a storage location contains a valid state

5.5.1. MEMory:NSTates

Syntax MEMory: NSTates?

Description Returns the total number of *SAV/*RCL states available in the PSU.

Return Returns numeric value which is one greater than the maximum that can be sent as a pa-

rameter to the *SAV and *RCL commands.

Usage MEM:NST?

example 10

Errors Related Commands

5.5.2. MEMory:STATe:CATalog

Syntax MEMory:STATe:CATalog?

Description This guery requests a list of defined names in the MEMory:STATe subsystem.

Return The PSU returns a list of defined <name>'s in a comma separated list. Each <name> is

returned in a quoted string.

MEM:STAT:CAT? Usage

example

"Power down state", "All outputs on", "dual 15V/300mA", "Power protection at 100W", "--Not used--", "--Not used--", "--Not

used--", "--Not used--", "--Not used--", "--Not used--"

Errors

Related MEMory:STATe:NAME

Commands

5.5.3. MEMory:STATe:DELete

Syntax MEMory:STATe:DELete {

MEMory:STATe:DELete:ALL

Description When used with a profile number this command deletes the contents of the specified

storage location. The MEMory:STATe:DELete:ALL deletes the contents of storage loca-

tions 1 through 9.

An error is generated on an attempt to recall a deleted state.

Parameters Type Range Default ofile> Numeric 1 - 9

Return None

Usage

MEM:STAT:DEL 2

example

Errors

Related *RCL Commands *SAV

5.5.4. MEMory:STATe:NAME

Syntax

MEMory:STATe:NAME? {

This command associates a <name> with a *SAV/*RCL register number. May assign Description

> same name to different locations and state names are unaffected by *RST. Deleting a storage location's contents MEMory:STATe:DELete resets associated name to "--Not

used--"

Parameters Name Type Range Default ofile> 1 - 9Numeric quoted string 0 to 32 characters <name>

Return Returns a *SAV/*RCL register number associates with profile number.

MEM:STAT:DEF, 2, "All outputs on" Usage

MEM:STAT:DEF? 2 example

"All outputs on"

Errors

Related MEMory:STATe:DELete

Commands

5.5.5. MEMory:STATe:RECall:AUTO

MEMory:STATe:RECall:AUTO {<bool>} Syntax

MEMory:STATe:RECall:AUTO?

Description This command disables or enables the automatic recall of a specific stored PSU state se-

> lected using the MEMory:STATe:RECall:SELect command when power is turned on. Select ON to automatically recall one of the ten stored states or the "power-down" state (location 0) when power is turned on. Select OFF to issue a reset (*RST) when power is

turned on.

Parameters Name Range Default Type Discrete ONIOFFI0I1 <bool>

Return The guery command returns 0 (OFF) or 1 (ON).

MEM:STAT:REC:AUTO? Usage

example 1

Errors

Related *SAV Commands MEMory:STATe:RECall:SELect

SYSTem:POWer

5.5.6. MEMory:STATe:RECall:SELect

Syntax MEMory:STATe:RECall:SELect {ct {continue

MEMory:STATe:RECall:SELect?

Description This command selects which PSU state will be used at power on if the automatic recall

> mode is enabled (see MEMory:STATe:RECall:AUTO ON command). If the automatic recall mode is disabled (MEMory:STATe:RECall:AUTO OFF), then a "factory reset" (return

to the default values) is issued when power is turned on.

Parameters Name Type Range Default ofile> 0 - 9Numeric

The query command returns numeric value for 0 to 9 indicating which instrument state Return

will be used at power on.

MEM:STAT:REC:SEL? Usage

example

Errors

Related *SAV

Commands MEMory:STATe:RECall:AUTO

SYSTem:POWer

5.5.7. MEMory:STATe:VALid

Syntax MEMory:STATe:VALid? {<profile>}

Description This command gueries the specified storage location to determine if a valid state is cur-

rently stored in this location.

Use this command before sending the *RCL command to determine if a valid state has

been previously stored on queried location.

Name **Parameters** Type Range Default 0 - 9cprofile> Discrete

Return Returns 0 if no state has been stored or if it has been deleted. It returns 1 if a valid state

is stored in this location.

MEM:STAT:VAL? 2 Usage

example

Errors

Related *RCL Commands *SAV

5.6. OUTPut

The OUTPut subsystem controls the output, power-on, protection, remote sense and tracking state.

SCPI command	Description
OUTPut	
[:STATe] { <bool>}</bool>	Enables the specified output channel(s)
:MODE?	Returns the channel mode of operation
:PROTection	
:CLEar	Resets latched protection
:SENSe	Enables the remote sense function of the channel

5.6.1. OUTPut[:STATe]

OUTPut[:STATe] {<bool>} [, <channel>] Syntax

OUTPut[:STATe]? [<channel>]

Description This command enables or disables the specified output channel(s). The enabled state is ON (1); the disabled state is OFF (0). The state of a disabled output is a condition of zero output voltage and zero source current.

> Execution of this command also affects bit 10 (OE) and bit 11 (DP) of the Operation Instrument Isummary register (see Section 3.3.2).

> Self-test operation initiated by *TST? command will put all PSU channels into disable state.

> When the BP OPTION is enabled and the channels are not grouped together (SYSTem:GROup commands scheduled for M3) this command sets LED indicators above binding posts in the following manner:

- Turn on/off Out1+/Out1- green indicators (LED_O1+, LED_O1- or TLC5925 Out7 and Out3) when CH1 is selected
- Turn on/off Out2+/Out2- indicators (LED_O2+, LED_O2- or TLC5925 Out13 and Out10) when CH2 is selected

Execution of the OUTP ON command on the channel with tripped one or more protection (OCP, OVP, OPP or OTP) will generate error 201. Use OUTPut:PROTection:CLEar command to clear all tripped protections.

This command also affects Sense+/Sense- indicators (LED S1+, LED S1-, LED S2+, LED S2-) controlled by the OUTPut:SENSe command.

Parameters	Name	Туре	Range	Default
	<bool></bool>	Discrete	ON OFF 0 1	_
	<channel></channel>	Discrete	CH1 CH2	_
Return	The query command re	turns 0 if the output	is OFF, and 1 if the outpu	ıt is ON.
Usage example	OUTP ON, CH1 OUTP? CH1 1			
Errors	108, "Cal output d 201, "Cannot execu		ing protection"	
Related Commands	*TST OUTPut:PROTection:C OUTPut:SENSe	LEar		

5.6.2. OUTPut:MODE?

Syntax OUTPut:MODE? [, <channel>]

Description This command simplify resolving a results that can be obtained reading the bit 8 (CV) and 9 (CC) of the read-only Instrument Isummary Operation Status register for a specific channel (see table in the Section 3.3.2). The PSU can works in one of the three output modes:

- CV (Constant Voltage), when the output voltage equals the voltage setting value and the output current is determined by the load
- CC (Constant Current), when the output current equals the current setting value and the output voltage is determined by the load and
- UR (Unregulated) that is critical mode between CV and CC modes that could be noticed when the output voltage is close to the one end of the full scale (i.e. somewhere below 2V and above 48V for the 50V model that depends of the connected load).

The UR mode is not supported in software simulator.

Parameters	Name	Type	Range	Default
	<channel></channel>	Discrete	CH1 CH2	_
Return	The query returns CV, C	CC or UR.		
Usage example	Set output voltage to 20V and max. current, check that output voltage is as defined that indicate the constant voltage mode of operation:			
	VOLT 20; CURR MAX MEAS: VOLT?			
	20.0			
	OUTP:MODE?			
	CV			
Errors				
Related Commands	STATus:OPERation:INS STATus:OPERation:INS STATus:OPERation:INS	Trument:ISUMmary	[<n>]:CONDition</n>	

5.6.3. OUTPut:PROTection:CLEar

Syntax OUTPut:PROTection:CLEar [<channel>]

Description This command clears the latched protection status that disables the output when an

over-voltage, over-current or a power-limit condition is detected.

All conditions that generate the fault must be removed before the latched status can be cleared. The output is restored to the state it was in before the fault condition occurred.

Parameters	Name	Туре	Range	Default		
	<channel></channel>	Discrete	CH1 CH2	_	_	
Return	None					
Usage	The following command clears the latched protection status on all channels:					
example	OUTP:PROT:CLE					
Related						

5.6.4. OUTPut:SENSe

Commands

Syntax OUTPut:SENSe {<bool>} [, <channel>]

OUTPut:SENSe? [<channel>]

Description This command enables or disables remote sensing on the specified output channel(s).

The enabled state is ON (1); the disabled state is OFF (0). Execution of this command also affects bit 12 (RSENSE) of the Operation Instrument Isummary register (see Section <u>3.3.2</u>).

Self-test operation initiated by *TST? command will put remote sense on all PSU channels into disable state.

When the BP_OPTION is enabled and the channels are not grouped together (SYSTem:GROup commands scheduled for M3) this command sets LED indicators above binding posts and sense relays in the following manner:

- Turn on/off Sense1+/Sense1- indicators (LED_S1+, LED_S1- or TLC5925 Out5 and Out4) and sense relay K_S1 (TLC5925 Out1) when CH1 is selected
- Turn on/off Sense2+/Sense2- indicators (LED_S2+, LED_S2- or TLC5925 Out12 and Out11) and sense relay K_S2 (TLC5925 Out14) when CH2 is selected

Remote sensing has no effect during CC (Constant Current) operation. Sense+/Sense-indicators (LED_S1+, LED_S1-, LED_S2+, LED_S2-) will not be affected if output state is off (OUTPut OFF command).

Parameters	Name	Type	Range	Default
	<bool></bool>	Discrete	ON OFF 0 1	OFF
	<channel></channel>	Discrete	CH1 CH2	_
Return	The query command re ON.	turns 0 if the remot	e sense is OFF, and 1 if t	the remote sense is
Usage example	OUTP:SENS ON, CH2 OUTP:SENS? CH2			
	1			
Errors	302,"Option not in	nstalled"		
Related Commands	*TST OUTPut:[:STATe]			

5.7. SOURce

The SOURce commands are used to set the voltage, current, OVP, OCP and OPP values of the specified channel. Although the <u>APPLy</u> command provides the most straightforward method to program the PSU over the remote interfaces, the SOURce commands give you more flexibility to change individual parameters.

SCPI command	Description
[SOURce[<n>]]</n>	
:CURRent	
[:LEVel]	
[:IMMediate][:AMPLitude] { <current>}</current>	Sets the output current
:STEP[:INCRement] { <step>}</step>	Sets the step of the current change
:PROTection	
:DELay	
[:TIME] { <time>}</time>	Sets the over-current protection (OCP) programming delay
:STATe { <bool>}</bool>	Enables/disables over-current protection on the selected channel
:TRIPped?	Returns status of over-current protection activation
:POWer	
:PROTection[:LEVel]	Sets the over-power protection (OPP) level
:DELay	
[:TIME] { <time>}</time>	Sets the over-power protection programming delay
:STATe { <bool>}</bool>	Enables/disables over-power protection on the selected channel
:TRIPped?	Returns status of over-power protection activation
:VOLTage	
[:LEVel]	
[:IMMediate][:AMPLitude] { <voltage>}</voltage>	Sets the output voltage
:STEP[:INCRement] { <step>}</step>	Sets the step of the voltage change
:PROTection	
:DELay	
[:TIME] { <time>}</time>	Sets the over-voltage protection (OVP) programming delay
:STATe { <bool>}</bool>	Enables/disables over-voltage protection on the selected channel
:TRIPped?	Returns status of over-voltage protection activation

5.7.1. [SOURce[<n>]]:CURRent

Syntax [SOURce[<n>]]:CURRent[:LEVel][:IMMediate][:AMPLitude] {<current>|MIN|DEF|MAX|

UPIDOWN}

[SOURce[<n>]]:CURRent[:LEVel][:IMMediate][:AMPLitude]? [MIN|DEF|MAX]

Description This command sets the immediate current level of the channel. Units are in amperes.

When [:SOURce[<n>]] or [<n>] is omitted, the currently selected channel will be affected

by this command.

This command also increases or decreases the immediate current level using the 'UP' or DOWN parameter by a predetermined amount. The command CURRent:STEP sets the amount of increase or decrease. Notice that a new increment setting will cause an execution error -222,"Data out of range" when the maximum or the minimum rated current is exceeded.

At *RST, the signal being sourced will be set to a "safe" condition. This is achieved by setting the amplitude to its MINimum value (see Section 8.1).

Return

The guery command returns the programmed current level. CURR? MIN, CURR? DEF and CURR? MAX can be used to obtain minimum, default and maximum current level on the currently selected channel. For actual output current value use MEASure:CURRent command.

Parameters	Name	Туре	Range	Default
	<current></current>	Numeric (NR2), dis- crete	0 to MAXimum, MIN DEF MAX UP DOWN The maximum value is dependent on the PSU current rating. See Section 8.1	-

Usage example

A 10 ohm load is connected and voltage is set to 20V. With MAX current set measured current will be 2A. When new current value is set to 1.2A, voltage will drop to 12V (the channel enters the CC mode of operation):

INST CH1 VOLT 20 CURR MAX MEAS: VOLT? 20.00 CURR 1.2 MEAS: VOLT?

Query that returns maximum current of the currently selected channel:

CURR? MAX

5.00

12.00

Errors -222, "Data out of range"

Related *RST

Commands MEASure[:SCALar]:CURRent[:DC]?

[SOURce[<n>]]:CURRent[:LEVel][:IMMediate]:STEP[:INCRement]

5.7.2. [SOURce[<n>]]:CURRent:STEP

[SOURce[<n>]]:CURRent[:LEVel][:IMMediate]:STEP[:INCRement] {<step>|DEFault} Syntax [SOURce[<n>]]:CURRent[:LEVel][:IMMediate]:STEP[:INCRement]? [DEFault]

Set the step of the current change of the channel. When [SOURce[<n>]] or [<n>] is omit-Description

ted, the currently selected channel will be affected by this command. Step change is performed by using UP and DOWN as parameter for the [SOURce[<n>]]:CURRent com-

mand.

Return The query returns the step of the current change of the specified channel.

Parameters Name Range Default Type <step> Numeric (NR2) 0.01 to 1A|DEFault 0.05 Usage Return default step value:

example CURR:STEP? DEF

0.05

When a 10 ohm load is connected with voltage set to 20V and current to 1A the first channel enters CC mode of operation. Current is then increased from 1A in two steps to 1.2A.

APPL CH1, 20,1 MEAS: VOLT?

10.00

CURR:STEP 0.1

CURR UP

MEAS: CURR?

1.10

CURR UP

MEAS: CURR?

1.20

MEAS: VOLT?

12.00

Errors

Related

[SOURce[<n>]]:CURRent

Commands

5.7.3. [SOURce[<n>]]:CURRent:PROTection:DELay[:TIME]

Syntax [SOURce[<n>]]:CURRent:PROTection:DELay[:TIME] {<time>|DEFault}

[SOURce[<n>]]:CURRent:PROTection:DELay[:TIME]? [DEFault]

Description This command sets the over-current protection delay. The over-current protection func-

tion will not be triggered on the selected output channel during the delay time. After the

delay time has expired, the over-current protection function will be active.

This prevents momentary changes in output status from triggering the over-current protection function. Programmed values can range from 0 to 10 seconds. See also <u>Section</u>

8.1

Return The query command returns the programmed delay time.

Parameters Name Type Range Default

<time> Numeric, discrete 0 – 10|DEFault 20ms

Usage example

Get default OCP delay of 20 miliseconds:

CURR: PROT: DEL? DEF

0.02

Errors

Related O

OUTPut:PROTection:CLEar

Commands

5.7.4. [SOURce[<n>]]:CURRent:PROTection:STATe

Syntax [SOURce[<n>]]:CURRent:PROTection:STATe {<bool>}

[SOURce[<n>]]:CURRent:PROTection:STATe?

Description This command enables or disables the over-current protection (OCP) function. The enabled state is ON (1); the disabled state is OFF (0).

Since the PSU do not have a dedicated over-current protection circuit that can be programmed independently of output current level, entering the CC (constant current) mode of operation is used as a trigger to start OCP sequence. When delay time specified with

the [SOURce[<n>]]:CURRent:PROTection:DELay[:TIME] command expired the output turns off and the Questionable Condition status register OCP bit 9 is set. An error tone will also follow if beeper is enabled (see SYSTem:BEEPer:STATe).

[SOURce[<n>]]:CURRent:PROTection:TRIPped? command can be used to query whether over-current protection occurred on the selected channel.

Return The query command returns 0 if the current protection state is OFF, and 1 if the current

protection state is ON.

Parameters Name Type Range Default

<bool> Discrete ON|OFF|0|1 OFF

example ₀

Errors

Related OUTPut:PROTection:CLEar

Commands [SOURce[<n>]]:CURRent:PROTection:DELay[:TIME]

[SOURce[<n>]]:CURRent:PROTection:TRIPped

SYSTem:BEEPer:STATe

5.7.5. [SOURce[<n>]]:CURRent:PROTection:TRIPped?

Syntax [SOURce[<n>]]:CURRent:PROTection:TRIPped?

Description Query whether OCP occurred on the currently selected channel. When protection is

tripped bit 9 (OCP) of the Questionable Instrument Isummary register will be set (see

Section 3.4.2).

The OUTPut:PROTection:CLEar command can be send to clear OCP condition on the

selected channel.

Return This query returns a 1 if the protection circuit is tripped and a 0 if it is untripped.

example ₁

Errors

Related OUTPut:PROTection:CLEar

Commands

5.7.6. [SOURce[<n>]]:POWer:PROTection[:LEVel]

Syntax [SOURce[<n>]]:POWer:PROTection[:LEVel] {<current>|MINimum|DEFault|MAXimum}

[SOURce[<n>]]:POWer:PROTection[:LEVel]?

Description Set the over-power protection (OPP) value of the channel. When [:SOURce[<n>]] or

[<n>] is omitted, the currently selected channel will be affected by this command. When the over-power protection function of the specified channel is enabled ([SOURce[<n>]]:POWer:PROTection:STATe), the output turns off automatically when the

output power exceeds the over-power protection value currently set.

[SOURce[<n>]]:POWer:PROTection:TRIPped? command can be used to query whether

over-power protection occurred on the selected channel.

Return Query the over-power protection (OPP) value of the selected channel.

Parameters Name Type Range Default

<current> Numeric (NR2), discrete 0 to maximum, MIN|

DEF|MAX
The maximum value is dependent on the

DEFault

PSU power rating. See Section 8.1 Usage Set power protection to 50W on the channel 2:

Errors

Related [SOURce[<n>]]:POWer:PROTection:TRIPped? Commands [SOURce[<n>]]:POWer:PROTection:STATe

5.7.7. [SOURce[<n>]]:POWer:PROTection:DELay[:TIME]

Syntax [SOURce[<n>]]:POWer:PROTection:DELay[:TIME] {<time>|DEFault}

[SOURce[<n>]]:POWer:PROTection:DELay[:TIME]? [DEFault]

Description This command sets the over-power protection (OPP) delay. The over-power protection

function will not be triggered on the selected output channel during the delay time. After

the delay time has expired, the over-power protection function will be active.

This prevents momentary changes in output status from triggering the over-power protection function. Programmed values can range from 0 to 300 seconds. See also <u>Section</u>

<u>8.1</u>

Return The guery command returns the programmed delay time.

 Parameters
 Name
 Type
 Range
 Default

 <time>
 Numeric
 0 – 300|DEFault
 10

Usage example

Get default OPP delay of 10 seconds:

POW:PROT:DEL? DEF

10

Errors

Related OUTPut:PROTection:CLEar

Commands

5.7.8. [SOURce[<n>]]:POWer:PROTection:STATe

Syntax [SOURce[<n>]]:POWer:PROTection:STATe {<bool>}

[SOURce[<n>]]:POWer:PROTection:STATe?

Description This command enables or disables the over-power protection (OPP) function. The en-

abled state is ON (1); the disabled state is OFF (0). If the over-power protection function is enabled and the measure output power reach value set by [SOURce[<n>]]:POWer:PROTection[:LEVel] the output is disabled and the Questionable

Condition status register OPP bit 10 is set.

Return The query command returns 0 if the current protection state is OFF, and 1 if the current

protection state is ON.

Parameters Name Type Range Default

<bool> Discrete ON|OFF|0|1 OFF

Usage POW:PROT:STAT ON example POW:PROT:STAT?

1

Errors

Related OUTPut:PROTection:CLEar

Commands [SOURce[<n>]]:POWer:PROTection[:LEVel]

5.7.9. [SOURce[<n>]]:POWer:PROTection:TRIPped?

Syntax [SOURce[<n>]]:POWer:PROTection:TRIPped?

Description Query whether OPP occurred on the currently selected channel. When protection is

tripped bit 10 (OPP) of the Questionable Instrument Isummary register will be set (see Section 3.4.2).

The <u>OUTPut:PROTection:CLEar</u> command can be send to clear OPP condition on the selected channel.

Return This query returns a 1 if the protection circuit is tripped and a 0 if it is untripped.

example 0

Errors

Related OUTPut:PROTection:CLEar

Commands

5.7.10. [SOURce[<n>]]:VOLTage

Syntax [SOURce[<n>]]:VOLTage[:LEVel][:IMMediate][:AMPLitude] {<voltage>|MINimum|DE-

Fault|MAXimum|UP|DOWN}

 $[SOURce[< n >]] : VOLTage[:LEVel][:IMMediate][:AMPLitude]? \\ [MINimum|DEFault|MAXi-IMMediate][:AMPLitude]? \\ [MINimum][:AMPLitude]? \\ [MINim][:AMPLitude]? \\ [MINim][:AMPLitude]? \\ [MINim][:AMPLitude]? \\ [MINim][:AMPLitude]?$

mum]

Description This command sets the immediate voltage level of the output channel. Units are in volts.

When [:SOURce[<n>]] or [<n>] is omitted, the currently selected channel will be affected by this command.

This command also increases or decreases the immediate voltage level using the 'UP' or DOWN parameter by a predetermined amount. The command VOLTage:STEP sets the amount of increase or decrease. Notice that a new increment setting will cause an execution error -222,"Data out of range" when the maximum or the minimum rated current is exceeded.

At *RST, the signal being sourced will be set to a "safe" condition. This is achieved by setting the amplitude to its MINimum value (see <u>Section 8.1</u>).

Return

The query command returns the programmed voltage level. VOLT? MIN, VOLT? DEF and VOLT? MAX can be used to obtain minimum, default and maximum voltage level on the currently selected channel. For actual output voltage value use MEASure:VOLTage? command.

Parameters	Name	Туре	Range	Default
	<voltage></voltage>	Numeric (NR2), discrete	0 to MAXimum, MIN DEF MAX UP DOWN The maximum value is dependent on the PSU voltage rating. See Section 8.1	-

Usage example

A 10 ohm load is connected and current is set to 1A. With MAX voltage set measured voltage will be 10V. When new voltage value is set to 5V, current will drop to 0.5A (the channel enters the CV mode of operation):

INST CH1
VOLT MAX
CURR 1
MEAS:CURR?
1.00
VOLT 5
MEAS:CURR?
0.50

Query that returns maximum current of the currently selected channel:

CURR? MAX

5ms

5.00

-222, "Data out of range" **Errors**

Related *RST

Commands MEASure[:SCALar]:VOLTage[:DC]?

[SOURce[<n>]]:VOLTage[:LEVel][:IMMediate]:STEP[:INCRement]

5.7.11. [SOURce[<n>]]:VOLTage:STEP

[SOURce[<n>]]:VOLTage[:LEVel][:IMMediate]:STEP[:INCRement] {<step>|DEFault} Syntax

[SOURce[<n>]]:VOLTage[:LEVel][:IMMediate]:STEP[:INCRement]? [DEFault]

Set the step of the voltage change of the channel. When [SOURce[<n>]] or [<n>] is omit-Description

ted, the currently selected channel will be affected by this command. Step change is performed by using UP and DOWN as parameter for the [SOURce[<n>]]:VOLTage com-

Return The query returns the step of the voltage change of the specified channel.

Default **Parameters** Name Type Range Numeric (NR2), discrete 0.01 to 10VIDEFault 0.1 <step>

Usage Return default step value: example

VOLT:STEP? DEF

0.10

By connecting a 10 ohm load and current set to 2A and voltage to 10V the first channel enters the CV mode of operation. Voltage is then decreased from 10V in two steps to 6V:

APPL CH1, 10,2 MEAS: CURR?

1.0

VOLT:STEP 2 VOLT DOWN VOLT DOWN MEAS: VOLT?

6.0

MEAS: CURR?

0.60

Errors

Related

[SOURce[<n>]]:VOLTage

Commands

5.7.12. [SOURce[<n>]]:VOLTage:PROTection:DELay[:TIME]

Syntax [SOURce[<n>]]:VOLTage:PROTection:DELay[:TIME] {<time>|DEFault}

[SOURce[<n>]]:VOLTage:PROTection:DELay[:TIME]? [DEFault]

Description This command sets the over-voltage protection delay. The over-voltage protection func-

tion will not be triggered on the selected output channel during the delay time. After the

delay time has expired, the over-voltage protection function will be active.

This prevents momentary changes in output status from triggering the over-voltage protection function. Programmed values can range from 0 to 10 seconds. See also Section

<time>

Return The guery command returns the programmed delay time.

Parameters Name Range Default Type 0 - 10|DEFault

Numeric

EEZ PSU SCPI reference M1

Usage Get default OVP delay of 50 miliseconds:

0.050

Errors

Related OUTPut:PROTection:CLEar

Commands

5.7.13. [SOURce[<n>]]:VOLTage:PROTection:STATe

Syntax [SOURce[<n>]]:VOLTage:PROTection:STATe {<bool>}

[SOURce[<n>]]:VOLTage:PROTection:STATe?

Description This command enables or disables the over-voltage protection (OVP) function. The en-

abled state is ON (1); the disabled state is OFF (0).

Since the PSU do not have a dedicated over-voltage protection circuit that can be programmed independently of output current level, entering the CV (constant voltage) mode of operation is used as a trigger to start OVP sequence. When delay time specified with the [SOURce[<n>]]:VOLTage:PROTection:DELay[:TIME] command expired the output turns off and the Questionable Condition status register OCP bit 8 is set. An error tone

will also follow if beeper is enabled (see SYSTem:BEEPer:STATe).

[SOURce[<n>]]:VOLTage:PROTection:TRIPped? command can be used to query

whether over-voltage protection occurred on the selected channel.

Return The query command returns 0 if the voltage protection state is OFF, and 1 if the voltage

protection state is ON.

Parameters Name Type Range Default

<bool> Discrete ON|OFF|0|1 OFF

example

Errors

Related OUTPut:PROTection:CLEar

Commands [SOURce[<n>]]:VOLTage:PROTection:DELay[:TIME]

[SOURce[<n>]]:VOLTage:PROTection:TRIPped

SYSTem:BEEPer:STATe

5.7.14. [SOURce[<n>]]:VOLTage:PROTection:TRIPped?

Syntax [SOURce[<n>]]:VOLTage:PROTection:TRIPped?

Description Query whether OVP occurred on the currently selected channel. When protection is

tripped bit 8 (OVP) of the Questionable Instrument Isummary register will be set (see

Section 3.4.2).

The OUTPut:PROTection:CLEar command can be send to clear OVP condition on the

selected channel.

Return This query returns a 1 if the protection circuit is tripped and a 0 if it is untripped.

example ₀

Errors

Related OUTPut:PROTection:CLEar

Commands

5.8. STATus

Status register programming lets you determine the operating condition of the instrument at any time. This subsystem controls the SCPI-defined status-reporting structures. SCPI defines, in addition to those in IEEE 488.2, QUEStionable, OPERation, Instrument SUMmary and INSTrument registers. These registers conform to the IEEE 488.2 specification and each may be comprised of a condition register, an event register, an enable register. The purpose and definition of the SCPI-defined registers is described in "Volume 1: Syntax and Style". SCPI also defines an IEEE 488.2 queue for status. The queue provides a human readable record of instrument events. The application programmer may individually enable events into the queue.

STATus:PRESet enables errors and disables all other events.

SCPI command	Description
STATus	
:OPERation	
[:EVENt]?	Returns the value of the Operation Event register
:CONDition?	Returns the value of the Operation Instrument Condition register
:ENABle { <value>}</value>	Enables specific bits in the Operation Event register
:INSTrument[<n>]</n>	
[:EVENt]?	Returns the value of the Operation Instrument Event register
:CONDition?	Returns the value of the Operation Instrument Condition register
:ENABle { <value>}</value>	Enables specific bits in the Operation Instrument Event register
:ISUMmary <n></n>	
[:EVENt]?	Returns the value of the Operation Instrument Isummary Event register
:CONDition?	Returns the value of the Operation Instrument Isummary Condition register
:ENABle { <value>}</value>	Enables specific bits in the Operation Instrument Isummary Event register
:PREset	Presets all enable registers to power-on state
:QUEStionable	
[:EVENt]?	Returns the value of the Questionable Event register
:CONDition?	Returns the value of the Questionable Condition register
:ENABle { <value>}</value>	Enables specific bits in the Questionable Event register
:INSTrument[<n>]</n>	
[:EVENt]?	Returns the value of the Questionable Instrument Event register
:CONDition?	Returns the value of the Questionable Instrument Condition register
:ENABle { <value>}</value>	Enables specific bits in the Questionable Instrument Event register
:ISUMmary <n></n>	
[:EVENt]?	Returns the value of the Questionable Instrument Isummary Event register
:CONDition?	Returns the value of the Questionable Instrument Isum-

mary Condition register

<u>:ENABle {<value>}</u> Enables specific bits in the Questionable Instrument

Isummary Event register

5.8.1. STATus:OPERation[:EVENt]?

Syntax STATus:OPERation[:EVENt]?

Description This query returns the value of the read-only Operation Status Event register The bits are

latched and reading the register will clear it. The *CLS command can be also used to

clear the register.

Return The value returned is the binary-weighted sum of all bits set in the register. For example,

if bit 9 (decimal value = 512) and bit 13 (decimal value = 8192) are set, this command will

return 8704. See table in the Section 3.3 for bits description.

Usage example

If GROUp PARallel (bit 8) is set (next query returns 0 since the first query clears the

event register):

STAT: OPER?

256

STAT: OPER?

0

Errors

Related *CLS Commands *STB?

STATus:OPERation:ENABle

5.8.2. STATus: OPERation: CONDition?

Syntax STATus: OPERation: CONDition?

Description This guery returns the value of the read-only Operation Status Condition register.

Return The value returned is the binary-weighted sum of all bits set in the register. For example,

if bit 9 (decimal value = 512) and bit 13 (decimal value = 8192) are set, this command will

return 8704. See table in the Section 3.3 for bits description.

Usage If GROUp PARallel (bit 8) is set:

example
 STAT:OPER:COND?

256

Errors

Related STATus:OPERation:ENABle

Commands

5.8.3. STATus: OPERation: ENABle

Syntax STATus:OPERation:ENABle {<value>}

STATus:OPERation:ENABle?

Description This command and its query set and read the value of the Operation Status Enable regis-

ter. The Enable register is a mask for enabling specific bits from the Operation Event register to set the operation summary bit 7 (OPER) of the Status Byte register. This bit is the logical OR of all the Operational Event register bits that are enabled by the Operation

Status Enable register.

Return Query the Operation Status Enable register. The PSU returns a binary-weighted decimal

representing the bits set in the enable register.

Parameters Name Type Range Default

<value> Numeric A decimal value PREset=0 which corresponds to

the binary-weighted sum of the bits in the register (see the table in <u>Section 3.3</u>)

Usage Enable ISUM (bit 13): example STAT:OPER:ENAB 8192

Errors

Related *CLS Commands *STB?

STATus:OPERation[:EVENt]?

5.8.4. STATus:OPERation:INSTrument[:EVENt]?

Syntax STATus:OPERation:INSTrument[:EVENt]?

Description This guery returns the value of the read-only Instrument Operation Status Event register.

The bits are latched and reading the register will clear it. The *CLS command can be also

used to clear the register.

Return The value returned is the binary-weighted sum of all bits set in the register. For example,

if bit 1 (decimal value = 2) and bit 2 (decimal value = 4) are set, this command will return

6. See table in the Section 3.3.1 for bits description.

Usage If bit 2 (INST2) is set: example STAT: OPER: INST?

4

Errors

Related *CLS

Commands STATus:PREset

5.8.5. STATus: OPERation: INSTrument: CONDition?

Syntax STATus:OPERation:INSTrument:CONDition?

Description This query returns the value of the read-only Instrument Operation Status Condition reg-

ister.

Return The value returned is the binary-weighted sum of all bits set in the register. For example,

if bit 1 (decimal value = 2) and bit 2 (decimal value = 4) are set, this command will return

6. See table in the <u>Section 3.3.1</u> for bits description.

Usage If bit 2 (INST2) is set:

4

Errors

Related STATus:PREset

Commands

5.8.6. STATus: OPERation: INSTrument: ENABle

Syntax STATus:OPERation:INSTrument:ENABle {<value>}

STATus:OPERation:INSTrument:ENABle?

Description Enable bits in the Instrument Operation Status Enable register. The selected bits are then

reported to the Operation Status Event register.

Return Query the Instrument Operation Status Enable register. The PSU returns a bina-

ry-weighted decimal representing the bits set in the enable register.

Parameters	Name	Туре	Range	Default	
	<value></value>	Numeric	A decimal value which corresponds to the binary-weighted sum of the bits in the register (see the table in Section 3.3.1)	PREset=0	
11	Enable INICEA (bit 4)	and INICTO (bit O).			

Usage Enable INST1 (bit 1) and INST2 (bit 2):

Errors

Related *CLS

Commands STATus:PREset

5.8.7. STATus:OPERation:INSTrument:ISUMmary[<n>][:EVENt]?

Syntax STATus:OPERation:INSTrument:ISUMmary[<n>][:EVENt]?

Description This query returns the value of the read-only Instrument Isummary Operation Status

Event register for a specific channel of the PSU represented by numeric value [<n>]. When [<n>] is omitted, the system queries the Instrument Isummary Operation Status Event register of the current channel. The bits are latched and reading the register will

clear it. The *CLS command can be also used to clear the register.

Return The value returned is the binary-weighted sum of all bits set in the register. See table in

the Section 3.3.2 for bits description.

Usage If bit 8 (CV1) and bit 10 (OE1) on the channel 1 are set (256+1024=1280):

example
 STAT:OPER:INST:ISUM1?

1280

Errors

Related *CLS

Commands OUTPut:MODE?

5.8.8. STATus:OPERation:INSTrument:ISUMmary[<n>]:CONDition?

Syntax STATus:OPERation:INSTrument:ISUMmary[<n>]:CONDition?

Description This query returns the value of the read-only Instrument Isummary Operation Status

Condition register for a specific channel of the PSU represented by numeric value [<n>]. When [<n>] is omitted, the system queries the Instrument Isummary Operation Status

Condition register of the current channel.

Return The value returned is the binary-weighted sum of all bits set in the register. See table in

the Section 3.3.2 for bits description.

Usage If bit 8 (CV1) and bit 10 (OE1) on the channel 1 are set (256+1024=1280):

1280

Errors

Related OUTPut:MODE?

Commands

5.8.9. STATus:OPERation:INSTrument:ISUMmary<n>:ENABle

Syntax STATus:OPERation:INSTrument:ISUMmary[<n>]:ENABle {<value>}

STATus:OPERation:INSTrument:ISUMmary[<n>]:ENABle?

Description Enable bits in the Instrument Isummary Operation Status Enable register for a specific

channel of the PSU represented by numeric value [<n>]. When [<n>] is omitted, the system queries the Instrument Isummary Operation Status Enable register of the current channel. The selected bits are then reported to the Status Byte.

This command and its query set and read the value of the Operation Status Enable register. The Enable register is a mask for enabling specific bits from the Operation Event register to set the operation summary bit (OPER) of the Status Byte register. This bit (bit 7) is the logical OR of all the Operational Event register bits that are enabled by the Operation Status Enable register

Return

Query the Instrument Isummary Operation Status Enable register. The PSU returns a binary-weighted decimal representing the bits set in the enable register.

Parameters	Name	Туре	Range	Default
	<value></value>	Numeric	A decimal value which corresponds to the binary-weighted sum of the bits in the register (see the table in Section 3.3.2)	PREset=0

Usage example

The query returns that VOLT1 (bit 0), CURR1 (bit 1) and TEMP1 (bit 4) are set (1+2+16=19):

INST? CH2

INST CH1

STAT: OPER: INST: ISUM: ENABLE?

19

Errors

Related *CLS

Commands STATus:PREset

5.8.10. STATus:PREset

Syntax STATus:PREset

Description This command clears all bits in the Enable registers.

Return None

Usage

STAT: PRE

example

Errors

Related *CLS

Commands

5.8.11. STATus:QUEStionable[:EVENt]?

Syntax STATus:QUEStionable[:EVENt]?

Description Query the Questionable Status event register. The bits are latched and reading the regis-

ter will clear it. The *CLS command can be also used to clear the register.

Return The PSU returns a decimal value which corresponds to the binary-weighted sum of all

bits in the register. See table in the <u>Section 3.4</u> for bits description.

Usage If the error is detected in RTC (Real-time clock) circuit, the bit 3 (TIME) is set and this

example command returns 8:

STAT: QUES?

8

Errors

Related *CLS

Commands

5.8.12. STATus: QUEStionable: CONDition?

Syntax STATus:QUEStionable:CONDition?

Description Query the Questionable Status condition register.

Return The PSU returns a decimal value which corresponds to the binary-weighted sum of all

bits in the register. See table in the <u>Section 3.4</u> for bits description.

Usage If the error is detected in RTC (Real-time clock) circuit, the bit 3 (TIME) is set and this

example command returns 8:

STAT: QUES: COND?

8

Errors

Related Commands

5.8.13. STATus: QUEStionable: ENABle

Syntax STATus:QUEStionable:ENABle {<value>}

STATus:QUEStionable:ENABle?

Description Enable bits in the Questionable Status Enable register. The selected bits are then report-

ed to the Status Byte.

When <enable value> is set to 0, executing this command will clear the Questionable

Status Enable register.

Return Query the Questionable Status Enable register. The PSU returns a binary-weighted deci-

mal representing the bits set in the enable register.

Parameters Name Type Range Default

<value> Numeric A decimal value PREset=0

which corresponds to

which corresponds to the binary-weighted sum of the bits in the register (see table in

Section 3.4)

Usage The query returns that TIME (bit 3), TEMPerature (bit 4) and ISUM (bit 13) are enabled

example (8+16+8192=8216):

STAT: QUES: ENAB?

8216

Errors

Related *CLS

Commands STATus:PREset

5.8.14. STATus:QUEStionable:INSTrument[:EVENt]?

Syntax STATus:QUEStionable:INSTrument[:EVENt]?

Description Query the questionable instrument event register. The bits are latched and reading the

register will clear it. The *CLS command can be also used to clear the register.

Return The PSU returns a decimal value which corresponds to the binary-weighted sum of all

bits in the register and clears the register. See table in the Section 3.4.1 for bits descrip-

tion.

Usage Result of the query when INST1 (bit 1) and INST2 (bit 2) are set (2+4=6):

6

Errors

Related *CLS

Commands

5.8.15. STATus: QUEStionable: INSTrument: CONDition?

Syntax STATus:QUEStionable:INSTrument:CONDition?

Description Query the questionable instrument condition register.

Return The PSU returns a decimal value which corresponds to the binary-weighted sum of all

bits in the register and clears the register. See table in the Section 3.4.1 for bits descrip-

tion.

Usage Result of the query when INST1 (bit 1) and INST2 (bit 2) are set (2+4=6):

example
 STAT:OUES:INST:COND?

6

Errors

Related Commands

5.8.16. STATus: QUEStionable: INSTrument: ENABle

Syntax STATus:QUEStionable:INSTrument:ENABle {<value>}

STATus:QUEStionable:INSTrument:ENABle?

Description Set the value of the questionable instrument enable register. This register is a mask for

enabling specific bits from the questionable instrument event register to set the instrument summary bit 13 (ISUM) of the Questionable Status register. The ISUM bit of the Questionable Status register is the logical OR of all the questionable instrument event

register bits that are enabled by the questionable instrument enable register.

Return Query the Questionable Instrument Enable register. The PSU returns a binary-weighted

decimal representing the bits set in the enable register.

Parameters Name Type R

Name
Type
Range
Default

<value>
Numeric
A decimal value
which corresponds to
the binary-weighted
sum of the bits in the
register (see table in
Section 3.4.1)

Usage Set INST1 (bit 1) and INST2 (bit 2):

Errors

Related *CLS

Commands

5.8.17. STATus:QUEStionable:INSTrument:ISUMmary[<n>][:EVENt]?

Syntax STATus:QUEStionable:INSTrument:ISUMmary[<n>][:EVENt]?

Description Return the value of the Questionable Instrument Isummary Event register for a specific

channel of the PSU represented by numeric value [<n>]. When [<n>] is omitted, the system queries the questionable instrument Isummary enable register of the current chan-

nel. The event register is a read-only register which holds (latches) all events. Reading the Questionable Instrument Isummary Event register clears it. The *CLS command can be also used to clear the register.

When the PSU is operating as a voltage source, bit 1 (CURRent) is set. When the PSU is operating as a current source, bit 0 (VOLTage) is set. When the output is unregulated (UR), both bits are set (for example, while the output is changing to a new programmed value or when the PSU is sinking instead of sourcing because down-programmer is active with battery with higher voltage then set output is connected).

Return The PSU returns a binary-weighted decimal representing the bits set in the enable regis-

ter. See table in the Section 3.4.2 for bits description.

Result of the guery when over-current protection (OCP) condition is detected (bit 9): Usage

example STAT: QUES: INST: ISUM1?

512

Errors

Related *CLS

Commands

5.8.18. STATus:QUEStionable:INSTrument:ISUMmary[<n>]:CONDition?

STATus:QUEStionable:INSTrument:ISUMmary[<n>]:CONDition? Syntax

Description Return the value of the Questionable Instrument Isummary Condition register for a specific channel of the PSU represented by numeric value [<n>]. When [<n>] is omitted, the system queries the questionable instrument Isummary enable register of the current channel.

> When the PSU is operating as a voltage source, bit 1 (CURRent) is set. When the PSU is operating as a current source, bit 0 (VOLTage) is set. When the output is unregulated (UR), both bits are set (for example, while the output is changing to a new programmed value or when the PSU is sinking instead of sourcing because down-programmer is active with battery with higher voltage then set output is connected).

Return The PSU returns a binary-weighted decimal representing the bits set in the enable regis-

ter. See table in the <u>Section 3.4.2</u> for bits description.

Usage Result of the query when over-current protection (OCP) condition is detected (bit 9):

example

STAT:QUES:INST:ISUM1:COND?

512

Errors

Related Commands

5.8.19. STATus:QUEStionable:INSTrument:ISUMmary[<n>]:ENABle

STATus:QUEStionable:INSTrument:ISUMmary[<n>]:ENABle {<value>} Syntax

STATus:QUEStionable:INSTrument:ISUMmary[<n>]:ENABle?

Description Set the value of the Questionable Instrument Isummary Enable register for a specific channel of the PSU represented by numeric value [<n>]. When [<n>] is omitted, the system queries the Questionable Instrument Isummary Enable register of the current channel. The *CLS command can be used to clear the register.

> This register is a mask for enabling specific bits from the Questionable Instrument Isummary Event register to set the Instrument Summary bit (bits 1 and 2) of the Questionable Instrument register. These bits are the logical OR of all the Questionable Instrument Isummary Event register bits that are enabled by the Questionable Instrument Isummary Enable register.

Return	Query the value of the Questionable Instrument Isummary Enable register.				
Parameters	Name	Туре	Range	Default	
	<value></value>	Numeric	A decimal value which corresponds to the binary-weighted sum of the bits in the register (see table in Section 3.4.2)	PREset=0	
Usage example	value=2), TEMP2 (bit 4, OPP2 (bit 10, value=1024	value 16), OVP1 4), therefore the er	/OLT2 (bit 0, value=1), Cl (bit 8, value=256), OCP2 nable value is 1+2+16+256	(bit 9, value=512),	
	STAT:QUES:INST:ISUN	12:ENAB 1811			
Errors					
Related Commands	*CLS STATus:PREset				

5.9. SYSTem

System commands control system functions that are not directly related to output control, measurement, or status functions.

SCPI command	Description
SYSTem	
:BEEPer[:IMMediate]	Issues a single beep immediately
:STATe { <bool>}</bool>	Enables beeper function
:CAPability?	Returns an <instrument_specifier></instrument_specifier>
:DATE { <yyyy>,<mm>,<dd>}</dd></mm></yyyy>	Sets the date of the system clock
:ERRor	
[:NEXT]?	Queries and clears errors from the error queue
:COUNt?	Queries the error/event queue for the number of unread items
:POWer { <bool>}</bool>	Enters the PSU into the Stand-by mode
:TEMPerature	
:PROTection	
[:HIGH]	
[:LEVel] { <temperature>[, <sensor>]}</sensor></temperature>	Sets the OTP value
:CLEar[. { <sensor>}]</sensor>	Clears the latched protection status of the over-temperature protection (OTP)
:DELay	Sets time-out period
[:TIME] { <delay>[, <sensor>]}</sensor></delay>	Sets the OTP programming delay
:STATe { <bool>[, <sensor>]}</sensor></bool>	Enables/disables OTP on the selected temperature sensor
:TRIPped? [<sensor>]</sensor>	Returns status of OTP activation
:TIME { <hh>,<mm>,<ss>}</ss></mm></hh>	Sets the time of the system clock
:VERSion?	Returns the SCPI version number

5.9.1. SYSTem:BEEPer

Syntax SYSTem:BEEPer[:IMMediate]

Description This command issues a single beep immediately.

Usage SYST:BEEP

example

5.9.2. SYSTem:BEEPer:STATe

Syntax SYSTem:BEEPer:STATe {<bool>} SYSTem:BEEPer:STATe?

Description When the beeper is enabled, the PSU generates audible sound in any of the following situations:

- the power is turns on or off (see SYSTem:POWer),
- when error occurs during front panel operation or remote operation (see <u>Section 7</u> for the list of error messages),
- · self-test is failed and
- any of the protection function is "tripped"

Parameters	Name	Туре	Range	Default
	<bool></bool>	Discrete	ON OFF 0 1	ON
Usage example	SYST:BEEP:STAT ON SYST:BEEP:STAT?			
	1			
Related Commands	SYSTem:BEEPer[:IMMe SYSTem:POWer	ediate]		

5.9.3. SYSTem:CAPability?

Syntax SYSTem:CAPability?

Description This query returns the PSU's capabilities and outputs the appropriate specifiers.

See also SCPI Volume 4: Section 7.1, 1.4.1, 7.2.1, 7.2.2, and 7.2.3

SYSTem: CAPability? Usage

example DCSUPPLY WITH (MEASURE | MULTIPLE | TRIGGER)

5.9.4. SYSTem:DATE

Syntax SYSTem:DATE {<yyyy>,<mm>,<dd>}

SYSTem:DATE?

Description Sets the date of the system clock (RTC). Specify the year, month, and day.

The self-test procedure compare date and time stored in RTC registers with values stored in the non-volatile memory (EEPROM). When the later is greater then former or any of them lost integrity (i.e. any of value is outside allowed range: for example seconds are higher then 60 or months are higher then 12, etc.) self-test will failed. The *TST? will return 1 and detailed report could be queried using the DIAGnostic:TEST? command.

The bit 3 (TIME) of the Questionable Status register will be set (see Section 3.4) if datetime self-test failed or datetime was never set.

Return Query the current date of the system clock in YYYY, MM, DD format.

Parameters	Name	Туре	Range	Default
	<yyyy></yyyy>	Numeric	2000 – 2099	_
	<mm></mm>	Numeric	1 – 12	_
	<dd></dd>	Numeric	1 – 31	_
Usage example	SYST:DATE?			
	2015, 10, 24			
Errors				
Related	*TST?			

Commands DIAGnostic[:INFOrmation]:TEST?

SYSTem:TIME

5.9.5. SYSTem:ERRor

Syntax SYSTem:ERRor[:NEXT]?

Description This guery command reads and clear errors from the error gueue. A record of up to 20

errors can be stored in the PSU's error queue. See also "Error Messages" in Section 7. Errors are retrieved in first-in-first-out (FIFO) order. The first error returned is the first error that was stored. The PSU beeps once each time an error is generated. The error

queue is cleared when power has been off or after a *CLS command.

Return SYSTem:ERRor[:NEXT]? queries and clears the error messages in the error queue. The

query returns the number and content of the error message.

Usage SYST: ERR?

example -113, "Undefined header"

Errors If more than 20 errors have occurred, the last error stored in the gueue (the most recent

error) is replaced with:

-350, "Queue overflow"

No additional errors are stored until you remove errors from the queue.

Related *CLS Commands *RST

SYSTem:ERRor:COUNt

5.9.6. SYSTem:ERRor:COUNt?

Syntax SYSTem:ERRor:COUNt?

Description This query command queries the error/event queue for the number of unread items. As

errors and events may occur at any time, more items may be present in the queue at the

time it is actually read.

Return

Usage SYST:ERR:COUN?

example 10

Errors

Related *CLS Commands *RST

SYSTem:ERRor[:NEXT]

5.9.7. SYSTem:POWer

Syntax SYSTem:POWer {<bool>}

SYSTem:POWer?

Description This command controls powering down and powering up sequence of the main trans-

former that supply all PSU channels. The "Stand-by" indicator (LED PWR, TLC5925

Out15) will be switched on when the PSU enters the Stand-by mode.

*RST command will perform SYSTem:POWer ON that follows SYSTem:POWer OFF after

5 seconds.

Arduino Shield without BP option (parameter BP OPTION is false) has LED PWR con-

nected to the digital output LED_PWR (pin 66).

Return Query returns PSU power Stand-by status.

Parameters Name Type Range Default

bool> Discrete ON|OFF|0|1 OFF

1

Errors

Related *RST Commands *TST?

SYSTem:BEEP:STATe

5.9.8. SYSTem:TEMPerature:PROTection[:HIGH][:LEVel]

Syntax SYSTem:TEMPerature:PROTection[:HIGH][:LEVel] {<temperature>[, <sensor>]}

SYSTem:TEMPerature:PROTection[:HIGH][:LEVel]? [<sensor>]

Description Set the over-temperature protection (OTP) value in degrees Celsius (°C) of the selected temperature sensor. When the over-temperature protection function of the specified temperature sensor is enabled (SYSTem:TEMPerature:PROTection[:HIGH]:STATe), one of the following action will be performed when the temperature exceeds the over-temperature protection value currently set:

> MAIN – Switch off power of the main transformer and set bit 4 of the Questionable Status register

If MAIN temperature sensor cause over-temperature condition an error tone will also follow if beeper is enabled (see SYSTem:BEEPer:STATe).

SYSTem:TEMPerature:PROTection[:HIGH]:TRIPped? command can be used to query whether over-temperature protection occurred on the selected temperature sensor.

Return Query the over-temperature protection (OTP) value of the selected temperature sensor.

Parameters Name Type Range Default <temperature> Numeric (NR2) 0 - 10070 Discrete [MAIN] MAIN <sensor> TEMP: PROT: 50.5, MAIN Usage example TEMP: PROT? MAIN 50.50

Errors

Related *RST

Commands SYSTem:TEMPerature:PROTection[:HIGH]:STATe

SYSTem:TEMPerature:PROTection[:HIGH]:TRIPped?

5.9.9. SYSTem:TEMPerature:PROTection[:HIGH]:CLEar

SYSTem:TEMPerature:PROTection[:HIGH]:CLEar[, {<sensor>}] Syntax

Description This command clears the latched protection status when an over-temperature is detect-

ed.

All conditions that generate the fault must be removed before the latched status can be cleared. The output is restored to the state it was in before the fault condition occurred.

Return None

Name	Туре	Range	Default
<sensor></sensor>	Discrete	[MAIN]	MAIN

Usage example TEMP: PROT: CLE

Errors

Related Commands

5.9.10. SYSTem:TEMPerature:PROTection[:HIGH]:DELay[:TIME]

Syntax SYSTem:TEMPerature:PROTection[:HIGH]:DELay[:TIME] {<delay>[, <sensor>]}

SYSTem:TEMPerature:PROTection[:HIGH]:DELay[:TIME]?[, {<sensor>}]

This command sets the over-temperature protection delay. The over-temperature protec-Description

tion function will not be triggered during the delay time. After the delay time has expired,

the over-temperature protection function will be active.

Programmed values can range from 0 to 300 seconds. See also Section 8.1

Return The guery returns programmed over-temperature protection delay.

Parameters	Name	Туре	Range	Default
	<delay></delay>	Numeric	0 - 300 seconds	10
	<sensor></sensor>	Discrete	[MAIN]	MAIN
Usage example	TEMP:PROT:DEL 30, S2			
Errors				

5.9.11. SYSTem:TEMPerature:PROTection[:HIGH]:STATe

SYSTem:TEMPerature:PROTection[:HIGH]:STATe {<bool>[, <sensor>]} Syntax

SYSTem:TEMPerature:PROTection[:HIGH]:STATe?[, {<sensor>}]

Description This command enables or disables the over-temperature protection (OTP) function. The

enabled state is ON (1); the disabled state is OFF (0). If the over-temperature protection function is enabled and the measured output power reach value set by [SOURce[<n>]]:POWer:PROTection[:LEVel] the output is disabled and the Questionable

Condition status register OPP bit 10 is set.

Return The query command returns 0 if the current protection state is OFF, and 1 if the current

protection state is ON.

Parameters Name Range Default Type ONIOFFI0I1 OFF <bool> Discrete Discrete [MAIN] MAIN <sensor>

TEMP: PROT: STAT? S1 Usage

example

Errors

Related

Commands

*RST

Related *RST

Commands SYSTem:TEMPerature:PROTection[:HIGH]:CLEar

5.9.12. SYSTem:TEMPerature:PROTection[:HIGH]:TRIPped?

Syntax SYSTem:TEMPerature:PROTection[:HIGH]:TRIPped?[, {<sensor>}]

Description Query whether OTP occurred on the selected temperature sensor. When protection is

tripped bit 4 (TEMPerature) of the Questionable Status register will be set (see Section

3.4).

The SYSTem:TEMPerature:PROTection[:HIGH]:CLEar command can be send to clear

OTP condition caused by the selected temperature sensor.

Return This guery returns a 1 if the protection circuit is tripped and a 0 if it is untripped.

Parameters Name Type Range Default <sensor> Discrete [MAIN] MAIN

Usage

TEMP: PROT: TRIP?

example

Errors

Related

SYSTem:TEMPerature:PROTection[:HIGH]:CLEar

Commands

5.9.13. SYSTem:TIME

Syntax SYSTem:TIME {<hh>,<mm>,<ss>}

SYSTem:TIME?

Description Sets the time of the system clock (RTC). Specify the hours, minutes, and seconds.

The self-test procedure compare date and time stored in RTC registers with values stored in the non-volatile memory (EEPROM). When the later is greater then former or any of them lost integrity (i.e. any of value is outside allowed range: for example seconds are higher then 60 or months are higher then 12, etc.) self-test will failed. The *TST? will return 1 and detailed report could be queried using the DIAGnostic:TEST? command.

The bit 3 (TIME) of the Questionable Status register will be set (see Section 3.4) if datetime self-test failed or datetime was never set.

Return Query the current time of the system clock in HH, MM, SS format.

Parameters	Name	Туре	Range	Default
	<hh></hh>	Numeric	0 – 23	-
	<mm></mm>	Numeric	0 – 59	_
	<ss></ss>	Numeric	0 – 59	_
Usage example	SYST:TIME?			
	15, 10, 33			
Errors				

*TST? Related

Commands DIAGnostic[:INFOrmation]:TEST?

SYSTem:DATE

5.9.14. SYSTem: VERSion?

Syntax SYSTem: VERSion?

Description This command returns the version of the SCPI (Standard Commands for Programmable

Instruments) standard with which the instrument is in compliance

Return The command returns a string in the form "YYYY.V", where YYYY represents the year of

the version and V represents a version for that year.

SYST: VERS? Usage example 1999.0

Related Commands

6. Device-specific (unclassified) commands

The commands in this section are device-specific to the PSU. They are not included in the 1999.0 version of the SCPI standard. However, these commands are designed with the SCPI standard in mind, and they follow all of the command syntax rules defined by the standard.

6.1. APPLy

The APPLy command provides the most straightforward method to program the PSU over the remote interface.

Syntax APPLy {<channel>}

[,<voltage>|MINimum|MAXimum|DEF[,<current>|MINimum|MAXimum|DEFault]]

APPLy? {<channel>}[, <param>]

Description This command is a combination of INSTrument:SELect (or INSTrument:NSELect),

[SOURce[<n>]]:VOLTage and [SOURce[<n>]]:CURRent commands.

The APPLy changes the PSU's output to the newly programmed values only if the programmed values are valid within the presently selected range. An execution error will occur if the programmed values are not valid within the selected range. You can substitute MINimum, MAXimum, or DEFault in place of a specific value for the voltage and current

parameters (see table below).

	parameters (see table below).			
Parameters	Name	Туре	Range	Default
	{ <channel>}</channel>	Discrete	CH1 CH2	_
	<voltage></voltage>	Numeric	0 to maximum, MIN DEF MAX UP DOWN The maximum value is dependent on the PSU voltage rating. See <u>Section 8.1</u>	-
	<current></current>	Numeric	0 to MAXimum, MIN DEF MAX UP DOWN The maximum value is dependent on the PSU current rating. See <u>Section 8.1</u>	-
	<param/>	Discrete	CURR VOLT	_
Return	APPLy? query the voltage/current of the specified channel.			
Usage	Set the voltage and current of CH1 to 35.5V and 0.5A respectively:			

example

APPL CH1,35.5,0.5

Query the voltage and current settings of the first channel:

APPL? CH1

CH1:50V/3A, 35.500, 0.500

Query only current setting of the second channel:

APPL? CH2, CURR

0.25

Related

INSTrument:NSELect Commands INSTrument[:SELect]

> [SOURce[<n>]]:VOLTage[:LEVel][:IMMediate][:AMPLitude] [SOURce[<n>]]:CURRent[:LEVel][:IMMediate][:AMPLitude]

7. Error messages

The system-defined error/event numbers are chosen on an enumerated ("1 of N") basis. The SCPI-defined error/event numbers and the <error/event_description> portions of the full queue item are listed here. The first error/event described in each class (for example, -100, -200, -300, -400) is a "generic" error.

7.1. Command Error [-199, -100]

An <error/event number> in the range [-199, -100] indicates that an syntax error has been detected by the PSU's parser. The occurrence of any error in this class cause the command error bit (CME, bit 5) in the Standard Event Status Register (see <u>Section 3.1</u>) to be set.

Return string	Description
0,"No error"	The queue is completely empty. Every error/event in the queue has been read or the queue was purposely cleared by power-on, *CLS, etc.
-100, "Command error"	Generic syntax error.
-101,"Invalid character"	An invalid character was found in the command string. You may have inserted a character such as #, \$, or % in the command keyword or within a parameter. Example:
	OUTP:STAT #ON
-103,"Invalid separator"	An invalid separator was found in the command string. You may have used a comma instead of a colon, semicolon, or blank space, or you may have used a blank space instead of a comma. Example:
	TRIG:SOUR, BUS
-104,"Data type error"	The wrong parameter type was found in the command string. You may have specified a number where a string was expected, or vice versa. Example (password is not a quoted string): CAL ON, 123
-108, "Parameter not allowed"	More parameters were received than expected for the command. You may have entered an extra parameter, or added a parameter to a command that does not accept a parameter. Example: INST CH1, CH2
-109, "Missing parameter"	Fewer parameters were received than expected for the command. You omitted one or more parameters that are required for this command. Example: APPL
-113, "Undefined header"	A command was received that is not valid for this PSU. You may have misspelled the command or it may not be a valid command. If you are using the short form of the command, remember that it may contain up to four letters. Example: MEASU:CURR?

-114,"Header suffix out of range"	The numeric suffix attached to a command header is not one of the allowable values. Example: STAT:QUES:INST:ISUM3?
-131,"Invalid suffix"	A suffix was incorrectly specified for a numeric parameter. You may have misspelled the suffix. Example (use A instead of V): VOLT 3A
-138, "Suffix not allowed"	A suffix was received following a numeric parameter which does not accept a suffix. Example (SEC is not a valid suffix): STAT:QUES:ENAB 10 SEC
-151,"Invalid string data"	An invalid character string was received. Check to see if you have enclosed the character string in single or double quotes. Example:
	DISP:TEXT 'ON

7.2. Execution Error [-299, -200]

An <error/event number> in the range [-299, -200] indicates that an error has been detected by the PSU's execution control block. The occurrence of any error in this class cause the execution error bit (EXE, bit 4) in the Standard Event Status Register (see <u>Section 3.1</u>) to be set. One of the following events has occurred:

- A <PROGRAM DATA> element following a header was evaluated by the device as outside of its legal input range or is otherwise inconsistent with the PSU's capabilities.
- A valid program message could not be properly executed due to some PSU condition.

Execution errors will be reported by the PSU after rounding and expression evaluation operations have taken place. Rounding a numeric data element, for example, will not be reported as an execution error. Events that generate execution errors will not generate Command Errors, device-specific errors, or Query Errors; see the other error definitions in this section.

Return string	Description
-200,"Execution error"	This is the generic execution error when more specific error is not assigned in the case that command execution failed.
-222,"Data out of range"	A numeric parameter value is outside the valid range for the command. Example:
	VOLT 166
-223,"Too much data"	A character string was received but could not be executed because the string length was more than 32 characters. This error can be generated by the CALibration:REMark command.
-224,"Illegal parameter value"	A discrete parameter was received which was not a valid choice for the command. You may have used an invalid parameter choice. Example: VOLT ON
	VOLI ON
-240,"Hardware error"	Command or query could not be executed because failure is detected during power-up self-test. Use *TST? command to query self-test results. See also <u>Section 7.3.1</u>
-241, "Option not installed"	Command or query could not be executed because of missing

	PSU hardware. Example (remote sense cannot be activated when BP_OP-TION is false): OUTP:SENS ON
-242, "Channel fault detected"	POWERGOOD signal failure is detected on any of the installed channel. If such condition is happened the PSU will be immediately put into the stand-by mode.

7.3. Device-Specific Error [-399, -300], [1, 32767]

errors; see the other error definitions in this section.

An <error/event number> in the range [-399, -300] or [1, 32767] indicates that the PSU has detected an error which is not a command error, a query error, or an execution error; some PSU operations did not properly complete, possibly due to an abnormal hardware or firmware condition. These codes are also used for self-test response errors. The occurrence of any error in this class cause the device-specific error bit (DDE, bit 3) in the Standard Event Status Register (see Section 3.1) to be set. Events that generate device-specific errors do not generate command errors, execution errors, or query

Return string	Description
-310,"System error"	Internal firmware error.
-330, "Self-test failed"	The PSU's complete self-test failed from the remote interface (*TST? command). In addition to this error, more specific self-test errors are also reported. See also <u>Section 7.3.1</u>
-350,"Queue overflow"	The error queue is full because more than 16 errors have occurred. No additional errors are stored until you remove errors from the queue. The error queue is cleared when power has been turned off, or after a *CLS (clear status) command has been executed.
-363,"Input buffer overrun"	Input buffer overrun. Serial or Ethernet port input buffer overflows with data.
100, "Channel not found"	Non existing channel number is specified. Example:
	SOUR3: VOLT?
101,"Calibration mode is off"	Calibration is not enabled. The PSU will not accept calibration commands.
102,"Invalid cal password"	The calibration password is incorrect.
104, "Bad sequence of cal commands"	Calibration commands have not been entered in the proper sequence.
105,"Cal password too long"	A calibration password was received which contained more than 16 characters.
106,"Cal password too short"	A calibration password was received which contained less than 4 characters.
107,"Cal value out of range"	The specified calibration value (CALibration:CURRent:DATA or CALibration:VOLTage:DATA) is not valid for the present measurement function and range.
108, "Cal output disabled"	Calibration is aborted by sending the OUTP OFF command during an output calibration.
109,"Invalid cal data"	One or more calibration data have value that prohibit calibration parameters calculation. For example MID value is lower then MIN, or MIN is higher then MAX, or MID value is out of

accepted tolerance that it cannot be predicted with newly cal-

	culated calibration parameters.		
110,"Cal params missing or corrupted"	Calibration parameters activation initiated by CALibration:STATe ON, " <password>" failed because calibration has never been conducted or existing parameters are corrupted.</password>		
111, "No new cal data exists" Attempt to save calibration data with the CAL:SAVE comma while no new calibration data are entered.			
201, "Cannot execute before clearing protection"	Command such as OUTP ON cannot be executed on the channel where one or more protections are tripped.		
270,"CH1 ADC timeout detected"	Channel is switched off after 3 consecutive ADC timeouts are detected.		

7.3.1. Self-Test Error Messages

During power-up the PSU will start self-test sequence when communication with all SPI devices that is marked as installed will be established. Scope of self-test depends of device capability and it could vary from simple reading device registers and waiting for expecting response to more complex operation such as set DAC registers and read back set values using ADC (if ADC test passed). Every test failure will be announced by error beep, and one error message per failed test will be inserted into error queue. That also cause the device-specific error bit (DDE, bit 3) in the Standard Event Status Register (see Section 3.1) to be set.

Return string	Description	
210,"CH1 IOEXP test failed"	Communication with Channel 1 I/O expander is not possible. I/O expander is not functional or SPI 10-pin ribbon cable is not connected.	
211, "CH2 IOEXP test failed"	Communication with Channel 2 I/O expander is not possible. I/O expander is not functional or SPI 10-pin ribbon cable is not connected.	
220,"CH1 ADC test failed"	Communication with Channel 1 ADC is not possible. Values written into various registers are not equal to the returned values or SPI 10-pin ribbon cable is not connected.	
221, "CH2 ADC test failed"	Communication with Channel 2 ADC is not possible. Values written into various registers are not equal to the returned values or SPI 10-pin ribbon cable is not connected.	
230,"CH1 DAC test failed"	Channel 1 DAC is not functional, communication is failed or difference between set and acquired DAC output value is too high when MCU sends a test voltage data to the DAC and converts the DAC output to digital data (using ADC I_SET input).	
231,"CH2 DAC test failed"	Channel 2 DAC is not functional, communication is failed or difference between set and acquired DAC output value is too high when MCU sends a test voltage data to the DAC and converts the DAC output to digital data (using ADC I_SET input).	
240,"External EEPROM test failed"	Non-volatile memory on the Arduino board checksum test failed.	
250,"RTC test failed"	RTC on the Arduino board is not present or date or time values are not valid or last datetime stored into non-volatile memory is greater then RTC datetime.	
260,"Ethernet test failed"	Ethernet controller on the Arduino board test failed.	

For example if SPI-bus cable is incidentally not connected or wrongly wired on channel 1 two errors will be generated and placed into error queue what can be check using the following command sequence:

SYST: ERR: COUN?

SYST:ERR?

210,"CH1 IOEXP test failed"

SYST:ERR?

220,"CH1 ADC test failed"

8. Parameters and settings

8.1. Programming parameters

The PSU firmware could be used to control channels with various characteristics. For example voltage range could be from 0 to 30V, 0 to 40V or 0 to 50V and current range could vary from 0 to 3.12A to 0 to 5A. It's also possible to mix two channels with different voltage and current ranges i.e. 0 - 40V/0 - 5A and 0 - 50V/0 - 3.12A. Use *IDN? command to find out what channels are defined in the firmware.

8.1.1. Voltage

Programming range / Model	0 – 30V / <i>30</i>	0 – 40V / <i>40</i>	0 – 50V / 50
MAXimum [V]	30	40	50
MINimum [V]	0	0	0
DEFault [V]	0	0	0
Value after *RST or *TST?	0	0	0
STEP MINimum [V]	10m	10m	10m
STEP MAXimum [V]	5	5	5
STEP DEFault [V]	100m	100m	100m
PROTection DELay MINimum [s]	0	0	0
PROTection DELay MAXimum [s]	10	10	10
PROTection DELay DEFault [s]	5m	5m	5m
CALibration VALue MINimum[V]	0.2	0.2	0.2
CALibration VALue MIDdle[V]	14.1	19.1	24.1
CALibration VALue MAXimum[V]	28	38	48

8.1.2. Current

Programming range / Model	0 – 3.12V / <i>0</i> 3	0 – 5A / <i>05</i>
MAXimum [A]	3.12	5
MINimum [A]	0	0
DEFault [A]	0	0
Value after *RST or *TST?	0	0
STEP and STEP MINimum [A]	10m	10m
STEP MAXimum [A]	1	1
STEP DEFault [A]	50m	50m
PROTection DELay MINimum [s]	0	0
PROTection DELay MAXimum [s]	10	10
PROTection DELay DEFault [s]	20m	20m
CALibration VALue MINimum[A]	50m	50m
CALibration VALue MIDdle[A]	1.525	2.425
CALibration VALue MAXimum[A]	3	4.8

8.1.3. Power

The total number of possible combinations for power parameters are 6 of which two typical examples are stated below:

Programming range / Model example	0 – 50V, 0 – 3.12V / <i>05/03</i>	0 – 40V, 0 – 5A / <i>40/05</i>
i rogramming range i woder example	$0 - 30 \text{V}, \ 0 - 3.12 \text{V} / 03/03$	0 - 40 V, 0 - 3/\ 1 \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \

MINimum [W]	5	10
DEFault [W]	100	150
MAXimum [W]	150	160
PROTection LEVel DEFault [W]	100	150
PROTection DELay MINimum [s]	1	1
PROTection DELay MAXimum [s]	300	300
PROTection DELay DEFault [s]	10	10

8.2. Reset Settings (*RST)

At power-on or after execution of the ${*RST}$ common command, device settings will be set to states that are listed in the table that follows. See also the ${\underline{\mathsf{MEMory:STATe:RECall:AUTO}}$ command.

Command	Power on	*RST
*ESE	0	Not affected
*ESR	0	Not affected
*SRE	0	Not affected
*STB?	0	???
CAL[:MODE]	Ol	FF
CAL:STAT	ON if valid calibrating data for ists in the non-volatile memory	r both voltage and current ex- y, otherwise OFF.
INST:NSEL	Power down state	Not affected
INST:SEL	Power down state	Not affected
OUTP[:STAT]	Power down state	OFF
OUTP:SENS	Power down state	OFF
[SOUR[n]]:CURR	Power down state	DEF (see <u>Section 8.1</u>)
[SOUR[n]]:CURR:PROT:DEL	Power down state	DEF (see <u>Section 8.1</u>)
[SOUR[n]]:CURR:PROT:STAT	Power down state	OFF
[SOUR[n]]:CURR:PROT:TRIP?	()
[SOUR[n]]:CURR:STEP	Power down state	DEF (see Section 8.1)
[SOUR[n]]:POW:PROT[:LEV]	Power down state	DEF (see Section 8.1)
[SOUR[n]]:POW:PROT:DEL	Power down state	DEF (see Section 8.1)
[SOUR[n]]:POW:PROT:STAT	Power down state	ON
[SOUR[n]]:POW:PROT:TRIP?	()
[SOUR[n]]:VOLT	Power down state	DEF (see Section 8.1)
[SOUR[n]]:VOLT:PROT:DEL	Power down state	DEF (see Section 8.1)
[SOUR[n]]:VOLT:PROT:STAT	Power down state	OFF
[SOUR[n]]:VOLT:PROT:TRIP?	()
[SOUR[n]]:VOLT:STEP	Power down state	DEF (see Section 8.1)
STAT:OPER[:EVEN]	0	Not affected
STAT:OPER:COND	0	Not affected
STAT:OPER:ENAB	0	Not affected
STAT:OPER:INST[:EVEN]	0	Not affected
STAT:OPER:INST:COND	0	Not affected

8.Parameters and settings

	_	
STAT:OPER:INST:ENAB	0	Not affected
STAT:OPER:INST:ISUM[:EVEN]	0	Not affected
STAT:OPER:INST:ISUM:COND	0	Not affected
STAT:OPER:INST:ISUM:ENAB	0	Not affected
STAT:QUES[:EVEN]	0	Not affected
STAT:QUES:COND	0	Not affected
STAT:QUES:ENAB	0	Not affected
STAT:QUES:INST[:EVEN]	0	Not affected
STAT:QUES:INST:COND	0	Not affected
STAT:QUES:INST:ENAB	0	Not affected
STAT:QUES:INST:ISUM[:EVEN]	0	Not affected
STAT:QUES:INST:ISUM:COND	0	Not affected
STAT:OPER:INST:ISUM:ENAB	0	Not affected
SYST:ERR:COUN?		0
SYST:POW	Power down state	ON
TEMP:PROT [MAIN]	Power down state	70
TEMP:PROT:DEL	Power down state	10
TEMP:PROT:STAT [MAIN]	Power down state	ON

9. Software simulator

The PSU firmware can be also compiled and executed as a Windows, Linux or OS X application. The software simulator is a terminal application that can respond to any currently supported SCPI command described in this document. SCPI commands could be entered directly in the simulator's terminal window (Fig. 7) or remotely by using the e.g. a <u>Telnet</u> client (Fig. 5).

```
*/Downloads
:~/Downloads$ ./eez_psu_sim
EEZ PSU software simulator ver. M1.0.90
Listening on port 5025
```

Fig. 4: Simulator welcome screen

```
Trying 127.0.0.1...
Connected to localhost.
Escape character is '^]'.
*idn?
EEZ,1/50/03-1/40/05 (Simulator),00001,M1.0.90
diag:test?
"1, EEPROM, installed, passed","1, Ethernet, installed, passed","1, RTC, installed, passed","2, BP option, installed, skipped","1, CH1 IOEXP, installed, passed","1, CH1 DAC, installed, passed","1, CH2 IOEXP, installed, passed","1, CH2 DAC, installed, passed","1, CH2 ADC, installed
```

Fig. 5: Remote connection using a telnet client

The simulator also has a GUI part when started open a separate window with the picture of the PSU front panel.

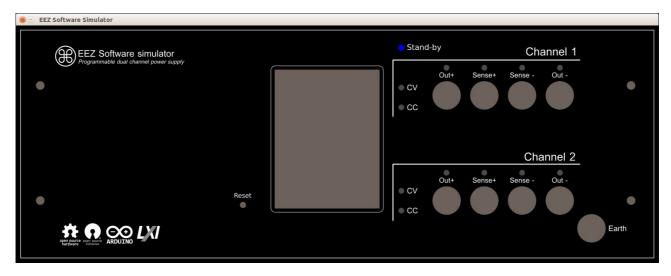


Fig. 6: Simulator GUI front panel

The GUI simulator front panel currently displays only changes in LED indicators and indicates if load is applied on the output terminals or not. For example if 8.2 Ohm load is connected to the channel 1 and cause that channel enters CC mode the GUI front panel will indicate that in the following way:

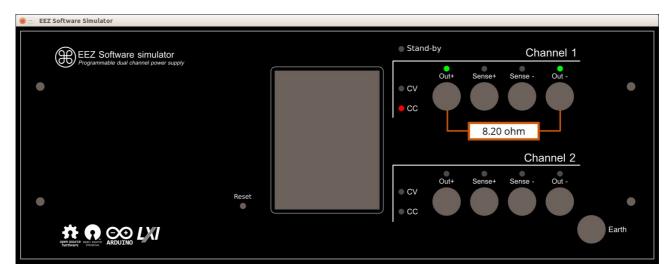


Fig. 7: Simulator GUI with connected load on the channel 1

9.1. SIMUlator

The SIMUlator subsystem represent a set of unclassified SCPI commands that can be used to manage external parameters and events such as load impedance, connection and disconnection of the load, sensor temperature or the PSU control circuit power supply state. Thanks to them e.g. simulation of the measuring and protection commands that depends of external events become more meaningful. For example MEASure:CURRent? without connected load will always returns zero, or activation of the VOLTage:PROTection:STATe will automatically trip the OVP since channel cannot starts in CC mode of operation when output is switched on, etc.

SCPI command	Description
SIMUlator	
<u>:EXIT</u>	Closes simulator
<u>:GUI</u>	Starts simulator's GUI
:LOAD { <value>}</value>	Sets value of the virtual load
:STATe { <bool>}</bool>	"Connects" virtual load to the channel output
:PWRGood { <bool>}</bool>	Sets the PWRGOOD signal state
:TEMP { <value>}</value>	Sets the temperature sensor value

9.1.1. SIMUlator: EXIT

Syntax SIMUlator:EXIT

Description This command close all Software simulators windows (terminal and GUI if started).

Return None

Usage SIMU: EXIT

example Errors

Related Commands

9.1.2. SIMUlator:GUI

Syntax SIMUlator:GUI

Description Use this command to start the GUI simulator in the new window. See Fig. 6

Return None

Usage SIMU:GUI

example

Errors

Related

Commands

9.1.3. SIMUlator:LOAD

Syntax SIMUlator:LOAD {<value>}

SIMUlator:LOAD?

Description This command is used to define impedance of the virtual load that is connected to the

channel output. Units are in ohms. With load connected it is possible to simulate e.g. CC mode of operation, current and power measurement, OCP and OPP functionality, etc.

The simulator currently cannot emulate the "UR" mode of operation (see the

OUTPut:MODE? command).

Default **Parameters** Name Type Range <value> Numeric 0 - 9999999|INFinite

The query command returns the programmed load value. Return

Usage example SIMU:LOAD 10

Errors

Related

OUTPut:MODE?

Commands

9.1.4. SIMUlator:LOAD:STATe

Syntax SIMUlator:LOAD:STATe {<bool>}

SIMUlator:LOAD?

Description This command is used to "connect" or "disconnect" the virtual load to the channel output.

If the GUI simulator is started (the SIMUlator:GUI command) load symbol with selected

value in Ohms will be displayed (See Fig. 4)

Parameters Name Range Default Type ON|OFF|0|1 <bool> Discrete

Return The query command returns the load state.

Usage example SIMU:LOAD:STAT?

0

MEAS: CURR?

0.00

SIMU:LOAD:STAT ON

MEAS: CURR?

1.50

Errors

Related

OUTPut:MODE? Commands SIMUlator:GUI

SIMUlator:LOAD

9.1.5. SIMUlator: PWRGood

SIMUlator:PWRGood {<bool>} Svntax

SIMUlator:PWRGood?

This command can be used to simulate detection of an internal power supply failure. Description

> When PWRGOOD signal is changed from 1 to 0 the PSU is going to the Stand-by mode (equal to the command SYSTem:POW OFF). The PSU mode cannot be changed until

PWRGOOD is not changed to 1.

Parameters Name Type Range Default <bool> Discrete ON|OFF|0|1 ON

The query command returns the PWRGOOD signal state. Return

Usage SYST: POW?

example

SIMU: PWRG 0 SYST: POW?

 \cap

Errors

Related SYSTem:POWer

Commands

9.1.6. SIMUlator:TEMPerature

SIMUlator:TEMPerature {<value>} SIMUlator:TEMPerature? Syntax

Description Use this command to set temperature in degrees Celsius (°C) that will "sense" tempera-

ture sensor.

Parameters Name Range Default Type <value> 0 - 100Numeric

The query command returns the set temperature value.

SIMU:TEMP 45 Usage example MEAS: TEMP?

45.00

Errors

Return

Related Commands

10. Programming examples

10.1. Set channel output values and working with the OCP

This is a SCPI commands sequence that sets a voltage, current, and the over-current protection (OCP) on the channel two:

INST? Check currently selected output

1

INST CH2 Select channel two as current channel

VOLT 10 Set output voltage
CURR Set output current
CURR: PROT: STAT? Check OCP status

0

CURR: PROT: STAT 1 Enable OCP

CURR: PROT: DEL 100ms Set OCP delay

OUTP 1 Enable output

MEAS? *Measure output voltage*

10.00

MEAS: CURR? Measure output current

0.00 Current is zero since no load is connected

If software simulator is used, connection of the load can be also simulated:

SIMU:LOAD 20 Define connected load impedance

MEAS? Measure voltage once again

10.00

MEAS: CURR? Measure current once again

0.50 Measured current

The following command sequence could be used to test channel mode with load previously defined and after the load impedance is lowered enough that output current reach programmed value. The OCP has to be disabled because previously defined 100ms delay does not give us enough time to execute the whole sequence for testing channel mode and output voltage and current values:

OUTP: MODE? Check mode of operation

"CV" The channel is in constant-voltage mode since output current is below pre-

viously programmed level

SIMU:LOAD? Check load value

10

CURR: PROT: STAT? Check OCP status

1

CURR: PROT: STAT OFF Disable OCP

SIMU:LOAD 4 Decrease load impedance

OUTP: MODE? Check once again mode of operation

"CC" Channel enters constant-current mode since $I_{max} = U/R = 10/4 = 2.5A$

and current is limited to the 1A

EEZ PSU SCPI reference M1

MEAS: CURR? Measure output current

1.00

MEAS? Measure output voltage

4.00 Output voltage is decreased since U = I * R = 1 * 4 = 4V

The OCP will "trip" when output current reach programmed value and channel stay in the CC mode for more then programmed OCP delay time. To test that with e.g. the <u>software simulator</u> we'll disable channel output first, enable OCP and when change channel output back to enabled state:

OUTP OFF Disable channel output

CURR: PROT: TRIP? Check OCP status

OCP is not activated

CURR: PROT: STAT ON Enable OCP

VOLT? Check programmed output voltage

10.00

CURR? Check programmed output current

1.00

SIMU:LOAD? Check simulated load value

4

OUTP ON Enable channel output

CURR: PROT: TRIP? Check OCP status once again

1 OCP has been tripped

OUTP? Check channel output state

O Channel output is changed to OFF stated by the OCP

The channel output state cannot be changed to enabled until any of protection is active. We have to clear protection first. If the same load that caused the first protection trip is still connected the channel output will be disabled immediately after the protection programmed delay time expired. Therefore we also have to disconnect load or disable protection. The later method will be used in the command sequence that follows:

OUTP ON First attempt to enable channel output

OUTP?

O This attempt failed, the channel output remain disabled

OUTP: PROT: CLE Channel protections reset

OUTP ON Second to enable channel output

O Channel output was enabled for a short time (100ms) and returns back to

OFF state

CURR: PROT: TRIP? Check OCP status

1 OCP has been tripped

OUTP: PROT: CLE Reset channel protections once again

CURR: PROT: STAT OFF Disable OCP

OUTP ON Third attempt to enable channel output

OUTP?

1 Output is finally enabled

OUTP: MODE?

10.2. Voltage and current calibration

For optimum calibration results the following condition are recommended:

- the calibration ambient temperature is stable and between 20 °C and 30 °C.
- ambient relative humidity is less than 80%.
- Allow a 1-hour warm-up period before verification or calibration (use DIAG:OTIM? LAST).
- Use short and thick cables to connect test setups.

Step	Commands	Description
1	<pre>INST {CH1 CH2}; OUTP ON</pre>	Select the channel to be calibrated and enable the channel output.
2	VOLT:PROT:STAT OFF POW:PROT:STAT OFF	Disable if required the voltage and power protection function.
3	CAL ON, " <password>"</password>	PSU enters calibration mode on the channel selected in step 1. Both voltage and current on the selected channel are set to the MINimum value. The VOLT? and CURR? commands can be optionally used here to test channel output values.
4		For voltage calibration, connect a digital voltmeter (DVM) across the PSU's output terminals.
5	CAL: VOLT: LEV MIN	Set the channel to the low-end (MIN) calibration point.
6	CAL:VOLT 0.249	Enter the reading you obtained from the external DVM.
7	CAL:VOLT:LEV MID	Set the channel to the middle (MID) calibration point.
8	CAL:VOLT 25.058	Enter the reading you obtained from the DVM.
9	CAL:VOLT:LEV MAX	Set the channel to the high (MAX) calibration point.
10	CAL:VOLT 49.86	Enter the reading you obtained from the DVM.
11		For current calibration, connect an appropriate current monitoring resistor (shunt) across the output terminals and connect the DVM across the shunt resistor.
12		Repeat step 5 through step 10 by substituting CURR for VOLT for current calibration. For example, CAL:CURR:LEV MIN. The OCP function has to be disabled (CURR:PROT:STAT OFF).
13		Repeat step 1 through step 12 for the other channel calibration.
14	CAL:REM " <string>"</string>	Record calibration information such as next calibration due date for future reference. The calibration string may contain up to 40 characters.
15	CAL:SAVE	Save to non-volatile memory new calibration data.
16	CAL OFF, " <password>"</password>	PSU exit calibration mode. Both voltage and current on the selected channel are again set to the MINimum value.

10.3. Working with profiles

The following command sequence could be used to store current set of parameters to the profile location 4 in the non-volatile memory:

MEM:STAT:VAL? 4	Check to see if profile selected location is empty
0	
MEM:STAT:NAME? 4	We can also check that by querying profile location name
"Not used"	

EEZ PSU SCPI reference M1

<pre>INST CH1 VOLT?;:CURR?;:OUTP?</pre>	Examine currently programmed output values of the first channel
0.00;0.00;0	
<pre>INST CH2 VOLT?;:CURR?;:OUTP?</pre>	Examine currently programmed output values of the second channel
0.00;0.00;0	
VOLT 12;:CURR 300mA INST CH1 VOLT 12;:CURR 300mA OUTP 1;:OUTP 1, CH2	Reprogram both channel output values that will be stored as a new profile
*SAV 4	All profile parameters is now storing on the selected location
MEM:STAT:NAME? 4	Check profile name
11 11	
MEM:STAT:NAME 4, "Dual 12V/300mA, Output ON"	Set the profile name (only ASCII characters are allowed!)
MEM:STAT:NAME? 4	Check the profile name once again
"Dual 12V/300ma, Output ON"	

We can now turn the PSU off (when it enters the Stand-by mode) turn it on again and check some of the programmed parameters:

SYST:POW 0	The PSU enters the Stand-by mode
SYST:POW 1	Returns back from the Stand-by mode. Please note that this command can be executed with the minimum of 5 seconds delay otherwise a -200, "Execution error" will be generated (you can check that with the SYST:ERR? command)
VOLT?;:CURR?;:OUTP?	Query programmed voltage, current and output state of the currently selected channel
0.00;0.00;0	Returned data indicate that previously saved values in profile number 4 were not used
*RCL 4 VOLT?;:CURR?;:OUTP?	Recall parameters from desired location and execute query once again
12.00;0.30;1	The channel output values are now programmed using the selected profile

We can automate above mentioned process that channel profile parameters stored in non-volatile memory are using on power up. First we'll check what is a current status of automatic recall and what profile will be used in the case of automatic recall:

MEM:STAT:REC:AUTO?	Query status of automatic profile recall during power on sequence
0	Automatic recall is turned off
MEM:STAT:REC:AUTO ON	Turn on automatic recall
MEM:STAT:REC:SEL?	Query which profile will be used when automatic recall is turned on
0	Selected profile was 0
MEM:STAT:REC:SEL 4	Change power on profile to 4
SYST:POW 0	Switch the PSU to the Stand-by mode once again
SYST:POW 1	Returns back from the Stand-by mode. Again wait at least 5 sec-

onds before enters this command

VOLT?;:CURR?;:OUTP? Query programmed voltage, current and output state of the cur-

rently selected channel

12.00;0.30;1 The channel output values are programmed using the selected profile

prome

10.4. Get identification info and self-test results

The PSU's identification information could be beneficial when more then one instrument are controlled. Additionally in the following example information about self-test will be queried:

```
*IDN?
EEZ, 1/50/03-1/40/05
(Due),00001,M1.0.93
*TST?
DIAG: TEST?
"1, EEPROM, installed, passed", "1,
Ethernet, installed, passed", "1, RTC,
installed, passed","1, DateTime,
installed, passed", "2, BP option,
installed, skipped", "1, CH1 IOEXP,
installed, passed", "1, CH1 DAC,
installed, passed","1, CH1 ADC,
installed, passed", "1, CH2 IOEXP,
installed, passed", "1, CH2 DAC,
installed, passed","1, CH2 ADC,
installed, passed"
```

Query identification string

PSU with two different channels is identified, the first channel is 0-50V/3A and the second is 0-40V/5A. Serial number is 00001, and firmware version M1.0.93

Execute self-test and query result

Self-test is passed

Query additional information about self-test

The self-test could be performed even when the PSU is in the Stand-by mode. We'll first switch the PSU into the Stand-by mode. At the end of this example we are using additional diagnostic command that allows us to query information about channel's ADC measurements.

```
SYST:POW 0
DIAG:TEST?

"1, EEPROM, installed, passed","1, Ethernet, installed, passed","1, RTC, installed, passed","1, DateTime, installed, passed","2, BP option, installed, skipped"

SYST:POW 1
DIAG:ADC?

"U_SET=12.02 V","U_MON=12.00
V","I_SET=0.30 A","I_MON=0.00 A"
```

The PSU enters the Stand-by mode

Query additional information about self-test

Only Arduino Shield +BP module diagnostic information is returned

Returns back from the Stand-by mode

Additional information about currently selected channel ADC inputs

U_SET and I_SET are measured values of the DAC outputs, U_MON and I_MON are actual output values. I_MON is 0 because no load is connected. A small difference between set and actual output voltage exists because calibration data are currently in use.

11. SCPI commands scheduled for the Milestone Three (M3)

Please note that the following list is preliminary and more accurate lists will be available after the Milestone Two (M2) is reached.

SCPI command	Description
DCL	Requires the client (controller) to send a "DCL\n" string
*SRE	Sets the value of the Service Request Enable register
*TRG	Generates a software trigger
*WAI	Waits until all pending commands are completed
ABORt	Resets the trigger system and places all trigger sequences in the IDLE state
CALibration	
:TEMPerature	
[:DATA] { <new value="">}</new>	Enters the calibration value
DIAGnostic	
[:INFOrmation]	
:BOARds?	Returns a list of the installed boards in the PSU
:CCOunt:PON?	Returns the cumulative number of power-ons
:CCOunt:PROTection:TEMPerature? { <sensor>}</sensor>	Returns the cumulative number of OTP activation
:FIRMware?	Returns the firmware information
DISPlay { <bool>}</bool>	Sets the front panel TFT display state
:BRIGhtness { <numeric_value>}</numeric_value>	Sets the intensity of the front panel TFT display
:TEXT { <quoted string="">}</quoted>	Displays a message on the front panel TFT display
:CLEar	Clear a message on the front panel TFT display
:CMAP	
:DEFault	Resets all color maps to default value
:COLor	
:RGB { <red>,<green>,<blue>}</blue></green></red>	Sets the RGB values for the color map
INITiate	
[:IMMediate]	Completes one full trigger cycle
:CONTinuous { <bool>}</bool>	Enables/disables continuous transient triggers
INSTrument	
:COUPle	
[:TRIGger]	Trigger coupling between two logical outputs
OUTPut	
:COUPle	

[:STATe] {<bool>} Enables channel coupling for output synchronization :INSTrument Selects which channels are coupled :DPRog {<bool>} Disables down-programmer circuit :COUPle {<bool>} Enables channel coupling for protection faults :TRACk[:STATe] {<bool>} Enables tracking mode [SOURce[<n>]] :CURRent [:LEVel] :TRIGgered [:AMPLitude] {<current>} Sets the triggered output current :MODE {<mode>} Sets the current trigger mode :LIST :COUNt Sets the number of times that the list is executed :CURRent[:LEVel] Specifies the current setting for each list step :DWELI Specifies the dwell time for each list step :LOAD {<list_number>} Loads stored list from the non-volatile memo-:SAVE {< list number>} Saves LIST to the non-volatile memory :VOLTage[:LEVel] Specifies the voltage setting for each list step :LOCK Channel parameters are locked and cannot be changed without providing password :VOLTage [:LEVel] :TRIGgered [:AMPLitude] {<voltage>} Sets the triggered output voltage :MODE {<mode>} Sets the voltage trigger mode **SYSTem** :COMMunicate :ETHernet Ethernet communication parameters :CONTrol? Queries communication port for SRQ handling :DHCP {<bool>} Enables the DHCP mode :DNS {<ip address>} Sets the DNS (Domain Name Service) ad-:GATEway {<ip_address>} Sets the network gateway address :HOSTname {<name>} Sets the Ethernet communication host name :IPADdress {<ip_address>} Sets the IP address :MAC {<mac address>} Returns the Ethernet device MAC address :PORT {<number>} Sets the Ethernet communication port Sets the subnet mask :SMASk {<mask>} :NTP {<ip address>} Sets NTP (Network Time Protocol) server :SERial Serial (via USB) communication parameters Sets the baud rate :BAUD {<speed>}

11.SCPI commands scheduled for the Milestone Three (M3)

:BITS {<number>} Sets the number of data bits

:PARity {<parity>} Sets parity bit

SBITs {<number>} Sets the number of stop bits

:ERRor

:ALL? Queries the error/event queue for all the un-

read items

:CODE[:NEXT]? Queries the error/event queue for the next

item code

:GROup[:DEFine]

:PARAllel Makes single output from multiple channels

connected in parallel

:SERial Makes single output from multiple channels

connected in serial

:DELete[:ALL] Deletes any existing group of channels

:KLOCk Lock the local input device :LFRequency {<value>} Sets power-line frequency

:LOCal Returns from remote mode to local mode

:PASSword:NEW {<old code>, <new code>} Changes system password

:REMote PSU in the remote mode of oper-

ation

12. SCPI commands summary

Common command		Description		
*CLS	Clears all status da	Clears all status data structures		
*ESE { <value>}</value>	Programs the Standard Event Status Enable register bits			
<u>*ESR?</u>	Reads the Standard Event Status Register			
<u>*IDN?</u>	Returns the UNIQUE identification of the PSU			
<u>*OPC</u>	Operation Complete Command used for program synchronization			
*RCL { <profile>}</profile>	Recalls the PSU state stored in the specified storage location			
<u>*RST</u>	Reset PSU to the initial state			
*SAV { <profile>}</profile>	Stores the current PSU state in the specified storage location			
*STB?	Reads the Status Byte register			
*TST?	Returns Self-Test results			
SCPI Co	mmand	Description		
CALibrate[:MODE] { <box< td=""><td>ol>, <password>}</password></td><td>Enables/disables calibration mode</td></box<>	ol>, <password>}</password>	Enables/disables calibration mode		
:CLEar { <password>]</password>	}	Clears all calibration parameters		
:CURRent				
[:DATA] { <new td="" val<=""><td><u>ue>}</u></td><td>Enters the calibration value</td></new>	<u>ue>}</u>	Enters the calibration value		
:LEVel { <level>}</level>		Calibrates the output current programming		
:PASSword				
:NEW { <old>, <ne< td=""><td><u>w>}</u></td><td>Changes calibration password</td></ne<></old>	<u>w>}</u>	Changes calibration password		
:REMark { <string>}</string>		Saves calibration information		
:SAVE		Saves the new cal constants in non-volatile memory		
:STATe { <bool>, <password>}</password></bool>		Enables calibration parameters		
:VOLTage				
[:DATA] { <new value="">}</new>		Enters the calibration value		
:LEVel { <level>}</level>		Calibrates the output voltage programming		
DIAGnostic				
[:INFOrmation]				
:ADC?		Returns the latest values acquired by ADC		
:CALibration?		Returns a list of the calibration parameters		
:PROTection?				
:TEST?		Returns results of the most recent self-test		
INSTrument				
[:SELect] { <channel>}</channel>		Selects the output to be programmed		
:NSELect { <channel_number>}</channel_number>		Selects the output to be programmed		
MEASure				
[:SCALar]				
:CURRent				
[:DC]? [<channel>]</channel>		Takes a measurement; returns the average current		

:POWer	
[:DC]? [<channel>]</channel>	Takes a measurement; returns the average power
:TEMPerature	
[:DC]? { <sensor>}</sensor>	Takes a measurement; returns the average temperature
[:VOLTage]	
[:DC]? [<channel>]</channel>	Takes a measurement; returns the average voltage
MEMory	
:NSTates?	Returns total number of state storage memory locations
:STATe	
:CATalog?	Lists the names associated with all ten state storage locations
:DELete { <pre><pre>cprofile>}</pre></pre>	Deletes the contents of a state storage location
:ALL	Deletes the contents of all state storage locations
:NAME { <profile>, <name>}</name></profile>	Assigns a custom name to a state storage locations
:RECall	
:AUTO { <bool>}</bool>	Specifies whether the power-down state is recalled from location 0 on power-on
:SELect { <profile>}</profile>	Specifies which PSU state will be used at power on
:VALid? { <profile>}</profile>	Determines whether a storage location contains a valid state
OUTPut	
[:STATe] { <bool>}</bool>	Enables the specified output channel(s)
:MODE?	Returns the channel mode of operation
:PROTection	
:CLEar	Resets latched protection
:SENSe	Enables the remote sense function of the channel
SIMUlator	
<u>:EXIT</u>	Closes simulator
:GUI	Starts simulator's GUI
:LOAD { <value>}</value>	Sets value of the virtual load
:STATe { <bool>}</bool>	"Connects" virtual load to the channel output
:PWRGood { <bool>}</bool>	Sets the PWRGOOD signal state
:TEMP { <value>}</value>	Sets the temperature sensor value
[SOURce[<n>]]</n>	
:CURRent	
[:LEVel]	
<pre>[:IMMediate][:AMPLitude] {<current>}</current></pre>	Sets the output current
:STEP[:INCRement] { <step>}</step>	Sets the step of the current change
:PROTection	
:DELay	

[:TIME] {<time>} Sets the over-current protection (OCP) programming

delay

:STATe {<bool>} Enables/disables over-current protection on the select-

ed channel

Returns status of over-current protection activation :TRIPped?

:POWer

:PROTection[:LEVel] Sets the over-power protection (OPP) level

:DELay

[:TIME] {<time>} Sets the over-power protection programming delay

Enables/disables over-power protection on the select-:STATe {<bool>}

ed channel

:TRIPped? Returns status of over-power protection activation

:VOLTage

[:LEVel]

[:IMMediate][:AMPLitude]

{<voltage>}

:STEP[:INCRement] {<step>}

Sets the step of the voltage change

:PROTection

:DELay

Sets the over-voltage protection (OVP) programming [:TIME] {<time>}

Sets the output voltage

delay

Enables/disables over-voltage protection on the select-:STATe {<bool>}

ed channel

:TRIPped? Returns status of over-voltage protection activation

STATus

:OPERation

[:EVENt]? Returns the value of the Operation Event register

Returns the value of the Operation Instrument Condi-:CONDition?

tion register

Enables specific bits in the Operation Event register :ENABle {<value>}

:INSTrument[<n>]

Returns the value of the Operation Instrument Event [:EVENt]?

register

Returns the value of the Operation Instrument Condi-:CONDition?

tion register

Enables specific bits in the Operation Instrument Event :ENABle {<value>}

register

:ISUMmary<n>

[:EVENt]? Returns the value of the Operation Instrument Isum-

mary Event register

:CONDition? Returns the value of the Operation Instrument Isum-

mary Condition register

:ENABle {<value>} Enables specific bits in the Operation Instrument Isum-

mary Event register

:PREset Presets all enable registers to power-on state

:QUEStionable

[:EVENt]? Returns the value of the Questionable Event register

:CONDition? Returns the value of the Questionable Condition regis-

ter

<u>:ENABle {<value>}</u> Enables specific bits in the Questionable Event regis-

ter

:INSTrument[<n>]

[:EVENt]? Returns the value of the Questionable Instrument

Event register

:CONDition? Returns the value of the Questionable Instrument Con-

dition register

<u>:ENABle {<value>}</u> Enables specific bits in the Questionable Instrument

Event register

:ISUMmary<n>

[:EVENt]? Returns the value of the Questionable Instrument

Isummary Event register

:CONDition? Returns the value of the Questionable Instrument

Isummary Condition register

<u>:ENABle {<value>}</u> Enables specific bits in the Questionable Instrument

Isummary Event register

SYSTem

<u>:BEEPer[:IMMediate]</u> Issues a single beep immediately

:STATe {<bool>} Enables beeper function

:CAPability? Returns an <instrument_specifier>
:DATE {<vvvv>,<mm>,<dd>}
Sets the date of the system clock

:ERRor

[:NEXT]? Queries and clears errors from the error queue

:COUNt? Queries the error/event queue for the number of un-

read items

<u>:POWer {<bool>}</u> Enters the PSU into the Stand-by mode

:TEMPerature

:PROTection

[:HIGH]

[:LEVel] {<temperature>[, Sets the OTP value

<sensor>]}

:CLEar[, {<sensor>}] Clears the latched protection status of the over-tem-

perature protection (OTP)

:DELay Sets time-out period

[:TIME] {<delay>[, <sensor>]} Sets the OTP programming delay

:STATe {<bool>[, <sensor>]} Enables/disables OTP on the selected temperature

sensor

:TRIPped? [<sensor>] Returns status of OTP activation

:TIME {<hh>,<mm>,<ss>}

Sets the time of the system clock

:VERSion? Returns the SCPI version number

