

# Project One

## 搜索算法

### 小练习



Farmer Cabbage Goat Wolf

Actions:

有八种可能的动作

表示农民独自回到左岸

F> F<

FC> FC<

意思是农夫会把山羊带到右岸

FG> FG<

FW> FW<

Approach: build a search tree ("what if?")

如左图：一个农民要带着一只狼、一只羊、一颗白菜过河。

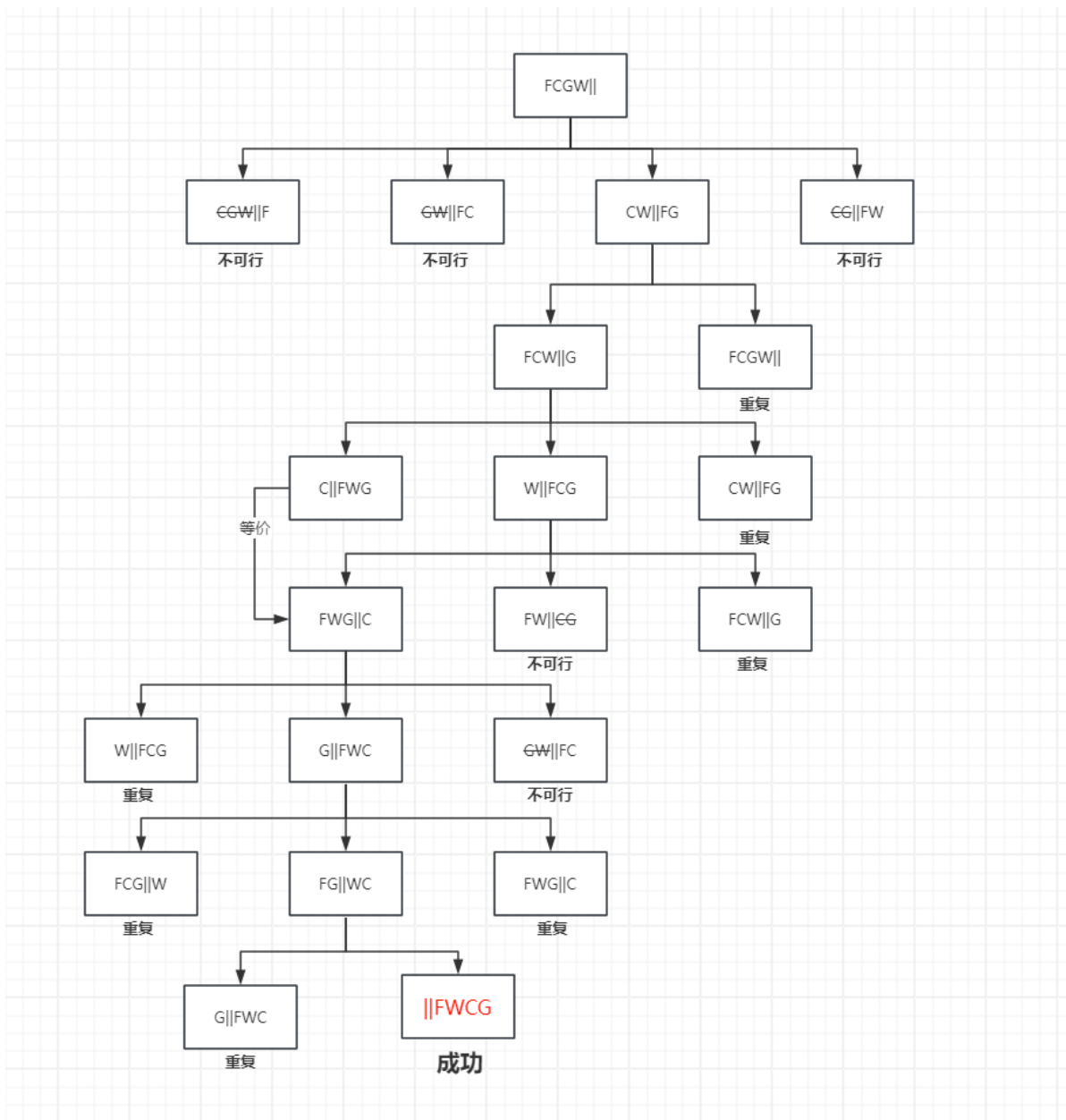
(1) 人不在的时候，狼会吃羊、羊会吃草

(2) 猎人每次只能带一样东西过河。

要求：画出状态空间图，如下图



答案如图



## 1. 算法回顾

### • 1.1: BFS (每条边的权重为1)

```

#include<iostream>
#include<queue>
using namespace std;
vector<int> g[100001];
int visit[100001]={0};
int parent[100001]={0};
queue<int> q;

int bfs(int n){
    int startpoint=1,count=0;
    while(!q.empty()){
        startpoint=q.front();
        if(startpoint==n){
            count++;
            while(startpoint!=1){

```

```

        startpoint=parent[startpoint];
        count++;
    }
    return count;
}
q.pop();
visit[startpoint]=1;
for(auto i:g[startpoint]){
    if(visit[i]==0){
        q.push(i);
        parent[i]=startpoint;
        visit[i]=1;
    }
}
}
return -1;
}

int main(){
    int n=0,m=0,start=0,end=0;
    cin>>n>>m;
    for(int i=0;i<m;i++){
        cin>>start>>end;
        g[start].push_back(end);
    }
    for(int i=0;i<100000;i++){
        visit[i]=0;
        parent[i]=0;
    }
    q.push(1);
    cout<<bfs(n);
}

```

V是顶点数量，E是边数量

时间复杂度：O(E)

空间复杂度：O(V+E)

使用邻接表，会从起始点遍历可达点，遍历的最差情况是要遍历图中所有的边，因此时间复杂度是O(E)。题目需要记录邻接表(大小为E)、队列q(大小为V)、访问节点数组visit(大小为V)、父节点数组parent(大小为V)，因此空间复杂度是O(V+E)。

## • 1.2: 朴素版Dijkstra (图最短路)

```

#include <iostream>
#include <queue>
using namespace std;
vector<pair<int, int>> g[100001];
int state[100001] = {0};
int dis[100001] = {0};
#define _MAX 9999999

int dijkstra(int n)

```

```

{
    int startpoint = 1, t = 0;
    dis[1] = 0;
    for (int i = 0; i < n; i++)
    {
        t = -1;
        for (int j = 1; j <= n; j++)
        {
            if (state[j] == 0)
            {
                if (t == -1 || dis[j] < dis[t])
                {
                    t = j;
                }
            }
        }
        state[t] = 1;
        for (auto i : g[t])
        {
            int tmp1 = i.first;
            int tmp2 = i.second;
            if (state[tmp1] == 0)
            {
                dis[tmp1] = min(tmp2 + dis[t], dis[tmp1]);
            }
        }
    }
    if (dis[n] != _MAX)
        return dis[n];
    else
        return -1;
}

int main()
{
    int n = 0, m = 0, start = 0, end = 0, value = 0;
    cin >> n >> m;
    for (int i = 0; i < m; i++)
    {
        cin >> start >> end >> value;
        g[start].push_back({end, value});
    }
    for (int i = 0; i < 100000; i++)
    {
        state[i] = 0;
        dis[i] = _MAX;
    }
    cout << dijkstra(n);
}

```

V是顶点数量，E是边数量

时间复杂度：O(V+E<sup>2</sup>)

空间复杂度：O(V+E)

使用邻接表，会从起始点依次选择未访问的节点中距离起点最近的节点进行扩展，直到所有可达的顶点都被访问过。在每次扩展时，更新到达附近节点的最短距离。要遍历图中所有的边，并且每次都要寻找距离起点最近的节点，因此时间复杂度是 $O(E)$ 。

题目需要记录邻接表 `g` (大小为 $E$ 、每个元素是一个 `pair`，表示到达的顶点和边的权重)、记录更新状态的数组 `state` (大小为 $V$ )、记录到节点距离的数组 `dis` (大小为 $V$ )，因此空间复杂度是 $O(V+E)$ 。

### • 1.3: 堆优化版Dijkstra (图最短路)

```
#include <iostream>
#include <queue>
using namespace std;

vector<pair<int, int>> g[100001];
int state[100001] = {0};
int dis[100001] = {0};
#define _MAX 99999999
struct node
{
    friend bool operator<(node n1, node n2)
    {
        return n1.dis > n2.dis;
    }
    int dis;
    int number;
};

priority_queue<node> q;

int dijkstra(int n)
{
    dis[1] = 0;
    struct node cur_node;
    cur_node.dis = 0;
    cur_node.number = 1;
    q.push(cur_node);
    while (!q.empty())
    {
        cur_node = q.top();
        q.pop();
        int cur_number = cur_node.number;
        int cur_dis = cur_node.dis;
        if (state[cur_number])
        {
            continue;
        }
        state[cur_number] = 1;
        for (auto i : g[cur_number])
        {
            int tmp1 = i.first;
            int tmp2 = i.second;
            if (state[tmp1] == 0)
            {
                dis[tmp1] = min(tmp2 + dis[cur_number], dis[tmp1]);
                struct node new_node;
```

```

        new_node.dis = dis[tmp1];
        new_node.number = tmp1;
        q.push(new_node);
    }
}
}
if (dis[n] != _MAX)
    return dis[n];
else
    return -1;
}

int main()
{
    int n = 0, m = 0, start = 0, end = 0, value = 0;
    cin >> n >> m;
    for (int i = 0; i < m; i++)
    {
        cin >> start >> end >> value;
        g[start].push_back({end, value});
    }
    for (int i = 0; i < 10000; i++)
    {
        state[i] = 0;
        dis[i] = _MAX;
    }
    cout << dijkstra(n);
}

```

V是顶点数量，E是边数量

时间复杂度：O(VlogV+E)

空间复杂度：O(V+E)

使用邻接表，会从起始点依次选择未访问的节点中距离起点最近的顶点进行扩展，直到所有可达的顶点都被访问过。在每次扩展时，更新到达附近节点的最短距离。要遍历图中所有的边，并且每次优先队列都要通过堆（速度为logV）给出距离起点最近的节点，因此时间复杂度是O(VlogV+E)。

题目需要记录邻接表g（大小为E、每个元素是一个pair，表示到达的顶点和边的权重）、记录更新状态的数组state（大小为V）、记录到节点最小距离的数组dis（大小为V）、优先队列q（大小为V），因此空间复杂度是O(V+E)。

## 2. 八数码问题

### • 2.1: DFS（解存在性问题）

```

#include <iostream>
#include <queue>
#include <vector>
#include <stack>
#include <set>
using namespace std;

```

```

struct node
{
    string cur_s;
    int cur_x = 0;
}; //状态, 位置

int dx[4] = {0, -1, 0, 1};
int dy[4] = {-1, 0, 1, 0};
set<string> vis;
stack<node> st;
string target = "12345678x";

int dfs_8digits()
{
    while(!st.empty()) {
        struct node cur_node=st.top();
        st.pop();
        if (cur_node.cur_s == target) {
            return 1;
        }
        int x1 = cur_node.cur_x / 3;
        int y1 = cur_node.cur_x % 3;

        for (int i = 0; i < 4; i++) {
            int x2 = dx[i] + x1, y2 = dy[i] + y1;
            if (x2 < 0 || y2 < 0 || x2 > 2 || y2 > 2)
                continue;
            string new_s = cur_node.cur_s;
            int new_x = x2 * 3 + y2;
            swap(new_s[cur_node.cur_x], new_s[new_x]);
            struct node new_node;
            new_node.cur_s = new_s;
            new_node.cur_x = new_x;
            if (vis.count(new_s) == 0) {
                vis.insert(new_s);
                st.push(new_node);
            }
        }
    }
    return 0;
}

int main()
{
    string s = "";
    char t;
    int x = 0;
    for (int i=0;i<9;i++)
    {
        cin >> t;
        s += t;
        if (t == 'x')
        {
            x = i;
        }
    }
}

```

```

    }
    vis.insert(s);
    struct node first_node;
    first_node.cur_s = s;
    first_node.cur_x = x;
    st.push(first_node);
    cout<<dfs_8digits();
}

```

八数码dfs: 由于每步操作产生4个分支, 受最大搜索深度d的影响, 八数码dfs的时间复杂度为 $O(4^d)$ , 空间复杂度在未空间优化、剪枝的情况下应该是9!

使用 stack 用于dfs搜索过程中存储待搜索的节点, 如果使用递归会导致调用层数过多报错。每次尝试将空格与周边存在的邻格交换, 直到与目标状态一致。会使用 set 记录访问过的状态避免重复搜索。

## • 2.2: BFS (求解最少步数)

```

#include <iostream>
#include <queue>
#include <vector>
#include <set>
using namespace std;

struct node
{
    string cur_s;
    int cur_x = 0;
    int count = 0;
}; //状态, 位置, 层数

int dx[4] = {0, -1, 0, 1};
int dy[4] = {-1, 0, 1, 0};
queue<node> q;
set<string> vis;

string target = "12345678x";

int bfs_8digits()
{
    while (!q.empty())
    {
        struct node cur_node;
        cur_node = q.front();
        if (cur_node.cur_s == target)
        {
            return cur_node.count;
        }
        q.pop();
        int x1 = cur_node.cur_x / 3;
        int y1 = cur_node.cur_x % 3;

        for (int i = 0; i < 4; i++)
        {

```



```

        int x2 = dx[i] + x1, y2 = dy[i] + y1;
        if (x2 < 0 || y2 < 0 || x2 > 2 || y2 > 2)
            continue;
        string new_s = cur_node.cur_s;
        int new_x = x2 * 3 + y2;
        int new_count = cur_node.count + 1;
        swap(new_s[cur_node.cur_x], new_s[new_x]);
        if (vis.count(new_s))
        {
            continue;
        }
        else
        {
            vis.insert(new_s);
        }
        struct node new_node;
        new_node.cur_s = new_s;
        new_node.cur_x = new_x;
        new_node.count = new_count;
        q.push(new_node);
    }
}
return -1;
}

int main()
{
    string s = "";
    char t;
    int x = 0;
    for (int i=0;i<9;i++)
    {
        cin >> t;
        s += t;
        if (t == 'x')
        {
            x = i;
        }
    }
    vis.insert(s);
    struct node first_node;
    first_node.cur_s = s;
    first_node.cur_x = x;
    q.push(first_node);
    cout<<bfs_8digits();
}

```

八数码bfs：由于每步操作产生4个分支，受最大搜索深度d的影响，八数码bfs的时间复杂度为 $O(4^d)$ ，空间复杂度在未空间优化、剪枝的情况下应该是9！

使用 `queue` 用于bfs搜索过程中存储待搜索的状态，通过逐层扩展来找到从初始状态到目标状态的最少步数。每次尝试将空格与周边存在的邻格交换，直到与目标状态一致。会使用 `set` 记录访问过的状态避免重复搜索。

相比于dfs，bfs通常能够更快地找到解，且能够找到最短路径。

## • 2.3: Dijkstra (特殊的A star)

```
#include <iostream>
#include <queue>
#include <vector>
#include <set>
using namespace std;

struct node
{
    string cur_s;
    int cur_x = 0;
    int count = 0;
    friend bool operator< (node n1, node n2)
    {
        return n1.count > n2.count;
    }
}; //状态, 位置, 层数

int dx[4] = {0, -1, 0, 1};
int dy[4] = {-1, 0, 1, 0};
priority_queue<node> q;
set<string> vis;

string target = "12345678x";

int dijkstra_8digits()
{
    while (!q.empty())
    {
        struct node cur_node;
        cur_node = q.top();
        if (cur_node.cur_s == target)
        {
            return cur_node.count;
        }
        q.pop();
        int x1 = cur_node.cur_x / 3;
        int y1 = cur_node.cur_x % 3;

        for (int i = 0; i < 4; i++)
        {
            int x2 = dx[i] + x1, y2 = dy[i] + y1;
            if (x2 < 0 || y2 < 0 || x2 > 2 || y2 > 2)
                continue;
            string new_s = cur_node.cur_s;
            int new_x = x2 * 3 + y2;
            int new_count = cur_node.count + 1;
            swap(new_s[cur_node.cur_x], new_s[new_x]);
            if (vis.count(new_s))
            {
                continue;
            }
            else
            {

```

```

        vis.insert(new_s);
    }
    struct node new_node;
    new_node.cur_s = new_s;
    new_node.cur_x = new_x;
    new_node.count = new_count;
    q.push(new_node);
}
}
return -1;
}

int main()
{
    string s = "";
    char t;
    int x = 0;
    for (int i=0;i<9;i++)
    {
        cin >> t;
        s += t;
        if (t == 'x')
        {
            x = i;
        }
    }
    vis.insert(s);
    struct node first_node;
    first_node.cur_s = s;
    first_node.cur_x = x;
    q.push(first_node);
    cout << dijkstra_8digits();
}

```

八数码dijkstra：由于每步操作产生4个分支，最大搜索深度d，`priority_queue`内部需要堆排序，八数码dijkstra的时间复杂度为 $O(\log 4d \cdot 4^d)$ ，空间复杂度在未空间优化、剪枝的情况下应该是9！

使用`priority_queue`用于dijkstra搜索过程中存储待搜索的状态，保证每次从队列中取出的节点是当前最小步数的节点，虽然在这里和bfs效果相同，因为每一步代价都是一样的。每次尝试将空格与周边存在的邻格交换，直到与目标状态一致。会使用`set`记录访问过的状态避免重复搜索。

由于交换步骤的代价肯定是1，所以效果与bfs一致。

## • 2.4: A star (求解最少步数)

```

#include <iostream>
#include <queue>
#include <set>
#include <map>
using namespace std;

struct node
{

```

```

string cur_s;
int cur_x = 0;
int count = 0;
int fn = 0;
string path;
friend bool operator<(node n1, node n2)
{
    return n1.fn > n2.fn;
}
}; //状态, 位置, 层数
int dx[4] = {0, -1, 0, 1};
int dy[4] = {-1, 0, 1, 0};
char step[4] = {'l', 'u', 'r', 'd'};
priority_queue<node> q;
map<string, int> vis;

string target = "12345678x";

bool answer_available(string s)
{
    int cnt = 0;

    for (int i = 0; i < 9; i++)
    {
        for (int j = i + 1; j < 9; j++)
        {
            if (s[i] == 'x' || s[j] == 'x')
            {
                continue;
            }
            if (s[i] > s[j])
            {
                cnt++;
            }
        }
    }
    return cnt % 2;
}

int f(struct node cur_node)
{
    int h = 0;
    int x1 = cur_node.cur_x / 3;
    int y1 = cur_node.cur_x % 3;
    for (int i = 0; i < 9; i++)
    {
        if (i == cur_node.cur_x)
        {
            continue;
        }
        else
        {
            h += abs(i / 3 - (cur_node.cur_s[i] - '1') / 3) + abs(i % 3 -
(cur_node.cur_s[i] - '1') % 3);
        }
    }
}

```

```

    }
    return h + cur_node.count;
};

string A_8digits()
{
    while (!q.empty())
    {
        struct node cur_node;
        cur_node = q.top();
        if (cur_node.cur_s == target)
        {
            return cur_node.path;
        }
        q.pop();
        if(vis[cur_node.cur_s]<cur_node.count){continue;}
        int x1 = cur_node.cur_x / 3;
        int y1 = cur_node.cur_x % 3;

        for (int i = 0; i < 4; i++)
        {
            int x2 = dx[i] + x1, y2 = dy[i] + y1;
            if (x2 < 0 || y2 < 0 || x2 > 2 || y2 > 2)
                continue;
            string new_s = cur_node.cur_s;
            int new_x = x2 * 3 + y2;
            int new_count = cur_node.count + 1;
            string new_path = cur_node.path + step[i];
            swap(new_s[cur_node.cur_x], new_s[new_x]);
            if (vis.count(new_s)&&vis[new_s]<=new_count)
            {
                continue;
            }
            else
            {
                vis[new_s]=new_count;
            }
            struct node new_node;
            new_node.cur_s = new_s;
            new_node.cur_x = new_x;
            new_node.count = new_count;
            new_node.fn = f(new_node);
            new_node.path = new_path;
            q.push(new_node);
        }
    }
    return "unsolvable";
}

int main()
{
    string s = "";
    char t;
    int x = 0;
    for (int i = 0; i < 9; i++)

```

```

{
    cin >> t;
    s += t;
    if (t == 'x')
    {
        x = i;
    }
}
vis[s]=0;
struct node first_node;
first_node.cur_s = s;
first_node.cur_x = x;
f(first_node);
q.push(first_node);
if (answer_available(s))
{
    cout << "unsolvable";
}
else
{
    cout << A_8digits();
}
}

```

八数码 A\*：由于每步操作产生4个分支，最大搜索深度d，priority\_queue 内部需要堆排序，八数码 A\* 的时间复杂度为 $O(\log 4d \cdot 4^d)$ ，空间复杂度在未空间优化、剪枝的情况下应该是 $9!$

同样使用 priority\_queue 保证了每个处理的节点都是当前步数和估计剩余步数之和最小的节点。每次尝试将空格与周边存在的邻格交换，直到与目标状态一致。会使用 map 记录访问过的节点以及对应的 fn，如果访问过的节点的 fn 更新后会比 map 记录中的小，那么就会修改 map 并将节点修改为新状态加入 priority\_queue。函数 f 是评价函数  $f(n) = g(n) + h(n)$ ， $h(n)$  的计算方法在这里是计算1~8到正确位置的曼哈顿距离。

A\* 算法的主要精髓在评价函数  $f(n) = g(n) + h(n)$ 。相比于Dijkstra算法，A\*算法在评价函数下能够更快地找到最短路径。当  $h(n) = 0$  时算法变为Dijkstra；当  $h(n) = 0$  并且边权为1时变为 bfs。

## 3. 迷宫问题

### • 3.1: DFS

```

import matplotlib.pyplot as plt

directions = [(1, 0), (0, -1), (-1, 0), (0, 1)]

def dfs(maze, n, m):
    visited = set()
    visited.add((0, 0))
    memory = [(0, 0, 0)]
    stack = [(0, 0, 0)] # (row, col, steps)
    parents = [[None] * m for _ in range(n)]
    path = []

```

```

global_step = 0
while stack:
    row, col, steps = stack.pop()
    global_step+=1
    if (row, col) == (n - 1, m - 1):
        path.append((row, col, steps))
        while steps and not (row==0 and col == 0):
            row, col ,steps= parents[row][col]
            path.append((row, col, steps))
        path.reverse()
        return path, memory
    for dr, dc in directions:
        new_row, new_col = row + dr, col + dc
        if 0 <= new_row < n and 0 <= new_col < m and maze[new_row][new_col]
== 0 and (new_row, new_col) not in visited:
            visited.add((new_row, new_col))
            memory.append((new_row, new_col, global_step))
            stack.append((new_row, new_col, global_step))
            parents[new_row][new_col] = (row, col, steps)

def visualize_maze_with_path(maze, path, interval, memory):
    if path:
        path_x, path_y, steps = zip(*path)
        plt.figure(figsize=(len(maze[0])/2, len(maze)/2))
        plt.imshow(maze, cmap='Greys', interpolation='nearest')

        new_colored_cells = []

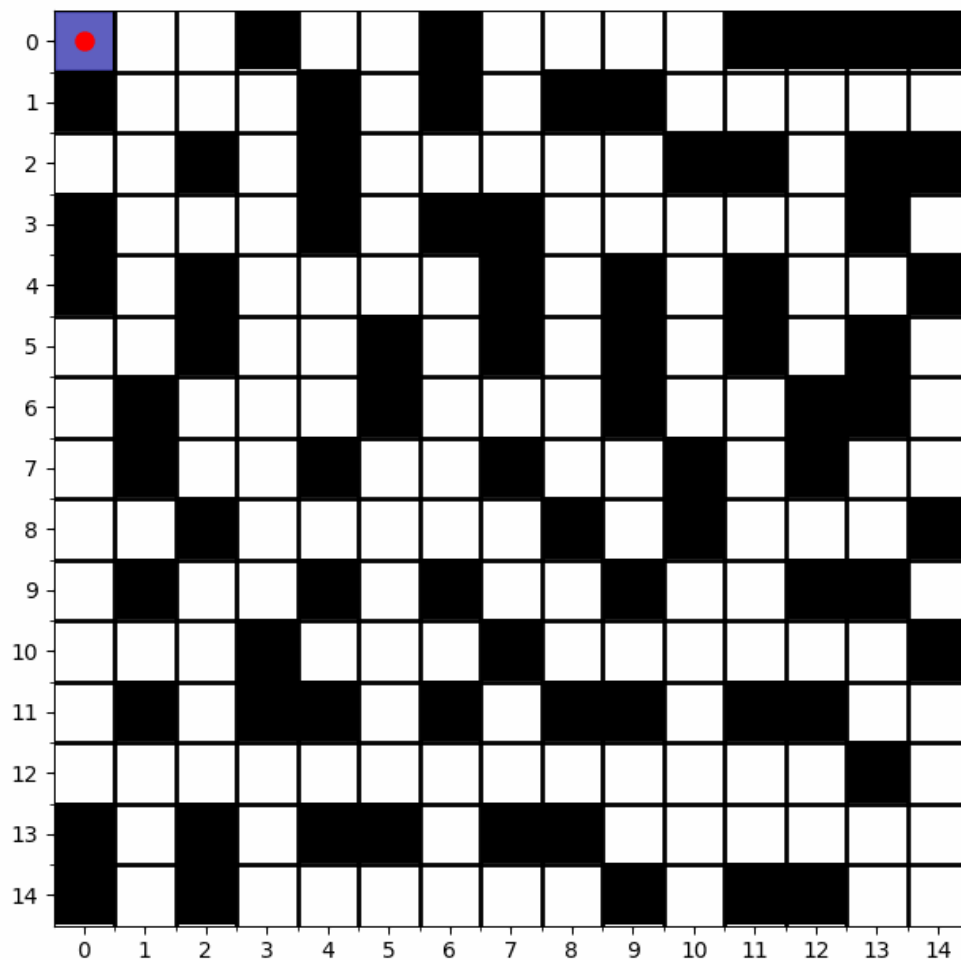
        k=0
        for i in range(steps[-1]+1):
            if(i==steps[k]):
                plt.plot(path_y[:k + 1], path_x[:k + 1], marker='o',
                        markersize=8, color='red', linewidth=3)
                k+=1
            for x, y in new_colored_cells:
                color = 'yellow'
                plt.fill_between([y - 0.5, y + 0.5], x - 0.5,
                                x + 0.5, color=color, alpha=0.5)

            new_colored_cells.clear()

            for x, y, step in memory:
                if step == i:
                    color = 'blue'
                    new_colored_cells.append((x, y))
                    plt.fill_between([y - 0.5, y + 0.5], x - 0.5,
                                    x + 0.5, color=color, alpha=0.5)

        plt.xticks(range(len(maze[0])))
        plt.yticks(range(len(maze)))
        plt.gca().set_xticks(
            [x - 0.5 for x in range(1, len(maze[0]))], minor=True)
        plt.gca().set_yticks(
            [y - 0.5 for y in range(1, len(maze))], minor=True)

```





## • 3.2: BFS

```
import matplotlib.pyplot as plt

directions = [(1, 0), (-1, 0), (0, 1), (0, -1)]

def bfs(maze, n, m):
    visited = set()
    visited.add((0, 0))
    memory = [(0, 0, 0)]
    queue = [(0, 0, 0)] # (row, col, steps)
    parents = [[None] * m for _ in range(n)]
    path = []
    while queue:
        row, col, steps = queue.pop(0)
        if (row, col) == (n - 1, m - 1):
            path.append((row, col, steps))
            print(steps)
            while steps:
                steps -= 1
                row, col = parents[row][col]
                path.append((row, col, steps))
            path.reverse()
            return path, memory
        for dr, dc in directions:
            new_row, new_col = row + dr, col + dc
            if 0 <= new_row < n and 0 <= new_col < m and maze[new_row][new_col]
            == 0 and (new_row, new_col) not in visited:
                visited.add((new_row, new_col))
                memory.append((new_row, new_col, steps + 1))
                queue.append((new_row, new_col, steps + 1))
                parents[new_row][new_col] = (row, col)

def visualize_maze_with_path(maze, path, interval, memory):
    if path:
        path_x, path_y, steps = zip(*path)
        plt.figure(figsize=(len(maze[0])/2, len(maze)/2))
        plt.imshow(maze, cmap='Greys', interpolation='nearest')

        new_colored_cells = []

        for i in range(len(path)):
            plt.plot(path_y[:i + 1], path_x[:i + 1], marker='o',
                    markersize=8, color='red', linewidth=3)

            for x, y in new_colored_cells:
                color = 'yellow'
                plt.fill_between([y - 0.5, y + 0.5], x - 0.5,
                                x + 0.5, color=color, alpha=0.5)

            new_colored_cells.clear()

        for x, y, step in memory:
```

```

        if step == i:
            color = 'blue'
            new_colored_cells.append((x, y))
            plt.fill_between([y - 0.5, y + 0.5], x - 0.5,
                             x + 0.5, color=color, alpha=0.5)

plt.xticks(range(len(maze[0])))
plt.yticks(range(len(maze)))
plt.gca().set_xticks(
    [x - 0.5 for x in range(1, len(maze[0]))], minor=True)
plt.gca().set_yticks(
    [y - 0.5 for y in range(1, len(maze))], minor=True)
plt.grid(which="minor", color="black", linestyle='-', linewidth=2)
plt.axis('on')
plt.pause(interval)
plt.show()

```

```
interval = 0.25
```

```

n, m = map(int, input().split())
maze = []
for _ in range(n):
    row = list(map(int, input().split()))
    maze.append(row)

```

```

path, memory = bfs(maze, n, m)
visualize_maze_with_path(maze, path, interval, memory)

```

### • 3.3: Dijkstra

```

import matplotlib.pyplot as plt
import queue
directions = [(1, 0), (-1, 0), (0, 1), (0, -1)]

def dijkstra(maze, n, m):
    memory = [(0, 0, 0)]
    distances = {(i, j): float('inf') for i in range(n) for j in range(m)}
    distances[(0, 0)] = 0
    pq = queue.PriorityQueue()
    pq.put((0, (0, 0)))
    parents = [[None] * m for _ in range(n)]
    path = []
    while queue:
        steps, (row, col) = pq.get()
        if (row, col) == (n - 1, m - 1):
            path.append((row, col, steps))
            print(steps)
            while steps:
                steps -= 1
                row, col = parents[row][col]
                path.append((row, col, steps))

```

```

        path.reverse()
        return path, memory
    for dr, dc in directions:
        new_row, new_col = row + dr, col + dc
        if 0 <= new_row < n and 0 <= new_col < m and maze[new_row][new_col]
== 0:
            if steps + 1 < distances[(new_row, new_col)]:
                distances[(new_row, new_col)] = steps + 1
                memory.append((new_row, new_col, steps + 1))
                pq.put((steps + 1, (new_row, new_col)))
                parents[new_row][new_col] = (row, col)

def visualize_maze_with_path(maze, path, interval, memory):
    if path:
        path_x, path_y, steps = zip(*path)
        plt.figure(figsize=(len(maze[0])/2, len(maze)/2))
        plt.imshow(maze, cmap='Greys', interpolation='nearest')

        new_colored_cells = []

        for i in range(len(path)):
            plt.plot(path_y[:i + 1], path_x[:i + 1], marker='o',
                    markersize=8, color='red', linewidth=3)

            for x, y in new_colored_cells:
                color = 'yellow'
                plt.fill_between([y - 0.5, y + 0.5], x - 0.5,
                                x + 0.5, color=color, alpha=0.5)

            new_colored_cells.clear()

            for x, y, step in memory:
                if step == i:
                    color = 'blue'
                    new_colored_cells.append((x, y))
                    plt.fill_between([y - 0.5, y + 0.5], x - 0.5,
                                    x + 0.5, color=color, alpha=0.5)

        plt.xticks(range(len(maze[0])))
        plt.yticks(range(len(maze)))
        plt.gca().set_xticks(
            [x - 0.5 for x in range(1, len(maze[0]))], minor=True)
        plt.gca().set_yticks(
            [y - 0.5 for y in range(1, len(maze))], minor=True)
        plt.grid(which="minor", color="black", linestyle='-', linewidth=2)
        plt.axis('on')
        plt.pause(interval)
    plt.show()

interval = 0.25

n, m = map(int, input().split())
maze = []

```

```

for _ in range(n):
    row = list(map(int, input().split()))
    maze.append(row)

path, memory = dijkstra(maze, n, m)
visualize_maze_with_path(maze, path, interval, memory)

```

### • 3.4: A star

```

import matplotlib.pyplot as plt
import queue
directions = [(1, 0), (-1, 0), (0, 1), (0, -1)]

def A(maze, n, m):
    visited = set()
    visited.add((0, 0))
    memory = [(0, 0, 0)]
    distances = {(i, j): float('inf') for i in range(n) for j in range(m)}
    distances[(0, 0)] = 0
    pq = queue.PriorityQueue()
    pq.put((n + m - 2, (0, 0, 0)))
    parents = [[None] * m for _ in range(n)]
    path = []
    while queue:
        dis, (row, col, steps) = pq.get()
        if (row, col) == (n - 1, m - 1):
            path.append((row, col, steps))
            print(steps)
            while steps:
                steps -= 1
                row, col = parents[row][col]
                path.append((row, col, steps))
            path.reverse()
            return path, memory
        for dr, dc in directions:
            new_row, new_col = row + dr, col + dc
            if 0 <= new_row < n and 0 <= new_col < m and maze[new_row][new_col]
            == 0 and (new_row, new_col) not in visited:
                visited.add((new_row, new_col))
                new_dist = steps + abs(n - 1 - row) + abs(m - 1 - col)
                memory.append((new_row, new_col, steps + 1))
                pq.put((new_dist, (new_row, new_col, steps + 1)))
                parents[new_row][new_col] = (row, col)

def visualize_maze_with_path(maze, path, interval, memory):
    if path:
        path_x, path_y, steps = zip(*path)
        plt.figure(figsize=(len(maze[0])/2, len(maze)/2))
        plt.imshow(maze, cmap='Greys', interpolation='nearest')
        new_colored_cells = []

```

```

for i in range(len(path)):
    plt.plot(path_y[:i + 1], path_x[:i + 1], marker='o',
             markersize=8, color='red', linewidth=3)

for x, y in new_colored_cells:
    color = 'yellow'
    plt.fill_between([y - 0.5, y + 0.5], x - 0.5,
                    x + 0.5, color=color, alpha=0.5)

new_colored_cells.clear()

for x, y, step in memory:
    if step == i:
        color = 'blue'
        new_colored_cells.append((x, y))
        plt.fill_between([y - 0.5, y + 0.5], x - 0.5,
                        x + 0.5, color=color, alpha=0.5)

plt.xticks(range(len(maze[0])))
plt.yticks(range(len(maze)))
plt.gca().set_xticks(
    [x - 0.5 for x in range(1, len(maze[0]))], minor=True)
plt.gca().set_yticks(
    [y - 0.5 for y in range(1, len(maze))], minor=True)
plt.grid(which="minor", color="black", linestyle='-', linewidth=2)
plt.axis('on')
plt.pause(interval)
plt.show()

interval = 0.25

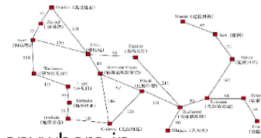
n, m = map(int, input().split())
maze = []
for _ in range(n):
    row = list(map(int, input().split()))
    maze.append(row)

path, memory = A(maze, n, m)
visualize_maze_with_path(maze, path, interval, memory)

```

## 小练习

## Example



- Suppose we want to place three new airports anywhere in Romania, such that the sum of squared straight-line distances from each city on the map to its nearest airport is minimized.
- The state space: the locations of the three new airports
  - $(x_1, y_1), (x_2, y_2), (x_3, y_3)$
  - Six variables  $\mathbf{x} = \langle x_1, y_1, x_2, y_2, x_3, y_3 \rangle$
- Objective function  $f(\mathbf{x}) = f(x_1, y_1, x_2, y_2, x_3, y_3)$ 
  - $C_i$  is the set of cities whose closest airport is airport  $i$ .

$$f(\mathbf{x}) = f(x_1, y_1, x_2, y_2, x_3, y_3) = \sum_{i=1}^3 \sum_{c \in C_i} (x_i - x_c)^2 + (y_i - y_c)^2.$$

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## 答案如图

$$\mathbf{x} \leftarrow \mathbf{x} - H_f^{-1}(\mathbf{x}) \nabla f(\mathbf{x})$$

$$H_{ij} = \frac{\partial^2 f}{\partial x_i \partial x_j} = \frac{\partial}{\partial x_j} \sum_{c \in C_i} (x_i - x_c)$$

$$\therefore H_f(\mathbf{x}) = \begin{bmatrix} 2 \sum_{c \in C_1} 1 & & \\ & 2 \sum_{c \in C_2} 1 & \\ & & \ddots \\ & & & 2 \sum_{c \in C_3} 1 \end{bmatrix}$$

$$\therefore H_f^{-1}(\mathbf{x}) = \begin{bmatrix} \frac{1}{2 \sum_{c \in C_1} 1} & & \\ & \ddots & \\ & & \frac{1}{2 \sum_{c \in C_3} 1} \end{bmatrix}$$

$$\therefore H_f^{-1}(\mathbf{x}) \nabla f(\mathbf{x}) = \left[ \frac{\sum_{c \in C_1} x_i - x_c}{\sum_{c \in C_1} 1}, \frac{\sum_{c \in C_1} y_i - y_c}{\sum_{c \in C_1} 1}, \dots, \frac{\sum_{c \in C_3} y_i - y_c}{\sum_{c \in C_3} 1} \right]$$

$$\therefore \text{机场坐标: } \left[ \frac{\sum_{c \in C_1} x_c}{\sum_{c \in C_1} 1}, \frac{\sum_{c \in C_1} y_c}{\sum_{c \in C_1} 1} \right]$$

$$\left[ \frac{\sum_{c \in C_2} x_c}{\sum_{c \in C_2} 1}, \frac{\sum_{c \in C_2} y_c}{\sum_{c \in C_2} 1} \right]$$

$$\left[ \frac{\sum_{c \in C_3} x_c}{\sum_{c \in C_3} 1}, \frac{\sum_{c \in C_3} y_c}{\sum_{c \in C_3} 1} \right]$$