

particle

April 9, 2022

This file describes a particle in the plasma whose motion is affected by the externally applied Magnetic and Electric fields, as an instantiable object of the Particle class.

```
[1]: import numpy as np # For computations
```

```
[3]: class Particle:
    '''
    An object instance of the Particle class can:
    1. hold information of name, charge, mass, position, velocity and
    ↪ optionally acceleration
    2. call methods to update the position and velocity based on different
    ↪ strategies

    SUGGESTIONS FOR IMPROVEMENTS
    1.
    '''
    def __init__(self, name, q, m, r_0, v_0, a_0 = [0,0,0]):
        '''
        The properties of a particle are initialized.

        Arguments:
        self
        name: particle's name
        q: particle's charge
        m: particle's mass
        r_0: particle's initial position
        v_0: particle's initial velocity
        a_0: particle's initial acceleration
        It seems that acceleration is not necessary to be recorded according to
        ↪ the current setup,
        so it is initialized to zero by default, requiring initial acceleration
        ↪ as an optional argument.

        Returns:
        nothing
        '''
```

```

    #description:: Type
    self.name = name
    #name:: String
    self.q = q
    #charge:: Number
    self.m = m
    #mass:: Number
    self.r = r_0
    #position:: [x:: Number, y:: Number, z:: Number]
    self.v = v_0
    #velocity:: [v_x:: Number, v_y:: Number, v_z:: Number]
    self.a = a_0
    #acceleration:: [a_x:: Number, a_y:: Number, a_z:: Number]

def __str__(self):
    '''
    For a particle, generate a string describing it, for use in printing.

    Arguments:
    self

    Returns:
    a formatted string describing the particle
    '''

    return f'{self.name} \n mass:{self.m} charge:{self.q} \
    \n position: ({self.r[0]}, {self.r[1]}, {self.r[2]}) \
    \n velocity: ({self.v[0]}, {self.v[1]}, {self.v[2]}) \
    \n acceleration: ({self.a[0]}, {self.a[1]}, {self.a[2]})'

def update_acceleration(self, da):
    '''
    Currently all update is done in the Boris_update method.
    Using other update strategies may require using this function.
    '''

    pass

def update_velocity(self, dv):
    '''
    Currently all update is done in the Boris_update method.
    Using other update strategies may require using this function.
    '''

```

```

pass

def update_position(self, dr):
    """
    Currently all update is done in the Boris_update method.
    Using other update strategies may require using this function.
    """

    pass

def update(self, args):
    """
    Updates the particle based on some update strategy.
    Currently Boris_update() is used as the update strategy.
    Other update strategies could also be used.

    Arguments:
    self
    args: tuple of arguments that the currently used update strategy takes.

    For the Boris update method, the required arguments are:
    afield: an instance object of the Class Field defined in the file field.
    ↪ ipynb
    dt: time step
    argsE: arguments required to call the currently used electric field
    argsB: arguments required to call the currently used magnetic field

    Returns:
    nothing
    """

    #unwrap the tuple args and get the arguments required for the currently
    ↪ used update method
    #currently the Boris_update method is used
    afield, dt, argsE, argsB = args
    #Call the Boris_update method
    self.Boris_update(afield, dt, argsE, argsB)

def Boris_update(self, afield, dt, argsE, argsB):
    """
    Updates the particle state based on the Boris update strategy(Boris
    ↪ Algorithm).

```

```

Arguments:
self
afield: an instance object of the Class Field defined in the file field.
→ipynb
dt: time step

argsE: arguments required to call the currently used electric field
arguments required to call the currently used radial_E_field method of
→the Field class,
to get the electric field:
    Not required from arguments this one - r: the position where
→the fields are required to be computed.
    Typically this is the position of a particle of interest.
V: voltage at the electrode
center : center equivalent position of the electrode
a default coordinate of [0,0,0] may be used for the position of the
→electrode

argsB: arguments required to call the currently used magnetic field
arguments required to call the currently used helmholtz_coil_B_field
→method of the Field class,
to get the magnetic field:
n: number of turns in the coil
I: current in the coil
R: radius of the coil
B_hat: the direction of the magnetic field, i.e the axis of the coil
mu_0: the constant mu_0 to be passed in using the constants in the
→constants.ipynb file

Returns:
nothing
'''

# Define q_prime
q_prime = (self.q / self.m) * (dt / 2)

'''
#This is for other E and B fields
# Get E and B fields from the afield argument by passing in the current
→position of the particle
argsE = V, center
E = afield.get_E_field(self.r, V, center)
argsB = n, I, R, B_hat, mu_0
B = afield.get_B_field(self.r, n, I, R, B_hat, mu_0)
'''

```

```

#Currently only uniform magnetic and electric fields are used
E = np.array(argsE)
B = np.array(argsB)

#Boris velocity update
v_minus = np.add(self.v, q_prime * E)
v_plus = np.add(v_minus, q_prime * 2 * np.cross(v_minus, B))
v_new = np.add(v_plus, q_prime * E)

self.v = v_new

#could have also done:
#self.v += (2 * q_prime) * (E + np.cross( (self.v + q_prime * E), B))

#update position
self.r = np.add(self.r, dt * v_new)

```

```
[ ]:
```