# Algorithms I

# **Tutorial 1 Solution Hints**

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# Problem 1

Try it yourself.

# Problem 2

$$f_4(n), f_2(n), f_5(n), f_1(n), f_3(n)$$

# Problem 3

$$T(n) = n + \frac{n}{2} + \frac{n}{3} + \ldots + 1$$

$$T(n) = n \left(1 + \frac{1}{2} + \frac{1}{3} + \ldots + \frac{1}{n}\right)$$

$$T(n) = n \cdot H_n, H_n$$
 is  $n^{th}$  harmonic number  $= O(n \log n)$ 

# Problem 4

f(i) = a[i] - i is a non-decreasing function. So, we can binary search for i to check if f(i) = 0 for some i.

#### Problem 5

A cyclically sorted array can be represented as a concatenation of two sorted arrays. We just need to identify the position where the first array ends (let's call this position pivot). e.g. in [3,1,2], the arrays are [3] and [1,2]. Once we find pivot, we can binary search in the two arrays individually. pivot is the maximum index i such that array[0] < array[i]. So, we can find pivot by doing a binary search in the original array.

#### Problem 6

We'll use a stack that can store a node of the binary tree. Pseudo-code:

```
PUSH(stack, root)

while stack is not empty do

p \leftarrow \text{POP}(\text{stack})

print p \rightarrow key

if p has right child then

PUSH(stack, p \rightarrow right)
```

```
end if
      if p has left child then
          PUSH(stack, p \to left)
      end if
  end while
Problem 7
We'll use a stack that can store a \{node, 0/1\} pair of the binary tree.
Pseudo-code:
  PUSH(stack, \{root, 0\})
  while stack is not empty do
      \{p, x\} \leftarrow \text{POP(stack)}
      if x = 1 then
          print p \to key
      else
          if p has right child then
             PUSH(stack, \{p \rightarrow right, 0\})
          end if
          PUSH(stack, \{p, 1\})
          if p has left child then
             PUSH(stack, \{p \to left, 0\})
          end if
      end if
  end while
Problem 8
  function ARESAME(p, q)
      if p = NULL \land q = NULL then
          {f return} true
      else if p = NULL \lor q = NULL then
          return false
      end if
      if p \to key = q \to key then
          return ARESAME(p \rightarrow left, q \rightarrow left) \land ARESAME(p \rightarrow right, q \rightarrow right)
      else
          return false
      end if
  end function
```

#### Problem 9

At each node in the BST, we also store size of the sub-tree rooted at that node. Now, we create a balanced BST (e.g. Red-Black tree) and update the size accordingly while insertion and deletion. Now, we need to find  $\lceil \frac{n}{2} \rceil^{th}$  element. Let's take  $k = \lceil \frac{n}{2} \rceil$ . We start at root node. If size of sub-tree of current node is equal to k, we return the key of current node as median. If left child has more than or equal to k elements, we continue searching in the left child. Otherwise, we update k := k - size(left child sub-tree) - 1 and continue searching in the right child.

# Problem 10

Let's first find the node with minimum key. Let's call this node x. If x has a right child (let's call it y), then the second minimum will be the minimum key in the sub-tree rooted at y. So, we start at y and keep following the left pointer as long there's a left child. We'll end up at the required node.

If x has no right child, then the parent of x has the second minimum key.

# Problem 11

We can do this using in-order traversal. For a BST, in-order traversal must give a sorted sequence. So, we just maintain the key of the previously visited node during traversal. At each node, it's key must be greater than the key of the previously visited node.

#### Problem 12

No, the deletion operation is not commutative.

#### Problem 13

Largest:  $2^{2k} - 1$ , Smallest:  $2^k - 1$ 

#### Problem 14

We'll use a max heap of size k. For the first k values, we just insert them into the heap. For the next values, if the new value is smaller than the top value of the heap then we delete the top value from heap and insert the new value. If the new value is larger than the max value, we just ignore. The top value of the heap will be the  $k^th$  smallest value.

#### Problem 15

We maintain one min heap  $(H_L)$  for values smaller than or equal to median and one max heap  $(H_R)$  for values greater than or equal to median. We also maintain the condition that size of  $H_L$  and  $H_R$  differ by at most 1 i.e.  $||H_L| - |H_R|| \le 1$ .

At each step we maintain the current median of the stream of numbers. Now, there are 3 cases when a new element x arrives:

- $|H_L| = |H_R| 1$ , If x is less than the current median then insert x into  $H_L$ , otherwise delete the top element from  $H_R$  and insert it into  $H_L$ , also insert x into  $H_R$ .
- $|H_L| = |H_R|$ , If x is less than the current median then insert x into  $H_L$ , otherwise insert x into  $H_R$ .
- $|H_L| = |H_R| + 1$ , If x is greater than the current median then insert x into  $H_R$ , otherwise delete the top element from  $H_L$  and insert it into  $H_R$ , also insert x into  $H_L$ .

If  $|H_L| = |H_R|$ , we take median as the average of the top elements from  $H_L$  and  $H_R$ . Otherwise, we take the top element from the heap having more number of elements.